Iterative Hessian Sketch for Constrained Least-Squares

Lydia Hsu, Shuaiwen Wang

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• Consider the constrained least-squares

$$x_{ls} := \arg\min_{x \in C} \frac{1}{2} ||Ax - y||_2^2$$

where C: constraint; $A \in \mathbb{R}^{n \times p}$: design matrix; y: response.

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- ullet $S \in \mathbb{R}^{m imes n}$: sketching matrix; $\mathbb{E} S^{ op} S = I_n$.

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- random row sampling: randomly select m rows from I_n (rescaled by $\sqrt{\frac{n}{m}}$);
- randomized orthogonal system: randomly select m rows from an orthogonal matrix H (rescaled by $\sqrt{\frac{n}{m}}$);

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• We expect the optimal method satisfies $m \approx O(p)$ Think about this part more carefully?;

Hessian Sketch

• Only sketch *A*, but not *y*:

$$x_{hs} := \arg\min_{x \in C} \frac{1}{2} \|SAx\|_2^2 - \langle A^\top y, x \rangle.$$

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Iterative Hessian Sketch

- Idea: construct a new least-squares problem for which the optimal solution is $x^{LS}-x^t$. Then applying HS to the problem will produce a new x^{t+1} whose distance to x^{LS} has been reduced by a factor of ρ .
- $\hat{u} := \operatorname{argmin}_{u \in \{C x^t\}} \{\frac{1}{2} ||Au||_2^2 \langle A^T (y Ax^t), u \rangle \}.$ By construction, $\hat{u} = x^{LS} - x^t$.
- Advantages: sample size efficiency and computational time saving

Iterative Hessian Sketch Algorithm

Algorithm

- Initialize $x^0 = 0$.
- ② For iterations t = 0, 1, 2, ...N 1, generate independent sketches $S^{t+1} \in \mathbb{R}^{m \times n}$, and perform the updates $x^{t+1} = argmin_{x \in C} \{\frac{1}{2m} \|S^{t+1}A(x-x^t)\|_2^2 \langle A^T(y-Ax^t), x \rangle \}.$
- **3** Return $\hat{x} = x^N$.

References



Sarlos (2006)

Title of the publication

Journal Name 12(3), 45 - 678.

Evaluation for Sketch Performance

Cost Approximation

In terms of f-cost, the approximated \tilde{x} is said to be ϵ -optimal if

$$f(x^{LS}) \le f(\tilde{x}) \le (1+\epsilon)^2 f(x^{LS}).$$

Solution Approximation

In terms of f-cost, the prediction norm defined as

$$\|\tilde{x} - x^{LS}\|_A := \frac{1}{\sqrt{n}} \|A(\tilde{x} - x^{LS})\|_2.$$

Thank you!