Pan A Thévenin's Theorem ed: goal: Given on orbitrary linear circuit, we would like to know how it would respond to external excitation; in other word, we'd like to know its i-v characteristic. 1 Approach: leverage the concept of superposition! we append a testing current source, with the original circuit together they form a new circuit.

An arbitrary circuit

The property of the original circuit.

The property of the original current source, with the original circuit.

The property of the original current source, with the original current source, with the original circuit. !\<u>\</u> set itest =0 | set internal sources =0 Reg Z vb Ditest Voc: open-circuit voltage By superposition,  $V_t = V_a + V_b$ => equivalently, this relation > Vt = Voc + Itest Reg describes the following circuit: slope = Reg + + RTH Vt DAtest Voc V 75 × We rename Reg to RTH to honor Therenin

P28 Therefore, we have the following equivalence: ( fatest Voc D RTH OTitest In other word, we may reduce an arbitrary circuit to an equivalent circuit of the form: we name VTH = Voc V<sub>TH</sub> P<sub>TH</sub> in honor of Thevenin. Example:  $152 \times 252 \text{ } \Rightarrow \text{$ Another example = find I = ? calculating VTH: 252 ZSZ 10SZ VI 2A 222 - VTH

VTH = 2A × 252 = 4 V We may replace the left side calculating RTH:

Land E RTH = 2 52 of x-y by an equivalent circuit:  $\Rightarrow I = \frac{4}{2+10} = \frac{1}{3}A$ 

Exercise: create the Thevenin Equivalent Circuit 
$$P_{2q}$$
 for the following circuit:

 $R_1$ 
 $R_2$ 
 $R_3$ 
 $R_4$ 
 $R_4$ 
 $R_4$ 
 $R_5$ 
 $R_7$ 
 $R_7$ 

130 In the exercise on the previous page, you might wonder why we can do the following transformation:  $\begin{bmatrix} x_1 & x_2 & y_2 & y_3 & y_4 & y_5 & y_5 & y_6 & y_$ Could it be possible that there are some current flowing through R, and/or Rz? We can use KCL to figure it out: In  $\frac{2z}{R_1} \times for node Z_1$ , we have  $\begin{bmatrix}
R_1 & \frac{3}{2}R_2 & \hat{I}_a - \hat{I}_b - \hat{I}_c = 0 \\
\hat{I}_c & \frac{1}{2} & \frac{1}{2} & for node Z_2, we have
\end{bmatrix}$ notre = 0 compare Therefore, we see that na = 0. In practice, it is often helpful to think in terms of equivalent resistance, which may make the situation much more obvious:  $\begin{bmatrix} R_1 & \frac{3}{3}R_2 & 0 & \frac{3}{3}R_3 \\ R_1 & \frac{3}{3}R_2 & 0 & \frac{3}{3}R_3 \end{bmatrix} \times \underbrace{\begin{pmatrix} R_1 & 1/R_2 \end{pmatrix}}_{(R_1 & 1/R_2)}$ 

Exercise: In the following circuit, determine voltage Vo: I. D. 32R, 32, Vo We may do the following transformation:  $I. \bigcirc \begin{array}{c} & & & \\ & &$ then we might conclude that  $V_o = I_i \cdot R_i$ , but it is wrong. apare To see this, it could be helpful to clearly label the nodes between which you calculate the equivalent resistance:  $\frac{3R_1}{3R_1} = \frac{3R_1}{4} + \frac$ thus we see that Vo is not the voltage across A, B, and  $v_0 = (voltage across A, B) \times \frac{K_1}{R_1 + R_1}$  $= (I_1 \cdot R_1) \times \frac{R_1}{R_1 + R_1} = \frac{1}{2} I_1 R_1$  is the correct answer.