```
U-Boot TPL 2019.07 (Sep 01 2019 - 15:37:34 +0530)
Trying to boot from BOOTROM
Returning to boot ROM...

U-Boot SPL 2019.07 (Sep 01 2019 - 15:37:34 +0530)
Trying to boot from MMC1
Expected Linux image is not found. Trying to start U-boot

U-Boot 2019.07 (Sep 01 2019 - 15:37:34 +0530)

Model: Amarula Vyasa-RK3288
DRAM:  2 GiB
MMC:   dwmmc@ff0c0000: 1, dwmmc@ff0f0000: 0
Loading Environment from MMC... *** Warning - bad CRC, using default environment

In:     serial
Out:   serial
Err:   serial
Model: Amarula V
Net:  eth0: ethe
Hit any key to s
switch to partit
=>
```

2019 State of U-Boot Development Report

Jagan Teki, Amarula Solutions | OSFC 2019

Jagan Teki

- ➔ CEO and Embedded Linux Engineer at Amarula Solutions
  - ◆ *Bootloader*: BootROM, bootloaders, U-Boot, boot bsps, chip/board bring ups, devicetrees, device drivers, boottime, secure boot, atf, optee and etc.
  - ◆ *Embedded Linux*: Linux bsps, devicetrees, device drivers, multimedia, optimizations, integrations and etc.

- ➔ Mainline contributions
  - ◆ **Linux**
    - Contributor of Allwinner, Rockchip, i.MX platforms, bsps, device drivers.
    - Maintainer of few **DSI** LCD panels.
  - ◆ **U-Boot**
    - Contributor of Xilinx Zynq, Allwinner, Rockchip, i.MX platforms, bsps, device drivers.
    - Maintainer of Allwinner **sunXi** SoCs
    - Maintainer of **SPI/SPI-NOR** Subsystems
  - ◆ Contributor of **Buildroot**, **Yocto**

Agenda

U-Boot background

- ➔ Das U-Boot
- ➔ Supporting platforms/languages
- ➔ Development process
- ➔ Project statistics

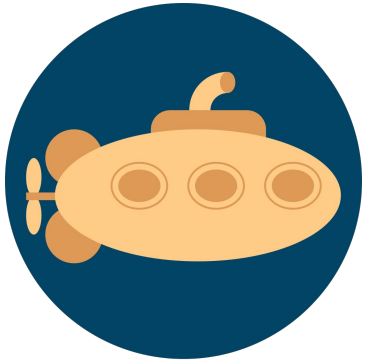
Features merged till v2019.07

- ➔ Build systems, tools
- ➔ U-Boot, stages
- ➔ Image boot, complexities
- ➔ Devicetree, improvements
- ➔ Driver model
- ➔ Firmware upgrades
- ➔ Miscellaneous

Summary

- ➔ Lessons learned from 18 years of U-Boot
- ➔ Future plans

Das U-Boot



U-Boot

1876	162	1570136	~50	Wolfgang Denk, Tom Rini	v2019.07
Developers	Employers	Lines of Code	Maintainers	Head	Recent release

Source: cloc and gitgm with v1.3.0...v2019.10-rc3

Supporting platforms and languages

Architecture/SoC

ARM32: Aspeed, Altera, Allwinner, Atmel, Broadcom, Qemu, Qualcomm, Marvell, NXP, Rockchip, STM32, Tegra, TI, UniPhier, Xilinx

ARM64: Allwinner, Marvell, NXP, Rockchip, Tegra, UniPhier, Xilinx

X86 (Baytrail, Broadwell, Quark, etc)

ARC, M68K, MicroBlaze, MIPS, NDS32, NIOS2, PowerPC, RISCV, Sandbox, SuperH, Xtensa

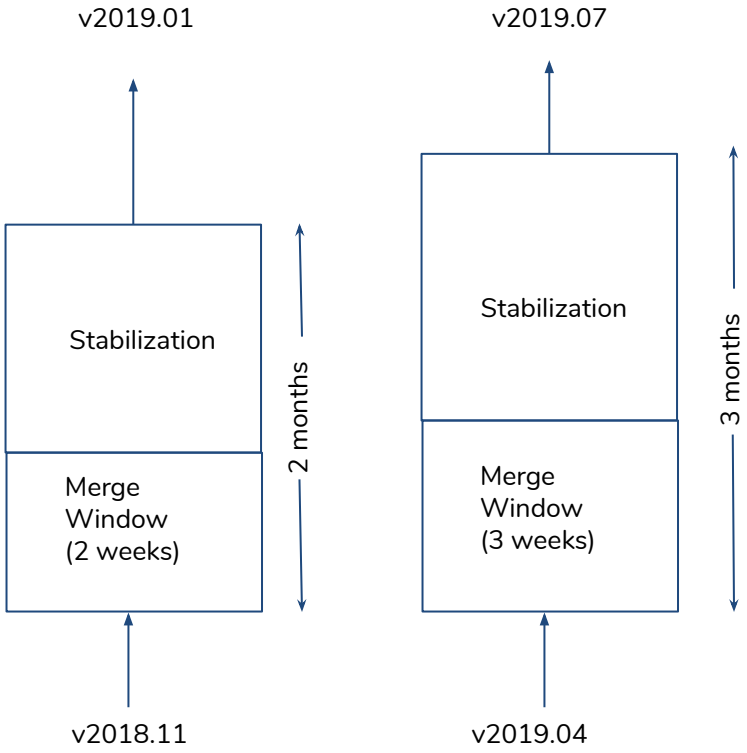
Boards

185+ different board vendors
~1400 different boards

Language

C
C/C++ Header
Assembly
Python
make
Perl
Bourne Shell
C++
yacc
YAML
Glade
lex
NAnt script
Markdown
Bourne Again Shell
DOS Batch
CSS
Kermit
Tcl/Tk
sed
INI

Development process



U-Boot Version	Release Date	Development Duration
v2019.07	2019-07-18	101
v2019.04	2019-04-08	84
v2019.01	2019-01-14	61
v2018.11	2018-11-14	65
v2018.09	2018-09-10	63
v2018.07	2018-07-09	63
v2018.05	2018-05-07	55
v2018.03	2018-03-13	64
v2018.01	2018-01-08	56
v2017.11	2017-11-13	63
v2017.09	2017-09-11	63
v2017.07	2017-07-10	63
v2017.05	2017-05-08	56
v2017.03	2017-03-13	63
v2017.01	2017-01-09	56
v2016.11	2016-11-14	63

U-Boot Changesets, Code size

U-Boot Version	Development Duration	Change Set	No.Of Lines++	No.Of Lines--
v2019.07	101	2047	169802	64752
v2019.04	84	1193	76038	22237
v2019.01	61	1149	99015	19344
v2018.11	65	1105	78339	18402
v2018.09	63	983	62059	23685
v2018.07	63	1055	88664	54500
v2018.05	55	977	72596	38379
v2018.03	64	1193	101060	25747
v2018.01	56	785	46990	31695
v2017.11	63	989	107828	22718
v2017.09	63	1308	64047	36307
v2017.07	63	1371	100569	201667
v2017.05	56	915	86135	116801
v2017.03	63	664	41330	31385
v2017.01	56	883	112574	72846
v2016.11	63	1031	73321	20937

Who is Contributing the work

Developer Name	Changeset
Simon Glass	4951
Wolfgang Denk	3523
Tom Rini	3015
Marek Vasut	2081
Masahiro Yamada	2037
Stefan Roese	1737
Michal Simek	1255
Bin Meng	1232
Heinrich Schuchardt	919
Fabio Estevam	899
Jagan Teki	853
Mike Frysinger	808
Stephen Warren	746
Kumar Gala	662
Peng Fan	614
Heiko Schocher	611
York Sun	587
Hans de Goede	548
Nobuhiro Iwamatsu	474
Kever Yang	435
Lokesh Vutla	415
Joe Hershberger	409
Stefano Babic	403
Philipp Tomsich	379

Who is Sponsoring the work

Employer Name	Changeset	%
(Unknown)	14229	26.8%
NXP	5979	11.3%
Google, Inc.	5206	9.8%
DENX Software Engineering	5041	9.5%
Texas Instruments	3021	5.7%
Xilinx	1538	2.9%
Socionext Inc.	1178	2.2%
Samsung	1130	2.1%
NVidia	941	1.8%
Analog Devices	908	1.7%
Panasonic	879	1.7%
ST Microelectronics	868	1.6%
Konsulko Group	728	1.4%
Amarula Solutions	690	1.3%
Linaro	683	1.3%
Rockchip	669	1.3%
Red Hat	551	1.0%
Atmel	490	0.9%
Renesas Electronics	447	0.8%
Guntermann & Drunck	442	0.8%
Bootlin	426	0.8%
National Instruments	415	0.8%
Toradex	408	0.8%
CompuLab	340	0.6%

Note: Top 25 developers/employers till v2019.10-rc3

Who is Reporting the work

Employer Name	Changeset	%
Simon Glass	61	9.1%
Fabio Estevam	53	7.9%
Tom Rini	46	6.8%
Michal Simek	36	5.4%
Lokesh Vutla	35	5.2%
Alexander Graf	32	4.8%
Masahiro Yamada	28	4.2%
Heinrich Schuchardt	27	4.0%
Stephen Warren	19	2.8%
Nishanth Menon	19	2.8%
Bin Meng	15	2.2%
Joe Hershberger	12	1.8%
Chris Packham	11	1.6%
Patrice Chotard	11	1.6%
Mike Frysinger	10	1.5%
Philipp Tomsich	8	1.2%
Anatolij Gustschin	8	1.2%
Simon Goldschmidt	8	1.2%
Hans de Goede	7	1.0%
York Sun	6	0.9%
Jagan Teki	6	0.9%
Jean-Jacques Hiblot	6	0.9%
Roger Quadros	6	0.9%
Kim Phillips	6	0.9%
Marek Vasut	5	0.7%

Note: Top 25 bug reports till v2019.10-rc3

Bringing in new developers

U-Boot Version	Change Set	No.Of Developers	No.Of Employers
v2019.07	2047	215	28
v2019.04	1193	182	25
v2019.01	1149	140	25
v2018.11	1105	130	28
v2018.09	983	138	28
v2018.07	1055	141	27
v2018.05	977	128	23
v2018.03	1193	151	25
v2018.01	785	132	29
v2017.11	989	123	27
v2017.09	1308	130	25
v2017.07	1371	129	27
v2017.05	915	139	26
v2017.03	664	126	26
v2017.01	883	136	24
v2016.11	1031	114	22

U-Boot Build Systems

- ➔ Kbuild
- ➔ Kconfig
- ➔ Tools

Kbuild

Gitlab master or dev tree at
https://gitlab.com/u-boot/u-boot

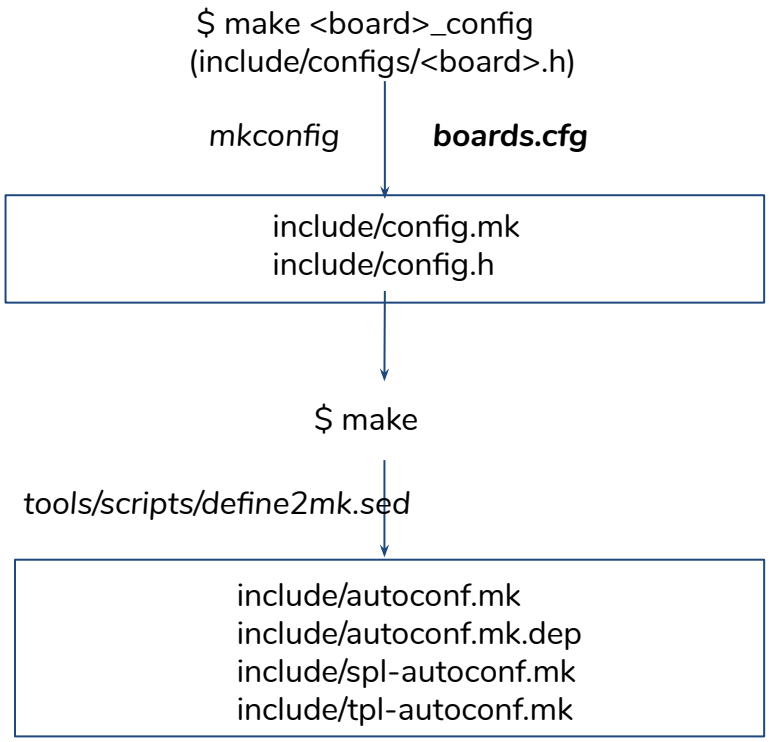
Custodian's or Maintainers tree at
https://gitlab.denx.de/u-boot/custodians

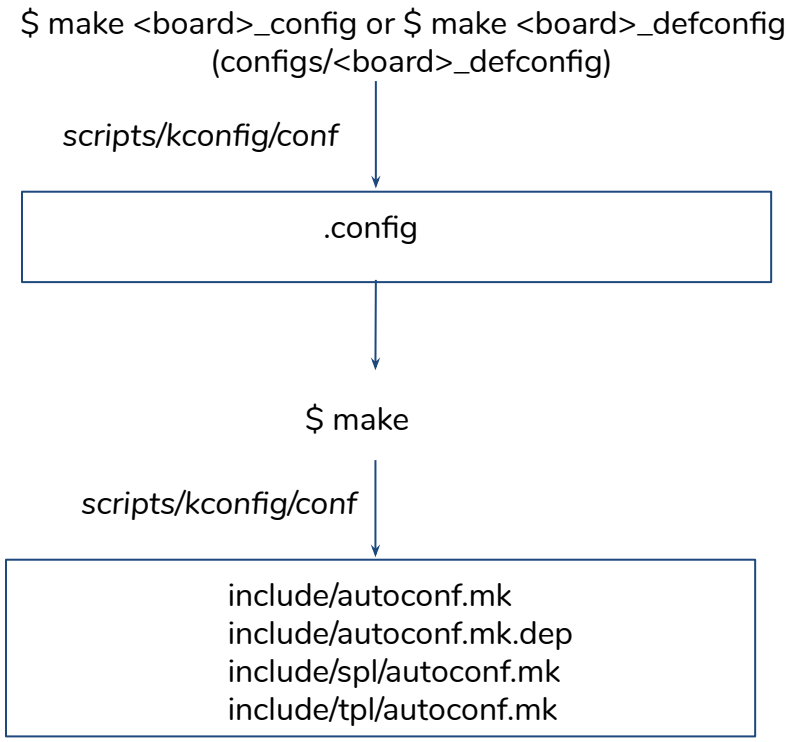
Example of building vyasa RK3288 board
$ git clone git://gitlab.com/u-boot/u-boot.git
$ u-boot
$ export ARCH=arm
$ export
CROSS_COMPILE=arm-linux-gnueabi-
$ make vyasa-rk3288_defconfig
$ make

```
  scripts/kconfig/conf  --syncconfig Kconfig
  CHK     include/config.h
  UPD     include/config.h
  CFG     u-boot.cfg
  GEN     include/autoconf.mk
  GEN     include/autoconf.mk.dep
  CFG     spl/u-boot.cfg
  GEN     spl/include/autoconf.mk
  CFG     tpl/u-boot.cfg
  GEN     tpl/include/autoconf.mk
  CHK     include/config/uboot.release
  UPD     include/config/uboot.release
  CHK     include/generated/version_autogenerated.h
  UPD     include/generated/version_autogenerated.h
  CHK     include/generated/timestamp_autogenerated.h

  LD      arch/arm/cpu/built-in.o
  CC      arch/arm/cpu/armv7/cache_v7.o
  AS      arch/arm/cpu/armv7/cache_v7_asm.o
  CC      arch/arm/cpu/armv7/cpu.o
  CC      arch/arm/cpu/armv7/cp15.o
  CC      arch/arm/cpu/armv7/syslib.o
  AS      arch/arm/cpu/armv7/sctlr.o
  AS      arch/arm/cpu/armv7/lowlevel_init.o
  LD      arch/arm/cpu/armv7/built-in.o
  AS      arch/arm/cpu/armv7/start.o
  CC      arch/arm/lib/eabi_compat.o
  AS      arch/arm/lib/crt0_arm_efi.o
  CC      arch/arm/lib/reloc_arm_efi.o
  CC      arch/arm/mach-rockchip/boot_mode.o
  CC      arch/arm/mach-rockchip/rk3288-board.o
  CC      arch/arm/mach-rockchip/sdram_common.o
  CC      arch/arm/mach-rockchip/rk_timer.o
  CC      arch/arm/mach-rockchip/rk3288/clk_rk3288.o
  CC      arch/arm/mach-rockchip/rk3288/rk3288.o
  CC      arch/arm/mach-rockchip/rk3288/syscon_rk3288.o
  CC      board/amarula/vyasa-rk3288/vyasa-rk3288.o
```

```
  CC      spl/arch/arm/mach-rockchip/sdram_common.o
  CC      spl/arch/arm/mach-rockchip/rk_timer.o
  CC      spl/arch/arm/mach-rockchip/rk3288/clk_rk3288.o
  CC      spl/arch/arm/mach-rockchip/rk3288/rk3288.o
  CC      spl/arch/arm/mach-rockchip/rk3288/syscon_rk3288.o
  CC      spl/arch/arm/mach-rockchip/bootrom.o
  CC      spl/arch/arm/mach-rockchip/rk3288-board-spl.o
  CC      spl/arch/arm/cpu/armv7/cache_v7.o
  CC      spl/arch/arm/cpu/armv7/cpu.o
  AS      spl/arch/arm/cpu/armv7/lowlevel_init.o
  AS      spl/arch/arm/cpu/armv7/start.o
  LD      spl/u-boot-spl
OBJCOPY   spl/u-boot-spl-nodtb.bin
  COPY    spl/u-boot-spl.dtb
  CAT     spl/u-boot-spl-dtb.bin
  COPY    spl/u-boot-spl.bin

  CC      tpl/arch/arm/mach-rockchip/sdram_common.o
  CC      tpl/arch/arm/mach-rockchip/rk_timer.o
  CC      tpl/arch/arm/mach-rockchip/rk3288/clk_rk3288.o
  CC      tpl/arch/arm/mach-rockchip/rk3288/rk3288.o
  CC      tpl/arch/arm/mach-rockchip/rk3288/syscon_rk3288.o
  CC      tpl/arch/arm/mach-rockchip/bootrom.o
  CC      tpl/arch/arm/mach-rockchip/rk3288-board-tpl.o
  CC      tpl/arch/arm/cpu/armv7/cache_v7.o
  AS      tpl/arch/arm/cpu/armv7/cache_v7_asm.o
  CC      tpl/arch/arm/cpu/armv7/cpu.o
  CC      tpl/arch/arm/cpu/armv7/cp15.o
  CC      tpl/arch/arm/cpu/armv7/syslib.o
  AS      tpl/arch/arm/cpu/armv7/lowlevel_init.o
  AS      tpl/arch/arm/cpu/armv7/start.o
  LDS     tpl/u-boot-spl.lds
  LD      tpl/u-boot-tpl
OBJCOPY   tpl/u-boot-tpl-nodtb.bin
  COPY    tpl/u-boot-tpl.bin
  COPY    u-boot.dtb
MKIMAGE   u-boot-dtb.img
```

Kconfig


$ make <board>_config
(include/configs/<board>.h)
mkconfig
boards.cfg
include/config.mk
include/config.h
$ make
tools/scripts/define2mk.sed
include/autoconf.mk
include/autoconf.mk.dep
include/spl-autoconf.mk
include/tpl-autoconf.mk


$ make <board>_config or $ make <board>_defconfig
(configs/<board>_defconfig)
scripts/kconfig/conf
.config
$ make
scripts/kconfig/conf
include/autoconf.mk
include/autoconf.mk.dep
include/spl/autoconf.mk
include/tpl/autoconf.mk

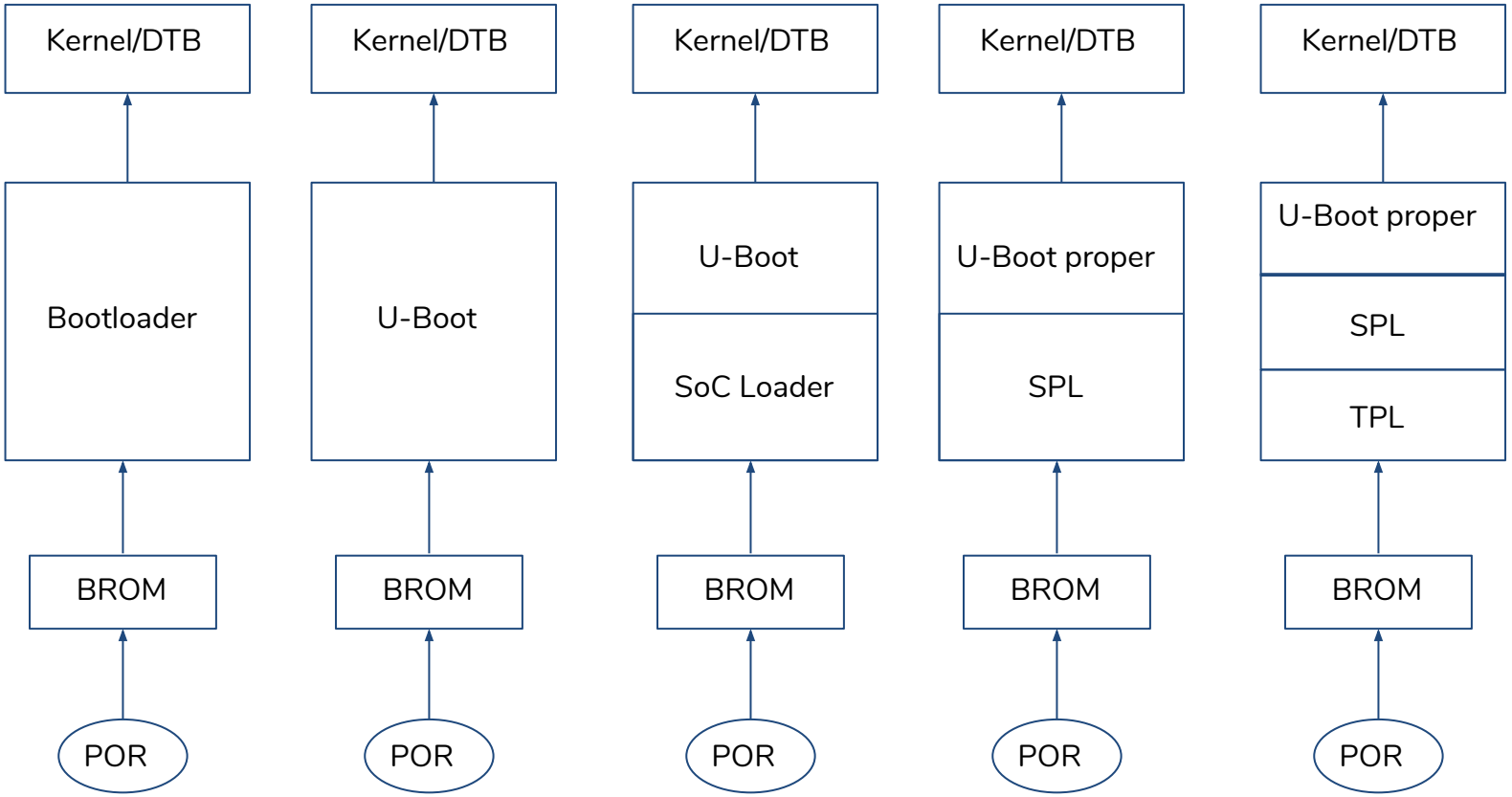
Tools: Build, Testing

- Patman
  - Manual patch creation, cover-letter, adding maintainers etc can be error-prone.
  - Create patch, insert cover-letter, add maintainer (via ~/.git-mailrc), run checkpatch.pl etc
  - How to use? tools/patman/README
- Buildman
  - U-Boot builder for multiple commits, branches etc
  - Replaced by legacy MAKEALL
  - Understandable output summary
  - tools/buildman/README

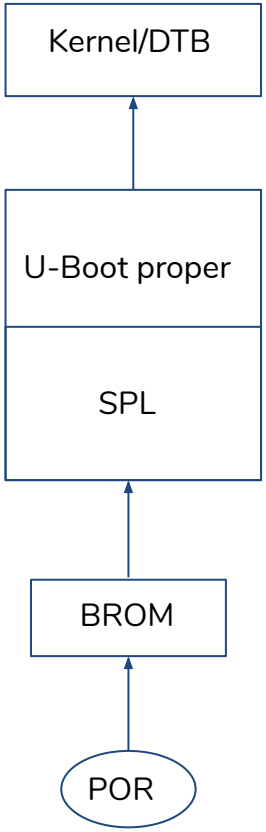
- travis-ci.org
  - Automated build environment, with limited run-time, free to use
  - May take longer duration, if more jobs are initiated
  - .travis.yml, u-boot travis build plugin
- test.py
  - Pytest framework
  - Works for sandbox, qemu, some real hardware
  - Sanity tests for dm code
  - doc/README.trace
- trace
  - Kind of Linux ftrace
  - Collect execution and sent to host for analysis

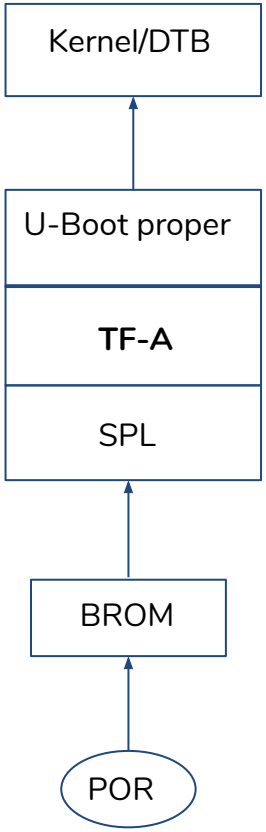
U-Boot, Stages

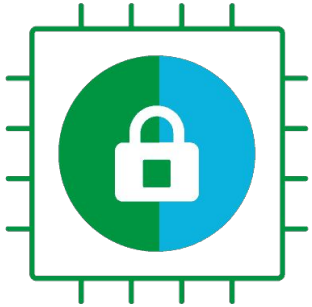
U-Boot


Kernel/DTB
Bootloader
BROM
POR
Kernel/DTB
U-Boot
BROM
POR
Kernel/DTB
U-Boot
SoC Loader
BROM
POR
Kernel/DTB
U-Boot proper
SPL
BROM
POR
Kernel/DTB
U-Boot proper
SPL
TPL
BROM
POR

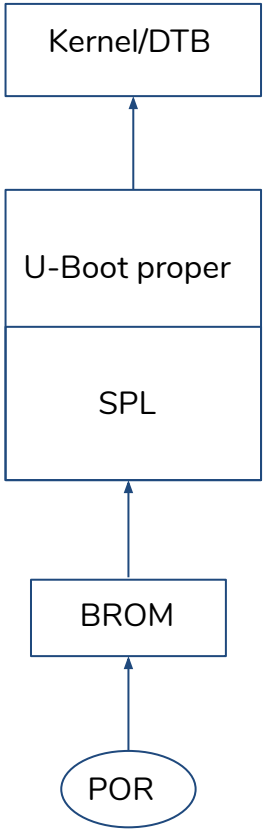
TF-A

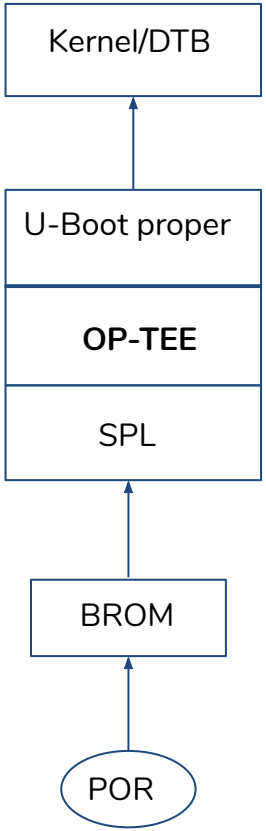

Kernel/DTB
U-Boot proper
SPL
BROM
POR

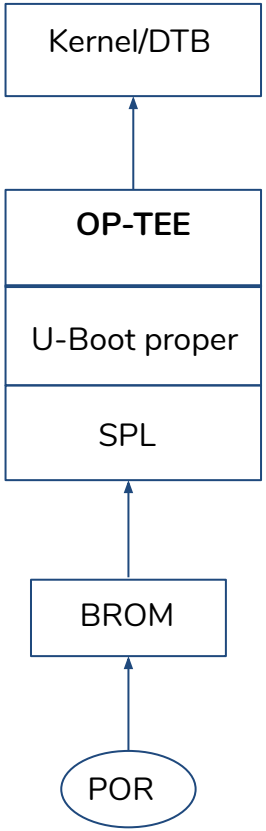

Kernel/DTB
U-Boot proper
TF-A
SPL
BROM
POR



OP-TEE, ARMv7

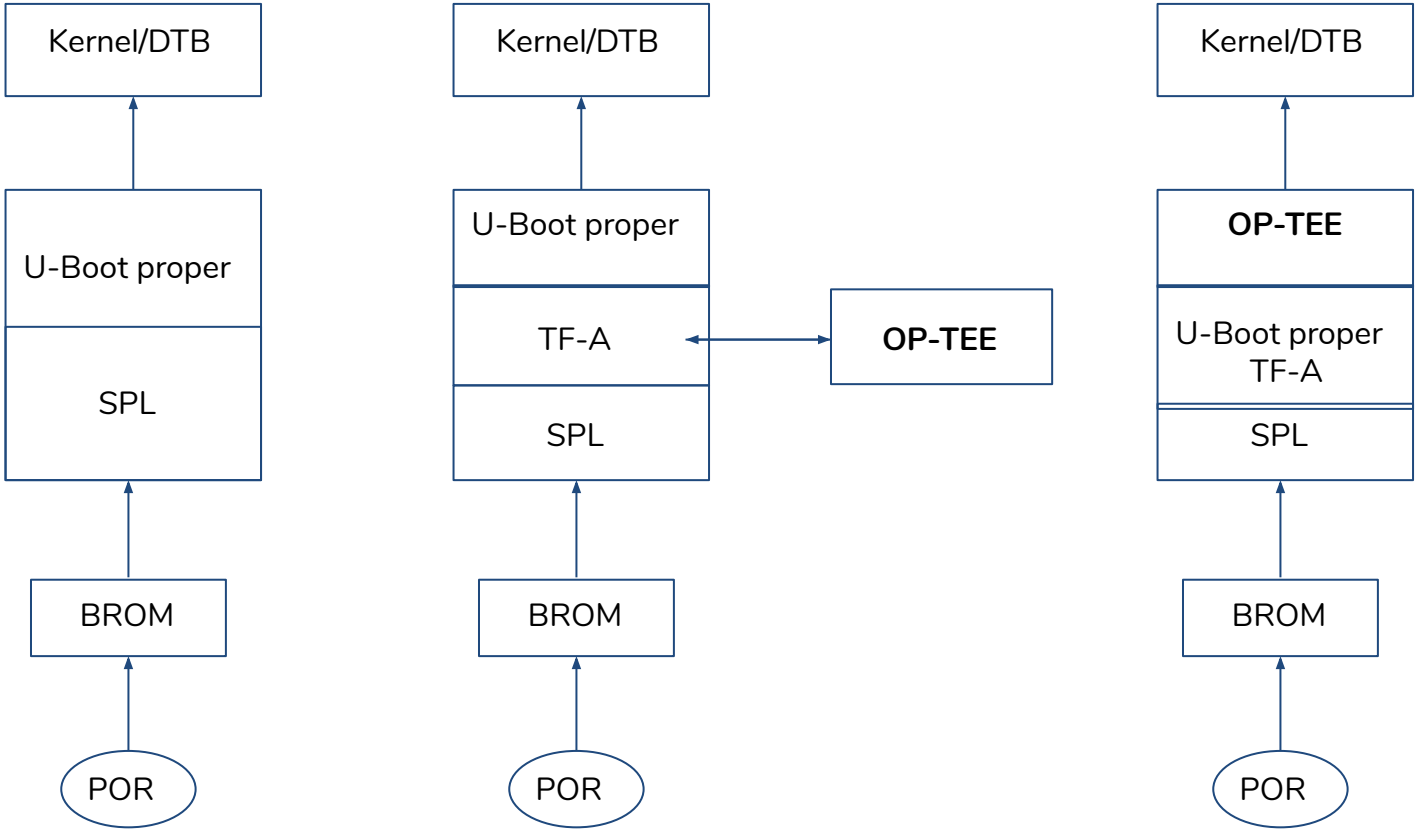

Kernel/DTB
U-Boot proper
SPL
BROM
POR


Kernel/DTB
U-Boot proper
OP-TEE
SPL
BROM
POR


Kernel/DTB
OP-TEE
U-Boot proper
SPL
BROM
POR


OP-TEE

OP-TEE, ARMv8


Kernel/DTB
U-Boot proper
SPL
BROM
POR
Kernel/DTB
U-Boot proper
TF-A
SPL
OP-TEE
BROM
POR
Kernel/DTB
OP-TEE
U-Boot proper
TF-A
SPL
BROM
POR

U-Boot Sequence

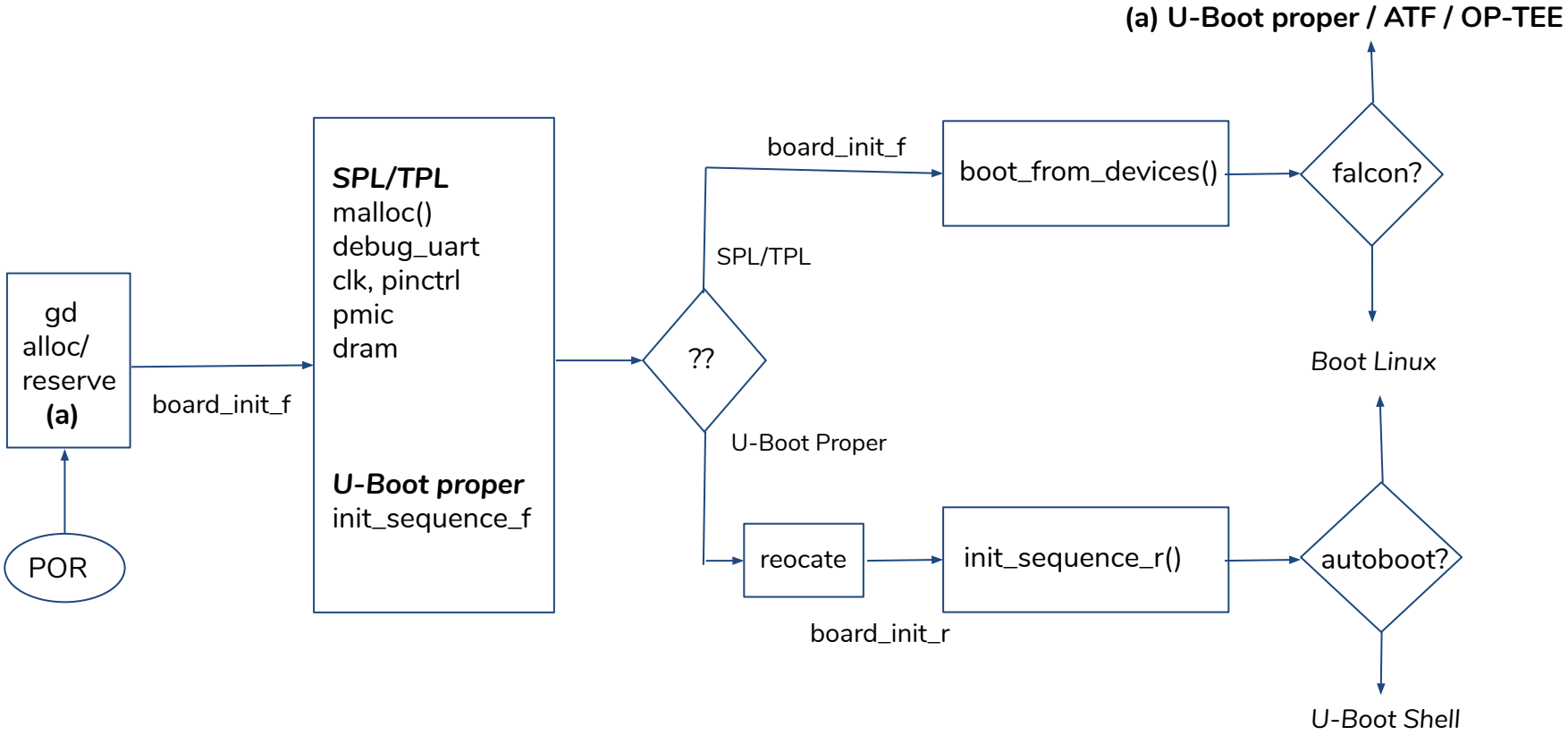


Image boot, Complexity

- ➔ Legacy image
- ➔ FIT
- ➔ Verified image
- ➔ Secure boot
- ➔ Falcon mode
- ➔ EFI boot
- ➔ Distro boot

Legacy Image

- ➔ Fixed offset images - standalone, zImage binaries
- ➔ go addr [arg ...]
- ➔ u-boot Image format
- ➔ Single component uImage
- ➔ Monolithic, combination of images
- ➔ bootm [addr [arg ...]]

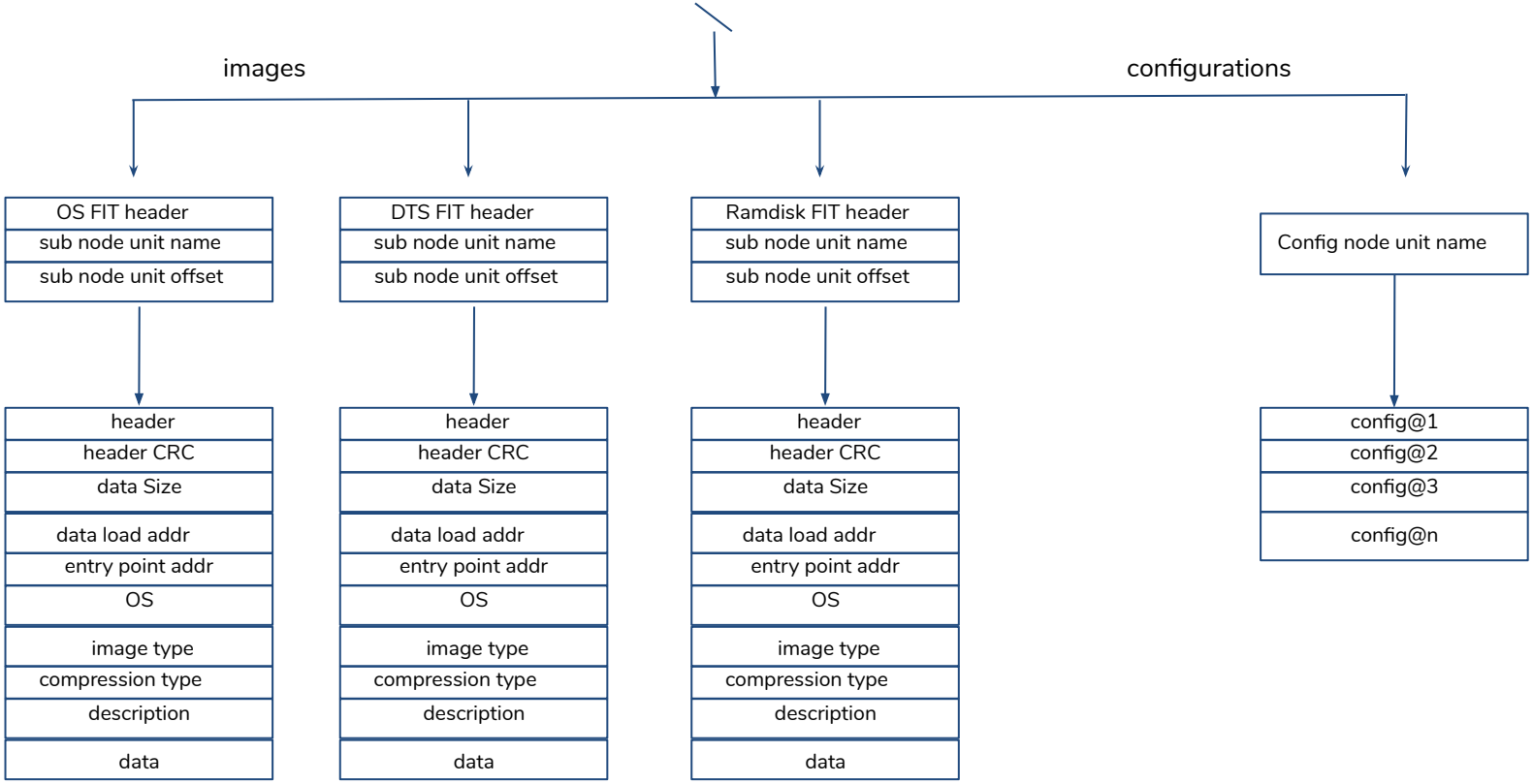
? Not flexible, indexing

? No hash integrity

? No scope of security addition

```
$ mkimage \
  > -A arm \
  > -O linux \
  > -T kernel \
  > -a 0x10008000 \
  > -e 0x10008000 \
  > -n "Linux-4.19.0-rc2" \
  > -d zImage uImage
Image Name:   Linux-4.19.0-rc2-next-20180905-0
Created:      Tue Sep 11 23:07:55 2018
Image Type:   ARM Linux Kernel Image (uncompressed)
Data Size:    8372992 Bytes = 8176.75 kB = 7.99 MB
Load Address: 10008000
Entry Point:  10008000


$ mkimage
> -A arm \
> -O linux \
> -T multi \
> -a 0x10008000 \
> -e 0x10008000 \
> -n 'Multi image' \
> -d vmlinux.bin.gz:ramdisk.image.gz:imx6q-icore-rqs.dtb uMulti
Image Name:   Multi image
Created:      Tue Sep 11 23:07:55 2018
Image Type:   ARM Linux Multi-File Image (gzip compressed)
Data Size:    82092755 Bytes = 80168.71 KiB = 78.29 MiB
Load Address: 10008000
Entry Point:  10008000
Contents:
   Image 0: 7609333 Bytes = 7430.99 KiB = 7.26 MiB
   Image 1: 74445331 Bytes = 72700.52 KiB = 71.00 MiB
   Image 2: 38071 Bytes = 37.18 KiB = 0.04 MiB

```

FIT (Flattened uImage Tree)



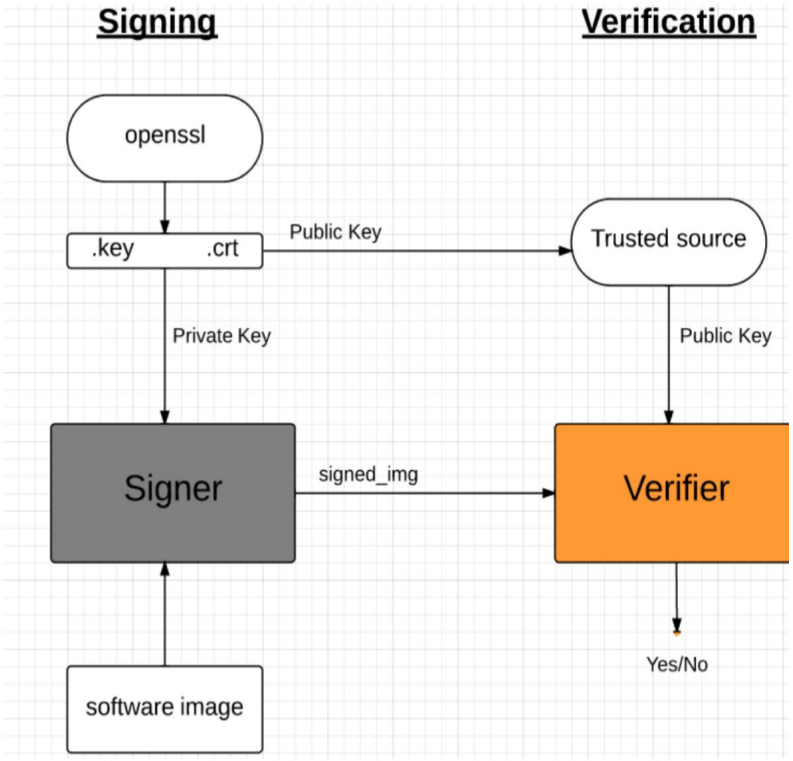
FIT, contd

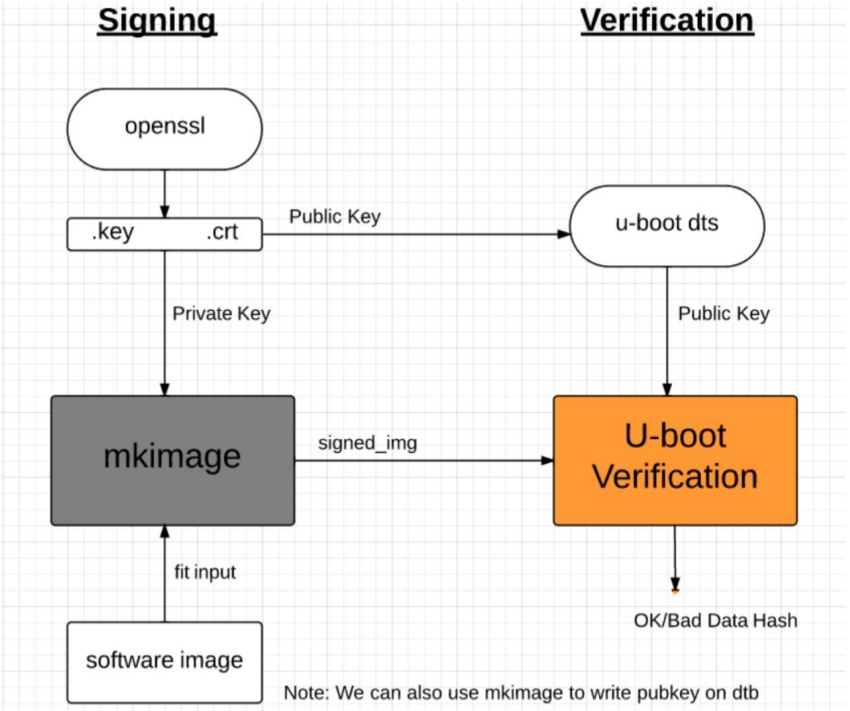
```
/dts-v1/;
/ {
    description = "FIT with single Linux kernel and FDT blob";
    #address-cells = <1>;
    images {
        kernel@1 {
            description = "i.MX6 Linux kernel";
            data = /incbin/("./vmlinux.bin.gz");
            type = "kernel";
            arch = "arm";
            os = "linux";
            compression = "gzip";
            load = <0x10008000>;
            entry = <0x10008000>;
            hash@1 {
                algo = "md5";
            };
            hash@2 {
                algo = "sha1";
            };
        };

        fdt@1 {
            description = "Engicam i.CoreM6 Quad/Dual RQS Starter Kit Devicetree blob";
            data = /incbin/("./imx6q-icore-rqs.dtb");
            type = "flat_dt";
            arch = "arm";
            compression = "none";
            hash@1 {
                algo = "md5";
            };
            hash@2 {
                algo = "sha1";
            };
        };
    };

    configurations {
        default = "conf@1";
        conf@1 {
            description = "Boot Linux kernel with FDT blob";
            kernel = "kernel@1";
            fdt = "fdt@1";
        };
    };
};
```

```
icorem6qdl-rqs> fatload mmc 0:1 $loadaddr fit.itb
reading fit.itb
6167494 bytes read in 335 ms (17.6 MiB/s)
icorem6qdl-rqs> bootm $loadaddr
Booting FIT image from mmc ...
## Loading kernel from FIT Image at 12000000 ...
   Using 'conf@1' configuration
   Verifying Hash Integrity ... OK
   Trying 'kernel@1' kernel subimage
     Description:  i.MX6 Linux kernel
     Type:         Kernel Image
     Compression:  gzip compressed
     Data Start:   0x120000f0
     Data Size:    6130148 Bytes = 5.8 MiB
     Architecture: ARM
     OS:           Linux
     Load Address: 0x10008000
     Entry Point:  0x10008000
     Hash algo:    md5
     Hash value:   b975a202ea2963c53c53f527329930cd
     Hash algo:    sha1
     Hash value:   78b93fe404b795de8c837af27d67f4df9b96083a
   Verifying Hash Integrity ... md5+ sha1+ OK
## Loading fdt from FIT Image at 12000000 ...
   Using 'conf@1' configuration
   Trying 'fdt@1' fdt subimage
     Description:  Engicam i.CoreM6 Quad/Dual RQS Starter Kit Devicetree blob
     Type:         Flat Device Tree
     Compression:  uncompressed
     Data Start:   0x125d8dbc
     Data Size:    35298 Bytes = 34.5 KiB
     Architecture: ARM
     Hash algo:    md5
     Hash value:   4371a4dfe55127c2fda8a9feb4d3b313
     Hash algo:    sha1
     Hash value:   e34a9326b5e7fd43557753ef980fe67326f82ea1
   Verifying Hash Integrity ... md5+ sha1+ OK
   Booting using the fdt blob at 0x125d8dbc
   Uncompressing Kernel Image ... OK
   Using Device Tree in place at 125d8dbc, end 125e479d

Starting kernel ...
```

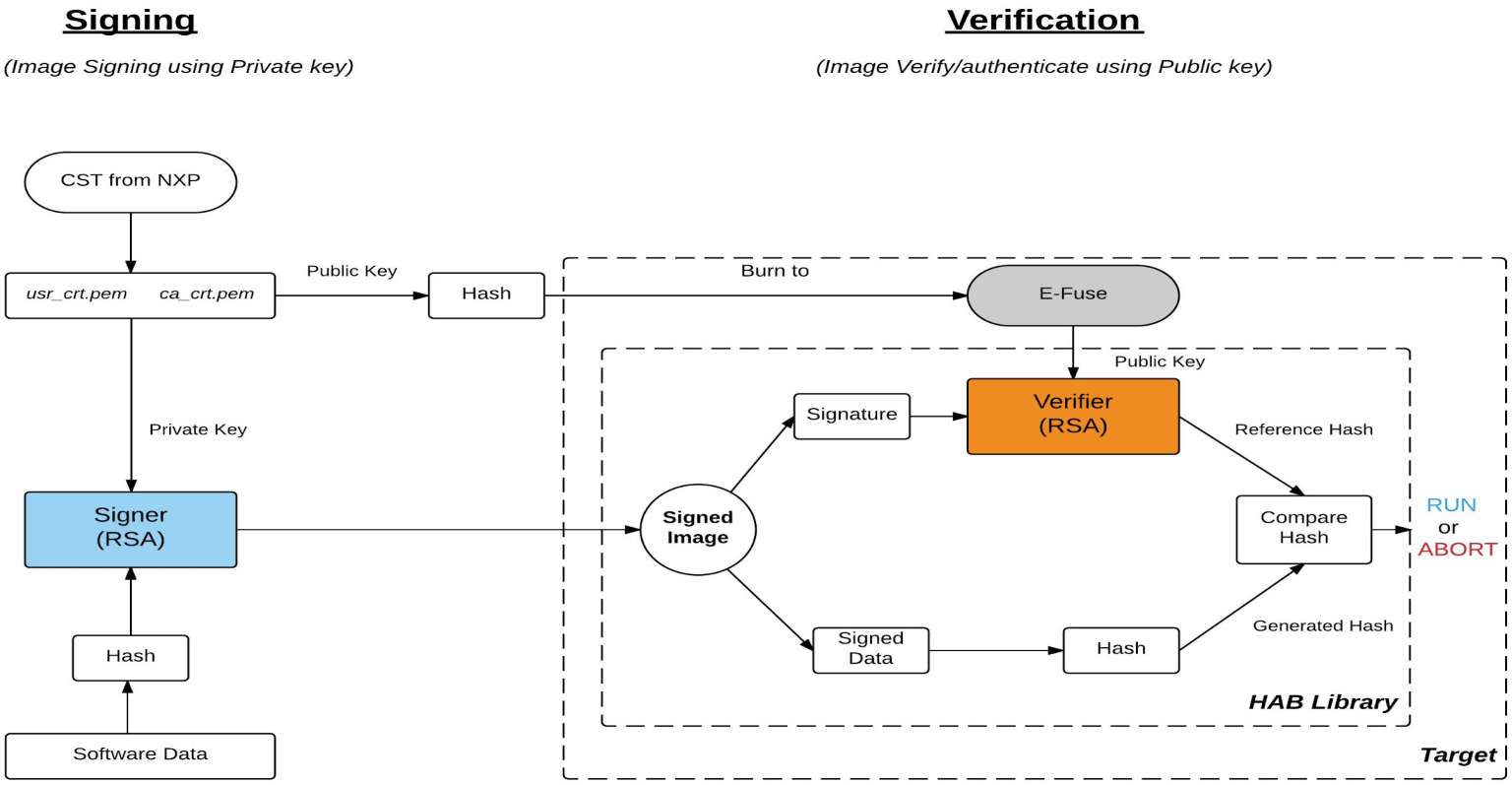
FIT Complexity ?

Verified boot (Software)

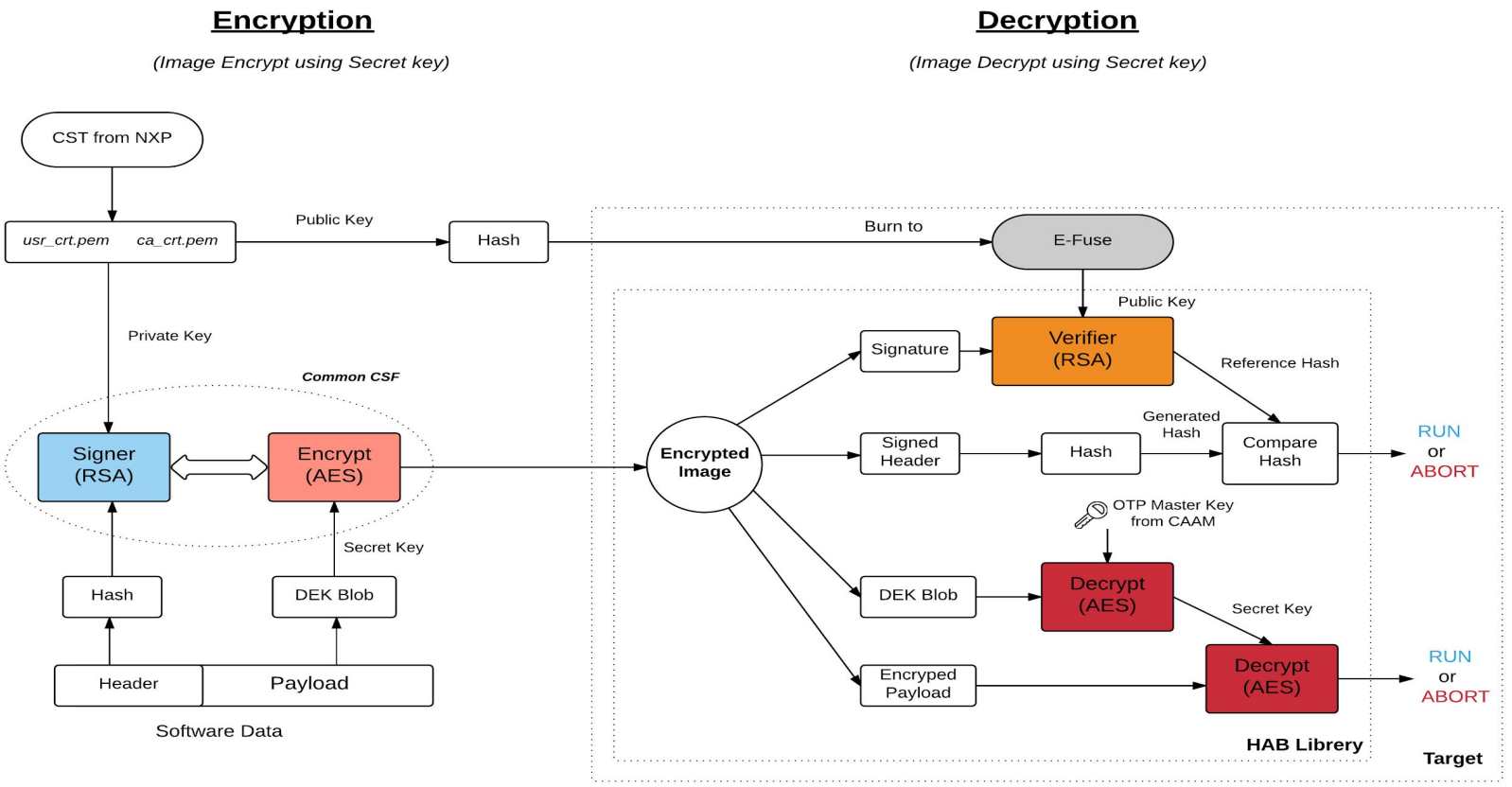




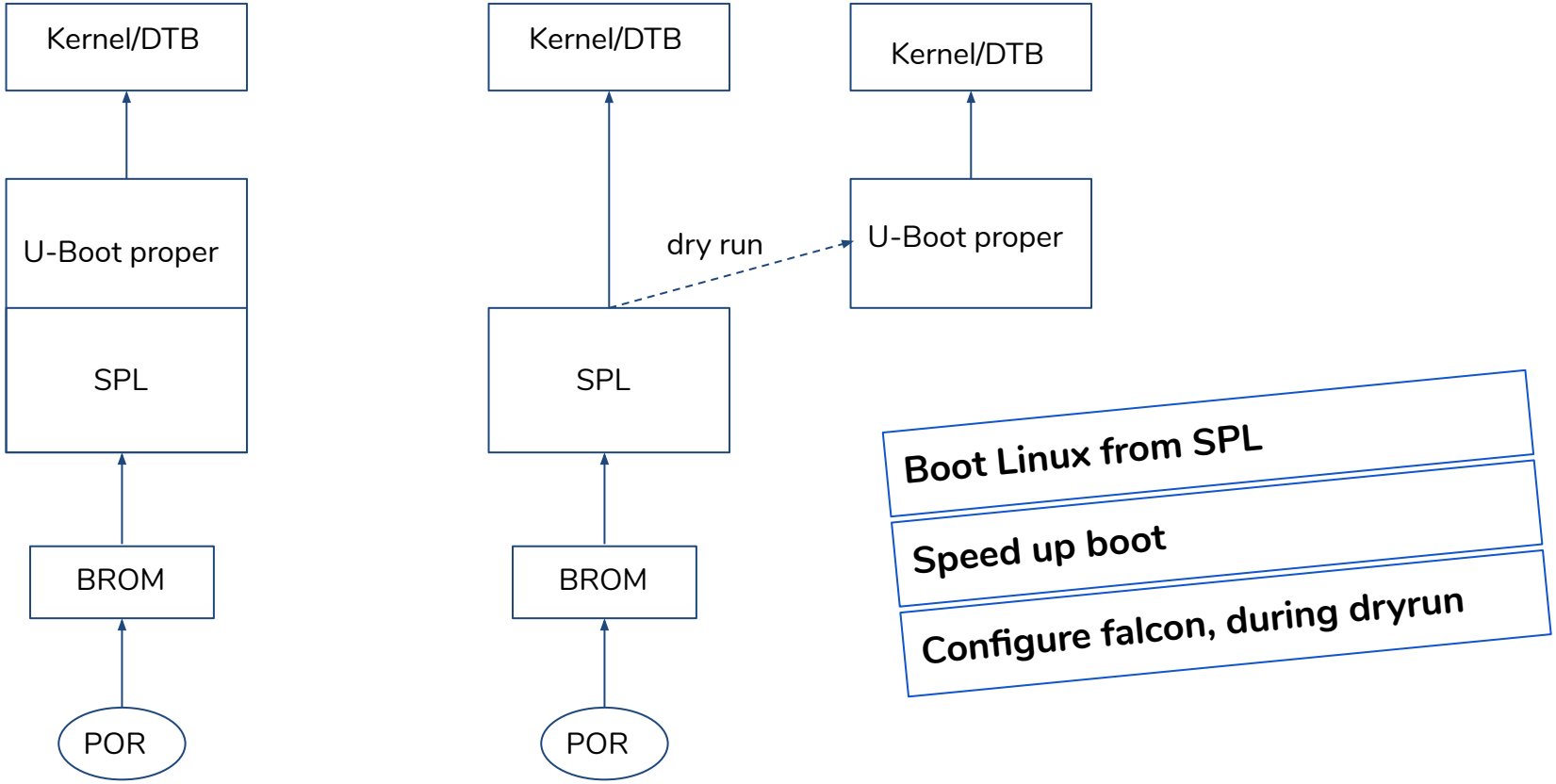
Secure boot, Signed



Secure boot, Encrypted



Falcon mode


Kernel/DTB
U-Boot proper
SPL
BROM
POR
Kernel/DTB
dry run
U-Boot proper
SPL
BROM
POR
Kernel/DTB
Boot Linux from SPL
Speed up boot
Configure falcon, during dryrun

Falcon, is useful?

```
[0.001344 0.001342] U-Boot TPL 2017.09-rc2-13373-g2cffd0d-dirty (Aug 31 2017 - 20:41:14)
[0.005975 0.004631] Trying to boot from BOOTROM
[0.008394 0.002419] Returning to boot ROM...
[0.216735 0.208341]
[0.217195 0.000460] U-Boot SPL 2017.09-rc2-13373-g2cffd0d-dirty (Aug 31 2017 - 20:41:14)
[0.223097 0.005902] Trying to boot from MMC1[0.262093 0.038996] Expected Linux image is not found. Trying to start U-boot
[0.436129 0.174036]
[0.436416 0.000287]
[0.436696 0.000280] U-Boot 2017.09-rc2-13373-g2cffd0d-dirty (Aug 31 2017 - 20:41:14 +0530)
[0.442273 0.005577][0.442369 0.000096] Model: Amarula Vyasa-RK3288
[0.444854 0.002485] DRAM:  2 GiB
[0.479422 0.034568] MMC:   dwmmc@ff0c0000: 1
[0.627295 0.147873] *** Warning - bad CRC, using default environment
[0.631527 0.004232]
[0.635980 0.004453] In:    serial@ff690000
[0.637982 0.002002] Out:   serial@ff690000
[0.640004 0.002022] Err:   serial@ff690000
[0.642244 0.002240] Model: Amarula Vyasa-RK3288
[0.644783 0.002539] Net:   Net Initialization Skipped
[0.647824 0.003041] No ethernet found.
[0.651954 0.004130] Hit any key to stop autoboot:  0
[0.772503 0.120549] switch to partitions #0, OK
[0.774802 0.002299] mmc1 is current device
[1.069762 0.294960] Scanning mmc 1:1...
[1.312386 0.242624] Found /boot/extlinux/extlinux.conf
[1.315209 0.002823] Retrieving file: /boot/extlinux/extlinux.conf
[1.353460 0.038251] 145 bytes read in 28 ms (4.9 KiB/s)
[1.356412 0.002952] 1:    Vyasa Linux-4.13
[1.358237 0.001825] Retrieving file: /boot/uImage
[1.740753 0.382516] 7836344 bytes read in 375 ms (19.9 MiB/s)
[1.744302 0.003549] append: console=ttyS2,115200n8 root=/dev/mmcblk0p1 rootwait quiet
[1.750086 0.005784] Retrieving file: /boot/rk3288-vyasa.dtb
[1.786952 0.036866] 36291 bytes read in 28 ms (1.2 MiB/s)
[1.789950 0.002998] ## Booting kernel from Legacy Image at 02000000 ...
[1.794524 0.004574]    Image Name:   Linux-4.13.0-rc4-next-20170810-0
[1.799040 0.004516]    Image Type:   ARM Linux Kernel Image (uncompressed)
[1.803818 0.004778]    Data Size:    7836280 Bytes = 7.5 MiB
[1.807426 0.003608]    Load Address: 02000000
[1.809776 0.002350]    Entry Point:  02000000
[1.812097 0.002321]    Verifying Checksum ... OK
[1.945372 0.133275] ## Flattened Device Tree blob at 01f00000
[1.948106 0.002734]    Booting using the fdt blob at 0x1f00000
[1.951715 0.003609]    Loading Kernel Image ... OK
[1.968363 0.016648]    Loading Device Tree to 0fff4000, end 0ffffdc2 ... OK
[1.974709 0.006346]
[1.974911 0.000202] Starting kernel ...
[0.002243 0.002243]
[1.273396 1.271153] [    0.090111] dmi: Firmware registration failed.
[1.617881 0.344485] [    0.581926] EXT4-fs (mmcblk0p1): couldn't mount as ext3 due to feature incompatibilities
[1.627592 0.009711] [    0.592177] EXT4-fs (mmcblk0p1): couldn't mount as ext2 due to feature incompatibilities
[4.596400 2.968808] Starting logging: OK
[4.610216 0.013816] Initializing random number generator... done.
[4.622379 0.012163] Starting network: OK
[4.746329 0.123950]
[4.748163 0.001834] Welcome to VYASA RK3288!
[4.750725 0.002562] vyasa-rk3288 login:
```

```
[0.001135 0.001134] U-Boot TPL 2017.09-rc2-13373-g2cffd0d-dirty (Aug 31 2017 - 20:41:14)
[0.005690 0.004555] Trying to boot from BOOTROM
[0.008221 0.002531] Returning to boot ROM...
[0.196488 0.188267]
[0.196704 0.000216] U-Boot SPL 2017.09-rc2-13373-g2cffd0d-dirty (Aug 31 2017 - 20:41:14)
[0.202759 0.006055] Trying to boot from MMC1
[1.879613 1.676854] [    0.090151] dmi: Firmware registration failed.
[2.287880 0.408267] [    0.645755] EXT4-fs (mmcblk0p1): couldn't mount as ext3 due to feature incompatibilities
[2.301935 0.014055] [    0.660209] EXT4-fs (mmcblk0p1): couldn't mount as ext2 due to feature incompatibilities
[2.425052 0.123117] Starting logging: OK
[2.440868 0.015816] Initializing random number generator... done.
[2.452302 0.011434] Starting network: OK
[2.580451 0.128149]
[2.584354 0.003903] Welcome to VYASA RK3288!
[2.586697 0.002343] vyasa-rk3288 login:
```

EFI boot

- ➔ Most of AArch64 and x86 UEFI is default booting system.
- ➔ U-Boot support via EFI_LOADER, CMD_BOOTEFI configs.

```
=> load mmc 0:2 ${fdt_addr_r} boot/dtb
29830 bytes read in 14 ms (2 MiB/s)
=> load mmc 0:1 ${kernel_addr_r} efi/debian/grubaa64.efi
reading efi/debian/grubaa64.efi
120832 bytes read in 7 ms (16.5 MiB/s)
=> bootefi ${kernel_addr_r} ${fdt_addr_r}
```

doc/README.uefi

ELCE 2017: Marrying U-Boot, UEFI and grub, Alexander Graf

Distro boot

- ➔ *bootargs* - system boot environment commands
- ➔ board-specific logic with respect to storage mechanism
- ➔ DISTRO_DEFAULTS, generic distribution configuration

```
# u-boot, extlinux.conf
label linux-5.0.0-rc3
  kernel /Image
  devicetree /sun50i-a64-amarula-relic.dtb
  append console=ttyS0,115200 earlyprintk root=/dev/mmcblk0p2 rootwait rw
```

Devicetree, improvements

- ➔ Kconfig
- ➔ FDT
- ➔ OF livetree
- ➔ FDT Overlay
- ➔ OF platdata

FDT (Flat Device Tree)

- Run-time hardware configuration
- Single U-Boot binary for multiple boards (with board controlled dts)
- Handle via libfdt
- Enabled via CONFIG_OF_CONTROL

- FDT supported U-Boot can build
  - with default dts, CONFIG_DEFAULT_DEVICE_TREE=<dts-file-name> in defconfig
    - $ make
  - with user-specified dts
    - $ make DEVICE_TREE=<dts-file-name>

- Sample, UniPhier Pro4 reference, Pro4 Ace, Pro4 Sanji boards
  - $ make uniphier_v7_defconfig (single configuration)
  - $ make DEVICE_TREE=uniphier-pro4-ref
  - $ make DEVICE_TREE=uniphier-pro4-ace
  - $ make DEVICE_TREE=uniphier-pro4-sanji

- DTB packing during build
  - CONFIG_OF_EMBED
  - CONFIG_OF_SEPARATE

FDT, u-boot

- ➔ Maintain U-Boot specific node definitions in separate file
- ➔ Useful for DT allocation in SPL
- ➔ u-boot,dm-pre-alloc, u-boot,dm-spl

```
/* arch/arm/dts/imx6qdl-u-boot.dtsi */
/ {
      soc {
                  u-boot,dm-spl;
                  aips-bus@02000000 {
                        u-boot,dm-spl;
                  };
       };
};

&gpio1 {
      u-boot,dm-spl;
};
```

FDT, libfdt

```c
int fdt_delprop(void *fdt, int nodeoffset, const char *name)
{
        struct fdt_property *prop;
        int len, proplen;

        FDT_RW_CHECK_HEADER(fdt);

        prop = fdt_get_property_w(fdt, nodeoffset, name, &len);
        if (!prop)
                return len;

        proplen = sizeof(*prop) + FDT_TAGALIGN(len);
        return fdt_splice_struct_(fdt, prop, proplen, 0);
}

int ft_board_setup(void *blob, bd_t *bd)
{
        int nodeoffset;

        nodeoffset = fdt_path_offset(blob, "/soc/aips-bus@02100000/usdhc@02198000");

        return fdt_delprop(blob, nodeoffset, "no-1-8-v");
}
```

? add/update, copy large amount

? tree need to rebuilt

? tree traversing is slow

Livetree (Live Device Tree)

- ➔ Pointer-based *hierarchical structures*
- ➔ Support after relocation
- ➔ ofnode , point to either flat tree or livetree
- ➔ Enabled via CONFIG_OF_LIVE

```
static int zynq_spi_ofdata_to_platdata(struct udevice *bus)
{
     struct zynq_spi_platdata *plat = bus->platdata;

     /* old code */
     plat->regs = (struct zynq_spi_regs *)devfdt_get_addr(bus);
     plat->frequency = fdtdec_get_int(blob, node, "spi-max-frequency", 250000000);

     /* new code */
     plat->regs = (struct zynq_spi_regs *)dev_read_addr(bus);
     plat->frequency = dev_read_u32_default(bus, "spi-max-frequency", 250000000);

    return 0;
}
```

FDT Overlay

- ➔ DTO, enable centralize DTB to be overlaid on the device tree.
- ➔ Single image of multitude of similar boards and their expansion options
- ➔ **HAT** - Rasberry PI, Tinker board
- ➔ DTO can load U-Boot via
  - ◆ FIT image
  - ◆ Manual load

```
/dts-v1/;
/ {
    images {
        kernel {
                data = /incbin/("./zImage");
                type = "kernel";
                load = <0x10080000>;
                entry = <0x10080000>;
        };
        fdt-1 {
                data = /incbin/("./imx6q-icore.dtb");
                type = "flat_dt";
        };
        fdt-2 {
                data = /incbin/("./imx6q-icore-mipi.dtb");
                type = "flat_dt";
        };
        configurations {
                default = "imx6q-icore.dtb";
                imx6q-icore.dtb {
                        kernel = "kernel";
                        fdt = "fdt-1";
                };
                imx6q-icore-mipi.dtb {
                        kernel = "kernel";
                        fdt = "fdt-2";
                };
        };
    };
};
```

FDT Overlay, loading

```
/* via FIT */
=> bootm $loadaddr#imx6q-icore.dtb#imx6q-icore-mipi

/* Manual load */
=> setenv fdt_addr 0x18000000
=> setenv fdt_ovaddr 0x180c0000

=> load mmc 0:1 ${fdt_addr} ${bootdir}/base.dtb
=> load mmc 0:1 ${fdt_ovaddr} ${bootdir}/overlay.dtb

=> fdt resize 8192

=> fdt apply $fdt_ovaddr

=> bootm ${loadaddr} - ${fdt_addr}
```

OF Platdata

- ➔ SPL size increases with FDT
- ➔ Enabled via CONFIG_SPL_OF_PLATDATA
- ➔ Explicitly define the device details Like legacy platform_device in Linux

```
#include <dm/platform_data/spi_davinci.h>

static const struct davinci_spi_platdata davinci_spi_data = {
      .regs = (struct davinci_spi_regs *)0x01f0e000,
      .num_cs = 4,
};

U_BOOT_DEVICE(davinci_spi) = {
       .name = "davinci_spi",
       .platdata = &davinci_spi_data,
};
```

Driver model

- ➔ Driver model
- ➔ DM, CPU
- ➔ DM, Power
- ➔ DM, Core
- ➔ DM, Peripherals
- ➔ Block layer
- ➔ USB layer

Driver model

? ad-hoc model, direct functions call

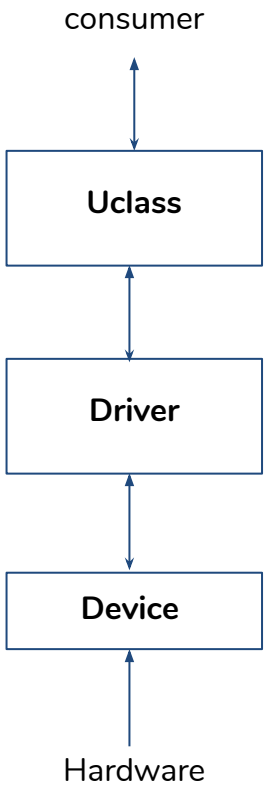
? multiple controllers can't fit same driver

? not scalable, difficult to maintain

Simple, scalable, modular, homogeneous

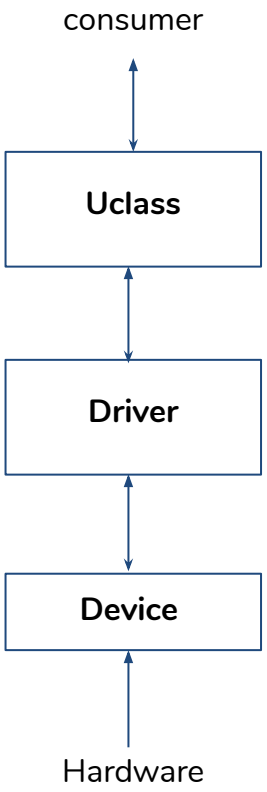
Lazy initialization, but bounded

Small overhead, SPL

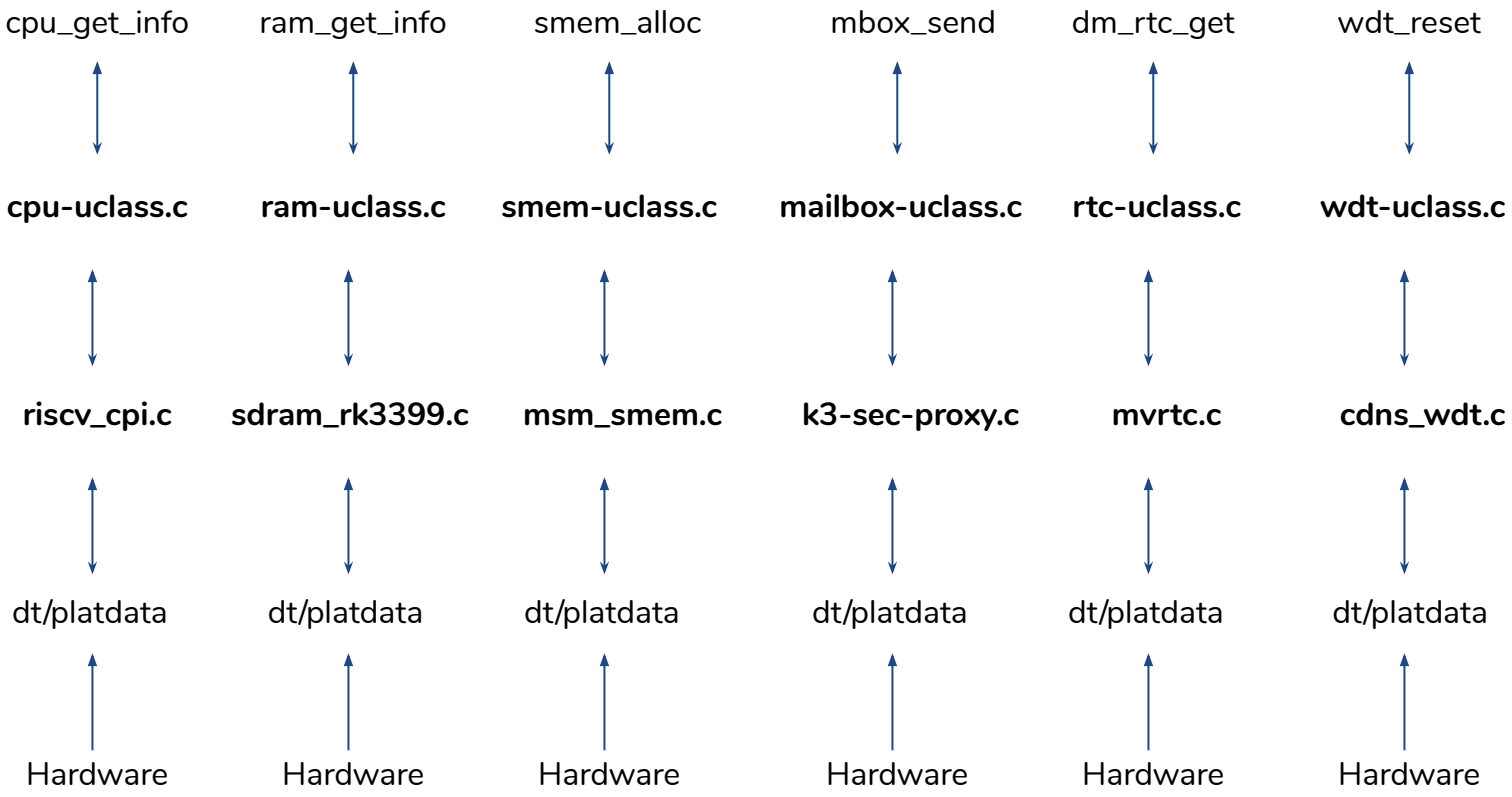


```
=> dm tree
 Class     index  Probed  Driver      Name
-----------------------------------------
 root          0  [ + ]   root_drive  root_driver
 clk           0  [   ]   fixed_rate  |-- oscillator
 mmc           0  [ + ]   rockchip_r  |-- dwmmc@ff0c0000
 blk           0  [ + ]   mmc_blk     |   `-- dwmmc@ff0c0000.blk
 mmc           1  [ + ]   rockchip_r  |-- dwmmc@ff0f0000
 blk           1  [   ]   mmc_blk     |   `-- dwmmc@ff0f0000.blk
 serial        0  [ + ]   ns16550_se  |-- serial@ff690000
 eth           0  [   ]   gmac_rockc  |-- ethernet@ff290000
 usb           0  [   ]   dwc2_usb    |-- usb@ff540000
 usb           1  [   ]   dwc2_usb    |-- usb@ff580000
 ram           0  [   ]   rockchip_r  |-- dmc@ff610000
 i2c           0  [ + ]   i2c_rockch  |-- i2c@ff650000
 pmic          0  [ + ]   rk8xx pmic  |   `-- pmic@1b
 regulator     0  [   ]   rk8xx_buck  |       |-- DCDC_REG1
 regulator     1  [   ]   rk8xx_buck  |       |-- DCDC_REG2
 regulator     2  [   ]   rk8xx_buck  |       |-- DCDC_REG3
 regulator     3  [   ]   rk8xx_buck  |       |-- DCDC_REG4
 regulator     4  [   ]   rk8xx_ldo   |       |-- LDO_REG1
```

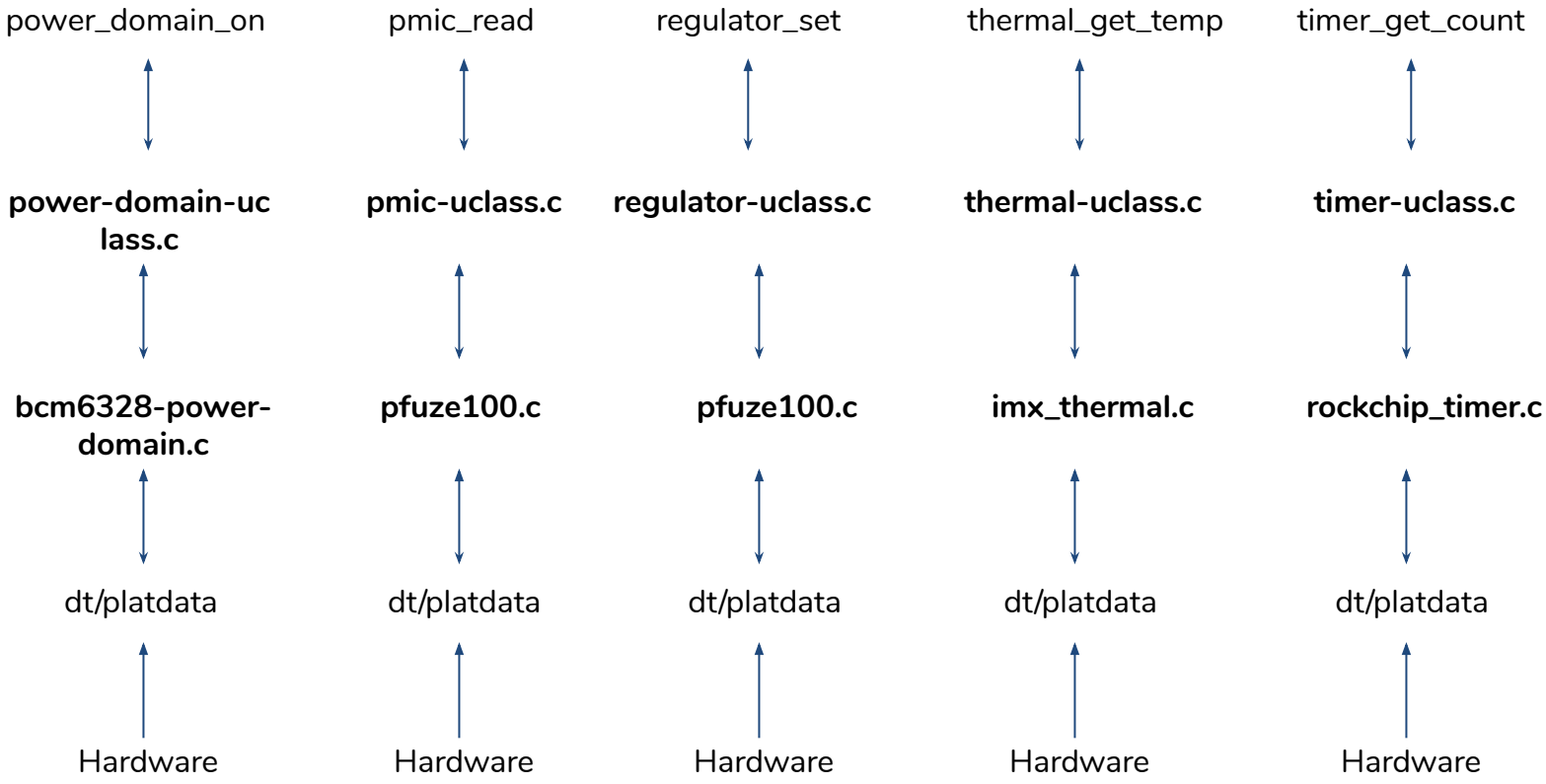
Driver model



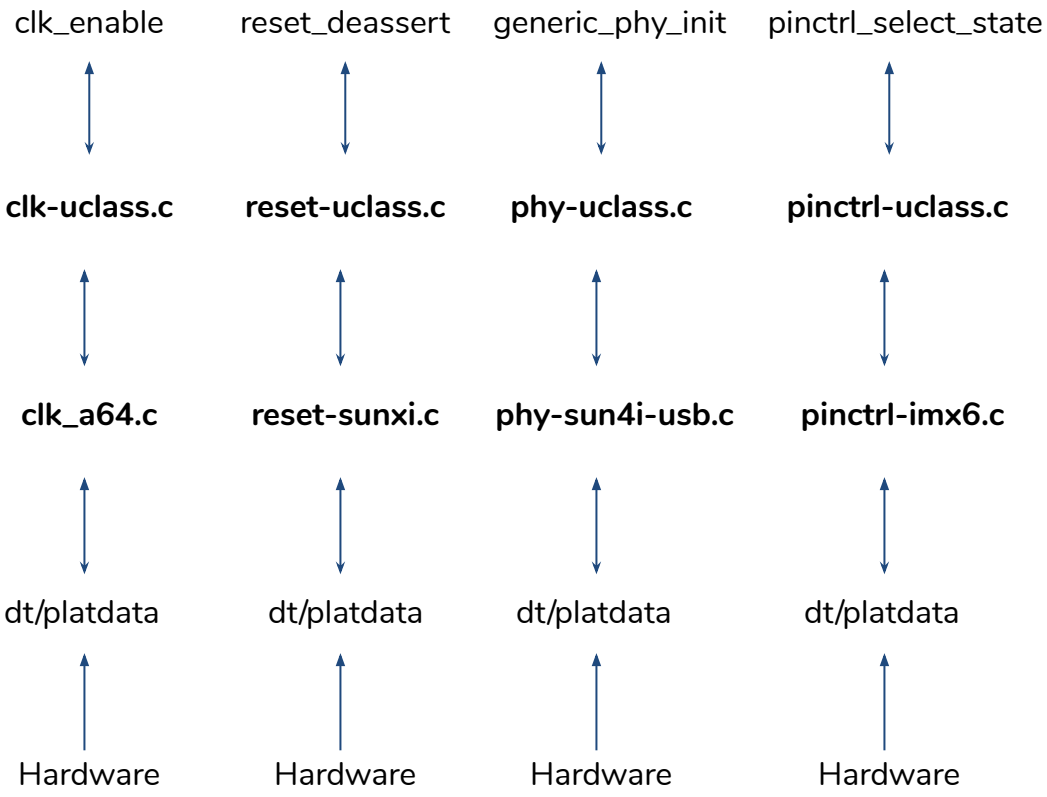
DM, CPU


cpu_get_info
ram_get_info
smem_alloc
mbox_send
dm_rtc_get
wdt_reset
cpu-uclass.c
ram-uclass.c
smem-uclass.c
mailbox-uclass.c
rtc-uclass.c
wdt-uclass.c
riscv_cpi.c
sdram_rk3399.c
msm_smem.c
k3-sec-proxy.c
mvrtc.c
cdns_wdt.c
dt/platdata
dt/platdata
dt/platdata
dt/platdata
dt/platdata
dt/platdata
Hardware
Hardware
Hardware
Hardware
Hardware
Hardware

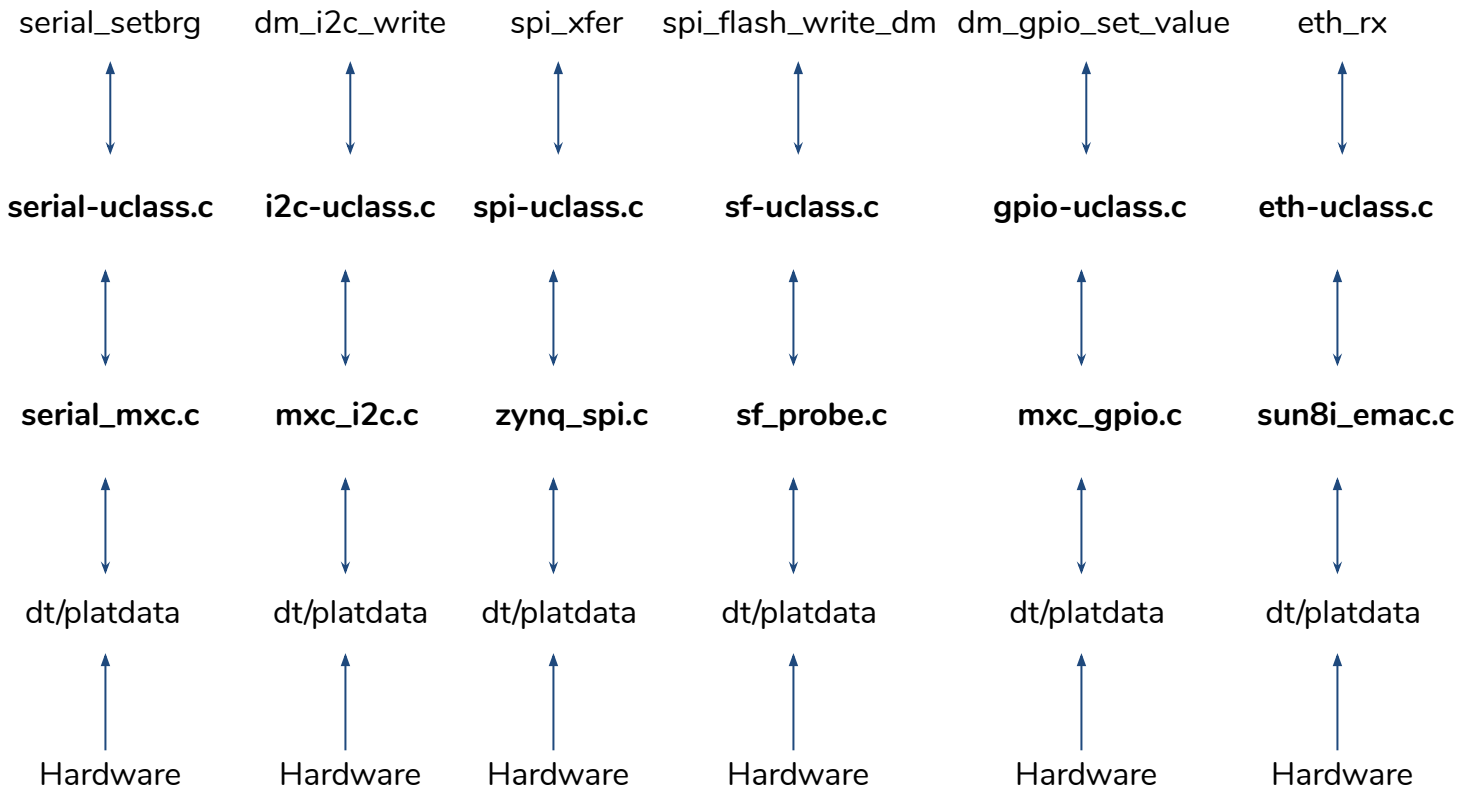
DM, Power


power_domain_on
pmic_read
regulator_set
thermal_get_temp
timer_get_count
power-domain-uclass.c
pmic-uclass.c
regulator-uclass.c
thermal-uclass.c
timer-uclass.c
bcm6328-power-domain.c
pfuze100.c
pfuze100.c
imx_thermal.c
rockchip_timer.c
dt/platdata
dt/platdata
dt/platdata
dt/platdata
dt/platdata
Hardware
Hardware
Hardware
Hardware
Hardware

DM, Core


clk_enable
reset_deassert
generic_phy_init
pinctrl_select_state
clk-uclass.c
reset-uclass.c
phy-uclass.c
pinctrl-uclass.c
clk_a64.c
reset-sunxi.c
phy-sun4i-usb.c
pinctrl-imx6.c
dt/platdata
dt/platdata
dt/platdata
dt/platdata
Hardware
Hardware
Hardware
Hardware

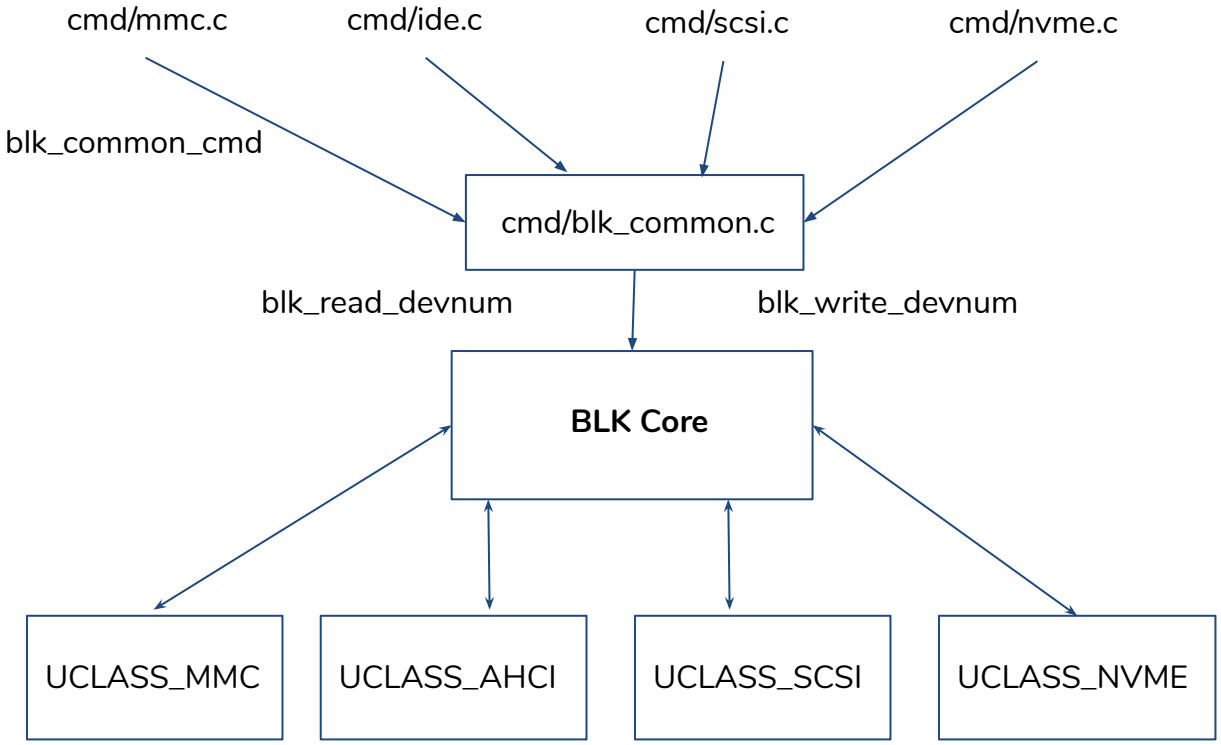
DM, Peripherals



```
UCLASS_DRIVER(spi) = {
	.id		= UCLASS_SPI,
	.name		= "spi",
	.flags		= DM_UC_FLAG_SEQ_ALIAS,
	.post_bind	= dm_scan_fdt_dev,
	.post_probe	= spi_post_probe,
	.child_pre_probe = spi_child_pre_probe,
	.per_device_auto_alloc_size = sizeof(struct dm_spi_bus),
	.per_child_auto_alloc_size = sizeof(struct spi_slave),
	.per_child_platdata_auto_alloc_size = sizeof(struct dm_spi_slave_platdata),
	.child_post_bind = spi_child_post_bind,
};
U_BOOT_DRIVER(zynq_qspi) = {
	.name	= "zynq_qspi",
	.id	= UCLASS_SPI,
	.of_match = zynq_qspi_ids,
	.ops	= &zynq_qspi_ops,
	.ofdata_to_platdata = zynq_qspi_ofdata_to_platdata,
	.platdata_auto_alloc_size = sizeof(struct zynq_qspi_platdata),
	.priv_auto_alloc_size = sizeof(struct zynq_qspi_priv),
	.probe	= zynq_qspi_probe,
};
```

```c
static int sun4i_usb_phy_exit(struct phy *phy)
{
    clk_disable(&usb_phy->clocks);
    reset_assert(&usb_phy->resets);
}
static int sun4i_usb_phy_init(struct phy *phy)
{
    clk_enable(&usb_phy->clocks);
    reset_deassert(&usb_phy->resets);
}
static struct phy_ops sun4i_usb_phy_ops = {
    .init = sun4i_usb_phy_init,
    .exit = sun4i_usb_phy_exit,
};
static int sun4i_usb_phy_probe(struct udevice *dev)
{
    clk_get_by_name(dev, "usb0_phy", &phy->clocks);
    reset_get_by_name(dev, "usb0_reset", &phy->resets);
}
U_BOOT_DRIVER(sun4i_usb_phy) = {
    .id    = UCLASS_PHY,
    .ops = &sun4i_usb_phy_ops,
    .probe = sun4i_usb_phy_probe,
};
```

Generic Block Layer

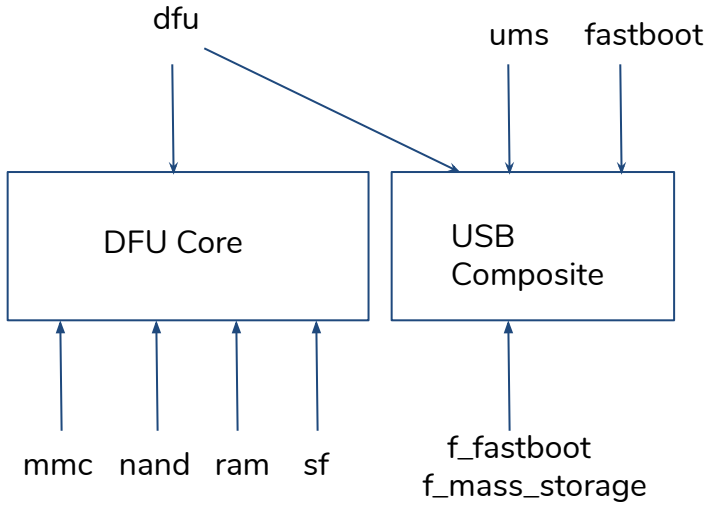


USB framework

- via UCLASS_USB
- uclass core: drivers/usb/host/usb-uclass.c
- platform specific uboot driver: drivers/usb/host/ehci-generic.c
- USB control, bulk, interrupt, create_int_queue etc via dm_usb_ops
- include/usb.h
- cmd/usb.c
- USB Gadgets can probe via Gadget UCLASS
- drivers/usb/gadget/ether.c, USB ETH Gadget
- MUSB can operate Host and Peripheral
- MUSB Host access via UCLASS_USB
- MUSB Peripheral access via
  - UCLASS_USB_DEV_GENERIC - host devices
  - UCLASS_USB_GADGET_GENERIC - gadget devices
- drivers/usb/musb-new/sunxi.c, SunXi MUSB driver

Firmware Upgrade

- ➔ Upgrade firmware images on running U-Boot
- ➔ DFU
- ➔ DFU via tftp
- ➔ UMS
- ➔ Fastboot



Miscellaneous

- ➔ Debug
- ➔ AVB
- ➔ x86, Slimboot
- ➔ Binman
- ➔ CI, tboot

Debug

- ➔ printf
- ➔ CONFIG_DEBUG
- ➔ GDB
- ➔ Early UART (CONFIG_DEBUG_UART)

```
#include <debug_uart.h>

static inline void _debug_uart_init(void)
{
    _mxc_serial_init(base);
 }

static inline void _debug_uart_putc(int ch)
{
    while (!(readl(&base->ts) & UTS_TXEMPTY))
        WATCHDOG_RESET();

    writel(ch, &base->txd);
}
DEBUG_UART_FUNCS

debug_uart_init();
printch('T');
printch('P');
printch('L');
```

AVB 2.0

➔ Verified Boot establishes a chain of trust from the bootloader to system images

```
avb init <dev> - initialize avb 2.0 for <dev>
avb verify - run verification process using hash data from vbmeta structure
avb read_rb <num> - read rollback index at location <num>
avb write_rb <num> <rb> - write rollback index <rb> to <num>
avb is_unlocked - returns unlock status of the device
avb get_uuid <partname> - read and print uuid of partition <partname>
avb read_part <partname> <offset> <num> <addr> - read <num> bytes from
partition <partname> to buffer <addr>
avb write_part <partname> <offset> <num> <addr> - write <num> bytes to
<partname> by <offset> using data from <addr>
```

x86, Slimboot

- ➔ Support Broadwell, Apollolake bare-metals
- ➔ Intel FSP, FSP2?
- ➔ x86 boot can support coreboot as payload for U-Boot
- ➔ SBL as payload for U-boot
- ➔ SBL supports QEMU, Apollolake, Whiskeylake, Coffeelake-R platforms.

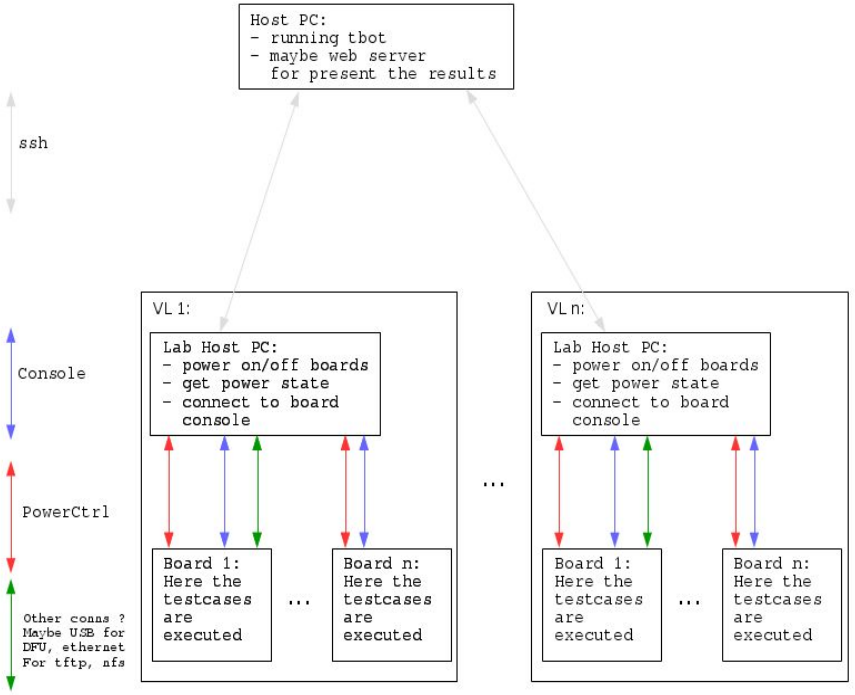
Binman

➔ Binman - Packaging multiple image components

```
/ {
    binman {
       filename = "u-boot-sunxi-with-spl.bin";
       pad-byte = <0xff>;
       blob {
            filename = "spl/sunxi-spl.bin";
       };
       u-boot-img {
            offset = <CONFIG_SPL_PAD_TO>;
       };
    };
};
```

tbot

- ➔ Execute test cases on boards
- ➔ Heiko Schocher, page https://www.tbot.tools/overview.html



Summary

- ➔ Lessons learned
- ➔ Future plans

Lessons learned from 18 years of U-Boot

- ➔ Release cycles - short and long does matters
- ➔ Strong distributed, hierarchical development model
- ➔ Supporting of new tools, make proper code validation
- ➔ More hands of developers, employers and maintainers
- ➔ Started with PPC, ARM - now support most possible architecture
- ➔ x86 development
- ➔ Drivers no longer, direct functions calls - DM

Future plans

- ➔ Kconfig migration
- ➔ Driver model migrations
  - ◆ BLK, DM_MMC, DM_SCSI, DM_USB
  - ◆ DM_SPI, DM_SPI_FLASH, DM_VIDEO, DM_PCI
- ➔ MTD driver model
- ➔ X86 development

Conclusion

- ➔ Use DT and DM for new ports
- ➔ Hands on with DM conversion
- ➔ ML: u-boot@lists.denx.de
- ➔ IRC: #u-boot
- ➔ LIn: https://www.linkedin.com/in/jaganteki/
- ➔ HABv4: https://wiki.amarulasolutions.com/uboot/secure_boot/imx6_habv4.html
- ➔ OP-TEE case study: https://wiki.amarulasolutions.com/optee/index.html
- ➔ Wiki: https://wiki.amarulasolutions.com

Questions??

Thank you

Jagan Teki <jagan@amarulasolutions.com>