Sharing Main Memory, Segmentation (cont)

ECE595
Feb 10

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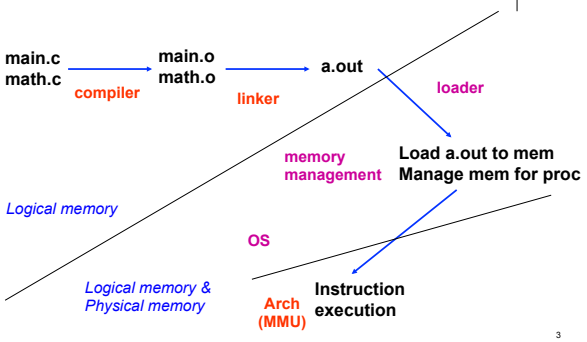
Outline

- Segmentation
- External fragmentation & Generic dynamic allocation problem
- OS implementation of segmentation

Connecting the dots

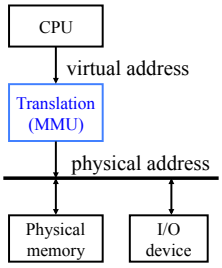


3. Dynamic memory relocation

- Instead of changing the address of a program before it's loaded, change the address dynamically *during every reference*
  - Under dynamic relocation, each program-generated address (called a *logical address* or *virtual address*) is translated in hardware to a *physical* or *real address*

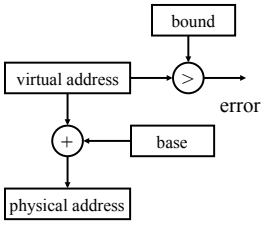
Can this be done in software?

Translation overview



- Actual translation is in hardware (MMU)
- Controlled in software
- CPU view
  - what program sees, virtual addresses
- Memory view
  - physical memory addresses

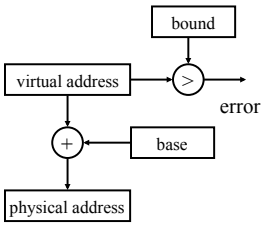
3.1 Base and bound



- Built in Cray-1 (1976)
- A program can only access physical memory in [base, base+bound]
- On a context switch: save/restore base, bound registers
- Pros:
  - simple, fast, cheap
  - Can relocate segment

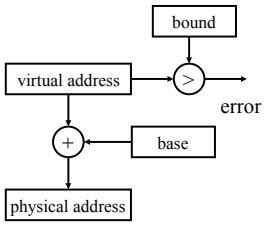
All problems in computer science can be solved by another level of indirection.
David Wheeler

3.1 Base and bound



- The essence:
  - A level of indirection
  - Phy. Addr = Vir. Addr + base
- How to relocate segment in physical memory?
  - From Base 1 to Base 2?

3.1 Base and bound



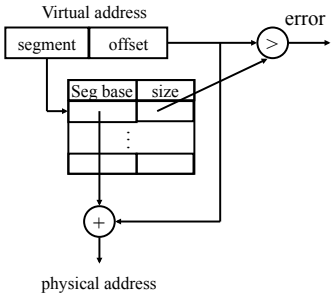
- Cons:
  - Only one segment
  - How can two processes share code while keeping private data areas (shared editors)?

What have we achieved?

- 4 drawbacks

1. No protection
2. Low utilization -- Cannot relocate dynamically
   - Cannot do anything about holes
3. No sharing -- Single segment per process
   - Cannot share part of process address space (e.g. text)
4. Entire address space needs to fit in mem
   - Need to swap whole, very expensive!

3.2 Multiple Segments



- Have a table of (seg, size)
- Further protection: each entry has (nil, read, write, exec)
- On a context switch: save/restore the table (or a pointer to the table) in kernel memory

How does this allow 2 processes to share code segment?

Segmentation example

text segment [0x0000, 0x04B0]

foo:

019A: LD R1, 15DC
01C2: jmp 01F4
01E0: call 0320
01F4: X:

bar procedure

0320: bar:

Data segment [0x1000, 0x16A0]

15DC: _Y:

2-bit segment number, 12-bit offset

Segment	Base	Bounds	RW
0	4000	4B0	10
1	0	6A0	11
2	3000	FFF	11
3	--	--	00

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➔ Where is 01F4 in physical memory?

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➔ Where is 15DC in physical memory?

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➔Suppose SP is initially 265C. Where is it in physical mem?

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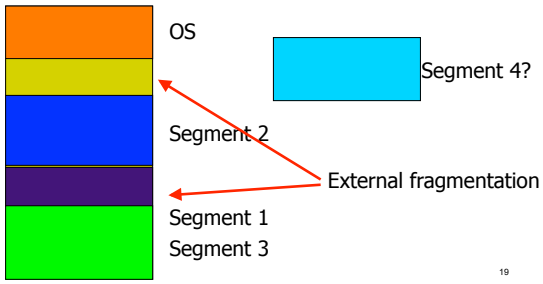
➔ which portions of the virtual and physical address spaces are used by this process?

Pros/cons of segmentation

- Pros:
  - Process can be split among several segments
    - Allows sharing
  - Segments can be assigned, or swapped independently
- Cons:
  - External fragmentation: many holes in physical memory
    - Also happens in base and bound scheme

Simple multiprogramming: Single segment per process, static relocation



What fundamentally causes external fragmentation?

1. Segments of many different sizes
2. Each has to be allocated contiguously

Can we solve Dynamic memory allocation problem?

- Problem: External fragmentation caused by holes too small
- How much can a smart allocator help?
  - The allocator maintains a free list of holes
  - Allocation algorithms differ in how to allocate from the free list

Dynamic allocation algorithms

- Best fit: allocate the smallest chunk big enough
- First fit: allocate the first chunk big enough
  - Rotating first fit
- Is best fit necessarily better than first fit?
  - Example: 2 free blocks of size 20 and 15
  - If allocation ops are 10 then 20, which one wins?
  - If ops are 8, 12, then 12, which one wins?

Dynamic allocation algorithms

- Analysis shows
  - First fit tends to leave average-size holes
  - Best fit tends to leave some very large holes, very small holes
- Knuth claims that if storage is close to running out, it will run out regardless of which scheme is used
  → Pick the easiest or most efficient (e.g. first fit)

Segmentation: OS implementation

- Keep segment table in PCB
- When creating process, allocate space for segments, fill in PCB bases/bounds
- When process dies, return physical space used by segments to free pool
- Context switch?
  - Saves old segment table / Loads new segment table to MMU
  - What about context switch of threads?
  - True-or-false: CS between threads of same process cheaper than CS between processes

[lec2] Kernel data structure: Process Control Block (Process Table)

- Process management info
  - State (ready, running, blocked)
  - PC & Registers, parents, etc
  - CPU scheduling info (priorities, etc.)
- Memory management info
  - Segments, page table, stats, etc
- I/O and file management
  - Communication ports, directories, file descriptors, etc.

Managing segments (cont)

To enlarge a segment:

- See if space above segment is free. If so, just update the bound and use that space
- Or, move this segment to disk and bring it back into a larger hole (or maybe just copy it to a large hole)

Managing segments (cont)

- When there is no space to allocate a new segment:
  - Compact memory – how?

Summary: Evolution of Memory Management (so far)

Scheme	How	Pros	Cons
Simple uniprogramming	1 segment loaded to starting address 0	Simple	1 process 1 segment No protection
Simple multiprogramming	1 segment relocated at loading time	Simple, Multiple processes	1 segment/process No protection External frag.
Base & Bound	Dynamic mem relocation at runtime	Simple hardware, Multiple processes Protection	1 segment/process, External frag.
Multiple segments	Dynamic mem relocation at runtime	More hardware, Protection, multi segs/process	External frag.