An HPF Compiler for the IBM SP

The SPMDizer of the IBM product HPF compiler

HPF -- High Performance Fortran

- HPF was a parallel Fortran Dialect whose development was spearheaded by Mehrotra (NASA Langley), Zima and Chapman (Vienna), Kennedy (Rice) and Fox (Syracuse, now at IU)
- Was the hot language in the early/mid 1990s
- DEC, PGI and IBM were major commercial implementations

Motivation

- Distributed memory was the programming model of the 90s
 - attack of the killer micros
 - scaling to large number of processors
- Shared memory automatic parallelization was recognized as very hard
- Data distribution added to this complexity

Make the programmer handle distribution

- Let the programmer handle the distribution of data
 - templates
 - logical processor grids
 - distributions of arrays onto templates and processor grids
- Remainder of the program can be written in an sequential Fortran 90 style

Let the compiler handle parallelization and communication

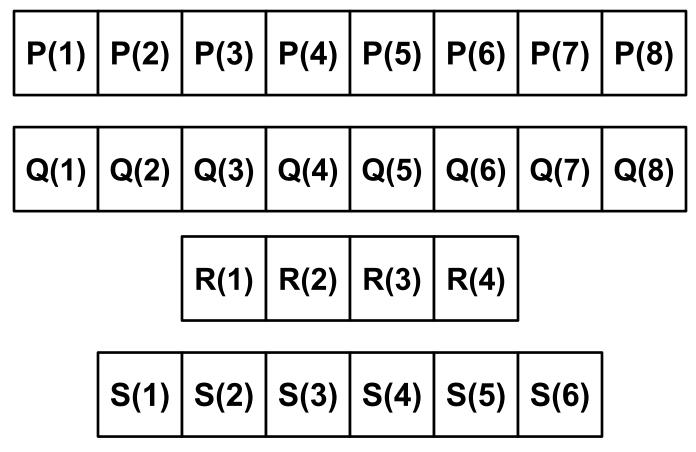
- Driven by data distribution
- Computation scheduled by having processors compute values of data that is distributed onto them (i.e. that they own)
- Communication is determined by what needs to be communicated to computed owned values
- Loops needing no communication inside the loop are parallel
- Ultimately, just as hard as shared memory autoparallelization

Processor grids

P(0,0)	P(0,1)	P(0,2)	P(0,3)
P(1,0)	P(1,1)	P(1,2)	P(1,3)
P(2,0)	P(2,1)	P(2,2)	P(2,3)
P(3,0)	P(3,1)	P(3,2)	P(3,3)

!HPF\$ PROCESSOR P(4,4)

Processor Grids



!HPF\$ PROCESSORS P(NUMBER OF PROCESSORS())

!HPF\$ PROCESSORS Q(8)

!HPF\$ PROCESSORS :: R(4), S(6)

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Distributing data onto processor grids

B(l,l)	B(1,2)		B(1,100)
B(2,1)	B(2,2)		(2,1 00)
B(100,1)	B(100,2)	··· I	8(100,100

P(0,0)	P(0,1)	P(0,2)	P(0,3)
P(1,0)	P(1,1)	P(1,2)	P(1,3)
P(2,0)	P(2,1)	P(2,2)	P(2,3)
P(3,0)	P(3,1)	P(3,2)	P(3,3)

integer B(100,100) !HPF\$ PROCESSOR P(4,4)

BLOCK DISTRIBUTED

P(0,0)	P(0,1)	P(0,2)	P(0,3)
			i dela del
B(1:25,1:25)	B(1:25,26:50)	B(1:25,51:75)	B(1:25,76:100)
P(1,0)	P(1,1)	P(1,2)	P(1,3)
B(26:50,1:25	B(26:50,26:50)) B(26:50,51:75) B(26:50,76:100)
B(O O)	7/0 11	B(a a)	B(0.3)
P(2,0)	P(2,1)	P(2,2)	P(2,3)
B(51:75,1:25)	B(51:75,26:50) B(51:75,51:75	B(51:75,76:100)
P(3,0)	P(3,1)	P(3,2)	P(3,3)
B(76:100,1:25)	B(76:100,26:50	B(76:100,51:75	B(76:100,76:100

integer B(100,100)
!HPF\$ DISTRIBUTED B(BLOCK,BLOCK)

BLOCK DISTRIBUTED

P(0,0)	P(0,1)	P(0,2)	P(0,3)
B(1:25,1:25)	B(1:25,26:50)	B(1:25,51:75)	B(1:25,76:100)
P(1,0)	P(1,1)	P(1,2)	P(1,3)
B(26:50,1:25	B(26:50,26:50) B(26:50,51:75) B(26:50,76:100)
P(2,0)	P(2,1)	P(2,2)	P(2,3)
B(51:75,1:25)	B(51:75,26:50) B(51:75,51:75	B(51:75,76:100)
P(3,0)	P(3,1)	P(3,2)	P(3,3)
B(76:100,1:25)	B(76:100,26:50)B(76:100,51:75	B(76:100,76:100)

integer B(100,100)
!HPF\$ PROCESSORS P(4,4)
!HPF\$ DISTRIBUTE B(BLOCK,BLOCK) ONTO P

Default processor grids

 If not processor grid is specified, then a linear grid with however many processors there are at runtime is specified (for a one-D array). Finding the actual processor grid size a challenge.

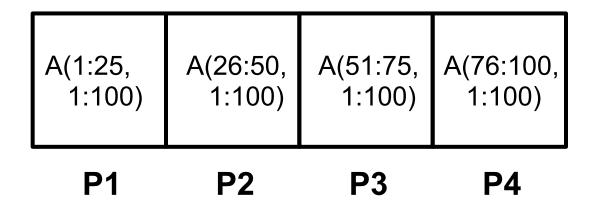
A(1:25)	A(26:50)	A(51:75)	A(76:100)

integer A(100)
!HPF\$ DISTRIBUTE A(BLOCK)

Distributions

- Each dimension can be distributed separately
- BLOCK, CYCLIC, BLOCK(k),
 REPLICATED ("*") all supported

Rank of processor grid smaller than the rank of array



FLOAT A(100,100)
!HPF\$ Processor P(4)
!DISTRIBUTE A(BLOCK,*) ONTO P

Rank of processor grid larger than rank of array

A(1:25)	A(26:50)	A(51:75)	A(76:100
A(1:25)	A(26:50)	A(51:75)	A(76:100
A(1:25)	A(26:50)	A(51:75)	A(76:100
A(1:25)	A(26:50)	A(51:75)	A(76:100

FLOAT A(100)
!HPF\$ Processor P(4,4)
!DISTRIBUTE A(BLOCK,*) ONTO P

ALIGNMENT

 Sometimes we want to distribute one array and align other arrays with it.

```
do i = 1, 50

a(2*i) = a(2*i) + b(i)

end do
```

```
!HPF$ PROCESSOR P(4)
!HPF$ DISTRIBUTE B(BLOCK) ONTO P(4)
!HPF$ ALIGN A(2*I) WITH B(I)
```

ALIGNMENT

```
do i = 1, 50

a(2*i) = a(2*i) + b(i)

end do
```

!HPF\$ PROCESSOR P(4)
!HPF\$ DISTRIBUTE A(BLOCK) ONTO P(4)
!HPF\$ ALIGN B(I) WITH A(2*I)

A(1:25) B(1:12) A(26:50) B(13:25)

A(51:75) B(26:37) A(76:100) B(38:50)

ALIGNMENT

```
do i = 1, 50

a(i) = a(i) + b(i-2)

end do
```

!HPF\$ PROCESSOR P(4)
!HPF\$ DISTRIBUTE A(BLOCK) ONTO P(4)
!HPF\$ ALIGN B(I) WITH A(i+2)

A(1:25) B(1:23) A(26:50)

B(24:48)

A(51:75)

B(49:73)

A(76:100) B(74:100)

Templates

- Templates can be thought of as virtual targets to align with, i.e. an array of nothing
- Templates, in turn, are distributed onto processor grids or aligned with other templates

TEMPLATE example

 Sometimes we want to distribute one array and align other arrays with it using a template

```
do i = 1, 50

a(i) = a(i) + b(i-2)

end do
```

```
!HPF$ PROCESSOR P(4)
!HPF$ TEMPLATE T(52)
!HPF$ ALIGN A(I) WITH T(I)
!HPF$ ALIGN B(I) WITH T(I+2)
!HPF$ DISTRIBUTE T(BLOCK) ONTO P
```

 Sometimes we want to distribute one array and align other arrays with it using a template.

```
do\ i=1,50 do\ j=1,50 a(i,j)=a(i,j)*\ b(j,i) end do end\ do !HPF\$\ PROCESSOR\ P(4,4) !HPF\$\ TEMPLATE\ T(50,50) !HPF\$\ ALIGN\ A(I,J)\ WITH\ T(I,J) !HPF\$\ ALIGN\ B(J,I)\ WITH\ T(J,I) !HPF\$\ DISTRIBUTE\ T(BLOCK,BLOCK)\ ONTO\ P_{20}
```

A numbering of blocks of an array block distributed.

This notation is used only to make it easier to type in the block names without worrying about specific elements of an array α in the block.

α1	α2	α3	α4
α5	α6	α7	α8
α9	α10	α11	α12
α13	α14	α15	α16

```
do i = 1, 50

do j = 1,50

a(i,j) = a(i,j) * b(j,i)

end do

end do
```

!HPF\$ PROCESSOR P(4,4) !HPF\$ TEMPLATE T(50,50)	a13	a
!HPF\$ ALIGN A(I,J) WITH T(I,J)		•
!HPF\$ ALIGN B(J,I) WITH T(J,I)		
!HPF\$ DISTRIBUTE T(BLOCK,BLOCK)	ONTO	P

a1	a2	a3	a4
a5	a6	a7	a8
a9	a10	a11	a12
a13	a14	a15	a16

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```
do i = 1, 50

do j = 1,50

a(i,j) = a(i,j) * b(j,i)

end do

end do
```

b1	b5	b9	b13
b2	b6	b10	b14
b3	b7	b11	b15
b4	b8	b12	b16

!HPF\$ PROCESSOR P(4,4)
!HPF\$ TEMPLATE T(50,50)
!HPF\$ ALIGN A(I,J) WITH T(I,J)
!HPF\$ ALIGN B(J,I) WITH T(J,I)

!HPF\$ DISTRIBUTE T(BLOCK, BLOCK) ONTO P

Template allows all arrays aligned with it to be distributed together.

!HPF\$ PROCESSOR P(4,4)

!HPF\$ TEMPLATE T(50,50)

!HPF\$ ALIGN A(I,J) WITH T(I,J)

!HPF\$ ALIGN B(J,I) WITH T(J,I)

!HPF\$ DISTRIBUTE T(BLOCK,BLOCK) ONTO P

a1	a2	a3	a4
b1	b5	b9	b13
a5	a6	a7	a8
b2	b6	b10	b11
a9	a10	a11	a12
b3	b7	b11	b15
a13	a14	a15	a16
b4	b8	b12	b16

Distribution functions

• Let α be an array, τ a template, π a processor grid, and various f_i be functions mapping elements of α onto whatever α is distributed onto/aligned with.

Distribution functions

• Let α , β be an array, τ a template, π a processor grid, and various f_i be functions mapping elements of α onto whatever α is distributed onto/aligned with.

```
!HPF$ ALIGN \alpha(i) WITH \beta(i+1) // i' = f_1(i+1) !HPF$ ALIGN \beta(i) WITH \tau(2*i) // i' = f_2(2*i) !HPF$ DISTRIBUTE \tau(\text{BLOCK}) // f_3 f_3(f_2(f_1(i))) is the distribution function
```

Distribution functions

```
!HPF$ ALIGN \alpha(i) WITH \beta(i+1) // f_1
\alpha(i) aligned with element \beta(i+1)
!HPF$ ALIGN \beta(i) WITH \tau(2*i) // f_2
\alpha(i) aligned with element \tau(2*(i+1))
Given by f_2(f_1(i))
!HPF$ DISTRIBUTE \tau(BLOCK) // f_3
Elements of \tau are block distributed onto the
default processor grid using the appropriate
formula f3
f_3(f_2(f_1(i))) is the final distribution function
```

Architecture of the Compiler

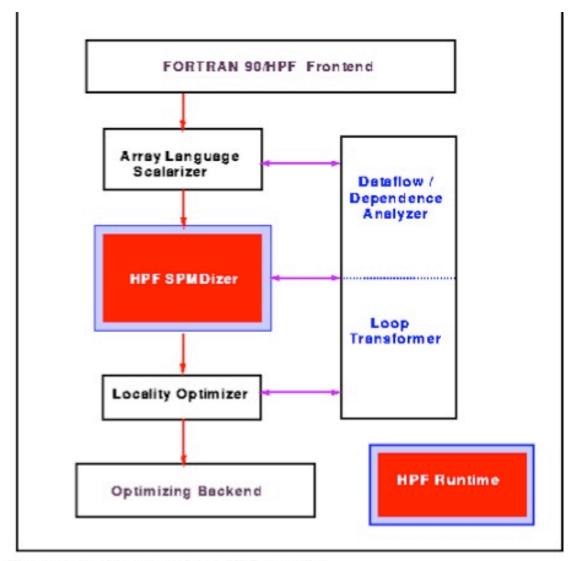


Figure 1: Architecture of the pHPF compiler

Architecture of the SPMDizer

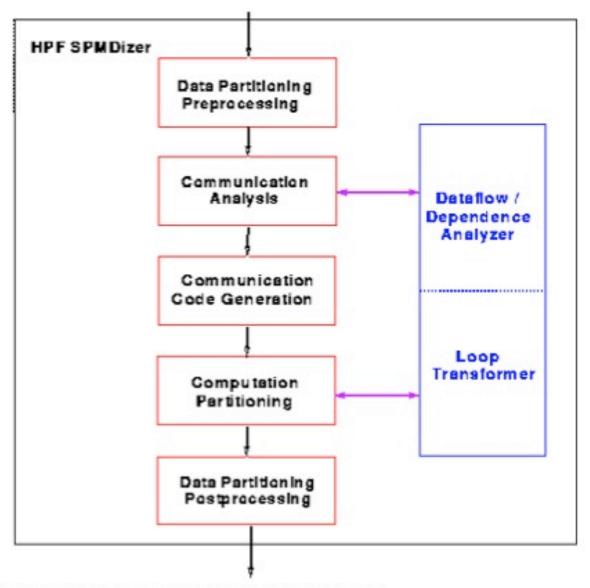


Figure 2: Architecture of the pHPF SPMDizer

Determining distributions

- The default is to let the programmer do this.
- Research by Uli Kremer (at Rice, now Maryland) and others aimed to do this automatically
 - Search a space of possible optimizations to determine which distribution incurred the least expense for data movement
 - Problem made harder by allowing redistribution

The owner's computes rule

- Developed by Pingali (UT Austin) and Anne Rogers (U. Chicago)
- Processor owning the target of an operation performs the operations
- a(i) = a(i) + b(i-2) processor owning a(i) performs the computation
- Compiler must determine
 - what elements of a it owns
 - what elements of a and b it needs to compute its a values
 - generate communication to acquire those a and b elements and send elements to other processors
 - only execute the iterations of the loop nest that cause each processor to compute its owned elements

One way to determine communication

- Look at the pattern of *lhs* references and *rhs* references with respect to the distribution.
- The distribution function is useful for this
- Some amount of pattern matching also used.

```
// assume 4 processors
float a(16), b(16)
!HPF$ ALIGN a(i) with b(i)
!HPF$ DISTRIBUTE \
       a(BLOCKED)
do i = 1, n
 a(i) = \dots
 do i = 1, n
   b(j) = a(j) \dots
 end
end
```

- P1 will compute a(1:4) and b(1:4)
- P1 only needs elements a(1:4)
- No communication needed

```
// assume 4 processors
float a(16), b(16)
!HPF$ DISTRIBUTE \
       a(BLOCKED)
!HPF$ DISTRIBUTE \
       b(*)
do i = 1, n
 a(i) = \dots
 do i = 1, n
   b(j) = a(j) \dots
 end
end
```

- b replicated over the processors
- Every processor has a copy of the b array
- P1 will compute a(1:4) and b(1:16)
- P1 needs elements a(1:16)
- P1 needs to receive elements a(1:16)
- P1 needs to send elements a(1:4) to all processors

```
// assume 4 processors
float a(16), b(16)
!HPF$ DISTRIBUTE \
       a(BLOCKED)
!HPF$ DISTRIBUTE \
       b(*)
do i = 1, n
 a(i) = ...
 do i = 1, n
   b(j) = a(j) \dots
 end
end
```

- P1 needs to receive elements a(1:16)
- P1 needs to send elements a(1:4) to all processors
- All-to-all communication allows a collective operation to be picked.

```
do i = 1, n

a(i) = a(i+1)

end
```

- P2 will compute a(5:8)
- P1 needs elements a(6:9)
- P1 needs to receive element a(9)
- P1 needs to receive a(9) and send a(5) to its lower neighbor
- Point-to-point operation -- send/ receive communication

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Send/recv communication

```
// assume 4 processors
float a(16), b(16)
!HPF$ DISTRIBUTE \
       a(BLOCKED)
!HPF$ DISTRIBUTE B(*)
do i = 1, n
 a(i) = ...
 do j = 1, n
   b(j) = a(j) \dots
 end
end
```

- P1 needs to receive elements a(1:16)
- P1 needs to send elements a(1:4) to all processors
- All-to-all communication allows a collective operation to be picked.

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Look for the following patterns

- one-to-one (or one-to-a-few): send/recv message passing communication
- one-to-many: bcast or scatter, depending on whether all elements sent to all, or some sent to some
- many-to-one: gather or reduce operation
- many-to-many: allgather, allscatter or alltoall communication

Scheduling strategy

- Figure out the iterations needed by each Pi for each Ihs reference using owner's computes
- Iteration space for Pi is
 - union of all of these (need to execute all required iterations)
 - intersected with the original loop bounds (can't execute more iterations that originally desired)
- Put guards around references to ensure it executes only for its iterations

Scheduling computation

```
float a(100), b(100)
!HPF$ ALIGN a(i) WITH b(i)
!HPF$ DISTRIBUTE a(BLOCK) \
       on P(4)
do i = 1, 100
  a(i) = ...
  if (i .gt. 0) then b(i-1) = ...
end do
                                 a(26:50)
                                           a(51:75)
                                                    a(76:100)
                                 a(26:50)
                                           b(51:75)
                                                    b(76:100)
                                                        12
                        Р1
                                   P2
                                              P3
```

b(1:25)	a(26:50) a(26:50)	b(51:75)	b(76:100)	
a(1:25)	a(26:50)	a(51:75)	a(76:100)	

```
float a(100), b(100)
!HPF$ ALIGN a(i) WITH b(i)
!HPF$ DISTRIBUTE a(BLOCK) \
on P(4)
```

Figure out the iterations needed by each Pi for each *lhs* reference using owner's computes (intersection of written and owned elements)

```
do i = 1, 100

// P1 executes i=1..25; P2 i=26..50; P3 i=51..75; P3 i=76..100
a(i) = . . .

// P1 executes i=2..26; P2 i=27..51; P3 i=52..76; P3 i=77..101
if (i .gt. 0) then b(i-1) = . . .

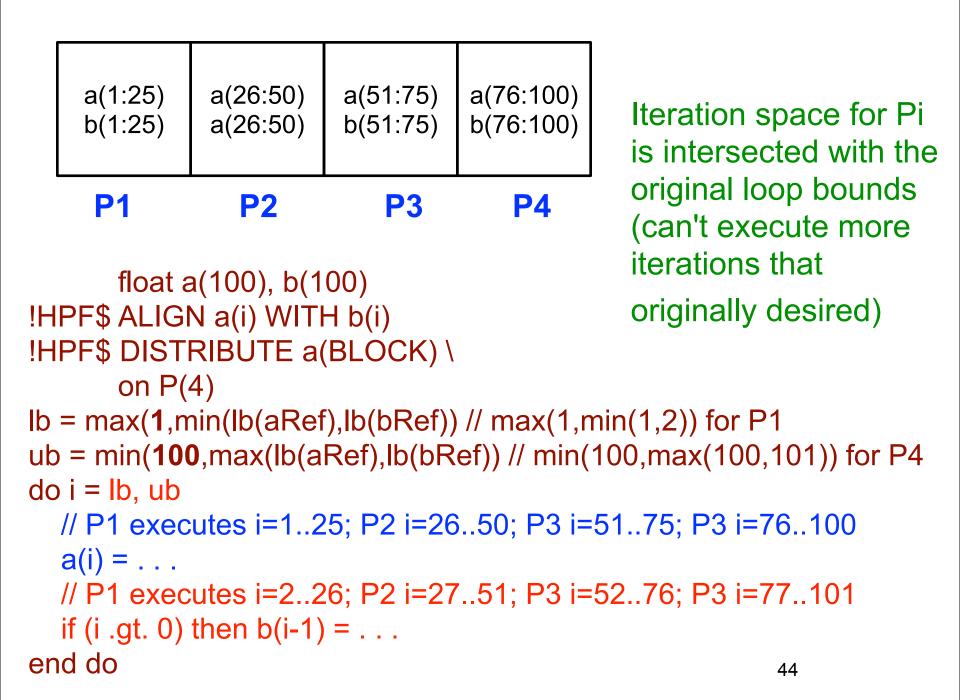
end do
```

```
a(1:25) a(26:50) a(51:75) a(76:100) b(1:25) P2 P3 P4
```

```
Iteration space for Pi is union
       float a(100), b(100)
                                       of iterations spaces for all
!HPF$ ALIGN a(i) WITH b(i)
                                       references
!HPF$ DISTRIBUTE a(BLOCK) \
       on P(4)
Ib = min(Ib(aRef),Ib(bRef) // min(1,2) for P1, min(51,52) for P3
ub = max(lb(aRef), lb(bRef) // max(25,26) for P1, max(75,76) for P3
do i = 1, 100
                                                                   aRef
  // P1 executes i=1...25; P2 i=26...50; P3 i=51...75; P3 i=76...100
  a(i) = ...
                                                                   bRef
  // P1 executes i=2..26; P2 i=27..51; P3 i=52..76; P3 i=77..101
  if (i .gt. 0) then b(i-1) = ...
end do
                                                           42
```

```
a(1:25) a(26:50) a(51:75) a(76:100) b(1:25) P2 P3 P4
```

```
Iteration space for Pi is union
       float a(100), b(100)
                                       of iterations spaces for all
!HPF$ ALIGN a(i) WITH b(i)
                                       references
!HPF$ DISTRIBUTE a(BLOCK) \
       on P(4)
Ib = min(Ib(aRef),Ib(bRef) // min(1,2) for P1, min(51,52) for P3
ub = max(lb(aRef), lb(bRef) // max(25,26) for P1, max(75,76) for P3
do i = lb, ub
  // P1 executes i=1..25; P2 i=26..50; P3 i=51..75; P3 i=76..100
  a(i) = ...
  // P1 executes i=2..26; P2 i=27..51; P3 i=52..76; P3 i=77..101
  if (i .gt. 0) then b(i-1) = ...
end do
                                                           43
```



```
a(26:50)
    a(1:25)
                         a(51:75)
                                   a(76:100)
                                   b(76:100)
              a(26:50)
                         b(51:75)
    b(1:25)
                                                Put guards around
                                                references to ensure
     P1
                 P2
                            P3
                                       P4
                                                it executes only for its
       float a(100), b(100)
                                                iterations
!HPF$ ALIGN a(i) WITH b(i)
!HPF$ DISTRIBUTE a(BLOCK) \
       on P(4)
Ib = max(1,min(lb(aRef),lb(bRef)) // max(1,min(1,2)) for P1
ub = min(100, max(lb(aRef), lb(bRef)) // min(100, max(100, 101)) for P4
doi = 1, 100
  // P1 executes i=1..25; P2 i=26..50; P3 i=51..75; P3 i=76..100
  if (i \in Ib(aRef) \dots ub(aRef)) then a(i) = \dots
  // P1 executes i=2..26; P2 i=27..51; P3 i=52..76; P3 i=77..101
  if (i \in lb(bRef) \dots ub(bRef)) and (i .gt. 0) then b(i-1) = \dots
end do
                                                            45
```

An example

```
integer A(100)
integer B(100,100)
!HPF$ DISTRIBUTED B(BLOCK,BLOCK)
!HPF$ ALIGN A(i) WITH B(1,i)
B = SPREAD(A,1,100)
END
```

Distribution and alignment functions allow the compiler to express which processor an element is one, and which elements are on a processor, as functions that can be manipulated as solved.

Scalarization

- Want to turn as much code as possible into "scalar" code, i.e. operations are on single elements.
- Allows uniform compiler internals over code that was originally vector code and code that was originally scalar code.

```
integer A(100)
integer B(100)
!HPF$ DISTRIBUTED B(BLOCK,BLOCK)
!HPF$ ALIGN A(I) WITH B(1,I)
B = SPREAD(A,1,100)
END
```

becomes

```
do i_5 = 1, 100,1
do i_6 = 1,100,1
B(i_6,i_5) = a(i,5)
end do
end do
```

Plus distribution information

An early "gotcha" with F90

do i_5 = 1, 100,1
integer A(100)
integer B(100)

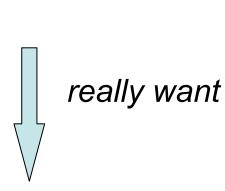
$$a(1:100) = b(1:100) + a(1:100)$$

END

do i_5 = 1, 100,1
 $t(i_5) = b(i_5) + a(i_5)$
 $a(i_5) = t(i_5)$
end do
end do

F90 semantics say execution as if

- i. the *rhs* computation is performed and placed in a temporary
- ii. the temporary is written into the *lhs*
- iii. enforces anti-dependences



Now what?

- Schedule, or spread, computation across processors
 - Owner computes rule the most popular way to do this
 - Processor that owns the LHS datum computes values stored into the LHS datum
- Values on the RHS that reside on a different processor than the LHS owner must be communicated to the LHS owner.

SPMD code for the Spread

```
integer, pointer :: 4, B
    DATA PARTITIONING
     call hpf_get_mmprocs(2,numprocs,pid)
     global_bounds(1) = 1
     global_bounds(2) = 100
     global_bounds(3) = 1
     global_bounds(4) = 100
     blocksize(1) = ((100 + minprocs(1)) - 1) / numprocs(1)
     blocksize(2) = ((100 + mmprocs(2)) - 1) / numprocs(2)
     icvn_lbound(1) = 1 + blocksize(1) * pid(1)
     iown_ubound(1) = blocksize(1) + iown_lbound(1) - 1
     icwn_lbound(2) = 1 + blocksize(2) * pid(2)
     iown_ubound(2) = blocksize(2) + iown_lbound(2) - 1
     call hpf_allocate(H, global_bounds, blocksize ...)
     call hpf_allocate(4,...)
     COMMUNICATION
     cb_section(1) = iown_lbound(2)
     cb_section(2) = minO(iown_ubcund(2),100)
     cb_section(3) = 1
     call hpf_allocate_computation_buffer(buffer,cb_section,...)
     if (pid(2) .le. 99 / blocksize(2) .and. pid(1) .le. 99 / blocksize(1)
   & .or. pid(1) .eq. 0) then
       send_section(1) = iown_lbound(2)
       send_section(2) = minO(iown_ubgund(2),100)
       send_section(3) = 1
       call hpf_bcast_section(4,send_section, buffer...)
     LOOPS SHRUNK BY COMPUTATION PARTITIONING
     do i_8=iown_lbound(2),min0(iown_ubound(2),100),1
       do i_9=iown_lbound(1),minO(iown_ubound(1),100),1
         B(i_9,i_8) = buffer(i_8)
     end do
     call deallocate(buffer)
Figure 5: SPMDized SPREAD program
```

Don't try to read this, but this is the final SPMD code for the original example program.

Three kinds of code:

- Data partitioning bookkeepting code
- 2. Communication code
- Shrunked computation loop to achieve parallelism

SPMDization

Enforce the owner compute's rule

```
do i 5 = 1, 100, 1
     do i 6 = 1,100,1
       b(i 6,i 5) = a(i,5)
     end do
                      do i 5 = 1, 100, 1
   end do
                        do i 6 = 1,100,1
                          if (I 6 .ge. p*blocksize(1) + 1 .and.
                             I 6 .le. (p+1)*blocksize(1) .and.
p = 0 \dots numproc-1
                             I 5 .ge. p*blocksize(2) + 1 .and.
                                     I 5 .le. lb+blocksize(2)-1) then
                             b(i 6, i 5) = a(i 5)
                          end
                        end do
                      end do
```

```
do i 5 = 1, 100.1
  do i 6 = 1.100.1
    if (I_6 .ge. p*blocksize(1) + 1.and.
    I 6.le.lb+blocksize(1)-1.and.
    I 5.ge. p*blocksize(2) + 1.and.
    I 5.le.lb+blocksize(2)-1) then
    B(i 6, i 5) = a(i 5)
                                         do i 5 = 1.100.1
    end
                                          do i 6 = 1,100,1
                                            a owner(1) = 1
  end do
                                            a owner(2) = (i \ 5+numprocs(2)-1)/numprocs(2)
end do
            proc owns a(i 5)?
                                            if (pid(1).eq.a owner(1).and.pid(2).eq.a owner(2)) then
                                              send(a(i_5), ...); send(a(i_5), ...); ... send(a(i_5), ...)
                                              abuff = a(i_5) /* this allows a uniform reference to a(i_5) */
                                            end
                                            if (i \ 6 \ .ge. \ p*blocksize(1) + 1.and.
                                               i 6.le.lb+blocksize(1)-1.and.
                                                i_5.ge. p*blocksize(2) + 1.and.
                                               i_5.le.lb+blocksize(2)-1) then
                                               if!(pid(1).eq.a owner(1).and.pid(2).eq.a owner(2))
                                               then
                                                  receive(abuff)
                                               end
                                               B(i 6,i 5) = abuff
                                               end
                                            end
                                          end do
                                         end do
```

```
do i_5 = 1, 100,1

do i_6 = 1,100,1

if (I_6 .ge. p*blocksize(1) + 1.and.

I_6.le.lb+blocksize(1)-1.and.

I_5.ge. p*blocksize(2) + 1.and.

I_5.le.lb+blocksize(2)-1) then

B(i_6,i_5) = a(i_5)

end

end do

end do
```

Put $a(i_5)$ in abuff so if we own it, and receive it into abuff if we don't own it. Allows single name for owner and non-owner

```
do i 5 = 1.100.1
 do i 6 = 1,100,1
    a owner(1) = 1
    a owner(2) = (i \ 5 + numprocs(2) - 1)/numprocs(2)
    if (pid(1).eq.a owner(1).and.pid(2).eq.a owner(2)) then
      send(a(i_5), ...); send(a(i_5), ...); ... send(a(i_5), ...)
      abuff = \overline{a(i \ 5)} /* this allows a uniform reference to a(i \ 5) */
    end
    if (i \ 6 \ .ge. \ p*blocksize(1) + 1.and.
       i 6.le.lb+blocksize(1)-1.and.
       i 5.ge. p*blocksize(2) + 1.and.
       i 5.le.lb+blocksize(2)-1) then
       if !(pid(1).eq.a owner(1).and.pid(2).eq.a_owner(2))
         receive(abuff)
       end
       B(i_6,i_5) = abuff
       end
    end
 end do
end do
```

```
do i 5 = 1, 100.1
 do i 6 = 1.100.1
    if (I_6 .ge. p*blocksize(1) + 1.and.
    I 6.le.lb+blocksize(1)-1.and.
    I 5.ge. p*blocksize(2) + 1.and.
    I 5.le.lb+blocksize(2)-1) then
    B(i 6, i 5) = a(i 5)
                                        do i 5 = 1.100.1
    end
                                         do i 6 = 1,100,1
 end do
                                           a owner(1) = 1
                                           a owner(2) = (i \ 5 + numprocs(2) - 1)/numprocs(2)
end do
                                           if (pid(1).eq.a owner(1).and.pid(2).eq.a owner(2)) then
                                             send(a(i_5), ...); send(a(i_5), ...); ... send(a(i_5), ...)
                                             abuff = \overline{a(i_5)} /* this allows a uniform reference to a(i_5) */
                                           end
                                           if (i 6 .ge. p*blocksize(1) + 1.and.
                                              i 6.le.lb+blocksize(1)-1.and.
  If we are in-bounds and
                                              i_5.ge. p*blocksize(2) + 1.and.
                                              i 5.le.lb+blocksize(2)-1) then
  don't own a(i \ 5) receive
                                              if !(pid(1).eq.a owner(1).and.pid(2).eq.a_owner(2))
  it into abuff
                                                 receive(abuff)
                                              end
                                              B(i_6,i_5) = abuff
                                              end
                                           end
```

end do end do

```
do i_5 = 1, 100,1

do i_6 = 1,100,1

if (I_6 .ge. p*blocksize(1) + 1.and.

I_6.le.lb+blocksize(2) + 1.and.

I_5.ge. p*blocksize(2) + 1.and.

I_5.le.lb+blocksize(2)-1) then

B(i_6,i_5) = a(i_5)

end

end do

end do

end do

end do

end do

end do

end do
```

do the assign of *abuff* into the appropriate element of *b*(*i* 6, *i* 5)

```
a owner(2) = (i \ 5 + numprocs(2) - 1)/numprocs(2)
    if (pid(1).eq.a owner(1).and.pid(2).eq.a owner(2)) then
      send(a(i_5), ...); send(a(i_5), ...); ... send(a(i_5), ...)

abuff = a(i_5) /* this allows a uniform reference to a(i_5) */
    if (i \ 6 \ .ge. \ p*blocksize(1) + 1.and.
        i 6.le.lb+blocksize(1)-1.and.
        i 5.ge. p*blocksize(2) + 1.and.
        i_5.le.lb+blocksize(2)-1) then
        if!(pid(1).eq.a owner(1).and.pid(2).eq.a owner(2))
           receive(abuff)
        end
        B(i_6,i_5) = abuff
        end
    end
  end do
end do
```

This code is very inefficient

```
do i 5 = 1, 100, 1
  doi 6 = 1,100,1
    a \ owner(1) = 1
    a owner(2) = (i 5+numprocs(2)-1)/numprocs(2)
    if (pid(1).eq.a_owner(1).and.pid(2).eq.a_owner(2)) then send(a(i_5), ...); send(a(i_5), ...); ... send(a(i_5), ...)
      abuff = a(i 5)
    end
    if (i 6 .ge. p*blocksize(1) + 1.and.
        i 6.le.lb+blocksize(1)-1.and.
        i 5.ge. p*blocksize(2) + 1.and.
        i 5.le.lb+blocksize(2)-1) then
        if (pid(1).eq.a_owner(1).and.pid(2).eq.a_owner(2))
           receive(abuff)
        end
        B(i_6, i_5) = abuff
    end
  end do
end do
```

- every iteration executed on every processor
 - All processors do work of whole program within a constant factor.
- Data communicated element by element
- Much redundant computation that appears to be loop independent

Shrink the loop bounds

```
i 6lb = min(1,p*blocksize(1) + 1)
\overline{1} 6ub = max(100,i 6ilb+blocksize(1)-1)
i_5lb = min(1,p*blocksize(2) + 1)

i_5ub = max(i_5lb+blocksize(2)-1)
do i 5 = i 5lb, i 5ub, 1
  do i 6 = i 6lb, i 6ub, 1
    a owner(1) = 1
    a owner(2) = (i \ 5 + numprocs(2) - 1)/numprocs(2)
    if (pid(1).eq.a owner(1).and.pid(2).eq.a owner(2)) then
      send(a(i 5), ...)
      abuff = a(i 5)
    end
    if then
       if (pid(1).eq.a owner(1).and.pid(2).eq.a owner(2))
       then
          receive(abuff)
       end
       B(i 6,i 5) = abuff
    end
  end do
end do
```

Each processor only does part of the work

Recognize the communication

```
i 6lb = min(1,p*blocksize(1) + 1)
\overline{i} 6ub = max(100,i 6ilb+blocksize(1)-1)
 5lb = min(1,p*blocksize(2) + 1)
 5ub = max(i 5lb+blocksize(2)-1)
a owner(1) = 1
a owner(2) = (i \ 5 + numprocs(2) - 1)/numprocs(2)
if (pid(1).eq.a_owner(1).and.pid(2).eq.a_owner(2)) then
  bcast(abuff, part of a owned)
end
do i 5 = i 5lb, i 5ub, 1
  do i 6 = i 6lb, i 6ub, 1
   if then
     B(i_6,i_5) = abuff(i_5)
    end
 end do
end do
```

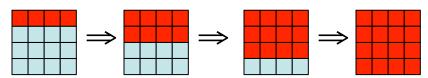
loop iteration space where the processor owns the LHS datum.

If the startup code is

Computation consists

of some startup code,

and that part of the



If the startup code is relatively fast, we get very good speedups.

Communication generation

 Look at subscript patterns and mapping information to see what the pattern is (c is constant, i, j, k are index variables).
 Assume data is aligned in what follows.

```
-a(...,i,...) = ... b(...,c,...) broadcast

-a(...,i,...) = ... b(...,i-c,...) shift

-a(...,c,...) = ...b(...,i,...) reduction
```

Also perform optimizations

Communication optimizations Loop distribution

```
!HPF Align D(I) with A(i,1)
do i = 1, n
D(i) = D(i) + s * B(i)

Communication for D(I)
do j = 1, n
A(i,j)=A(i,j)+D(i)
end do

End do
```

Do communication once instead of n times.

```
!HPF Align D(I) with A(i,1)
    do i = 1, n
        D(i) = D(i) + s * B(i)
    enddo
    Communication for D(1:n)
    do i = 1, n
        do j = 1, n
        A(i,j)=A(i,j)+D(i)
    end do
End do
```

Communication Optimizations Message Coalescing

```
!HPF Distribute (block,block) :: A,B
 Shift communication for (B(i-1,j))
                                                     can combine into
 Shift communication for (B(i-1,j-1))
                                                     one message
 do j = 2, n
   do I = 2, n
     A(i,j) - f(B(i-1,j), B(i-1,j-1))
   enddo
 enddo
                    Shift communication for (B(i-1,j) U (B(i-1,j-1))
                    do j = 2, n
                      do I = 2, n
                        A(i,j) - f(B(i-1,j), B(i-1,j-1))
                      enddo
                    enddo
```

Communication optimizations wavefront

```
$HPF! Distribute A(block,block)

do j = 2, n

do l = 2, n

a(i,j) = f(A(i-1,j),A(i,j-1))

end do

end do
```

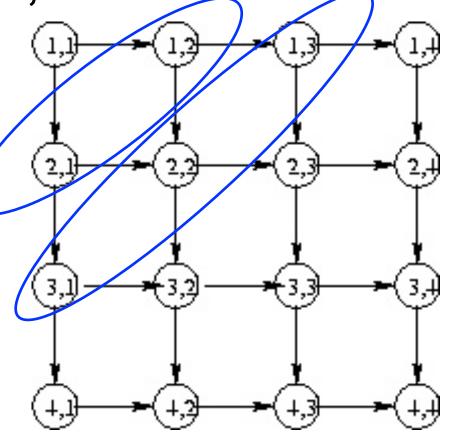
Naïve communication generation puts communication inside both the i and j loops because of the true dependence.

```
$HPF! Distribute A(block,block)
do j = 2, n
receive(a2buff,...)
do l = 2, n
receive(a1buff, ...)
a(i,j) = f(a1buff,a2buff)
send(a(l,j), ...)
end do
send(a(1,j),...)
end do
```

Communication optimizations wavefront, continued

\$HPF! Distribute A(block,block) do j = 2, n do l = 2, n a(i,j) = f(A(i-1,j),A(i,j-1))end do end do

Note that there is parallelism



Communication optimizations wavefront, continued

```
$HPF! Distribute A(block,block)

do j = 2, n

receive(abuff1,...)

receive(abuff2,...)

do i = 2, n

a(i,j) = \mathscr{a}(abuff2(i-1,j),abuff1(i,j-1))

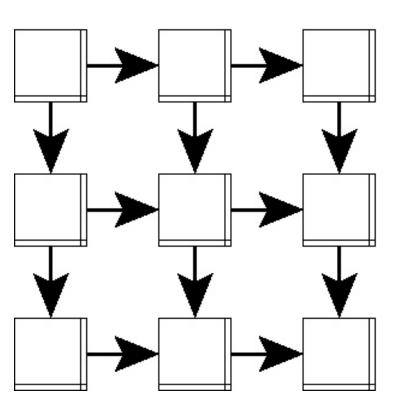
end do

shift(A,down,...)

shift(A,across,...)

end do
```

Each shift communicates a strip of A, not just a single element.



Communication optimizations wavefront, continued

```
$HPF! Distribute A(block,block)

do j = 2, n

receive(abuff1,...)

receive(abuff2,...)

do i = 2, n

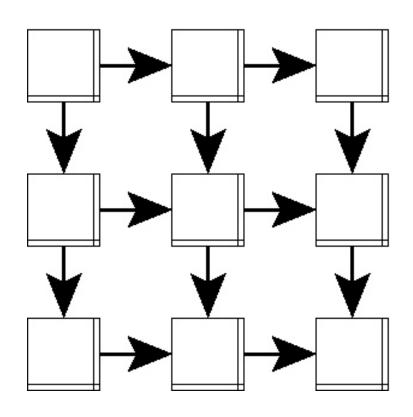
a(i,j) = *\textstyle{\sigma}(abuff2(i-1,j),abuff1(i,j-1)))

end do

shift(A,down,...)

shift(A,across,...)

end do
```



Trade-off between granularity of parallelism and number of messages. Reduces message startup cost and latency overhead

The real code for SPREAD Data Partitioning

```
integer, pointer::A, B
! DATA PARTITIONING
 call hpf_get_numprocs,numprocs,pid)
 global bounds(1) = 1 // lower bounds dimension 1
 global bounds(2) = 100 // upper bounds dimension 1
 global bounds(3) = 1 // I lower bounds dimension 2
 global bounds(4) = 100 // upper bounds dimension 1
 blocksize(1) = ((100+numprocs(1)-1)/numprocs(1) // blocksize dimension 1
  blocksize(2) = ((100+numprocs(2))-1)/numprocs(2) // blocksize dimension 2
 iown_lbound(1) = 1+blocksize(1)*pid(1) // LB owned elts dim 1
 iown_ubound(1) = blocksize(1)*iown_lbounds(1)-1 // UB owned elts dim 1
 iown_lbound(2) = 1+blocksize(2)*pid(2) // LB owned elts dim 2
 iown ubound(2) = blocksize(2)*iown lbounds(2)-1 // UB owned elts dim 2
 call hpf_allocate(B, global_bounds, blocksize, ...) // allocate local space for B
 call hpf_allocate(A, ...) // allocate local space for A
```

The real code for SPREAD Communication

! COMMUNICATION

```
cb_section(1) = iown_lbound(2) // communication buffer lower bound cb_section(2) =
    min0(iown_lbound(2),100) // comm buffer upper bound
cb_section(3) = 1 // comm buffer stride
call hpf_allocate_computation_buffer(buffer, cb_section, ...) // alloc comm buffer
if (pid(2).le.99/blocksize(2).and.pid(1).le.99/blocksize(1).or.pid(1).eq.0) then
    send_section(1) = iown_lbound(2)
    send_section(2) = min0(iown_ubound(2), 100)
    send_section(3) = 1
    ...
    call hpf_bcast_section(A, send_section, buffer, ...)
end if
```

The real code for SPREAD Computation

```
! LOOPS SHRUNK BY COMPUTATION PARTITIONING do i_8=iown(lbound(2), min0(iown_ubound(2),100),1 do i_9=iown_lbound(1),min0(iown_ubound(1),100),1 B(i_9,i_8) = buffer(i_8) end do end do call deallocate(buffer) end
```

Performance

Program	Serial	1 proc	2 proc	4 proc	8 proc	16 proc	32 proc
Grid(b,b,*)	1 (43.6)	1.01	2.01	4.02	7.92	15.47	30.49
Grid*(b,b,*)	1.00	1.02	2.02	4.03	7.98	14.09	30.28
Grid MPL	1.00	1.00	2.00	3.98	7.89	15.78	30.43
Tomcatv(*,b)	1 (40.06	0.89	1.76	3.29	6.36	11.34	17.65
Ncar(*,b)	1 (14.34)	0.89	2.13	3.88	6.91	12.12	18.33
Ncar(b,b)	1	1.01	1.71	3.74	6.75	12.20	19.32
Ncar MPL	1	1.14	2.28	4.53	8.82	16.62	31.10
X42(*,b)	1 (0.84)	1.03	1.95	3.65	6.61	10.98	16.45
X42(b,b)	1	1.18	2.03	3.81	6.99	13.36	21.96
X42 MPL	1	1	1.98	3.85	7.50	13.77	24.70

How successful was HPF?

- Major hardware vendors had implementations (IBM, DEC, Portland Group (PGI) for others)
- Good performance on regular programs
- Lots of research funding from both industry and NSF
 - Rice, Syracuse, UIUC, IBM, DEC had major research efforts
 - Dominated conferences
 - Do you want your language to be a research topic?

What killed HPF?

- Unrealistic expectations: just put in data distributions and we will do the rest
- Often bad performance initially
- Unpredictable performance: slight change in program led to major, inexplicable changes in performance
- Different subset for every vendor
- Could not handle irregular programs well