

# 南开大学

# 计算机学院

机器学习实验报告

# 实验四 决策树分类器

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# 摘要

关键字: 层次聚类, Machine Learning, Deep Learning

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### 一、 实验描述与要求

基本要求: 绘制聚类前后样本分布情况

- 1. 基于 Watermelon-train1数据集(只有离散属性),构造ID3决策树;
- 2. 基于构造的 ID3 决策树,对数据集 Watermelon-test1进行预测,输出分类精度;中级要求:
- 1. 对数据集Watermelon-train2,构造C4.5或者CART决策树,要求可以处理连续型属性;
- 2. 对测试集Watermelon-test2进行预测,输出分类精度;

### 二、程序设计与代码实现

### (一) ID3算法决策树构建

首先, ID3算法的核 思想应用信息增益准则作为标准,我们根据公式就可以实现计算信息熵,代码如下:

```
# 计算信息熵

def calculate_entropy(y):
    log2 = math.log2
    unique_labels = np.unique(y)
    entropy = 0
    for label in unique_labels:
        count = len(y[y == label])
        p = count / len(y)
        entropy += -p * log2(p)

return entropy
```

#### 接下来,我们需要定义树的节点,代码如下:

```
class DecisionNode():

def __init__(self, feature_i=None, threshold=None,

value=None, true_branch=None, false_branch=None):

self.feature_i = feature_i

self.threshold = threshold

self.value = value

self.true_branch = true_branch

self.false_branch = false_branch
```

#### 然后要对特征进行划分,代码如下:

```
def divide_on_feature(X, feature_i, threshold):
    split_func = None
    if isinstance(threshold, int) or isinstance(threshold, float):
        split_func = lambda sample: sample[feature_i] >= threshold
    else:
        split_func = lambda sample: sample[feature_i] == threshold

    X_1 = np.array([sample for sample in X if split_func(sample)])
    X_2 = np.array([sample for sample in X if not split_func(sample)])
    return np.array([X_1, X_2])
```

#### 接着,就是我们决策树的内容,代码如下:

```
class DecisionTree(object):
       def __init__(self, min_samples_split=2, min_impurity=1e-7,
                    max_depth=float("inf"), loss=None):
           self.root = None #根节点
           self.min_samples_split = min_samples_split
           self.min_impurity = min_impurity
           self.max_depth = max_depth
           # 计算值如果是分类问题就是信息增益,回归问题就基尼指数
           self._impurity_calculation = None
           self._leaf_value_calculation = None #计算叶子
           self.one_dim = None
           self.loss = loss
       def fit(self, X, y, loss=None):
14
           self.one_dim = len(np.shape(y)) == 1
           self.root = self._build_tree(X, y)
           self.loss=None
       def _build_tree(self, X, y, current_depth=0):
19
           """递归求解树
           ....
           largest_impurity = 0
           best_criteria = None
          best_sets = None
           if len(np.shape(y)) == 1:
               y = np.expand_dims(y, axis=1)
31
           Xy = np.concatenate((X, y), axis=1)
           n_samples, n_features = np.shape(X)
           if n_samples >= self.min_samples_split and current_depth <= self.max_depth:</pre>
               # 计算每一个特征的增益值
               for feature_i in range(n_features):
                   feature_values = np.expand_dims(X[:, feature_i], axis=1)
                   unique_values = np.unique(feature_values)
                   for threshold in unique_values:
                       Xy1, Xy2 = divide_on_feature(Xy, feature_i, threshold)
                       if len(Xy1) > 0 and len(Xy2) > 0:
                           y1 = Xy1[:, n_features:]
                           y2 = Xy2[:, n_features:]
                           # 计算增益值
                           impurity = self._impurity_calculation(y, y1, y2)
                           if impurity > largest_impurity:
52
                               largest_impurity = impurity
                               best_criteria = {"feature_i": feature_i, "threshold":
53
                                                                          threshold)
```

```
best_sets = {
                                   "leftX": Xy1[:, :n_features],
                                   "lefty": Xy1[:, n_features:],
                                    "rightX": Xy2[:, :n_features],
                                    "righty": Xy2[:, n_features:]
           if largest_impurity > self.min_impurity:
61
               true_branch = self._build_tree(best_sets["leftX"], best_sets["lefty"],
                                                            current_depth + 1)
               false_branch = self._build_tree(best_sets["rightX"], best_sets["righty"],
63
                                                           current_depth + 1)
               return DecisionNode(feature_i=best_criteria["feature_i"], threshold=
                                                           best_criteria[
                   "threshold"], true_branch=true_branch, false_branch=false_branch)
           # 计算节点的目标值
67
           leaf_value = self._leaf_value_calculation(y)
           return DecisionNode(value=leaf_value)
       def predict_value(self, x, tree=None):
           """预测
74
           if tree is None:
               tree = self.root
           if tree.value is not None:
               return tree.value
82
83
           feature_value = x[tree.feature_i]
84
           branch = tree.false_branch
           if isinstance(feature_value, int) or isinstance(feature_value, float):
               if feature_value >= tree.threshold:
88
                   branch = tree.true_branch
           elif feature_value == tree.threshold:
               branch = tree.true_branch
92
           return self.predict_value(x, branch)
93
       def predict(self, X):
95
           y_pred = []
           for x in X:
               y_pred.append(self.predict_value(x))
98
           return y_pred
```

### 最后是分类器的实现,代码如下:

```
class ClassificationTree(DecisionTree):

def _calculate_information_gain(self, y, y1, y2):

# 计算信息增益

p = len(y1) / len(y)
```

```
entropy = calculate_entropy(y)
          info_gain = entropy - p * calculate_entropy(y1) - (1 - p) * calculate_entropy(
                                                      y2)
          return info_gain
      def _majority_vote(self, y):
          most_common = None
          max\_count = 0
          for label in np.unique(y):
               # 投票决定当前的节点为哪一个类
              count = len(y[y == label])
              if count > max_count:
                  most common = label
                  max_count = count
19
          return most common
      def fit(self, X, y):
           self._impurity_calculation = self._calculate_information_gain
           self._leaf_value_calculation = self._majority_vote
          super(ClassificationTree, self).fit(X, y)
```

#### (二) CART决策树构建

对于CART决策树,我们只需要把ID3算法中计算信息熵函数修改为计算基尼系数的函数, 代码如下:

```
def calculate_variance(X):
    """ Return the variance of the features in dataset X """

mean = np.ones(np.shape(X)) * X.mean(0)

n_samples = np.shape(X)[0]

variance = (1 / n_samples) * np.diag((X - mean).T.dot(X - mean))

return variance
```

#### 同时把分类器中计算函数修改为:

```
def _calculate_variance_reduction(self, y, y1, y2):
    var_tot = calculate_variance(y)
    var_1 = calculate_variance(y1)
    var_2 = calculate_variance(y2)
    frac_1 = len(y1) / len(y)
    frac_2 = len(y2) / len(y)

# 使用方差缩减
variance_reduction = var_tot - (frac_1 * var_1 + frac_2 * var_2)

return sum(variance_reduction)
```

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### 三、 测试与结果演示

#### (一) ID3决策树

通过测试数据集来测试,代码如下:

结果如图2所示

5 import sys; print('Python %s on %s' % (sys.version, sys.platform)) p.0.7

图 1: ID3决策树结果

#### (二) CART决策树

这里需要注意的是我们需要把密度从字符串形式转换为float类型,代码如下:

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```
clf = RegressionTree()
clf.fit(x_train,y_train)

y_pred = clf.predict(x_test)

accuracy = accuracy_score(y_pred,y_test)

print(accuracy)
```

结果如图2所示



图 2: CART决策树结果

