

Intro to Self-Driving Cars Nanodegree

Weekly Outline

Week #	Material to Cover
First Day	<ul style="list-style-type: none"> Welcome Join Slack and Forums Support services available
Week 1	<ul style="list-style-type: none"> Orientation Bayesian Thinking: Introduction Project 0: Joy Ride
Week 2	<ul style="list-style-type: none"> Bayesian Thinking: <ul style="list-style-type: none"> Probability Conditional Probability Programming Probability in Python Bayes' Rule Programming Probability Distributions
Week 3	<ul style="list-style-type: none"> Bayesian Thinking: <ul style="list-style-type: none"> Gaussian Distribution Robot Localization Histogram Filter in Python Optional (and highly encouraged) Project: Histogram Filter in Python
Week 4	<ul style="list-style-type: none"> Working with Matrices: <ul style="list-style-type: none"> Section Overview Introduction to Kalman Filters State and Object Oriented Programming
Week 5	<ul style="list-style-type: none"> Working with Matrices: <ul style="list-style-type: none"> Matrices and Transformation of State
Week 6	<ul style="list-style-type: none"> Working with Matrices: <ul style="list-style-type: none"> Implement Matrix Class Project 1: Implement Matrix Class C++ Basics: <ul style="list-style-type: none"> C++ Getting Started C++ Vectors Practical C++
Week 7	<ul style="list-style-type: none"> C++ Basics <ul style="list-style-type: none"> C++ Object Oriented Programming Python and C++ Speed Translate Python to C++ Project 2: Translate Python to C++

Week 8	<ul style="list-style-type: none"> • Performance Programming in C++: <ul style="list-style-type: none"> ◦ C++ Intro to Optimization ◦ C++ Optimization Practice
Week 9	<ul style="list-style-type: none"> • Performance Programming in C++: <ul style="list-style-type: none"> ◦ Optimize Histogram Filter • Optional project: Optimize Histogram Filter • Navigating Data Structures: <ul style="list-style-type: none"> ◦ How to Solve Problems
Week 10	<ul style="list-style-type: none"> • Navigating Data Structures: <ul style="list-style-type: none"> ◦ Data Structures ◦ The Search Problem
Week 11	<ul style="list-style-type: none"> • Navigating Data Structures: <ul style="list-style-type: none"> ◦ Implement Route Planner • Project 3: Implement Route Planner • Vehicle Motion and Control: <ul style="list-style-type: none"> ◦ Odometers ◦ Speedometers and Derivatives
Week 12	<ul style="list-style-type: none"> • Vehicle Motion and Control: <ul style="list-style-type: none"> ◦ Accelerometers, Rate Gyros and Integrals ◦ Two Dimensional Robot Motion and Trigonometry
Week 13	<ul style="list-style-type: none"> • Vehicle Motion and Control: <ul style="list-style-type: none"> ◦ Reconstructing Trajectories from Sensor Data • Optional Project: Reconstructing Trajectories from Sensor Data
Week 14	<ul style="list-style-type: none"> • Computer Vision and Machine Learning: <ul style="list-style-type: none"> ◦ Computer Vision and Classification
Week 15	<ul style="list-style-type: none"> • Project 4: Traffic Light Classifier
Week 16	<ul style="list-style-type: none"> • Graduation: <ul style="list-style-type: none"> ◦ Congratulations! You've Finished! ◦ Guaranteed Admission into your next Nanodegree
End of Term	