

ECE 20200 : Linear Circuit Analysis II School of ECE, Purdue University

LECTURE 12

- H(s): poles, zeros, s-plane
- Stability

Reference: Decarlo/Lin

PP 685-693

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H(s): poles, zeros, s-plane

Transfer functions

General structure

$$H(s) = \frac{n(s)}{d(s)} = \frac{K}{(s-z_1)(s-z_2)(s-z_3)\cdots(s-z_m)}$$

$$= \frac{(s-z_1)(s-z_2)(s-z_3)\cdots(s-z_m)}{(s-p_1)(s-p_2)(s-p_3)\cdots(s-p_n)}$$

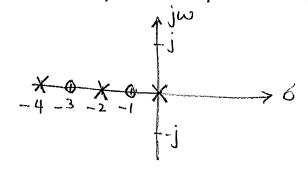
$$= \frac{s^m + b_1 s^{m-1} + \cdots + b_m}{s^m + a_1 s^{m-1} + \cdots + a_n}$$

(a)
$$Z_i$$
 are finite zeros of $H(s)$: $H(Z_i) = 0$ $m \le n$ in ECE20200

- (b) p_i are finite poles of H(s): $H(p_i) = \infty$
- (c) n-m = # of infinite zeros

Example 1.
$$H(s) = a.5 \frac{(s+1)(s+3)}{s(s+2)(s+4)}$$

Draw the pole-zero plot of $H(s)$.



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Example 2. Draw the pole-zero plot of H(s) = (s+1)(s+3) $\int_{-\infty}^{\infty} J\omega$ $((s+1)^2+1)(s+2)$

Example 3. Find H(s) from the pole-zero plot given below. Suppose H(0) = 5.

Stability

- 1. Bounded function |f(t)| < K < 00 for Vt.
- 2. BIBO stability (Bounded Input Bounded Output stability)
 - ⇒ Bounded input must ALWAYS map to Bounded output for BIBO stability.

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3. Test for BIBO stability.

If Pi is a pole of H(s), then the circuit/
system is BIBO stable if and only if

Re{Pi} <0 for all poles Pi.

In other words, all poles must be in the left half-plane (complex s-plane)

- 4. If Re $\{p_i\}$ is zero, $p_i = 6_i + j\omega_i = j\omega_i$, or $p_i = 0$, then any sinusoid of the form $K_i \sin(\omega_i t) + K_2 \cos(\omega_i t)$ where K_i or K_2 is non-zero, or if $p_i = 0$, a step input will give unbounded output and thus the system/circuit is unstable.
- 5. If $H(s) = \frac{1}{s}$, then the step response is $L^{-1}\left[\frac{1}{s} \cdot \frac{1}{s}\right] = L^{-1}\left[\frac{1}{s}\right] = tu(t) \to \infty \text{ as } t\to \infty$
- 6. If $H(s) = \frac{K}{(s+6)^2 + \omega^2} = \frac{K}{s^2 + \omega^2}$, then for the input $\frac{1}{s^2 + \omega^2}$, we obtain the response to be $\int_{-\infty}^{\infty} \left[\frac{K}{(s^2 + \omega^2)^2} \right] = Kt \sin(\omega t) \rightarrow \infty$ as $t \rightarrow \infty$

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Example: Find the range of 'a' for instability.

Use nodal analysis to obtain H(s)

$$V_A - V_{in} - aV_{out} + \frac{V_A - V_{out}}{5} = 0$$

at B:
$$\frac{V_{\text{out}} - V_{\text{A}}}{S} + V_{\text{out}} = 0$$

Substitute (2) into (1)

$$H(s) = \frac{V_{\text{out}}}{V_{\text{in}}} = \frac{1}{s+2-a}$$

pole:
$$s+2-a=0 \Rightarrow pole at$$

For the system to be unstable,

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WORKSHEET 1

Qualitative Analysis of an H(s).

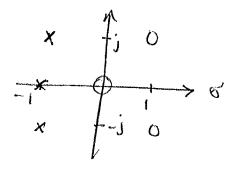
$$H(s) = 36 \frac{(s-1)^2(s+2)^2}{(s+1)^2(s+4)(s-3)^2}$$

- 1. How many finite zeros?
- 2. Multiplicaties of finite zeros?
- 3. Locations of finite zeros?
- 4. How many finite poles?
- 5. Multiplicaties of finite poles?
- 6. Locations of finite poles?
- 7. How many infinite zeros?
- 8. T/F The impulse response contains a term of the form KS(t).
- 9. The circuit/system described by the above transfer function is BIBO stable. T/F
- 10. Pole/zero plot of H(s).

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Worksheet 2

Given H(1) = 15 and the pole-zero plot below. Find H(s).



2)
$$H(1) = 15 = K \times \begin{bmatrix} \\ \\ \end{bmatrix}$$