## Algorithm 1 generating time series with RSGP

Require:  $0 \le \alpha \le 1$ 

Ensure:  $K(t,t') = K_{RSGP} = \alpha K_{GP} + (1-\alpha)K_{RS}$ 

for t := 1, ..., T do

1. Given the previous value and reward history, infer the distribution from the conditional probability:

$$[x^1, ..., x^{t-1}, x^t] \sim \mathcal{N}(0, [K_{t-1,t-1}, K_{t-1,1}; K_{1,t-1}, K_{1,1}])$$

- 2. Sample  $x^t$  from the distribution obtained in step 1.
- 3. Update the reward,  $K_{RS}$  and K based on new sample  $x^t$  end for

$$K_{RSGP}(t, t - s) = \sigma_{SE}^2 K_{SE}(t, t - s) + \sigma_{RS}^2 K_{RS}(t, t - s) + \sigma_0^2 I$$
$$K_{SE}(t, t - s) = \exp(-\frac{s^2}{2l_{SE}^2})$$

$$K_{RS}(t,t-s) = \left\{ \begin{array}{ll} \exp(-\frac{s^2}{2l_{RS}^2}) & \mbox{if trial t-s was rewarded} \\ 0 & \mbox{otherwise} \end{array} \right.$$

## Algorithm 2 using reward gradient search

for t := 1, ..., T do

1. Gradient derived from the previous performance and reward

$$\Delta x = \alpha (x^{t-1} - x^{t-2})(r^{t-1} - r^{t-2})$$

2. Generate  $x^t$  with the added scalar production noise  $\epsilon \sim \mathcal{N}(0, \sigma_p)$ 

$$x_n = x^{t-1} + \Delta x + \epsilon$$

3. Compute the amplitude of reward  $r^t$  based on  $x^t$  and reward profile. end for

## Algorithm 3 Markov chain Monte Carlo sampling

for t := 1, ..., T do

- 1. Keep in memory a target variable  $x^*$  that is currently highest scored according to the value estimate V(x)
- 2. One this trial, sample the target variable  $x^+$  from a Gaussian distribution in the vicinity of  $x^*$  and standard deviation  $\sigma_e$
- 3. Generate a new x by sampling from a Gaussian distribution with mean  $x^+$  and standard deviation  $\sigma_p$  (scalar noise). Assign the reward as the value of new sample  $V(x^+)$ .
- 4. Use a probabilistic Metropolis-Hastings rule to accept or reject  $x^+$  as the new  $x^*$ . The acceptance probability is

$$\mathbf{P}(\mathbf{accept}\; x^+) = \frac{e^{\beta V(x^+)}}{e^{\beta V(x^+)} + e^{\beta V(x^*)}}$$

where  $\beta$  is a free parameter controlling the volatility, known as the inverse temperature in Reinforcement learning.

end for