#### CSC0056: Data Communication

# Lecture 05: Point-to-Point Protocols (2)

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#### Course information



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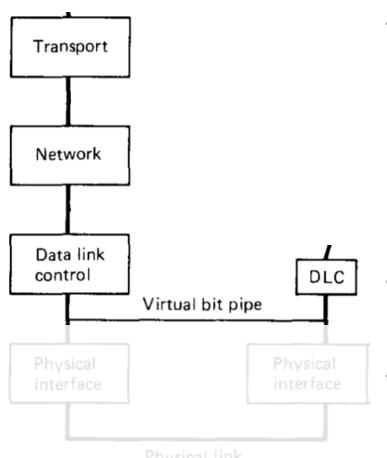
Acknowledgement: Some slides' materials in this course are borrowed with permission from the 2014 edition of the course taught by Prof. Yao-Hua Ho 賀耀華 Figures are obtained from the textbook available at http://web.mit.edu/dimitrib/www/datanets.html

#### Outline of lecture 05

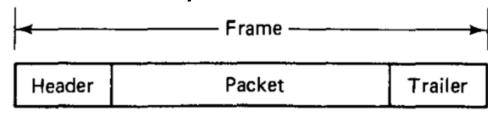
Lecture04 was cancelled due to typhoon

- Data retransmission strategies and analysis (data link layer)
  - Stop-and-wait ARQ
  - Go-back-N ARQ
  - Selective repeat
- Point-to-point protocols at higher layers

# Data transmission viewed from the data link layer



 Data link layer creates a frame by appending a header and trailer to each of the packet from the network layer

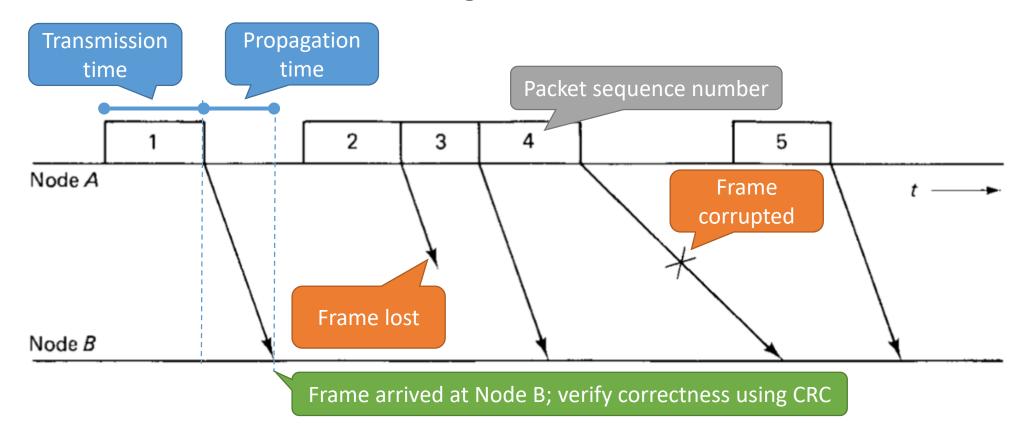


- Data link layer views the underlying point-topoint channel as an *unreliable* virtual bit pipe
- A frame could be lost or corrupted (i.e., contains errors) in the virtual bit pipe

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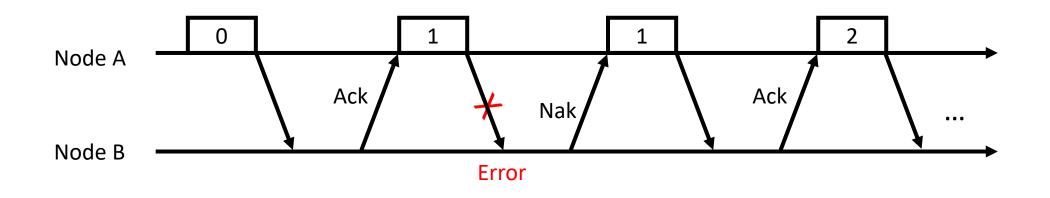
# ARQ: <u>Automatic Repeat Request</u>

Model and definition, assuming Node A sends frames to Node B



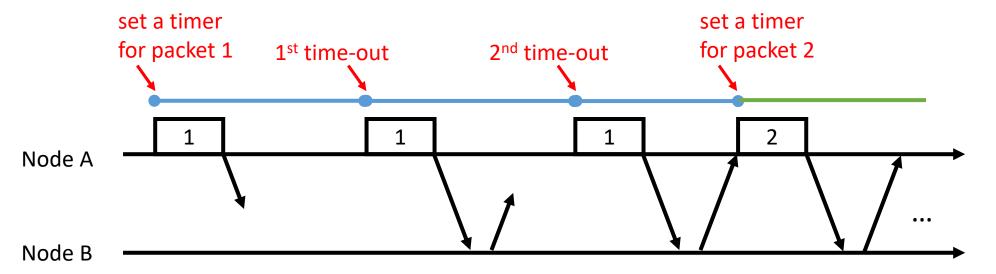
#### An initial idea of Stop-and-Wait ARQ

- Node A sends a new packet only if it received an acknowledgement from Node B (called an Ack)
- Node B sends an Ack if the received frame is error-free; otherwise, it sends a negative acknowledgement (called an Nak)



#### The need for time-out and re-transmission

- With no time-out, Node A may wait forever (for either Ack or Nak)
  if a frame is lost in either direction during transmission...
- Upon a time-out, Node A will re-transmit the same packet
- Design issue: what is a desirable length of a timer? (see later slides)



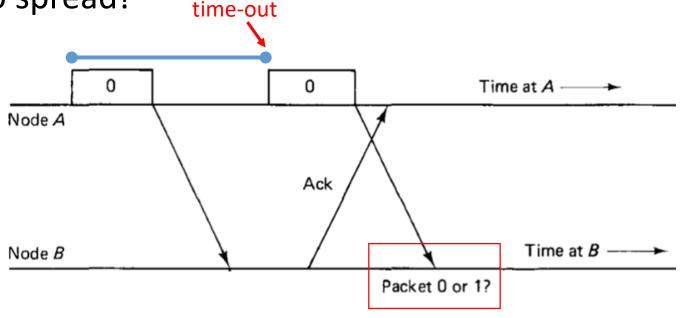
#### The need for packet sequence number

 Node B otherwise may not be able to tell if a frame contains a new packet or if a frame contains a previous packet

✓ In general, in designing distributed algorithms, a challenge is that

information takes time to spread!

Correctness and efficiency are two critical aspects in design of distributed algorithm.

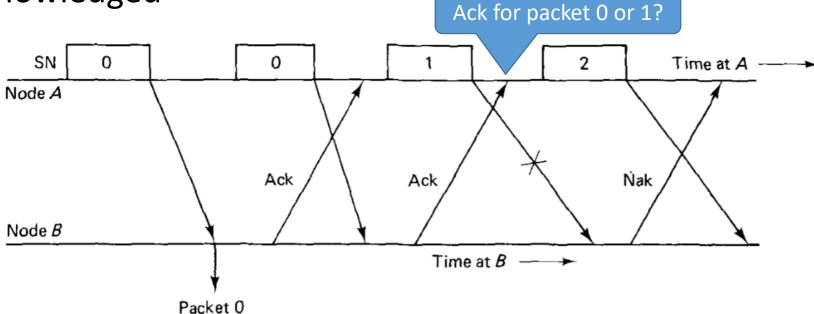


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## The need for distinct acknowledgements

With simple Ack/Nak, Node A might not be able to tell which packet

Node B acknowledged

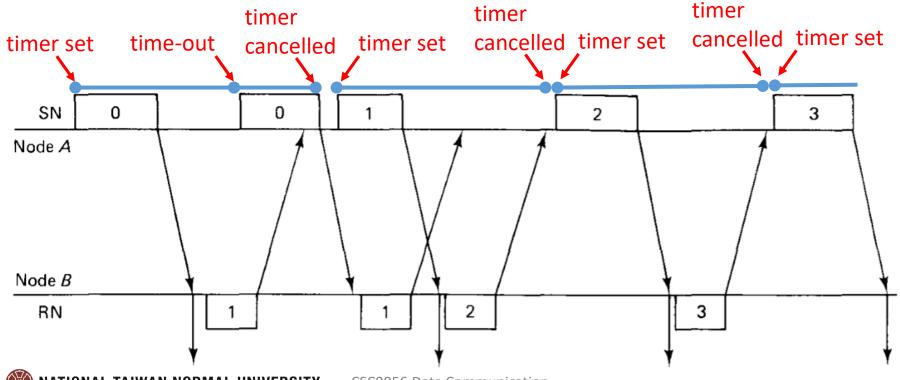


Solution: Node B sends the number of frame currently awaited

## A working version of stop-and-wait ARQ

• Using time-out, sequence number (SN), and request number (RN) to coordinate Nodes A and B

(Read the textbook for the assumptions and the algorithm)



## Analyzing efficiency of the stop-and-wait

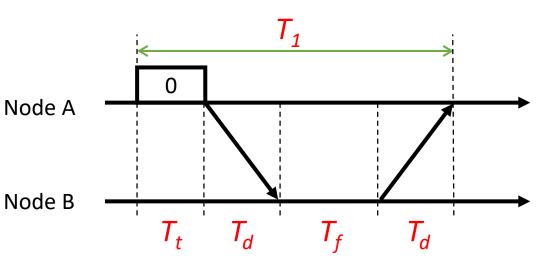
- There are several ways to look at efficiency
- Way #1 (latency): let *T* be the total time between the transmission of a packet and reception of its Ack

✓ If error-free, 
$$T = T_1 = T_t + 2T_d + T_f$$

 $T_t$ : packet transmission time

 $T_d$ : delay in propagation and processing

 $T_f$ : feedback transmission time

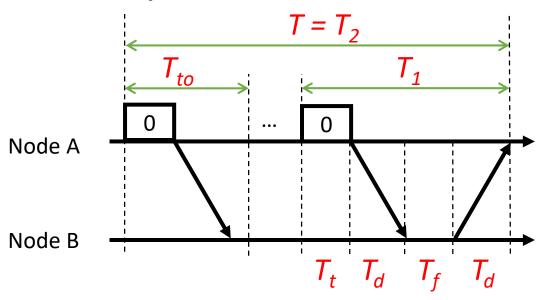


## Efficiency in terms of latency

✓ With chances of error,

$$T = T_2 = T_1 + T_{to}(EX-1)$$

$$EX = q^{-1}$$
(Refer to the note for a proof)



#### ✓ Latency depends on $T_{to}$ and q

EX: the expected number of times a packet must be transmitted for a stop-and-wait system

q: the probability that a packet is correctly received and acked on a given transmission

 $T_{to}$ : length of a timer (i.e., duration before a time-out)

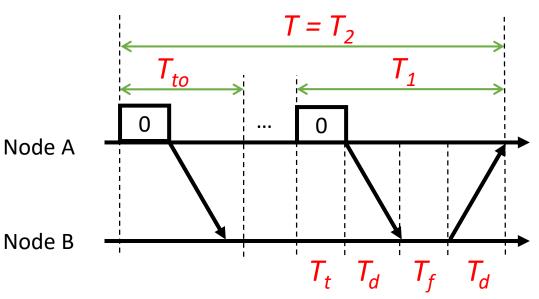
 $T_t$ : packet transmission time

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 $T_2$ : total time between the transmission of a packet and reception of its Ack

#### Effects of the length of timer

• Setting  $T_{to} > T_1$ , we have  $T_2 = T_1 + T_{to}(q^{-1}-1) > q^{-1}T_1$ 

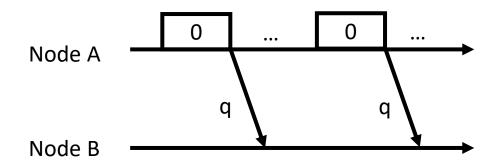


- setting  $T_{to} < T_1$ , make sense?
  - will cause additional redundancy
  - $\triangleright$  but then we have  $T_2 < q^{-1}T_1$ , which gives us a way to bound the latency.
  - The percentage of increase in latency is  $(T_2 T_1)/T_1 < (1 q)/q$ .
- Exercise: plug in different values of q and see how T changes

# Another way to look at efficiency of the stop-and-wait: link goodput

• Way #2 (link goodput): (way #1 at slide #11)

Define efficiency *E* as the expected number of packets delivered to node B per frame from A to B



✓ Efficiency E = 1/EX = q = 1-p

(Similar to the proof that we used for analyzing latency)

for all ARQ protocols,  $E \leq 1-p$ 

EX: the expected number of transmissions before the packet is correctly received

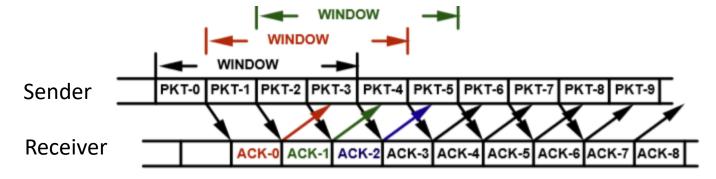
p: the probability of frame error

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q: the probability of no frame error (q=1-p)

# Improving over stop-and-wait: the go-back-N protocol (widely used)

- The **stop-and-wait** protocol is inefficient since the sender cannot send a new packet before the previous one is acknowledged
- The go-back-N protocol allows transmission of new packets before earlier ones are acknowledged
  - Maintain a sliding window where the sender can send packets that are within the window (range) of packets
  - The window advances as the sender received Acks for earlier packets



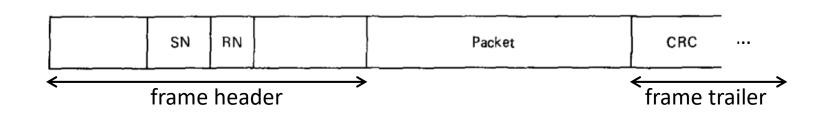
#### Algorithm of the go-back-N protocol

- Sender sets window size=N, and will not set packet i+N until it has received the acknowledgement for packet i
  - Let  $SN_{min}$  be the latest value of RN obtained from the receiver. The window includes packet indices ranging from  $SN_{min}$  to  $SN_{min}+N-1$
  - The sender goes back and re-transmits packet SN<sub>min</sub> when either it has reached the end of the window or a *time-out* occurred (the timer in this case is set for the time to send a full window of packets).
- Receiver operates just like that in the stop-and-wait protocol
  - Cannot accept packet out of order
  - Sending request number RN=*i*+1 means that it acknowledged all packets up to and including *i*

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## Consideration in sending request number RN

- In both stop-and-wait and go-back-N protocols, there are two ways a receiver may send request number RN:
  - 1. If traffic is unidirectional, the receiver sends a non-data frame containing the RN value
  - 2. If traffic is bi-directional, the receiver may *piggyback* RN in a frame going in the opposite direction; use non-data frame also, in the absence of traffic
  - ✓ Either way, the receiver must send out RN within bounded time





Example of go back 7 Received packet contain RN=1Window (0,6) (1,7) (2,8) (3,9) (5,11) SN = 0 1 2 3 4 5 6

Node A

 Note that packet RN-1 must be accepted at Node B before Node B can send a request for packet RN

Node B

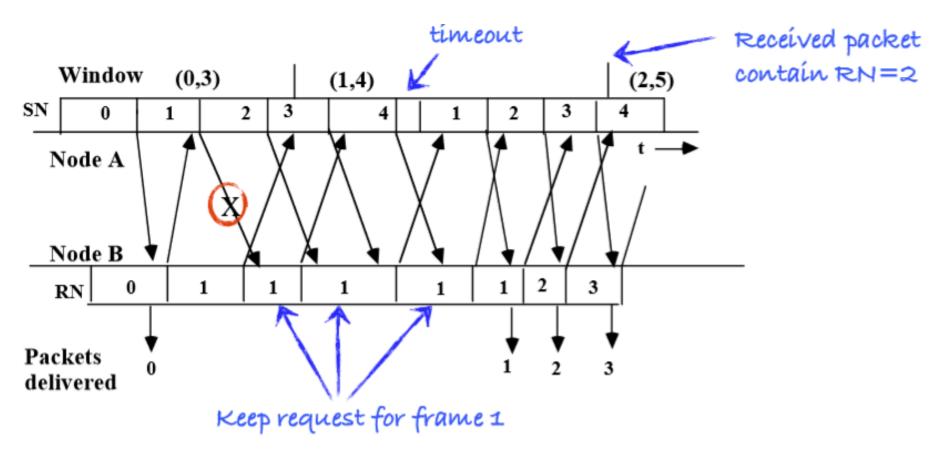
**Packets** 

delivered

 $\mathbf{R}\mathbf{N}$ 

0

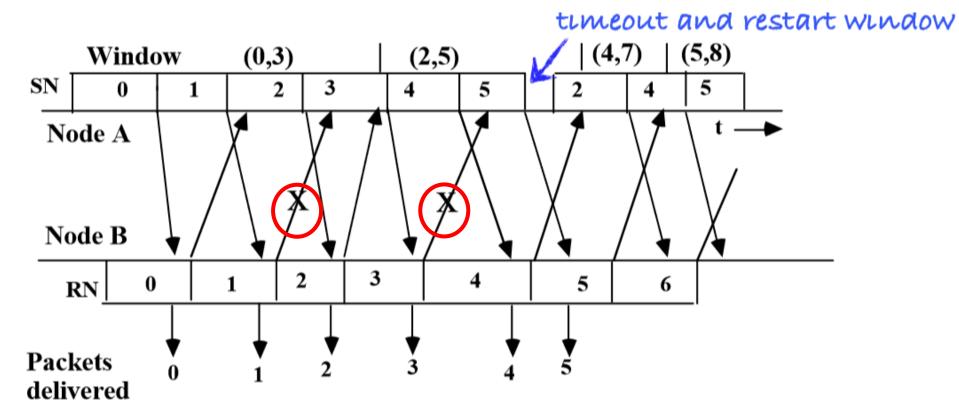
## Handling transmission error (go back 4)



After an error, the sender has to re-transmit the entire set of packets in a window

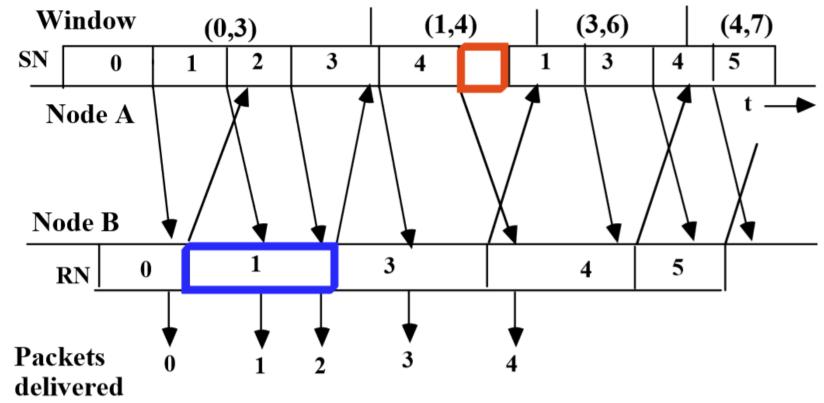
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## Handling feedback error (go back 4)



- Newer acknowledgements may prevent some re-transmissions : )
  - Examples: RN=2 and RN=4

## Effect of long frames (go back 4)



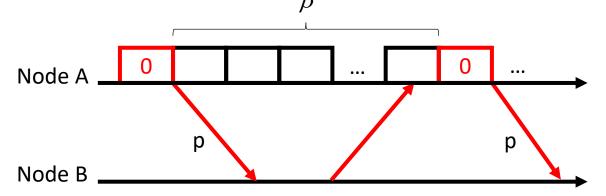
 Long feedback frames may cause a sender to wait or go back, since they slow down acknowledgements

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# Efficiency of the go back N protocol (link goodput)

• Define efficiency E as the expected number of packets delivered to node B per frame from A to B

✓ Efficiency 
$$E = 1/EX$$
  
=  $(1-p)/(1+p\beta)$   
(See the lecture note)



EX: the expected number of transmitted frames from A to B per successfully accepted packet at B

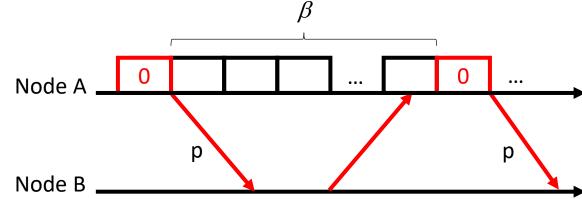
*p* : the probability of frame error

 $\beta$ : the expected number of transmitted frames from A to B between the transmission of a given frame and the reception of feedback about that frame

## Improving over go-back-N: the selective repeat protocol

 Go-back-N has improved over stop-and-wait in terms of waiting time before transmission

- But in terms of link goodput E
  - In stop-and-wait: E = 1-p
  - In go-back-N:  $E = (1-p)/(1+p\beta)$

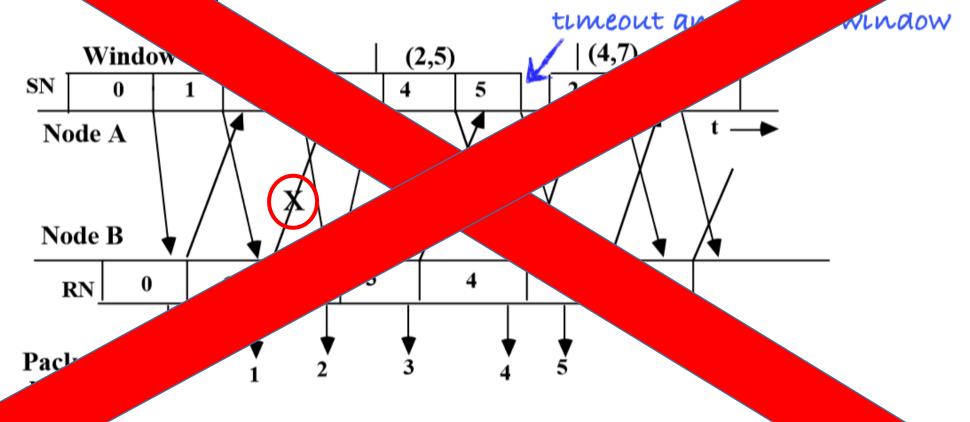


- The selective repeat protocol:
  - Request re-transmission only for those packets that are not correctly received
  - In other words, ideally  $\beta$  will decrease over time, which gives  $E \cong 1-p$

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#### E ple:

select repeat with window size =



wledged packets will not need to be re-sent

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# Requesting for re-transmission in selective repeat

- Implicit
  - The receiver acknowledges every good packet, packets that are not acknowledged before a time-out are subject to re-transmission
- Explicit
  - An explicit NAK can request ret-transmission of just one packet
  - This option can expedite the re-transmission
- ✓ One or both approaches are used in practice

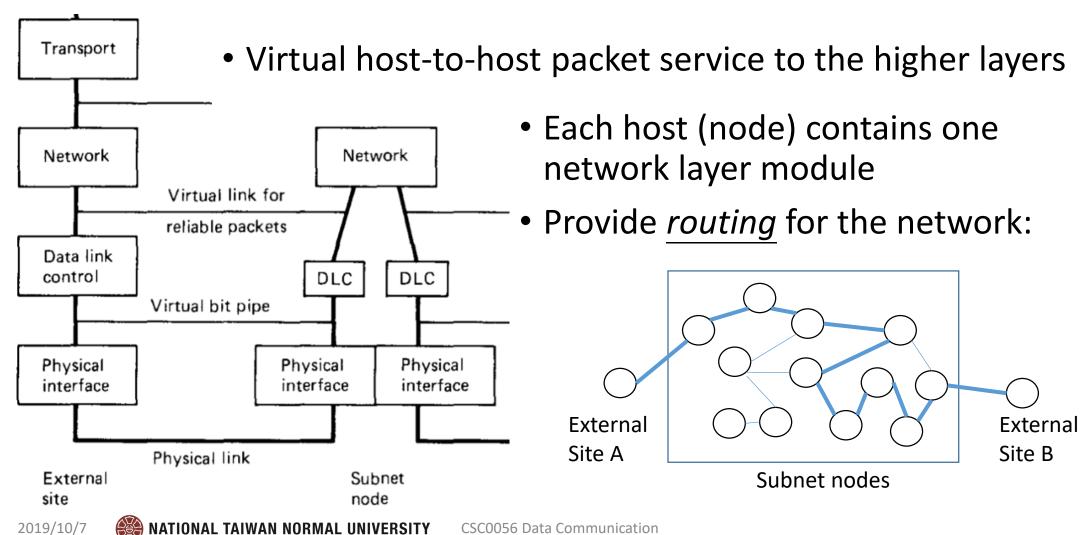
#### Rules of the selective repeat protocol

- Window protocol just like the go-back-N
  - Window size W
- Sender can transmit new packets as long as their number is with W of all unacknowledged packets
- Sender re-transmits unacknowledged packets after a time-out
  - or upon a NAK if NAK is employed
- Receiver acknowledges all correct packets
- Receiver in addition must <u>buffer all correct packets</u> until they can be deliver in order to the higher layer

#### Outline of lecture 05

- Data retransmission strategies and analysis (data link layer)
  - Stop-and-wait ARQ
  - Go-back-N ARQ
  - Selective repeat
- Point-to-point protocols at higher layers

#### Concept review of the network layer



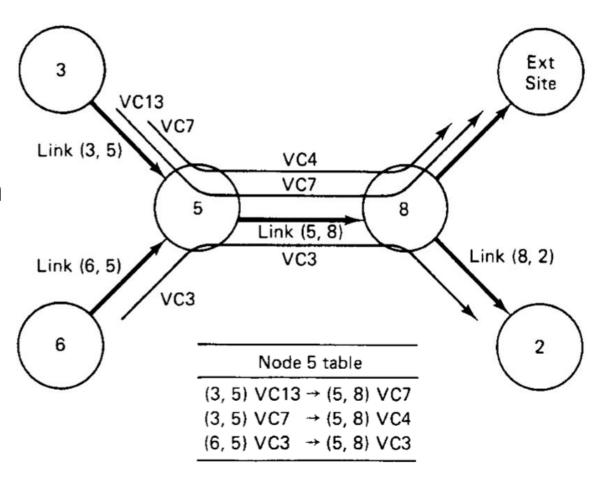
## Session identification and addressing

• Definition of a session:

A sequence of messages between two users over a network.

 At each node, need to distinguish packets of different sessions

- Example: virtual circuit routing
  - Use virtual channel numbers (VC#) to route packets over virtual circuits in the network



#### Error recovery at higher layers

- Conceptually very similar to ARQ at the data link layer
  - Point-to-point error recovery: two nodes and a link in between
  - End-to-end error recovery: two sites and a subnet in between
    - May operate on a go-back-n/selective repeat basis
- Key difference: at higher layers, packets might arrive out of order
  - Solution candidates:
    - Enforce ordering
    - Use a large modulus number for packet numbering
    - Destroy a packet after some time
- Error recovery in TCP (Sec. 2.9.3)

