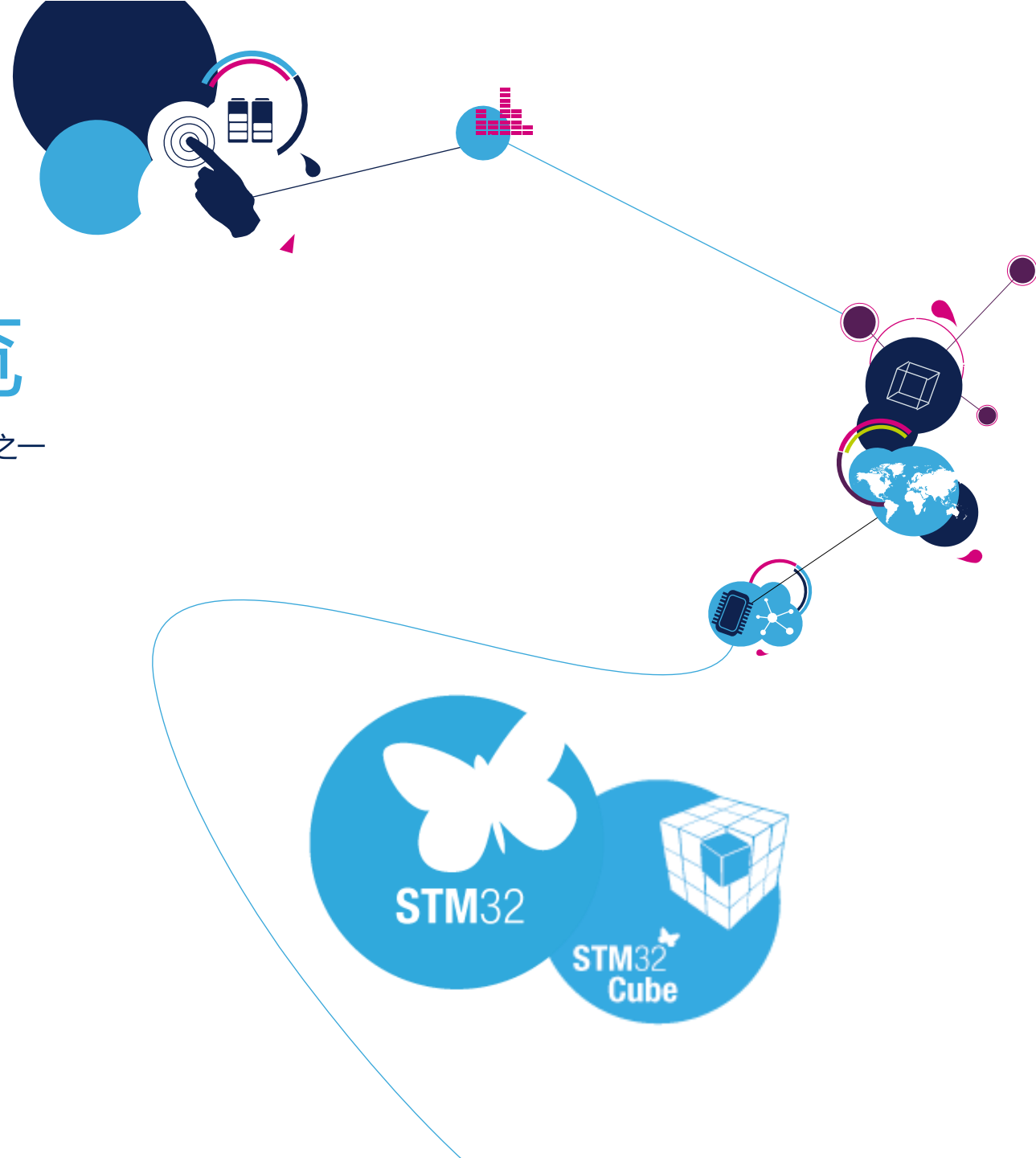


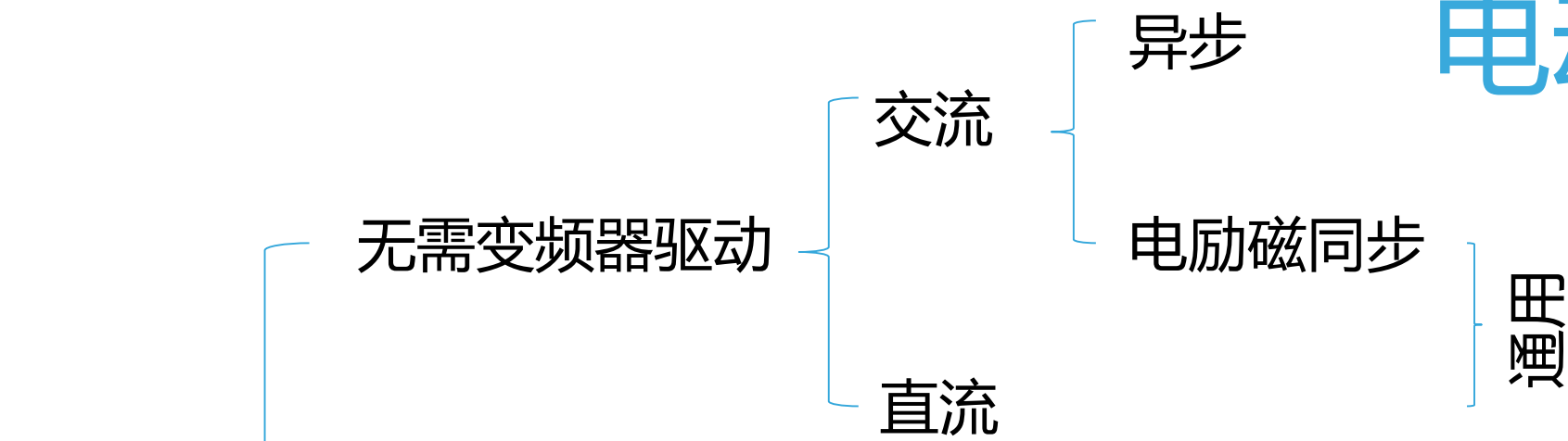
ST MC SDK 5.x 概览

STM32电动机控制应用系列讲座之一



电动机分类

2



● ST 有基于STM8,STM32的样例程序

● ● ST MC SDK

电压频率比为常数方式

电动机

需变频器驱动

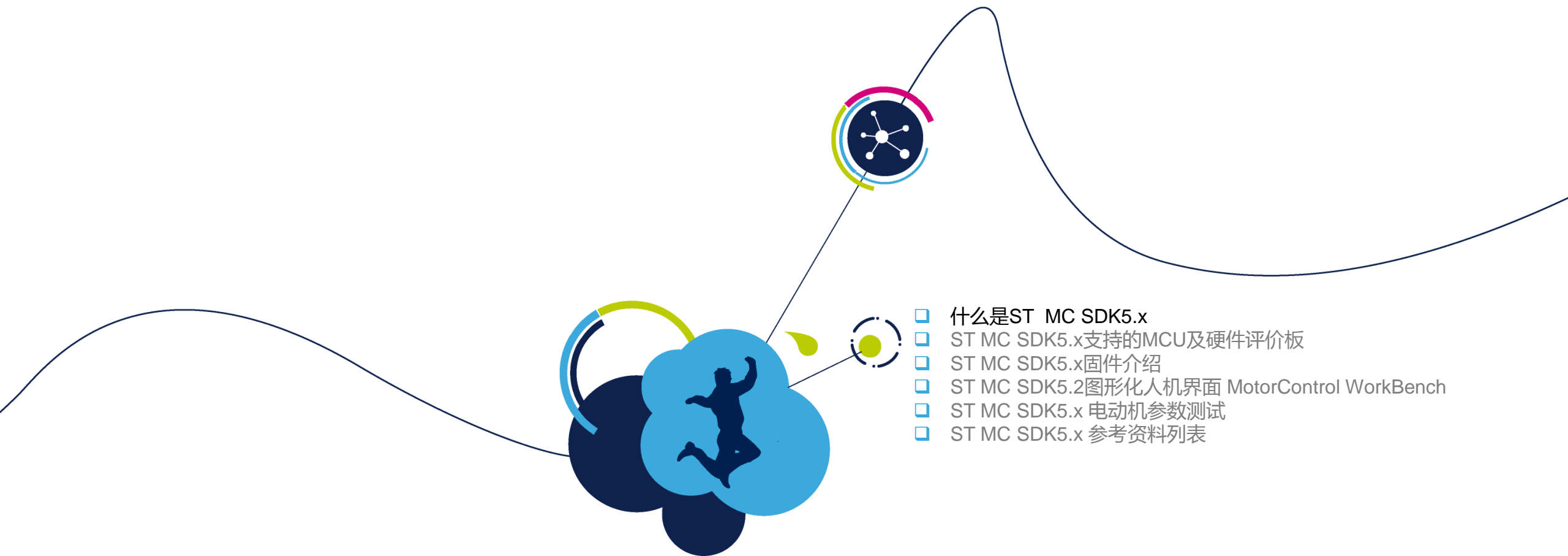
| 电动机 \ 控制方法 | 相控 | V/f | 矢量控制 | 方波控制 | 斩控 | 微步 |
|-------------|----|-----|------|------|----|----|
| 异步 | ● | ● | ● | | | |
| 永磁同步 (直流无刷) | | ● | ● ● | ● | | |
| 开关磁阻 | | | ● | | | ● |
| 步进 | | | | | | ● |
| 直流 | | | | | ● | |

方波控制与矢量控制方法对比

3

| 控制方法 | 方波控制 | 矢量控制 <small>正弦波</small> |
|-------|------|-------------------------|
| 固件复杂度 | 😊 | 😞 |
| 硬件需求 | 😊 | 😞 |
| 换相退磁 | 😞 | 😊 |
| 转矩波动 | 😞 | 😊 |
| 低速噪音 | 😞 | 😊 |
| 启动转矩 | 😞 | 😊 |
| 电动机效率 | 😞 | 😊 |

- 什么是ST MC SDK5.x
- ST MC SDK5.x支持的MCU及硬件评价板
- ST MC SDK5.x固件介绍
- ST MC SDK5.2图形化人机界面 MotorControl WorkBench
- ST MC SDK5.x 电动机参数测试
- ST MC SDK5.x 参考资料列表



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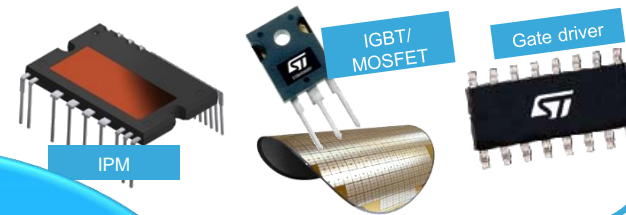
什么是ST MC SDK5.x

3-Phase Motors PMSM FOC SDK

用于电动机控制的MCU包
括8位机与32位机



功率器件
IPM / 分立器件



ST MC Workbench



人机图形化界面
完整的用户设置和实时
监控功能

Motor Control
Ecosystem

硬件Demo板



ST MC SDK

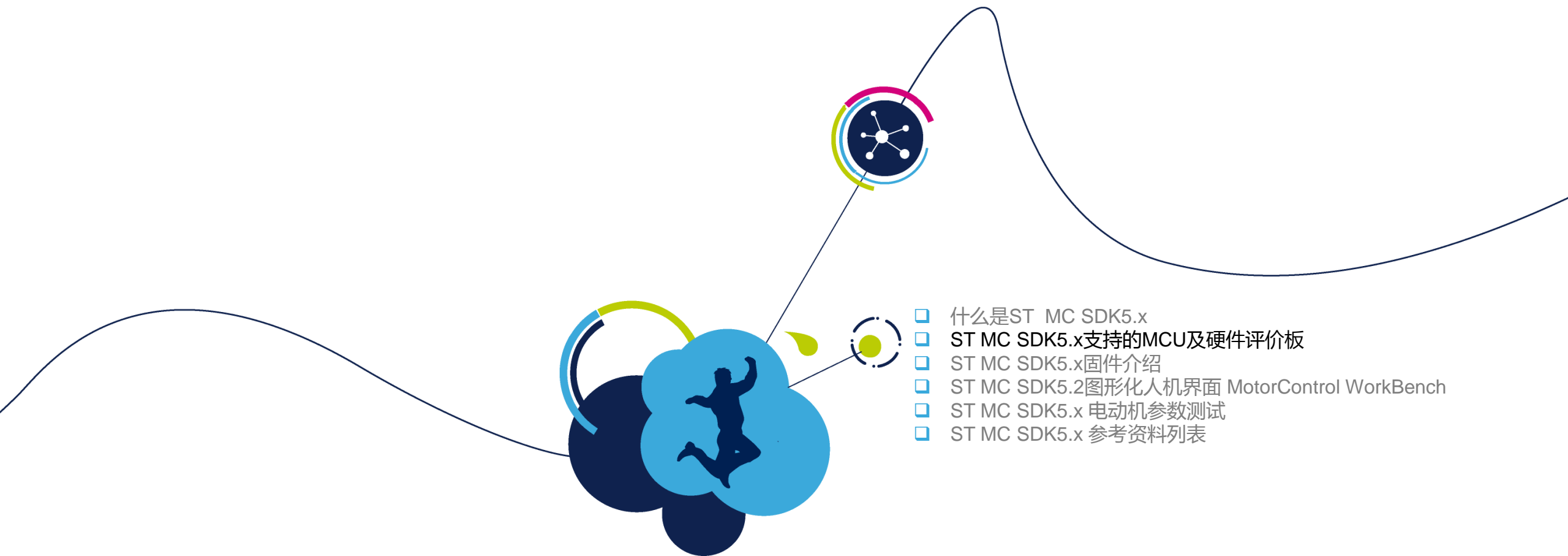
固件库

完善的FOC算法库适用于多
种应用领域



ST MC SDK 分为

- ☐ X-CUBE-MCSDK
- ☐ X-CUBE-MCSDK-FUL



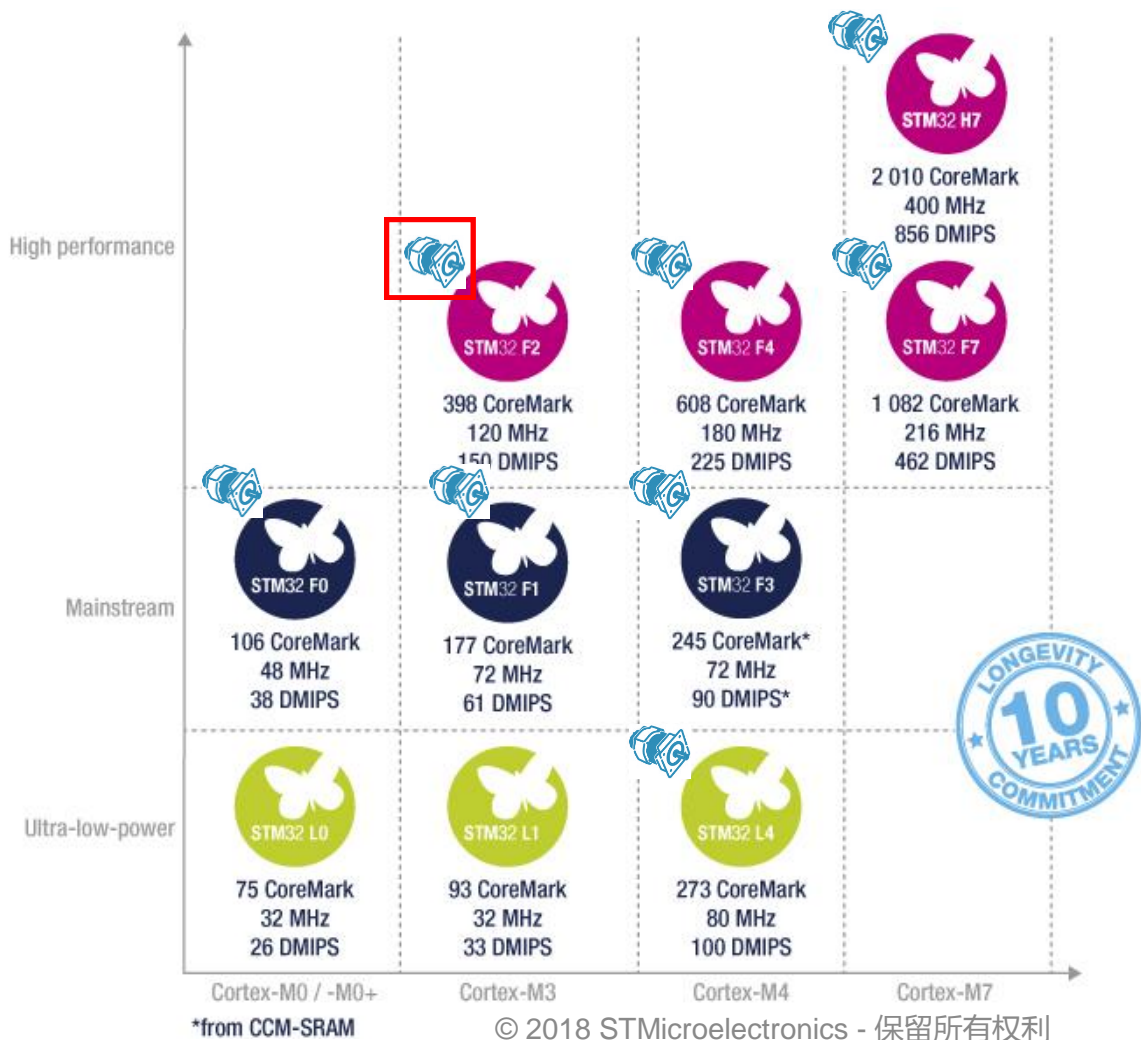
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ST MC SDK5.x支持的MCU及硬件评价板

适用于电动机控制的STM32产品线

8

8 个系列/超过31条产品线



ST MC SDK5.2支持的芯片型号

9



| | |
|---------|---|
| STM32F7 | STM32F746ZG / STM32F769NI |
| STM32F4 | STM32F417IG / STM32F415ZG / STM32F407IG / STM32F446ZE / STM32F446RE / STM32F401RE |
| STM32L4 | STM32L452RE / STM32L476RG |
| STM32F3 | STM32F302VB / STM32F302VC / STM32F302R8 / STM32F303VB / STM32F303VC / STM32F303ZE / STM32F303VE / STM32F303RE |
| STM32F1 | STM32F103 High, Medium and Low Densities |
| STM32F0 | STM32F030RC / STM32F030R8 / STM32F031C6 / STM32F051R8 / STM32F051C8 / STM32F072VB / STM32F072RB |

ST MC SDK5.2支持的功能 (1/2)

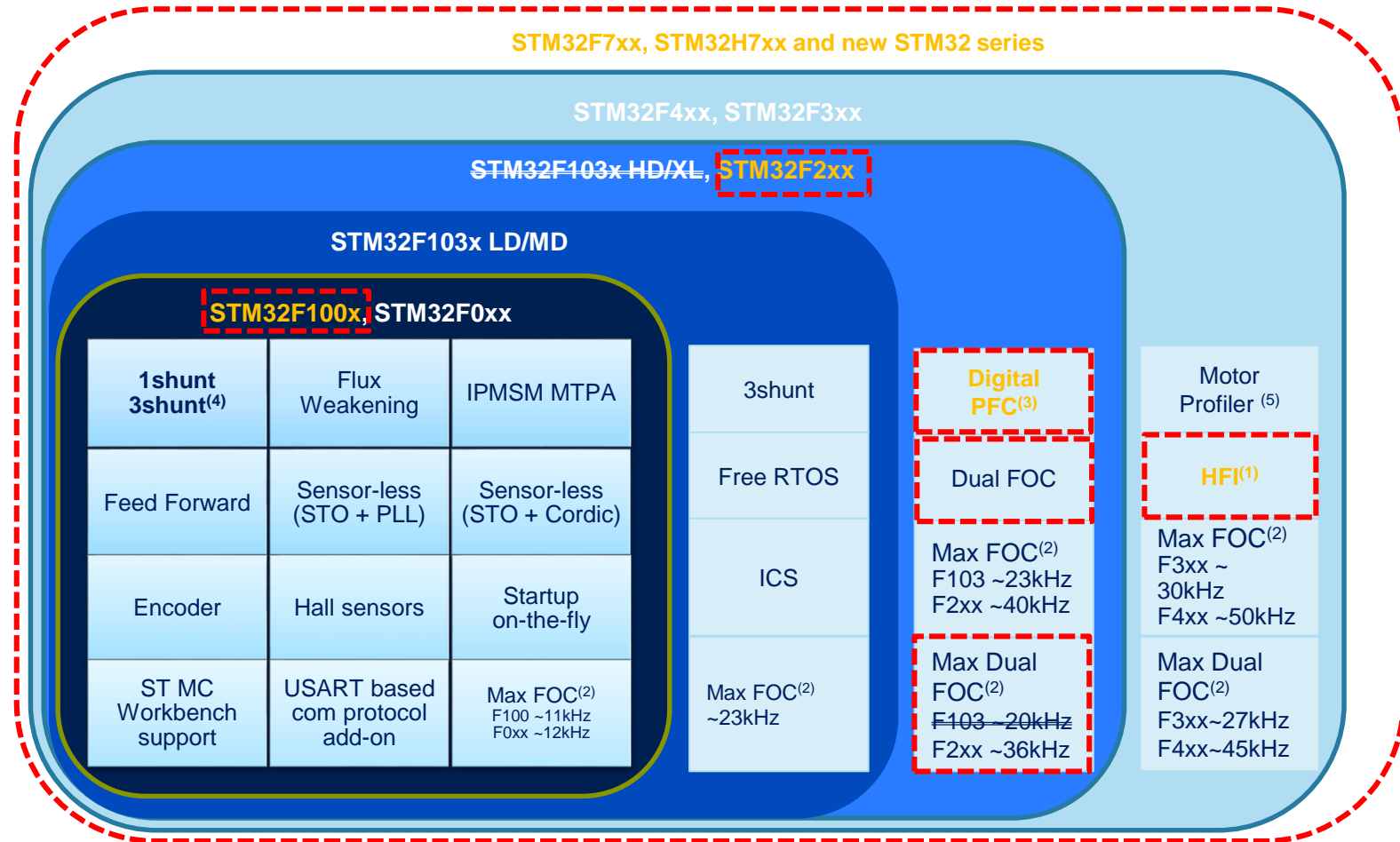
10



| STM32 series | F0 | F1 | F3 | F4 | F7 (v5.3) | L4 (V5.3) |
|---|----|----|----|----|-----------|-----------|
| • 1 Shunt单电阻检测 | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| • 3 Shunt三电阻检测 | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| • Hall sensors/Encoder • 霍尔传感器/增量编码器 | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| • ICS 电流传感器 | x | ✓ | ✓ | ✓ | ✓ | ✓ |
| • Flux weakening • 弱磁控制 | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| • MTPA 单位电流最大力矩输出 算法 | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| • Sensorless (PLL / Cordic)无 位置传感 (锁相环/Cordic算 法) | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| • Feed Forward电流前馈 | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| • Single FOC单电机控制 | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| • Dual FOC双电机控制 | x | x | ✓ | ✓ | ✓/x | x |

ST MC SDK5.2支持的功能 (2/2)

11



适用于电动机控制的ST硬件评价板

12

覆盖不同的需求

控制板 + 功率板
Control + Power

Eval/Nucleo + Power/Expansion

Control stages



MC Connector



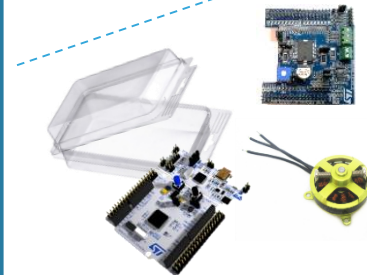
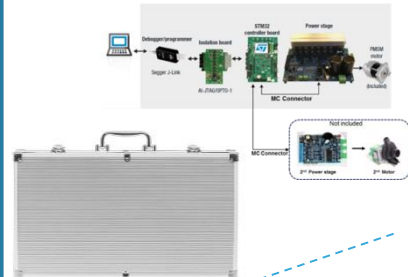
Power stages



控-驱一体板
(Complete Drive)



电动机开发套件
Motor Control Kit



另外，还有一类Inverters未在上面列出。

硬件评价板- 电动机控制套件

Motor Control kit

13

P-NUCLEO-IHM001 or 2

- 廉价套件
 - 用于评价利用STM32驱动电压最高不超过36[V]，电流不超过1.4[A]的小电动机。
- 套件组成:
 - NUCLEO-F302R8
 - Microcontroller board based on STM32F302
 - X-NUCLEO-IHM07M1
 - Driver board based on L6230
 - BLDC Motor



EVB到Nucleo的转换板

X-NUCLEO-IHM09M1

14



- ❑ ST 电机控制板标准接口(34 pins) 兼容主流ST功率驱动板
- ❑ 支持 STM32 Nucleo板, 用 ST morpho connectors
- ❑ 兼容ST 6步控制和FOC控制对应的硬件
- ❑ 具备DAC/GPIO的调试功能
- ❑ 所有连接点都有相应的测试点
- ❑ LED 可用于故障显示
- ❑ 板上有电位器(可用于速度指令给定)

MC SDK5.2支持的 Control Boards (1/4)

15

| Control Boards Type | Family | MCU | Board | Description |
|---------------------|--------|--------|--------------------------------------|---|
| NUCLEO | F0 | F030R8 | <u>NUCLEO-F030R8</u> | STM32 Nucleo-64 development board with STM32F030R8 MCU, supports Arduino and ST morpho connectivity |
| | | F072RB | <u>NUCLEO-F072RB</u> | STM32 Nucleo-64 development board with STM32F072RB MCU, supports Arduino and ST morpho connectivity |
| | F1 | F103RB | <u>NUCLEO-F103RB</u> | STM32 Nucleo-64 development board with STM32F103RB MCU, supports Arduino and ST morpho connectivity |

MC SDK5.2支持的 Control Boards (2/4)

16

| Control Boards Type | Family | MCU | Board | Description |
|---------------------|--------|--------|--------------------------------------|---|
| NUCLEO | F3 | F302R8 | <u>NUCLEO-F302R8</u> | STM32 Nucleo-64 development board with STM32F302R8 MCU, supports Arduino and ST morpho connectivity |
| | | F303RE | <u>NUCLEO-F303RE</u> | STM32 Nucleo-64 development board with STM32F303RE MCU, supports Arduino and ST morpho connectivity |
| | F4 | F446RE | <u>NUCLEO-F446RE</u> | STM32 Nucleo-64 development board with STM32F446RE MCU, supports Arduino and ST morpho connectivity |
| | | F401RE | <u>NUCLEO-F401RE</u> | STM32 Nucleo-64 development board with STM32F401RE MCU, supports Arduino and ST morpho connectivity |

MC SDK5.2支持的 Control Boards (3/4)

17

| Control Boards Type | Family | MCU | Board | Description |
|---------------------|--------|--------|--------------------------------------|---|
| NUCLEO | F7 | F746ZG | <u>NUCLEO-F746ZG</u> | STM32 Nucleo-144 development board with STM32F746ZG MCU, supports Arduino, ST Zio and morpho connectivity |
| | L4 | L453RE | <u>NUCLEO-L452RE</u> | STM32 Nucleo-64 development board with STM32L452RE MCU, supports Arduino and ST morpho connectivity |
| | | L476RG | <u>NUCLEO-L476RG</u> | STM32 Nucleo-64 development board with STM32L476RG MCU, supports Arduino and ST morpho connectivity |

MC SDK5.2支持的 Control Boards (4/4)

18

| Control Boards Type | Family | MCU | Board | Description |
|---------------------|--------|---------|---------------------------------|---|
| EVB | F0 | F072VB | STM32072B-EVAL | Evaluation board with STM32F072VB MCU |
| | F3 | F303VE | STM32303E-EVAL | Evaluation board with STM32F303VE MCU |
| | F4 | F407IG | STM3240G-EVAL | Evaluation board with STM32F407IG MCU |
| | | F417IG | STM3241G-EVAL | Evaluation board with STM32F417IG MCU |
| | | F446ZE | STM32446E-EVAL | Evaluation board with STM32F446ZE MCU |
| | | F415ZGT | STEVAL-IHM039V1 | Dual motor drive control stage based on the STM32F415ZG microcontroller |
| | F7 | F769NI | STM32F769I-EVAL | Evaluation board with STM32F769NI MCU |
| | L4 | L476ZG | STM32L476G-EVAL | Evaluation board with STM32L476ZG MCU |

MC SDK5.2支持的 Power Boards (1/3)

19

| Interface | Board | Description |
|-----------|--|---|
| EVB | <u>STEVAL-IHM023V3</u> | 1 kW 3-phase motor control evaluation board featuring L6390 drivers and STGP10H60DF IGBT |
| | <u>STEVAL-IHM028V2</u> | 2 kW 3-phase motor control evaluation board featuring the STGIPS20C60 IGBT intelligent power module |
| | <u>STEVAL-IHM045V1</u> | 3-phase high voltage inverter power board for FOC based on the STGIPN3H60A (SLLIMM™-nano) |
| | <u>STEVAL-IPM10F</u> | Motor control power board based on the SLLIMM™ 2nd series of IGBT IPMs |
| | <u>STEVAL-IPM15B</u> | Motor control power board based on the SLLIMM™ 2nd series of IGBT IPMs |
| | <u>STEVAL-IPM05F</u> | 500 W motor control power board based on STGIF5CH60TS-L SLLIMM™ 2nd series IPM |
| | <u>STEVAL-IPM08B</u> | 800 W motor control power board based on STGIB8CH60TS-L SLLIMM™ 2nd series IPM |
| | <u>STEVAL-IPM10B</u> | 1200 W motor control power board based on STGIB10CH60TS-L SLLIMM™ 2nd series IPM |
| | <u>STEVAL-IPM10F</u> | 1000 W motor control power board based on STGIF10CH60TS-L SLLIMM™ 2nd series IPM |

MC SDK5.2支持的 Power Boards (2/3)

20

| Interface | Board | Description |
|-----------|---------------------------------------|--|
| EVB | <u>STEVAL-IPM15B</u> | 1500 W motor control power board based on STGIB15CH60TS-L SLLIMM™ 2nd series IPM |
| | <u>STEVAL-IPMNG3Q</u> | 300 W motor control power board based on STGIPQ3H60T-H SLLIMM™-nano IPM |
| | <u>STEVAL-IPMNG5Q</u> | 450 W motor control power board based on STGIPQ5C60T-HZ SLLIMM™-nano IPM |
| | <u>STEVAL-IPMNG8Q</u> | 600 W motor control power board based on STGIPQ8C60T-HZ SLLIMM™-nano IPM |
| | <u>STEVAL-IPMNM1N</u> | 60 W motor control power board based on STIPN1M50T-H SLLIMM™ nano IPM MOSFET |
| | <u>STEVAL-IPMNM2N</u> | 100 W motor control power board based on STIPN2M50T-H SLLIMM™ nano IPM MOSFET |

MC SDK5.2支持的 Power Boards (3/3)

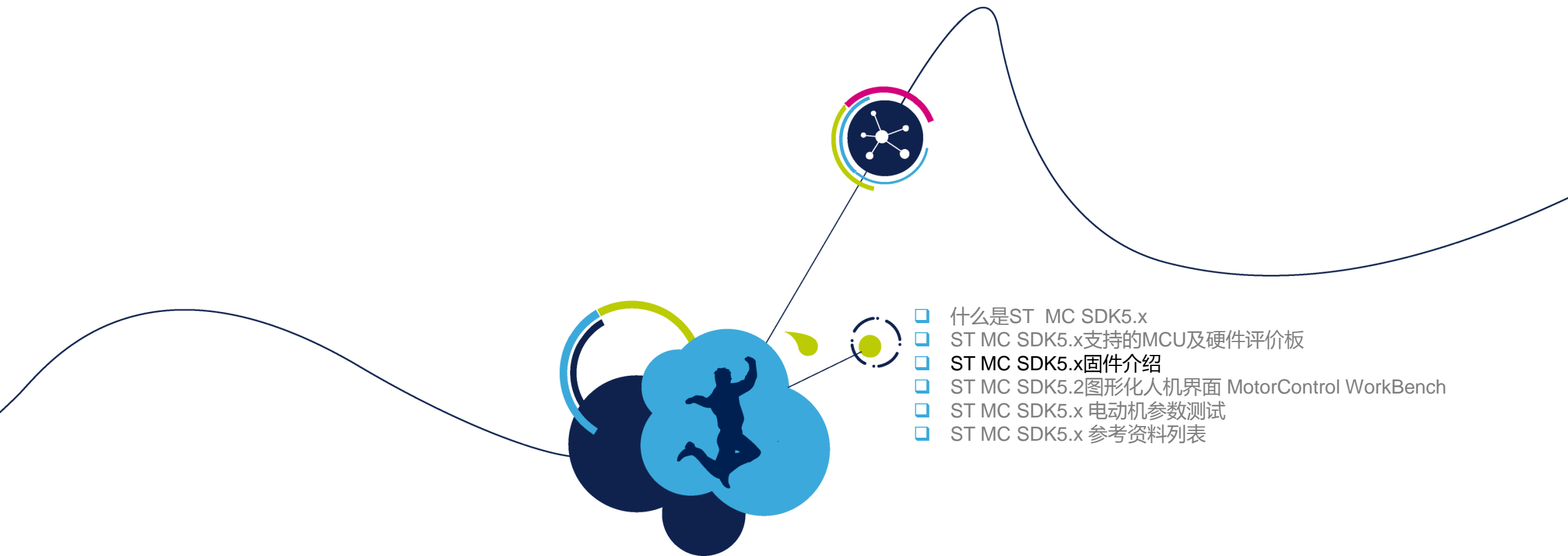
21

| Interface | Board | Description |
|-----------|---|---|
| NUCLEO | <u>X-NUCLEO-IHM07M1</u> | Three-phase brushless DC motor driver expansion board based on L6230 for STM32 Nucleo |
| | <u>X-NUCLEO-IHM08M1</u> | Low-Voltage BLDC motor driver expansion board based on STL220N6F7 for STM32 Nucleo |
| | <u>X-NUCLEO-IHM11M1</u> | Low voltage three-phase brushless DC motor driver expansion board based on STSPIN230 for STM32 Nucleo |

MC SDK5.2支持的 Inverters

22

| Family | MCU | Board | Description |
|--------|--------|--|---|
| / | STM32 | STEVAL_SPIN3201 | STSPIN32F0 Advanced BLDC controller with embedded STM32 MCU evaluation board(3-shunt) |
| / | STM32 | STEVAL_SPIN3202 | STSPIN32F0A advanced 3-phase BLDC driver with embedded STM32 MCU single shunt evaluation board (1-shunt) |
| F1 | F103RC | STEVAL_IHM034V2 | Dual motor control and PFC demonstration board featuring the STM32F103 and STGIPS20C60 |
| F3 | F303RE | X-NUCLEO-IHM16 + NUCLEO-F303RE | Bundle used for EMEA workshop X-NUCLEO-IHM16 : Three-phase brushless DC motor driver expansion board based on STSPIN830 for STM32 Nucleo |
| F3 | F303 | STEVAL-ESC001V1 | Electronic speed controller reference design for drones |

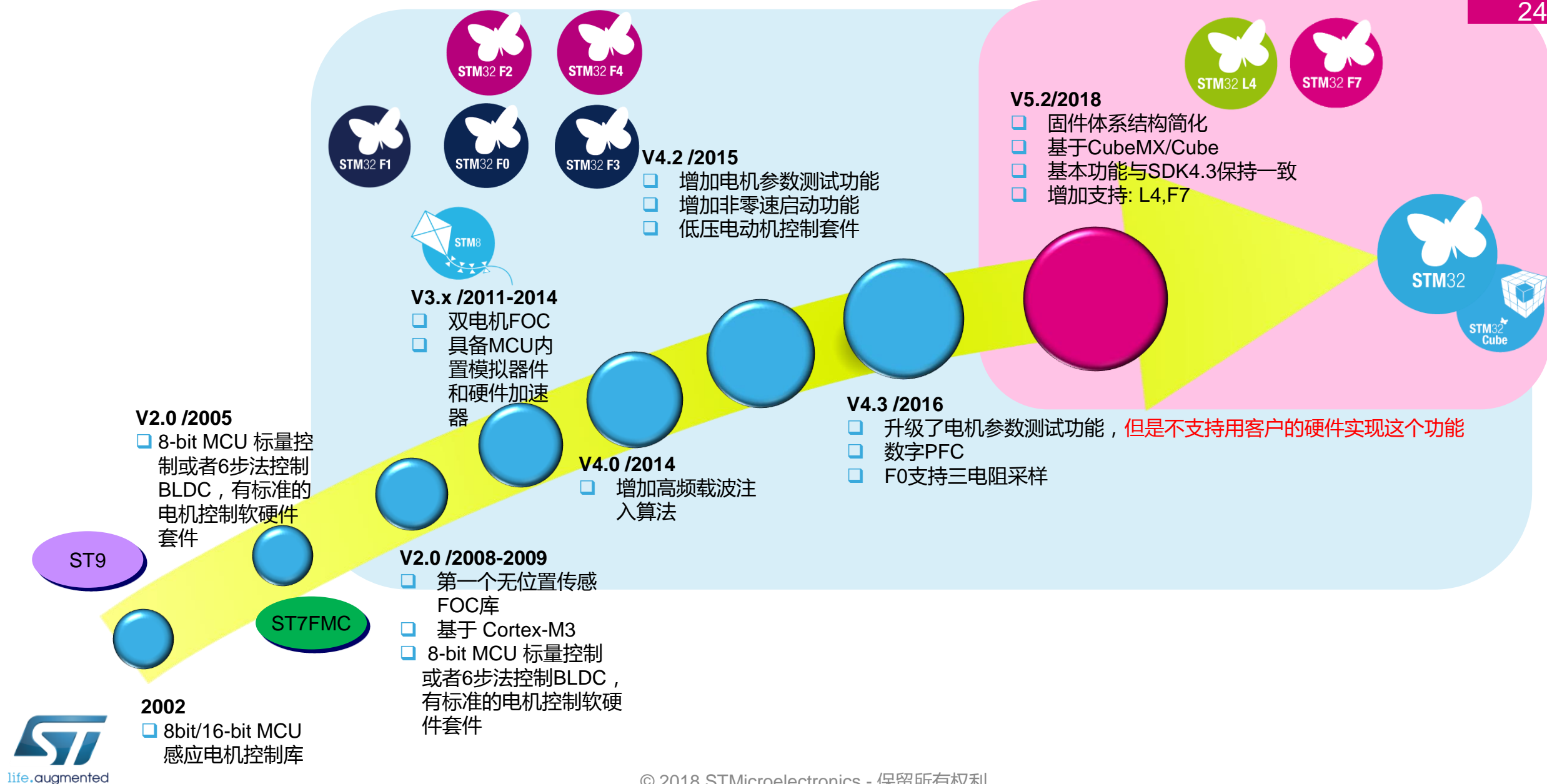


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- ST MC SDK5.x 参考资料列表

ST MC SDK5.x固件介绍

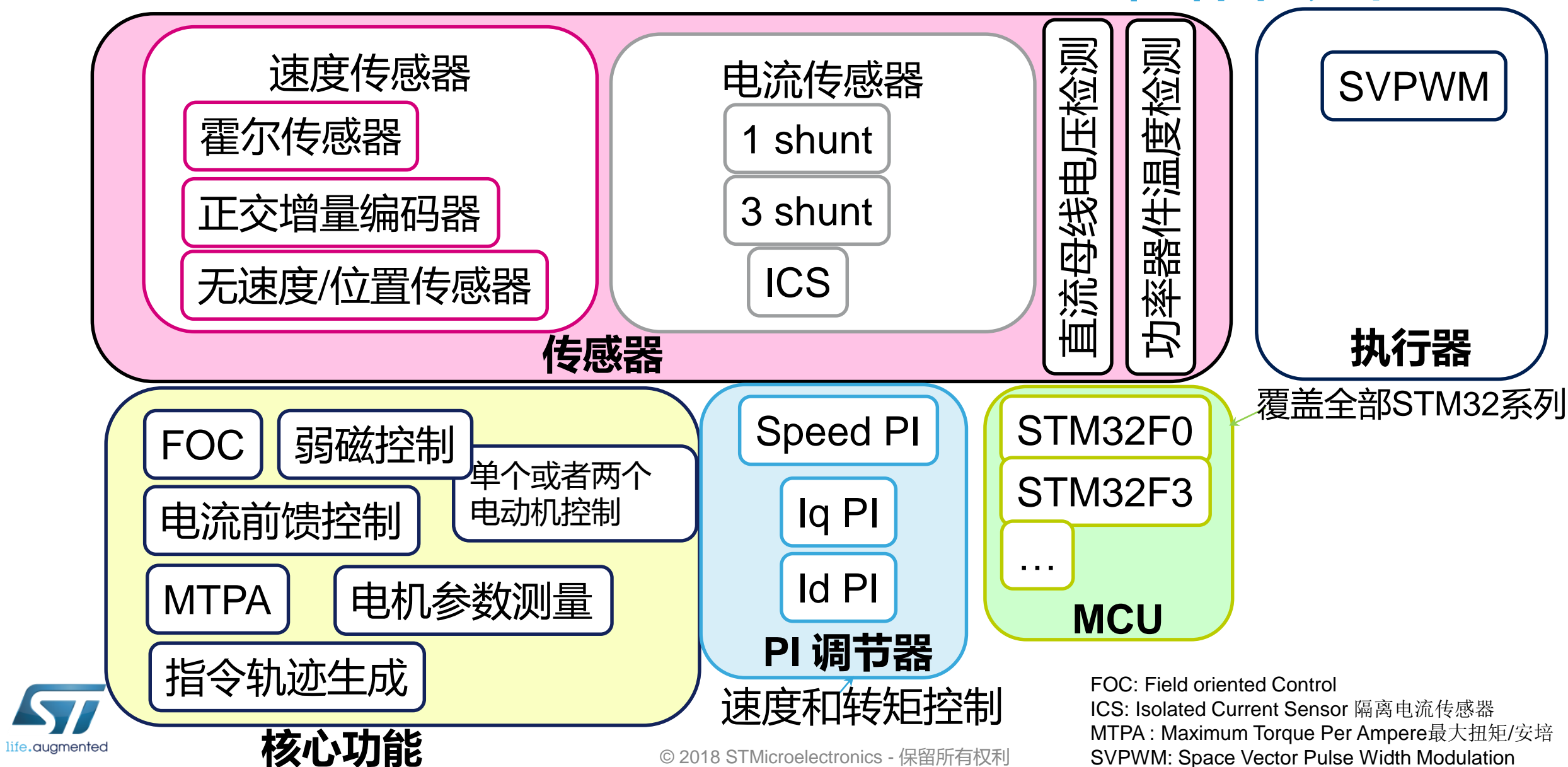
ST MC SDK 发展路线图

24



ST MC SDK5.2固件功能

25

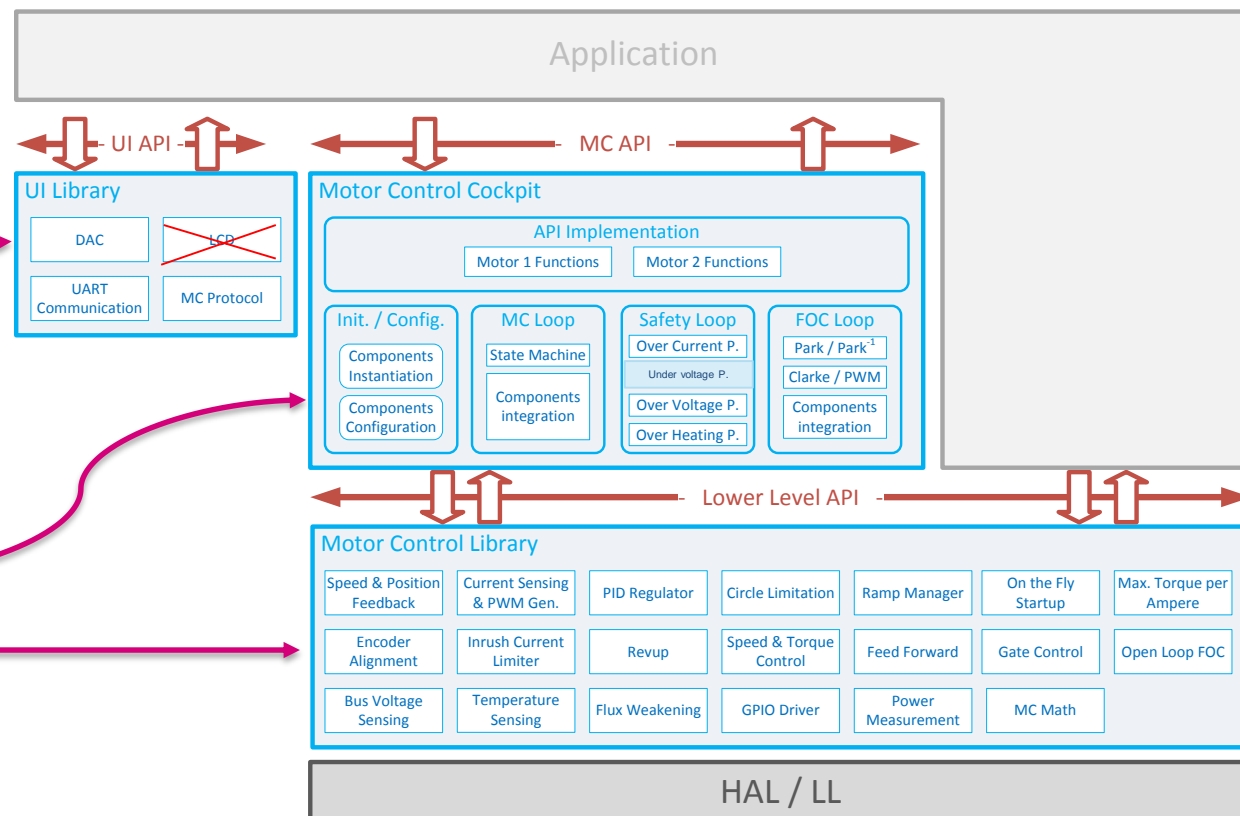


ST MC SDK5.2固件体系结构(1/3)

26

固件包含三部分:

- 用户接口库
- Motor Control Cockpit
- 电机控制库

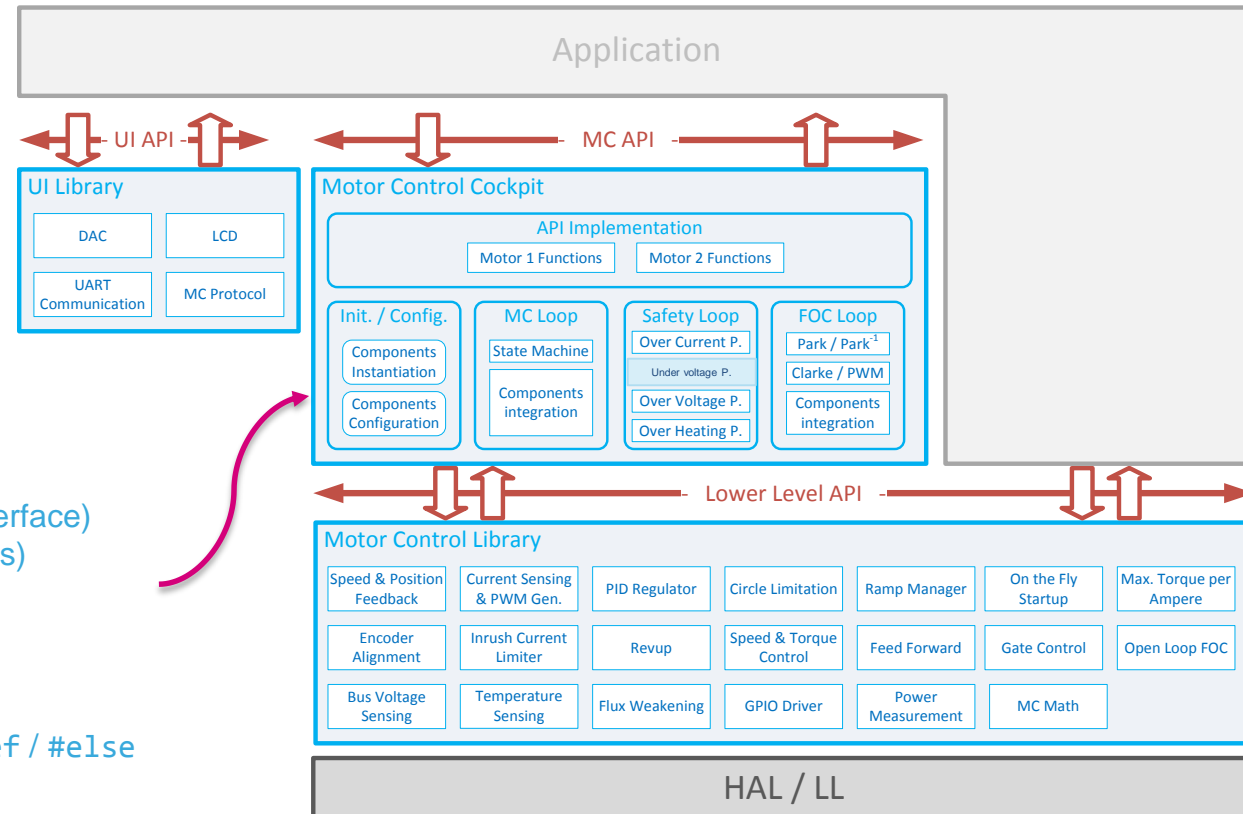


ST MC SDK5.2固件体系结构(2/3) 与SDK4.3的主要区别(1/2)

27

Motor Control Cockpit

- ≈ SDK4.3 MCApplication
- 包含:
 - MC API (SDK4.3 MCInterface)
 - Loops (SDK4.3 MCTasks)
 - 固件初始化
- 代码生成
 - WB直接输出
 - 只输出需要的代码
 - 不再使用条件编译`#ifdef / #else / #endif`

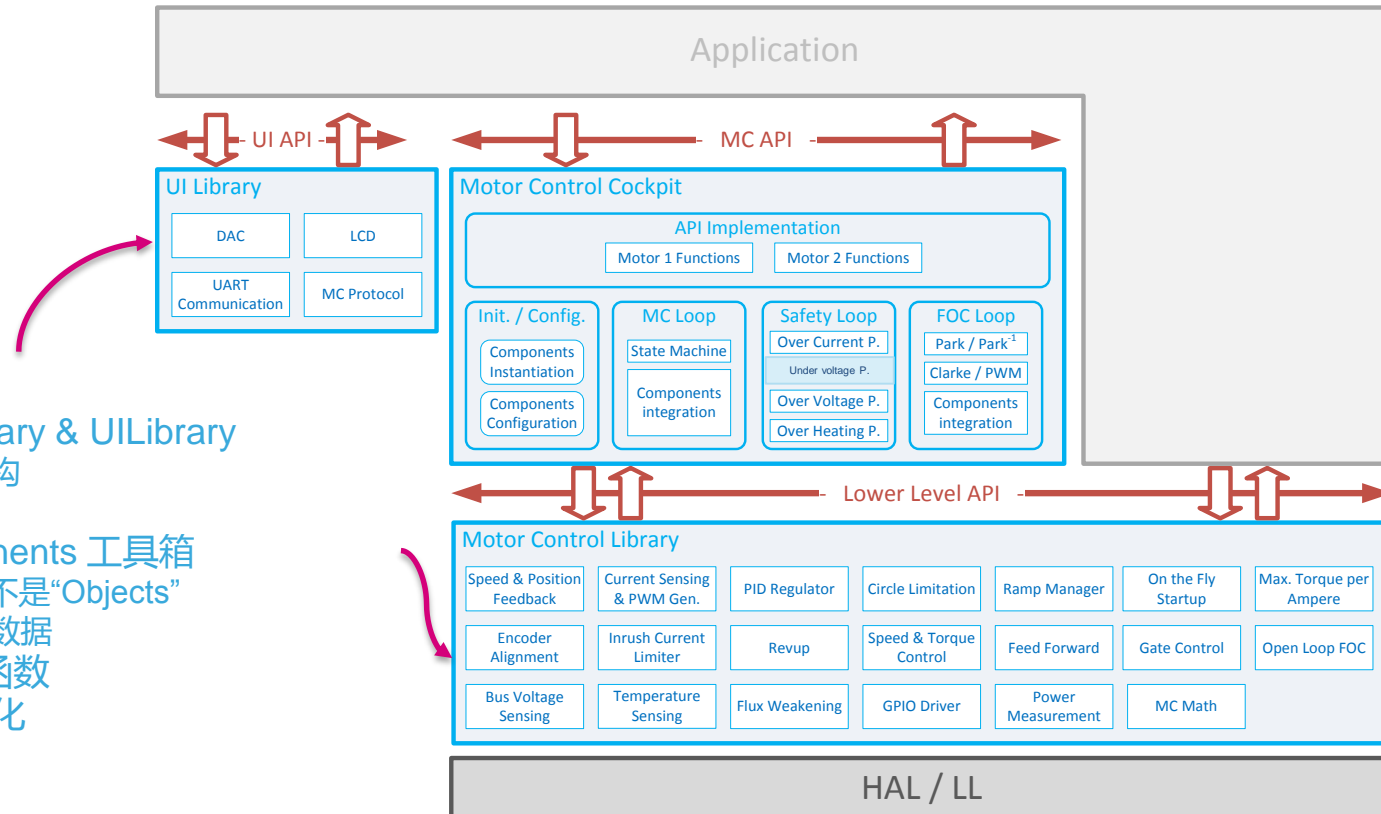


ST MC SDK5.2固件体系结构(3/3) 与SDK4.3的主要区别(2/2)

28

库

- ≈ SDK4.3 MCLibrary & UILibrary
 - 变更了数据结构
 - 算法保持不变
- Library == Components 工具箱
 - Components 不是“Objects”
 - 代码不再隐藏数据
 - 不再定义虚函数
- 库的结构得到了简化



ST MC SDK5.2 Motor Control Cockpit介绍(1/2)

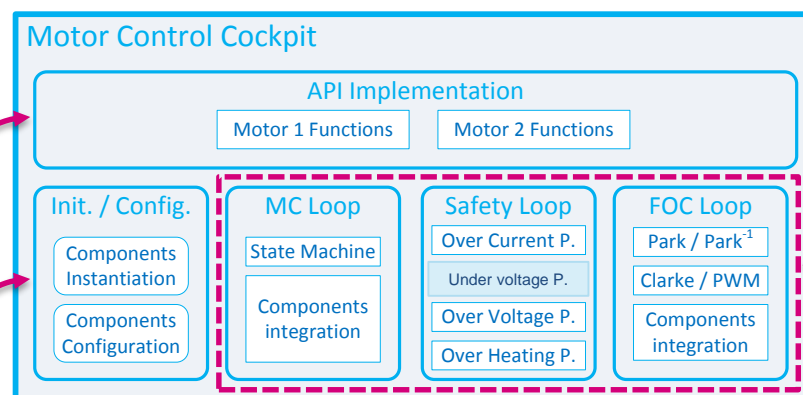
29

- MC Cockpit 由以下三个部分组成

MC Interface

实现MC Cockpit与其他部分的接口 MC API

电机控制配置
实例化和初始化所有需要的Component



MC Dynamics

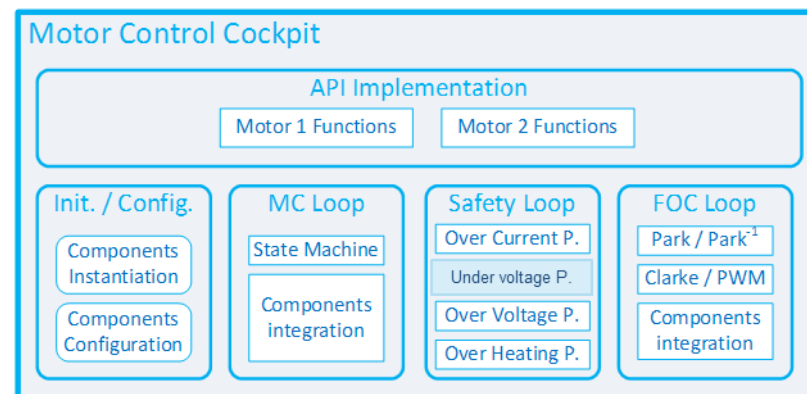
实现电动机控制的逻辑

- 矢量控制循环 (High Freq)
- 电动机控制循环(Med Freq)
- 保护循环(Safety Tasks)

ST MC SDK5.2 Motor Control Cockpit介绍(2/2)

30

- Motor Control Cockpit 代码是由WB后台调用CubeMX自动生成的
 - 基于用户在WB中的配置
- 生成代码的特性
 - **短小**: 只生成项目所需要的代码。
 - **简单**: 没有条件编译。(#ifdef / #else / #endif)
 - **高效**: 无虚函数. 代码直接调用定义的函数，无需函数指针。



改进：从v4.3 到 v5.x

31

- 简化固件程序架构

- 不再面向对象

- 固件基于STM32Cube

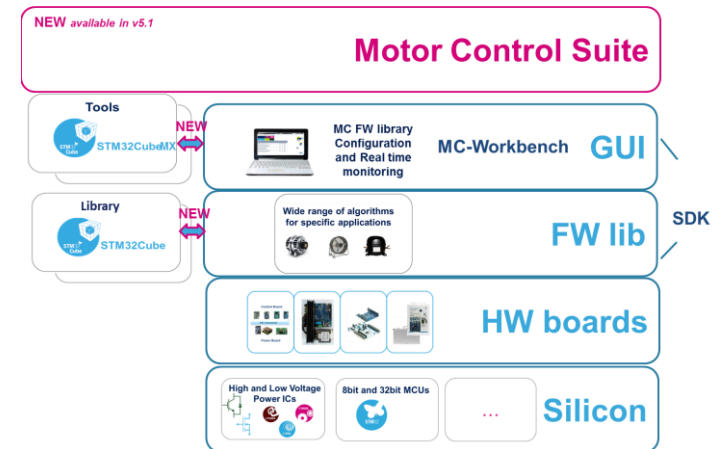
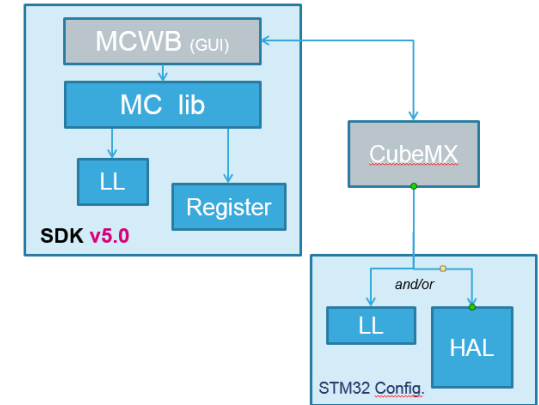
- 用HAL/LL代替SPL

- 建立了MC_workbench 对 CubeMX (Tool)的调用

- Cube MX => 用于初始化MCU的外围设备

- Motor Control Suite (Tool)

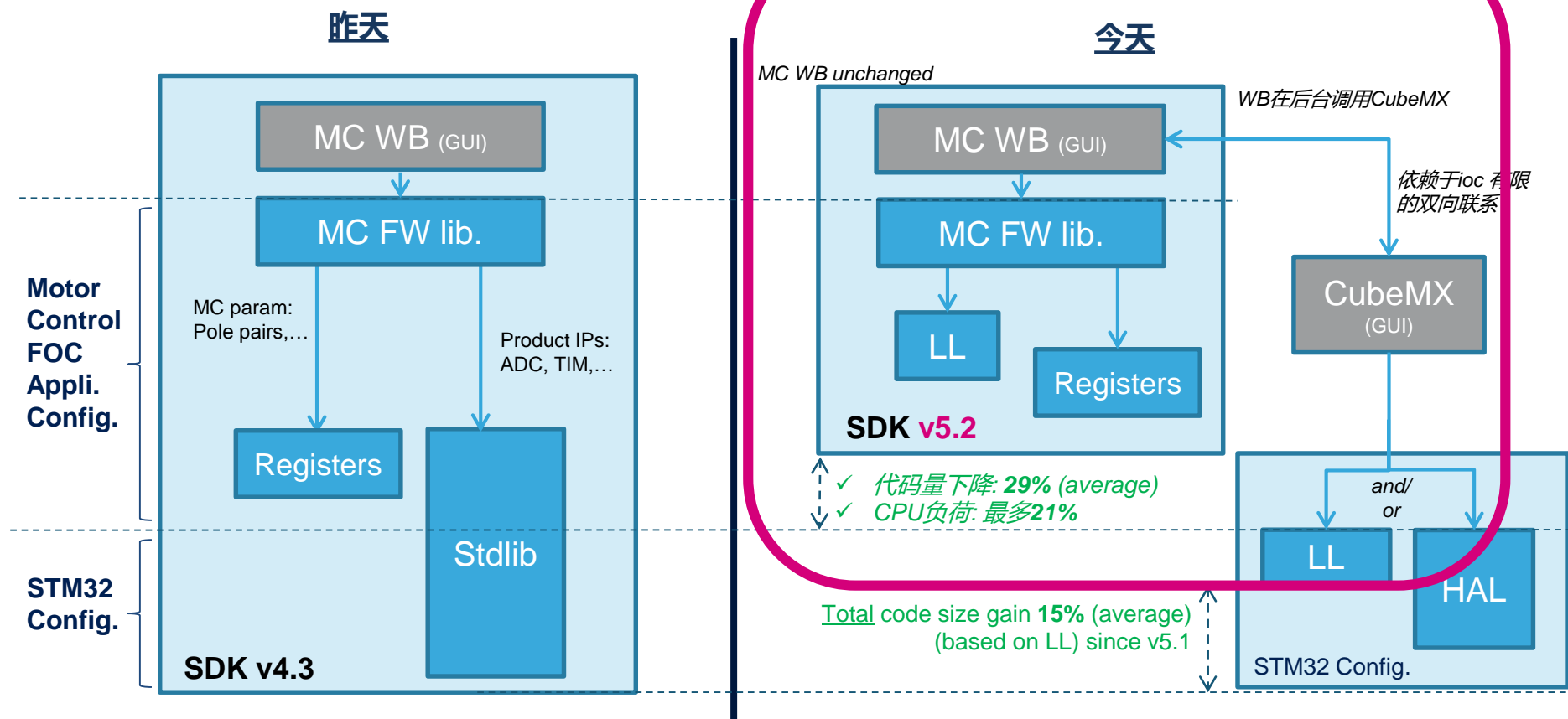
- 涵盖全部 MCU及硬件评价板的选择
- 统一到CubeMX/Cube的框架下
- WB成为CubeMX的调用
- 针对具体应用有对应的固件库可以选择



ST MC SDK5.2 与 SDK4.3固件库的体系结构对比

32

代码尺寸 < 22KB



15% code size gain from v4.3 to V5.2 !

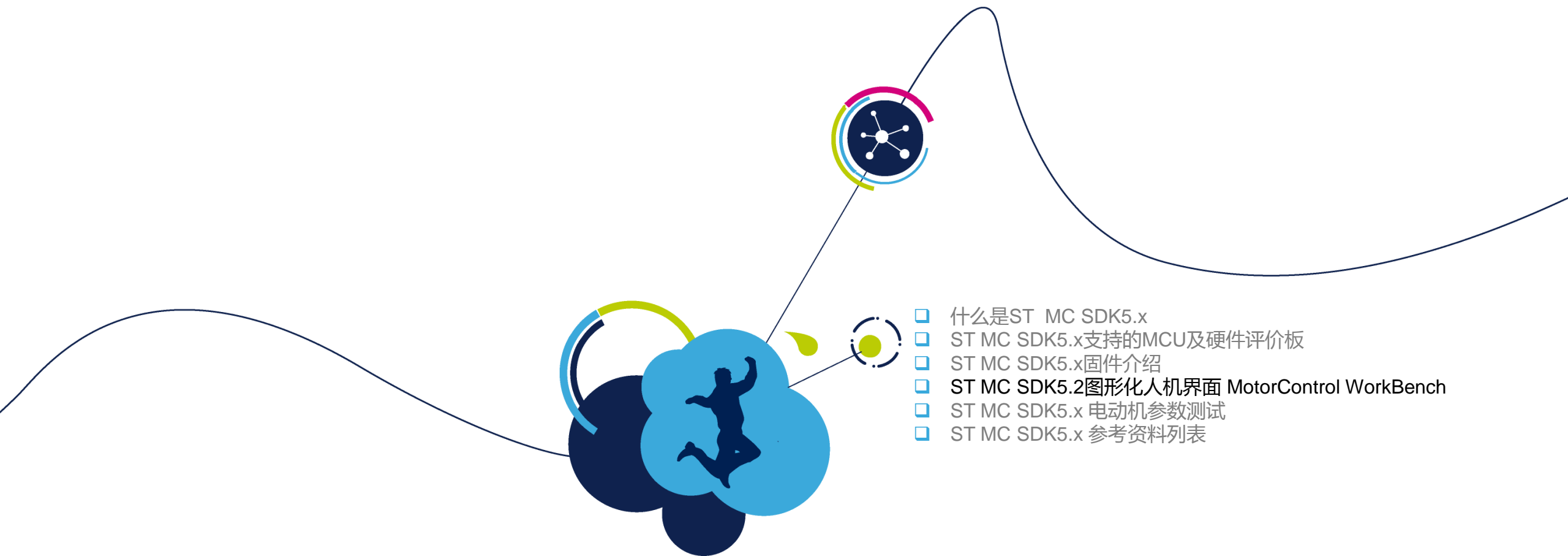
ST MC SDK v5.2—性能测试结果

PWM 载波频率 20kHz / 10kHz FOC

33

| MCU | Nb Motor | Config | MCSDK4.3 | | | | MCSDK5.2 | | | | | | Compare 4.3 vs 5.2 | | | |
|--------|----------|----------|------------------|----------------------|-------------|--------------|------------------|------------------------------------|-----------------------------------|-------------|----------|---------|--------------------|------------|-------------------------------------|-----------------------------------|
| | | | CPU Workload (%) | Total Code size (kB) | MC Lib (kB) | STD Lib (kB) | CPU Workload (%) | Grand Total Code Size (+ HAL) (kB) | Grand Total Code Size (+ LL) (kB) | MC Lib (kB) | HAL (kB) | LL (kB) | CPU Workload (%)* | MC Lib (%) | Grand Total Code Size (+ HAL) (Kb)* | Grand Total Code Size (+ LL) (%)* |
| F072RB | Single | 1x Shunt | 52.0 | 19.3 | 17.3 | 2.0 | 46.4 | 18.0 | 16.9 | 13.1 | 5.2 | 3.2 | -10.6% | -24.1% | -6.9% | -12.6% |
| F072RB | Single | 3x Shunt | 49.0 | 19.6 | 17.7 | 2.0 | 42.6 | 17.1 | 16.3 | 12.5 | 4.6 | 3.2 | -13.0% | -29.2% | -12.8% | -17.0% |
| F303RE | Single | 1x Shunt | 20.0 | 21.2 | 18.2 | 3.0 | 20.4 | 22.4 | 19.9 | 14.9 | 8.1 | 4.4 | 2.2% | -18.0% | 5.6% | -6.2% |
| F303RE | Single | 3x Shunt | 18.5 | 23.0 | 20.6 | 2.4 | 17.8 | 23.4 | 19.3 | 16.1 | 7.7 | 2.6 | -3.5% | -21.9% | 1.9% | -16.1% |
| F446RE | Single | 1x Shunt | 10.5 | 20.1 | 17.7 | 2.4 | 10.2 | 20.1 | 19.0 | 14.7 | 5.5 | 3.3 | -3.1% | -17.0% | -0.3% | -5.8% |
| F446RE | Single | 3x Shunt | 8.9 | 17.8 | 15.8 | 2.0 | 8.2 | 18.2 | 15.7 | 13.2 | 4.8 | 2.0 | -8.1% | -16.4% | 2.3% | -12.1% |
| F303VE | DUAL | 3x Shunt | 38.9 | 25.2 | 22.8 | 2.4 | 38.2 | 25.5 | 21.8 | 18.6 | 7.9 | 2.6 | -1.8% | -18.6% | 1.0% | -13.5% |
| F415ZG | DUAL | 3x Shunt | 23.1 | 19.9 | 17.9 | 2.0 | 18.3 | 19.6 | 17.7 | 15.2 | 4.8 | 2.0 | -20.8% | -14.9% | -1.2% | -11.1% |

- 代码尺寸（应用程序+电动机控制库+驱动程序）最多下降了17%。（SDK5.x: F0+3-shunt+LL）
- 电动机控制库的代码尺寸下降的幅度从 14% 到 29%不等



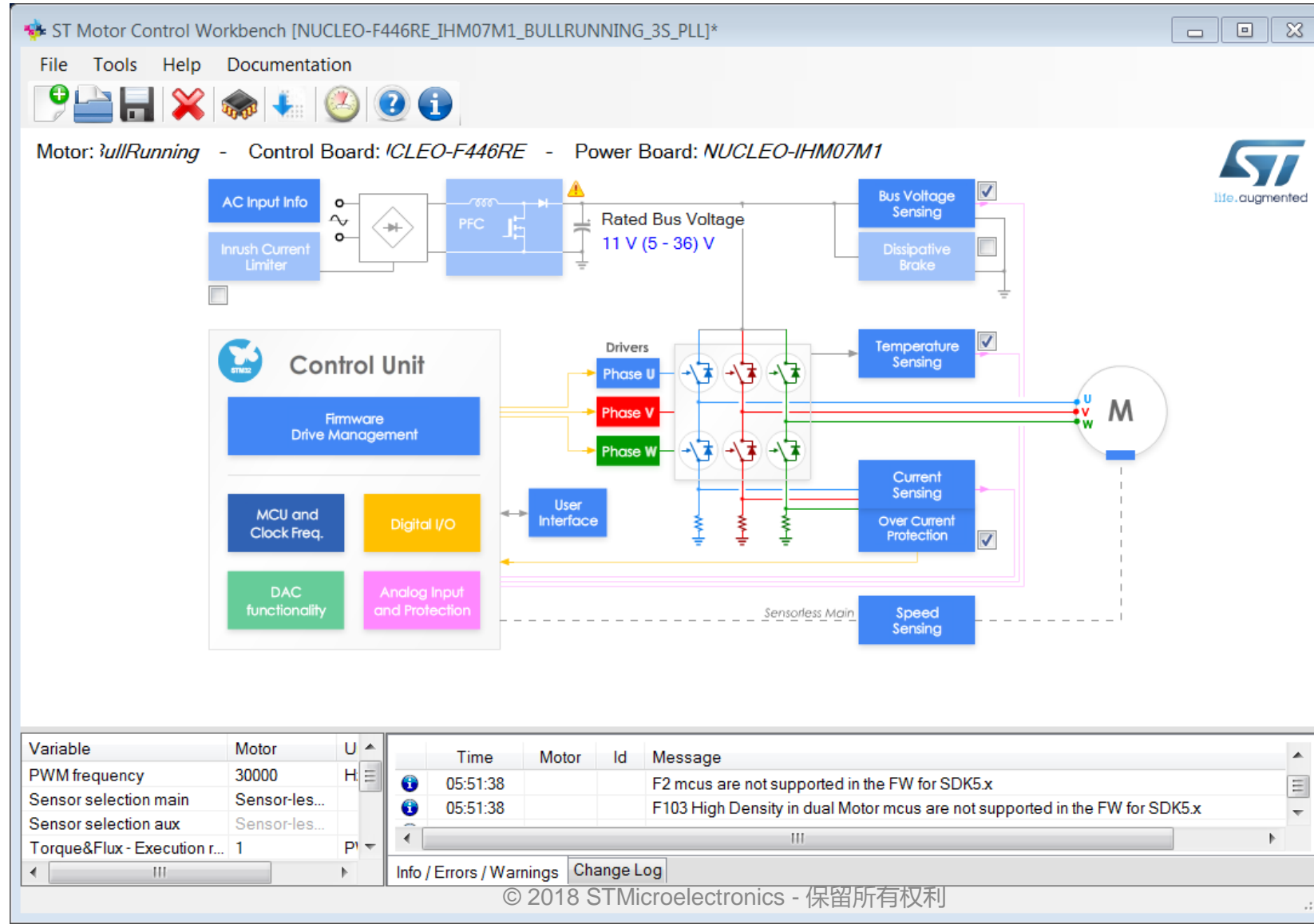
- 什么是ST MC SDK5.x
- ST MC SDK5.x支持的MCU及硬件评价板
- ST MC SDK5.x固件介绍
- ST MC SDK5.2图形化人机界面 MotorControl WorkBench
- ST MC SDK5.x 电动机参数测试
- ST MC SDK5.x 参考资料列表

ST MC SDK5.2图形化人机界面 MotorControl WorkBench

ST MC SDK5.2图形用户界面(1/3)

Motor Control Workbench 参数配置界面

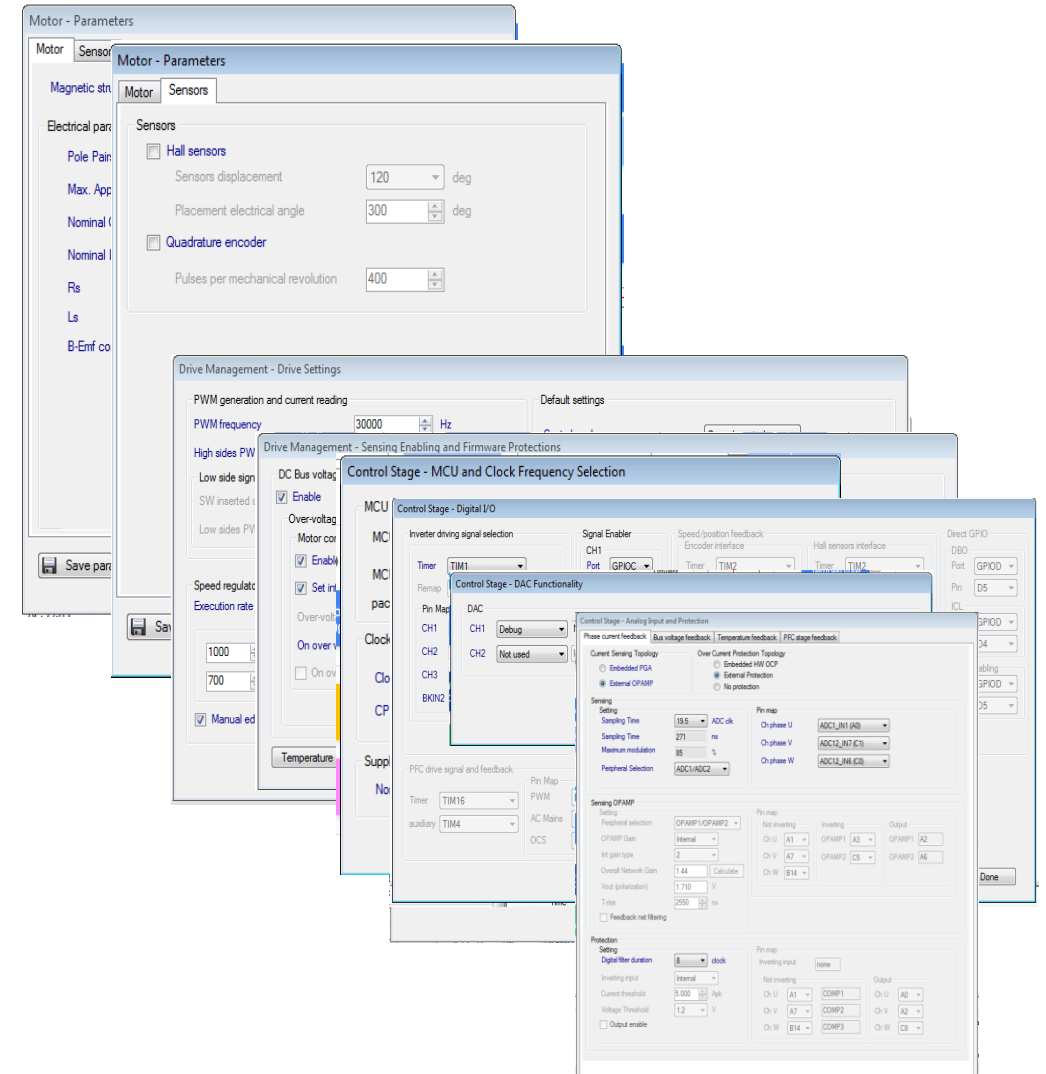
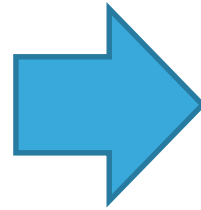
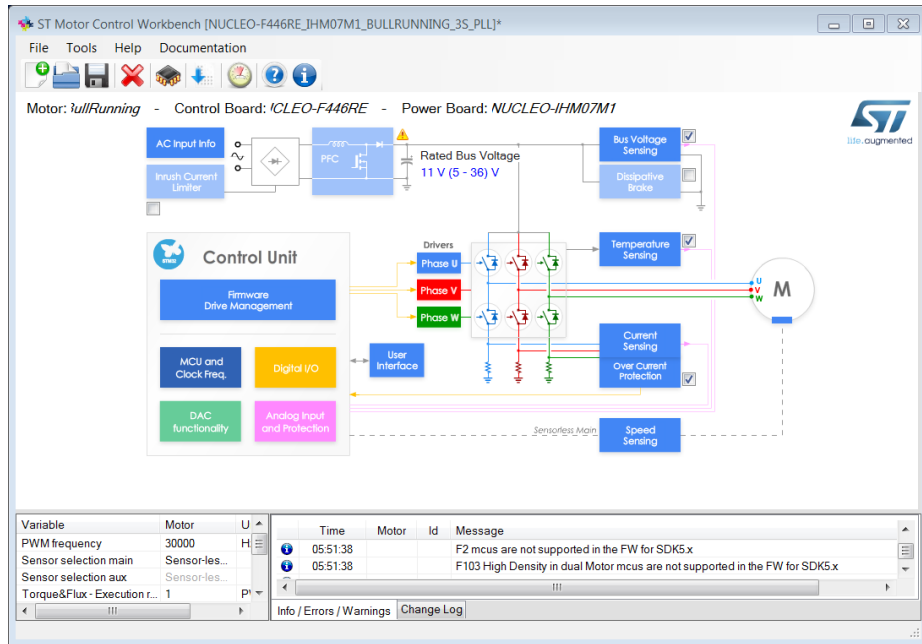
35



ST MC SDK5.2图形用户界面(2/3)

Motor Control Workbench 参数配置界面

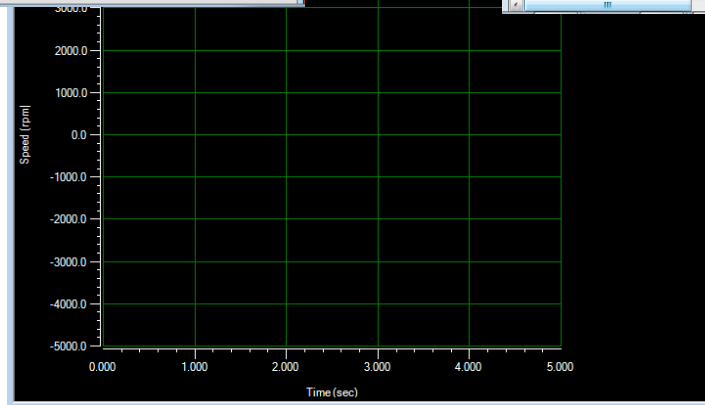
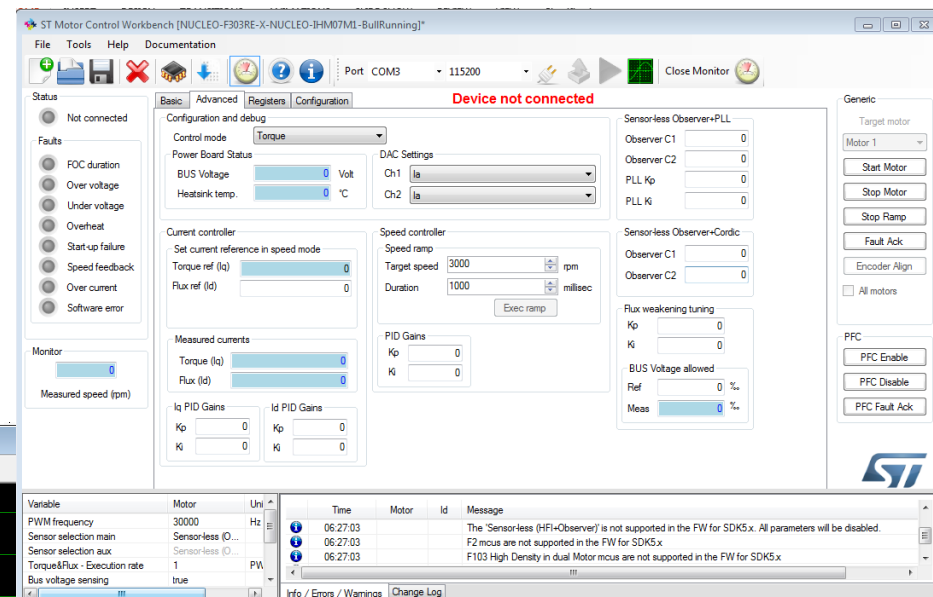
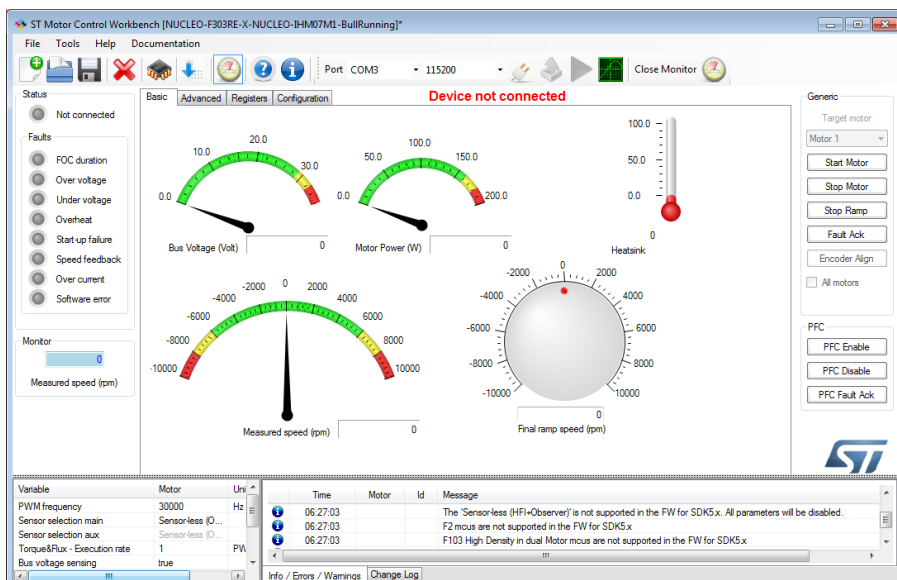
36



ST MC SDK5.2图形用户界面(3/3)

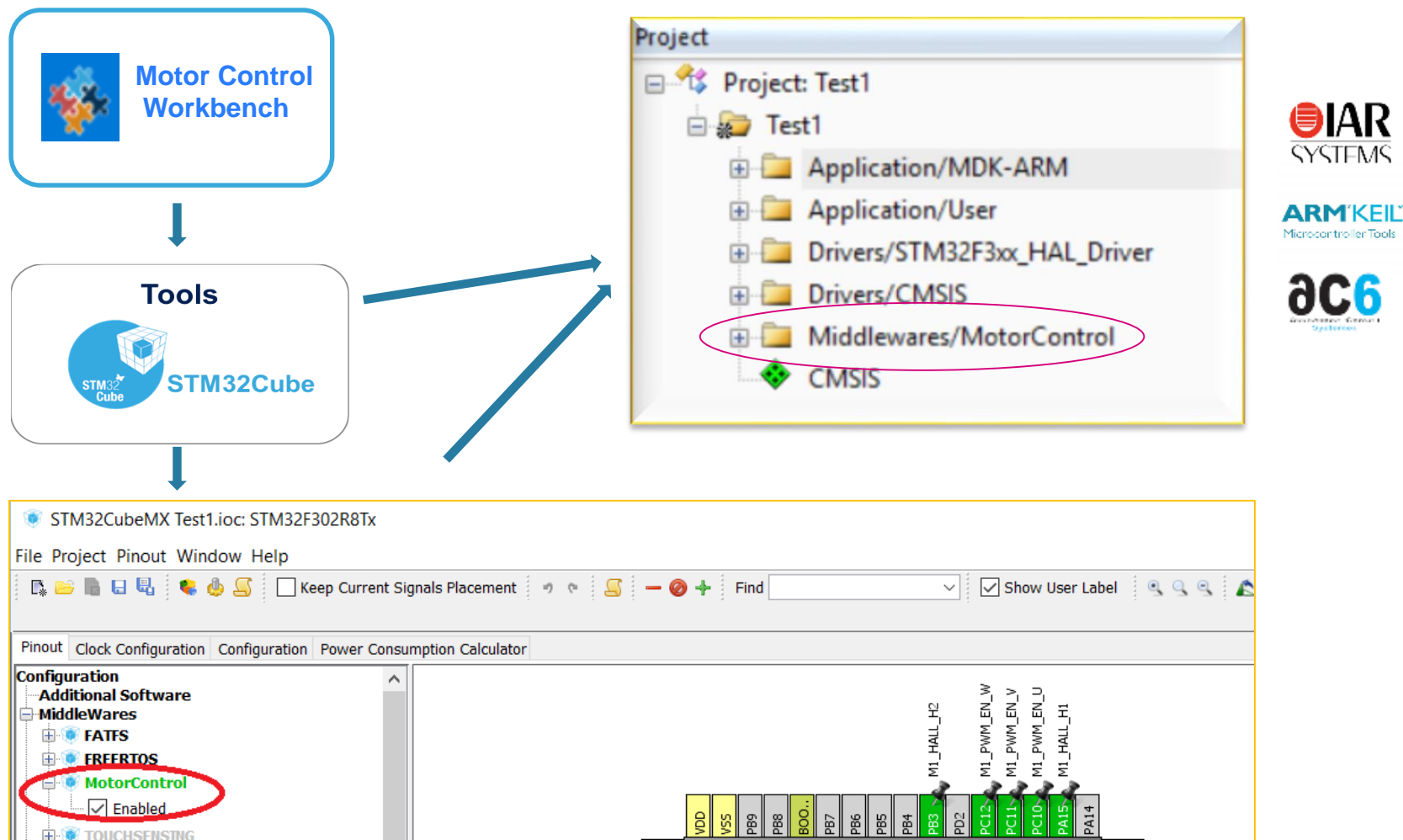
Motor Control Workbench 与固件交互界面

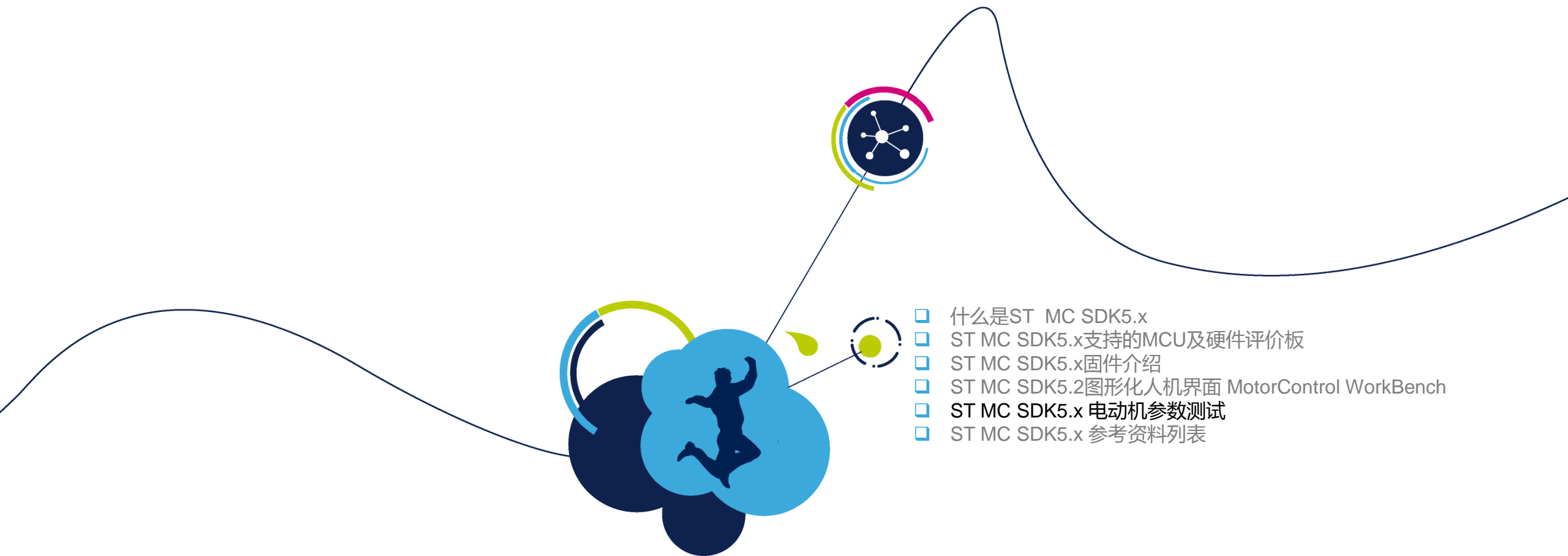
37



ST MC SDK5.2代码生成流程

38



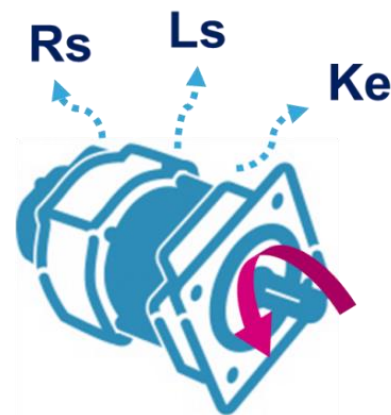
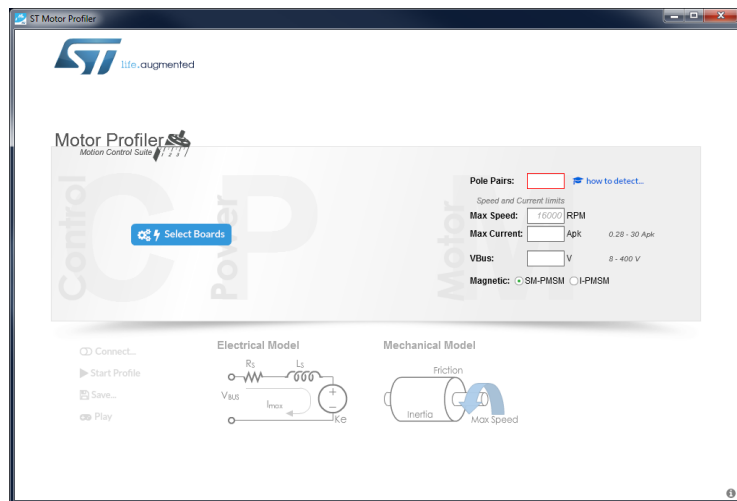


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ST MC SDK5.x 电动机参数测试

ST MC SDK5.2 电动机参数自动检测

40



- 自动测量电动机参数(R_s , L_s , K_e)
- 不需要额外的测量仪器
- 1[min]之内让电动机运转起来
- 当 $R_s \geq 1 \Omega$ 并且 $L_s \geq 1 \text{ mH}$ 时,这个工具参数检测的精度最高

ST MC SDK5.2电动机参数测试界面

41

电动机电参数识别 + 电动机机械参数识别

Motor Profiler
Motion Control Suite

NUCLEO-F302R8
STM32F302R8T6

X-NUCLEO-IHM07M1 3Sh
L6230PD

One Motor Control connector
ST-LINK/V2 Embedded

Bus Voltage: 8 - 48 Vdc
Output peak current: 0.28 - 2.8 A

Pole Pairs: 7 [how to detect...](#)

Speed and Current limits

Max Speed: 16000 RPM

Max Current: 1.8 Apk 0.28 - 2.8 Apk

VBus: 12 V 8 - 48 V

Magnetic: ☒ SM-PMSM ☐ I-PMSM

Remember to properly configure the boards in Motor Control mode

☒ Disconnect

[Start Profile](#)

[Save...](#) 保存识别的参数

[Play](#) 可以开始控制电机转动

Electrical Model

R_s 0.24 Ω L_s 0.02 mH

V_{BUS} 12.24 V

I_{max} 1.17 Apk

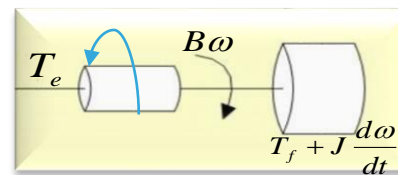
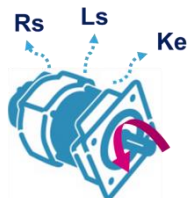
K_e 0.87 Vrms/kRPM

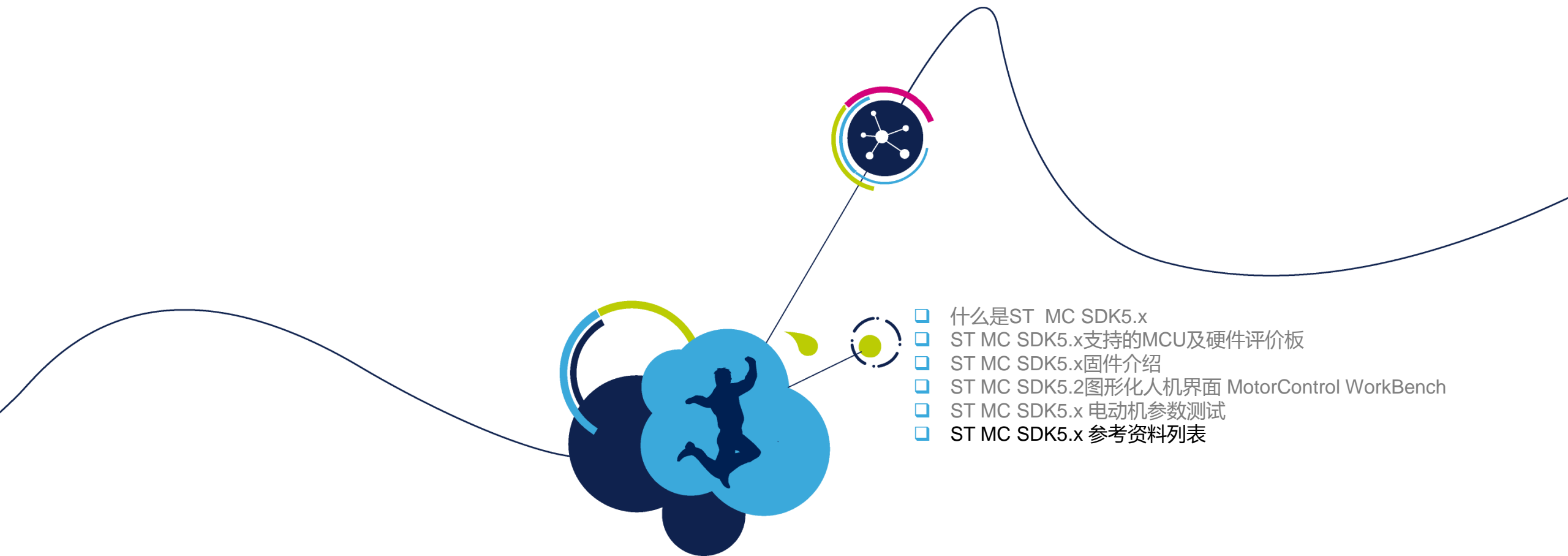
Mechanical Model

Friction 516.99 nN·m·s

Inertia 346.9 nN·m·s²

Max Speed 15700 RPM





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ST MC SDK5.x 参考资料列表

SDK5.x 技术文档(1/2)

43

| | Title | Type | Contents |
|------------------------|---|------------------|---|
| DB3548 | STM32 MC SDK software expansion for STM32Cube | Data Brief | 数据手册，说明MC SDK作为STM32Cube的扩展部件所具备的基本特性、功能、产品信息及版权等内容 |
| UM2374 | Getting started with STM32 motor control SDK v5.0 | User Manual | 用户手册——入门。 |
| UM2392 | STM32 motor control SDK5.x - Firmware | User Manual | 用户手册——固件。 作为内容补充，也请继续参考 UM1052 。未来，UM2392将会全面替代UM1052。 |
| UM2380 | STM32 motor control SDK v5.2 tools | User Manual | 用户手册——工具。 介绍如何使用MC SDK的工具： Motor Profiler, WB |
| AN5143 | How to migrate motor control application software from SDK v4.3 to SDK v5.x | Application note | 应用文档。介绍如何从SDK4.3的应用移植到SDK5.x。 |
| AN5166 | Guidelines for control and customization of power boards with STM32 MC SDK v5.0 | Application Note | 应用文档。帮助用户快速用自己的目标硬件来调试MC SDK。 |

随机资料:

| Title | Type | Path | Description |
|-------------------------|------|--|-------------|
| Release note | html | ..\STMicroelectronics\MC_SDK_5.2.0\Release Notes for X-Cube-MCSDK.html | 版本发布说明 |
| Getting start(UM2374) | PDF | ..\STMicroelectronics\MC_SDK_5.2.0\Documentation\en.DM00484271.pdf | 用户手册——入门。 |
| MotorControlSDKFirmware | CHM | ..\STMicroelectronics\MC_SDK_5.2.0\Documentation\MotorControlSDKFirmware.chm | 固件参考手册 |

视频:

| Title | Type |
|---|-------|
| MC SDK5.0 getting started | Video |

培训资料:

| Title | Type |
|---|--------------------|
| STM32 Motor Control training materials(Chinese) | Training materials |

Releasing your creativity

45



- Thank you -

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