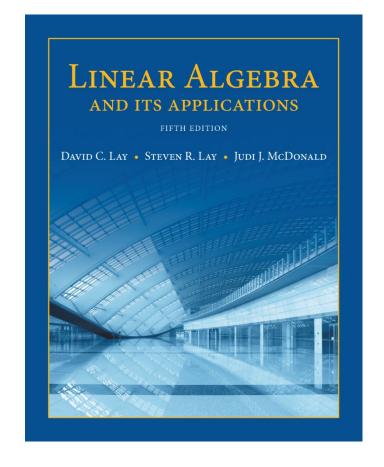
1

Linear Equations in Linear Algebra

1.1

SYSTEMS OF LINEAR EQUATIONS



LINEAR EQUATION

• A **linear equation** in the variables x_1, \dots, x_n is an equation that can be written in the form

$$a_1 x_1 + a_2 x_2 + \dots + a_n x_n = b$$

where b and the coefficients a_1, \ldots, a_n are real or complex numbers, usually known in advance.

• A system of linear equations (or a linear system) is a collection of one or more linear equations involving the same variables — say, x_1, \ldots, x_n .

LINEAR EQUATION

- A **solution** of the system is a list $(s_1, s_2, ..., s_n)$ of numbers that makes each equation a true statement when the values $s_1, ..., s_n$ are substituted for $x_1, ..., x_n$, respectively.
- The set of all possible solutions is called the solution set of the linear system.
- Two linear systems are called **equivalent** if they have the same solution set.

LINEAR EQUATION

- A system of linear equations has
 - 1. no solution, or
 - 2. exactly one solution, or
 - 3. infinitely many solutions.
- A system of linear equations is said to be **consistent** if it has either one solution or infinitely many solutions.
- A system is **inconsistent** if it has no solution.

MATRIX NOTATION

 The essential information of a linear system can be recorded compactly in a rectangular array called a matrix. Given the system,

$$x_{1} - 2x_{2} + x_{3} = 0$$

$$2x_{2} - 8x_{3} = 8$$

$$-4x_{1} + 5x_{2} + 9x_{3} = -9,$$

with the coefficients of each variable aligned in columns, the matrix

$$\begin{bmatrix} 1 & -2 & 1 \\ 0 & 2 & -8 \\ -4 & 5 & 9 \end{bmatrix}$$

Is called the **coefficient matrix** (or matrix of **coefficients**) of the system

MATRIX NOTATION

- An augmented matrix of a system consists of the coefficient matrix with an added column containing the constants from the right sides of the equations.
- For the given system of equations,

$$\begin{bmatrix} 1 & -2 & 1 & 0 \\ 0 & 2 & -8 & 8 \\ -4 & 5 & 9 & -9 \end{bmatrix}$$
 is called the **augmented matrix** of the system.

MATRIX SIZE

- The size of a matrix tells how many rows and columns it has. If m and n are positive integers, an m×n matrix is a rectangular array of numbers with m rows and n columns. (The number of rows always comes first.)
- The basic strategy for solving a linear system is to replace one system with an equivalent system (i.e., one with the same solution set) that is easier to solve.

Example 1: Solve the given system of equations.

$$x_{1} - 2x_{2} + x_{3} = 0 \qquad ----(1)$$

$$2x_{2} - 8x_{3} = 8 \qquad ----(2)$$

$$-4x_{1} + 5x_{2} + 9x_{3} = -9 \qquad ----(3)$$

• **Solution:** The elimination procedure is shown here with and without matrix notation, and the results are placed side by side for comparison.

$$x_{1} - 2x_{2} + x_{3} = 0$$

$$2x_{2} - 8x_{3} = 8$$

$$-4x_{1} + 5x_{2} + 9x_{3} = -9$$

$$\begin{bmatrix} 1 & -2 & 1 & 0 \\ 0 & 2 & -8 & 8 \\ -4 & 5 & 9 & -9 \end{bmatrix}$$

• Keep x_1 in the first equation and eliminate it from the other equations. To do so, add 4 times equation 1 to equation 3.

$$4x_1 - 8x_2 + 4x_3 = 0$$

$$-4x_1 + 5x_2 + 9x_3 = -9$$

$$-3x_2 + 13x_3 = -9$$

• The result of this calculation is written in place of the original third equation:

$$x_{1} - 2x_{2} + x_{3} = 0$$

$$2x_{2} - 8x_{3} = 8$$

$$-3x_{2} + 13x_{3} = -9$$

$$\begin{bmatrix} 1 & -2 & 1 & 0 \\ 0 & 2 & -8 & 8 \\ 0 & -3 & 13 & -9 \end{bmatrix}$$

• Now, multiply equation 2 by 1/2 in order to obtain 1 as the coefficient for x_2 .

$$x_{1} - 2x_{2} + x_{3} = 0$$

$$x_{2} - 4x_{3} = 4$$

$$-3x_{2} + 13x_{3} = -9$$

$$\begin{bmatrix} 1 & -2 & 1 & 0 \\ 0 & 1 & -4 & 4 \\ 0 & -3 & 13 & -9 \end{bmatrix}$$

• Use the x_2 in equation 2 to eliminate the $3x_2$ in equation 3.

$$3x_{2} - 12x_{3} = 12$$

$$-3x_{2} + 13x_{3} = -9$$

$$x_{3} = 3$$

• The new system has a *triangular* form.

• Eventually, you want to eliminate the $-2x_2$ term from equation 1, but it is more efficient to use the x_3 term in equation 3 first to eliminate the $-4x_3$ and x_3 terms in equations 2 and 1.

$$4x_{3} = 12 -x_{3} = -3$$

$$x_{2} - 4x_{3} = 4 x_{1} - 2x_{2} + x_{3} = 0$$

$$x_{2} = 16 x_{1} - 2x_{2} = -3$$

Now, combine the results of these two operations.

$$x_{1} - 2x_{2} = -3$$

$$x_{2} = 16$$

$$x_{3} = 3$$

$$\begin{bmatrix} 1 & -2 & 0 & -3 \\ 0 & 1 & 0 & 16 \\ 0 & 0 & 1 & 3 \end{bmatrix}$$

• Move back to the x_2 in equation 2, and use it to eliminate the $-2x_2$ above it. Because of the previous work with x_3 , there is now no arithmetic involving x_3 terms. Add 2 times equation 2 to equation 1 and obtain the system:

• Thus, the only solution of the original system is (29,16,3). To verify that (29,16,3) is a solution, substitute these values into the left side of the original system, and compute.

$$(29)-2(16)+(3) = 29-32+3=0$$
$$2(16)-8(3) = 32-24=8$$
$$-4(29)+5(16)+9(3) = -116+80+27=-9$$

• The results agree with the right side of the original system, so (29,16,3) is a solution of the system.

ELEMENTARY ROW OPERATIONS

- Elementary row operations include the following:
 - 1. (Replacement) Replace one row by the sum of itself and a multiple of another row.
 - 2. (Interchange) Interchange two rows.
 - 3. (Scaling) Multiply all entries in a row by a nonzero constant.
- Two matrices are called **row equivalent** if there is a sequence of elementary row operations that transforms one matrix into the other.

ELEMENTARY ROW OPERATIONS

- It is important to note that row operations are reversible.
- If the augmented matrices of two linear systems are row equivalent, then the two systems have the same solution set.
- Two fundamental questions about a linear system are as follows:
 - 1. Is the system consistent; that is, does at least one solution *exist*?
 - 2. If a solution exists, is it the *only* one; that is, is the solution *unique*?

• Example 3: Determine if the following system is consistent:

$$x_{2} - 4x_{3} = 8$$

$$2x_{1} - 3x_{2} + 2x_{3} = 1$$

$$5x_{1} - 8x_{2} + 7x_{3} = 1$$
(5)

• **Solution:** The augmented matrix is

$$\begin{bmatrix} 0 & 1 & -4 & 8 \\ 2 & -3 & 2 & 1 \\ 5 & -8 & 7 & 1 \end{bmatrix}$$

• To obtain an x_1 in in the first equation, interchange rows 1 and 2:

$$\begin{bmatrix} 2 & -3 & 2 & 1 \\ 0 & 1 & -4 & 8 \\ 5 & -8 & 7 & 1 \end{bmatrix}$$

• To eliminate the $5x_1$ term in the third equation, add -5/2 times row 1 to row 3.

$$\begin{bmatrix} 2 & -3 & 2 & 1 \\ 0 & 1 & -4 & 8 \\ 0 & -1/2 & 2 & -3/2 \end{bmatrix}$$
 (6)

• Next, use the x_2 term in the second equation to eliminate the $-(1/2)x_2$ term from the third equation. Add 1/2times row 2 to row 3.

$$\begin{bmatrix}
2 & -3 & 2 & 1 \\
0 & 1 & -4 & 8 \\
0 & 0 & 0 & 5/2
\end{bmatrix}$$
(7)

• The augmented matrix is now in triangular form. To interpret it correctly, go back to equation notation.

$$2x_{1} - 3x_{2} + 2x_{3} = 1$$

$$x_{2} - 4x_{3} = 8$$

$$0 = 5/2$$
(8)

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- The equation 0 = 5/2 is a short form of $0x_1 + 0x_2 + 0x_3 = 5/2$.
- There are no values of x_1 , x_2 , x_3 that satisfy (8) because the equation 0 = 5/2 is never true.
- Since (8) and (5) have the same solution set, the original system is inconsistent (*i.e.*, has no solution).