





Generative Correlation Discovery Network for Multi-Label Learning

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Multi-label Learning



Far-away

Label Space

Background:

• One object can be described by tens or hundreds of descriptions such as color, shape, texture and category. It is meaningful to predict all the labels from one instance.

Goal:

- Multi-label learning aims to seek a mapping from the feature space to the multi-label space.
 - Input: Instance samples (Image or features)
 - Output: multiple predicted labels



Input instance [1]

Multi-label Classification Setting: Seeking a mapping from the feature space to the label space with multiple positive labels.

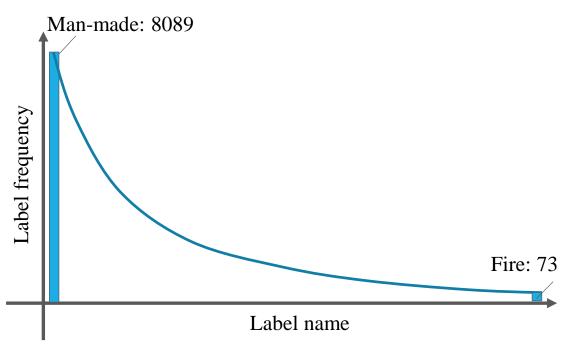
Challenges



1. Long-tail label distribution

The labels followed a long-tail distribution characteristic, which means some labels are always show up while some labels are rarely be assigned. The label imbalance significantly affect the learning performance in the multi-label learning setting.

E.g., For SUN dataset [1], the most common label (i.e., *Manmade*) shows up 8089 times in all the samples, while the rarest label (i.e., *Fire*) only shows up 73 times.



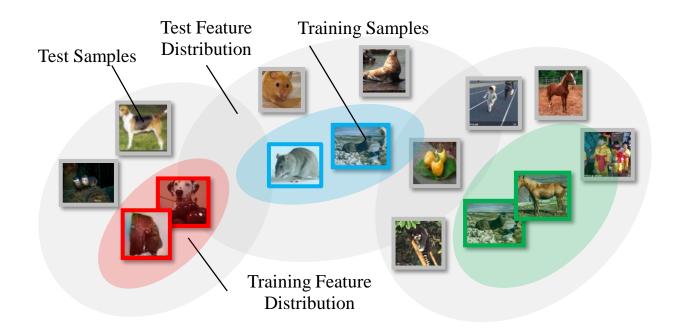
The curve of the label sample numbers. The difference is significant between the most common and rarest labels.

Challenges



2. Distribution gaps between training and testing sets.

- The training sets cannot cover the entire feature space of testing set due to the small scale of the existing datasets and long-tail label distribution characteristic.
- This challenge is common in most machine learning tasks but more significant in multi-label learning scenario.
- How to efficiently utilize the label distribution is challenge for achieving high performance.



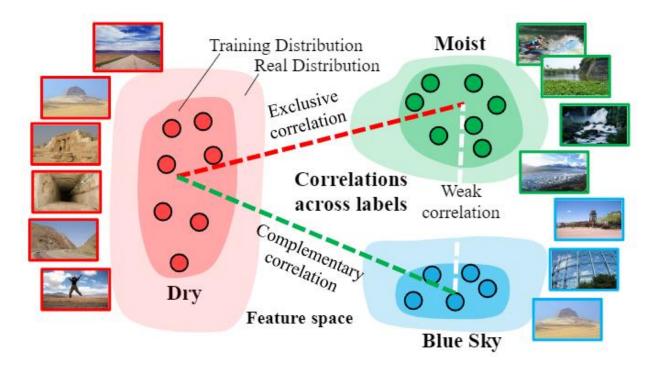
Distribution differences between training and testing features. Colored area denotes training set. Different colors indicate different labels. Gray area denotes testing set.

Challenges



3. Complicated correlations across different labels:

- Label correlation is crucial for high accurate label prediction.
- Label correlation / semantic knowledge is difficult, expensive and challenging to obtain.
- Existing correlation is difficult to extend to a wide range of real-world applications.



Label correlation is crucial for accurate multi-label prediction. For instance, *Dry* and *Moist* are exclusive, while *Dry* and *BlueSky* are complementary.

Model motivations



Generative Correlation Discovery Network for Multi-Label Learning:

We propose an end-to-end Generative Correlation Discovery Network (GCDN) method for multi-label learnin.

- GCDN captures the existing data distribution and synthesizes diverse data to enlarge the diversity of the training features.
- GCDN learns the label correlations based on a specifically-designed, simple but effective correlation discovery network. It automatically discover the label correlations and considerately improve the label prediction accuracy.

Contribution:

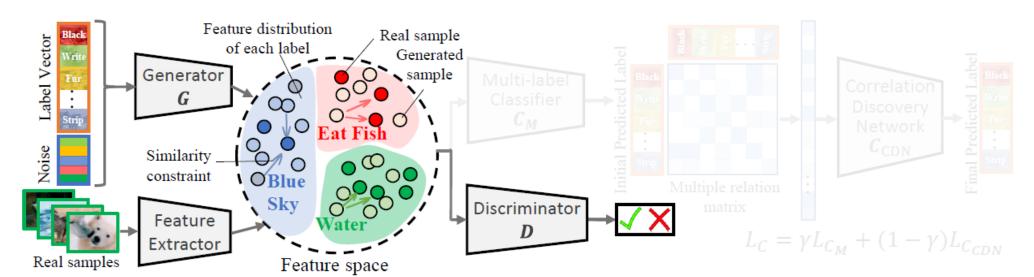
- 1. A specifically-designed multi-label conditional feature generative strategy is proposed. It synthesizes and diversifies the feature space to improve the model robustness and generalization.
- 2. A graph-based Correlation Discovery Network (CDN) is proposed to automatically learn semantic correlations across different labels and utilize the knowledge to further improve learning performance.

1. Conditional Generative Module



- A conditional generative module is proposed. It generates new data conditioned on the input multi-label input.
- The conditioned label is extracted from ground truth in the generator training procedure
- A randomly generated label vector is utilized for training the following multi-label classifiers.

$$L_D = E_{X \sim p_X(X)} \log D(X|Y) \qquad L_{Gd} = -E_{z \sim p_z(z)} \log(1 - D(G(z|Y))) + E_{z \sim p_z(z)} \log(1 - D(G(z|Y))) \qquad L_{Gs} = ||G(z|Y) - X||_F^2$$



Generative module to augment and diversify the training samples

2. Correlation Discovery Network

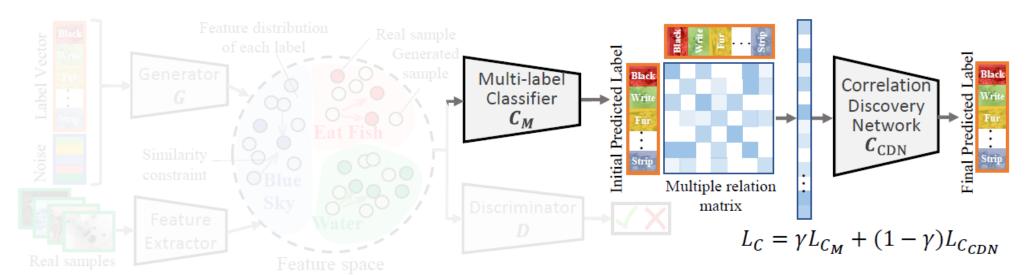


• $C_{\rm M}(.)$ obtains initial (low-accurate) results first, then $C_{CDN}(.)$ further utilizes the available prediction to "tune" the result to high-accurate..

$$L_{C_{CDN}} = \sum_{i=1}^{n_l} \|y_i - C_{CDN}(C_M(x_i)C_M(x_i)^\top)\|_2^2$$

• We balances the update processing between $C_{\rm M}(.)$ and $C_{CDN}(.)$ to further help each other in the training stage and achieve the promising performance at last.

$$L_C = \gamma L_{C_M} + (1 - \gamma) L_{C_{CDN}}$$



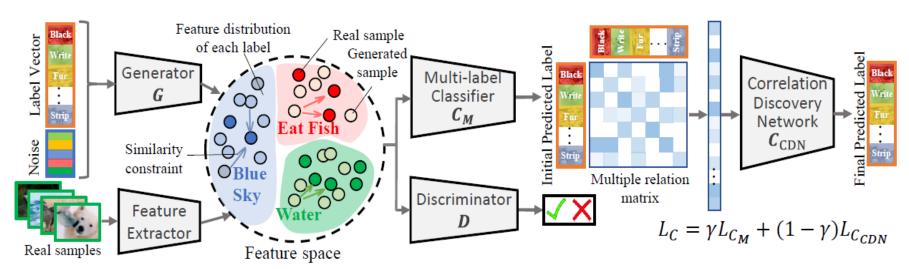
Generative module to augment and diversify the training samples

Our approach



Our complete model:

- Generative model is utilized to generate and diversify the training samples. An adjacent matrix is built based on the predicted multi-label associated with another fully connected network.
- The model atomically learns the latent label correlation across different labels.
- All the networks are trained simultaneously to achieve the best performance.



Framework of our approach, where a generator, a discriminator and a classifier, and the correlation discovery network are simultaneously trained.



Multi-label prediction performance:

- Six dataset are used for evaluate the multilabel recovery performance
 - Coreal, ESP, IAP, SUN, CUB, AWA
- Five evaluation metrics
 - Precision (Pre)
 - Recall (Rec)
 - F1
 - Non-zero Recall (N-R)
 - Mean average precision (mAP)

Data	Method	Pre	Rec	F1	N-R	mAP
	LR	0.2859	0.3211	0.3025	128	0.3630
	SSMLDR	0.2741	0.3366	0.3022	143	0.3410
	FastTag	0.3123	0.3657	0.3369	143	0.3871
	ML-PGD	0.2575	0.2911	0.2732	122	0.3727
Corel	SAE	0.2962	0.3442	0.3184	141	0.3823
Corei	AG2E	0.3011	0.3520	0.3245	157	0.3568
	Ours	0.3335	0.3714	0.3514	148	0.4417
	LR	0.3793	0.2038	0.2653	215	0.3440
	SSMLDR	0.3298	0.1885	0.2399	226	0.3156
	FastTag	0.4011	0.1927	0.2617	208	0.3904
	ML-PGD	0.3239	0.2012	0.2482	210	0.4077
ESP	SAE	0.3861	0.1743	0.2402	194	0.3842
ESP	AG2E	0.3548	0.1525	0.2133	213	0.3730
	Ours	0.4032	0.2178	0.2828	239	0.4327
	LR	0.4287	0.2041	0.2765	199	0.4211
	SSMLDR	0.3491	0.2520	0.2927	229	0.3981
	FastTag	0.4346	0.2267	0.2980	227	0.4596
	ML-PGD	0.4132	0.2441	0.3011	230	0.4674
IAD	SAE	0.3537	0.2282	0.2774	213	0.4309
IAP	AG2E	0.3829	0.2330	0.2897	229	0.4353
	Ours	0.4732	0.2648	0.3396	237	0.5295

	LR	0.6209	0.1473	0.2457	102	0.6807
	SSMLDR	0.6879	0.1700	0.2726	102	0.6723
	FastTag	0.6816	0.1473	0.2457	102	0.6914
	ML-PGD	0.7110	0.1614	0.2631	101	0.7087
SUN	SAE	0.7183	0.1638	0.2668	98	0.7012
SUN	AG2E	0.7685	0.1765	0.2871	99	0.6778
	Ours	0.7985	0.1835	0.2985	102	0.7093
	LR	0.2010	0.0239	0.0428	157	0.0638
	SSMLDR	0.3410	0.0473	0.0832	178	0.2329
	FastTag	0.2147	0.0359	0.0615	167	0.3144
	ML-PGD	0.3334	0.0451	0.0794	155	0.3288
CUB	SAE	0.3383	0.0514	0.0908	196	0.3255
	AG2E	0.3409	0.0531	0.0911	190	0.3106
	Ours	0.3718	0.0541	0.0944	214	0.3561
	LR	0.8798	0.0821	0.1500	75	0.8626
	SSMLDR	0.7812	0.0858	0.1546	67	0.8346
	FastTag	0.7861	0.0949	0.1694	72	0.8791
	ML-PGD	0.5395	0.0635	0.1136	57	0.9121
43374	SAE	0.9683	0.0957	0.1742	73	0.9397
AWA	AG2E	0.8483	0.0827	0.1507	73	0.9033
	Ours	0.9716	0.0871	0.1599	83	0.9291

Multi-label classification performance on six datasets



Augmented datasets:

The work of [1] proposes a complete/augmented label set

- Corel: Averagely 3.40 to 4.84 labels
- ESP: Averagely 4.69 to 7.27 labels

Zero-shot learning scenario:

The classes in training and testing sets are non-overlapped. It is a more challenging task since the distribution gaps are more significant.

Data	Methods	Pre	Rec	F1	N-R	mAP
	LR	0.2842	0.2304	0.2545	103	0.3762
	SSMLDR	0.3036	0.2791	0.2908	134	0.3660
	FastTag	0.3329	0.3145	0.3234	136	0.4127
	ML-PGD	0.3245	0.3011	0.3124	140	0.4275
Corel-A	SAE	0.3168	0.3037	0.3101	128	0.4192
Corer-A	AG2E	0.3273	0.3172	0.3221	143	0.3985
	Ours	0.3438	0.3219	0.3325	138	0.4773
	LR	0.3848	0.1256	0.1894	178	0.3913
	SSMLDR	0.3253	0.1697	0.2231	202	0.3357
	FastTag	0.3886	0.1531	0.2197	196	0.4254
	ML-PGD	0.3713	0.1184	0.1795	162	0.4211
ESP-A	SAE	0.3153	0.1425	0.1966	156	0.4050
ESP-A	AG2E	0.3518	0.1492	0.2095	196	0.4030
	Ours	0.4772	0.1944	0.2763	225	0.4436

Multi-label Learning performance on label augmented Corel and ESP datasets

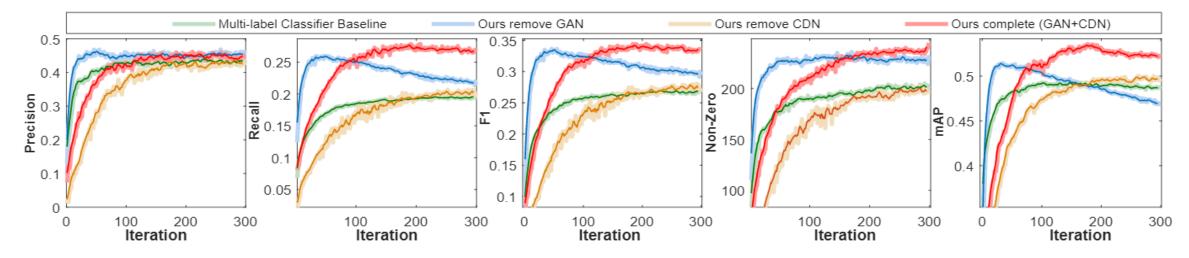
Data	Method	Pre	Rec	F1	N-R	mAP
	LR	0.7047	0.1548	0.2539	97	0.6616
	SSMLDR	0.6637	0.1481	0.2422	95	0.6581
	FastTag	0.6906	0.1522	0.2494	90	0.6706
	ML-PGD	0.7037	0.1471	0.2433	95	0.6829
SUN	SAE	0.6978	0.1710	0.2747	100	0.6513
SUN	AG2E	0.7125	0.1618	0.2637	88	0.6693
	Ours	0.7531	0.1857	0.2979	101	0.6911
	LR	0.2600	0.0307	0.0549	160	0.2693
	SSMLDR	0.2926	0.0383	0.0677	166	0.2329
	FastTag	0.2231	0.0434	0.0726	143	0.2967
	ML-PGD	0.2392	0.0365	0.0635	117	0.3178
CUB	SAE	0.2552	0.0469	0.0798	167	0.3102
CUB	AG2E	0.2808	0.0481	0.0821	163	0.2693
	Ours	0.3091	0.0488	0.0843	179	0.3264
	LR	0.7555	0.0766	0.1392	66	0.8809
	SSMLDR	0.7017	0.0764	0.1378	66	0.7858
	FastTag	0.8610	0.0912	0.1649	81	0.8918
	ML-PGD	0.4338	0.0623	0.1091	49	0.8677
A 33.7 A	SAE	0.9015	0.0926	0.1679	78	0.8918
AWA	AG2E	0.8247	0.0811	0.1476	71	0.8874
	Ours	0.9249	0.0804	0.1480	83	0.8784

Multi-label Learning in zeroshot learning setting



Ablation study:

- We run our approach based on 1) completed, 2) without GAN, 3) without CDN, and 4) without both GAN and CDN modules.
- The performance curves as the iteration increase are shown. We observe that the complete model achieves the highest performance. The CDN significantly improves the performance and the GAN model slightly improves the performance while significantly stabilizes the performance. We assume only CDN could easily cause overfitting due to the long-tail label distribution. Generative model effectively extend the feature distribution and improve the final prediction performance.

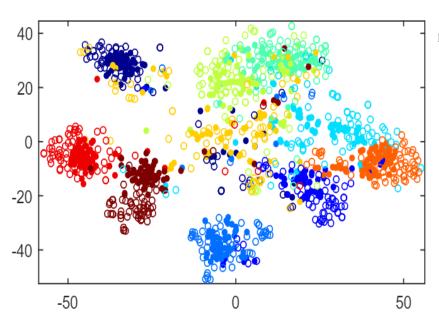


Ablation study of the proposed model. The curves indicate the performance when different modules are removed. It indicates the effectiveness of all the proposed modules in our GCDN model.



Ablation study:

- Visualization result of the real and generated samples in 2D space by t-SNE visualization approach. It shows that the real and generated samples are similar which helpful for sample augmentation and diversification.
- The experiment indicates that simply add noise in the feature space cannot improve the performance, which further demonstrates the effectiveness of generative strategy.



Real and generated samples in visual feature space

TABLE
MULTI-LABEL LEARNING PERFORMANCE OF ADDING VARIOUS
LOW-LEVEL GAUSSIAN NOISES TO THE ORIGINAL FEATURE OF CUB
DATASET.

Noise	Pre	Rec	F-1	N-R	mAP
0.00	0.3718	0.0541	0.0944	214	0.3561
0.05	0.3711	0.0540	0.0941	214	0.3561
0.10	0.3692	0.0538	0.0943	214	0.3537
0.15	0.3668	0.0537	0.0941	214	0.3511
0.20	0.3647	0.0534	0.0938	212	0.3482
0.25	0.3612	0.0533	0.0936	211	0.3467
0.30	0.3591	0.0531	0.0932	209	0.3416
0.35	0.3505	0.0530	0.0930	208	0.3389
0.40	0.3393	0.0529	0.0929	206	0.3351
0.45	0.3314	0.0528	0.0927	204	0.3232
0.50	0.3248	0.0526	0.0926	202	0.3215

Multi-label performance when different level of Gaussian noise is added into the visual feature



Parameter sensitivity of γ :

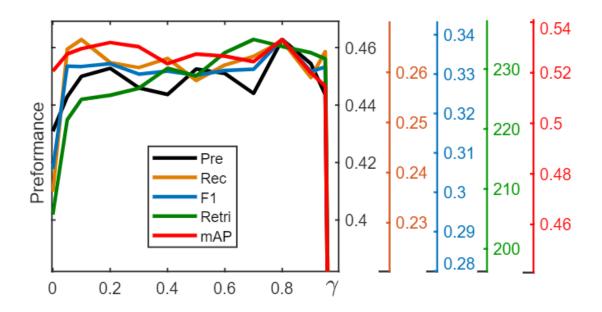
Parameter γ balances the weights between the multi-label classifier and the correlation discovery network:

- $\gamma = 1$, only multi-label classifier
- $\gamma = 0$, does not consider label correlations

$$L_C = \gamma L_{C_M} + (1 - \gamma) L_{C_{CDN}}$$

Conclusions:

- The performance achieves highest performance when $\gamma \in [0,1]$
- The proposed label correlation discovery network is effective for further improve the learning performance

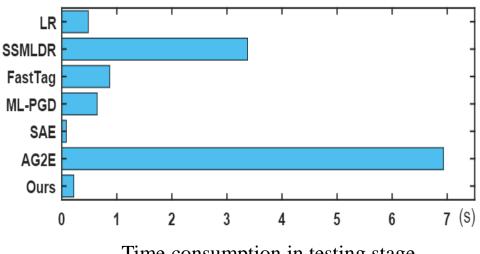


Parameter sensitivity of γ



Time Consumption:

- The approaches which require optimization procedure are computational costly (i.e., SSMLDR, AG2E).
- Other approach achieves relatively linear complicity which are fast (i.e., LR, FastTag, SAE)
- Although multiple layers are deployed in our model, the approach achieves the high speed due to the simple network structure and the GPU acceleration.



Time consumption in testing stage

Image annotation



Image annotation result:

- The case study of the image annotation result. The images are extracted from SUN dataset [1]
- The results illustrates that our approach achieves high performance and even recovery the "missing" labels in the ground truth data.



Samples of recovered labels from SUN dataset. **Black** font denotes labels that match with the ground truth. **Blue** font denotes labels that do not exist in the ground truth but match our judgments. **Red** font denotes incorrect labels from our model. The result shows that our approach is robust and able to recover labels even when labels are missed from the ground truth.

Image retrieval



Image retrieval results:

- Given a target label (e.g., *Wood*), image retrieval extract all the relevant images from the dataset.
- The results shows high retrieval performance. The most of the top retrieval results are correct.

Phenomena:

- Adjective and verb labels are more challenging than noun labels.
- Model prefers specific scenes than others



Image retrieval result of SUN dataset [1] in zero-shot scenario. Each row shows the images with the highest corresponding label score retrieved from the test set. Green and red boxes indicate correct and incorrect retrieval, respectively. For each target label, we show incorrect retrieval result and its score rankings on the image right corner.

GCDN Summary



Project goal

- Generative Correlation Discovery Network for multi-label learning (GCDN):
 - Learn feature distribution & Generative samples, fill up distribution gap.
 - Automatically explore semantic label correlations and further improve the learning performance.
- Four experimental settings:
 - Multi-label classification
 - Zero-shot Multi-label classification
 - Automatic image annotation
 - Image retrieval

- Six image datasets:
 - SUN, AWA, CUB, Core5K, ESP Game, IAPRTC-12
- Experimental results:
 - Quantified & visualization result
 - Ablation study demonstrates the effectiveness of the model
 - Efficient in the testing process



Questions?

Please contact: wanglichenxj@gmail.com for more questions.







Thank you!

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