# Evolving Mach 3.0 to a Migrating Thread Model

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#### **Terminology**

Thread: A sequential flow of control.

RPC: A control transfer modeling a procedure call, that crosses the protection barrier between two processes.

Static thread model: RPC is implemented by two separate threads, each confined to one process, passing messages.

Migrating thread model: RPC is implemented by one thread temporarily crossing the protection barrier and "doing its own work" in the server's code.

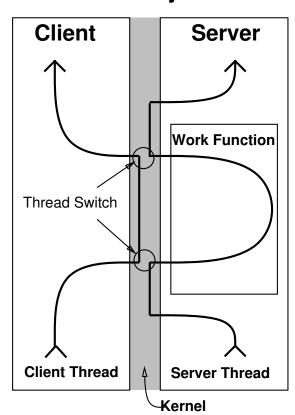
#### Thread Models in RPC

RPC is supposed to model a procedure call.

So, what's all the gunk on the left?!

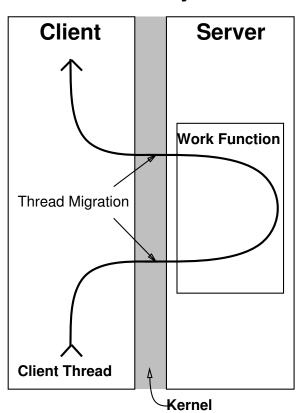
# **Switching**

"Active Objects"



# **Migrating**

"Passive Objects"



#### Research Overview

Questions: Is the migrating thread model a good idea? Does it make much difference?

*Project:* Design and implement a version of Mach based on migrating threads; compare the two versions.

Result: Migrating threads are better in speed, code simplicity, and functionality; do not sacrifice protection or backward compatibility.

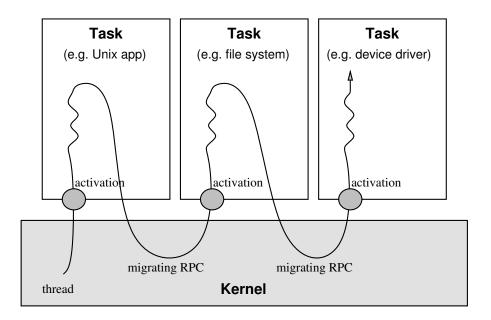
#### **Primary Issues**

- What is the execution environment of a client thread in a server?
- How can clients and servers be protected from each other?
- How can good controllability be provided?

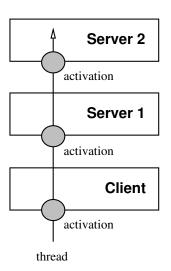
# Key Design Element: Split Up the Thread

- "Thread" (migrating part)
  - \* Logical flow of control
  - \* Schedulable entity (priority, policy, time quantum)
  - \* Resource accounting statistics
- "Activation" (static part)
  - \* Execution context(PC, registers, stack)
  - \* Exported point of control
     (Mach "control port")

# **Threads and Activations**



### **Threads and Activations**

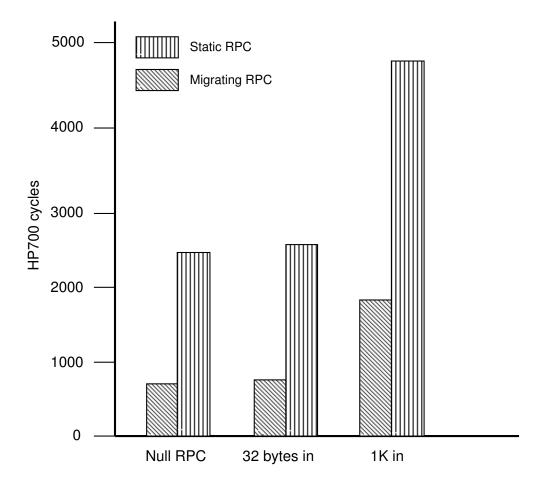


### And the winner is...

Migrating threads provide better:

- Performance
- Simplicity of kernel code
- Functionality

# **Performance Comparison**



### Why is it faster?

- Upcall semantics on server side
- Kernel-visible RPC (no "reply ports")
- No scheduler involvement

### **Simpler**

RPC paths:

Approx 2000 lines of code replaced by 400.

Control mechanisms:
Approx 3000 lines of code replaced by 1700.

#### **Macrobenchmark Results**

- "make" of gas: 2% faster
- link of HP-UX linker: 14% faster

*Note:* without additional leverage of migrating RPC yet.

# What made the RPC path simpler?

Answer: the same things that made it faster!

- Reversed call semantics on server side:
   146 instructions down to 33
- Kernel-visible RPC:
   206 instructions down to 12
- No scheduler involvement:
   408 instructions down to 30

#### More Functional

- Inherited thread attributes:
  - \* Priority (real-time)
  - \* Resource limits and accounting
- RPC call chain provides client-server communication channel

#### **Related Work**

- Amoeba: exports RPC to user
- Alpha: real time, remote migration
- LRPC on Taos
- Spring: confronted Unix issues
- "Passive Object" Systems:
   Emerald, Clouds, Psyche

### LRPC Comparison

- LRPC addressed data transfer also
- We attempted to isolate control transfer
- We examined simplicity
- We fully addressed controllability issues (Taos has weak protection semantics)

# Issues/Future Work

- Leverage to further optimize Mach RPC
- Use improved functionality to simplify servers
- Leverage for real-time support
- Extend to cross-node RPC
- Show another OS can be evolved

#### **Conclusions**

- A migrating thread model is faster, simpler, and more powerful.
- Exported RPC abstraction a prerequsite; synchronous invocation beats async.
- Existing systems can be adapted without sacrificing backward compatibility.

# Why We Don't Use Spring's Terminology

- High-level concept of "thread" fits the migrating entity better
- Encourages us to think in the new model
- Precedent: Alpha, LRPC
- Momentum