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Coordinat Descent

Least Angle Regression

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## Computation & optimization for Lasso - part 2

Luyang Han & Janosch Ott

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22 October 2018

### Luyang Han & Janosch Ott

- 1. Coordinate Descent
- 2. Least Angle Regression
- 3. Comparison of Optimization Methods
- 4. Recall: Duality
- 5. ADMM
- 6. Screening Rules

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### Coordinate Descent

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## Coordinate Descent Algorithm

What is the Coordinate Descent (CD) Algorithm?

$$\beta_k^{t+1} = \underset{\beta_k}{\operatorname{argmin}} \ f(\beta_1^t \ , \beta_2^t \ , \dots, \beta_k \ , \beta_{k+1}^t \ , \dots, \beta_p^t)$$
 and  $\beta_j^{t+1} = \beta_j^t \text{ for } j \neq k$ 

• An iterative algorithm that updates from  $\beta^t$  to  $\beta^{t+1}$  by choosing a single coordinate, and minimizing over this coordinate.

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## Separability Condition

### Motivation

Does CD procedure converge to the global minimum of a convex function?

- **Sufficient Condition:** the function is continuously differentiable and strictly convex in each coordinate.
- ⇒ restrictive

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## Separability Condition

Suppose the cost function f has the additive decomposition:

$$f(\beta_1,...,\beta_p) = g(\beta_1,...,\beta_p) + \sum_{j=1}^p h_j(\beta_j)$$

where  $g: \mathbb{R}^p \to \mathbb{R}$  is differentiable and convex, and the univariate functions  $h_j: \mathbb{R} \to \mathbb{R}$  are convex.

• <u>Lasso</u>:  $g(\beta) = \frac{1}{2N} ||\mathbf{y} - \mathbf{X}\beta||_2^2$  and  $h_j(\beta_j) = \lambda |\beta_j|$  satisfies the condition

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## Separability Condition: Example

An Example of failure of Coordinate Descent

$$\underset{\beta \in \mathbb{R}^p}{\operatorname{argmin}} \ \frac{1}{2N} \|\mathbf{y} - \mathbf{X}\beta\|_2^2 + \ \lambda_1 \sum_{j=1}^p |\beta_j| + \ \lambda_2 \sum_{j=2}^p |\beta_j - \beta_{j-1}|$$

- $h(\beta)$  is not separable
- Fused Lasso: coordinate descent procedure is not guaranteed to find the global minimum

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## Separability Condition: Example

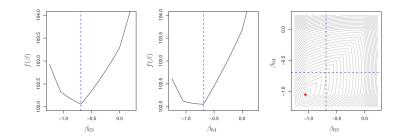


Figure: Fused Lasso: CD fails to reach the global minimum from Trevor Hastie, Robert Tibshirani, and Martin Wainwright (2015), Statistical learning with sparsity: the Lasso and generalizations, p111.

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## Lasso & Coordinate Descent

## **Optimality Condition:**

$$-\frac{1}{2N} \sum_{i=1}^{N} (y_i - \beta_0 - \sum_{k=1}^{p} x_{ik} \beta_k) x_{ij} + \lambda s_j = 0$$

where  $s_j \in sign(\beta_j)$  for j = 1, 2, ..., p

- Define the **partial residual**:  $r_i^{(j)} = y_i \sum_{k \neq j} x_{ik} \hat{\beta}_k$
- Then the solution for  $\hat{\beta}_j$  satisfies:

$$\hat{\beta}_j = \frac{S_{\lambda}(\frac{1}{N}\sum_{i=1}^N r_i^{(j)} x_{ij})}{\frac{1}{N}\sum_{i=1}^N x_{ij}^2}$$

where 
$$S_{\lambda}(\theta) = sign(\theta)(|\theta| - \lambda)_{+}$$

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## Lasso & Coordinate Descent

Illustration of Coordinate Descent in R

## Strategies to make the operation efficient:

## **Naive Updating**

$$r_i^{(j)} = y_i - \sum_{k \neq j} x_{ik} \hat{\beta}_k = r_i + x_{ij} \hat{\beta}_j$$

$$\frac{1}{N} \sum_{i=1}^{N} x_{ij} r_i^{(j)} = \frac{1}{N} \sum_{i=1}^{N} x_{ij} r_i + \hat{\beta}_j$$

### **Covariance Updating**

$$\sum_{i=1}^{N} x_{ij} r_i = \langle x_j, y \rangle - \sum_k \langle x_j, x_k \rangle \beta_{\hat{k}}$$

Warm Starts: For a decreasing sequence of values  $\{\lambda_0^L\}$ ,  $\hat{\beta}(\lambda_l)$  is typically a very good warm start for the solution  $\hat{\beta}(\lambda_{l+1})$ . We set  $\lambda_0 = \frac{1}{N} \max |\langle x_i, y \rangle|$  and  $\lambda_L \approx 0$ .

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## Lasso & Coordinate Descent

**Active-set Convergence:** Define the active set A and iterate the algorithm using only variables in A.

**Strong-set Convergence:** Define the strong set S and iterate the algorithm using only variables in S.

**Sparsity:** Sparsity of the design matrix X makes the operation of inner product efficient.

Details in Trevor Hastie, Robert Tibshirani, and Martin Wainwright (2015), Statistical learning with sparsity: the Lasso and generalizations, p113-114.

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## Elastic Net & Coordinate Descent

$$minimize_{\beta_0,\beta} \frac{1}{2} \sum_{i=1}^{N} (y_i - \beta_0 - x_i^T \beta)^2 + \lambda \left[ \frac{1}{2} (1 - \alpha) ||\beta||_2^2 + \alpha ||\beta||_1 \right]$$

- Combination of L1 and L2 penalty
- Satisfy the separability condition
- The solution satisfies:

$$\hat{\beta}_{j} = \frac{S_{\alpha\lambda}(\frac{1}{N}\sum_{i=1}^{N}r_{i}^{(j)}x_{ij})}{\frac{1}{N}\sum_{i=1}^{N}x_{ij}^{2} + (1-\alpha)\lambda}$$

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# Logistic Regression & Coordinate Descent

### Background

• Class Label G: Take values 1 and -1

Denote 
$$p(x_i; \beta_0, \beta) = Pr(G = 1|x_i)$$
  
Define log odds:  $\log \frac{Pr(G = -1|x)}{Pr(G = 1|x)} = \beta_0 + x^T \beta$ 

Maximize penalized log-likelihood:

$$\frac{1}{N} \sum_{i=1}^{N} \{ I(g_i = 1) \cdot \log(p(x_i; \beta_0, \beta)) + I(g_i = -1) \cdot \log(1 - p(x_i; \beta_0, \beta)) \} - \lambda ||\beta||_1$$
**Denote**  $y_i = I(g_i = -1)$ 

**Explicit form** of log likelihood (without penalty):

$$L(\beta_0, \beta) = \frac{1}{N} \sum_{i=1}^{N} \left[ y_i \cdot (\beta_0 + x_i^T \beta) - \log(1 + e^{\beta_0 + x_i^T \beta}) \right]$$

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# Logistic Regression & Coordinate Descent

### **Background**

• Form a quadratic objective function using Taylor expansion about current estimates  $(\tilde{\beta}_0, \tilde{\beta})$ : Idea of Newton method, Iterated Weighted Least Square problem

$$L_Q(\beta_0, \beta) = -\frac{1}{2N} \sum_{i=1}^{N} w_i (z_i - \beta_0 - x_i^T \beta)^2 + C(\tilde{\beta_0}, \tilde{\beta})$$

• Use Coordinate Descent to solve the problem  $minimize_{(\beta_0,\beta)} \{ -L_Q(\beta_0,\beta) + \lambda ||\beta||_1 \}$ 

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# Logistic Regression & Coordinate Descent

### Algorithm

OUTER LOOP: Decrement  $\lambda$ 

MIDDLE LOOP: Update the quadratic approximation  $L_Q$ 

using the current parameters  $(\beta_0, \beta)$ 

INNER LOOP: Run the coordinate descent algorithm on the

penalized weighted least squares problem

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## Least Angle Regression

### Introduction

- Relates to Forward Selection method
- Relates to Lasso method
- Able to deliver the entire solution path of the Lasso problem with squared-error loss as a function of the regularization parameter  $\lambda$

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## Least Angle Regression: Algorithm

- Start with all coefficients  $\beta_j$  equal to zero
- Find the predictor X<sub>j</sub> most correlated with y
- Increase the coefficient  $\beta_j$  in the direction of the sign of its correlation with y
- Take **residuals**  $r = y \hat{y}$  along the way; Stop when some other predictor  $X_k$  has **as much correlation** with r as  $X_j$  has
- Increase  $\beta_j, \beta_k$  in their joint least squares direction, until some other predictor has as much correlation with the residual r

Continue until: all predictors are in the model

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## Least Angle Regression: Algorithm

#### Algorithm 5.1 Least Angle Regression.

- 1. Standardize the predictors to have mean zero and unit  $\ell_2$  norm. Start with the residual  $\mathbf{r}_0 = \mathbf{y} \bar{\mathbf{y}}, \, \beta^0 = (\beta_1, \beta_2, \dots, \beta_p) = \mathbf{0}$ .
- 2. Find the predictor  $\mathbf{x}_j$  most correlated with  $r_0$ ; i.e., with largest value for  $|\langle \mathbf{x}_j, r_0 \rangle|$ . Call this value  $\lambda_0$ , define the active set  $\mathcal{A} = \{j\}$ , and  $\mathbf{X}_{\mathcal{A}}$ , the matrix consisting of this single variable.
- 3. For  $k = 1, 2, ..., K = \min(N 1, p)$  do:
  - (a) Define the least-squares direction  $\delta = \frac{1}{\lambda_{k-1}} (\mathbf{X}_{\mathcal{A}}^T \mathbf{X}_{\mathcal{A}})^{-1} \mathbf{X}_{\mathcal{A}}^T r_{k-1}$ , and define the *p*-vector  $\Delta$  such that  $\Delta_{\mathcal{A}} = \delta$ , and the remaining elements are zero.
  - (b) Move the coefficients  $\beta$  from  $\beta^{k-1}$  in the direction  $\Delta$  toward their least-squares solution on  $\mathbf{X}_{\mathcal{A}}$ :  $\beta(\lambda) = \beta^{k-1} + (\lambda_{k-1} \lambda)\Delta$  for  $0 < \lambda \leq \lambda_{k-1}$ , keeping track of the evolving residuals  $\mathbf{r}(\lambda) = \mathbf{y} \mathbf{X}\beta(\lambda) = \mathbf{r}_{k-1} (\lambda_{k-1} \lambda)\mathbf{X}\Delta$ .
  - (c) Keeping track of  $|\langle \mathbf{x}_{\ell}, \mathbf{r}(\lambda) \rangle|$  for  $\ell \notin \mathcal{A}$ , identify the largest value of  $\lambda$  at which a variable "catches up" with the active set; if the variable has index j, that means  $|\langle \mathbf{x}_{j}, \mathbf{r}(\lambda) \rangle| = \lambda$ . This defines the next "knot"  $\lambda_{k}$ .
  - (d) Set  $\mathcal{A} = \mathcal{A} \cup \{j\}$ ,  $\beta^k = \beta(\lambda_k) = \beta^{k-1} + (\lambda_{k-1} \lambda_k)\Delta$ , and  $r_k = \mathbf{y} \mathbf{X}\beta^k$ .
- 4. Return the sequence  $\{\lambda_k, \beta^k\}_0^K$ .

Figure: From Trevor Hastie, Robert Tibshirani, and Martin Wainwright (2015), Statistical learning with sparsity: the Lasso and generalizations, p119, Algorithm 5.1.

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# Least Angle Regression: Geometric Representation

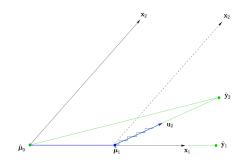


Figure: From Bradley Efron, Trevor Hastie, Iain Johnstone and Robert Tibshirani, (2004), Least Angle Regression, The Annals of Statistics, p412, Figure 2.

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# Connection between LAR and Lasso

### LAR

Let  $\mathbb{A}$  be the active set of variables for the LAR algorithm.  $\mathbf{x}_{j}^{T}(\mathbf{y} - \mathbf{X}\beta(\lambda)) = \lambda \cdot \mathbf{s}_{j}, \ \forall j \in \mathbb{A}$  where  $\mathbf{s}_{j}$  is the sign of inner product  $\lambda$ .

### **LASSO**

Let  $\mathbb A$  be the active set of variables in the solution for a given value of  $\lambda$ .

$$R(\beta) = \frac{1}{2}||\mathbf{y} - \mathbf{X}\beta||_2^2 + \lambda||\beta||_1$$

For differentiable  $R(\beta)$  , the stationary conditions give:

$$\mathbf{x}_{j}^{T}(\mathbf{y} - \mathbf{X}\beta) = \lambda \cdot sign(\beta_{j}), \forall j \in \mathbb{A}$$

If sign  $(\beta_j)$  matches  $s_j$ , the coefficient would be identical.

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# Connection between LAR and Lasso

- R Example
- LAR algorithm explains that the coefficient paths for the Lasso are piecewise linear
- Coefficient paths differ if  $sign(\beta_j)$  is different from  $s_j$
- Modification of LAR for computing Lasso solution:
   If a nonzero coefficient crosses zero before the next variable enters, drop it from A and recompute the current joint least squares direction.

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# Connection between LAR and Lasso

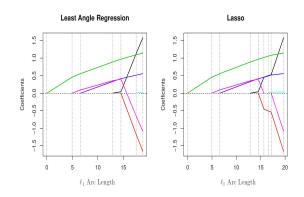


Figure: Cases where signs of  $\lambda$  and  $\beta$  disagree, from Trevor Hastie, Robert Tibshirani, and Martin Wainwright (2015), Statistical learning with sparsity: the Lasso and generalizations, p120, Figure 5.9.

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## Algorithm Performance

Simulation: Comparison of computation efficiency between CD and LAR

Set Up: 1

- Generate Gaussian data with N observations and p predictors, with each pair of predictors  $X_j$ ,  $X_k$  having the same population correlation  $\rho$ .
- Try different combination of N and p; Range  $\rho$  from 0 to 0.95.

$$Y = \sum_{j=1}^{p} X_j \beta_j + kZ$$
 where  $\beta_j = (-1)^j exp(\frac{-2(j-1)}{20}), Z \sim N(0,1)$  and  $k$  is a constant.

<sup>&</sup>lt;sup>1</sup>Jerome Friedman, Trevor Hastie, and Rob Tibshirani (2010), Regularization Paths for Generalized Linear Models via Coordinate Descent, Journal of Statistical Software, p12.

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## Algorithm Performance

	L	inear Re	gression	— Dens	e Featur	es
			Corre	lation		
	0	0.1	0.2	0.5	0.9	0.95
		-6	N = 1000	p = 100	)	
glmnet-naive	0.05	0.06	0.06	0.09	0.08	0.07
glmnet-cov	0.02	0.02	0.02	0.02	0.02	0.02
lars	0.11	0.11	0.11	0.11	0.11	0.11
			N = 5000	), p = 100	)	
glmnet-naive	0.24	0.25	0.26	0.34	0.32	0.31
glmnet-cov	0.05	0.05	0.05	0.05	0.05	0.05
lars	0.29	0.29	0.29	0.30	0.29	0.29
		13	N = 100,	p = 1000	)	
glmnet-naive	0.04	0.05	0.04	0.05	0.04	0.03
glmnet-cov	0.07	0.08	0.07	0.08	0.04	0.03
lars	0.73	0.72	0.68	0.71	0.71	0.67
			N = 100,	p = 5000	)	
glmnet-naive	0.20	0.18	0.21	0.23	0.21	0.14
glmnet-cov	0.46	0.42	0.51	0.48	0.25	0.10
lars	3.73	3.53	3.59	3.47	3.90	3.52
		1	V = 100,	p = 2000	0	
glmnet-naive	1.00	0.99	1.06	1.29	1.17	0.97
glmnet-cov	1.86	2.26	2.34	2.59	1.24	0.79
lars	18.30	17.90	16.90	18.03	17.91	16.39
		J	V = 100,	p = 5000	0	

Figure: Comparison of computing time, from Jerome Friedman, Trevor Hastie, and Rob Tibshirani (2010), Regularization Paths for Generalized Linear Models via Coordinate Descent, Journal of Statistical Software, Appendix 1.

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## Algorithm Performance

Simulation: Comparison of computation efficiency between Coordinate Descent, Proximal Gradient Descent and Nesterov Method

Set Up: 2

- Generated an N × p predictor matrix X with standard Gaussian entries and pairwise correlation 0 or 0.5 between the features.
- $|\beta_j| = exp \left[ -0.5(u(j-1))^2 \right]$  and  $u = \sqrt{\frac{\pi}{20}}$  and alternating signs -1,+1,-1...

<sup>&</sup>lt;sup>2</sup>Trevor Hastie, Robert Tibshirani, and Martin Wainwright (2015), Statistical learning with sparsity: the Lasso and generalizations, p117.

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## Algorithm Performance

Table 5.1 Lasso for linear regression: Average (standard error) of CPU times over ten realizations, for coordinate descent, generalized gradient, and Nesterov's momentum methods. In each case, time shown is the total time over a path of 20  $\lambda$  values.

	N = 10000, p = 100		N = 200, p = 10000		
Correlation	0	0.5	0	0.5	
Coordinate descent	0.110 (0.001)	0.127 (0.002)	0.298 (0.003)	0.513 (0.014)	
Proximal gradient	0.218 (0.008)	$0.671\ (0.007)$	1.207 (0.026)	2.912(0.167)	
Nesterov	0.251 (0.007)	$0.604\ (0.011)$	1.555 (0.049)	$2.914\ (0.119)$	

Figure: Comparison of computing efficiency between 3 methods, from Trevor Hastie, Robert Tibshirani, and Martin Wainwright (2015), Statistical learning with sparsity: the Lasso and generalizations, p117, Table 5.1.

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## Recall: Duality in optimization

Primal				
Optimize	$\min f(x)$			
Constraints	$g_i(x) \leq 0, h_j(x) = 0, x \in X$			
Function	$L(x,\lambda,\mu) := f(x) + \sum_{i} \lambda_{i} g_{i}(x) + \sum_{j} \mu_{j} h_{j}(x)$			
Dual				
Function	$q(\lambda,\mu) = \inf_{x \in X} L(x,\lambda,\mu)$			
Constraints	$\lambda \geq 0$			
Optimize	$\max_{\lambda \geq 0, \mu} q(\lambda, \mu)$			

Why though? - Dual problem is always convex!

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# Alternating Direction Method of Multipliers (ADMM)

Problem - decomposable!

$$\min_{\beta \in \mathbb{R}^m, \theta \in \mathbb{R}^n} f(\beta) + g(\theta) \quad \text{subject to } \mathbf{A}\beta + \mathbf{B}\theta - c = 0$$

Lagrangian - decomposable !

$$f(\beta) + g(\theta) + \langle \mu, \mathbf{A}\beta + \mathbf{B}\theta - c \rangle$$

Augmented Lagrangian - NOT decomposable !

$$L_
ho(eta, heta,\mu):=f(eta)+g( heta)+\langle\mu,\mathbf{A}eta+\mathbf{B} heta-c
angle+rac{
ho}{2}||\mathbf{A}eta+\mathbf{B} heta-c||_2^2$$

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## Dual Variable Update

Alternating Direction Method of Multipliers

$$\begin{split} \beta^{t+1} &= \operatorname*{arg\,min}_{\beta \in \mathbb{R}^m} L_{\rho}(\beta, \theta^t, \mu^t) \\ \theta^{t+1} &= \operatorname*{arg\,min}_{\theta \in \mathbb{R}^m} L_{\rho}(\beta^{t+1}, \theta, \mu^t) \\ \mu^{t+1} &= \mu^t + \rho(\mathbf{A}\beta^{t+1} + \mathbf{B}\theta^{t+1} - c) \end{split}$$

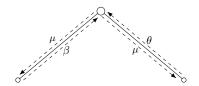


Figure: Own illustration of the dual ascent step in the ADMM algorithm utilising dual decomposition based on Geoff Gordon and Ryan Tibshirani (2012), Uses of Duality, https://www.cs.cmu.edu/~ggordon/10725-F12/slides/18-dual-uses.pdf.

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## ADMM - Why?

- convex problems with nondifferentiable constraints
- blockwise computation
  - sample blocks
  - feature blocks

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## ADMM for the Lasso - Problem

Problem in Lagrangian form

$$\underset{\beta \in \mathbb{R}^{p}, \theta \in \mathbb{R}^{p}}{\operatorname{minimize}} \left\{ \frac{1}{2} \left\| \mathbf{y} - \mathbf{X} \beta \right\|_{2}^{2} + \lambda \left\| \theta \right\|_{1} \right\} \quad \text{such that } \beta - \theta = 0$$

Augmented Lagrangian

$$L_{\rho}(\boldsymbol{\beta}, \boldsymbol{\theta}, \boldsymbol{\mu}) := \left\{ \frac{1}{2} \left\| \mathbf{y} - \mathbf{X} \boldsymbol{\beta} \right\|_2^2 + \lambda \left\| \boldsymbol{\theta} \right\|_1 \right\} + \langle \boldsymbol{\mu}, \boldsymbol{\beta} - \boldsymbol{\theta} \rangle + \frac{\rho}{2} ||\boldsymbol{\beta} - \boldsymbol{\theta}||_2^2$$

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## ADMM for the Lasso - Update

Update

$$\beta^{t+1} = (\mathbf{X}^T \mathbf{X} + \rho \mathbf{I})^{-1} (\mathbf{X}^T \mathbf{y} + \rho \theta^t - \mu^t)$$

$$\theta^{t+1} = S_{\lambda/\rho} (\beta^{t+1} + \mu^t/\rho)$$

$$\mu^{t+1} = \mu^t + \rho (\beta^{t+1} - \theta^{t+1})$$

where  $S_{\lambda/\rho}(z) = \operatorname{sign}(z)(|z| - \frac{\lambda}{\rho})_+$ .

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Screening Rules

Minor-Max Algorithms

Alternating Minimizations

## Screening Rules

- Pre-processing to eliminate features
- Very big data set, esp. large number of predictors
- Maybe too big to load into memory
- Screening rules eliminate predictors with minor calculation
- And very high / safe certainty (i.e. eliminated predictors would not show up in Lasso model based on full data)

They achieve a reduction in the number of variables, typically by an order of magnitude

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Least Angle Regression

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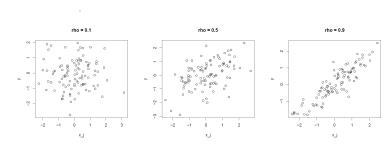
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## What is a good predictor?



correlation is an inner product

high absolute correlation ( = large absolute inner product)

- > high predictive power (compare plots)
- $> x_j$  with largest inner product has highest predictive power
- > thus for that j we are most willing to accept some penalty from  $\lambda$

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## Lasso - an iterative algorithm

Let  $\mathcal A$  be the active set of predictors. Let  $\lambda$  take values on a decreasing sequence.

### iterate

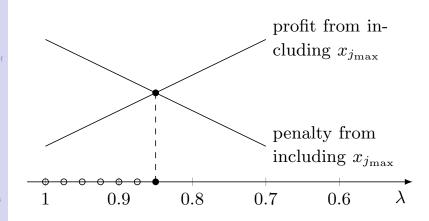
- 1. order predictors  $x_j$  not in  $\mathcal{A}$  by their "effectiveness" using  $\left|x_j^T y\right|$  or better  $\left|x_j^T (y \hat{y}_{\lambda})\right|$ , call the best predictor  $x_{j_{\text{max}}}$
- 2. move  $\lambda$  such that the positive effect from the best predictor  $x_{i_{max}}$  compensates the penalty by  $\lambda$
- 3. calculate solution for chosen  $\lambda$

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## Lasso - a visual intepretation



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## Back to screening rules

Let  $\lambda$  take values on a decreasing sequence. Let  $\lambda_{\max}$  be the  $\lambda$  where the first predictor has a non-zero coefficient.

$$\lambda_{\max} = \max_{j} \left| x_{j}^{T} y \right|$$

Let A be the active set of predictors.

$$\forall j \in \mathcal{A} \ \lambda = \left| x_j^T (y - \hat{y}) \right|$$

$$\forall j \notin \mathcal{A} \ \lambda > \left| x_j^T (y - \hat{y}) \right|$$

$$\forall j \notin \mathcal{A} \ \lambda > \left| x_j^T (y - \hat{y}) \right|$$

R example

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## Global vs. Sequential

Global (one-time screening):

Suppose we want to calculate a Lasso solution at  $\lambda < \lambda_{\text{max}}$ .

Sequential (iterative screening):

Suppose we have the Lasso solution  $\hat{\beta}(\lambda')$  at  $\lambda'$  and want to screen variables for solutions at  $\lambda < \lambda'$ .

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## Dual Polytope Projection (DPP)

#### Global DPP Rule

Suppose we want to calculate a Lasso solution at  $\lambda < \lambda_{\text{max}}$ . The DPP rule discards the  $i^{th}$  variable if

$$\left\|\mathbf{x}_{j}^{\mathsf{T}}\mathbf{y}\right\| < \lambda_{\mathsf{max}} - \left\|\mathbf{x}_{j}\right\|_{2} \left\|\mathbf{y}\right\|_{2} \frac{\lambda_{\mathsf{max}} - \lambda}{\lambda}$$

## Sequential DPP rule

Suppose we have the Lasso solution  $\hat{\beta}(\lambda')$  at  $\lambda'$  and want to screen variables for solutions at  $\lambda < \lambda'$ . We discard the  $j^{th}$  variable if

$$\left|\mathbf{x}_{j}^{T}(\mathbf{y} - \mathbf{X}\hat{eta}(\lambda'))\right| < \lambda' - \left\|\mathbf{x}_{j}\right\|_{2} \left\|\mathbf{y}\right\|_{2} \frac{\lambda_{\mathsf{max}} - \lambda}{\lambda}$$

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## Strong Rule

## Global Strong Rule

Suppose we want to calculate a Lasso solution at  $\lambda < \lambda_{\max}$ . The global strong rule discards the  $j^{th}$  variable if

$$\left|\mathbf{x}_{j}^{\mathsf{T}}\mathbf{y}\right|<\lambda-\left(\lambda_{\mathsf{max}}-\lambda\right)=2\lambda-\lambda_{\mathsf{max}}$$

## Sequential Strong Rule

Suppose we have the Lasso solution  $\hat{\beta}(\lambda')$  at  $\lambda'$  and want to screen variables for solutions at  $\lambda < \lambda'$ . We discard the  $j^{th}$  variable if

$$\left|\mathbf{x}_{j}^{T}(\mathbf{y}-\mathbf{X}\hat{eta}(\lambda'))\right|<2\lambda-\lambda'$$

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## Screening Rules - Example Setup

- simulated dataset
- N = 200, p = 5000 uncorrelated Gaussian predictors
- 1/4 true non-zero coefficients
- 100 decreasing lambda values equally spaced on the log-scale
- Compare Global DPP, Global Strong, Sequential DDP, Sequential Strong
- no violations for either of the strong rules

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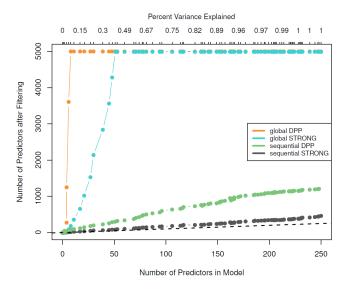


Figure: From Trevor Hastie, Robert Tibshirani, and Martin Wainwright (2015), Statistical learning with sparsity: the Lasso and generalizations, p129.

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## Summary I

#### Coordinate Descent

- An efficient algorithm implemented in glmnet but requires separability condition
- Application: Ridge, Lasso, Elastic Net, Logistic Regression, etc.; Failure: Fused Lasso

## Least Angle Regression

- Similar to the idea of Forward Selection
- Computationally efficient but does not scale well to large problems

#### Connection between LASSO and LAR

- LAR could be modified to obtain Lasso solution
- Explains the fact that Lasso coefficient solution path is piece-wise linear

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## Summary II

#### **ADMM**

- Use duality to your advantage
- Limitations in speed for Lasso, but useful in more complex settings

## Screening Rules

- Promising for very large p-s
- Difficult to find best rule, field in development

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## Additional slides: Minorization-Maximization Algorithms (MMA)

- Problem: minimize  $f(\beta)$  over  $\beta \in \mathbb{R}^p$  for f possibly non-convex
- Introduce additional variable heta
- Use  $\theta$  to majorize (bound from above) the objective function to be minimized

Majorization-Minimization Algorithms work analoguosly.

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## MMA visually

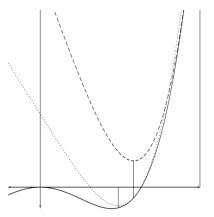


Figure: Figure from Jan De Leeuw (2015), Block Relaxation Methods in Statistics, doi.org/10.13140/RG.2.1.3101.9607

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## MMA analytically I

Def.  $\Psi : \mathbb{R}^p \times \mathbb{R}^p \to \mathbb{R}$  majorizes f at  $\beta \in \mathbb{R}^p$  if

$$\forall \theta \in \mathbb{R}^p \quad \Psi(\beta, \theta) \geq f(\beta)$$

with equality for  $\theta = \beta$ .

Minor-Max algorithm

- initialize  $\beta^0$
- update with  $eta^{t+1} = rg\min_{eta \in \mathbb{R}^p} \Psi(eta, eta^t)$

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## MMA analytically II

This scheme generates a sequence of  $\beta$ s for which the cost  $f(\beta^t)$  is nonincreasing, because

$$f(\beta^t) \stackrel{(i)}{=} \Psi(\beta^t, \beta^t) \stackrel{(ii)}{\geq} \Psi(\beta^{t+1}, \beta^t) \stackrel{(iii)}{\geq} f(\beta^{t+1})$$

where

- (i) & (iii) Definiton of majorize
  - (ii)  $\beta^{t+1}$  is a minimizer of  $\beta \mapsto \Psi(\beta, \beta^t)$

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Alternating Minimizations Let's consider an example . . .

$$f(\alpha,\beta) = (1 - \alpha\beta)^2$$

Def. A function  $f(\alpha, \beta) : \mathbb{R}^m \times \mathbb{R}^n \to \mathbb{R}$  is biconvex, if for each  $\alpha \in \mathbb{R}^m$  the function  $\alpha \mapsto f(\alpha, \beta)$  is convex and for each  $\beta \in \mathbb{R}^n$  the function  $\beta \mapsto f(\alpha, \beta)$  is convex.

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#### Alternate Convex Search

Block coordinate descent applied to  $\alpha$  and  $\beta$  blocks

- 1. Initialize  $(\alpha^0, \beta^0)$  at some point in the biconvex set to minimize over
- 2. For t = 0, 1, 2, ...
  - (i) Fix  $\beta = \beta^t$  and update  $\alpha^{t+1} \in \arg\min_{\alpha \in \mathcal{C}_{\beta^t}} f(\alpha, \beta^t)$
  - (ii) Fix  $\alpha = \alpha^{t+1}$  and update  $\beta^{t+1} \in \operatorname*{arg\,min}_{\alpha \in \mathcal{C}_{\alpha^{t+1}}} f(\alpha^{t+1}, \beta)$

For a function bounded from below, the algorithm converges to a partial optimum (i.e. as biconvexity, only optimal in one coordinate if the other coordinate is fixed).

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Alternating Minimizations Comments . . . Questions . . . Suggestions . . .

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# That's it. Thanks for listening.