

Random Interpolation Resize: A free image data augmentation method for object detection in industry

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论文链接: https://www.sciencedirect.com/science/article/pii/S0957417423008576

开源地址: https://github.com/wandahangFY/RIR.



1.论文动机: 从插值方式的角度进行数据增强 (详情请看原文)

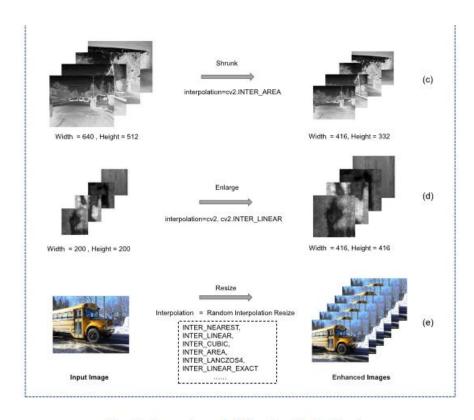


Fig. 2. Comparison of different methods of resize.

不使用RIR 方法:多个epoch迭代,每张图片只有一种插值方式 使用RIR 方法:多次迭代,每张图片可以有不同的插值方式

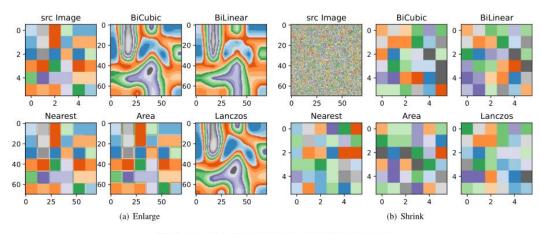


Fig. 3. Comparison of the results of various interpolation methods.

图3采用不同的插值方式对原图 (src Image) 进行放大或缩小 从图中可以看出,不同的插值方式之间是有差异的

2.原理:在训练阶段随机使用插值方式,在测试阶段采用默认的插值方式

训练阶段

使用RIR 方法

interp = random_interpolation_resize(

cv resize flags with weights=self.cv resize flags with weights)

使用RIR 方法

验证阶段

不使用RIR 方法

(采用常规的插值方式) (YOLOv8,11月之前有两种插值方式, 11月以后全部变成了双线性插值)

interp = cv2.INTER_LINEAR if (self.augment or r > 1) else cv2.INTER_AREA

3.添加教程

- 3.1 YOLOv8 添加步骤(已完成)
- 3.2 YOLOv5 添加步骤(TODO)
- 3.3 YOLOv7 添加步骤(已完成)
- 3.4 YOLOv5超参数进化添加步骤(TODO)

1. base.py 内部更改

init_.py
wandb
J.gitignore
pre-commit-con
CITATION.cff self.cv_resize_flags_with_weights = {cv2.INTER_NEAREST: 1 cv2.INTER_LINEAR: cv2.INTER_CUBIC: 1 cv2.INTER_AREA: 1 cv2.INTER_LANCZOS4: 1,
cv2.INTER_LINEAR_EXACT: 1

ultralytics/data/base.py 11月以后版本 (最新版) ultralytics/yolo/data/base.py 11月以前的版本

```
def random_interpolation_resize(cv_resize_flags_with_weights={cv2.INTER_NEAREST: 1.
                               cv2.INTER LINEAR: 1,
                               cv2.INTER_CUBIC: 1,
                              cv2.INTER_AREA: 1,
                               cv2.INTER LANCZOS4: 1
                               cv2.INTER_LINEAR_EXACT: 1
  return random.choices(list(cv_resize_flags_with_weights.keys())
             weights=list(cv_resize_flags_with_weights.values()), k=1)[0] # random.choices return a list
val flag=False
#1.3. 引入相关参数,可以修改各部分權重,默認全部1
self.use_rir = use_rir #
self.val_flag = val_flag
self.cv_resize_flags_with_weights = {cv2.INTER_NEAREST: 1,
                   cv2.INTER LINEAR: 1,
                   cv2.INTER CUBIC: 1.
                   cv2.INTER_AREA: 1.
                   cv2.INTER LANCZOS4: 1
                   cv2.INTER_LINEAR_EXACT: 1
    ------rir end------
```

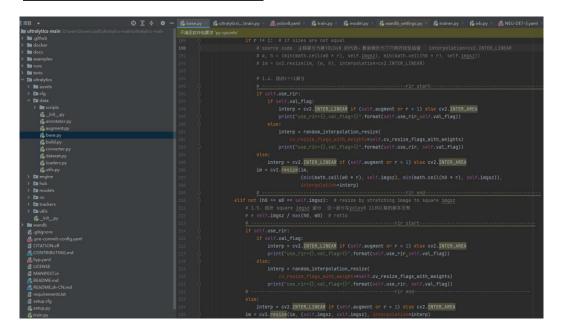
1. base.py 内部更改(11月以后)

1.4. 修改r!=1部分

1.5. 修改 square imgsz 部分 这一部分在YOLOv8 11月以前的版本没有

class BaseDataset(Dataset):

def load_image(self, i, rect_mode=True):

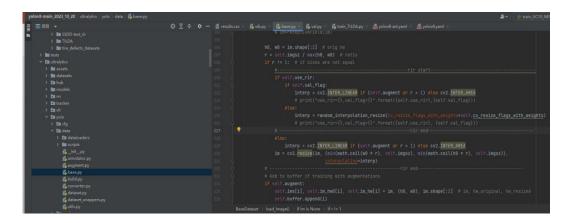


```
if rect_mode: # resize long side to imgsz while maintaining aspect ratio
  r = self.imgsz / max(h0, w0) # ratio
  if r!= 1: # if sizes are not equal
    # source code 注释部分为原YOLOv8 的代码,最新版改为了只用双线性插值
interpolation=cv2.INTER_LINEAR
    # im = cv2.resize(im, (w, h), interpolation=cv2.INTER_LINEAR)
    if self.use rir:
      if self.val_flag:
        interp = cv2.INTER_LINEAR if (self.augment or r > 1) else cv2.INTER_AREA
        print("use_rir={},val_flag={}".format(self.use_rir,self.val_flag))
        interp = random_interpolation_resize(
          cv_resize_flags_with_weights=self.cv_resize_flags_with_weights)
        print("use rir={},val flag={}".format(self.use rir, self.val flag))
      interp = cv2.INTER_LINEAR if (self.augment or r > 1) else cv2.INTER_AREA
    im = cv2.resize(im)
             (min(math.ceil(w0 * r), self.imgsz), min(math.ceil(h0 * r), self.imgsz)),
             interpolation=interp)
    # -----rir end------
elif not (h0 == w0 == self.imgsz): # resize by stretching image to square imgsz
   r = self.imgsz / max(h0, w0) # ratio
      ------rir start-----
  if self.use rir:
    if self.val_flag:
      interp = cv2.INTER_LINEAR if (self.augment or r > 1) else cv2.INTER_AREA
      print("use_rir={},val_flag={}".format(self.use_rir,self.val_flag))
      interp = random_interpolation_resize(
        cv_resize_flags_with_weights=self.cv_resize_flags_with_weights)
      print("use_rir={},val_flag={}".format(self.use_rir, self.val_flag))
  # -----rir end------
    interp = cv2.INTER_LINEAR if (self.augment or r > 1) else cv2.INTER_AREA
  im = cv2.resize(im, (self.imgsz, self.imgsz), interpolation=interp)
```

1. base.py 内部更改(11月以前的版本)

1.4. 修改r!=1部分

```
class BaseDataset(Dataset):
    def load_image(self, i, rect_mode=True):
```



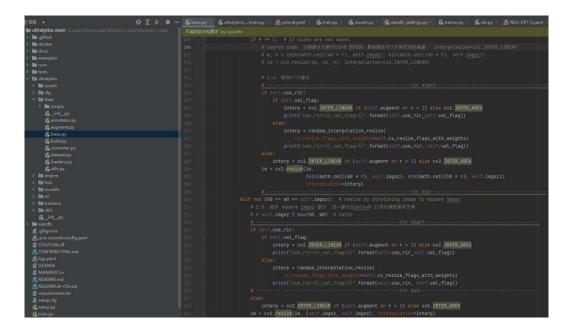
1. base.py 内部更改(11月以后的版本)



1.4. 修改r!=1部分

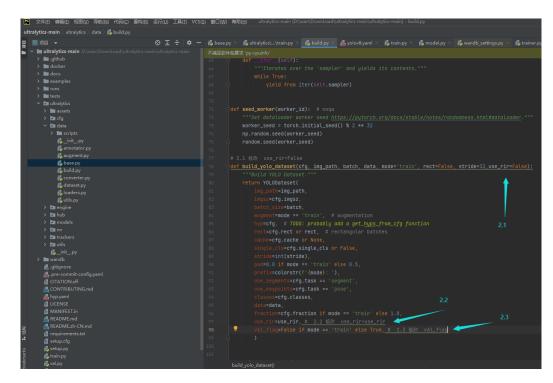
1.5. 修改 square imgsz 部分 这一部分在YOLOv8 11月以前的版本没有

def load_image(self, i, rect_mode=True):



```
if rect_mode: # resize long side to imgsz while maintaining aspect ratio
  r = self.imgsz / max(h0, w0) # ratio
    # source code 注释部分为原YOLOv8 的代码,最新版改为了只用双线性插值
interpolation=cv2.INTER_LINEAR
    # im = cv2.resize(im, (w, h), interpolation=cv2.INTER_LINEAR)
    if self.use rir:
      if self.val_flag:
        interp = cv2.INTER_LINEAR if (self.augment or r > 1) else cv2.INTER_AREA
        print("use_rir={},val_flag={}".format(self.use_rir,self.val_flag))
        interp = random_interpolation_resize(
          cv_resize_flags_with_weights=self.cv_resize_flags_with_weights)
        print("use_rir={},val_flag={}".format(self.use_rir, self.val_flag))
      interp = cv2.INTER_LINEAR if (self.augment or r > 1) else cv2.INTER_AREA
    im = cv2.resize(im)
             (min(math.ceil(w0 * r), self.imgsz), min(math.ceil(h0 * r), self.imgsz)),
             interpolation=interp)
    # -----rir end------
elif not (h0 == w0 == self.imgsz): # resize by stretching image to square imgsz
   r = self.imgsz / max(h0, w0) # ratio
       ------rir start-----
  if self.use rir:
    if self.val_flag:
      interp = cv2.INTER_LINEAR if (self.augment or r > 1) else cv2.INTER_AREA
      print("use_rir={},val_flag={}".format(self.use_rir,self.val_flag))
      interp = random_interpolation_resize(
        cv_resize_flags_with_weights=self.cv_resize_flags_with_weights)
      print("use_rir={},val_flag={}".format(self.use_rir, self.val_flag))
  # -----rir end-------
    interp = cv2.INTER_LINEAR if (self.augment or r > 1) else cv2.INTER_AREA
  im = cv2.resize(im, (self.imgsz, self.imgsz), interpolation=interp)
```

2. build_py build_yolo_dataset



ultralytics/data/build.py ultralytics/yolo/data/build.py

```
# 2.1 修改 use_rir=False
def build_yolo_dataset(cfg, img_path, batch, data, mode='train', rect=False, stride=32,use_rir=False):
   """Build YOLO Dataset.""
  return YOLODataset(
    img_path=img_path,
    imgsz=cfg.imgsz,
    batch size=batch,
    augment=mode == 'train', # augmentation
    hyp=cfg, # TODO: probably add a get_hyps_from_cfg function
    rect=cfg.rect or rect, # rectangular batches
    cache=cfg.cache or None,
    single_cls=cfg.single_cls or False,
    stride=int(stride),
    pad=0.0 if mode == 'train' else 0.5,
    prefix=colorstr(f'{mode}: '),
    use_segments=cfg.task == 'segment',
    use_keypoints=cfg.task == 'pose',
    classes=cfg.classes,
     data=data.
    fraction=cfg.fraction if mode == 'train' else 1.0,
    use_rir=use_rir, # 2.2 修改 use_rir=use_rir
    val_flag=False if mode == 'train' else True, # 2.3 修改 val_flag
```

ultralytics/models/yolo/detect/train.py

class DetectionTrainer(BaseTrainer):

传参

```
def build_dataset(self, img_path, mode='train', batch=None):

"""

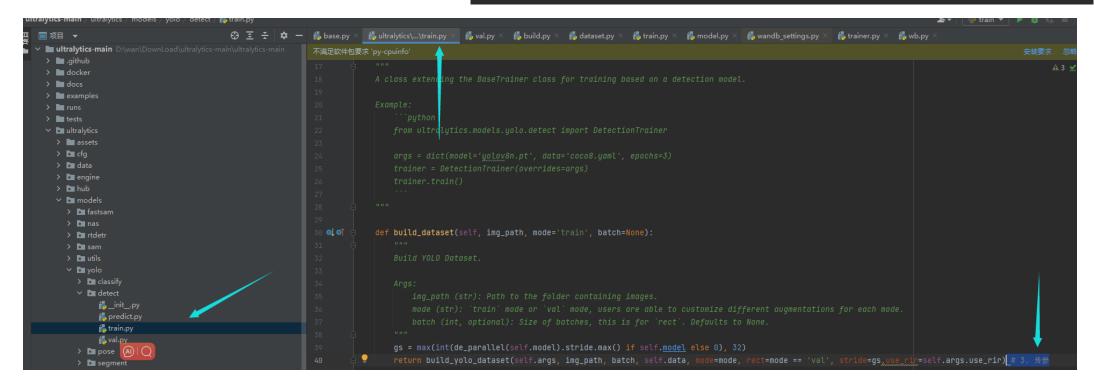
Build YOLO Dataset.

Args:
    img_path (str): Path to the folder containing images.
    mode (str): 'train' mode or 'val' mode, users are able to customize different augmentations for each mode.
    batch (int, optional): Size of batches, this is for 'rect'. Defaults to None.

"""

gs = max(int(de_parallel(self.model).stride.max() if self.model else 0), 32)
    return build_yolo_dataset(self.args, img_path, batch, self.data, mode=mode, rect=mode == 'val',

stride=gs,use_rir=self.args.use_rir) # 3. 传参
```



4. ultralytics/models/yolo/detect/val.py

传参

class DetectionValidator(BaseValidator):

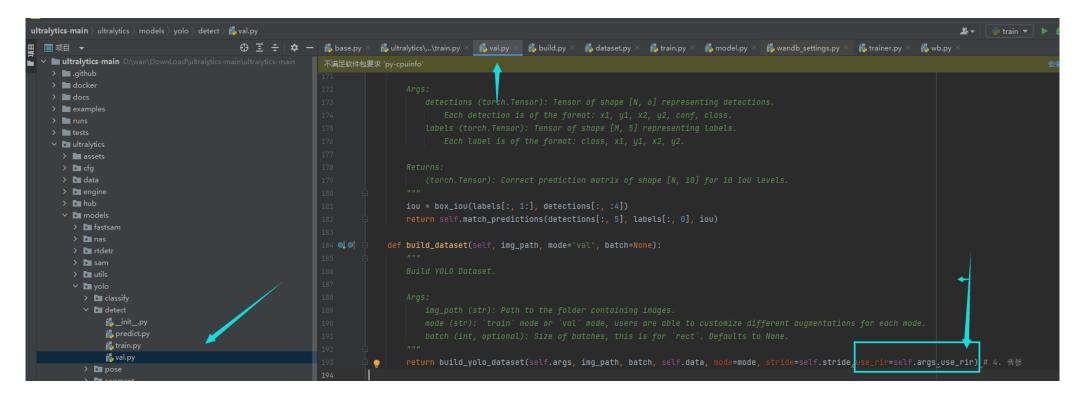
```
def build_dataset(self, img_path, mode='val', batch=None):
    """

Build YOLO Dataset.

Args:
    img_path (str): Path to the folder containing images.
    mode (str): `train` mode or `val` mode, users are able to customize different augmentations for each mode.
    batch (int, optional): Size of batches, this is for `rect`. Defaults to None.

""""

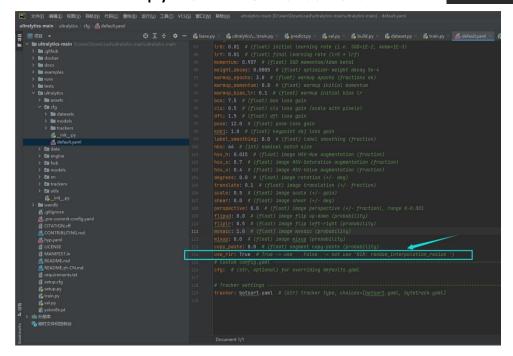
return build_yolo_dataset(self.args, img_path, batch, self.data, mode=mode,
stride=self.stride,use_rir=self.args.use_rir) # 4. 传参
```

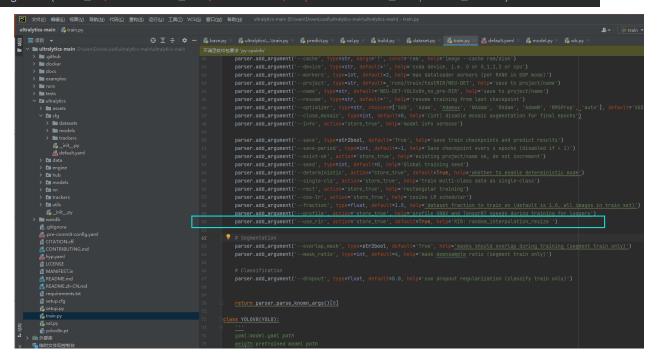


5. ultralytics/cfg/default.yaml 添加 train.py 添加(如果有的话)

use_rir: True # True -> use False -> not use 'RIR: random_interpolation_resize ')

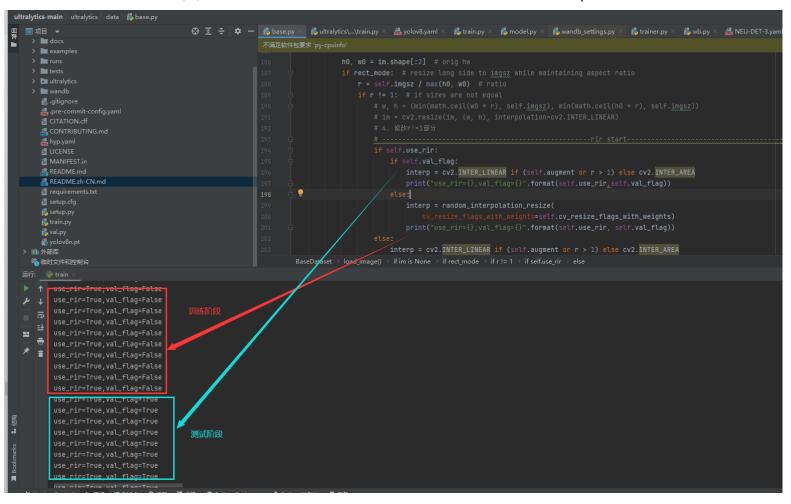
parser.add_argument('--use_rir', action='store_true', default=True, help='RIR: random_interpolation_resize ')





6.验证

- (1) 按照正常YOLOv8的训练步骤进行模型训练
- (2) 如果正确显示图中的内容,则表示添加成功,注释掉print,按原本的步骤运行即可



- 1.utils/dataset.py
- (1) 添加 random_interpolation_resize 函数
- (2) 更改load_image函数内的插值方式
- (3) 在 LoadImagesAndLabels 内添加use_rir和 val_flag __init__
- (4) 在 create_dataloader 内添加use_rir和 val_flag

2.train.py

- (5) 在两处create dataloader 内传入use rir和 val flag
- (6) 添加 顶层的 use_rir 参数

YOLOv7 项目地址(采用最新版进行演示, 2023.12.19)

https://github.com/WongKinYiu/yolov7

1.utils/dataset.py (1) 添加 random_interpolation_resize 函数

```
def random_interpolation_resize(cv_resize_flags_with_weights={cv2.INTER_NEAREST: 1,
                                           cv2.INTER LINEAR: 1.
                                           cv2.INTER_CUBIC: 1
                                           cv2.INTER_AREA: 1,
                                           cv2.INTER_LANCZOS4: 1
                                           cv2.INTER_LINEAR_EXACT: 1
  return random.choices(list(cv_resize_flags_with_weights.keys())
                  weights=list(cv_resize_flags_with_weights.values()), k=1)[0] # random.choices return a list
lov7-main 〉utils 〉 🐔 datasets.py
                                                                     return torcn.stack(img4, U), torcn.cat(lapel4, U), patn4, snapes4
 > 🖿 data
 > deploy
                                                              # 1. 添加 random_interpolation_resize 函数
 > 🖿 figure
                                                                f random_interpolation_resize(cv_resize_flags_with_weights={cv2.INTER_NEAREST: 1,
 > inference
 > 🖿 models
 > scripts
 > tools

✓ D utils

   > 🖿 wandb_logging
                                                                 return random.choices(list(cv_resize_flags_with_weights.keys()),
     __init_.py
     activations.py
     🚜 autoanchor.py
                                                              def load_image(self, index):
     🚜 google_utils.py
     🐔 loss.py
     🚜 metrics.py
     構 plots.py
                                                                     img = cv2.imread(path) # BGR
     torch_utils.py
                                                                     assert img is not None, 'Image Not Found ' + path
   🚜 .gitignore

₫ detect.py

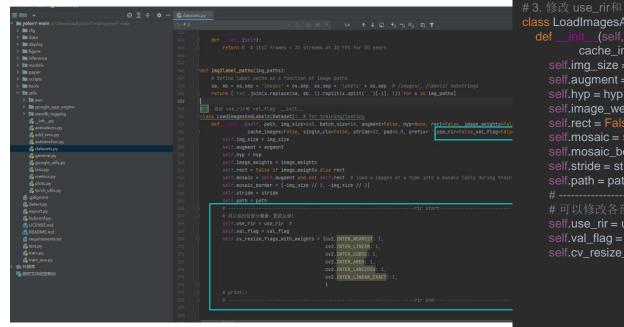
   🛵 export.py
```

1.utils/dataset.py (2) 更改load_image函数内的插值方式

```
> 🖿 data
figure
inference
 scripts
  > Da aws
  > google app engine
  > 🖿 wandb_logging
   🐔 _init_.py
                                                                          img = cv2.imread(path) # BGR
    autoanchor.pv
    datasets.pv
                                                                          r = self.img_size / max(h0, w0) # resize image to img_size
    🐍 general.py
    🚜 google_utils.py
                                                                                      interp = cv2.INTER_LINEAR if (self.augment or r > 1) else cv2.INTER_AREA
                                                                                 interp = cv2.INTER_LINEAR if (self.augment or r > 1) else cv2.INTER_AREA
76 临时文件和控制台
                                                                              img = cv2.resize(img, (int(w0 * r), int(h0 * r)), interpolation=interp)
```

```
# Ancillary functions -----
def load_image(self, index):
  img = self.imgs[index]
  if img is None: # not cached
    path = self.img_files[index]
    img = cv2.imread(path) # BGR
    assert img is not None, 'Image Not Found ' + path
    h0, w0 = img.shape[:2] # orighw
    r = self.img_size / max(h0, w0) # resize image to img_size
    if r!= 1: # always resize down, only resize up if training with augmentation
       #2. 更改插值方式
             # -----rir start-----ri
       if self.use rir:
         if self.val_flag:
           interp = cv2.INTER_LINEAR if (self.augment or r > 1) else cv2.INTER_AREA
            # print("use_rir={},val_flag={}".format({self.use_rir},{self.val_flag}))
           # logging.info(f'use_rir={self.use_rir} val_flag={self.val_flag}')
random_interpolation_resize(cv_resize_flags_with_weights=self.cv_resize_flags_with_weights)
            # print("use_rir={},val_flag={}".format({self.use_rir}, {self.val_flag}))
           # logging.info(f'use_rir={self.use_rir} val_flag={self.val_flag}')
         interp = cv2.INTER_LINEAR if (self.augment or r > 1) else cv2.INTER_AREA
       # -----rir end------
       img = cv2.resize(img, (int(w0 * r), int(h0 * r)), interpolation=interp)
    return img, (h0, w0), img.shape[:2] # img, hw_original, hw_resized
    return self.imgs[index], self.img_hw0[index], self.img_hw[index] # img, hw_original,
```

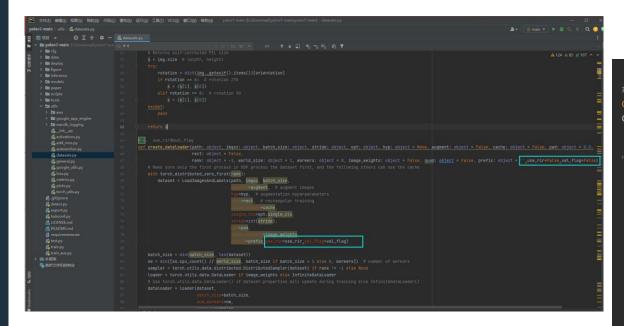
1.utils/dataset.py (3) 在 LoadImagesAndLabels 内添加use_rir和 val_flag __init_



```
class LoadImagesAndLabels(Dataset): # for training/testing
 def __init__(self, path, img_size=640, batch_size=16, augment=False, hyp=None, rect=False, image_weights=False,
         cache_images=False, single_cls=False, stride=32, pad=0.0, prefix=",use_rir=False,val_flag=False):
    self.img_size = img_size
     self.augment = augment
    self.hyp = hyp
    self.image_weights = image_weights
    self.rect = False if image_weights else rect
    self.mosaic = self.augment and not self.rect # load 4 images at a time into a mosaic (only during training)
    self.mosaic_border = [-img_size // 2, -img_size // 2]
    self.stride = stride
     self.path = path
    self.use rir = use rir #
    self.val_flag = val_flag
    self.cv_resize_flags_with_weights = {cv2.INTER_NEAREST: 1,
                           cv2.INTER_LINEAR: 1,
                          cv2.INTER_CUBIC: 1,
                          cv2.INTER_AREA: 1,
                          cv2.INTER_LANCZOS4: 1.
                           cv2.INTER LINEAR EXACT: 1
     # print()
```

1.utils/dataset.py (4) 在 create da

(4) 在 create_dataloader 内添加use_rir和 val_flag __init__



```
def create_dataloader(path: object, imgsz: object, batch_size: object, stride: object, opt: object, hyp: object = None, aug
cache: object = False, pad: object = 0.0,
             rect: object = False,
             rank: object = -1, world_size: object = 1, workers: object = 8, image_weights: object = False, quad: object
 .use_rir=False,val_flag=False) -> object:
  # Make sure only the first process in DDP process the dataset first, and the following others can use the cache
  with torch distributed zero first(rank):
     dataset = LoadImagesAndLabels(path, imgsz, batch_size,
                       augment=augment, # augment images
                       hyp=hyp, # augmentation hyperparameters
                       rect=rect, # rectangular training
                       cache images=cache,
                       single_cls=opt.single_cls,
                       stride=int(stride)
                       pad=pad,
                       image_weights=image_weights,
                       prefix=prefix,use_rir=use_rir,val_flag=val_flag)
  batch size = min(batch_size, len(dataset))
  nw = min([os.cpu_count() // world_size, batch_size if batch_size > 1 else 0, workers]) # number of workers
  sampler = torch.utils.data.distributed.DistributedSampler(dataset) if rank != -1 else None
  loader = torch.utils.data.DataLoader if image_weights else InfiniteDataLoader
  # Use torch.utils.data.DataLoader() if dataset.properties will update during training else InfiniteDataLoader()
  dataloader = loader(dataset
               batch_size=batch_size,
               sampler=sampler,
              collate_fn=LoadImagesAndLabels.collate_fn4 if quad else LoadImagesAndLabels.collate_fn)
  return dataloader, dataset
```

2.train.py

(5) 在两处create_dataloader 内传入use_rir和 val_flag

```
yolov7-main ) 👸 train.py
ৣ 🗏 项目 🕶 😌 🔄 💠 — 👸 datasets.py × 👸 train.py ×
   yolov7-main E:\Download\yolov7-ma Q+ create dataloader
    > 🖿 data
     > Dm models
     > paper
     > iii tools
     V D■ utils
      > 🖿 aws
                                   244 🖟 # 5. 两处调用create_dataloader 的地方给定 use_rir和val_flag(train: False, val:True)
         🚜 _init_.py
                                              dataloader, dataset = create_dataloader(train_path, imgsz, batch_size, gs, opt,
         activations.pv
                                                                                          hyp=hyp, augment=True, cache=opt.cache_images, rect=opt.rect, rank=rank,
world_size=opt.world_size, workers=opt.workers,
         ઢ add_nms.py
       🚜 .gitignore
                                              testloader = create_dataloader(test_path, imgsz_test, batch_size * 2, gs, opt, # testloader
                                                                                    world_size=opt.world_size, workers=opt.workers.
                                                                                    pad=0.5, prefix=colorstr('val: ')
      train.pv
    Ⅲ 外部库
```

2.train.py

(6) 添加 顶层的 use_rir 参数

parser.add_argument('--use_rir', type=bool, default=True, help='random_interpolation_resize') # 6. 项层调用

```
yolov7-main 〉 ち train.py
                 ⊕ 🔄 🛨 💠 — 👸 datasets.py × 👸 train.py ×
  ■ 项目 ▼
   yolov7-main E:\Download\yolov7-ma Q- create dataloader
   > 🖿 cfq
                                               parser.add_argument('--bucket', type=str, default='', help='qsutil bucket')
                                               parser.add_argument('--cache-images', action='store_true', help='cache images for faster training')
   > deploy
                                              parser.add_argument('--image-weights', action='store_true', help='use weighted image selection for training')
                                               parser.add_argument('--device', default='', help='cuda device, i.e. 0 or 0,1,2,3 or cpu')
                                               parser.add_argument('--multi-scale', action='store_true', help='vary img-size +/- 50%%')
                                               parser.add_argument('--single-cls', action='store_true', help='train multi-class data as single-class')
   > paper
   > scripts
                                               parser.add_argument('--adam', action='store_true', help='use torch.optim.Adam() optimizer')
   > tools
                                               parser.add_argument('--sync-bn', action='store_true', help='use SyncBatchNorm, only available in DDP mode')

✓ utils

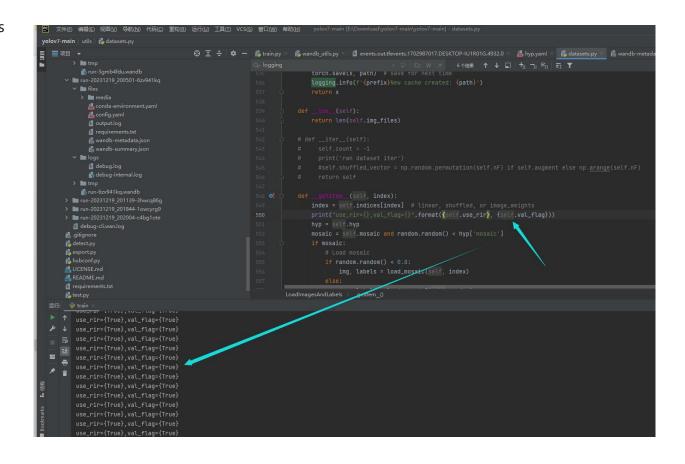
                                               parser.add_argument('--local_rank', type=int, default=-1, help='DDP parameter, do not modify')
                                               parser.add_argument('--workers', type=int, default=0, help='maximum number of dataloader workers')
     > google_app_engine
                                               parser.add_argument('--project', default='runs/train', help='save to project/name')
     > 🖿 wandb_logging
                                               parser.add_argument('--entity', default=None, help='W&B entity')
        🐔 __init__.py
                                               parser.add_argument('--name', default='exp', help='save to project/name')
        activations.py
                                               parser.add_argument('--exist-ok', action='store_true', help='existing project/name ok, do not increment')
        add_nms.py
                                               parser.add_argument('--quad', action='store_true', help='quad dataloader')
        autoanchor.py
                                               parser.add_argument('--linear-lr', action='store_true', help='linear LR')
        ื datasets.py
        💋 general.py
                                               parser.add_argument('--label-smoothing', type=float, default=0.0, help='Label smoothing epsilon')
        🛵 google_utils.py
                                               parser.add_argument('--upload_dataset', action='store_true', help='Upload dataset as W&B artifact table')
        ื loss.py
                                               parser.add_argument('--bbox_interval', type=int, default=-1, help='Set bounding-box image logging interval for W&B')
        # metrics.py
                                               parser.add_argument('--save_period', type=int, default=-1, help='Log model after every "save_period" epoch')
        💤 plots.py
                                               parser.add_argument('--artifact_alias', type=str, default="latest", help='version of dataset artifact to be used')
        torch_utils.py
                                               parser.add_argument('--freeze', nargs='+', type=int, default=[0], help='Freeze layers: backbone of yolov7=50, first3=0 1 2')
      gitignore.
                                               parser.add_argument('--v5-metric', action='store_true', help='assume maximum recall as 1.0 in AP calculation')
      🐍 detect.py
                                               parser.add_argument('--use_rir', type=bool, default=True, help='random_interpolation_resize') # 6. 顶层调用
      & export.py
                                               opt = parser.parse_args()
      # hubconf.py
     requirements.txt
      💤 test.py
      🚜 train.py
      train_aux.py
  > IIII 外部库
   % 临时文件和控制台
```

3.验证

- (1) 按照正常YOLOv7的训练步骤进行模型训练
- (2) 如果正确显示图中的内容,则表示添加成功,注释掉print,按原本的步骤运行即可

utils/dataset.py

LoadImagesAndLabels getitem



4.延伸创新点: (未做试验,欢迎继续探讨)

- (1) 分patch,每个patch采用不同的插值方式
- (2) 在训练和测试阶段均采用随机的插值方式
- (3) 在训练阶段最后n(n=30)个epoch
- (4) 其他可以类比的方法也可以采用 random, 试试效果

加工作量:

- (1) 搭配超参数进化,提升工作量(已在YOLOv5-6.1版本添加)
- (2) 搭配其他数据增强方法,组合成特定数据集(比如NEU-DET、GC10等)或者特定领域(工业检测、遥感领域等)的方法