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1. Social Planner's problem.

$$\max_{\substack{C_1, C_2, \\ l_1, l_2, \\ k'}} \left\{ (C_1^{0.5} C_2^{0.3} - \frac{l^2}{2})^2 + 0.96 \times V(z', A', k') \right\} = V(z, A, k)$$

$$\text{s.t. } C_1 + k' = e^z k^{0.33} l_1^{0.67} + 0.9k$$

$$C_2 = A l_2$$

$$l = l_1 + l_2$$

2. Steady state. - Solved by FOC of the Bellman Equation.

In the deterministic state where $z=0$ and $A=1$,

$$V(k) = \max_{l_1, l_2, k'} \left\{ (k^{0.33} l_1^{0.67} + 0.9k - k')^{0.5} l_2^{0.5} - \frac{(l_1 + l_2)^2}{2} + 0.96 V(k') \right\}$$

$$\text{F.o.c } [l_1] \quad l_1 + l_2 = 0.5 \times 0.67 \times l_2^{0.5} \times k^{0.33} \times l_1^{-0.33} \times (k^{0.33} l_1^{0.67} + 0.9k - k')^{-0.5}$$

$$[l_2] \quad l_1 + l_2 = 0.5 \times l_2^{-0.5} \times (k^{0.33} l_1^{0.67} + 0.9k - k')^{0.5}$$

$$[k'] \quad 1 = 0.96 \times (0.9 + l_1^{0.67} \cdot 0.33 k^{-0.67})$$

ET

$$k = k' = k''$$

By Fsolve of Matlab, we get

$$k_{ss} = 0.83$$

$$l_{1,ss} = 0.23$$

$$l_{2,ss} = 0.27$$

$$C_{1,ss} = 0.27$$

$$C_{2,ss} = 0.27$$

$$V_{ss} = 0.14$$