

Review

Multi variable Calculus.

Object : $f: \mathbb{R}^m \rightarrow \mathbb{R}^n$

$$\left(\begin{array}{c} \vec{x} \\ x_1 \\ \vdots \\ x_m \end{array} \right) \quad \left(\begin{array}{c} \vec{y} = f(\vec{x}) \\ y_1 = f_1(x_1, \dots, x_m) \\ \vdots \\ y_n = f_n(x_1, \dots, x_m) \end{array} \right)$$

Example: curve. $\gamma: \mathbb{R} \rightarrow \mathbb{R}^n$

$$t \rightarrow \vec{\gamma}(t)$$

surface: $\mathbb{R}^2 \rightarrow \mathbb{R}^3$

vector field: $\mathbb{R}^2 \rightarrow \mathbb{R}^2$
 $\mathbb{R}^3 \rightarrow \mathbb{R}^3$

Derivative

First order

• $f: \mathbb{R}^m \rightarrow \mathbb{R}$. partial derivative.

$$\nabla f = \left(\begin{array}{c} \frac{\partial f}{\partial x_1} \\ \vdots \\ \frac{\partial f}{\partial x_m} \end{array} \right)$$

Technique: Chain Rule.

∇f is normal to tangent plane.

linear approximation of f / tangent plane \nearrow for $f = f(\vec{x}_0)$

$$df = \frac{\partial f}{\partial x_1} dx_1 + \dots + \frac{\partial f}{\partial x_m} dx_m \quad \text{at } \vec{x} = \vec{x}_0.$$

$$\nabla_v f = \nabla f \cdot \vec{v} \quad (\text{directional derivative})$$

Application : • Critical Points

• Conservative Vector Field.

$$\text{curl}(\vec{F}) = \vec{0} \Rightarrow \vec{F} \text{ is conservative (when } D \text{ is nice)}$$

• Velocity.

• Taylor Expansion. near a point.
 Second order.

$$f(x) \approx f(\vec{x}_0) + \nabla f \cdot (\vec{x} - \vec{x}_0) + \underbrace{(\vec{x} - \vec{x}_0) \cdot H \cdot (\vec{x} - \vec{x}_0)^T}_{\frac{1}{2}}$$

when $n=2$. $H = \begin{pmatrix} f_{xx} & f_{xy} \\ f_{xy} & f_{yy} \end{pmatrix} \frac{1}{2}$.

Application: • determine local min/max.

• acceleration.

• curvature.

Integral

Fundamental Thm of Calculus.

• Double / Triple Integral.

strategy:

multiple layers after translating to iterated integral.

technique:

polar coordinate. (substitution) $r \cdot dr d\theta$

cylinder

$$r \cdot dr d\theta dz$$

sphere.

$$r^2 \sin\phi \, dr d\phi d\theta$$

application:

area

volume

arc length / surface area.

$$\|\vec{r}'(t)\|$$

$$\|\vec{x}_u \times \vec{x}_v\|$$

• Line Integral / Surface Integral.

L/S Integral of function: mass / center of mass

L/S Integral of vector fields: $\left\{ \begin{array}{l} \text{flux} \quad \vec{F} \cdot \vec{n} \\ \text{circulation} \quad \vec{F} \cdot \vec{T} \end{array} \right.$

In reality $\vec{F} \cdot \vec{T} = \vec{F} \cdot \frac{\vec{r}'(t)}{|\vec{r}'(t)|} = \vec{F} \cdot (\vec{x}_u \times \vec{x}_v)$

Basic Strategy: Parametrization \rightarrow Compute $\frac{\vec{F} \cdot \vec{n}}{t, (u, v)}$ or $\frac{\vec{F} \cdot \vec{T}}{t, (u, v)}$ as a function of L/S.

\downarrow

L/S integral of functions.

Technique: Green's Thm / Divergence Thm / Stoke's Thm.



Line Integral



Double Integral



$$\oint_{\partial D} \vec{F} \cdot \vec{n} \, ds$$

=

$$\iint_D (\nabla \cdot \vec{F}) \, dx \, dy.$$

\rightarrow divergence of \vec{F} .

$$\oint_{\partial D} \vec{F} \cdot \vec{T} \, ds$$

=

$$\iint_D \text{curl}(\vec{F}) \cdot \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \, dx \, dy.$$

\vec{n}

generalize.

\rightarrow Divergence Thm.

Surface Integral



∂V : surface.

$$\oiint_{\partial V} \vec{F} \cdot \vec{n} \, ds$$

\rightarrow outward

=

Triple Integral.



V: solid.

$$\iiint_V \nabla \cdot \vec{F} \, dx \, dy \, dz.$$

Stoke's Thm.

Line Integral



$$\oint_{\partial S} \vec{F} \cdot \underbrace{\vec{T}}_{\|\vec{r}'(t)\| dt} ds =$$

Surface Integral.



$$\iint_S (\text{curl}(\vec{F})) \cdot \underbrace{\vec{n}}_{\|\vec{x}_u \times \vec{x}_v\| du dv} dS$$