Yen-Jen Wang

Nationality: **Taiwan (R.O.C.)** wangvenien.github.io wangvenien0301@gmail.com Phone number: +1 6174338923

Education

❖ Institute for Interdisciplinary Information Sciences (IIIS), Tsinghua University, Beijing, China

- Master of Science August 2021 - June 2024 (expected)

- Major. in Computer Science GPA: 3.952 / 4.0

Department of Computer Science and Information Engineering (CSIE), National Taiwan University, Taipei, Taiwan

- Bachelor of Science September 2017 – January 2021

- Major. in Computer Science and Information Engineering

GPA: 3.83 / 4.3

- Guaranteed admission due to the Olympiad in Informatics in 2015 (as a high school freshman).

Selected Awards and Honors

5th Place, International Collegiate Programming Contest (ICPC) WorldFinals, Porto, Portugal

 From among 135 teams of three chosen from a field of 52,709 contestants from 3,233 universities in 110 countries on six continents (Source: ICPC Official Website).

❖ Silver Medal, International Olympiad in Informatics (IOI), Tehran, Iran

July 2017

❖ Grand Prize Winner, International Genetically Engineered Machine (iGEM), Boston, MA, USA October 2016

Publications (*: Equal contribution. Listed alphabetically.)

- ❖ Yen-Jen Wang, Bike Zhang, Jianyu Chen, Koushil Sreenath. "Prompt a Robot to Walk with Large Language Models", *Preprint*, arXiv 2309.09969
- ❖ Yen-Jen Wang, Xiaoyu Chen, Hai Zhong, Yanjiang Guo, and Jianyu Chen. "Reinforcement Learning with Partial Order Representation for Monotonic Physical System", *Under Review*
- ❖ Yanjiang Guo*, **Yen-Jen Wang***, Lihan Zha*, Zheyuan Jiang, Jianyu Chen. "DoReMi: Grounding Language Model by Detecting and Recovering from Plan-Execution Misalignment", *Preprint, arXiv* 2307.00329
- ❖ Yanjiang Guo*, Zheyuan Jiang*, **Yen-Jen Wang**, Jingyue Gao, and Jianyu Chen. "Distributed Motor Skill Learning for Complex Robotic Systems", In *2023 IEEE Robotics and Automation Letters (RA-L)*

Research Experience

Hybrid Robotics, University of California, Berkeley, Berkeley, CA

July 2023 – Present

- **Prompt a Robot to Walk with Large Language Models**: Using LLM directly outputs the low-level action to make a robot walk.
- **Point-goal Navigation for Quadrupedal Robots**: AI Habitat was used to train navigation, and legged_gym was used to train sports. Our goal is to explore the mutual influence between the two.
- Institute for Interdisciplinary Information Sciences, Tsinghua University, Beijing, China September 2021 Present
 Locomotion for Humanoid Robot: Train an RL policy for our custom humanoid robot to address the sim-to-real transfer problem.
 - **Reinforcement Learning with Partial Order Representation**: Improve the sample efficiency of reinforcement learning by capturing monotonically changing physical quantities in the environment.
 - Grounding Language Model by Detecting and Recovering from Plan-Execution Misalignment: Use LLMs to detect exceptions and re-plan in real-time. This dual-role approach, where LLMs assist in high-level planning and generating constraints that can indicate misalignment during execution.
 - **Pour Water Task on A Mobile Manipulator**: 1. Use ROS to control the mobile manipulator to complete the pouring task. 2. Use more accurate observation as a teaching model to train students using image input.

Selected Professional Experience

❖ Google LLC

July 2021 – October 2021

- Software Engineer Intern @ Android Core Networking Team, working with staff from Taiwan and Japan offices.
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July 2019 – August 2019

- Software Engineer Intern @ Planning and Control Team, working with staff from China and US offices.

❖ Tsinghua University, Beijing, China

- Teaching Assistant in Advanced Topics in Robotics with Professor. Jianyu Chen.

Spring 2023

- Director of the Organization Department of the Taiwan Students Association September 2022 March 2023
- Problem Setter of the Recommended Admissions Committee in the CS department. January 2022 August 2022

❖ National Taiwan University, Taipei, Taiwan

- Co-coach of the International Collegiate Programming Contest (ICPC) training course, which is instructed by Professors Chiou-Shann Fuh and Pu-Jen Cheng.

 August 2019 January 2021
- The president of the Academic Association in the CS department.

May 2019 – May 2020

- Mail service maintainer in the CS department.

August 2018 – January 2021

- Coordinator @ <u>IOICamp</u>: A training camp for prospective high school and college students participating in Olympiads in Informatics and other programming competitions. *June 2018 – January 2020*

***** Taiwan Olympiad in Informatics

- Co-coach of the Taiwan team in the International Olympiad in Informatics.

March 2018 - July 2021

Standard Language Tests

❖ TOEFL: 107 (Reading: 30, Listening: 30, Speaking: 20, Writing: 27)