

# Stochastic Galerkin Method

Yikai Wang

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## 1 DEFINITION IN SINGLE RANDOM VARIABLES

Let  $z$  be a random variable with a distribution function  $F(z) = P(z \leq Z)$ , The generalized polynomial chaos basis functions are the orthogonal polynomial functions satisfying

$$\mathbf{E}[\Phi_m(z)\Phi_n(z)] = \gamma_n \delta_{nm}$$

where

$$\gamma_n = \mathbf{E}[\Phi_n^2(z)]$$

are the normalization factors.

If  $z$  is continuous, then its probability density function (PDF) exists such that  $dF(z) = \rho(z)dz$  and the orthogonality can be written as

$$\mathbf{E}[\Phi_m(z)\Phi_n(z)] = \int \Phi_m(z)\Phi_n(z)\rho(z)dz = \gamma_n \delta_{nm}$$

Similarly, when  $z$  is discrete, the orthogonality can be written as

$$\mathbf{E}[\Phi_m(z)\Phi_n(z)] = \sum_i \Phi_m(z_i)\Phi_n(z_i)\rho_i$$

### 1.1 Hermite polynomial chaos

Let  $z$  is a standard Gaussian random variable with zero mean and unit variance. Its PDF is

$$\rho(z) = \frac{1}{\sqrt{2\pi}} e^{-z^2/2}$$

we employ the Hermite polynomials as the basis functions,

$$H_0(z) = 1, H_1(z) = z, H_2(z) = z^2 - 1, H_3(z) = z^3 - 3z$$

This is the classical Wiener-Hermite polynomial chaos basis.

### 1.2 Legendre polynomial chaos

## 2 General Procedure

### 2.1 Stochastic diffusion equation

$$-\nabla \cdot (a(\omega, x) \nabla u(\omega, x)) = f(\omega, x) \quad (\omega, x) \in \Omega \times D$$

$$u(\omega, x) = 0 \quad x \in \partial D$$

### 2.2 Tensor Product

$$(f \otimes g)(x, y) = f(x)g(y)$$

$$((A \otimes B)_{i_1 j_1})_{i_2 j_2} = A_{i_1 j_1} B_{i_2 j_2}$$

## 2.3 Solution

$$\mathbf{E}[\int_D a \nabla u \nabla v dx] = E[\int_D f v dx]$$

$$v(x) = \sum_{i=1}^N V_i \phi_i(x)$$

$$\int_D a \nabla (\sum_{i=1}^N U_i \phi_i(x)) \cdot \nabla \phi_j dx = \int_D f \phi_j dx$$

$$\sum_{i=1}^N U_i \int_D a \nabla \phi_i \cdot \nabla \phi_j dx = \int_D f \phi_j dx$$

$$KU = F$$

$$a(\omega, x) = \bar{a} + \sum_{l=1}^{\infty} \varphi_l(x) y_l(\omega)$$

where the function  $\varphi_l(x)$  are determined by the eigenvalues and eigenfunctions of the covariance function of  $a(\omega, x)$ , and  $y_l(\omega)$  are mutually independent.

$$u(\omega, x) = \sum_{n=1}^Q \sum_{i=1}^N (U_n)_i \psi_n(\omega) \phi_i(x)$$

$$\mathbf{E}[\int_D a \nabla \sum_{i=1}^N \sum_{n=1}^Q (U_n)_i \psi_n \phi_i \cdot \nabla \psi_m \phi_j dx] = \mathbf{E}[\int_D f \psi_m \phi_j dx]$$

$$\sum_{i=1}^N \sum_{n=1}^Q (U_n)_i \mathbf{E}[\int_D a \nabla \psi_n \phi_i \cdot \nabla \psi_m \phi_j dx] = \mathbf{E}[\int_D f \psi_m \phi_j dx]$$

$$\sum_{i=1}^N \sum_{n=1}^Q (U_n)_i \mathbf{E}[\psi_n \psi_m \int_D a \nabla \phi_i \cdot \nabla \phi_j dx] = \mathbf{E}[\psi_m \int_D f \phi_j dx]$$

$$a(\omega, x) = \sum_{l=0}^S a_l(x) y_l(\omega)$$

$$\sum_{l=0}^S \sum_{i=1}^N \sum_{n=1}^Q (U_n)_i \mathbf{E}[y_l \psi_n \psi_m \int_D a_l \nabla \phi_i \cdot \nabla \phi_j dx] = \mathbf{E}[\psi_m \int_D f \phi_j dx]$$

$$\sum_{l=0}^S \sum_{i=1}^N \sum_{n=1}^Q (U_n)_i \mathbf{E}[y_l \psi_n \psi_m] \int_D a_l \nabla \phi_i \cdot \nabla \phi_j dx = \mathbf{E}[\psi_m \int_D f \phi_j dx]$$

$\mathbf{E}[y_l \psi_n \psi_m]$  can be evaluated prior to any computations.

$$\sum_{l=0}^S \sum_{i=1}^N \sum_{n=1}^Q (U_n)_i (G_l)_{nm} (K_l)_{ij} = (F_m)_j$$

$$\sum_{l=0}^S \sum_{i=1}^N \sum_{n=1}^Q (U_n)_i ((G_l \otimes K_l)_{nm})_{ij} = (F_m)_j$$

$$\sum_{l=0}^S (G_l \otimes K_l) U = F$$