

## APPENDIX A

This section provides the proofs of Theorem 1, Theorem 2, and Corollary 1, respectively.

**Proof of Theorem 1.** We prove this theorem by showing that the fixed point  $\tilde{s}$  presented in Theorem 1 satisfies the condition  $\frac{d\tilde{s}_i(t)}{dt} = 0$  for any  $i \geq 0$ .

Based on the expected drift  $F(s)$ , the fixed point condition  $\dot{s}_i(t) = 0$  implies that

$$\begin{aligned} \bar{\lambda}^{[M]} s_{i-1}^d - \theta x s_i + \eta y (1 - s_i)^b &= \\ \bar{\lambda}^{[M]} s_i^d - \theta x s_{i+1} + \eta y (1 - s_{i+1})^b, \quad \forall i \in \mathcal{B}. \end{aligned} \quad (41)$$

Accordingly, we define the parameter  $\gamma$  as follows

$$\gamma \triangleq \bar{\lambda}^{[M]} s_i^d - \theta x s_{i+1} + \eta y (1 - s_{i+1})^b, \quad \forall i \in \mathcal{B}. \quad (42)$$

Note that  $\gamma$  is a constant to be determined later. Rearranging the terms yields

$$\begin{aligned} s_i &= \left[ \frac{\theta x s_{i+1} - \eta y (1 - s_{i+1})^b + \gamma}{\bar{\lambda}^{[M]}} \right]^{\frac{1}{d}} \\ &= g(s_{i+1}; \gamma), \end{aligned} \quad (43)$$

where  $s_{B+1} = 0$  and function  $g(\cdot; \gamma)$  is defined in (20). Furthermore, the boundary condition in Definition 1 leads to

$$1 = g^{B+1}(0; \gamma). \quad (44)$$

This completes the proof of this theorem.  $\square$

**Proof of Theorem 2.** We will prove this theorem based on Lemma 3 and Lemma 4. Specifically, Proposition 1 indicates

$$\begin{aligned} \lim_{\delta \rightarrow \infty} L^{[N]|\delta]}(z, \Phi) &= \lim_{\delta \rightarrow \infty} \frac{1}{\delta} \int_0^\delta L^{[N]}(\tau, z, \Phi) d\tau \\ &\stackrel{(a)}{=} \lim_{\delta \rightarrow \infty} \frac{1}{\delta} \int_0^\delta \sum_{i=1}^\infty S_i^{[N]}(\tau) d\tau \\ &\stackrel{(b)}{=} \sum_{i=1}^\infty \lim_{\tau \rightarrow \infty} S_i^{[N]}(\tau), \end{aligned} \quad (45)$$

where the equality (a) follows from Proposition 1, and the equality (b) follows from the limiting probability of the state  $S_i^{[N]}(\tau)$ .

Based on Lemma 3 and Lemma 4, we have

$$\lim_{N \rightarrow \infty} \lim_{\tau \rightarrow \infty} S^{[N]}(\tau) = \tilde{s}. \quad (46)$$

Combining (45) and (46) leads to

$$\lim_{M \rightarrow \infty} \lim_{\delta \rightarrow \infty} \|L^{[N]|\delta]}(z, \Phi) - l(z, \bar{\lambda}^{[M]})\| = 0, \quad (47)$$

which completes the proof of this theorem.  $\square$

**Lemma 3.** For any initial condition  $s^0$ , the mean field model converges exponentially to the fixed point  $\tilde{s}$ , i.e.,

$$\lim_{\tau \rightarrow \infty} s(\tau) = \tilde{s}. \quad (48)$$

**Proof of Lemma 3.** Given the mean field model  $s(\tau)$  in Definition 1 and the fixed point  $\tilde{s}$  in (14), we define the following Lyapunov function

$$\psi(\tau) \triangleq \sum_{i=1}^\infty \omega_i |s_i(\tau) - \tilde{s}_i|, \quad (49)$$

where  $w_i \geq 1$  for any  $i \geq 0$ .

Next we prove this lemma based on Lemma 5 and Lemma 6, which are some intermediate results presented in Appendix C. We start with defining two bounds (i.e.,  $s^{High}$  and  $s^{Low}$ ) for the original initial point  $s^0$  as follows:

$$s_i^{High} \triangleq \max(s_i^0, \tilde{s}_i), \quad \forall i \geq 0, \quad (50a)$$

$$s_i^{Low} \triangleq \min(s_i^0, \tilde{s}_i), \quad \forall i \geq 0. \quad (50b)$$

Accordingly, we let  $s^{Low}(t)$  and  $s^{High}(t)$  denote the solution of the mean field model with the initial condition  $s^{Low}$  and  $s^{High}$ , respectively. Lemma 6 indicates that

$$s_i^{Low}(\tau) \leq s_i(s^0, \tau) \leq s_i^{High}(\tau), \quad \forall i \geq 1, \tau > 0. \quad (51)$$

Lemma 5 indicates that

$$\lim_{\tau \rightarrow \infty} s^{Low}(\tau) = \tilde{s}, \quad (52a)$$

$$\lim_{\tau \rightarrow \infty} s^{High}(\tau) = \tilde{s}. \quad (52b)$$

Based on the above discussions, Squeeze Theorem leads to

$$\lim_{\tau \rightarrow \infty} s(s^0, \tau) = \tilde{s}, \quad (53)$$

which completes the proof.  $\square$

**Lemma 4.** Given the initial condition  $s(0) = \lim_{N \rightarrow \infty} S^{[N]}(0)$  for the mean field model, the following is true

$$\lim_{N \rightarrow \infty} \sup_{\tau \in [0, \delta]} \|S^{[N]}(\tau) - s(\tau)\| = 0. \quad (54)$$

**Proof of Lemma 4.** We prove this lemma based on Kurtz's Theorem (e.g., [18], [30], [47], [48]), which consists of three conditions.

First,  $\{S^{[N]}(\tau) : \forall \tau\}$  is a density dependent Markov chain.

Second, we show that the state transition rate is bounded. Specifically,  $\mathcal{E} \triangleq \{\pm e^a : \forall a \geq 1\}$  denotes the state transition set. When the system stays in state  $S = (S_i \in [0, 1] : \forall i \geq 0)$ . The rates of the transitions  $e^a$  and  $-e^a$  are given by

$$\begin{aligned} \beta_{e^a}(S) &= \frac{\lambda}{\theta} (S_{a-1}^d - S_a^d), \\ \beta_{-e^a}(S) &= x (S_a - S_{a+1}) + \frac{\eta}{\theta} y [(1 - S_{a+1})^b - (1 - S_a)^b]. \end{aligned} \quad (55)$$

Note that  $S_a \in [0, 1]$  for any  $a \geq 1$ . Hence the rate at which an transition occurs is bounded by  $\frac{\lambda}{\theta} + x + \frac{\eta}{\theta} y$ .

Third, the expected drift is Lipschitz continuous with the parameter  $2(x + \frac{\lambda}{\theta}d + \frac{\eta}{\theta}yb)$  according to Lemma 7.

The three aspects above show that the three conditions of Kurtz's Theorem hold, which completes this proof.  $\square$

**Proof of Corollary 1.** When  $(d, b) = (1, 1)$ , the fixed point condition  $\dot{s}_i(t) = 0$  implies that

$$\begin{aligned} \bar{\lambda}^{[M]} s_{i-1} - \theta x s_i - \eta y s_i &= \\ \bar{\lambda}^{[M]} s_i - \theta x s_{i+1} - \eta y s_{i+1}, \quad \forall i \in \mathcal{B}. \end{aligned} \quad (56)$$

We suppose that the above equalities equals to  $v$ . That is,

$$v = \bar{\lambda}^{[M]} s_i - \theta x s_{i+1} - \eta y s_{i+1}, \quad \forall i \in \mathcal{B}. \quad (57)$$

Accordingly, we let  $\rho = \frac{\bar{\lambda}^{[M]}}{\theta x + \eta y}$  and obtain

$$s_{i+1} = \rho s_i - \frac{v}{\theta x + \eta y}. \quad (58)$$

Based on the definition of the density-based state, we have

$$\begin{cases} s_0 = 1, \\ s_i = \rho^i - \frac{v}{\theta x + \eta y} \sum_{k=0}^{i-1} \rho^k, \quad \forall i \in \{1, 2, \dots, B\}, \\ s_{B+1} = 0. \end{cases} \quad (59)$$

Therefore, the parameter  $v$  satisfies the following equality

$$\frac{v}{\theta x + \eta y} \sum_{k=0}^B \rho^k = \rho^{B+1}. \quad (60)$$

Now we calculate  $l(x, y, \bar{\lambda}^{[M]})$  as follows:

$$\begin{aligned} l(x, y, \bar{\lambda}^{[M]}) &= \sum_{i=1}^B \rho^i - \frac{v}{\theta x + \eta y} \sum_{i=1}^B \sum_{k=0}^{i-1} \rho^k \\ &\stackrel{(a)}{=} \sum_{i=1}^B \rho^i - \frac{\rho^{B+1}}{\sum_{k=0}^B \rho^k} \sum_{i=1}^B \sum_{k=0}^{i-1} \rho^k \\ &= \frac{1}{1 - \rho} + B - \frac{1 + B}{1 - \rho^{1+B}} \end{aligned} \quad (61)$$

where the equality (a) follows from (60). This completes the proof of this corollary.  $\square$

## APPENDIX B

This section provides the proofs of Lemma 1, Lemma 2, Theorem 3, Corollary 2, and Corollary 3.

**Proof of Lemma 2.** We define  $\Phi_t$  as follows

$$\Phi_t \triangleq \sum_{(i,j) \in \mathcal{A}} w_t(i, j), \quad (62)$$

and prove this lemma in the following three steps.

**Part I:** We derive a lower bound for  $\Phi_{T+1}$ . Specifically, for any tuple  $(i, j) \in \mathcal{A}$ , we have

$$\begin{aligned} \Phi_{T+1} &\stackrel{(a)}{\geq} w_{T+1}(i, j) \\ &\stackrel{(b)}{=} w_1(i, j) \prod_{t=1}^T (1 - \epsilon)^{c_t(i, j)} \\ &\stackrel{(c)}{=} (1 - \epsilon)^{\sum_{t=1}^T c_t(i, j)}, \end{aligned} \quad (63)$$

where the inequality (a) follows that  $w_{T+1}(i, j) \geq 0$  for any  $(i, j) \in \mathcal{A}$ , the equality (b) follows the updating policy (9), and the equality (c) follows that  $w_1(i, j) = 1$  for any  $(i, j) \in \mathcal{A}$ .

**Part II:** Based on the definition (62), we have

$$\begin{aligned} \frac{\Phi_{t+1}}{\Phi_t} &\stackrel{(a)}{=} \sum_{(i,j) \in \mathcal{A}} \frac{w_{t+1}(i, j)}{\Phi_t} \\ &\stackrel{(b)}{=} \sum_{(i,j) \in \mathcal{A}} \frac{w_t(i, j)}{\Phi_t} \cdot (1 - \epsilon)^{c_t(i, j)} \\ &\stackrel{(c)}{=} \sum_{(i,j) \in \mathcal{A}} p_t(i, j) \cdot (1 - \epsilon)^{c_t(i, j)} \\ &\stackrel{(d)}{\leq} \sum_{(i,j) \in \mathcal{A}} p_t(i, j) \cdot [1 - \epsilon \cdot c_t(i, j)] \\ &= 1 - \epsilon \cdot \sum_{(i,j) \in \mathcal{A}} c_t(i, j) p_t(i, j), \end{aligned} \quad (64)$$

where the equality (a) follows the definition of  $\Phi_{t+1}$  in (62), the equality (b) is due to (30), the inequality (c) is due to (28), and the inequality (d) follows that  $(1 - \epsilon)^x \leq 1 - \epsilon x$  for any  $x \in [0, 1]$ .

Taking the logarithm on both sides yields

$$\begin{aligned} \ln \left( \frac{\Phi_{t+1}}{\Phi_t} \right) &\leq \ln \left( 1 - \epsilon \cdot \sum_{(i,j) \in \mathcal{A}} c_t(i, j) p_t(i, j) \right) \\ &\stackrel{(a)}{\leq} -\epsilon \cdot \sum_{(i,j) \in \mathcal{A}} c_t(i, j) p_t(i, j) \\ &\stackrel{(b)}{=} -\epsilon \cdot \sum_{(i,j) \in \mathcal{A}} \frac{C_t(x_{[i]}, y_{[j]}, \bar{\lambda}_t^{[M]})}{\bar{C}} \cdot p_t(i, j) \\ &\stackrel{(c)}{=} -\frac{\epsilon}{\bar{C}} \cdot \mathbb{E} \left[ C_t(x_{[i]}, y_{[j]}, \bar{\lambda}_t^{[M]}) \middle| \mathbf{p}_t \right], \end{aligned} \quad (65)$$

where the inequality (a) follows that  $\ln(1 - x) + x \leq 0$  for any  $x \in [0, 1]$ , the equality (b) follows the definition of  $c_t(i, j)$ , and the equality (c) follows  $\sum_{(i,j) \in \mathcal{A}} p_t(i, j) = 1$ . Rearranging the terms leads to

$$\mathbb{E} \left[ C_t(x_{[i]}, y_{[j]}, \bar{\lambda}_t^{[M]}) \middle| \mathbf{p}_t \right] \leq \frac{\bar{C}}{\epsilon} (\ln \Phi_t - \ln \Phi_{t+1}). \quad (66)$$

Summing over the above inequality over  $t$ , we obtain

$$\begin{aligned} \sum_{t=1}^T \mathbb{E} \left[ C_t(x_{[i]}, y_{[j]}, \bar{\lambda}_t^{[M]}) \middle| \mathbf{p}_t \right] &\leq \frac{\bar{C}}{\epsilon} \sum_{t=1}^T (\ln \Phi_t - \ln \Phi_{t+1}) \\ &\stackrel{(a)}{=} \frac{\bar{C}}{\epsilon} [\ln \Phi_1 - \ln \Phi_{T+1}] \\ &\stackrel{(b)}{=} \frac{\bar{C}}{\epsilon} [\ln(A_x A_y) - \ln \Phi_{T+1}], \end{aligned} \quad (67)$$

where the equality (a) uses the telescoping technique, and the equality (b) is due to  $\Phi_1 = A_x A_y$ .

**Part III:** Combining Part I and Part II leads to

$$\begin{aligned} C_T^{\mathfrak{A}} &= \sum_{t=1}^T \mathbb{E} \left[ C_t(x_{[i]}, y_{[j]}, \bar{\lambda}_t^{[M]}) \middle| \mathbf{p}_t \right] \\ &\leq \frac{\bar{C}}{\epsilon} [\ln(A_x A_y) - \ln \Phi_{T+1}] \\ &\stackrel{(a)}{\leq} \frac{\bar{C}}{\epsilon} \left[ \ln(A_x A_y) + \ln \left( \frac{1}{1 - \epsilon} \right) \sum_{t=1}^T c_t(i, j) \right] \\ &\stackrel{(b)}{=} \frac{\bar{C}}{\epsilon} \left[ \ln(A_x A_y) + \ln \left( \frac{1}{1 - \epsilon} \right) \sum_{t=1}^T \frac{C_t(x_{[i]}, y_{[j]}, \bar{\lambda}_t^{[M]})}{\bar{C}} \right] \\ &= \frac{\bar{C} \ln(A_x A_y)}{\epsilon} + \frac{1}{\epsilon} \ln \left( \frac{1}{1 - \epsilon} \right) \sum_{t=1}^T C_t(x_{[i]}, y_{[j]}, \bar{\lambda}_t^{[M]}), \end{aligned} \quad (68)$$

where the inequality (a) substitutes (63), the equality (b) follows the definition (29). Therefore, for any tuple  $(i, j) \in \mathcal{A}$ , we have

$$C_T^{\mathfrak{A}} \leq \frac{\bar{C} \ln(A_x A_y)}{\epsilon} + \frac{1}{\epsilon} \ln \left( \frac{1}{1 - \epsilon} \right) \sum_{t=1}^T C_t(x_{[i]}, y_{[j]}, \lambda_t). \quad (69)$$

Next we derive an upper bound for  $\ln(A_x A_y)$

$$\begin{aligned}
& \ln(A_x A_y) \\
&= \ln \left[ \left( 1 + \left\lfloor \log_{1+\beta} \left( \frac{x_H}{x_L} \right) \right\rfloor \right) \left( 1 + \left\lfloor \log_{1+\beta} \left( \frac{y_H}{y_L} \right) \right\rfloor \right) \right] \\
&\leq \ln \left[ \left( 1 + \log_{1+\beta} \left( \frac{x_H}{x_L} \right) \right) \left( 1 + \log_{1+\beta} \left( \frac{y_H}{y_L} \right) \right) \right] \\
&= \ln \left( 1 + \frac{\ln(\frac{x_H}{x_L})}{\ln(1+\beta)} \right) + \ln \left( 1 + \frac{\ln(\frac{y_H}{y_L})}{\ln(1+\beta)} \right) \\
&= \frac{\epsilon}{\bar{C}} \Psi(\epsilon, \beta).
\end{aligned} \tag{70}$$

Therefore, for any  $(i, j) \in \mathcal{A}$  we obtain

$$C_T^{\mathcal{A}} \leq \Psi(\epsilon, \beta) + \frac{1}{\epsilon} \ln \left( \frac{1}{1-\epsilon} \right) \sum_{t=1}^T C_t(x_{[i]}, y_{[j]}, \bar{\lambda}_t^{[M]}). \tag{71}$$

This completes the proof of this lemma.  $\square$

**Proof of Lemma 1.** We prove this lemma by deriving an upper bound for  $C_t(x_{[i^*]}, y_{[j^*]}, \bar{\lambda}_t^{[M]})$  in two steps.

$$\begin{aligned}
& C_t(x_{[i^*]}, y_{[j^*]}, \bar{\lambda}_t^{[M]}) \\
&= G(l(x_{[i^*]}, y_{[j^*]}, \bar{\lambda}_t^{[M]})) + \xi_t^P \theta x_{[i^*]}^\sigma + \xi_t^A \eta y_{[j^*]}^\sigma \\
&\stackrel{(a)}{=} G(l(x_{[i^*]}, y_{[j^*]}, \bar{\lambda}_t^{[M]})) + \xi_t^P \theta [x_{[i^*-1]}(1+\beta)]^\sigma \\
&\quad + \xi_t^A \eta [y_{[j^*-1]}(1+\beta)]^\sigma \\
&\stackrel{(b)}{\leq} G(l(x_{[i^*]}, y_{[j^*]}, \bar{\lambda}_t^{[M]})) + \xi_t^P \theta (x^*)^\sigma (1+\beta)^\sigma \\
&\quad + \xi_t^A \eta (y^*)^\sigma (1+\beta)^\sigma \\
&\stackrel{(c)}{\leq} G(l(x^*, y^*, \bar{\lambda}_t^{[M]})) + \xi_t^P \theta (x^*)^\sigma (1+\beta)^\sigma \\
&\quad + \xi_t^A \eta (y^*)^\sigma (1+\beta)^\sigma \\
&\leq (1+\beta)^\sigma C_t(x^*, y^*, \bar{\lambda}_t^{[M]}),
\end{aligned} \tag{72}$$

where the equality (a) follows from the definitions in (26) and (27). The inequality (b) follows from the condition in (33). The inequality (c) follows that  $G(l(x, y, \bar{\lambda}^{[M]}))$  is decreasing in  $(x, y)$ . This completes the proof.  $\square$

**Proof of Theorem 3.** Combining Lemma 2 and Lemma 1 completes the proof of this theorem.  $\square$

**Proof of Corollary 2.** Note that the parameter setting in this corollary implies that  $\beta = \frac{\alpha}{2^{1+\sigma}} \in (0, 1]$ , since  $\alpha \in (0, 2^{\sigma+1}]$ . Hence we obtain

$$\begin{aligned}
\Psi(\epsilon, \beta) &= \frac{\bar{C}}{\epsilon} \left[ \ln \left( 1 + \frac{\ln(\frac{x_H}{x_L})}{\ln(1+\beta)} \right) + \ln \left( 1 + \frac{\ln(\frac{y_H}{y_L})}{\ln(1+\beta)} \right) \right] \\
&\stackrel{(a)}{\leq} \frac{\bar{C}}{\epsilon} \left[ \ln \left( \frac{\ln(\frac{2x_H}{x_L})}{\ln(1+\beta)} \right) + \ln \left( \frac{\ln(\frac{2y_H}{y_L})}{\ln(1+\beta)} \right) \right] \\
&\stackrel{(b)}{=} \frac{\bar{C}}{\epsilon} \left[ 2 \ln \left( \frac{1}{\ln(1+\beta)} \right) + J - 2 \ln(2) \right] \\
&\stackrel{(c)}{\leq} \frac{\bar{C}}{\epsilon} \left[ 2 \ln \left( \frac{1}{2} + \frac{1}{\beta} \right) + J - 2 \ln(2) \right] \\
&\stackrel{(d)}{\leq} \frac{\bar{C}}{\epsilon} \left[ 2 \ln \left( \frac{1}{\beta} \right) + J \right]
\end{aligned} \tag{73}$$

where the last inequality follows that  $1 \leq \frac{\ln(2)}{\ln(1+\beta)}$  for any  $\beta \in (0, 1)$ . The equality (b) follows from  $J = \ln \left( \ln \frac{2x_H}{x_L} \right) + \ln \left( \ln \frac{2y_H}{y_L} \right) + 2 \ln(2)$ . The inequality (c) follows that  $\frac{1}{\ln(1+\beta)} \leq$

$\frac{1}{2} + \frac{1}{\beta}$  for any  $\beta > 0$ . The inequality (d) follows from  $\frac{1}{2} \leq \frac{1}{\beta}$ . When  $(\epsilon, \beta) = (\frac{\alpha}{2^{1+\sigma}}, \frac{\alpha}{2^{1+\sigma}})$ , we obtain

$$\Psi \left( \frac{\alpha}{2^{1+\sigma}}, \frac{\alpha}{2^{1+\sigma}} \right) \leq \frac{2^{1+\sigma} \bar{C}}{\alpha} \left[ 2 \ln \left( \frac{2^{2+\sigma}}{\alpha} \right) + J \right] \leq \frac{\alpha C_T^*}{2^{1+\sigma}}, \tag{74}$$

where the last inequality is due to the condition (38).

Furthermore, we have

$$\begin{aligned}
\frac{1}{\epsilon} \ln \left( \frac{1}{1-\epsilon} \right) (1+\beta)^\sigma &\stackrel{(a)}{\leq} (1+\epsilon)(1+\beta)^\sigma \\
&\leq [1 + \max(\epsilon, \beta)]^{1+\sigma} \\
&\stackrel{(b)}{\leq} 1 + (2^{1+\sigma} - 1) \cdot \max(\epsilon, \beta) \\
&= 1 + \frac{2^{1+\sigma} - 1}{2^{1+\sigma}} \cdot \alpha,
\end{aligned} \tag{75}$$

where the inequality (a) follows that  $\frac{1}{\epsilon} \ln \left( \frac{1}{1-\epsilon} \right) \leq 1 + \epsilon$  for any  $\epsilon \in [0, \frac{2}{3}]$ , the inequality (b) follows that  $\max(\epsilon, \beta) \in [0, 1]$  and  $(1+v)^a \leq 1 + (2^a - 1)v$  for any  $v \in [0, 1]$ .

Combining the above two steps leads to

$$C_T^{\mathcal{A}} \leq \frac{\alpha C_T^*}{2^{1+\sigma}} + \left( 1 + \frac{2^{1+\sigma} - 1}{2^{1+\sigma}} \cdot \alpha \right) C_T^* = (1+\alpha) C_T^*, \tag{76}$$

which completes the proof of this corollary.  $\square$

**Proof of Corollary 3.** With the parameters  $\epsilon = \sqrt{\frac{\ln(T)}{T}}$  and  $\beta = \frac{1}{\sqrt{T}}$ , we have  $\epsilon > \beta$  and  $\beta \in (0, 1)$ .

First, based on the inequality (75) and  $\epsilon > \beta$ , we obtain

$$\frac{1}{\epsilon} \ln \left( \frac{1}{1-\epsilon} \right) (1+\beta)^\sigma \leq 1 + (2^{1+\sigma} - 1) \epsilon. \tag{77}$$

Second, based on (73) and  $\beta \in (0, 1)$ , we obtain

$$\Psi(\epsilon, \beta) \leq \frac{\bar{C}}{\epsilon} \left[ 2 \ln \left( \frac{1}{\beta} \right) + J \right]. \tag{78}$$

Combining the above two steps yields

$$C_T^{\mathcal{A}} \leq \frac{\bar{C}}{\epsilon} \left[ 2 \ln \left( \frac{1}{\beta} \right) + J \right] + [1 + (2^{1+\sigma} - 1) \epsilon] C_T^*. \tag{79}$$

Rearranging the terms leads to

$$\begin{aligned}
& C_T^{\mathcal{A}} - C_T^* \\
&\leq \frac{\bar{C}}{\epsilon} \left[ 2 \ln \left( \frac{1}{\beta} \right) + J \right] + (2^{1+\sigma} - 1) \epsilon C_T^* \\
&\stackrel{(a)}{=} \bar{C} \sqrt{\frac{T}{\ln(T)}} [\ln(T) + J] + (2^{1+\sigma} - 1) C_T^* \sqrt{\frac{\ln(T)}{T}} \\
&\stackrel{(b)}{\leq} \bar{C} \sqrt{\frac{T}{\ln(T)}} [\ln(T) + J] + (2^{1+\sigma} - 1) \bar{C} \sqrt{T \ln(T)} \\
&= \bar{C} \sqrt{T \ln(T)} \left[ 2^{1+\sigma} + \frac{J}{\ln(T)} \right]
\end{aligned} \tag{80}$$

where the equality (a) substitutes the parameters  $\epsilon = \sqrt{\frac{\ln(T)}{T}}$  and  $\beta = \frac{1}{\sqrt{T}}$ . The inequality (b) follows that  $C_T^* \leq T \bar{C}$ . This completes the proof.  $\square$

## APPENDIX C

This section introduces three lemmas used in Appendix A.

**Lemma 5.** *If  $s_i(0) \leq \tilde{s}_i$  (or  $s_i(0) \geq \tilde{s}_i$ ) for any  $i \geq 1$ , then  $\psi(\tau)$  converges exponentially to zero, i.e.,*

$$\lim_{\tau \rightarrow \infty} \psi(\tau) = 0. \quad (81)$$

**Proof of Lemma 5.** We prove this lemma by showing that there exist a constant  $\delta > 0$  such that we have

$$\frac{d\psi(t)}{dt} \leq \delta\psi(t), \quad (82)$$

which indicates  $\psi(t) \leq \psi(0) \exp(-\delta t)$ .

For notation simplicity, we define  $\varepsilon_i(t)$  as follows:

$$\varepsilon_i(t) \triangleq s_i(t) - \tilde{s}_i, \quad \forall i \geq 0. \quad (83)$$

The Lyapunov function defined in (49) can be expressed as  $\psi(t) = \sum_{i \geq 1} w_i |\varepsilon_i(t)|$ . Next we show how to prove (82) for the case  $\varepsilon_i(t) \leq 0$  for any  $i \geq 1$ . In this case, we have  $\psi(t) = -\sum_{i \geq 1} w_i \varepsilon_i(t)$ . For notation simplicity, we define function  $H(\cdot)$  as follows:

$$H(\varepsilon_i(t), \tilde{s}_i, d) \triangleq [\varepsilon_i(t) + \tilde{s}_i]^d - \tilde{s}_i^d. \quad (84)$$

Based on the mean field model, we have

$$\begin{aligned} \frac{d\varepsilon(t)}{dt} &= \frac{ds_i(t)}{dt} \\ &= \frac{\lambda}{\theta} [s_{i-1}^d(t) - s_i^d(t)] - x[s_i(t) - s_{i+1}(t)] \\ &\quad - \frac{\eta}{\theta} \cdot y \left( [1 - s_{i+1}(t)]^b - [1 - s_i(t)]^b \right) \\ &\stackrel{(a)}{=} \frac{\lambda}{\theta} \left( [\varepsilon_{i-1}(t) + \tilde{s}_{i-1}]^d - [\varepsilon_i(t) + \tilde{s}_i]^d \right) \\ &\quad - x[\varepsilon_i(t) + \tilde{s}_i - \varepsilon_{i+1}(t) - \tilde{s}_{i+1}] \\ &\quad - \frac{\eta}{\theta} \cdot y \left( [1 - \varepsilon_{i+1}(t) - \tilde{s}_{i+1}]^b - [1 - \varepsilon_i(t) - \tilde{s}_i]^b \right) \\ &\stackrel{(b)}{=} \frac{\lambda}{\theta} [H(\varepsilon_{i-1}(t), \tilde{s}_{i-1}, d) + \tilde{s}_{i-1}^d - H(\varepsilon_i(t), \tilde{s}_i, d) - \tilde{s}_i^d] \\ &\quad - x[\varepsilon_i(t) - \varepsilon_{i+1}(t) + \tilde{s}_i - \tilde{s}_{i+1}] \\ &\quad - \frac{\eta}{\theta} \cdot y \left[ H(-\varepsilon_{i+1}(t), 1 - \tilde{s}_{i+1}, b) + (1 - \tilde{s}_{i+1})^b \right. \\ &\quad \left. - H(-\varepsilon_i(t), 1 - \tilde{s}_i, b) - (1 - \tilde{s}_i)^b \right] \\ &\stackrel{(c)}{=} \frac{\lambda}{\theta} [H(\varepsilon_{i-1}(t), \tilde{s}_{i-1}, d) - H(\varepsilon_i(t), \tilde{s}_i, d)] \\ &\quad - x[\varepsilon_i(t) - \varepsilon_{i+1}(t)] \\ &\quad - \frac{\eta}{\theta} \cdot y \left[ H(-\varepsilon_{i+1}(t), 1 - \tilde{s}_{i+1}, b) \right. \\ &\quad \left. - H(-\varepsilon_i(t), 1 - \tilde{s}_i, b) \right], \end{aligned} \quad (85)$$

where the equality (a) follows from (83), the equality (b) follows from the definition in (84), and the equality (c) follows that  $\tilde{s}$  is the fixed point. Therefore, the terms of  $\frac{d\psi(t)}{dt}$  involving  $\varepsilon_i(t)$  is given by (86). We want to choose  $w_{i-1}$ ,  $w_i$ , and  $w_{i+1}$  such that (87) holds. Note that (87) is equivalent to (88). Moreover,  $\frac{H(\varepsilon_i(t), \tilde{s}_i, d)}{-\varepsilon_i(t)}$  and  $\frac{H(-\varepsilon_i(t), 1 - \tilde{s}_i, b)}{-\varepsilon_i(t)}$  is decreasing

in  $\varepsilon_i(t) \in [-1, 1]$ . Therefore, the condition (88) holds if we ensure

$$w_{i-1} \leq w_i \leq w_{i+1}, \quad (89a)$$

$$\delta w_i \leq \frac{w_{i+1} - w_i}{\theta} \lambda \frac{H(1, \tilde{s}_i, d)}{-1} \quad (89b)$$

$$+ \frac{w_i - w_{i-1}}{\theta} \left( \theta x + \eta y \frac{H(-1, 1 - \tilde{s}_i, b)}{-1} \right). \quad (89c)$$

Moreover, (89c) is equivalent to

$$\begin{aligned} &w_{i+1} \\ &\leq w_i + \frac{(w_i - w_{i-1}) \left[ x - \frac{\eta}{\theta} y H(-1, 1 - \tilde{s}_i, b) \right] - \delta w_i}{\frac{\lambda}{\theta} H(1, \tilde{s}_i, d)} \\ &= w_i + \frac{(w_i - w_{i-1}) \left( x + \frac{\eta}{\theta} y \left[ (1 - \tilde{s}_i)^d - (-\tilde{s}_i)^d \right] \right) - \delta w_i}{\frac{\lambda}{\theta} \left[ (1 + \tilde{s}_i)^d - \tilde{s}_i^d \right]}. \end{aligned} \quad (90)$$

We are able to choose an increasing sequence  $\{w_i\}$  (starting with  $w_0 = 0$  and  $w_1 = 1$ ) and  $\delta$  that satisfy (90).  $\square$

**Lemma 6.** *Let  $s^*(\tau)$  and  $s(\tau)$  denote the solutions of the mean field model with initial conditions  $s^*(0)$  and  $s(0)$ , respectively. If  $s_i^*(0) \leq s_i(0)$  for any  $i \geq 1$ , then we have*

$$s_i^*(\tau) \leq s_i(\tau), \quad \forall i \geq 1 \text{ and } \tau > 0. \quad (91)$$

**Proof of Lemma 6.** We prove this lemma by contradiction. Given the initial conditions satisfying  $s_i^*(0) < s_i(0)$  for any  $i \geq 1$ , we suppose that the inequality is first violated at  $t'$ . That is, there exists  $k \geq 1$  such that  $s_k^*(t') = s_k(t')$ . Then we consider the following cases.

1) Case  $s_{k-1}^*(t') < s_{k-1}(t')$  and  $s_{k+1}^*(t') < s_{k+1}(t')$ . In this case, we have

$$\begin{aligned} &\frac{ds_k^*(t')}{dt} - \frac{ds_k(t')}{dt} \\ &= \frac{\lambda}{\theta} \left( [s_{k-1}^*(t')]^d - [s_k^*(t')]^d \right) - x(s_k^*(t') - s_{k+1}^*(t')) \\ &\quad - \frac{\eta}{\theta} y \left( [1 - s_{k+1}^*(t')]^b - [1 - s_k^*(t')]^b \right) \\ &\quad - \frac{\lambda}{\theta} \left( [s_{k-1}(t')]^d - [s_k(t')]^d \right) + x(s_k(t') - s_{k+1}(t')) \\ &\quad + \frac{\eta}{\theta} y \left( [1 - s_{k+1}(t')]^b - [1 - s_k(t')]^b \right) \\ &= \frac{\lambda}{\theta} \left( [s_{k-1}^*(t')]^d - [s_{k-1}(t')]^d \right) - x(s_{k+1}(t') - s_{k+1}^*(t')) \\ &\quad - \frac{\eta}{\theta} y \left( [1 - s_{k+1}^*(t')]^b - [1 - s_{k+1}(t')]^b \right) \\ &\leq 0. \end{aligned} \quad (92)$$

Therefore, there exists  $t'' < t'$  such that

$$\begin{cases} s_k^*(t'') - s_k(t'') < 0, \\ \frac{ds_k^*(t)}{dt} - \frac{ds_k(t)}{dt} < 0, \quad \forall t \in [t'', t'], \end{cases} \quad (93)$$

which leads to

$$\begin{aligned} &s_k^*(t') - s_k(t') \\ &= s_k^*(t'') - s_k(t'') + \int_{t''}^{t'} \left[ \frac{ds_k^*(t)}{dt} - \frac{ds_k(t)}{dt} \right] dt < 0. \end{aligned} \quad (94)$$

This contradicts with  $s_k^*(t') = s_k(t')$ .

$$\begin{aligned}
& -\frac{w_i}{\theta} \left( -\lambda H(\varepsilon_i(t), \tilde{s}_i, d) - \theta x \varepsilon_i(t) + \eta y H(-\varepsilon_i(t), 1 - \tilde{s}_i, b) \right) - \frac{w_{i+1}}{\theta} \lambda H(\varepsilon_i(t), \tilde{s}_i, d) \\
& - \frac{w_{i-1}}{\theta} \left( \theta x \varepsilon_i(t) - \eta y H(-\varepsilon_i(t), 1 - \tilde{s}_i, b) \right) \\
& = \frac{w_i - w_{i+1}}{\theta} \lambda H(\varepsilon_i(t), \tilde{s}_i, d) + \frac{w_i - w_{i-1}}{\theta} \left( \theta x \varepsilon_i(t) - \eta y H(-\varepsilon_i(t), 1 - \tilde{s}_i, b) \right).
\end{aligned} \tag{86}$$

$$\frac{w_i - w_{i+1}}{\theta} \lambda H(\varepsilon_i(t), \tilde{s}_i, d) + \frac{w_i - w_{i-1}}{\theta} \left( \theta x \varepsilon_i(t) - \eta y H(-\varepsilon_i(t), 1 - \tilde{s}_i, b) \right) \leq \delta w_i \varepsilon_i(t). \tag{87}$$

$$\frac{w_{i+1} - w_i}{\theta} \lambda \frac{H(\varepsilon_i(t), \tilde{s}_i, d)}{-\varepsilon_i(t)} + \frac{w_i - w_{i-1}}{\theta} \left( \theta x + \eta y \frac{H(-\varepsilon_i(t), 1 - \tilde{s}_i, b)}{-\varepsilon_i(t)} \right) \geq \delta w_i. \tag{88}$$

2) Case  $s_{k-1}^*(t') = s_{k-1}(t')$  and  $s_{k+1}^*(t') < s_{k+1}(t')$ . Similar contradiction still exists.

3) Case  $s_{k-1}^*(t') < s_{k-1}(t')$  and  $s_{k+1}^*(t') = s_{k+1}(t')$ . Similar contradiction still exists.

4) Case  $s_{k-1}^*(t') = s_{k-1}(t')$  and  $s_{k+1}^*(t') = s_{k+1}(t')$ . If  $s_{k-2}^*(t') < s_{k-2}(t')$  or  $s_{k+2}^*(t') < s_{k+2}(t')$ , then similar contradiction still exists.

The discussions complete this proof.  $\square$

**Lemma 7.** The expected drift  $\mathbf{F}(\cdot)$  defined in Proposition 2 satisfies

$$\|\mathbf{F}(\mathbf{s}) - \mathbf{F}(\mathbf{r})\| \leq 2 \left( x + \frac{\lambda}{\theta} d + \frac{\eta}{\theta} y b \right) \|\mathbf{s} - \mathbf{r}\|. \tag{95}$$

**Proof of Lemma 7.** Based on the definition (14), we obtain

$$\begin{aligned}
\|\mathbf{F}(\mathbf{s}) - \mathbf{F}(\mathbf{r})\| &= \sum_{i=0}^{\infty} \left\| \frac{\lambda}{\theta} (s_{i-1}^d - s_i^d) - x(s_i - s_{i+1}) \right. \\
&\quad - \frac{\eta}{\theta} y [(1 - s_{i+1})^b - (1 - s_i)^b] \\
&\quad - \frac{\lambda}{\theta} (r_{i-1}^d - r_i^d) + x(r_i - r_{i+1}) \\
&\quad \left. + \frac{\eta}{\theta} y [(1 - r_{i+1})^b - (1 - r_i)^b] \right\| \\
&= \sum_{i=0}^{\infty} \left\| \frac{\lambda}{\theta} (s_{i-1}^d - r_{i-1}^d) - \frac{\lambda}{\theta} (s_i^d - r_i^d) \right. \\
&\quad - x(s_i - r_i) + x(s_{i+1} - r_{i+1}) \\
&\quad - \frac{\eta}{\theta} y [(1 - s_{i+1})^b - (1 - r_{i+1})^b] \\
&\quad \left. + \frac{\eta}{\theta} y [(1 - s_i)^b - (1 - r_i)^b] \right\| \\
&\leq \sum_{i=0}^{\infty} 2x \|s_i - r_i\| + \frac{2\lambda}{\theta} \|s_i^d - r_i^d\| \\
&\quad + \frac{\eta}{\theta} 2y \|(1 - s_i)^b - (1 - r_i)^b\|,
\end{aligned} \tag{96}$$

where the last inequality follows from the triangle inequality. Furthermore, we have

$$\|s_i^d - r_i^d\| = \left\| (s_i - r_i) \sum_{k=0}^{d-1} s_i^k \cdot r_i^{d-1-k} \right\| \leq \|s_i - r_i\| d, \tag{97}$$

and

$$\begin{aligned}
& \left\| (1 - s_i)^b - (1 - r_i)^b \right\| \\
&= \left\| (r_i - s_i) \sum_{k=0}^{b-1} (1 - s_i)^k \cdot (1 - r_i)^{b-1-k} \right\| \\
&\leq \|r_i - s_i\| b,
\end{aligned} \tag{98}$$

where the inequalities follows that  $0 \leq s_i, r_i \leq 1$ . Therefore, we have

$$\begin{aligned}
\|\mathbf{F}(\mathbf{s}) - \mathbf{F}(\mathbf{r})\| &\leq 2 \left( x + \frac{\lambda}{\theta} d + \frac{\eta}{\theta} y b \right) \sum_{i=0}^{\infty} \|s_i - r_i\| \\
&= 2 \left( x + \frac{\lambda}{\theta} d + \frac{\eta}{\theta} y b \right) \|\mathbf{s} - \mathbf{r}\|.
\end{aligned} \tag{99}$$

This completes the proof.  $\square$