

# 1. THE REGION FOR $\tilde{K}_{m,5}$ WITH THREE STEADY STATES

The mass-action ODEs  $\dot{x} = f(x)$  of  $\tilde{K}_{m,5}$  are given by ( $r_4 > mr_5$ ):

$$(1) \quad \begin{cases} f_1 = -r_1x_1x_2 - r_5x_1 - r_6x_1 + r_1 + r_5 + r_6, \\ f_2 = -r_1x_1x_2 - r_2x_2x_3 - r_7x_2 + r_1 + r_2 + r_7, \\ f_3 = -r_2x_2x_3 - r_3x_3x_4 - r_8x_3 + r_2 + r_3 + r_8, \\ f_4 = -r_3x_3x_4 - r_4x_4x_5 - r_9x_4 + r_3 + r_4 + r_9, \\ f_5 = -r_4x_4x_5 + mr_5x_1 - r_{10}x_5 + r_4 - mr_5 + r_{10}. \end{cases}$$

Assume  $r_6 = r_8 = r_9 = r_{10} = \varepsilon$ . For  $\varepsilon$  sufficiently small and the other rate constants satisfy:

$$(2) \quad \begin{cases} (m-1)r_1 > r_7, \\ (m-1)r_1r_i > (-1)^{i-1}m((r_1+r_5)r_7 - (m-1)r_1r_5), \quad i = 2, 3, 4, \end{cases}$$

the system (1) admits two steady states:  $\delta_1 = (1, 1, \dots, 1)$  and  $\delta_2$ .

Let

$$(3) \quad x = \varphi_1(y) : \begin{cases} x_i = y_i, i = 1, 2, 3, \\ x_4 = \frac{\varepsilon y_4}{y_5}, \\ x_5 = \frac{y_5}{\varepsilon}, \end{cases}$$

$$(4) \quad x = \varphi_2(y) : \begin{cases} x_i = y_i, i = 1, 2, \\ x_3 = \frac{\varepsilon y_3}{y_4}, \\ x_4 = \frac{y_4}{\varepsilon}, \\ x_5 = \frac{\varepsilon y_5}{y_4}, \end{cases}$$

and

$$(5) \quad x = \varphi_3(y) : \begin{cases} x_1 = y_1, \\ x_2 = \frac{\varepsilon y_2}{y_3}, \\ x_3 = \frac{y_3}{\varepsilon}, \\ x_4 = \frac{\varepsilon y_4}{y_5}, \\ x_5 = \frac{y_5}{\varepsilon}. \end{cases}$$

Substitute  $x = \varphi_i(y)$  ( $i = 1, 2, 3$ ) into  $f$  with  $y_1, \dots, y_5$  viewed as new variables and the resulting polynomial system is denoted by  $p^{(i)} := f|_{x=\varphi_i(y)}$  ( $i = 1, 2, 3$ ). Then let  $\varepsilon = 0$  and the resulting polynomial system is denoted by  $g^{(i)} := p^{(i)}|_{\varepsilon=0}$  ( $i = 1, 2, 3$ ).

**Case 1:** The system (1) admits exactly one steady state  $\delta_3$  of type  $[0\infty]$  for rate constants:

$$(6) \quad \begin{cases} (m-1)r_1 > r_7, \\ r_3 < r_1 + r_7, \\ (m-1)r_1r_3 > m((r_1+r_5)r_7 - (m-1)r_1r_5). \end{cases}$$

**Case 2:** Eliminate  $y_2$  from  $p_1^{(2)}$  and  $p_2^{(2)}$  and obtain

$$(7) \quad h_2 := r_1r_5y_1^2 + (r_1r_2 - r_1r_5 + r_1r_7 + r_5r_7)y_1 - (r_1 + r_5)r_7.$$

Let  $\xi_2$  be the positive root of (7). Then we have

$$(8) \quad \begin{cases} y_2 = \frac{r_1+r_2+r_7}{r_1\xi_2+r_7}, \\ y_3 = \frac{r_2+r_3}{r_3}, \\ y_4 = mr_5(1-\xi_2) - r_2, \\ y_5 = \frac{r_4-mr_5+mr_5\xi_2}{r_4}. \end{cases}$$

To ensure  $y_2, y_3, y_4, y_5 > 0$ , we need

$$(9) \quad \xi_2 < 1 - \frac{r_2}{mr_5},$$

which is equivalent to  $h_2(1 - \frac{r_4}{mr_5}) > 0$ . Note that

$$h_2(1 - \frac{r_4}{mr_5}) = -\frac{r_2((m-1)r_1r_2 - m((m-1)r_1r_5 - (r_1+r_5)r_7))}{m^2r_5}.$$

Hence  $h_2(1 - \frac{r_4}{mr_5}) > 0$  is equivalent to

$$(10) \quad (m-1)r_1r_2 - m((m-1)r_1r_5 - (r_1+r_5)r_7) < 0.$$

Hence the system (1) admits exactly one steady state  $\delta_4$  of type  $[0\infty 0]$  for rate constants:

$$(11) \quad \begin{cases} (m-1)r_1 > r_7, \\ (m-1)r_1r_5 > (r_1+r_5)r_7, \\ (m-1)r_1r_2 < m((m-1)r_1r_5 - (r_1+r_5)r_7). \end{cases}$$

**Case 3:** Eliminate  $y_1, y_2, y_3, y_5$  from  $p_i^{(3)}, i = 1, \dots, 5$  and obtain

$$(12) \quad h_3 := r_4(r_4 - r_3)y_4^2 + (r_1r_3 - mr_1r_4 - 2r_4^2 + r_3r_7)y_4 + (mr_1 + r_4)(r_3 + r_4).$$

Let  $\xi_3$  be the positive root of (12). Then we have

$$(13) \quad \begin{cases} y_1 = \frac{r_1+r_5}{r_5}, \\ y_2 = \frac{r_1+r_2+r_7}{r_2}, \\ y_3 = r_4(\xi_3 - 1) - r_1 - r_7, \\ y_5 = mr_1 - r_4(\xi_3 - 1). \end{cases}$$

To ensure  $y_1, y_2, y_3, y_5 > 0$ , we need

$$(14) \quad 1 + \frac{r_1 + r_7}{r_4} < \xi_3 < 1 + \frac{mr_1}{r_4}.$$

Note that

$$h_3(1 + \frac{mr_1}{r_4}) = -\frac{r_3(mr_1 + r_4)((m-1)r_1 - r_7)}{r_4} < 0.$$

Hence we must have  $h_3(1 + \frac{r_1+r_7}{r_4}) > 0$ , i.e.,

$$(15) \quad h_3(1 + \frac{r_1 + r_7}{r_4}) = -((m-1)r_1 - r_7)(r_1 + r_7 - r_3) > 0,$$

which is equivalent to  $r_3 > r_1 + r_7$ .

Hence the system (1) admits exactly one steady state  $\delta_5$  of type  $[0\infty 0\infty]$  for rate constants:

$$(16) \quad \begin{cases} (m-1)r_1 > r_7, \\ r_3 > r_1 + r_7. \end{cases}$$

The steady states  $\delta_i, i = 2, 3, 4, 5$  can be divided into two classes:

Types	Steady states
$\square, [0\infty 0]$	$\delta_2, \delta_4$
$[0\infty], [0\infty 0\infty]$	$\delta_3, \delta_5$

For specific rate constants, the system (1) admits at most one steady state from each class.

We summarize the open region for three steady states as follows:

$$(17) \quad \begin{cases} r_7 < (m-1)r_1, \\ r_5 < \frac{r_1 r_7}{(m-1)r_1 - r_7}, \\ r_4 > m r_5, \\ r_3 > \frac{m((r_1 + r_5)r_7 - (m-1)r_1 r_5)}{(m-1)r_1}, \end{cases}$$

and

$$(18) \quad \begin{cases} r_7 < (m-1)r_1, \\ r_5 > \frac{r_1 r_7}{(m-1)r_1 - r_7}, \\ r_4 > m r_5. \end{cases}$$

## 2. THE REGION FOR $\tilde{K}_{m,7}$ WITH THREE STEADY STATES

**Case 1:** The system (1) admits two steady state  $\delta_1 = (1, 1, \dots, 1)$  and  $\delta_2$  of type  $\square$  for rate constants:

$$(19) \quad \begin{cases} (m-1)r_1 > r_9, \\ (m-1)r_1 r_i > (-1)^{i-1} m((r_1 + r_7)r_9 - (m-1)r_1 r_7), \quad i = 2, \dots, 6. \end{cases}$$

**Case 2:** The system (1) admits exactly one steady state  $\delta_3$  of type  $[0\infty]$  for rate constants:

$$(20) \quad \begin{cases} (m-1)r_1 > r_9, \\ r_5 < r_3, \\ r_5 < r_1 + r_9, \\ (m-1)r_1 r_5 > m((r_1 + r_7)r_9 - (m-1)r_1 r_7). \end{cases}$$

**Case 3:** The system (1) admits exactly one steady state  $\delta_4$  of type  $[0\infty 0]$  for rate constants:

$$(21) \quad \begin{cases} (m-1)r_1 > r_9, \\ r_4 < r_2, \\ r_4 < m r_7, \\ (m-1)r_1 r_4 < m((m-1)r_1 r_7 - (r_1 + r_7)r_9). \end{cases}$$

**Case 4:** The system (1) admits exactly one steady state  $\delta_5$  of type  $[0\infty 0\infty]$  for rate constants:

$$(22) \quad \begin{cases} (m-1)r_1 > r_9, \\ r_3 < r_5, \\ r_3 < r_1 + r_9, \\ (m-1)r_1 r_3 > m((r_1 + r_7)r_9 - (m-1)r_1 r_7). \end{cases}$$

**Case 5:** The system (1) admits exactly one steady state  $\delta_6$  of type  $[0\infty 0\infty 0]$  for rate constants:

$$(23) \quad \begin{cases} (m-1)r_1 > r_9, \\ r_2 < r_4, \\ r_2 < mr_7, \\ (m-1)r_1r_2 < m((m-1)r_1r_7 - (r_1 + r_7)r_9). \end{cases}$$

**Case 6:** The system (1) admits steady states  $\delta_7$  of type  $[0\infty 0\infty 0\infty]$  for rate constants:

$$(24) \quad \begin{cases} (m-1)r_1 > r_9, \\ r_3 > r_1 + r_9, \\ r_5 > r_1 + r_9, \\ \dots \end{cases}$$

We need to show in Case 6, the system (1) admits at most one steady state of type  $[0\infty 0\infty 0\infty]$ , i.e., the following system admits at most one steady state:

$$(25) \quad \begin{cases} r_1 + r_7 - r_7y_1, \\ r_1 + r_2 + r_9 - r_2y_2, \\ r_2 + r_3 - r_2y_2 - y_3 - \frac{r_3y_3y_4}{y_5}, \\ r_3 + r_4 - r_4y_4 - \frac{r_3y_3y_4}{y_5}, \\ r_4 + r_5 - r_4y_4 - y_5 - \frac{r_5y_5y_6}{y_7}, \\ r_5 + r_6 - r_6y_6 - \frac{r_5y_5y_6}{y_7}, \\ r_6 - mr_7 + mr_7y_1 - r_6y_6 - y_7. \end{cases}$$

The steady states  $\delta_i, i = 2, \dots, 7$  can be divided into two classes:

Types	Steady states
$[], [0\infty 0], [0\infty 0\infty 0]$	$\delta_2, \delta_4, \delta_6$
$[0\infty], [0\infty 0\infty], [0\infty 0\infty 0\infty]$	$\delta_3, \delta_5, \delta_7$

For specific rate constants, the system (1) admits at most one steady state from each class.