Question 1. To solve $\operatorname{Median}(S)$ using $\operatorname{Select}(S,k)$ is trivial: Simply call $\operatorname{Select}(S,|S|/2)$ and return its answer as the answer to $\operatorname{Median}(S)$. To solve $\operatorname{Select}(S,k)$ using $\operatorname{Median}(S)$ first call $\operatorname{Median}(S)$ and let x be the element it returns. Let $S_{<}$ denote the subset of S consisting of those elements of S that are < x, and let $S_{>}$ denote the set consisting of those elements of S that are > x; obviously S_{\leq} and $S_{>}$ can be computed in O(|S|) time (by going through S once). If k = |S|/2 then we return x as the answer. If k < |S|/2 we recursively call $\operatorname{Select}(S_{<},k)$ and return its answer. Otherwise (i.e., if k > |S|/2) we recursively call $\operatorname{Select}(S_{>},k-1-|S|/2)$ and return its answer. A linear-time algorithm for $\operatorname{Median}(S)$ implies that the recurrence for the time of $\operatorname{Select}(S,k)$ is

 $T(n) = c_0$ if $n \leq \text{some constant } n_0$

$$T(n) \le T(n/2) + cn \text{ if } n > n_0.$$

Since 0.5 < 1, the solution to this recurrence is T(n) = O(n) (as explained in class).

Question 2. The main idea is to compare the median element of A to the median element of B: If the former is greater, then the elements in the larger half of A can be thrown away (for being too big – their ranks exceed n), and the elements in the smaller half of B can also be thrown away (for being too small – their ranks are surely smaller than n); in other words we recurse on the smaller half of A and the larger half of B. If it is the median of B that is greater than the median of A then we simply interchange the roles of A and B in the previous sentence. The reason it is correct to recurse in this way is that the element we are searching for has, in the recursive call, "lost" n/2 elements smaller than it and n/2 elements greater than it (the halves of A and B that were "thrown away"), and therefore its rank in the reduced-size problem is n - (n/2) = n/2. A more formal exposition is given below.

To simplify the exposition, assume that $A[1] < A[2] < \cdots < A[n]$ and $B[1] < B[2] < \cdots < B[n]$, that n is a power of 2, and that the elements of A and B are distinct, i.e., $A[i] \neq B[j]$ for all i, j. This question is about designing an efficient algorithm for finding the n-th smallest of the 2n combined elements of A and B.

In the recursive algorithm given below, we use the notation A[i:j] to denote the subarray of A from positions i to j (with $i \leq j$). The algorithm maintains the invariant that the sizes of the relevant subarrays are equal, and are powers of two (i.e., j-i+1=l-k+1=a power of two). The algorithm is supposed to return the (j-i+1)th smallest element in the union of A[i:j] and B[k:l]; for computing the n-th smallest of the 2n combined elements of A and B, it is simply called with Select(A[1:n], B[1:n]).

Algorithm Select(A[i:j], B[k:l])

- 1. If i = j (hence k = l) then return $\min\{A[i], B[k]\}$, otherwise continue to the next step.
- 2. Compare A[(j+i-1)/2] to B[(l+k-1)/2]. Assume without loss of generality that A[(j+i-1)/2] > B[(l+k-1)/2] (otherwise interchange the roles of A and B in what follows).

3. Return Select(A[i':j'], B[k':l']) where i' = 1 + (j+i-1)/2, j' = j, k' = k, l' = (l+k-1)/2.

The algorithm's time complexity satisfies the recurrence:

T(1) = c where c is a constant and, for n > 1:

T(n) = T(n/2) + d where d is a constant.

The above recurrence is similar to the one for binary search, and has a solution $T(n) = O(\log n)$.

Question 3. Let $S_i = \{I_1, \ldots, I_i\}$, i.e., S_i is the subset of S none of whose intervals extends to the right of r_i . Let C_i be a maximum-weight acceptable subset of S_i that contains interval I_i ; in other words the intervals of C_i have maximum total weight subject to the constraints of being nonoverlapping and including I_i . Note that if we had all of $\{C_1, C_2, \ldots, C_n\}$ then we could compute the answer in linear time by simply choosing the largest of the C_i s. Hence it suffices to compute all the C_i s.

Observe that $C_1 = w_1$ and that, for i > 1, we have

$$C_i = w_i + \max_{k: r_k < l_i} C_k$$

which immediately implies an $O(n^2)$ time algorithm for computing all the C_i s (by computing each of C_1, C_2, \ldots, C_n in that order, according to the above equation).

Question 4. For i = 0, 1, ..., (n/k) - 2, let S_i denote the subarray of A that has length 2k and begins at the (ik + 1)th position in A. The algorithm consists of sorting (in that order) the subarray of A called S_0 , then the subarray called S_1 (whose contents have of course changed as a result of sorting S_0), ..., then the portion called $S_{(n/k)-2}$. Correctness of this is seen by observing that, after sorting S_0 , the leftmost k items of A are at their final position in the sorted version of A (this follows from the property). The same is true for the leftmost k items of each S_i after we are done sorting it. The time for sorting each S_i is $O(k \log k)$, and since this must be done (n/k) - 1 times the overall time is $O(n \log k)$.