Multi model fusion for pedestrian trajectory prediction

1 Team details

• Challenge track: Trajectory Forecasting
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2 Abstract

Pedestrian trajectory prediction usually requires a large amount of data for model training. The quality and quantity of data have a significant impact on the prediction results. Data collection can be carried out in various ways, such as using cameras, radar, LIDAR, and other sensors. In this challenge, we fused multiple models on the JRDB dataset and obtained prediction results. The main methods used are NSP-SFM.