Aoran Wang

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EDUCATION

University of Luxembourg

Esch-sur-Alzette, Luxembourg

PhD in Computer Science (Focus: Machine Learning for Dynamical Systems)

Dec. 2020 - Nov. 2024 (Expected)

Karlsruhe Institute of Technology

Karlsruhe, Germany

Master of Science (Major: Autonomous Driving); GPA: 3.7/4.0

Oct. 2015 - Sep. 2019

Tongji University

Shanghai, China

Bachelor of Engineering (Major: Structural Mechanics); GPA: 3.7/4.0

Sep. 2011 - Jun. 2015

SKILLS

Languages: Python (advanced), C/C++ (advanced), HTML/CSS, MATLAB, Visual Basic, LaTex.

Developer Tools: Linux, Git, Docker, Google Cloud Platform, VS Code, Visual Studio, PyCharm, Slurm.

Libraries: PyTorch, TensorFlow, Scikit-Learn, Jupyter, pandas, NumPy, Matplotlib, CUDA.

Techniques: Convolutional Neural Networks, Graph Neural Networks, Variational Autoencoder, Bi-level Optimization,

Active Learning, AI4Science, Dynamical Systems, Generative AI, Reservoir Computing, Graph Theory.

PUBLICATIONS

- Wang, A., and Pang, J. (2024). Structural Inference of Dynamical Systems with Conjoined State Space Models. The Thirty-eighth Annual Conference on Neural Information Processing Systems (NeurIPS 2024). (To Appear)
- Wang, A., and Pang, J.. (2024). Benchmarking Structural Inference Methods for Interacting Dynamical Systems with Synthetic Data. The Thirty-eight Conference on Neural Information Processing Systems Datasets and Benchmarks Track (NeurIPS 2024 Datasets and Benchmarks Track). (To Appear)
- Wang, A., and Pang, J.. (2024). Structural Inference with Dynamics Encoding and Partial Correlation Coefficients. The Twelfth International Conference on Learning Representations (ICLR 2024). (Link to paper.)
- Wang, A., Tong, T.P., and Pang, J. (2023). Effective and Efficient Structural Inference with Reservoir Computing. Proceedings of the 40th International Conference on Machine Learning (ICML 2023). (Link to paper.)
- Wang, A., and Pang, J.. (2023). Active Learning based Structural Inference. Proceedings of the 40th International Conference on Machine Learning (ICML 2023). (Link to paper.)
- Wang, A., and Pang, J. (2022). Iterative Structural Inference of Directed Graphs. Advances in Neural Information Processing Systems 35 (NeurIPS 2022). (Link to paper.)
- Hu, H., Wang, A., Sons, M. and Lauer, M. (2020). ViPNet: An End-to-End 6D Visual Camera Pose Regression Network. IEEE 23rd International Conference on Intelligent Transportation Systems (ITSC 2020). (Link to paper.)

Projects

LLM4EDUKG | Python, Git, Unix Shell, VS Code

Mar. 2024 - Jun. 2024

- Assembled the first public dataset featuring four educational knowledge graphs, detailing knowledge components and their prerequisite relationships.
- Developed and assessed the capability of pre-trained large language models to interpret and reason over the dataset.
- Documented the development pipeline and disseminated the project via GitHub and a dedicated project website.

StructInfer | Python, Slurm, Git, Unix Shell, VS Code

Dec. 2022 - Apr. 2024

- Engineered and generated observation trajectories for dynamical systems across various dimensions.
- Conducted a comprehensive evaluation of 13 structural inference methods, assessing accuracy, scalability, data efficiency, and robustness.
- Published benchmark results and datasets, making them accessible via GitHub and a project-specific website.

Squirrel AI Hybrid: Shanghai and remote

Research Intern

Feb. 2024 - Present

• Developed recommendation system models for K-12 education using spatio-temporal graphs, enhanced by integrated database solutions to improve learning outcomes.

- Pioneered techniques to address missing data in educational records, utilizing spatio-temporal similarities to ensure data integrity and reliability.
- Initiated and led the LLM4EDUKG benchmark project, evaluating the reasoning abilities of pre-trained large language models on domain-specific knowledge graphs.
- Investigated the integration of domain knowledge into large language models using GraphRAG, developed a simulation environment to model student behavior.

University of Luxembourg

Esch-sur-Alzette, Luxembourg

Doctoral Researcher (PhD Student)

Dec. 2020 - Present

- Explored structural inference in dynamical systems through deep learning, contributing to advancements in modeling complex systems.
- Created StructInfer, a pioneering open benchmark for evaluating structural inference methods across disciplines, ensuring objectivity and reproducibility.
- Published research at premier AI conferences including NeurIPS 2022, ICML 2023, and ICLR 2024, and contributed
 as a reviewer at leading AI venues.

Karlsruhe Institute of Technology

Kalrsruhe, Germany

Student Assistant

Dec. 2019 - Mar. 2020

- Engineered an innovative visual localization technique using Graph Neural Networks and OpenCV to enhance the precision of monocular camera-based navigation in autonomous vehicles.
- Successfully presented and published the outcomes of the visual localization research in a peer-reviewed conference.
- Investigated combinatorial approaches to hierarchical visual localization, broadening the scope of research and uncovering potential advancements in the domain.

Robert Bosch GmbH

Renningen, Germany

Research Intern

Apr. 2018 - Aug. 2018

- Organized and delivered a tutorial on AUTOSAR for the research team, initiated communication with the director.
- Pioneered the development of a diagnosis system using an extended Kalman filter for an autonomous electric vehicle prototype's electric propulsion system.
- Explored the integration of modern AI methods into self-driving cars for diagnostic purposes.

REWARDS

- College-level Excellence, 2011-2015
- Outstanding Graduates of Tongji University, 2015
- Travel Grant, NeurIPS 2022, ICML 2023, ICLR 2024

Interests

Indoor Sports: Fitness, Badminton, Table Tennis.

Outdoor Sports: Snorkeling, Sky Diving, Hiking, Skiing, Surfing.

Arts: Photography, Classical Music, Jazz Music.