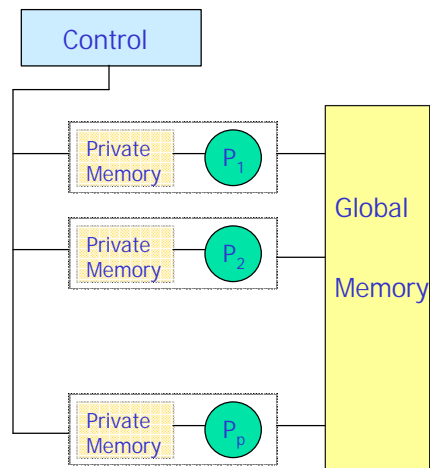


PRAM Algorithms

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Fall 2004

Parallel Random Access Machine (PRAM)

- Collection of numbered processors
- Accessing shared memory cells
- Each processor could have local memory (registers)
- Each processor can access any shared memory cell in unit time
- Input stored in shared memory cells, output also needs to be stored in shared memory
- PRAM instructions execute in 3-phase cycles
 - Read (if any) from a shared memory cell
 - Local computation (if any)
 - Write (if any) to a shared memory cell
- Processors execute these 3-phase PRAM instructions synchronously

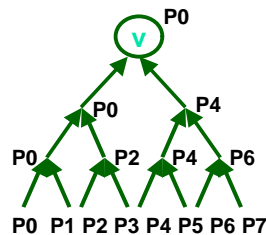


Shared Memory Access Conflicts

- Different variations:
 - Exclusive Read Exclusive Write (EREW) PRAM: no two processors are allowed to read or write the same shared memory cell simultaneously
 - Concurrent Read Exclusive Write (CREW): simultaneous read allowed, but only one processor can write
 - Concurrent Read Concurrent Write (CRCW)
- Concurrent writes:
 - Priority CRCW: processors assigned fixed distinct priorities, highest priority wins
 - Arbitrary CRCW: one randomly chosen write wins
 - Common CRCW: all processors are allowed to complete write if and only if all the values to be written are equal

A Basic PRAM Algorithm

- Let there be "n" processors and "2n" inputs
- PRAM model: EREW
- Construct a tournament where values are compared



Processor k is active in step j
if $(k \% 2^j) == 0$

At each step:

Compare two inputs,
Take max of inputs,
Write result into shared memory

Details:

Need to know who is the "parent" and
whether you are left or right child
Write to appropriate input field

PRAM Model Issues

- Complexity issues:
 - Time complexity = $O(\log n)$
 - Total number of steps = $n * \log n = O(n \log n)$
- Optimal parallel algorithm:
 - Total number of steps in parallel algorithm is equal to the number of steps in a sequential algorithm
- Use $n/\log n$ processors instead of n
- Have a local phase followed by the global phase
- Local phase: compute maximum over $\log n$ values
 - Simple sequential algorithm
 - Time for local phase = $O(\log n)$
- Global phase: take $(n/\log n)$ local maximums and compute global maximum using the tournament algorithm
 - Time for global phase = $O(\log (n/\log n)) = O(\log n)$

Time Optimality

- Example: $n = 16$
- Number of processors, $p = n/\log n = 4$
- Divide 16 elements into four groups of four each
- Local phase: each processor computes the maximum of its four local elements
- Global phase: performed amongst the maximums computed by the four processors

Finding Maximum: CRCW Algorithm

Given n elements $A[0, n-1]$, find the maximum.

With n^2 processors, each processor (i,j) compare $A[i]$ and $A[j]$, for $0 \leq i, j \leq n-1$.

FAST-MAX(A):

```

1.  n ← length[A]
2.  for i ← 0 to n-1, in parallel
3.    do m[i] ← true
4.  for i ← 0 to n-1 and j ← 0 to n-1, in parallel
5.    do if A[i] < A[j]
6.      then m[i] ← false
7.  for i ← 0 to n-1, in parallel
8.    do if m[i] = true
9.      then max ← A[i]
10. return max
    
```

	A[j]					
	5	6	9	2	9	m
A[i]	5	F	T	T	F	T
	6	F	F	T	F	T
	9	F	F	F	F	T
	2	T	T	T	F	T
	9	F	F	F	F	T
						max=9

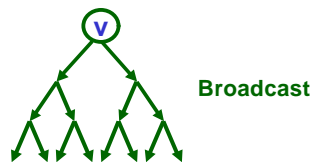
The running time is $O(1)$.

Note: there may be multiple maximum values, so their processors

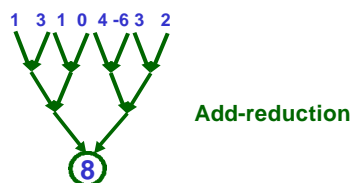
Will write to max concurrently. Its $work = n^2 \times O(1) = O(n^2)$.

Broadcast and reduction

- Broadcast of 1 value to p processors in $\log p$ time



- Reduction of p values to 1 in $\log p$ time
- Takes advantage of associativity in $+$, $*$, \min , \max , etc.

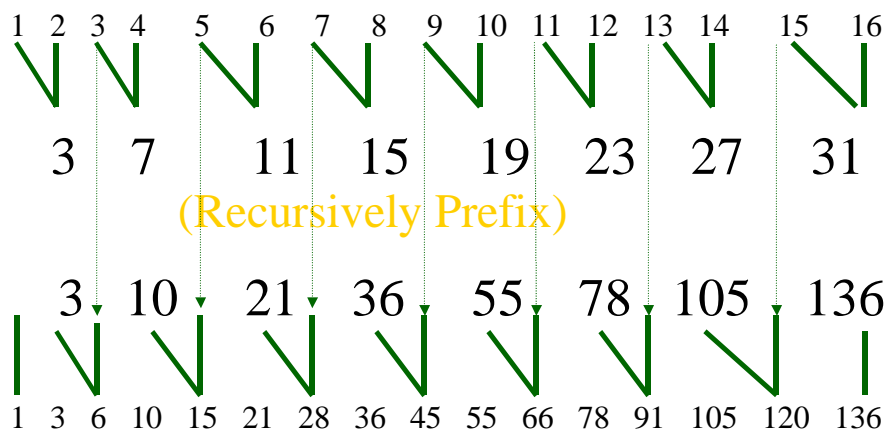


Scan (or Parallel prefix)

- What if you want to compute partial sums
- Definition: the **parallel prefix** operation take a **binary associative** operator \ominus , and an array of n elements
 $[a_0, a_1, a_2, \dots, a_{n-1}]$
 and produces the array
 $[a_0, (a_0 \ominus a_1), \dots, (a_0 \ominus a_1 \ominus \dots \ominus a_{n-1})]$
- Example: add scan of
 $[1, 2, 0, 4, 2, 1, 1, 3]$ is $[1, 3, 3, 7, 9, 10, 11, 14]$
- Can be implemented in $O(n)$ time by a serial algorithm
 - Obvious $n-1$ applications of operator will work

Prefix Sum in Parallel

Algorithm: 1. Pairwise sum 2. Recursively Prefix 3. Pairwise Sum



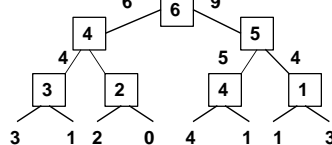
Implementing Scans

- Tree summation 2 phases
 - up sweep
 - get values L and R from left and right child
 - save L in local variable Mine
 - compute $Tmp = L + R$ and pass to parent
 - down sweep
 - get value Tmp from parent
 - send Tmp to left child
 - send $Tmp + Mine$ to right child

Up sweep:

mine = left

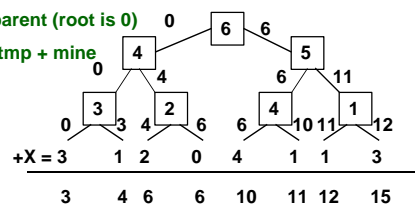
tmp = left + right



Down sweep:

tmp = parent (root is 0)

right = tmp + mine



E.g., Using Scans for Array Compression

- Given an array of n elements

$$[a_0, a_1, a_2, \dots, a_{n-1}]$$
 and an array of flags

$$[1, 0, 1, 1, 0, 0, 1, \dots]$$
 compress the flagged elements

$$[a_0, a_2, a_3, a_6, \dots]$$
- Compute a "prescan" i.e., a scan that doesn't include the element at position i in the sum

$$[0, 1, 1, 2, 3, 3, 4, \dots]$$
- Gives the index of the i^{th} element in the compressed array
 - If the flag for this element is 1, write it into the result array at the given position

E.g., Fibonacci via Matrix Multiply Prefix

$$F_{n+1} = F_n + F_{n-1}$$

$$\begin{pmatrix} F_{n+1} \\ F_n \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} F_n \\ F_{n-1} \end{pmatrix}$$

Can compute all F_n by `matmul_prefix` on

$$\left[\begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix} \right]$$

then select the upper left entry

Slide source: Alan Edelman, MIT

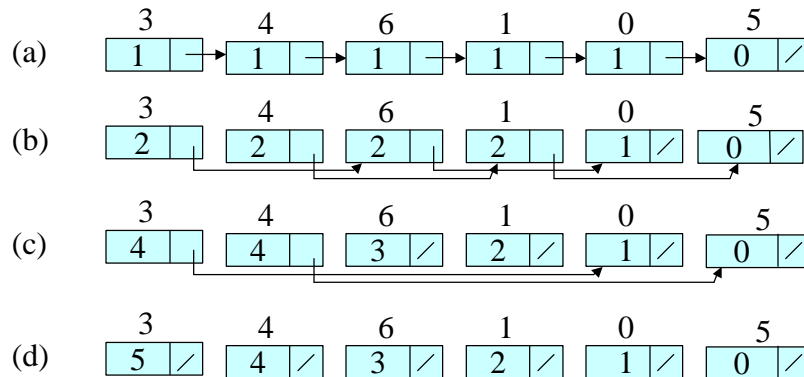
Pointer Jumping –list ranking

- Given a single linked list L with n objects, compute, for each object in L , its distance from the end of the list.
- Formally: suppose $next$ is the pointer field
$$D[i] = \begin{cases} 0 & \text{if } next[i] = \text{nil} \\ d[next[i]] + 1 & \text{if } next[i] \neq \text{nil} \end{cases}$$
- Serial algorithm: $\Theta(n)$

List ranking –EREW algorithm

- LIST-RANK(L) (in $O(\lg n)$ time)
 1. **for** each processor i , in parallel
 2. **do if** $\text{next}[i] = \text{nil}$
 3. **then** $d[i] \leftarrow 0$
 4. **else** $d[i] \leftarrow 1$
 5. **while** there exists an object i such that $\text{next}[i] \neq \text{nil}$
 6. **do for** each processor i , in parallel
 7. **do if** $\text{next}[i] \neq \text{nil}$
 8. **then** $d[i] \leftarrow d[i] + d[\text{next}[i]]$
 9. $\text{next}[i] \leftarrow \text{next}[\text{next}[i]]$

List-ranking –EREW algorithm



Recap

- PRAM algorithms covered so far:
 - Finding max on EREW and CRCW models
 - Time optimal algorithms: number of steps in parallel program is equal to the number of steps in the best sequential algorithm
 - Always qualified with the maximum number of processors that can be used to achieve the parallelism
 - Reduction operation:
 - Takes a sequence of values and applies an associative operator on the sequence to distill a single value
 - Associative operator can be: +, max, min, etc.
 - Can be performed in $O(\log n)$ time with up to $O(n/\log n)$ procs
 - Broadcast operation: send a single value to all processors
 - Also can be performed in $O(\log n)$ time with up to $O(n/\log n)$ procs

Scan Operation

- Used to compute partial sums
- Definition: the **parallel prefix** operation take a **binary associative** operator \ominus , and an array of n elements

$[a_0, a_1, a_2, \dots, a_{n-1}]$

and produces the array

$[a_0, (a_0 \ominus a_1), \dots, (a_0 \ominus a_1 \ominus \dots \ominus a_{n-1})]$

```
Scan(a, n):
  if (n == 1) { s[0] = a[0]; return s; }
  for (j = 0 ... n/2-1)
    x[j] = a[2*j]  $\ominus$  a[2*j+1];
  y = Scan(x, n/2);
  for odd j in {0 ... n-1}
    s[j] = y[j/2];
  for even j in {0 ... n-1}
    s[j] = y[j/2]  $\ominus$  a[j];
  return s;
```

Work-Time Paradigm

- Associate two complexity measures with a parallel algorithm
- $S(n)$: time complexity of a parallel algorithm
 - Total number of steps taken by an algorithm
- $W(n)$: work complexity of the algorithm
 - Total number of operations the algorithm performs
 - $W_j(n)$: number of operations the algorithm performs in step j
 - $W(n) = \sum W_j(n)$ where $j = 1 \dots S(n)$
- Can use recurrences to compute $W(n)$ and $S(n)$

Recurrences for Scan

```
Scan(a, n):  
  if (n == 1) { s[0] = a[0]; return s; }  
  for (j = 0 ... n/2-1)  
    x[j] = a[2*j]  $\ominus$  a[2*j+1];  
  y = Scan(x, n/2);  
  for odd j in {0 ... n-1}  
    s[j] = y[j/2];  
  for even j in {0 ... n-1}  
    s[j] = y[j/2]  $\ominus$  a[j];  
  return s;
```

$$\begin{aligned} W(n) &= 1 + n/2 + W(n/2) + n/2 + n/2 + 1 \\ &= 2 + 3n/2 + W(n/2) \end{aligned}$$

$$S(n) = 1 + 1 + S(n/2) + 1 + 1 = S(n/2) + 4$$

Solving, $W(n) = O(n)$; $S(n) = O(\log n)$

Brent's Scheduling Principle

- A parallel algorithm with step complexity $S(n)$ and work complexity $W(n)$ can be simulated on a p -processor PRAM in no more than $T_c(n,p) = W(n)/p + S(n)$ parallel steps
 - $S(n)$ could be thought of as the length of the "critical path"
- Some schedule exists; need some online algorithm for dynamically allocating different numbers of processors at different steps of the program
- No need to give the actual schedule; just design a parallel algorithm and give its $W(n)$ and $S(n)$ complexity measures
- Goals:
 - Design algorithms with $W(n) = T_s(n)$, running time of sequential algorithm
 - Such algorithms are called work-efficient algorithms
 - Also make sure that $S(n) = \text{poly-log}(n)$
 - Speedup = $T_s(n) / T_c(n,p)$

Application of Brent's Schedule to Scan

- Scan complexity measures:
 - $W(n) = O(n)$
 - $S(n) = O(\log n)$
- $T_c(n,p) = W(n)/p + S(n)$
- If p equals 1:
 - $T_c(n,p) = O(n) + O(\log n) = O(n)$
 - Speedup = $T_s(n) / T_c(n,p) = 1$
- If p equals $n/\log(n)$:
 - $T_c(n,p) = O(\log n)$
 - Speedup = $T_s(n) / T_c(n,p) = n/\log n$
- If p equals n :
 - $T_c(n,p) = O(\log n)$
 - Speedup = $n/\log n$
- Scalable up to $n/\log(n)$ processors

Segmented Operations

Inputs = Ordered Pairs
(operand, boolean)
e.g. (x, T) or (x, F)

**Change of
segment indicated
by switching T/F**

$+_2$	(y, T)	(y, F)
(x, T)	(x+y, T)	(y, F)
(x, F)	(y, T)	(x⊕y, F)

e. g.	1	2	3	4	5	6	7	8
	T	T	F	F	F	T	F	T
Result	1	3	3	7	12	6	7	8

Parallel prefix on a list

- A prefix computation is defined as:
 - Input: $\langle x_1, x_2, \dots, x_n \rangle$
 - Binary associative operation \otimes
 - Output: $\langle y_1, y_2, \dots, y_n \rangle$
 - Such that:
 - $y_1 = x_1$
 - $y_k = y_{k-1} \otimes x_k$ for $k = 2, 3, \dots, n$, i.e. $y_k = \otimes x_1 \otimes x_2 \dots \otimes x_k$.
 - Suppose $\langle x_1, x_2, \dots, x_n \rangle$ are stored orderly in a list.
 - Define notation: $[i, j] = x_i \otimes x_{i+1} \dots \otimes x_j$

Prefix computation

- LIST-PREFIX(L)
 1. **for** each processor i , in parallel
 2. **do** $y[i] \leftarrow x[i]$
 3. **while** there exists an object i such that $\text{prev}[i] \neq \text{nil}$
 4. **do for** each processor i , in parallel
 5. **do if** $\text{prev}[i] \neq \text{nil}$
 6. **then** $y[\text{prev}[i]] \leftarrow y[i] \otimes y[\text{prev}[i]]$
 7. $\text{prev}[i] \leftarrow \text{prev}[\text{prev}[i]]$

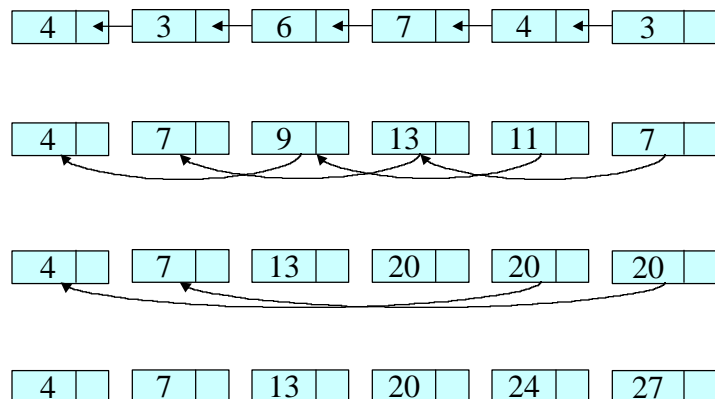
List Prefix Operations

- What is $S(n)$?
- What is $W(n)$?
- What is speedup on $n/\log n$ processors?

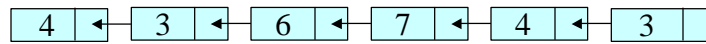
Announcements

- Readings:
 - Lecture notes from Sid Chatterjee and Jans Prins
 - Prefix scan applications paper by Guy Blelloch
 - Lecture notes from Ranade (for list ranking algorithms)
- Homework:
 - First theory homework will be on website tonight
 - To be done individually
- TA office hours will be posted on the website soon

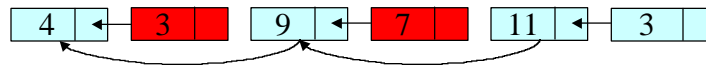
List Prefix



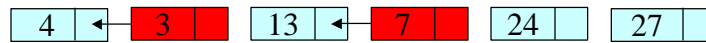
Optimizing List Prefix



Eliminate some elements:



Perform list prefix on remainder:



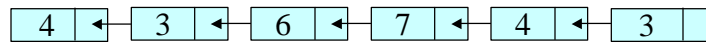
Integrate eliminated elements:



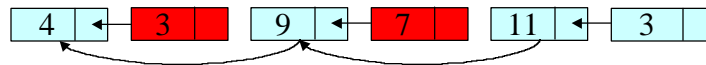
Optimizing List Prefix

- Randomized algorithm:
 - Goal: achieve $W(n) = O(n)$
- Sketch of algorithm:
 1. Select a set of list elements that are non adjacent
 2. Eliminate the selected elements from the list
 3. Repeat steps 1 and 2 until only one element remains
 4. Fill in values for the elements eliminated in preceding steps in the reverse order of their elimination

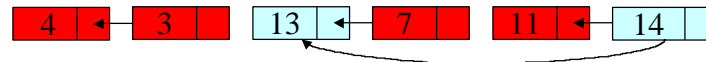
Optimizing List Prefix



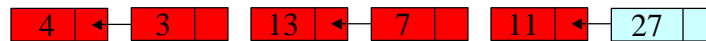
Eliminate #1:



Eliminate #2:



Eliminate #3:



Randomized List Ranking

- Elimination step:
 - Each processor is assigned $O(\log n)$ elements
 - Processor j is assigned elements $j \cdot \log n \dots (j+1) \cdot \log n - 1$
 - Each processor marks the head of its queue as a candidate
 - Each processor flips a coin and stores the result along with the candidate
 - A candidate is eliminated if its coin is a HEAD and if it so happens that the previous element is not a TAIL or was not a candidate

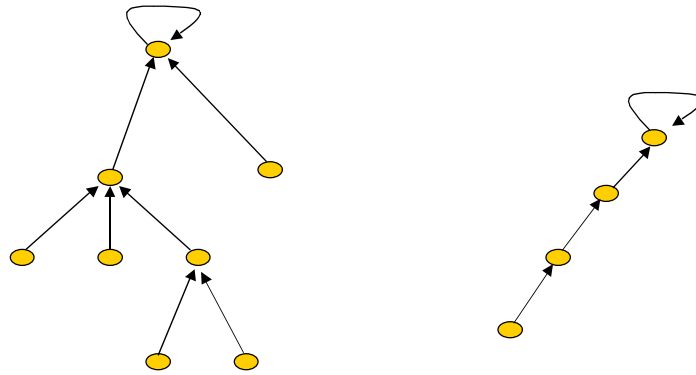
Find root –CREW algorithm

- Suppose a forest of binary trees, each node i has a pointer $parent[i]$.
- Find the identity of the tree of each node.
- Assume that each node is associated a processor.
- Assume that each node i has a field $root[i]$.

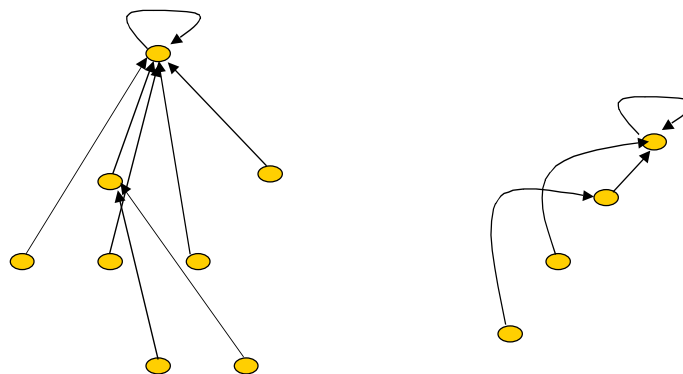
Find-roots –CREW algorithm

- FIND-ROOTS(F)
 1. **for** each processor i , in parallel
 2. **do if** $parent[i] = nil$
 3. **then** $root[i] \leftarrow i$
 4. **while** there exist a node i such that $parent[i] \neq nil$
 5. **do for** each processor i , in parallel
 6. **do if** $parent[i] \neq nil$
 7. **then** $root[i] \leftarrow root[parent[i]]$
 8. $parent[i] \leftarrow parent[parent[i]]$

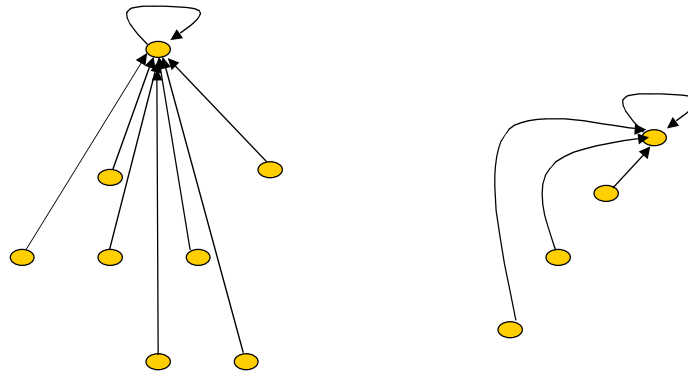
Pointer Jumping Example



Pointer Jumping Example



Pointer Jumping Example



Analysis

- Complexity measures:
 - What is $W(n)$?
 - What is $S(n)$?
- Termination detection: When do we stop?
- All the writes are exclusive
- But the read in line 7 is concurrent, since several nodes may have same node as parent.

Find roots –CREW vs. EREW

- How fast can n nodes in a forest determine their roots using only exclusive read? $\Omega(\lg n)$

Argument: when exclusive read, a given piece of information can only be copied to **one** other memory location in each step, thus the number of locations containing a given piece of information at most doubles at each step. Looking at a forest with one tree of n nodes, the root identity is stored in one place initially. After the first step, it is stored in at most two places; after the second step, it is stored in at most four places, ..., so need **$\lg n$** steps for it to be stored at n places.

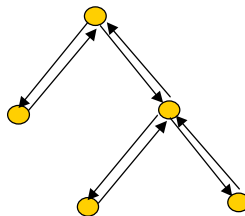
So CREW: $O(\lg d)$ and EREW: $\Omega(\lg n)$.

If $d=2^{o(\lg n)}$, CREW outperforms any EREW algorithm.

If $d=\Theta(\lg n)$, then CREW runs in $O(\lg \lg n)$, and EREW is much slower.

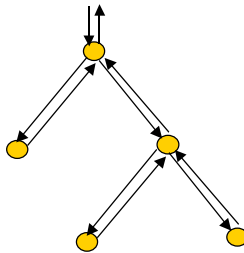
Euler Tours

- Technique for fast processing of tree data
- Euler circuit of directed graph:
 - Directed cycle that traverses each edge exactly once
- Represent tree by Euler circuit of its directed version



Using Euler Tours

- Trees = balanced parentheses
 - Parentheses subsequence corresponding to a subtree is balanced

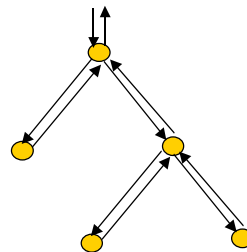


Parenthesis version: **((()((()))**

Depth of tree vertices

- Input:
 - $L[i]$ = position of incoming edge into i in euler tour
 - $R[i]$ = position of outgoing edge from i in euler tour

```
forall i in 1..n {
    A[L[i]] = 1;
    A[R[i]] = -1;
}
B = EXCL-SCAN(A, "+");
forall i in 1..n
    Depth[i] = B[L[i]];
```



Parenthesis version: **(() (() ()))**
 Scan input: **1 1 -1 1 1 -1 1 -1 -1 -1**
 Scan output: **0 1 2 1 2 3 2 3 2 1**

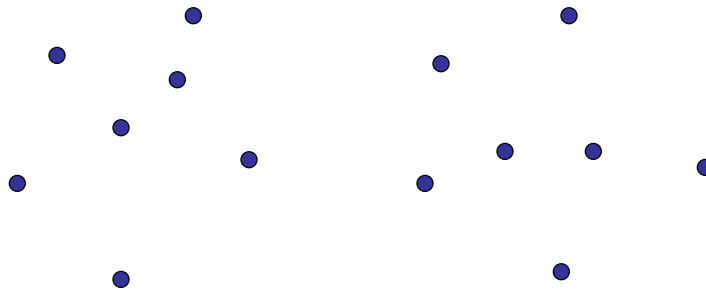
Divide and Conquer

- Just as in sequential algorithms
 - Divide problems into sub-problems
 - Solve sub-problems recursively
 - Combine sub-solutions to produce solution
- Example: planar convex hull
 - Give set of points sorted by x-coord
 - Find the smallest convex polygon that contains the points

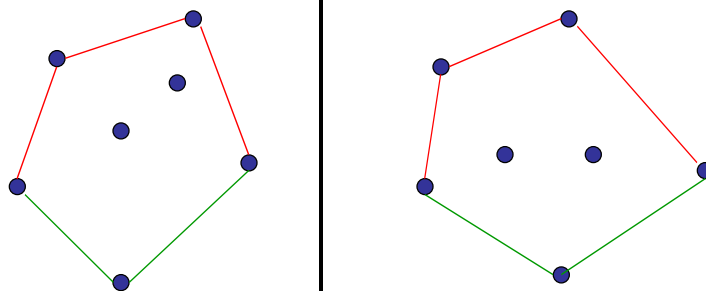
Convex Hull

- Overall approach:
 - Take the set of points and divide the set into two halves
 - Assume that recursive call computes the convex hull of the two halves
 - Conquer stage: take the two convex hulls and merge it to obtain the convex hull for the entire set
- Complexity:
 - $W(n) = 2 * W(n/2) + \text{merge_cost}$
 - $S(n) = S(n/2) + \text{merge_cost}$
 - If merge_cost is $O(\log n)$, then $S(n)$ is $O(\log^2 n)$
 - Merge can be sequential, parallelism comes from the recursive subtasks

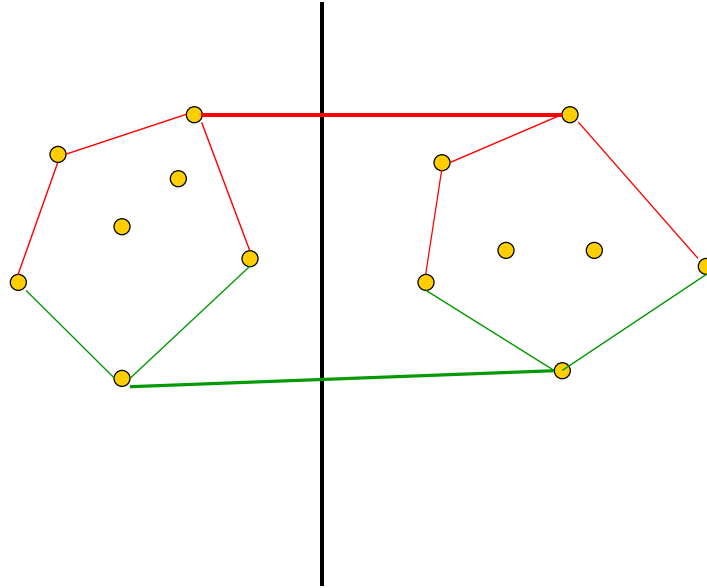
Complex Hull Example



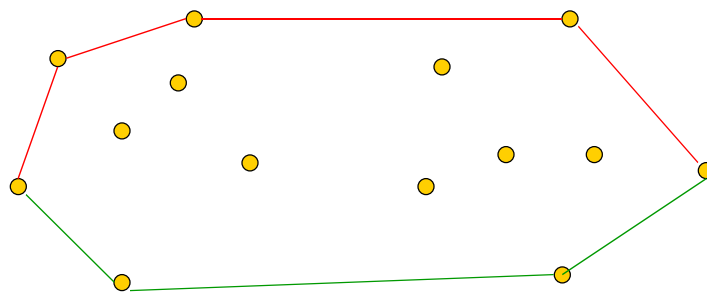
Complex Hull Example



Complex Hull Example



Complex Hull Example



Merge Operation

- Challenge:
 - Finding the upper and lower common tangents
 - Simple algorithm takes $O(n)$
 - We need a better algorithm
- Insight:
 - Resort to binary search
 - Consider the simpler problem of finding a tangent from a point to a polygon
 - Extend this to tangents from a polygon to another polygon
 - More details in Preparata and Shamos book on Computational Geometry (Lemma 3.1)