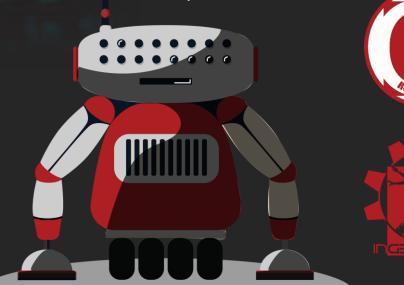
# CRAFT #0



# Introduction to RobotCraft 2024

9th Robotics Craftsmanship International Academy

<hello> <world!>





# **OBJECTIVES**

Presentation of lecturers and students

Welcome Package

Presentation of RobotCraft 2024 and its crafts

Presentation of the extra crafts



# INTRODUCE YOURSELF!

<hello> <world!>

#### Please, tell me:

- o What's your name?
- o Where are you from?
- O What's your course and University?
- What motivated you to join us?
- o What are your short-term and long-term objectives?



#### **NAME**

Micael Couceiro

#### **DEGREE**

PhD, Electrical and Computer Engineering

#### **SPECIALIZATION**

- Mobile Robotics
- Swarm Intelligence
- Artificial Intelligence
- Sports Engineering



- Introduction to Robotics
- Introduction to Programming
- Mobile Robotics Programming
- Artificial Intelligence



#### **NAME**

André Araújo

#### **DEGREE**

MSc, Electrical and Computer Engineering

# TIFEOS:

#### **SPECIALIZATION**

- Mobile Robotics
- Industrial Robotics
- ROS
- Firmware development

- Mechatronics
- Robot Operating System



#### **NAME**

Samuel Pereira

#### **DEGREE**

MSc, Automation and Communications in Energy Systems

#### **SPECIALIZATION**

- Cloud Robotics
- Internet-of-Things
- Automation



- Introduction to Programming
- Introduction to Linux



#### **NAME**

Carlos Pizzino

#### **DEGREE**

MSc, Electrical Engineering

#### **SPECIALIZATION**

- Mobile Robotics
- Artificial Intelligence
- SLAM



- Introduction to Linux
- Robot Operating System



#### **NAME**

Panagiotis Karfakis

#### **DEGREE**

MSc, Robotics Engineering

#### **SPECIALIZATION**

- ROS
- Localization



- Mobile Robotics Programming
- Robot Operating System



#### **NAME**

Beril Yalçınkaya

#### **DEGREE**

MSc, Computer Engineering

#### **SPECIALIZATION**

- Robotics
- ROS
- Arduino Programming
- Unity



- Introduction to Programming
- Mobile Robotics Programming
- Artificial Intelligence



#### NAME

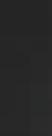
**Lucas Costa** 

#### **DEGREE**

BSc student, Electrical Engineering

#### **SPECIALIZATION**

- ROS
- Unity
- Arduino Programming



ROS Simulation





# WELCOME PACKAGE

- RobotCraft 2024 bag
- Ingeniarius' Pen
- Ingeniarius' Notebook
- Ingeniarius' USB flash
- Ingeniarius' bottle



# MOODLE

Access all the content of the course (attendance, classes, homeworks, etc.)

• Go to:

https://robotcraft.ingeniarius.pt/home

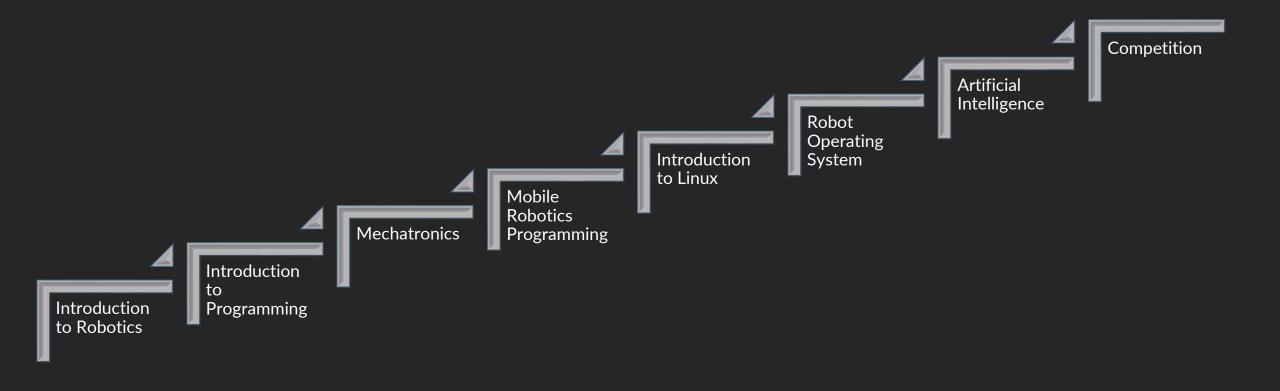
• Use the following login:

Username: <your e-mail>

Password: <your RobotCraft Registration password>

Choose your group!







#### week #1

## INTRODUCTION TO ROBOTICS

- ✓ Presentation of lecturers, mentors and interns
- ✓ Presentation of RobotCraft 2024 and the different crafts it comprises
- ✓ Introduction to robotics, describing the history of robotics and its evolution
- ✓ Presenting mobile robot morphologies, namely sensors and actuators
- ✓ Brief literature review related to robotics, presenting the necessary basic theoretical concepts



# week #1 INTRODUCTION TO PROGRAMMING

✓ Introduction to C/C++ programming



# week #2 MECHATRONICS

- ✓ Introduction to electromechanics in mobile robotics
- ✓ Electromechanical assembly of the mobile robotic platform



#### week #3/4

# MOBILE ROBOTICS PROGRAMMING

- ✓ Introduction to C language applied to Arduino programming
- ✓ Describe the features of Arduino solutions and ATMEL microcontroller (e.g., hardware architecture, cycles, pin configuration, communications), using the Arduino board
- ✓ Identify the different wireless communication technologies used in robotics (e.g., RF, Bluetooth, AdHoc, ZigBee)
- ✓ Introduction to low-level algorithms, flowcharts and pseudocode
- ✓ Acquire skills in the sensor and actuator practice used in robotics
- ✓ Develop a typical differential kinematic application using Arduino



# week #5 INTRODUCTION TO LINUX

✓ Introduction to *Linux OS* 



#### week #5/7

# ROBOT OPERATING SYSTEM

- ✓ Introduction to ROS
- ✓ Describe ROS features (e.g., stacks, publish-subscribe, topics, rosserial), and provide specific examples and case studies
- ✓ Present ROS-compatible simulators, such as Morse, Stage and Gazebo
- ✓ Introduction to high-level algorithms, flowcharts and pseudocode
- ✓ Follow ROS tutorial under simulation environment
- ✓ Explore rosserial for Arduino ROS communication
- ✓ Develop a typical robotic application using both *Arduino* and *ROS*



#### week #8

## ARTIFICIAL INTELLIGENCE

- ✓ Introduction to Artificial Intelligence, presenting different paradigms and some real applications
- ✓ Introduction and importance of integrating biologically-inspired models in robotics
- ✓ Formalizing a mobile robotic approach, devising biologically-inspired algorithms and finite-state machines
- ✓ Develop a streaming architecture to exchange all necessary data between Arduino and ROS (e.g., sensor readings, encoders readings, actuators control, etc.)



week #9

# ARTIFICIAL INTELLIGENCE

- ✓ Discussion of the competitive events, rules and prizes
- ✓ Consolidate concepts learned over all crafts and test the mobile robotic platform under a competitive scenario



# TIME TO COMPETE!

Open Labs: 26th August to 30th August

Competition: 30th or 31st August

- 1. Compete against each other in Maze BASIC and PRO!
- 2. The winning team will be rewarded





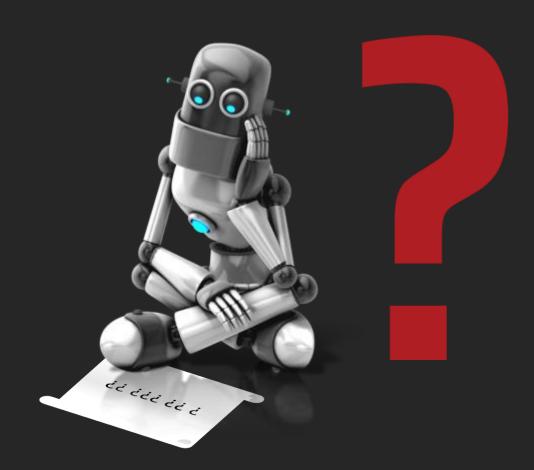
# CONCLUSIONS

- The course will comprise the base disciplines of robotics, falling within the fields of electrical engineering, computer sciences and mechatronics
- Students will develop a small mobile robot that benefits from both Arduino and ROS frameworks
- The competition will allow to evaluate the developed platform, as well as its kinematics and AI (maze solvers)



# **#0 TASK**

# Diagnostic Test



# CRAFT #0



# Thank you

