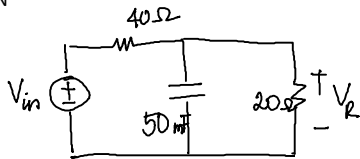


(13)

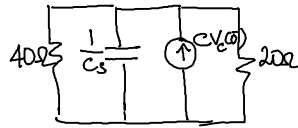
a)



(i) Zero-input response

$$Z(s) = 40 \parallel \frac{1}{Cs} \parallel 20$$

$$= \frac{1}{\frac{1}{40} + Cs + \frac{1}{20}} = \frac{40}{2s+3}$$



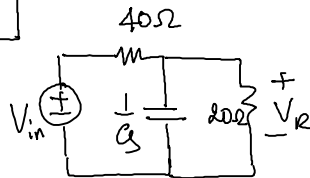
$$V_R(s) = Z(s) \cdot CV_C(0^-) = \frac{-24}{2s+3}$$

$$\Rightarrow v_R^{(0)}(t) = -12e^{-\frac{3}{2}t} u(t)$$

(ii) zero-state response

$$Z(s) = \frac{1}{Cs + \frac{1}{20}} = \frac{20}{s+1}$$

$$V_{in}(s) = \frac{3}{(s+2)^2}$$



$$V_R(s) = \frac{Z(s)}{Z(s) + 40} \cdot V_{in}(s) = \frac{3}{2s^3 + 11s^2 + 20s + 12}$$

$$\Rightarrow v_R^{(z)}(t) = (6e^{-\frac{3}{2}t} - 6e^{-2t} - 3te^{-2t}) u(t)$$

(iii) complete response

$$v_R(t) = v_R^{(0)}(t) + v_R^{(z)}(t) = (-6e^{-\frac{3}{2}t} - 6e^{-2t} - 3te^{-2t}) u(t)$$

b)

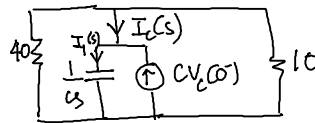
(i) Zero-input response

$$I_T(s) = CV_C(0^-) \cdot \frac{Cs}{Cs + \frac{1}{10} + \frac{1}{40}}$$

$$= \frac{9s}{20s+100}$$

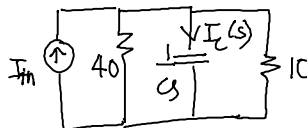
$$I_C(s) = I_T(s) - CV_C(0^-) = -\frac{9}{4s+20}$$

$$\Rightarrow i_C^{(0)}(t) = -\frac{9}{4} e^{-5t} u(t)$$



(ii) Zero-state response

$$I_C(s) = I_{in}(s) \cdot \frac{Cs}{Cs + \frac{1}{10} + \frac{1}{40}}$$



$$= \frac{6}{s^2 + 7s + 10}$$

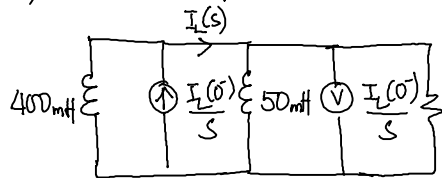
$$\Rightarrow i_c^{(2)}(t) = [2e^{-2t} - 2e^{-5t}] u(t)$$

iii) Complete response

$$i_c(t) = i_c^{(1)}(t) + i_c^{(2)}(t) = \left[2e^{-2t} - \frac{17}{4}e^{-5t} \right] u(t)$$

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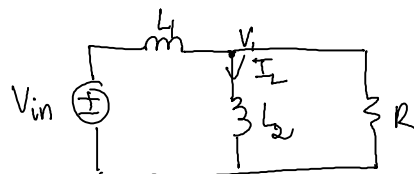
a) i. Zero-input



$$I_L(s) = \frac{I_L(0)}{s} = -\frac{4}{s}$$

$$i_L^{(1)}(t) = -4u(t)$$

ii) Zero-state



$$L_1 = 400 \text{ mH}$$

$$L_2 = 50 \text{ mH}$$

$$R = 200 \text{ m}\Omega$$

$$V_1(s) = V_{in}(s) \cdot \frac{L_2 s \parallel R}{(L_2 s \parallel R) + L_1 s} = \frac{2s}{2s^3 + 21s^2 + 70s + 72}$$

$$I_L(s) = \frac{V_1(s)}{L_2 s} = \frac{40}{2s^3 + 21s^2 + 70s + 72}$$

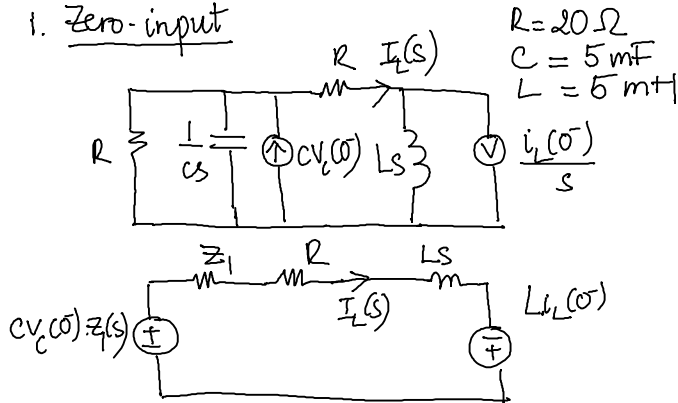
$$i_L^{(2)}(t) = \left[4e^{-2t} - 20e^{-4t} + 16e^{-\frac{9t}{2}} \right] u(t)$$

③ complete response

$$I_L(s) = \frac{-8s^3 - 84s^2 - 240s - 288}{2s^4 + 21s^3 + 70s^2 + 72s}$$

$$i_L(t) = i_L^{(1)}(t) + i_L^{(2)}(t) = \left[-4 + 4e^{-2t} - 20e^{-4t} + 16e^{-\frac{9t}{2}} \right] u(t)$$

⑤ i. Zero-input



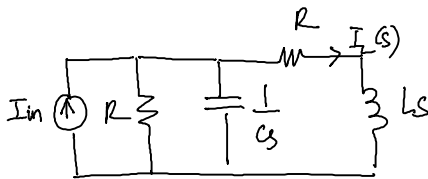
$$z_1(s) = \frac{1}{cs + \frac{1}{R}}$$

$$I_L(s) = \frac{[cv_c(0)z_1(s) + L i_L(0)]}{z_1(s) + R + Ls}$$

$$I_L(s) = \frac{2s + 220}{s^2 + 4010s + 80000}$$

$$i_L^{(1)}(t) = 2e^{-2005t} [\cosh(1985t) - .95 \sinh(1985t)]$$

⑥ ii zero-state



$$z_1(s) = \frac{1}{cs + \frac{1}{R}}$$

$$I_L(s) = I_{in}(s) \cdot \frac{z_1(s)}{z_1(s) + R + Ls}$$

$$\boxed{I_L(s) = \frac{280000s + 120000}{s^3 + 4014s^2 + 96040s + 320000}}$$

$$\Rightarrow i_L^{(2)}(t) = 15.6 e^{-2005t} [\cosh(1985t) + 10 \sinh(1985t)] - 15.6 e^{-4t}$$

(iii) complete $\boxed{I_L(s) = \frac{2s^2 + 280288s + 120880}{s^3 + 4014s^2 + 96040s + 320000}}$

$$\begin{aligned} i_L^{(t)} &= i_L^{(1)}(t) + i_L^{(2)}(t) \\ &= e^{-2005t} [17.6 \cosh(1985t) + 154 \sinh(1985t)] - 15.6 e^{-4t} \end{aligned}$$

(15)

KCL at $-$: $V_{in}(s) \left[\frac{1}{R_1} + G_1 s \right] + V_{out}(s) \left[\frac{1}{R_2} + G_2 s \right] = 0$

$$\Rightarrow H(s) = \frac{V_{out}(s)}{V_{in}(s)} = - \frac{\frac{1}{R_1} + G_1 s}{\frac{1}{R_2} + G_2 s} = - \frac{G_1 + G_1 s}{G_2 + G_2 s}$$

$$\begin{aligned} \text{If } C_2 = 0.2F \Rightarrow H(s) &= - \frac{G_1 + G_1 s}{G_2 + \frac{s}{5}} = - \frac{5G_1 s + 5G_1}{s + 5G_2} \\ &= - \frac{2s + 2}{s + 5} \end{aligned}$$

$$\Rightarrow \begin{cases} 5G_1 = 2 \\ 5G_1 = 2 \\ G_2 = 1 \end{cases} \Rightarrow \boxed{\begin{aligned} C_1 &= .4F \\ R_1 &= 2.5 \Omega \\ R_2 &= 1 \Omega \end{aligned}}$$

Step response:

$$\begin{aligned} V_{in}(t) &= u(t) \Rightarrow V_{in}(s) = \frac{1}{s} \\ V_{out}(s) &= H(s) V_{in}(s) = - \frac{1}{s} \left(\frac{2s + 2}{s + 5} \right) \end{aligned}$$

$$\Rightarrow \boxed{V_{out}(t) = \left[-\frac{2}{5} - \frac{8}{5} e^{-5t} \right] u(t)}$$

⑥ KCL at -

$$\frac{V_{in}(s)}{R_1} + [V_{in}(s) - V_{out}(s)] \left(\frac{1}{R_2} + C_s \right) = 0$$

$$\Rightarrow V_{in}(s) \left[\frac{1}{R_1} + \frac{1}{R_2} + C_s \right] = V_{out}(s) \left[\frac{1}{R_2} + C_s \right]$$

$$\Rightarrow H(s) = \frac{V_{out}(s)}{V_{in}(s)} = \frac{\left(\frac{1}{R_1} + \frac{1}{R_2} + C_s \right)}{\frac{1}{R_2} + C_s}$$

$$H(s) = \frac{s+3}{s+1}$$

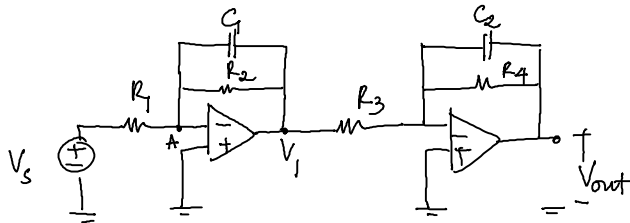
$$V_{in}(t) = 6te^{-3t}u(t) + 3e^{-t}u(t)$$

$$\Rightarrow V_{in}(s) = \frac{6}{(s+3)^2} + \frac{3}{s+1}$$

$$V_{out}(s) = H(s)V_{in}(s) = \frac{3s^2 + 24s + 33}{s^3 + 5s^2 + 7s + 3}$$

$$V_{out}(t) = [6e^{-t} - 3e^{-3t} + 6te^{-t}]u(t)$$

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KCL at node A :

$$\frac{V_s(s)}{R_1} + V_1(s) \left[\frac{1}{R_2} + C_s \right] = 0$$

$$\Rightarrow H_1(s) = \frac{V_1(s)}{V_s(s)} = -\frac{1/R_1}{1/R_2 + C_s} = -\frac{10^{-3}}{1/R_2 + 10^{-3}s}$$

$$H_1(s) = -\frac{1}{s + \frac{10^3}{R_2}} = -\frac{1}{s+4}$$

$$\Rightarrow R_2 = \frac{10^3}{4} = 250 \, \Omega$$

$$\begin{aligned} \text{Similarly } H_2(s) &= \frac{V_{out}(s)}{V_1(s)} = \frac{-1/R_3}{1/R_4 + C_2 s} = \frac{-10^{-3}}{10^{-3}s + \frac{1}{R_4}} = -\frac{1}{s + \frac{10^3}{R_4}} \\ &= -\frac{1}{s+2} \end{aligned}$$

$$\Rightarrow R_4 = \frac{1000}{2} = 500 \Omega$$

$$\therefore H(s) = H_1(s) H_2(s) = \frac{V_{out}(s)}{V_s(s)} = -\frac{1}{s+4} \cdot -\frac{1}{s+2}$$

$$\Rightarrow V_s(s) = V_s(s) \cdot \frac{1}{(s+4)(s+2)}$$

• impulse response : $V_s(s) = 1 \Rightarrow V_{out}(s) = \frac{1}{(s+4)(s+2)}$

$$\Rightarrow v_{out}(t) = \left(\frac{1}{2} e^{-2t} - \frac{1}{2} e^{-4t} \right) u(t)$$

• step response : $V_s(s) = \frac{1}{s} \Rightarrow V_{out}(s) = \frac{1}{s(s+4)(s+2)}$

$$\Rightarrow v_{out}(t) = \left(\frac{1}{8} - \frac{1}{4} e^{-2t} + \frac{1}{8} e^{-4t} \right) u(t)$$

⑥ KCL : $V_{in}(s) \left[\frac{1}{R_1} + C_1 s \right] = -V_1(s) \left[\frac{1}{R_2} + C_2 s \right]$

$$H_1(s) = \frac{V_1(s)}{V_{in}(s)} = -\frac{1/R_1 + C_1 s}{1/R_2 + C_2 s} = \frac{-20s - 25}{10s + 1}$$

• $V_1(s) \left[\frac{1}{R_3 + \frac{1}{C_3 s}} \right] = -V_{out}(s) \left[\frac{1}{R_4} + C_4 s \right]$

$$H_2(s) = \frac{V_{out}(s)}{V_1(s)} = -\frac{\frac{1}{R_3 + \frac{1}{C_3 s}}}{1/R_4 + C_4 s} = \frac{-20s}{20s^2 + 13s + 2}$$

$$H(s) = H_1(s) H_2(s) = \frac{400s^2 + 500s}{200s^3 + 150s^2 + 33s + 2}$$

- impulse response : $V_{out}(s) = 1 \cdot H(s)$

$$v_{out}(t) = \left[\frac{260}{9} e^{-\frac{t}{4}} - \frac{136}{9} e^{-\frac{2t}{5}} - \frac{46}{9} e^{-\frac{t}{10}} \right] u(t)$$

- step response : $V_{out}(s) = \frac{1}{s} H(s)$

$$\Rightarrow v_{out}(t) = \left[-\frac{800}{9} e^{-\frac{t}{4}} + \frac{340}{9} e^{-\frac{2t}{5}} + \frac{460}{9} e^{-\frac{t}{10}} \right] u(t)$$

```
%% hw4.
clc, clear
% 13.
%% a
syms s t;
C = .050;
R1 = 20;
Rin = 40;
Z1 = 1/(C*s + 1/R1);
f1 = 1/(s^2 + 2*s - 8);
vin = 3*t*exp(-2*t)*heaviside(t);
Vin = laplace(vin);
VR = Vin*(Z1/(Z1+Rin));
pretty(collect(Z1));
pretty(Vin);
pretty(collect(VR));
pretty(ilaplace(VR))
```

```
%ii.
Vc0 = -12;
Z = 1/(C*s + 1/R1 + 1/Rin);
VR = Vc0*C*Z;
pretty(collect(Z));
pretty(collect(VR));
pretty(ilaplace(VR));
```

```
% b
syms s t
vc0 = 18;
C = .025;
lin = 6/(s^2 + 2*s);
l1 = C*vc0*C*s/(C*s + 1/10 + 1/40);
lc = l1 - C*vc0;
pretty(collect(lc));
pretty(ilaplace(lc))
lc = lin * C*s/(C*s + 1/10 + 1/40);
pretty(collect(lc));
pretty(ilaplace(lc))
```

```
disp('=====');
disp('14. ');
%%14
%a.
L1 = .4;
L2 = .05;
R = 2;
Vin = 4/(s+4) - 2/(s+2);
```

```

Z1 = 1/(1/(L2*s) + 1/R);
V1 = Vin*Z1/(Z1 + L1*s);
IL = V1/(L2*s);
pretty(collect(V1));
pretty(collect(IL));
pretty(ilaplace(IL))
disp('14.b');
%b.
R = 20;
C = .005;
L = .005;
ILO = 2; VCO = 1;
Z1 = 1/(C*s + 1/R);
IL = (C*VCO*Z1 + L*ILO)/(Z1 + R + L*s);
pretty(collect(Z1));
pretty(collect(IL));
pretty((ilaplace(IL)))
lin = (7*s + 3)/(s+4);
IL2 = lin*Z1/(Z1 + R + L*s);
pretty(collect(Z1));
pretty(collect(IL2));
pretty((ilaplace(IL2)))
IL = IL + IL2;
pretty(collect(IL));
pretty((ilaplace(IL)))

disp('=====');
disp('15. ');
%% 15
% a
pretty((ilaplace(-1/s/(s+5)*(2*s+2))))
% b
C = .1;
R1 = 5;
R2 = 10;
H = (1/R1 + 1/R2 + C*s)/(1/R2 + C*s);
vin = 6*t*exp(-3*t) + 3*exp(-t);
pretty(collect(H));
V = laplace(vin);
pretty((V));
Vout = H*V;
pretty(collect(Vout));
pretty((ilaplace(Vout)))

disp('=====');
disp('16 a');
%%16
%a.
Vout = 1/(s+4)/(s+2);
pretty((ilaplace(Vout)))
pretty((ilaplace(Vout/s)))
disp('16 b');
%b
R1 = 40; R2 = 1000; R3 = 500; R4 = 2000;
C1 = .02; C2 = .01; C3 = .005; C4 = .002;
H1 = -(1/R1 + C1*s)/(1/R2 + C2*s);
H2 = -1/(R3 + 1/C3/s)/(1/R4 + C4*s);
pretty(collect(H1));
pretty(collect(H2));
H = H1*H2;
pretty(collect(H));
pretty((ilaplace(H)))
pretty((ilaplace(H/s)))

```