

Yen-Jen Wang

wangyenjen.github.io

wangyenjen@berkeley.edu

Phone number: +1 6174338923

Education

- ❖ **University of California, Berkeley, CA**
- Doctor of Philosophy August 2024 - June 2028 (Expected)
- Major: in Robotics and Control (Affiliated with BAIR and ME)
- Advisor: Koushil Sreenath
- ❖ **Tsinghua University, Beijing, China**
- Master of Science August 2021 - June 2024
- Major: in Robotics and AI (Affiliated with IIIS 交叉信息研究院) GPA: 3.94 / 4.0
- Advisor: Jianyu Chen
- Outstanding graduates of IIIS, Tsinghua University (**top 1 master's student**)
- ❖ **National Taiwan University, Taipei, Taiwan**
- Bachelor of Science September 2017 – January 2021
- Major: in Computer Science (Affiliated with CSIE) GPA: 3.83 / 4.3
- **Guaranteed admission** due to the Olympiad in Informatics in 2015 (as a high school freshman).

Selected Awards and Honors

- ❖ **5th Place**, International Collegiate Programming Contest (ICPC) World Finals, Porto, Portugal April 2019
- From among 135 teams of three chosen from a field of 52,709 contestants from 3,233 universities in 110 countries on six continents (Source: [ICPC Official Website](#)).
- ❖ **Silver Medal**, International Olympiad in Informatics (IOI), Tehran, Iran July 2017
- ❖ **Grand Prize Winner**, International Genetically Engineered Machine (iGEM), Boston, MA, USA October 2016

Publications (*: Equal contribution. Co-first Author)

- ❖ Xinyang Gu*, **Yen-Jen Wang***, Xiang Zhu*, Chengming Shi*, Yanjiang Guo, Yichen Liu, Jianyu Chen. “Advancing Humanoid Locomotion: Mastering Challenging Terrains with Denoising World Model Learning”, In *2024 Robotics: Science and Systems (RSS 2024)* (**Outstanding Paper Award Finalists**)
- ❖ Xinyang Gu*, **Yen-Jen Wang***, Jianyu Chen. “Humanoid-Gym: Reinforcement Learning for Humanoid Robot with Zero-Shot Sim2Real Transfer”, In ICRA 2024 Workshop on Agile Robotics.
- ❖ **Yen-Jen Wang**, Bike Zhang, Jianyu Chen, Koushil Sreenath. “Prompt a Robot to Walk with Large Language Models”, *Preprint, arXiv 2309.09969*
- ❖ Yanjiang Guo*, **Yen-Jen Wang***, Lihan Zha*, Zheyuan Jiang, Jianyu Chen. “DoReMi: Grounding Language Model by Detecting and Recovering from Plan-Execution Misalignment”, In *2024 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS 2024)* (**Oral**)
- ❖ Yanjiang Guo*, Zheyuan Jiang*, **Yen-Jen Wang**, Jingyue Gao, and Jianyu Chen. “Distributed Motor Skill Learning for Complex Robotic Systems”, In *2023 IEEE Robotics and Automation Letters (RA-L)*

Research Experience

- ❖ **Hybrid Robotics, University of California, Berkeley, Berkeley, CA** July 2023 – Present
- **Prompt a Robot to Walk with Large Language Models**: Using LLM directly outputs the low-level action to make a robot walk.
- **Point-goal Navigation for Quadrupedal Robots**: AI Habitat was utilized for training navigation, while legged_gym served for locomotion training. Our goal is to explore the mutual influence between the two aspects.
- ❖ **Institute for Interdisciplinary Information Sciences, Tsinghua University, Beijing, China** September 2021 – Present
- **Locomotion for Humanoid Robot**: Train an RL policy for XBot-S and XBot-L from Robot Era and address the sim-to-real transfer problem.
- **Grounding Language Model by Detecting and Recovering from Plan-Execution Misalignment**: Use LLMs to detect exceptions and re-plan in real-time. This dual-role approach, where LLMs assist in high-level planning and generating constraints that can indicate misalignment during execution.
- **Pour Water Task on A Mobile Manipulator**: 1. Use ROS to control the mobile manipulator to complete the pouring task. 2. Use more accurate observation as a teaching model to train students using image input.

Selected Professional Experience

- ❖ **Google LLC** July 2021 – October 2021
- Software Engineer Intern @ Android Core Networking Team, working with staff from Taiwan and Japan offices.
- ❖ **Pony.ai** July 2019 – August 2019
- Software Engineer Intern @ Planning and Control Team, working with staff from China and US offices.
- ❖ **Tsinghua University, Beijing, China**
- Problem Setter of the Undergraduate Recommended Admissions in CS department. January 2022 – August 2022
- ❖ **National Taiwan University, Taipei, Taiwan**
- Co-coach of the International Collegiate Programming Contest (ICPC) training course, which is instructed by Professors Chiou-Shann Fuh and Pu-Jen Cheng. August 2019 – January 2021
- ❖ **Taiwan Olympiad in Informatics**
- Co-coach of the Taiwan team in the International Olympiad in Informatics. March 2018 - July 2021