To be prepared for the exercises on $\underline{\text{Nov } 27, 2019}$ (10 points total)

Task 1 (5 points)

A satellite moves in an elliptical orbit, which can be described by 6 Keplerian Elements. For any particular epoch t in this case, Cartesian coordinates $r_i(t)$ and velocities $v_i(t)$ can be computed by the transformation (kep2cart). Suppose a communication satellite has the following orbital elements: semi-major axis = 2,6371 km, eccentricity = 0.4, inclination = 45°, argument of perigee = 110° and right ascension of the ascending node = 50°. Your task is now to:

- a) compute its positions and velocities for 1 day (sampling rate $\Delta t = 10\,s$) and plot its orbit and velocity components. (Hint: $t_0 = 0\,s$ and $M_0 = 0^\circ$)
- b) write another MATLAB function cart2kep to convert the Cartesian coordinates and velocities computed in (a) into five Keplerian Elements $(a, e, I, \Omega, \omega)$.
- c) transform the satellite orbit into the ECEF coordinate system by using this simplified formula:

 $r_e = R_3(\theta_{gr})r_i$, with Greenwich Apparent Sidereal Time $\theta_{gr} = \omega_E t$ and plot the orbit in the system r_e .

d) plot the Keplerian orbits for 1 day (sampling rate $\Delta t = 30 \, s$) of the GNSS satellites: GPS, Galileo and GLONASS. Their orbit informations are provided at GPS.txt, Galileo.txt and GLONASS.txt in ILIAS. The GNSS constellation is summarized below:

	GLONASS	GPS	Galileo
number of satellites	24	24	27
number of orbits	3	6	3
inclination	64.8°	55°	56°
semi-major axis [km]	25400	26500	29600

Task 2 (5 points)

The folder on ILIAS contains two Matlab scripts as well as one so-called RINEX NAV file (test.18n), which provides the orbital elements at a particular epoch for all GPS satellites in view. Please use the script main.m to load this information in Matlab and have a look at the orbital elements for different satellites (you can access the information of satellite XX via the struct SV(XX).navData). Your task is now to

- a) compute the distance (in meters) between GPS satellites 14 and 18 for GPS week number (WN) 2016 and time of the week (TOW) 561600 s.
- b) compute the WGS84 position and the velocity vector of GPS satellite 10 at epoch $t_0 = (WN 2016, TOW 564600)$.
- c) compute the WGS84 position of GPS satellite 10 at epoch $t_1 = t_0 1$ s.
- d) compute the WGS84 position of GPS satellite 10 at epoch $t_2 = t_0 + 1$ s.
- e) compute the velocity of satellite 10 at epoch numerically by

$$v = \frac{\boldsymbol{x}(t_2) - \boldsymbol{x}(t_1)}{2.0}$$

with the positions computed in (c) and (d) and compare to the result obtained in (b).