

EXAM 3 is next week

Time: 8:00-9:30 pm Wed Apr 11

Place: Elliott Hall

Material: lectures 1-22, HW 1-22, Recitations 1-12, Labs 1-12

focus will be on last 3rd of material (not on Exams 1 & 2)

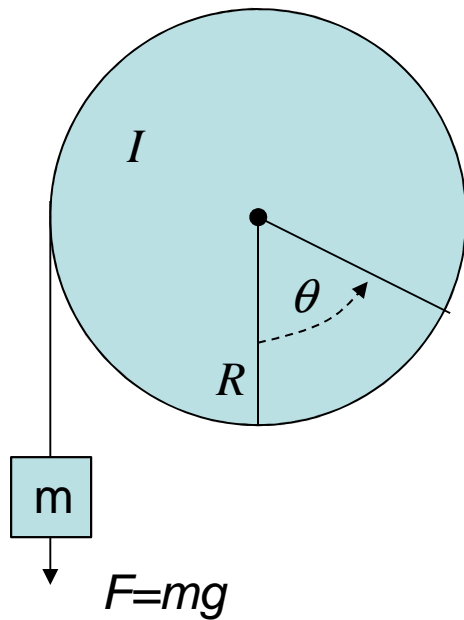
Problems: multiple choice, 10 questions (70 points)
write-up part, hand graded (30 points)

Equation sheet: provided with exam

Practice exam + equation sheet: will be posted at the end of this week

Note: no lecture on Thursday Apr 12!

Predicting Position with Rotation



A light string is wrapped around disk of radius R and moment of inertia I that can freely spin around its **fixed** axis. The string is pulled with force F during time Δt . Assume that the disk was initially at rest ($\omega_i=0$)

1) What will be the angular speed ω_f ?

Solution:

$$\Delta \vec{L}_{tot} = \vec{\tau}_{net} \Delta t$$

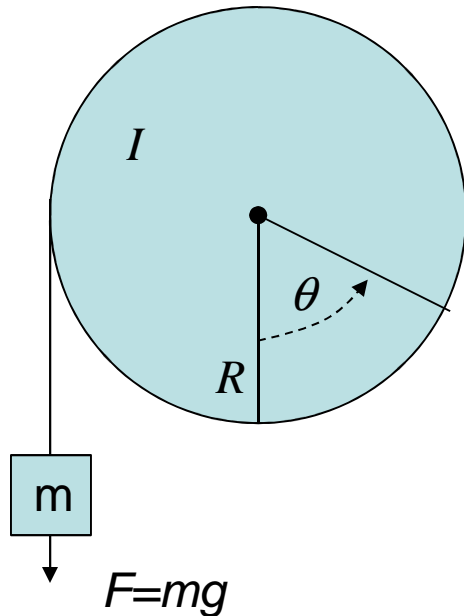
$$I \vec{\omega}_f - I \vec{\omega}_i = I \vec{\omega}_f = \vec{R} \times \vec{F} \cdot \Delta t$$

$$I \omega_f = RF \Delta t$$

$$\omega_f = \frac{RF \Delta t}{I}$$

$$\frac{d\vec{L}_{tot}}{dt} = \vec{\tau}_{net}$$

Predicting Position with Rotation



A light string is wrapped around disk of radius R and moment of inertia I that can freely spin around its *fixed* axis. The string is pulled with force F during time Δt . Assume that the disk was initially at rest ($\omega_i = 0$)

- 1) What will be the angular speed ω_f ?
- 2) How far (Δx) will the end of string move?

Solution:

$$\Delta\theta = \omega_{aver} \Delta t$$

$$\omega_{aver} \equiv \frac{\Delta\theta}{\Delta t}$$

ω changes linearly with time:

$$\omega_{aver} = \frac{\omega_i + \omega_f}{2} = \frac{\omega_f}{2}$$

$$\Delta\theta = \frac{\omega_f}{2} \Delta t = \frac{RF(\Delta t)^2}{2I}$$

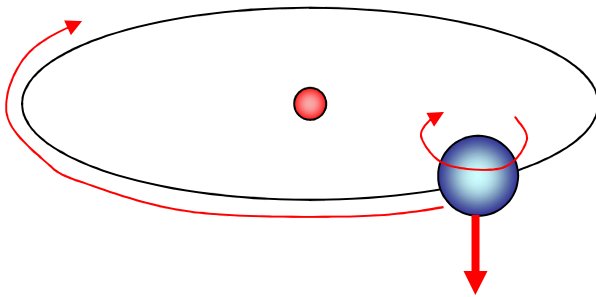
$$\Delta x = R\Delta\theta = \frac{F(R\Delta t)^2}{2I}$$

$$\frac{d\vec{L}_{tot}}{dt} = \vec{\tau}_{net} \quad \omega_f = \frac{RF\Delta t}{I}$$

See also examples
in Section 11.8

Angular momentum quantization

Many elementary particles behave as if they possess ***intrinsic rotational angular momentum***



Electron can have translational (orbital around nucleus), and intrinsic rotational angular momenta

Strange but true: **Angular momentum is quantized**

$$\text{Angular momentum quantum} = \hbar = \frac{h}{2\pi} = 1.05 \times 10^{-34} \text{ J s}$$

$$[\text{J s}] = [\text{kg m}^2 \text{s}^{-1}]$$



Whenever you measure a vector component of angular momentum you get either half-integer or integer multiple of \hbar

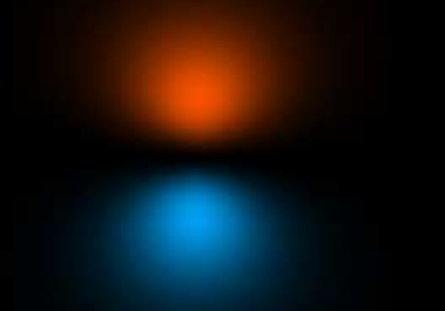
Orbital angular momentum comes in integer multiples, but intrinsic spin of “Fermions” (building blocks) is $\frac{1}{2}$ unit of \hbar

Orbital Angular Momentum

Where is the orbital angular momentum in a hydrogen orbital?

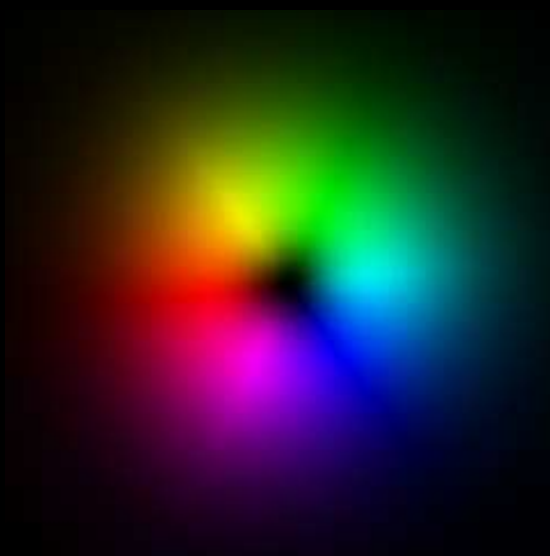


p_x



$i p_y$

+



$= |L=1, L_z=1\rangle$

Electron "current"
circles around
the atom.

Quantized because
these are 3D standing
electron waves
around the nucleus.

See *Atom in a Box*
www.daugerresearch.com

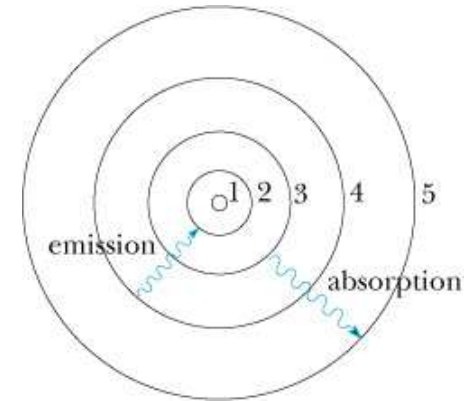
Bohr's Atomic Model



Niels Bohr

$$\left| \vec{L}_{A,trans,electron} \right| = \sqrt{mrkq_e^2}$$

1913: IDEA: Electron can only take orbits where its translational angular momentum is integer multiple of \hbar



Allowed radii:
$$r = N^2 \frac{\hbar^2}{kq_e^2 m_e}$$

$$\hbar = 1.05 \times 10^{-34} \text{ J} \cdot \text{s}$$

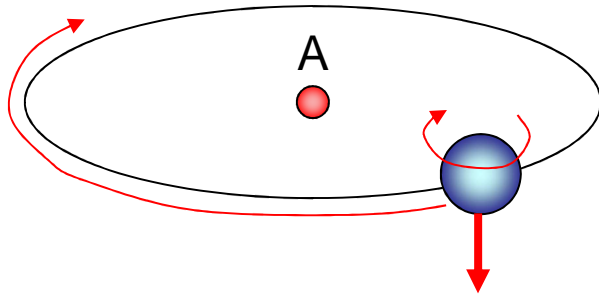
$$N = 1, 2, 3, \dots$$

This implies that only certain values of $L_{A,trans,electron}$ are allowed:

$$\left| \vec{L}_{A,trans,electron} \right| = N\hbar \quad \text{where } N=1,2,3,\dots$$

NOTE: Because K and U are functions of r and v, energy levels are quantized also. 6

Bohr Model



Consider an electron in circular orbit about a proton. What are the possible values of $L_{A,trans,electron}$?

Assume circular motion:

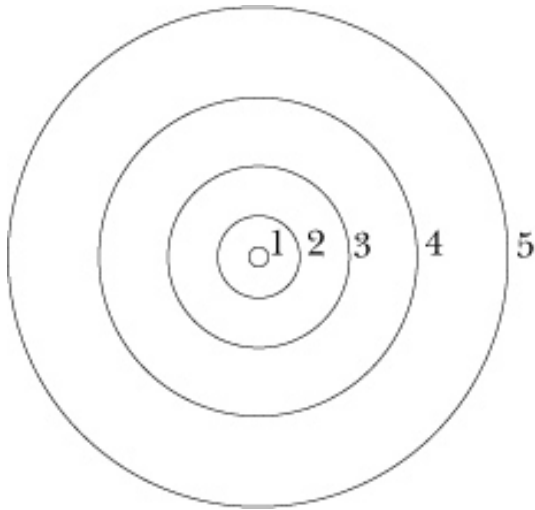
$$\left| \vec{F}_e \right| = \frac{m\nu^2}{r} \Rightarrow \frac{kq_e^2}{r^2} = \frac{m\nu^2}{r} \Rightarrow \nu = \sqrt{\frac{kq_e^2}{mr}}$$

$$\text{Thus, } \left| \vec{L}_{A,trans,electron} \right| = m\nu r = \sqrt{mrkq_e^2}$$

If any orbital radius r is allowed, $L_{A,trans,electron}$ can be anything.

However, only certain values of r are allowed . . .

The Bohr model: allowed radii and energies



See derivation on page 444-446

Allowed Bohr radii for electron orbits:

$$r_N = N^2 \frac{h^2}{\frac{1}{4\pi\epsilon_0} e^2 m} \approx N^2 (0.53 \times 10^{-10} \text{ m})$$

Use $E_N = K + U$ and

$$\left| \vec{F}_e \right| = \frac{m\nu^2}{r} = \frac{kq_e^2}{r^2}$$

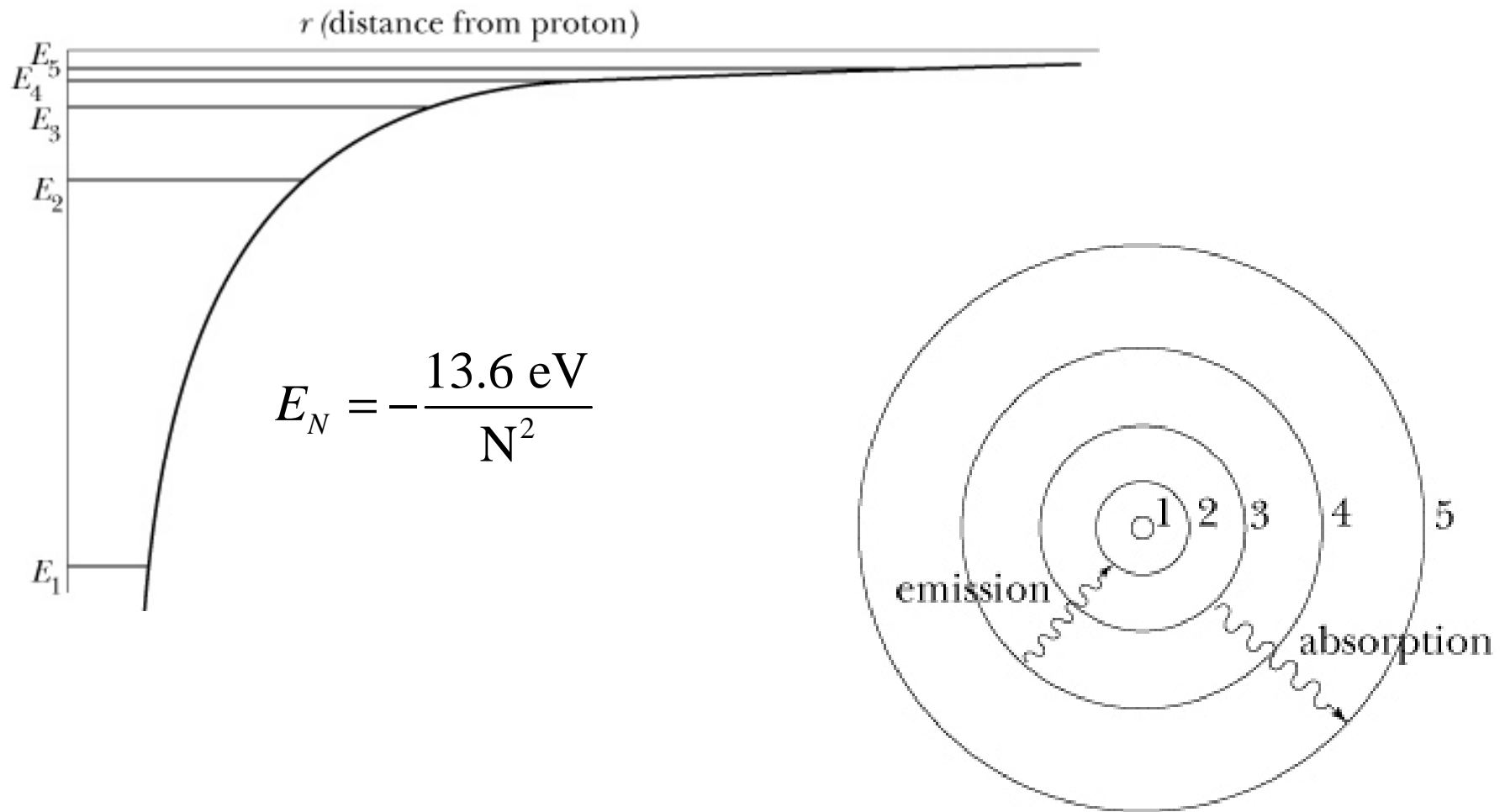
This is 2K

$$k = \frac{1}{4\pi\epsilon_o}$$

Bohr model energy levels:

$$E = - \frac{\left(\frac{1}{4\pi\epsilon_o} \right)^2 e^4 m}{2N^2 \hbar^2} = - \frac{13.6 \text{ eV}}{N^2}, \quad N=1,2,3,\dots$$

The Bohr model: and photon emission



Particle spin

↑ Rotational angular momentum

Electron, muon, neutrino have spin $1/2$:
measurements of a component of their angular momentum yields $\pm 1/2 \hbar$

Quarks have spin $1/2$

Protons and neutrons (three quarks) have spin $1/2$

Mesons: (quark+antiquark) have spin 0 or 1

Macroscopic objects: quantization of L is too small to notice!

Two lowest energy electrons in any atom have total angular momentum 0

Fermions: spin $1/2$, Pauli exclusion principle ← Cooper pairs: superconductivity

Bosons: integer spin

Rotational energies of molecules are quantized

Quantum mechanics: L_x, L_y, L_z can only be integer or half-integer multiple of \hbar

Quantized values of $L^2 = l(l+1)\hbar^2$ where l is integer or half-integer

Gyroscopic Stability



Edmund Scientifics

In 1917, the Chandler Company of Indianapolis, Indiana, created the "Chandler gyroscope," a toy gyroscope with a pull string and pedestal. It has been in continuous production ever since and is considered a classic American toy.
-- Wikipedia

Best Trick in the Book

$$\frac{d\vec{p}}{dt} = \vec{F}_{\text{net}}$$

$$\vec{p} = |p|\hat{p}$$

Vectors have *direction*
and *magnitude*.

Vector Notation and the Momentum Principle:

$$\begin{aligned}\frac{d\vec{p}}{dt} &= |p| \frac{d\hat{p}}{dt} + \hat{p} \frac{d|p|}{dt} \\ &= \vec{F}_{\perp} + \vec{F}_{\parallel}\end{aligned}$$

Use the chain rule

\vec{F}_{\perp} causes changes
in the *direction* of \vec{p}

\vec{F}_{\parallel} causes changes
in the *magnitude* of \vec{p}

Blast from the Past
Section 5.5

Best Trick *Not* in the Book

$$\frac{d\vec{L}}{dt} = \vec{\tau}_{\text{net}}$$

$$\vec{\tau} = |\tau|\hat{\tau}$$

Vectors have *direction*
and *magnitude*.

Vector Notation and the Angular Momentum Principle:

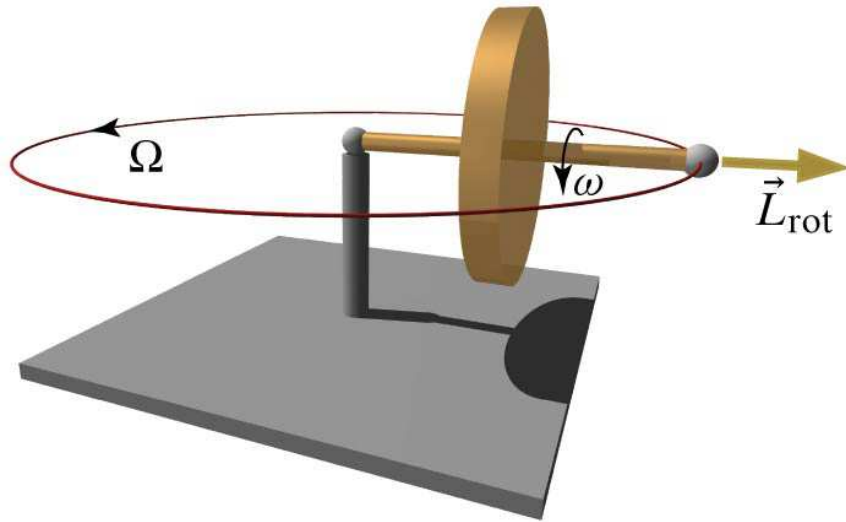
$$\begin{aligned}\frac{d\vec{L}}{dt} &= |L| \frac{d\hat{L}}{dt} + \hat{L} \frac{d|L|}{dt} \\ &= \vec{\tau}_{\perp} + \vec{\tau}_{\parallel}\end{aligned}$$

Use the chain rule

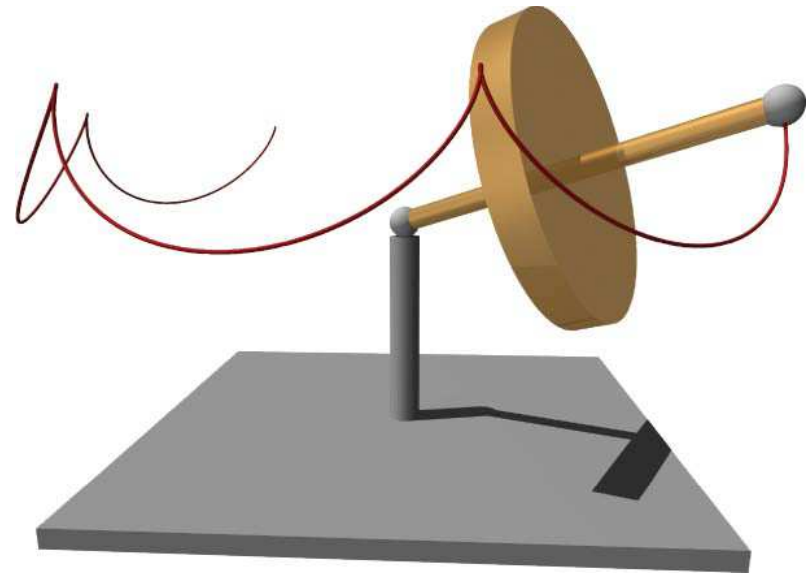
$\vec{\tau}_{\perp}$ causes changes
in the *direction* of \vec{L}

$\vec{\tau}_{\parallel}$ causes changes
in the *magnitude* of \vec{L}

Gyroscopes



Precession



Precession and nutation

i>clicker

$$\Omega = \frac{RMg}{I\omega}$$



A



B

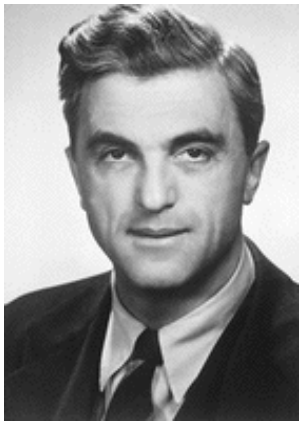
In which of the two gyroscopes is the disk spinning faster?

Precession phenomena (see book)

Magnetic Resonance Imaging (MRI)

Precession of spin axes in astronomy

Tidal torques



Felix Bloch
1905-1983



Edward Mills Purcell
1912-1997

NMR - nuclear magnetic resonance

Independently discovered (1946)

Nobel Price (1952)

B.S.E.E. from **Purdue**
electrical engineering

NMRI = MRI