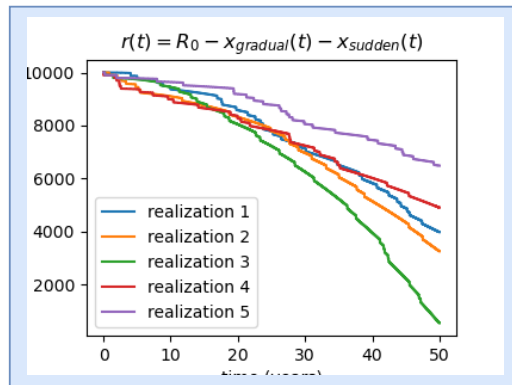
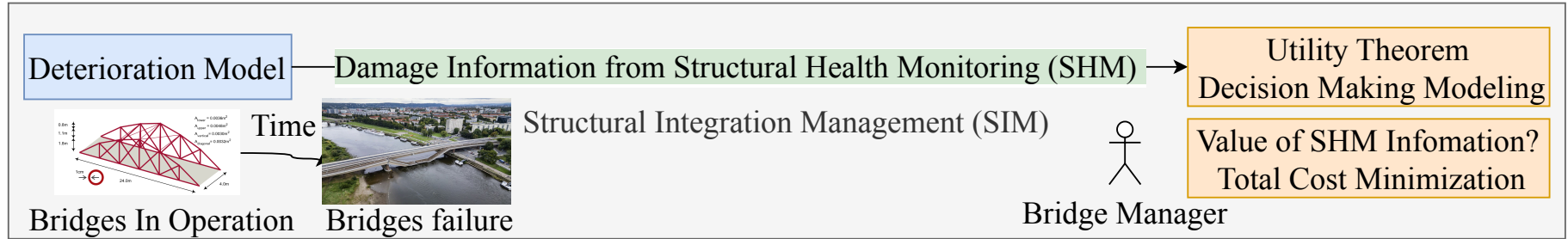


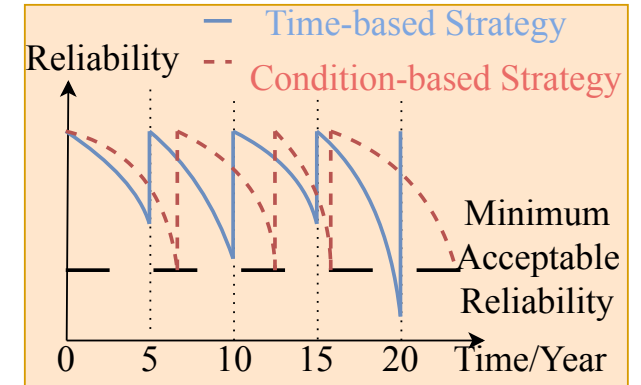
Traditional Strategy: Heuristic Decision Making

Modeling with predefined parameter

$$w = (p_{repair}^{threshold}, p_{inspect}^{threshold}, \Delta T_{insp})$$

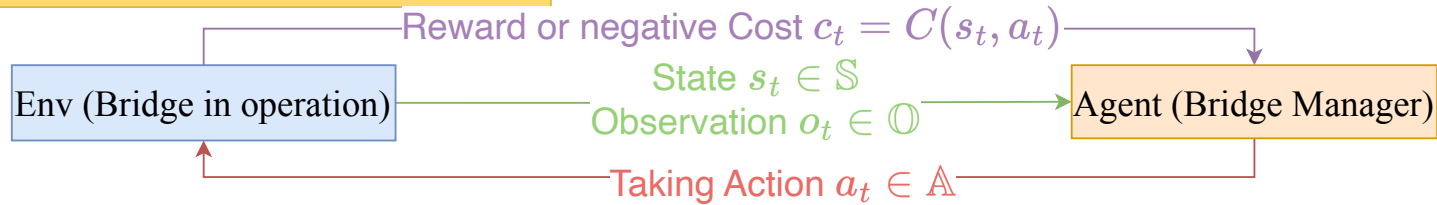


Structural Health Monitoring
Damage Identification:
Damage Existence?
Damage Localisation?
Damage Classification?
Damage Quantification?
Life Time Prognosis



Partially Observable Markov Decision Process

Modeling (POMDP) ($\mathcal{S}, \mathcal{O}, \mathcal{A}, \mathcal{T}, \mathcal{O}, \mathcal{R}, \gamma$)



The key is to minimize the expected total cost: $\pi^* = \arg \max_{\pi} Q^{\pi}(s_t, a_t); Q^*(s_t, a_t) = \max_{\pi} Q^{\pi}(s_t, a_t)$