

CSC0056: Data Communication

Lecture 04: Hamming Code and Data Retransmission Strategies

Reading assignment: Sections 2.4-2.4.1

Instructor: Chao Wang 王超

Department of Computer Science and Information Engineering

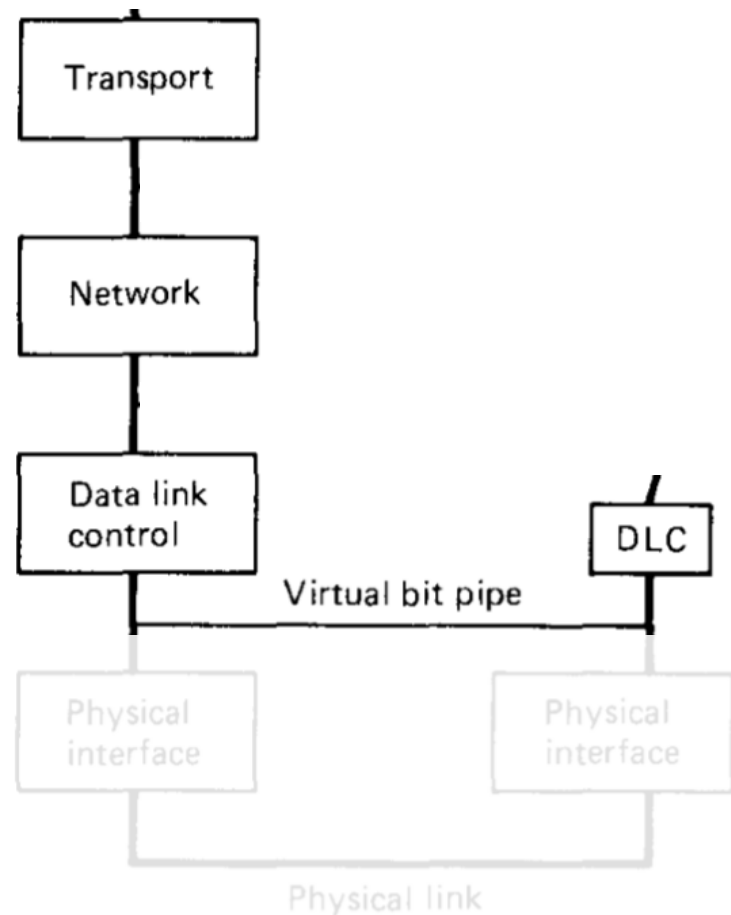


NATIONAL TAIWAN NORMAL UNIVERSITY

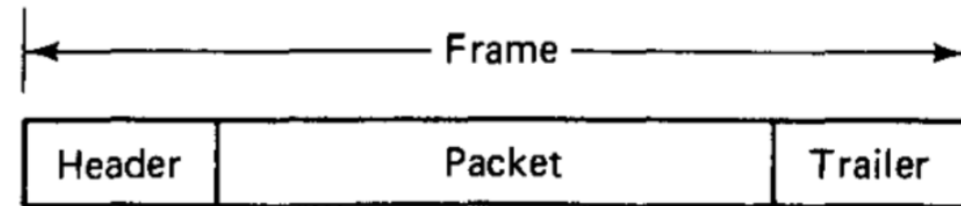
Outline of lecture04

- Hamming code for error detection and correction
 - For this part, we will use the whiteboard.
- Data retransmission strategies and analysis (data link layer)
 - ARQ basics
- Retransmission strategies at a higher layer

Data transmission viewed from the data link layer



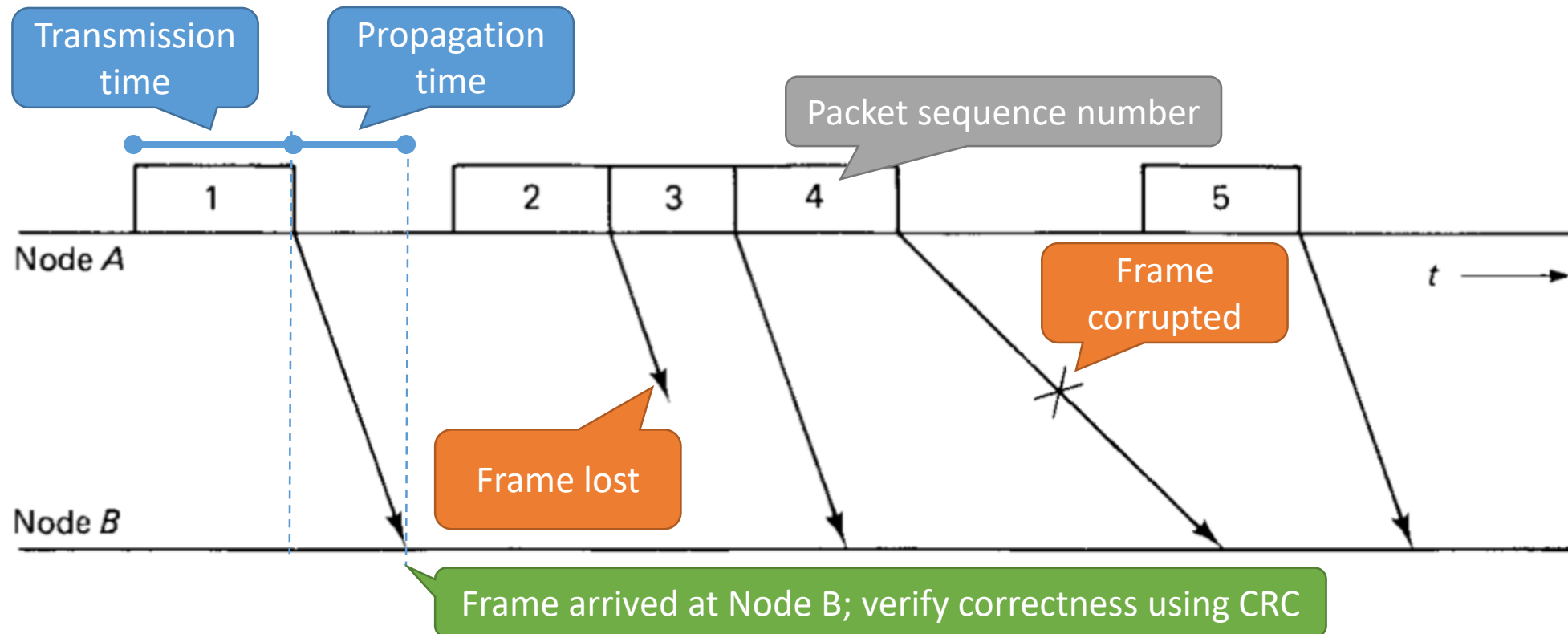
- Data link layer creates a *frame* by appending a header and trailer to each of the *packet* from the network layer



- Data link layer views the underlying point-to-point channel as an *unreliable* virtual bit pipe
- A frame could be lost or corrupted (i.e., contains errors) in the virtual bit pipe

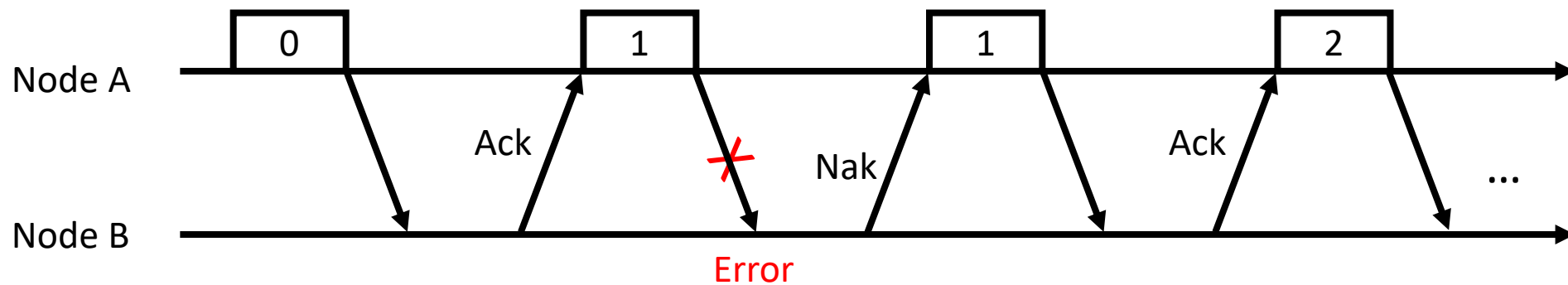
ARQ: Automatic Repeat Request

- Model and definition, assuming Node A sends frames to Node B



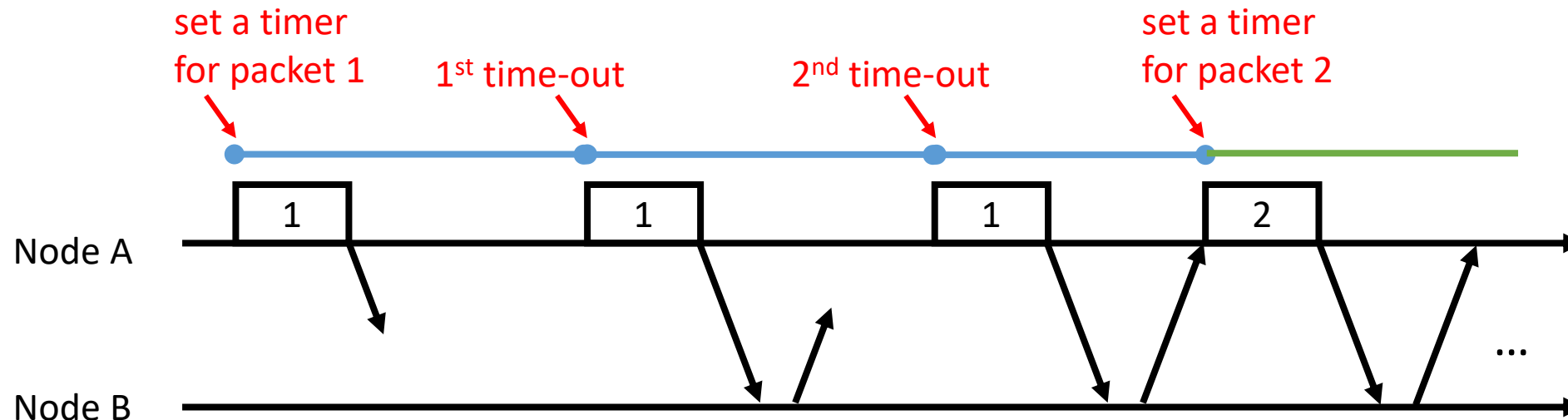
An initial idea of Stop-and-Wait ARQ

- Node A sends a new packet only if it received an acknowledgement from Node B (called an Ack)
- Node B sends an Ack if the received frame is error-free; otherwise, it sends a negative acknowledgement (called an Nak)



The need for time-out and re-transmission

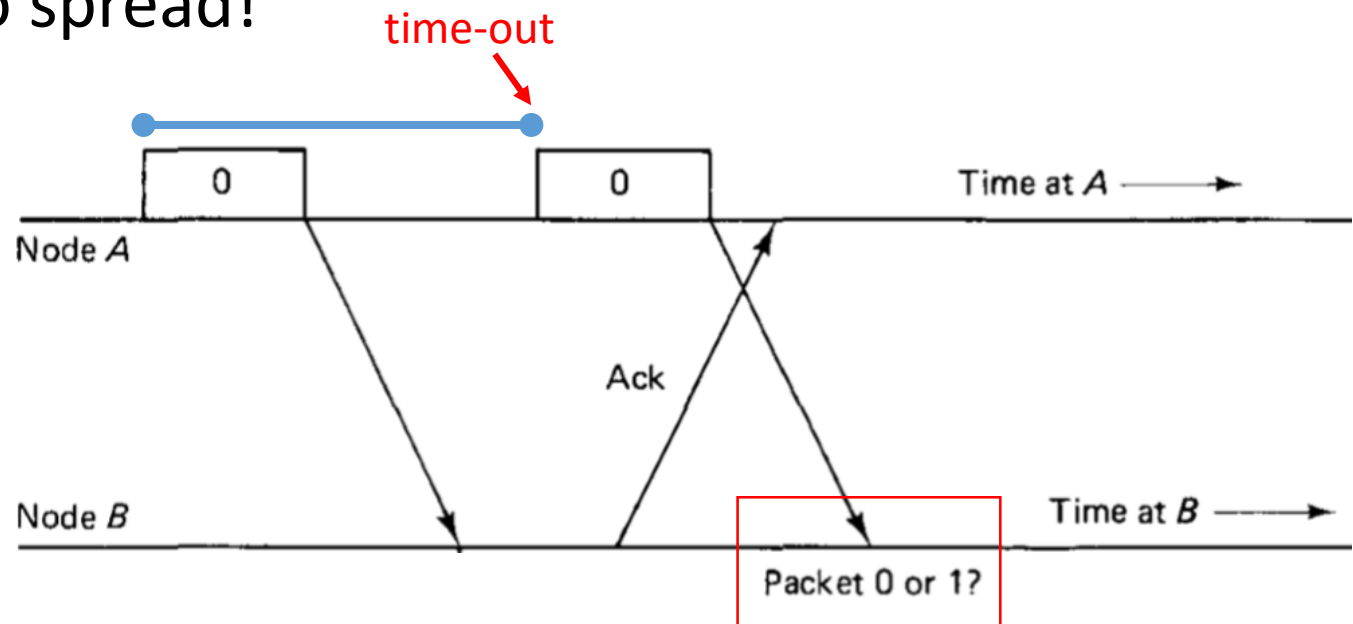
- With no time-out, Node A may wait forever (for either Ack or Nak) if a frame is lost in either direction during transmission...
- Upon a time-out, Node A will re-transmit the same packet
- Design issue: what is a desirable length of a timer? (see later slides)



The need for packet sequence number

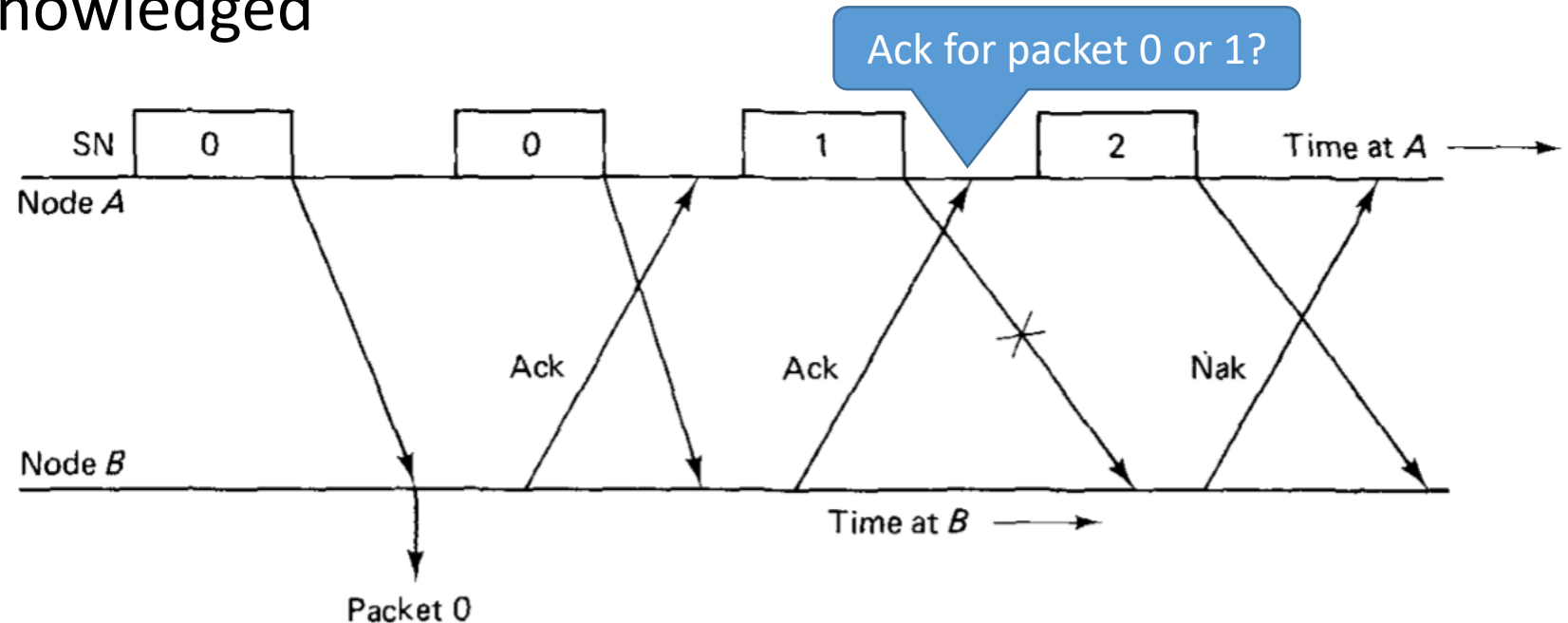
- Node B otherwise may not be able to tell if a frame contains a new packet or if a frame contains a previous packet
- ✓ In general, in designing distributed algorithms, a challenge is that information takes time to spread!

Correctness and efficiency are two critical aspects in design of distributed algorithm.



The need for distinct acknowledgements

- With simple Ack/Nak, Node A might not be able to tell which packet Node B acknowledged

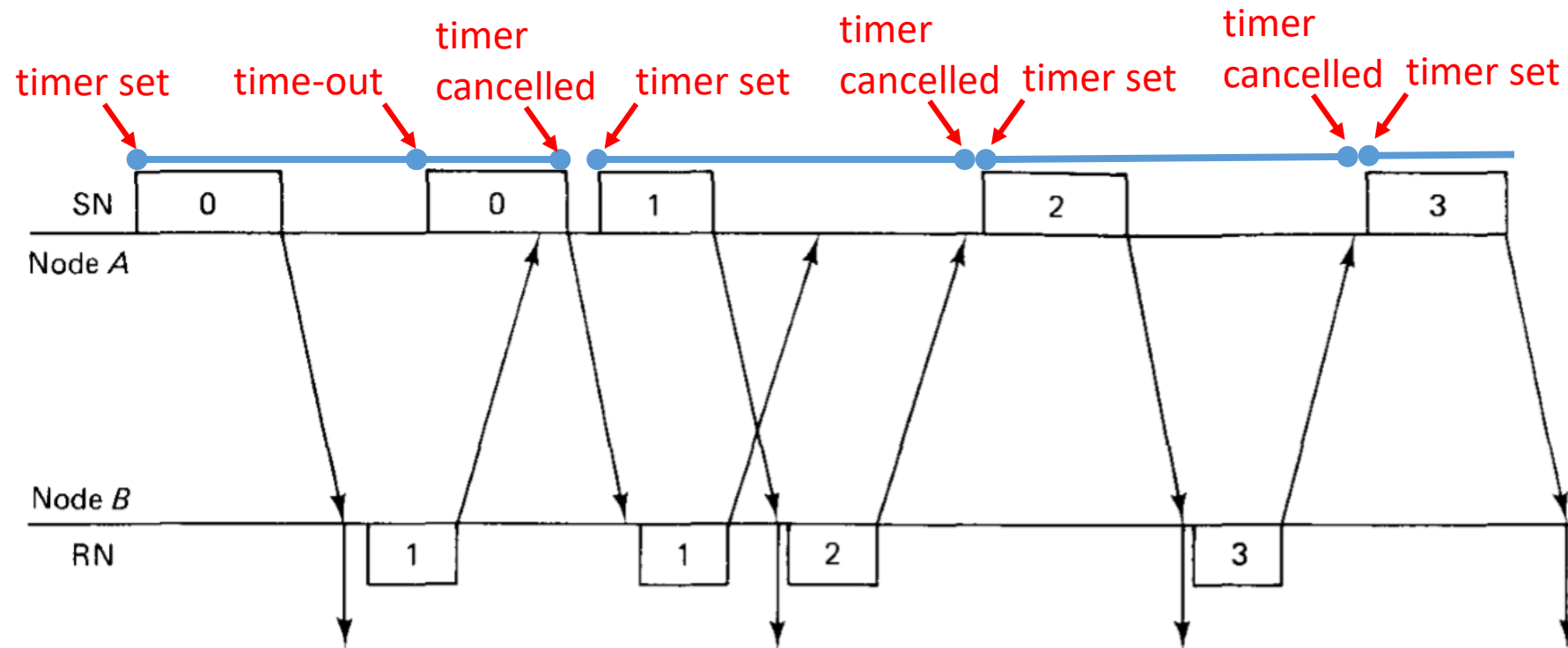


- Solution: Node B sends the number of frame currently *awaited*

A working version of stop-and-wait ARQ

- Using time-out, sequence number (SN), and request number (RN) to coordinate Nodes A and B

(Read the textbook for the assumptions and the algorithm)

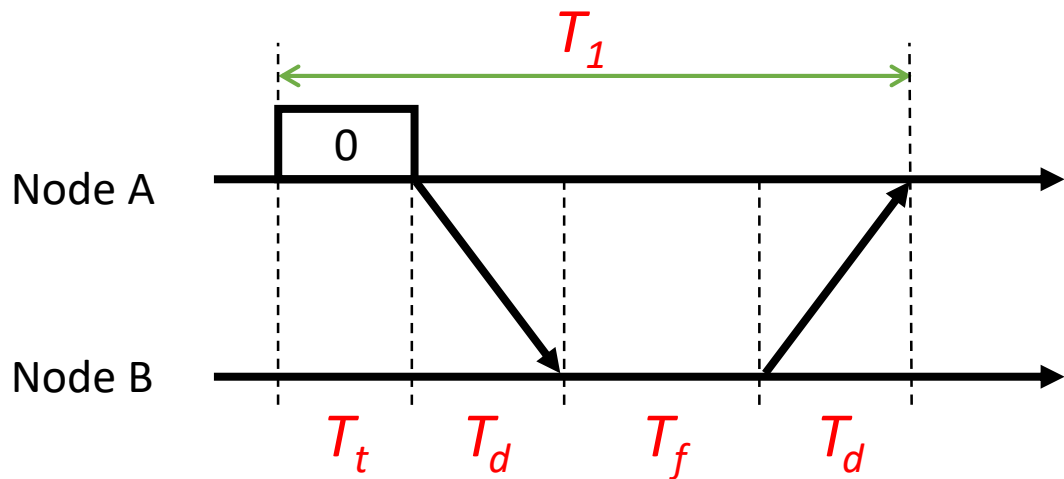


Analyzing efficiency of the stop-and-wait

- There are several ways to look at efficiency
- Way #1 (latency): let T be the total time between the transmission of a packet and reception of its Ack

✓ If error-free, $T = T_1 = T_t + 2T_d + T_f$

T_t : packet transmission time
 T_d : delay in propagation and processing
 T_f : feedback transmission time



Efficiency in terms of latency

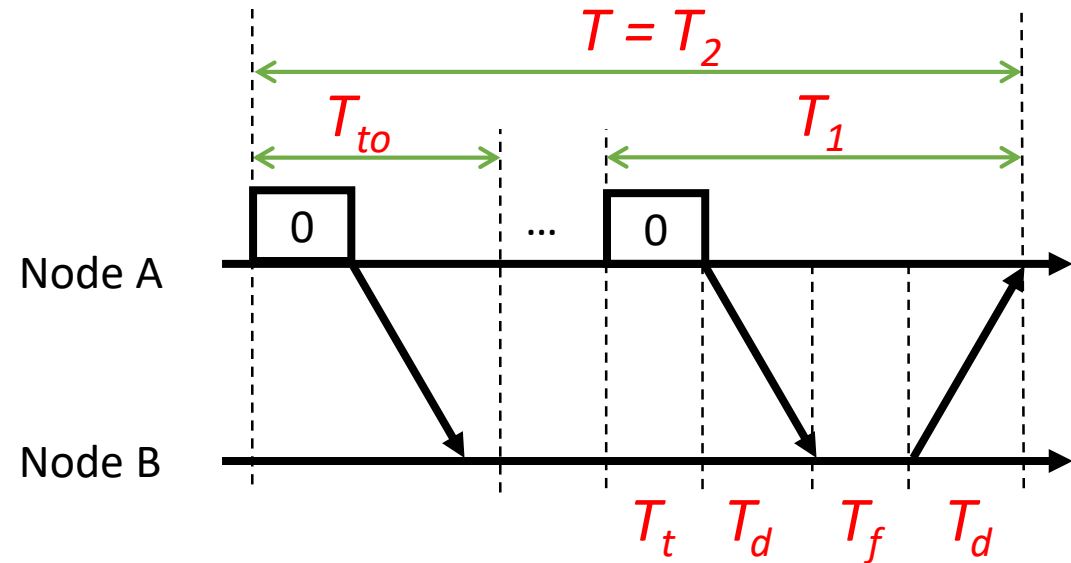
- ✓ With chances of error,

$$T = T_2 = T_1 + T_{to}(EX-1)$$

$$EX = q^{-1}$$

(Refer to the note for a proof)

- ✓ **Latency depends on T_{to} and q**



EX : the expected number of times a packet must be transmitted for a stop-and-wait system

q : the probability that a packet is correctly received and acked on a given transmission

T_{to} : length of a timer (i.e., duration before a time-out)

T_t : packet transmission time

T_2 : total time between the transmission of a packet and reception of its Ack

Effects of the length of timer

- Setting $T_{to} > T_1$, we have

$$T_2 = T_1 + T_{to}(q^{-1}-1) > q^{-1}T_1$$

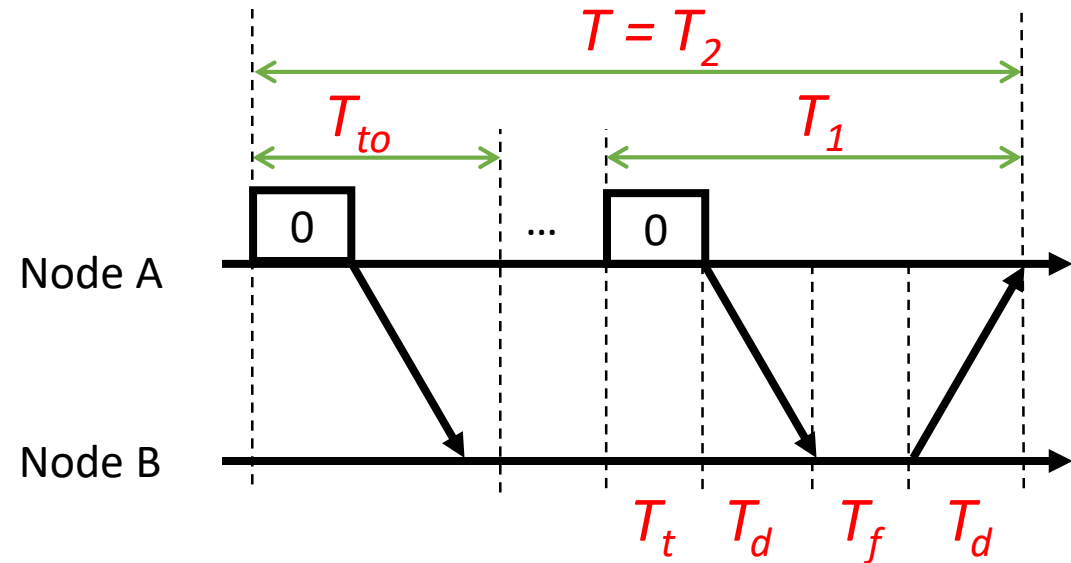
- setting $T_{to} < T_1$, make sense?

➤ will cause additional redundancy

➤ but then we have $T_2 < q^{-1}T_1$, which gives us a way to bound the latency.

➤ The percentage of increase in latency is $(T_2 - T_1)/T_1 < (1 - q)/q$.

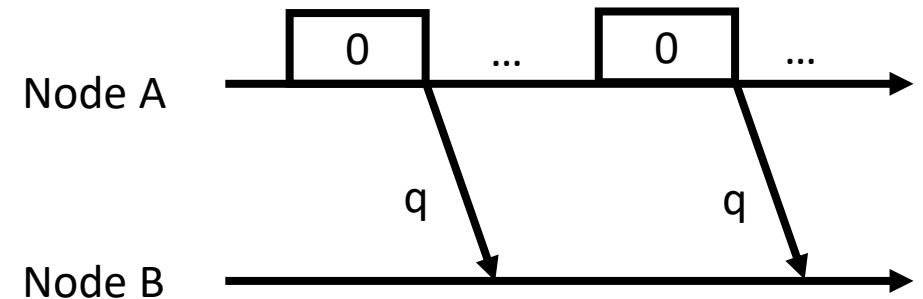
- Exercise: plug in different values of q and see how T changes



Another way to look at efficiency of the stop-and-wait : link goodput

- Way #2 (link goodput): (way #1 at slide #11)

Define efficiency E as the expected number of packets delivered to node B per frame from A to B



- ✓ **Efficiency $E = \frac{1}{EX} = q = 1-p$**
(Similar to the proof that we used for analyzing latency)

- ✓ **for all ARQ protocols, $E \leq 1-p$**

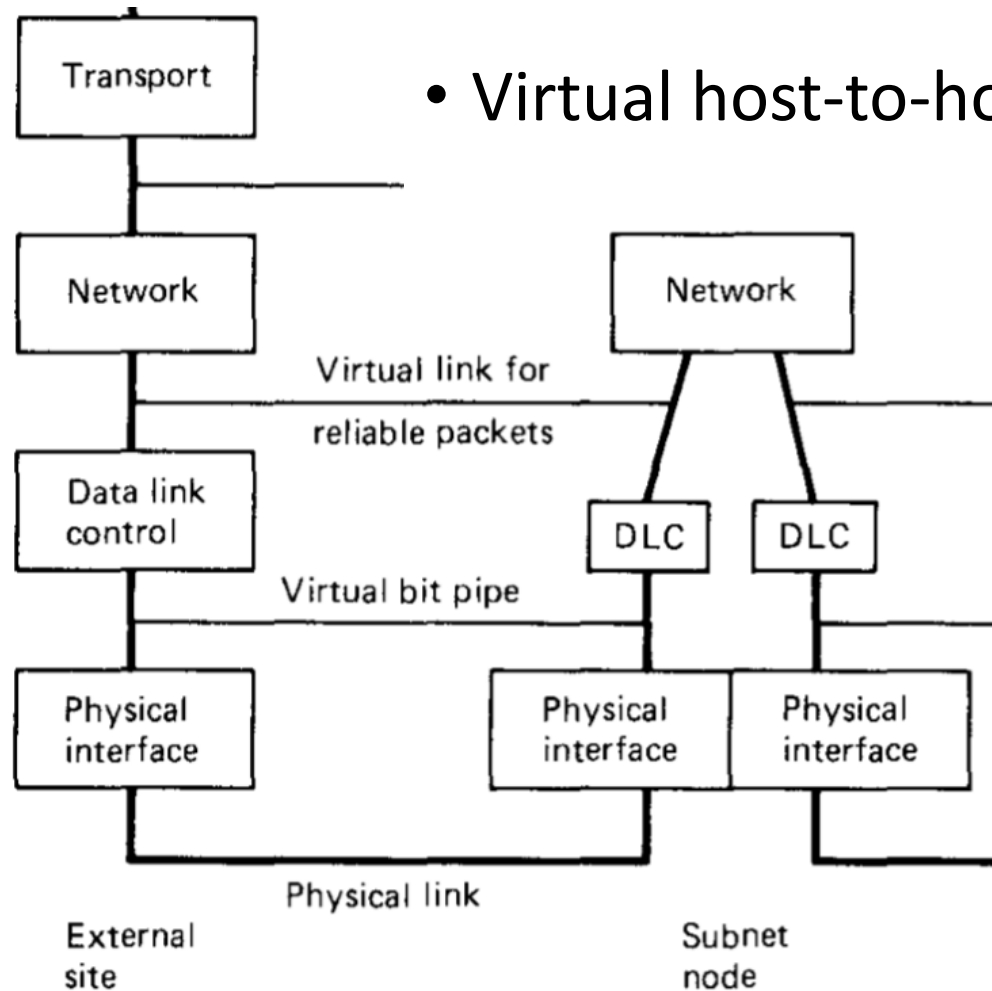
EX : the expected number of transmissions before the packet is correctly received
 p : the probability of frame error
 q : the probability of no frame error ($q=1-p$)

Outline of lecture04

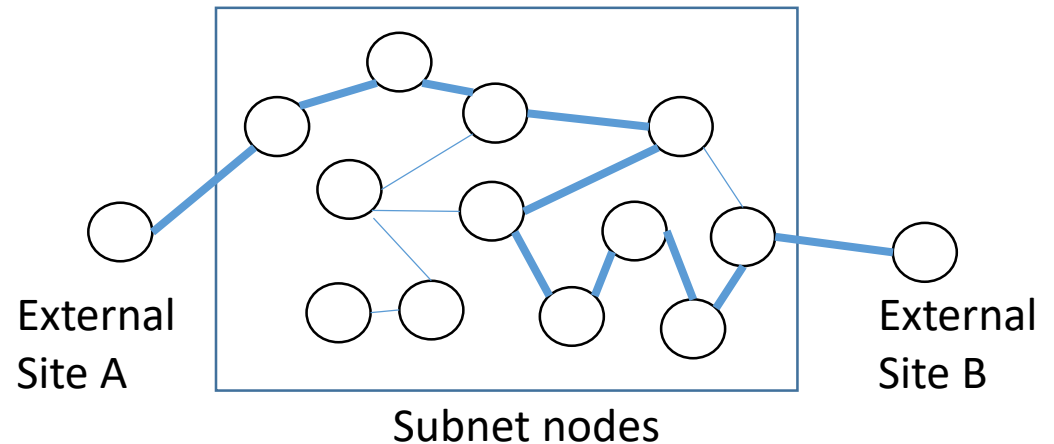
- Hamming code for error detection and correction
 - For this part, we will use the whiteboard.
- Data retransmission strategies and analysis (data link layer)
 - ARQ basics
- **Retransmission strategies at a higher layer**



Concept review of the network layer



- Virtual host-to-host packet service to the higher layers
- Each host (node) contains one network layer module
- Provide routing for the network:



Error recovery at higher layers

- Conceptually very similar to ARQ at the data link layer
 - Point-to-point error recovery: two nodes and a link in between
 - End-to-end error recovery: two sites and a subnet in between
 - May operate on a go-back-n/selective repeat basis
- Key difference: at higher layers, packets might arrive out of order
 - Solution candidates:
 - Enforce ordering
 - Use a large modulus number for packet numbering
 - Destroy a packet after some time
- Example: error recovery in TCP
 - You may refer to Sec. 2.9.3 in the textbook

