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# Three issues with shared memory programming

- We would like to execute programs whose different "parts" share data
- This raises three issues
  - I. If operations are not commutative they must execute them in the order specified by the program
  - 2. If operations are commutative they can execute in any order as long as one operation appears to execute after the other has finished
  - 3. Loads of variable values from memory must get the last value written
- We will now discuss these in more detail

# Barriers and loop distribution to enforce orders

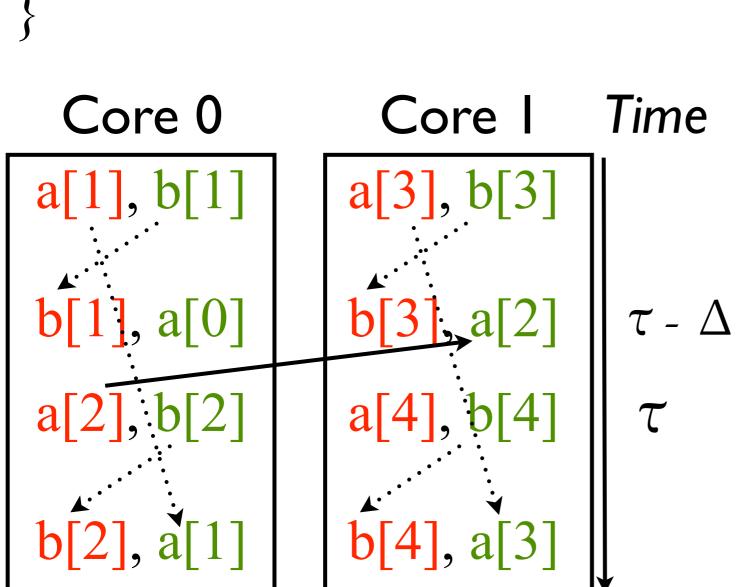
### Consider the program

```
for (int i = 1; i < 4; i++) {
a[i] = b[i] + ...;
b[i] = a[i-1]
```

Orders that must be honored are shown as arrows

### Execute on two cores

```
for (int i = 1; i < 4; i++) {
    a[i] = b[i] + . . .;
    b[i] = a[i-1]
}
```



Dashed orders enforced by sequential execution within a core

a[2] written in Core
0 must travel back in
time to reach read of
a[2]. Need to force
this order

# First step Distribute the loop

```
for (int i = 1; i < 4; i++) {
    a[i] = b[i] + . . .;
}
for (int i = 1; i < 4; i++) {
    b[i] = a[i-1]
}</pre>
```

Distribute the loop over the statements in the loop.

### Try running this on two cores

```
for (int i = 1; i < 4; i++) {
 a[i] = b[i] + \ldots;
                                  In a perfect world, this
                                           happens
for (int i = 1; i < 4; i++) {
 b[i] = a[i-1]
                                              Time
                                Core I
            Core 0
                              a[3], b[3]
```

### Try running this on two cores

```
for (int i = 1; i < 4; i++) {
                                     In the world that
 a[i] = b[i] + \ldots;
                                 exists, this can happen
                                Core I
                                              Time
for (int i = 1; i < 4; i++) {
 b[i] = a[i-1]
            Core 0
          a[1], b[1]
```

### A barrier is needed

```
for (int i = 1; i < 4; i++) {
  a[i] = b[i] + \dots;
                     Time
 barrier
for (int i = 1; i < 4; i++) {
                                      Core I
                                                   Time
  b[i] = a[i-1]
                 Core 0
               a[1], b[1]
barrier
```

### Barrier semantics

- Given a barrier b in each thread T
  - As each thread reaches the barrier, it enters it and waits until all threads have entered the barrier
  - When all threads have entered the barrier, all threads can proceed past the barrier
- Dangers in barriers
  - If one or more threads don't enter the barrier, the threads in it are stuck!

# Note: not all loops can be distributed!

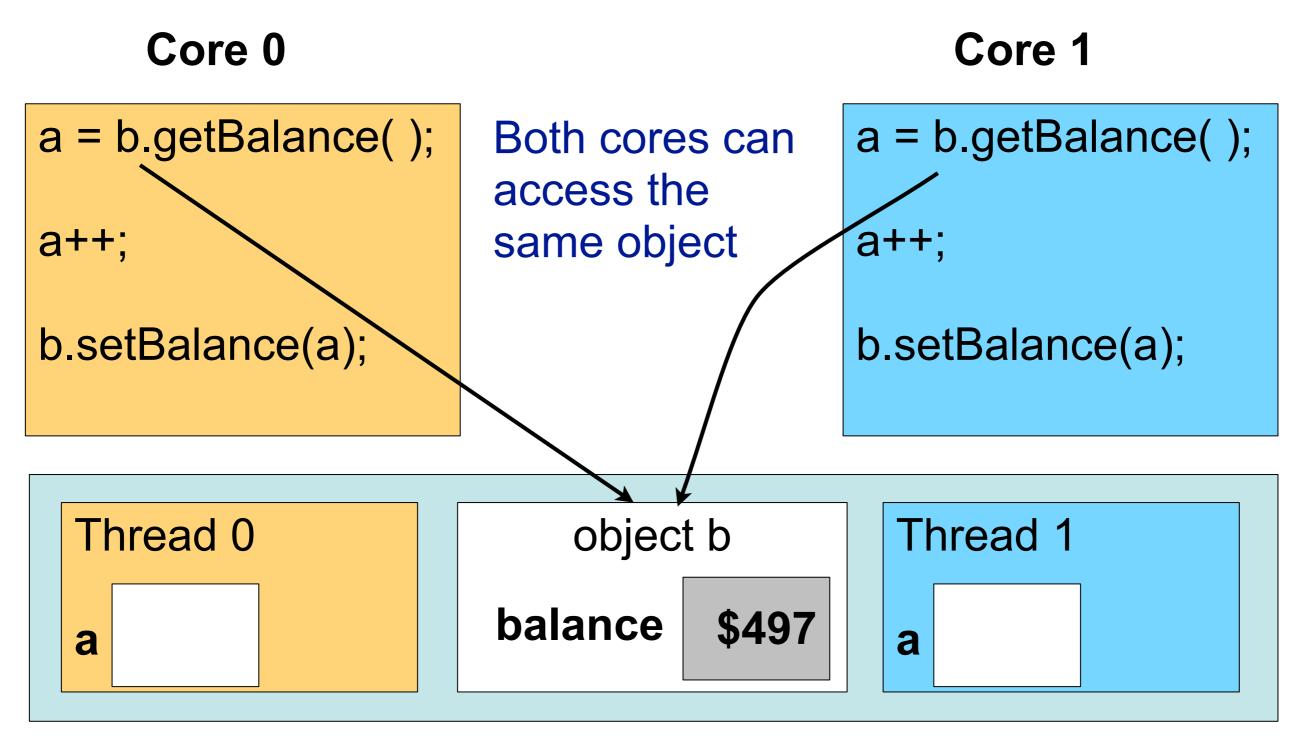
```
for (int i = 1; i < 4; i++) {
  a[i] = (b[i-1]) + \dots;
  b[i] = a[i-1]
     a[1] = b[0] + \dots;
    (b[1]) = a[0]
     a[2] = (b[1]) + \dots;
     b[2] = a[1]
     a[3] = b[2] + \dots;
     b[3] = a[2]
     a[4] = b[3] + \dots;
     b[4] = a[3]
```

```
for (int i = 1; i < 4; i++) {
 a[i] = b[i-1] + \dots;
                       Illegal
for (int i = 1; i < 4; i++) {
 b[i] = a[i-1]
                           The
 a[1] = b[0] + \dots;
 a[2] = (b[1]) + \dots;
                          order of
 a[3] = b[2] + \dots
                          reads
 a[4] = b[3] + \dots;
                           and
 (b[1]) = a[0]
                           writes to
 b[2] = a[1]
 b[3] = a[2]
                           changes
 b[4] = a[3]
```

# Atomicity Useful with commutative operations

- An operation is atomic if it executes as if nothing else happens to the state of the memory used by the operation during the execution of the instruction
- Shared memory programming models give synchronization instructions that allow us to specify that a collection of operations should be executed atomically
- If operations that can commute are executed atomically, they can be executed in any order and give the correct outcome
- We will now look at an example that shows the importance of atomic execution

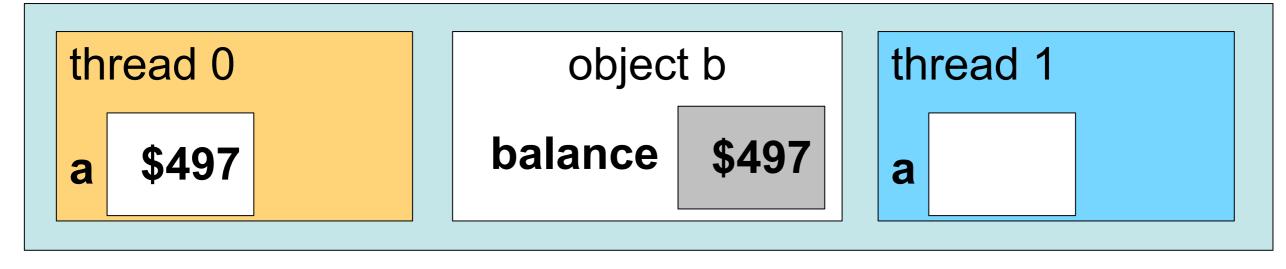
# Atomicity -- operations execute as though no changes are made to their operands during executions



**Program Memory** 

```
a = b.getBalance();
a++;
b.setBalance(a);
```

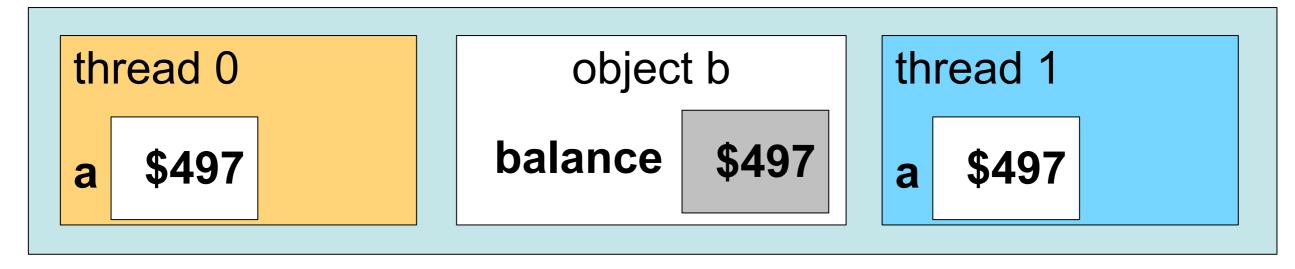
```
a = b.getBalance();a++;b.setBalance(a);
```



**Program Memory** 

```
a = b.getBalance();
a++;
b.setBalance(a);
```

```
a = b.getBalance();
a++;
b.setBalance(a);
```



**Program Memory** 

```
a = b.getBalance();
a++;
b.setBalance(a);
```

```
a = b.getBalance();
a++;
b.setBalance(a);
```



**Program Memory** 

```
a = b.getBalance();a++;b.setBalance(a);
```

The end result probably should have been \$499.
One update is lost.

```
a = b.getBalance();
a++;
b.setBalance(a);
```



**Program Memory** 

#### synchronization enforces atomicity

core 0 core 1

```
synchronized(b) {
  a = b.getBalance();
  a++;
  b.setBalance(a);
}
```

Make them atomic using synchronized

```
synchronized(b) {
  a = b.getBalance();
  a++;
  b.setBalance(a);
}
```

```
thread 0
balance $497

thread 1
a
```

**Program Memory** 

```
synchronized(b) {
  a = b.getBalance();
  a++;
  b.setBalance(a);
}
```

```
synchronized(b) {
  a = b.getBalance();
  a++;
  b.setBalance(a);
}
```

```
thread 0
balance $497

thread 1
a
```

```
synchronized(b) {
  a = b.getBalance();
  a++;
  b.setBalance(a);
}
```

```
synchronized(b) {
  a = b.getBalance();
  a++;
  b.setBalance(a);
}
```

```
thread 0
balance $498

thread 1
a $498
```

```
synchronized(b) {
  a = b.getBalance();
  a++;
  b.setBalance(a);
}
```

```
synchronized(b) {
  a = b.getBalance();
  a++;
  b.setBalance(a);
}
```

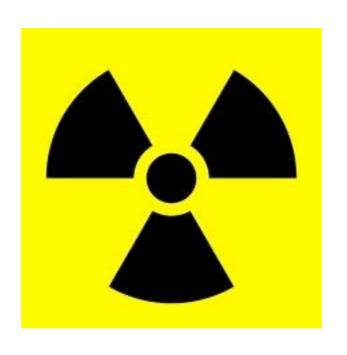
```
thread 0
a $498
balance $498
thread 1
a $498
```

```
synchronized(b) {
  a = b.getBalance();
  a++;
  b.setBalance(a);
}
```

```
synchronized(b) {
  a = b.getBalance();
  a++;
  b.setBalance(a);
}
```

```
thread 0
a $499
balance $499
thread 1
a $498
```

# Ensuring the last value written is read A short architectural overview



Warning: gross simplifications to follow

### Multiprocessor (shared memory multiprocessor)

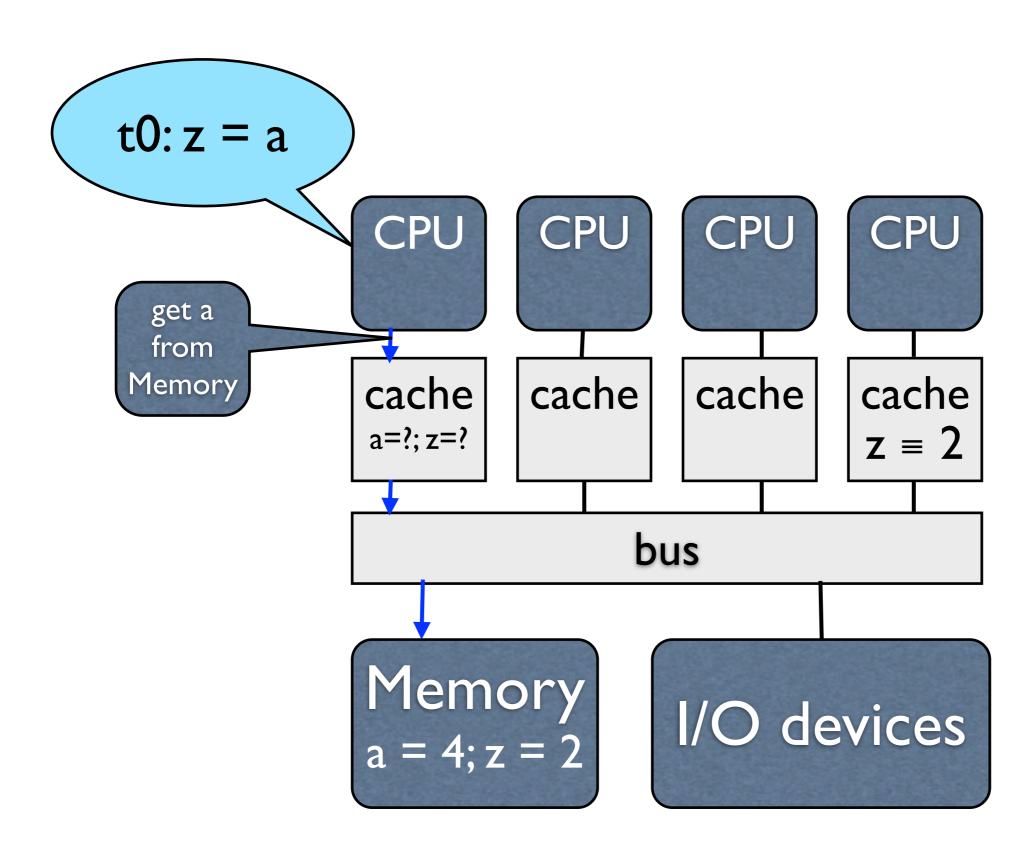
- Multiple CPUs with a shared memory (or multiple cores in the same CPU)
- The same address on two different processors points to the same memory location
  - Multicores are a version of this
- If multiple processors are used, they are connected to a *shared bus* which allows them to communicate with one another via the shared memory
- Two variants:
  - Uniform memory access: all processors access all memory in the same amount of time
  - Non-uniform memory access: different processors may see different times to access some memory.

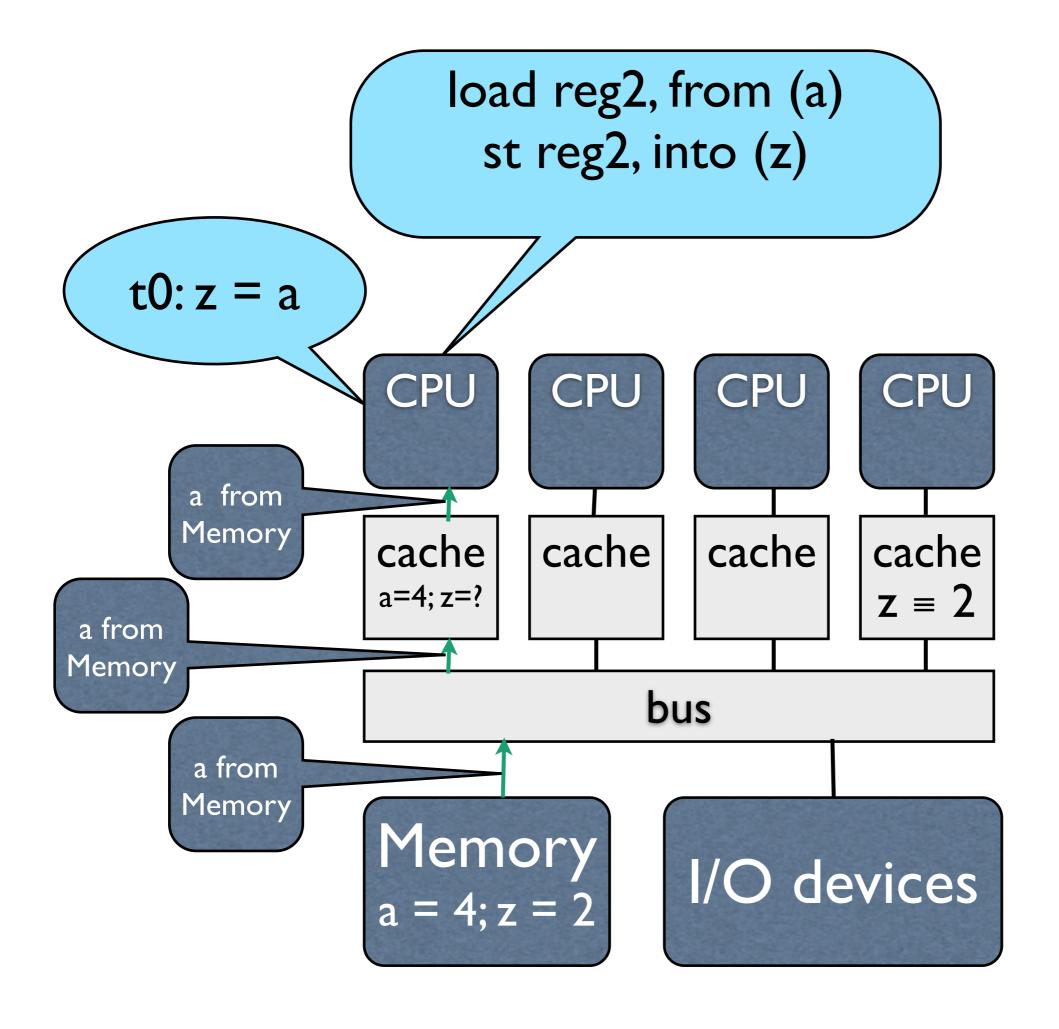
### Memory hierarchies

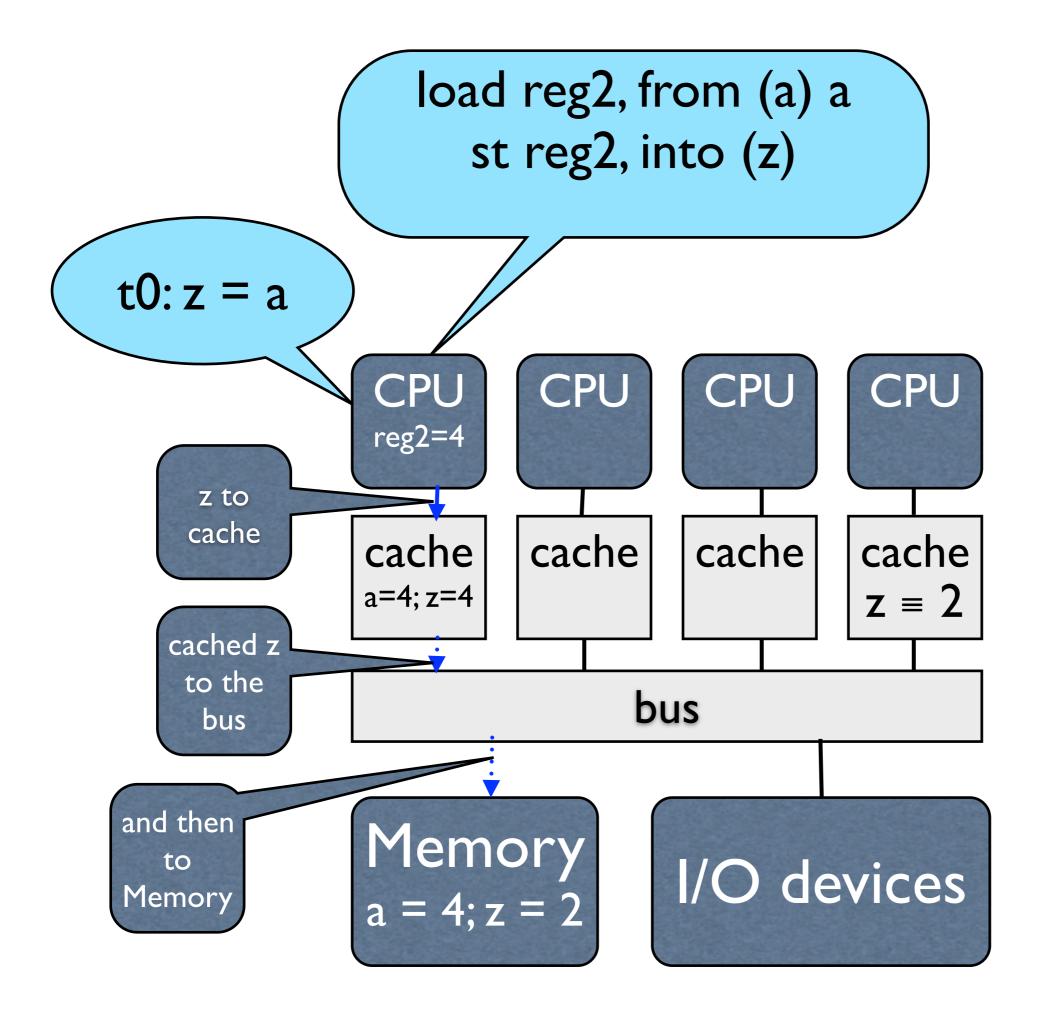
- A computer typically has a hierarchy of memory
  - Larger memories are slower, smaller memories are faster
  - From slow to fast a typical hierarchy is
    - disk 33 65 million cycles, terabytes;
    - ram 180 cycles, megabytes;
    - 13 cache 36 cycles, 2 to 20MB;
    - 12 cache (12 cycles, 256KB;
    - II cache (4 cycles, 64 KB;
    - registers (I cycles, I word to a quad-word)

### Coherence is needed

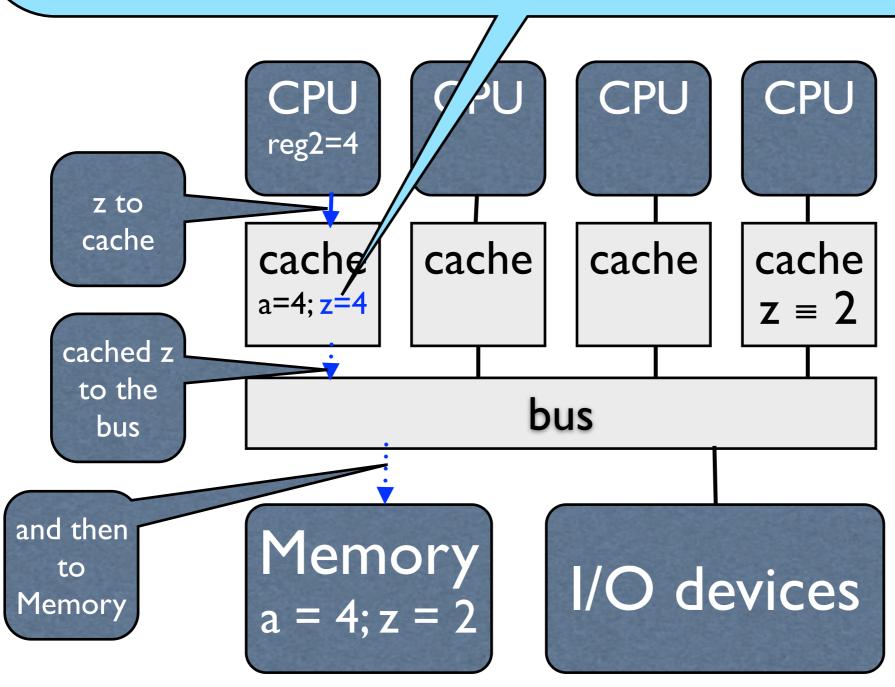
t0: z = a**CPU** CPU cache cache cache cache  $z \equiv 2$ bus Memory a = 4; z = 2I/O devices

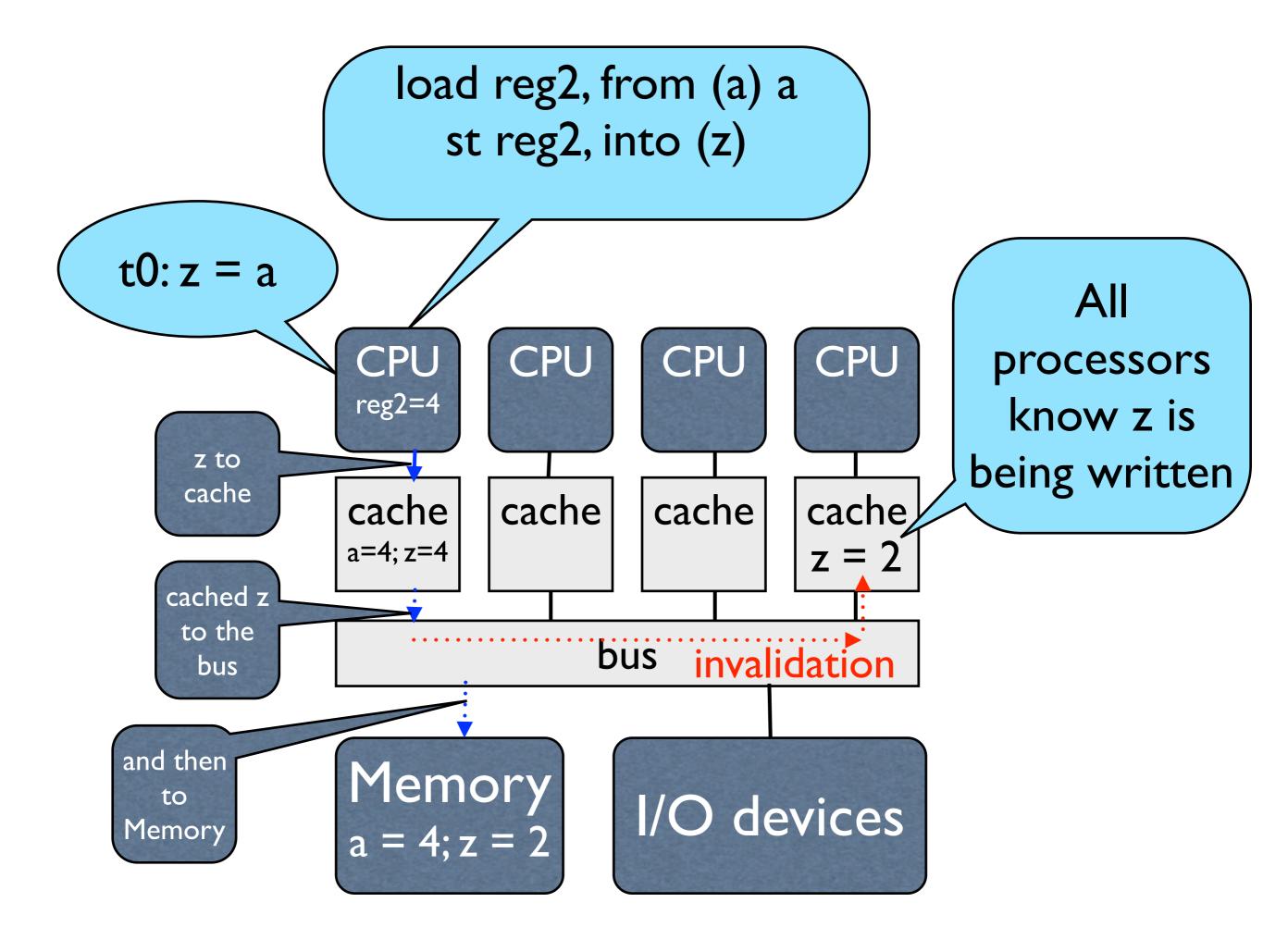


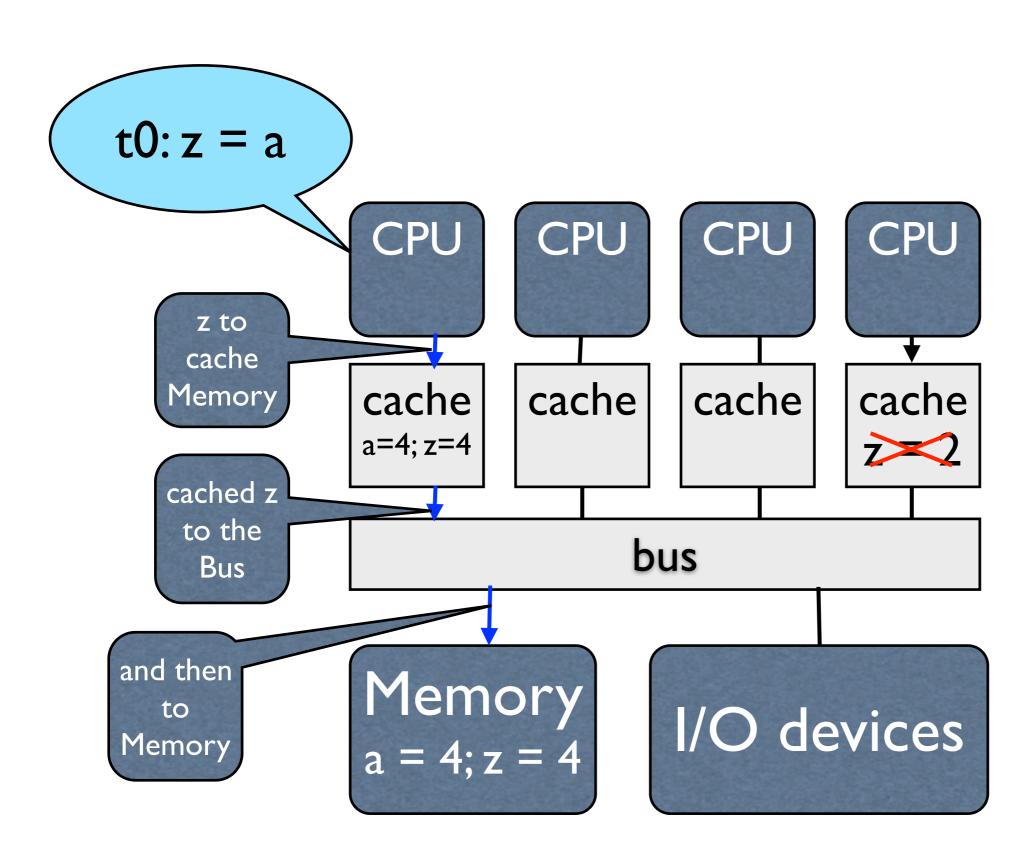


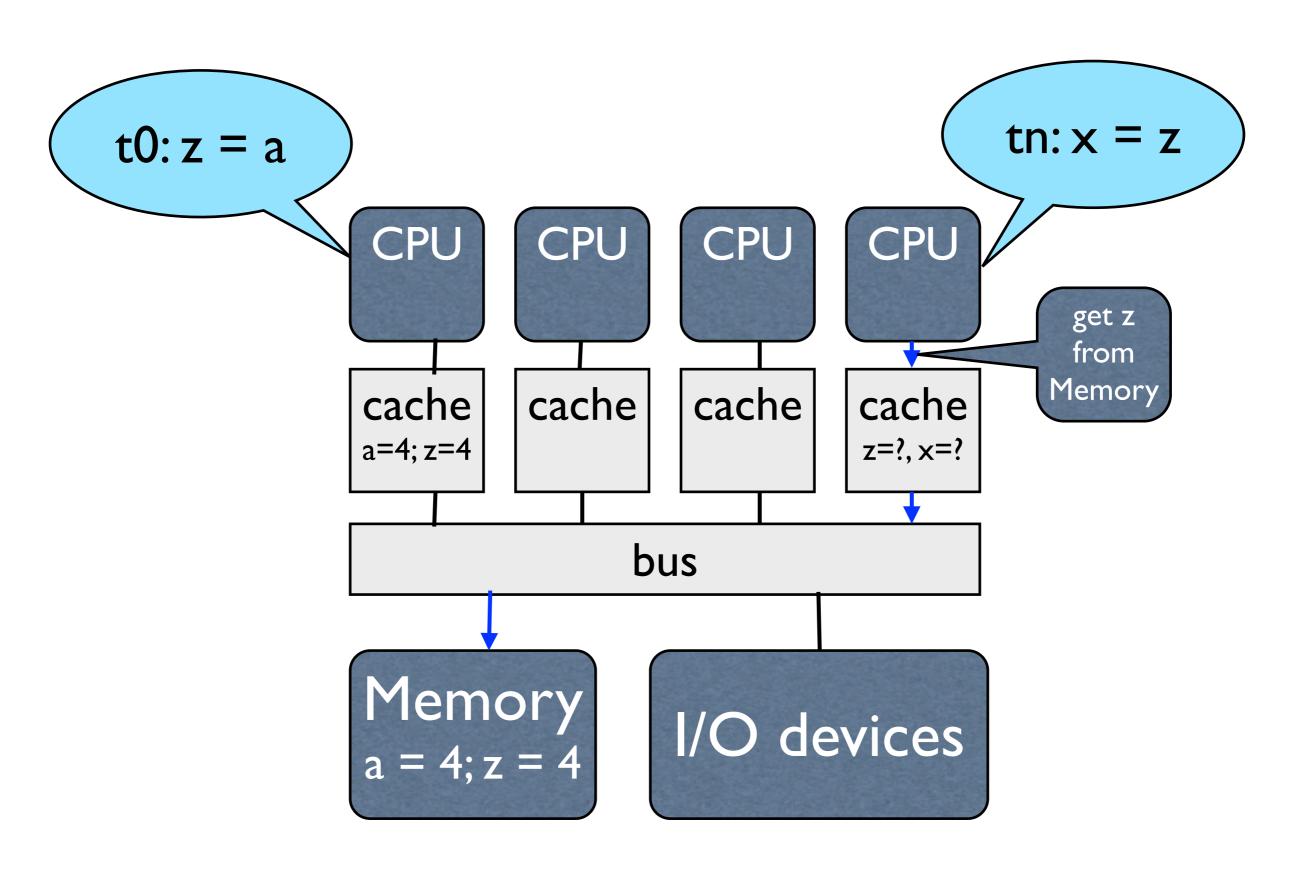


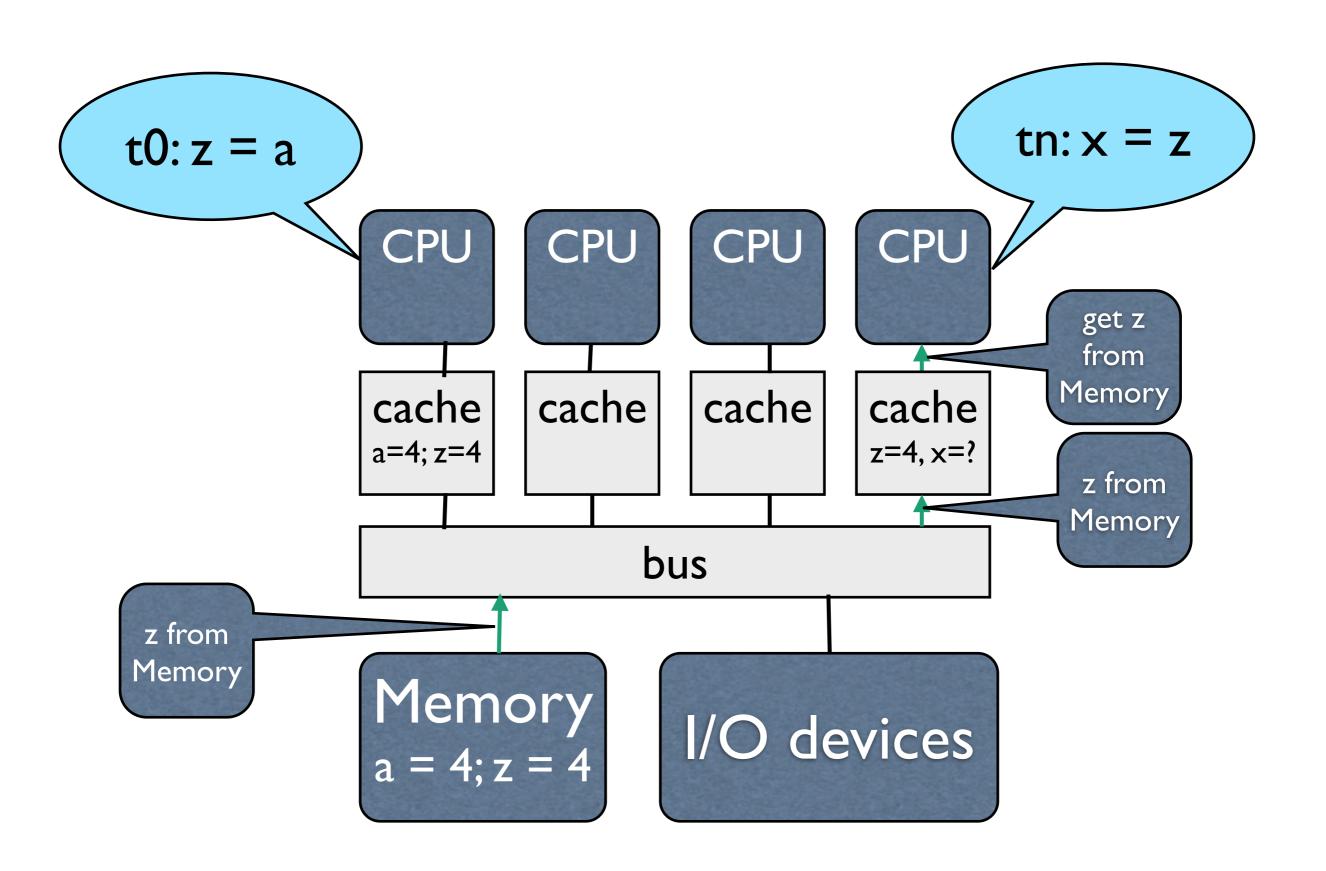
Writes are special. Many processors can read a variable (memory location) with no problem. Only one should be writing it. If many processors simultaneously write a variable values will be lost.

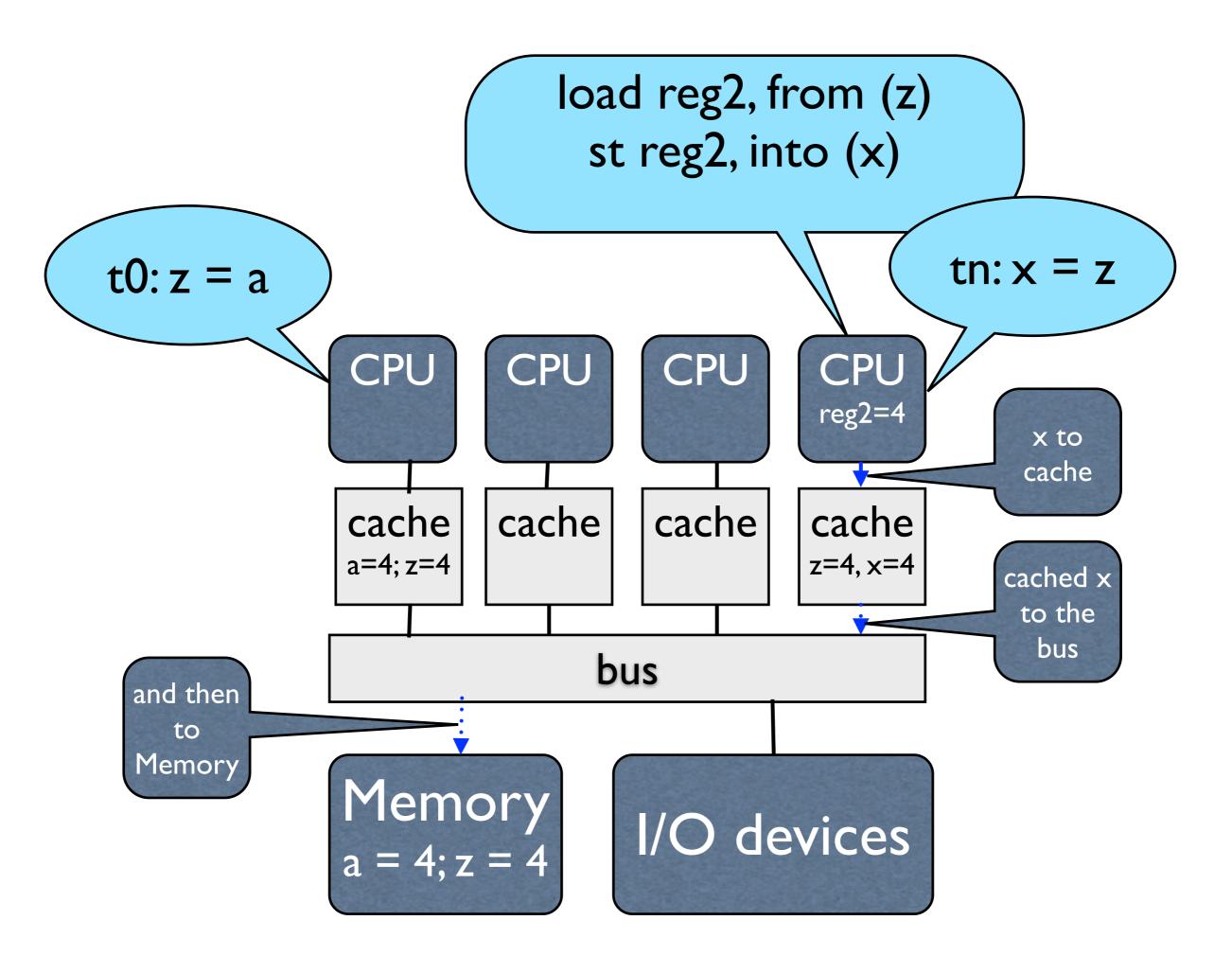


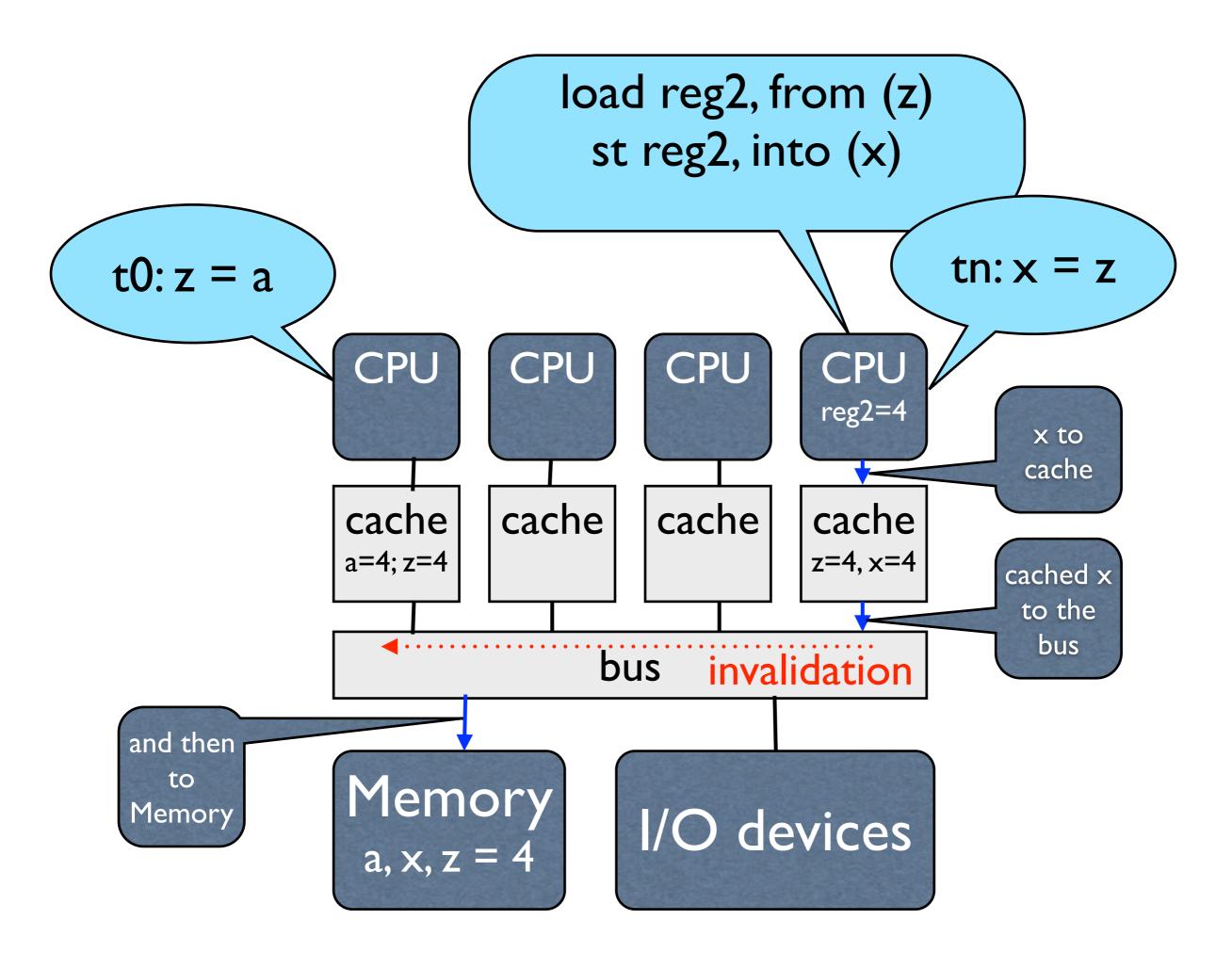




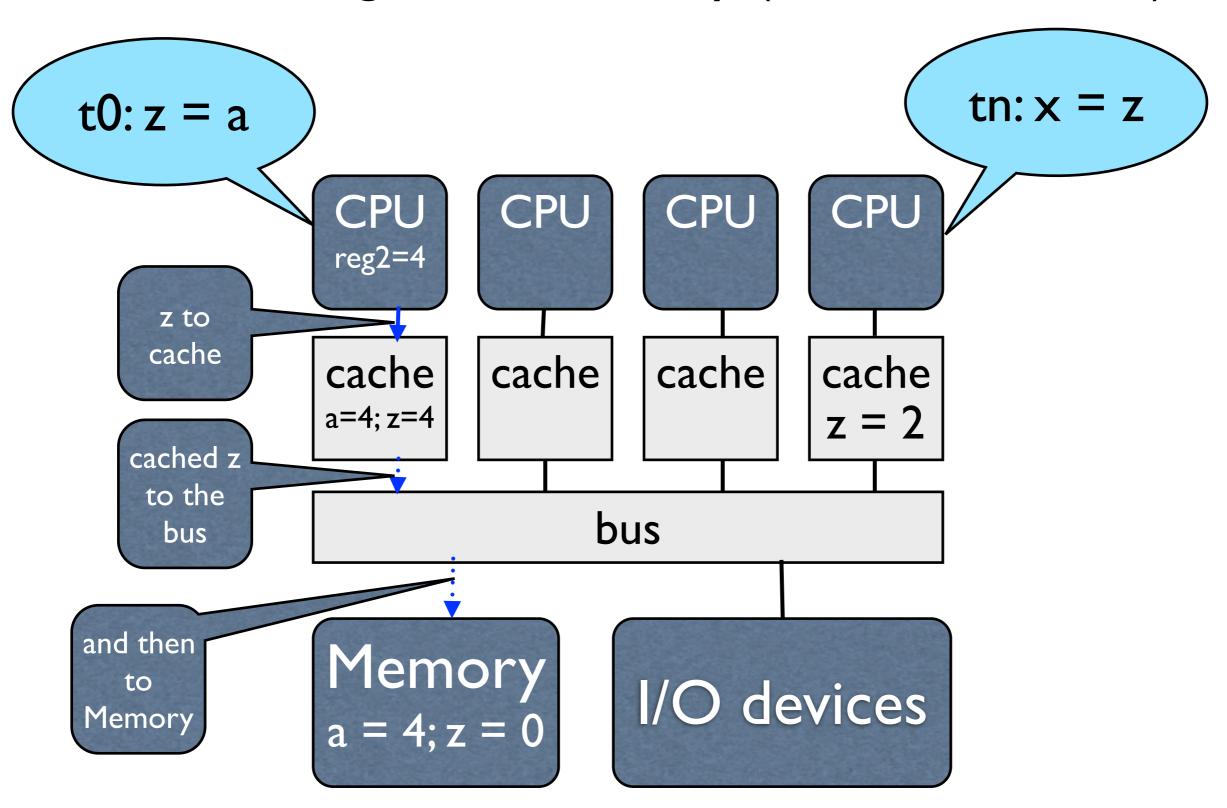




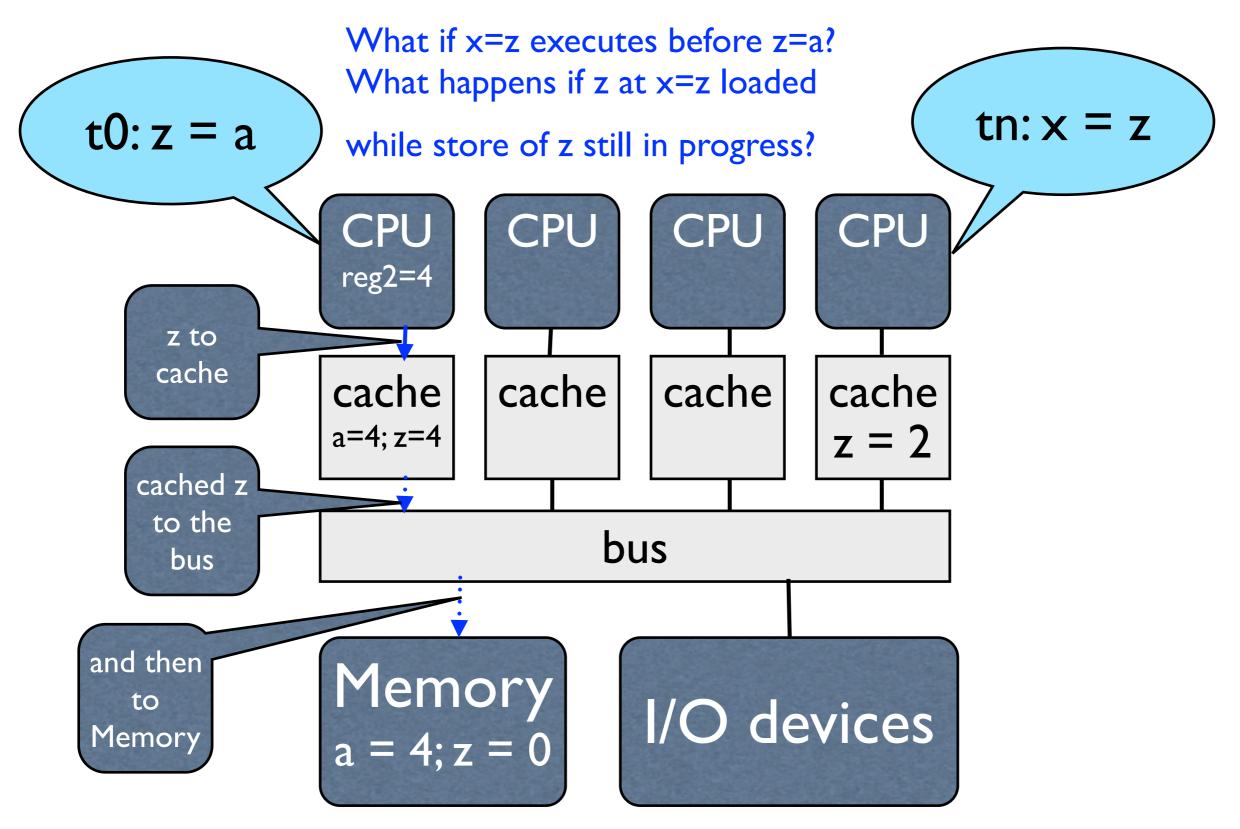




Hardware makes sure a core/processor reads the latest value assigned to memory (cache coherence)



### Software has to make sure operations occur in the right order across threads/processors



# Shared memory programming models provide the ability to write correct shared memory programs

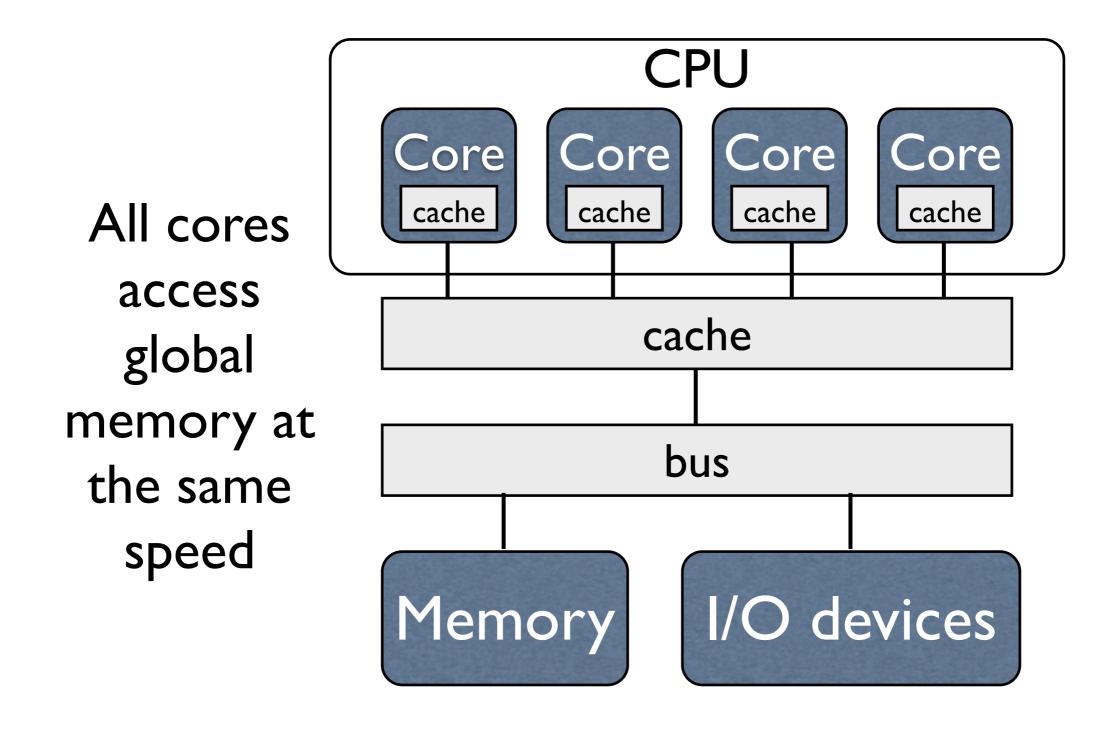
- Can either be a language, language extension, library or a combination
  - Java is a language and associated virtual machine that provides runtime support
  - OpenMP is a language extension (for C/C++ and Fortran) and an associated library (or runtime)
  - Pthreads (or Posix Threads) is a library with C/C
     ++ and Fortran bindings

# The slide that was here moved

 A Uniform Memory Access shared memory machine

# Different kinds of shared memory machines

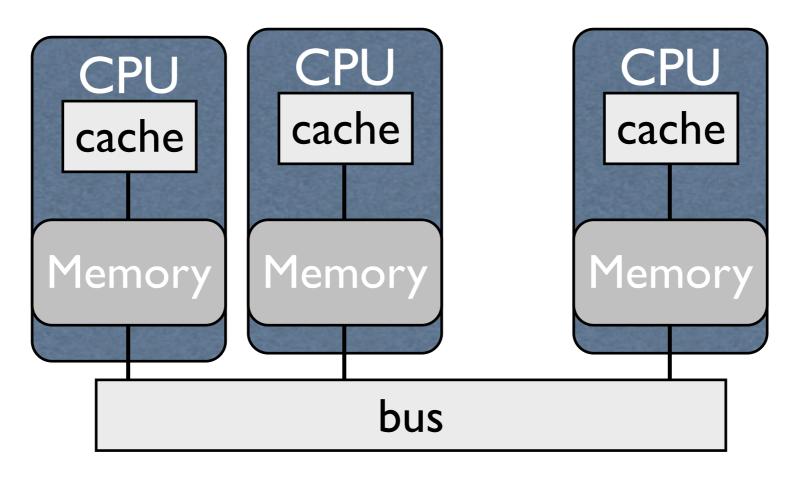
### Multicore machines usually share at least one *level* of cache



## A Uniform Memory Access shared memory machine

CPU CPU CPU CPU All processors access cache cache cache cache global memory at bus the same speed I/O devices Memory

# A NUMA shared memory machine



Processors will access their memory faster than their neighbors memory. Software and special hardware gives the illusion of a large shared address space.

## A programming model must provide a way of specifying

- what parts of the program execute in parallel with one another
- how the work is distributed across different cores
- the order that multiple reads and writes to the same memory will take place
- that a sequence of accesses to a variable will occur atomically or without interference from other threads.
- **And,** ideally, it will do this while giving good performance and allowing maintainable programs to be written.

#### OpenMP

- Open Multi-Processor
  - targets multicores and multi-processor shared memory machines
  - An open standard, not controlled by any manufacturer
- Allows loop-by-loop & region-by-region parallelization of sequential programs.

#### What executes in parallel?

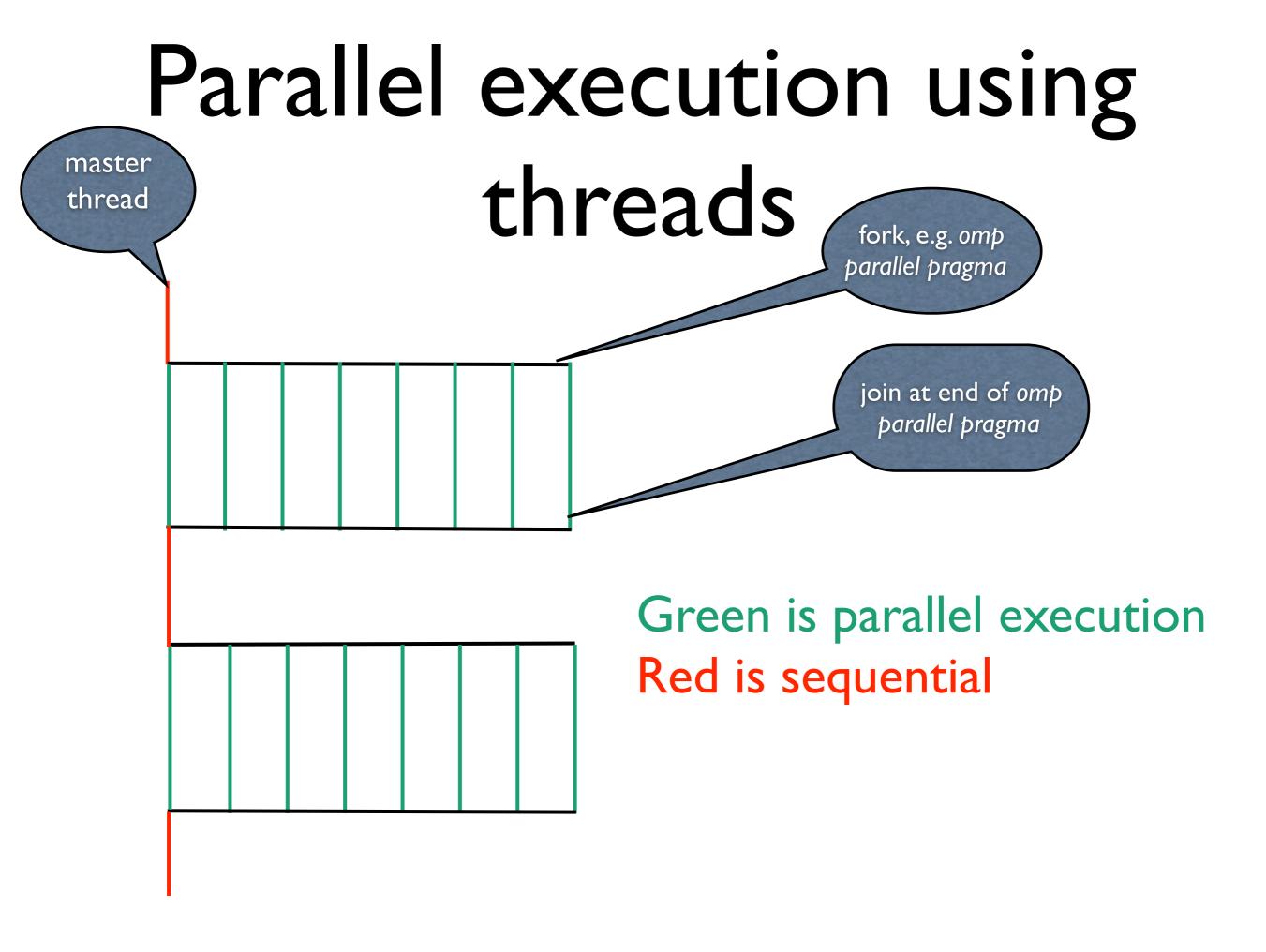
```
c = 57.0;
for (i=0; i < n; i++) {
  a[i] = c[i] + a[i]*b[i]
}</pre>
```

```
c = 57.0
#pragma omp parallel for
for (i=0; i < n; i++) {
    a[i] = c[i] + a[i]*b[i]
}</pre>
```

- pragma appears like a comment to a non-OpenMP compiler
- pragma requests parallel code to be produced for the following for loop

# Threads and processes The building blocks of shared memory programs

- Threads and processes are typically operating system entities and concepts
- A process has its own address space and owns a typically virtualized copy of the machine when executing
  - processes may own one or more threads
- A thread shares its address space with it's owning process and all other threads owned by the same process
  - each thread has its own copy of registers
  - local variables can be created that are accessible only by the thread
  - threads are the fundamental building block of parallel shared memory programs



#### How is the work distributed across different cores?

```
c = 57.0
#pragma omp parallel for schedule(static)
for (i=0; i < n; i++) {
   a[i] = c[i] + a[i]*b[i]
}</pre>
```

- Split the loop into chunks of contiguous iterations with approximately *t/n* iterations per chunk
- Thus, if 4 threads and 100 iterations, thread one would get iterations 0:24, thread 2 25:49, and so forth
- Other scheduling strategies supported.

### The order that reads and writes to memory occur

```
#pragma omp parallel for schedule(static)
for (i=0; i < n; i++) {
    a[i] = c[i] + a[i]*b[i]
}

#pragma omp parallel for schedule(static)
for (i=0; i < n; i++) {
    a[i] = c[i] + a[i]*b[i]
}
```

- Within an iteration, access to data appears in-order
- Across iterations, no order is implied. Races lead to undefined programs
- Across loops, an implicit barrier prevents a loop from starting execution until all iterations and writes (stores) to memory in the previous loop are finished
- Parallel constructs execute after preceding sequential constructs finish

### Relaxing the order that reads and writes to memory occur

```
#pragma omp parallel for schedule(static) nowait
for (i=0; i < n; i++) {
    a[i] = c[i] + a[i]*b[i]
}
#pragma omp parallel for schedule(static)
for (i=0; i < n; i++) {
    a[i] = c[i] + a[i]*b[i]
}</pre>
```

The *nowait* clause allows a thread to begin executing its part of the loop as soon as it finishes its part of the preceding computation

Note, however, that the barrier is associated with the first loop.

### Accessing variables without interference from other threads -- forcing atomicity

```
#pragma omp parallel for
for (i=0; i < n; i++) {
    a = a + b[i]
}</pre>
```

Dangerous -- all iterations are updating a at the same time -- a race (or data race).

```
#pragma omp parallel for
for (i=0; i < n; i++) {
#pragma omp critical
    a = a + b[i];
}</pre>
```

Stupid but correct -- critical pragma allows only one thread to execute the a = statement at a time. Is very inefficient!

#### OpenMP in more detail