



中国科学院自动化研究所
INSTITUTE OF AUTOMATION
CHINESE ACADEMY OF SCIENCES

图神经网络

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讲课提纲

一、图神经网络发展

二、典型图神经网络

三、图神经网络应用

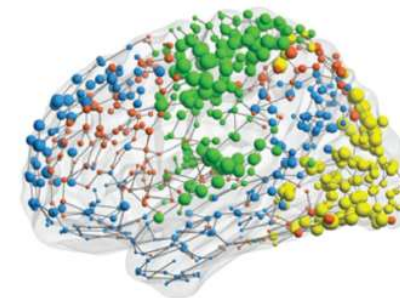
为什么要开展图神经网络研究



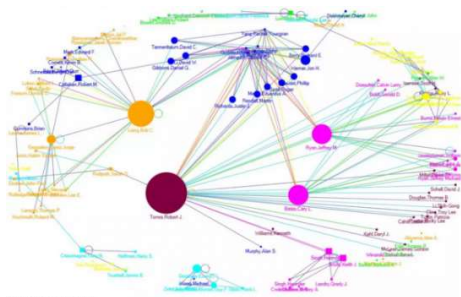
Social networks



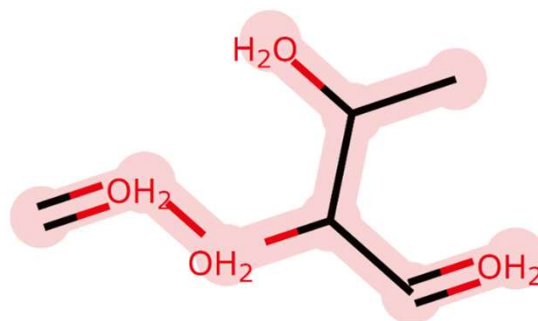
Traffic networks



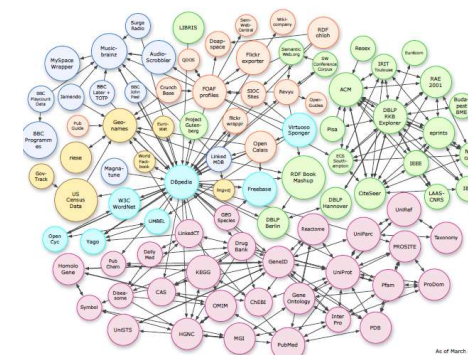
Functional networks



Citation Networks



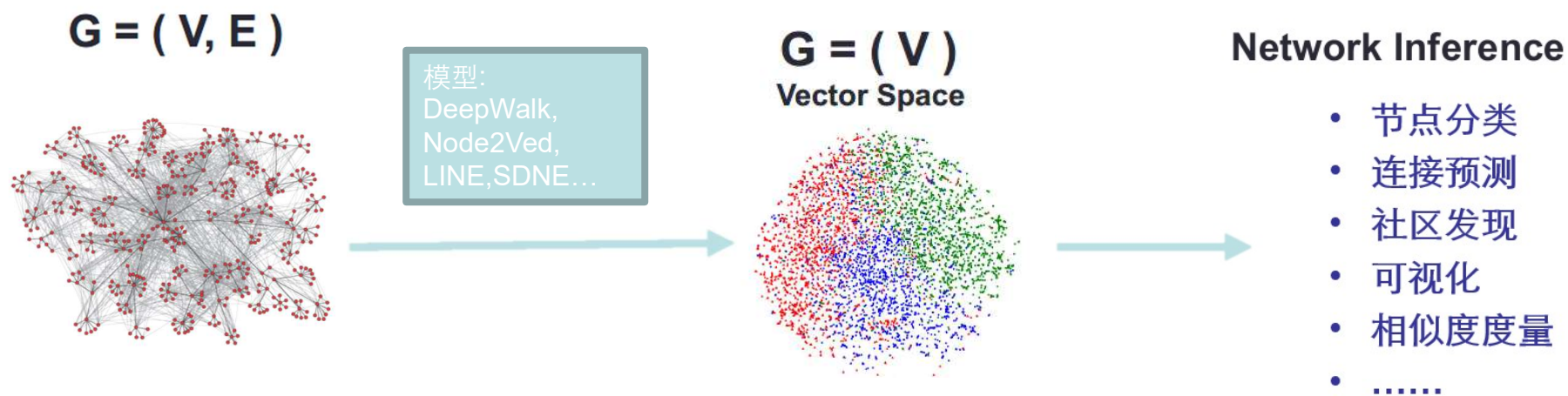
Chemical Compound



Knowledge Graph

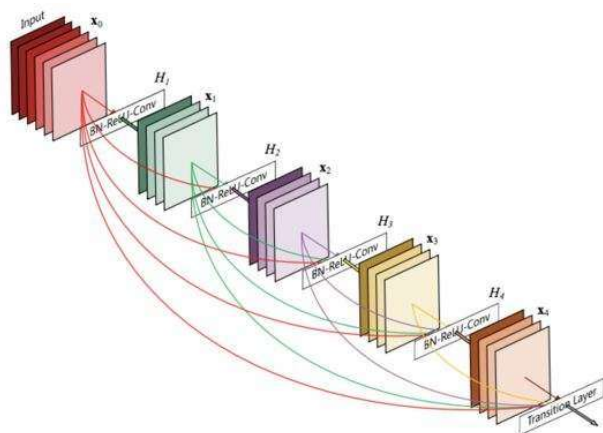
如何开展图神经网络研究

网络表示学习



缺陷：计算复杂度高，难以在大规模图数据上进行优化。

卷积神经网络



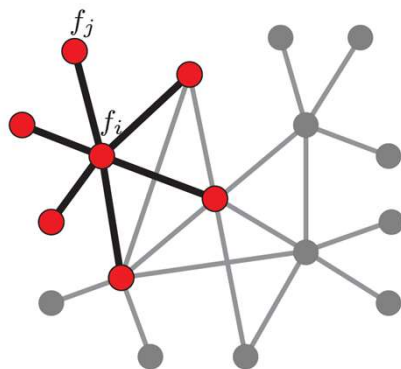
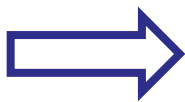
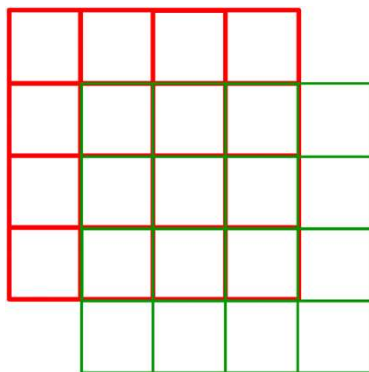
特点

局部连接

权重共享

多层结构

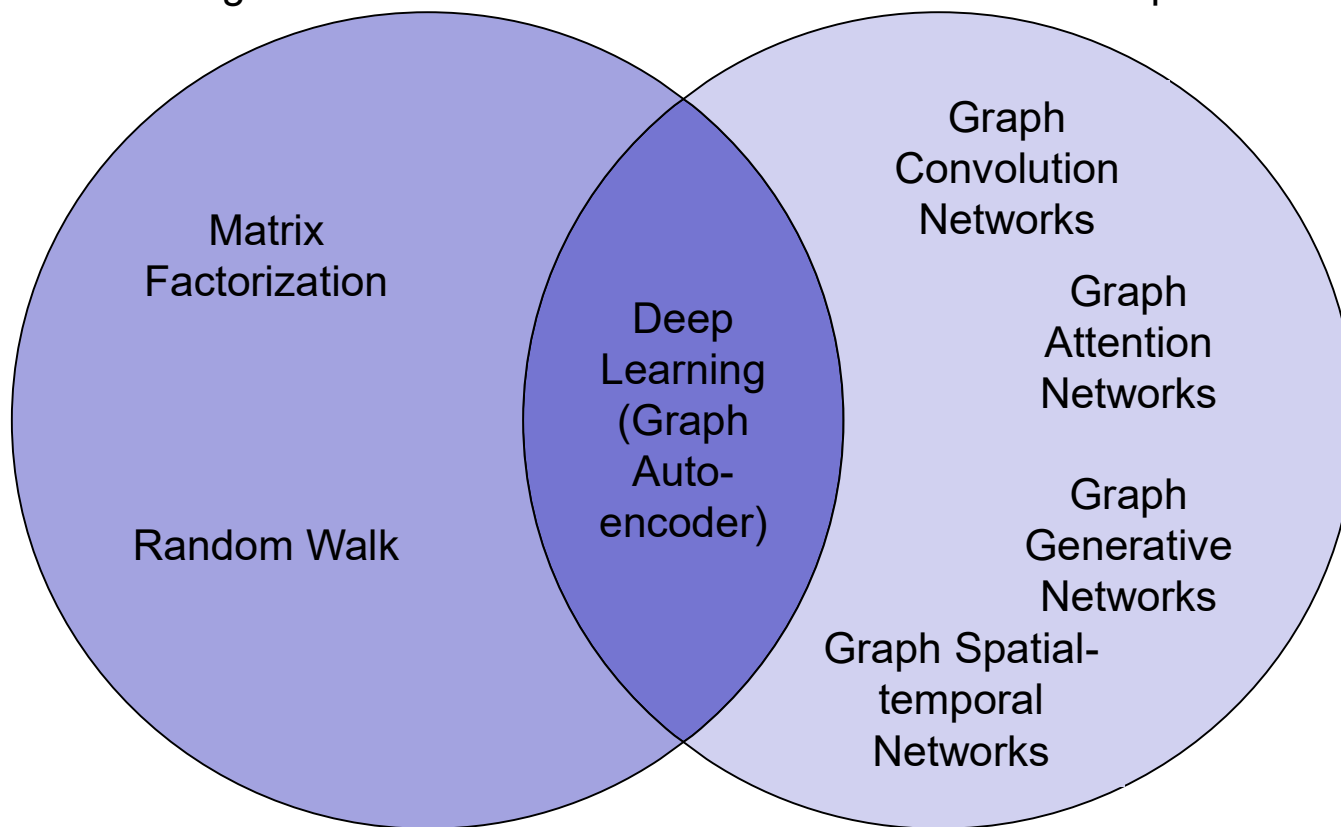
缺陷：只能处理规则的欧式数据，例如图像（2维网格）、文本（1维序列）。



图神经网络VS图嵌入

Graph Embedding

Graph Neural Networks





讲课提纲

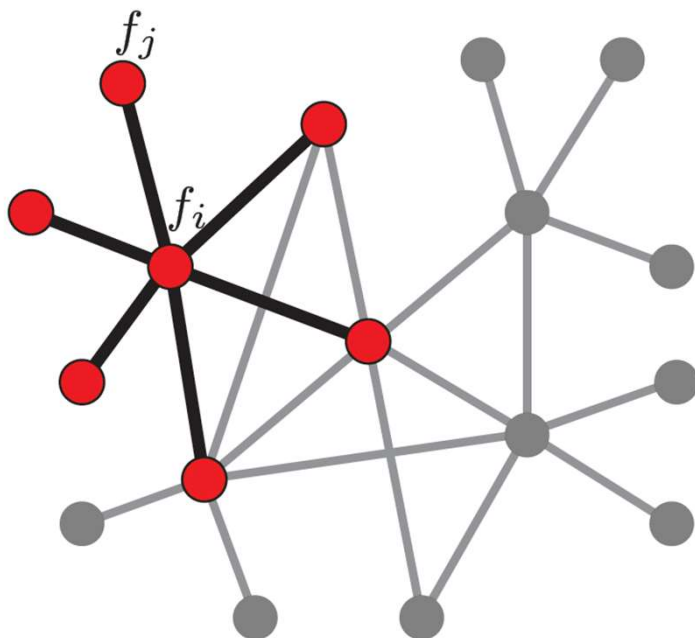
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1、图卷积网络

Graph theory concepts



Weighted undirected graph \mathcal{G}

Edges $\mathcal{E} \subseteq \mathcal{V} \times \mathcal{V}$ Vertices $\mathcal{V} = \{1, \dots, n\}$

Edges weights $w_{ij} \geq 0$ for $(i, j) \in \mathcal{E}$

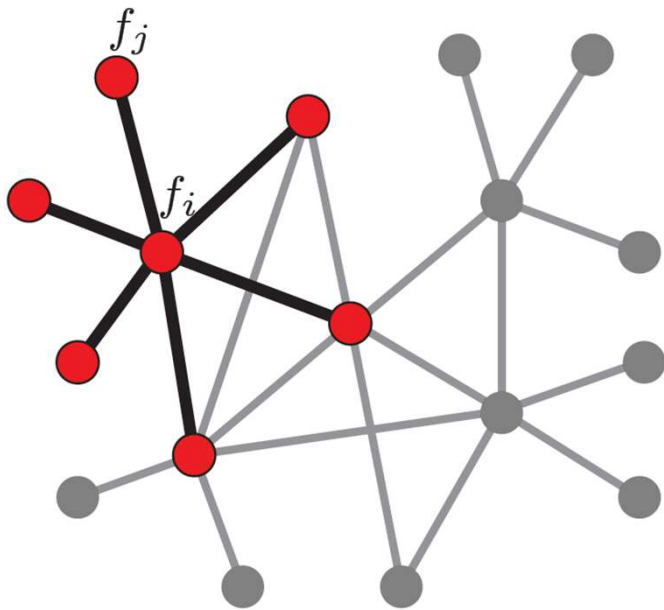
Functions over the vertices

$L^2(\mathcal{V}) = \{f: \mathcal{V} \rightarrow \mathbb{R}\}$ represented as vectors

$\mathbf{f} = (f_1, \dots, f_n)$

Hilbert space with inner product

$\langle f, g \rangle_{L^2(\mathcal{V})} = \sum_{i \in \mathcal{V}} f_i g_i = \mathbf{f}^T \mathbf{g}$



Unnormalized Laplacian Δ :

$$\begin{aligned}(\Delta f)_i &= \sum_{j:(i,j) \in \mathcal{E}} w_{ij}(f_i - f_j) \\ &= f_i \sum_{j:(i,j) \in \mathcal{E}} w_{ij} - \sum_{j:(i,j) \in \mathcal{E}} w_{ij} f_j\end{aligned}$$

difference between f and its local average

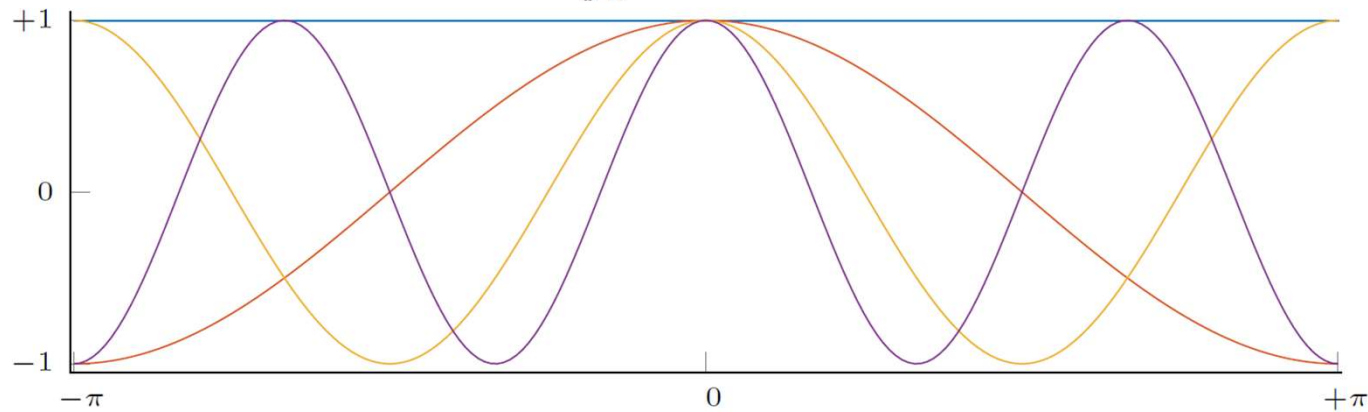
Represented as a positive semi-definite $n \times n$ matrix

$$\Delta = \mathbf{D} - \mathbf{W} \quad \mathbf{W} = (w_{ij}) \quad \mathbf{D} = \text{diag}(\sum_{j \neq i} w_{ij})$$

Fourier analysis on Euclidean spaces

A function $f: [-\pi, \pi] \rightarrow \mathbb{R}$ can be written as a Fourier series

$$f(x) = \sum_{k \geq 0} \underbrace{\langle f, e^{ikx} \rangle_{L^2([-\pi, \pi])}}_{\hat{f}_k \text{ Fourier coefficient}} e^{ikx}$$



Eigenfunctions of 1D Euclidean Laplacian

$$\text{[Red step function]} = \hat{f}_1 \text{ [Red constant line]} + \hat{f}_2 \text{ [Red sine wave]} + \hat{f}_3 \text{ [Red cosine wave]} + \dots$$



Spectral convolution

Convolution theorem: Fourier transform diagonalizes the convolution operator \Rightarrow convolution can be computed in the Fourier domain as

$$\widehat{(f * g)} = \hat{f} \cdot \hat{g}$$

Spectral convolution of $f, g \in L^2(\mathcal{V})$ can be defined by analogy

$$f \star g = \underbrace{\sum_{k \geq 1} \underbrace{\langle f, \phi_k \rangle_{L^2(\mathcal{V})} \langle g, \phi_k \rangle_{L^2(\mathcal{V})}}_{\text{product in the Fourier domain}} \phi_k}_{\text{inverse Fourier transform}}$$

In matrix-vector notation

$$\begin{aligned} f * g &= \Phi(\Phi^T g) \circ (\Phi^T f) \\ &= \Phi \underbrace{\text{diag}(\hat{g}_1, \dots, \hat{g}_n)}_{\text{Spectral filter coefficients}} \Phi^T f \end{aligned}$$

Spectral filter coefficients



ChebNet

Represent spectral transfer function as a **polynomial** of order K

$$\tau_{\theta}(\Lambda) = \sum_{k=0}^{K-1} \theta_k \Lambda^k$$

- $O(1)$ parameters per layer (K parameters)

$$y = g_{\theta}(L)f = \sum_{k=0}^{K-1} \theta_k T_k(\tilde{L})f \quad \theta \in \mathbb{R}^K \quad T_k(\tilde{L}) \in \mathbb{R}^{n \times n}$$

$$\tilde{L} = \frac{2L}{\lambda_{\max}} - I_n \quad \bar{f}_k = T_k(\tilde{L})f \in \mathbb{R}^n \quad \bar{f}_k = 2\tilde{L}\bar{f}_{k-1} - \bar{f}_{k-2}, \bar{f}_0 = f, \bar{f}_1 = \tilde{L}f$$

$$y = g_{\theta}(L)f = [\bar{f}_0, \dots, \bar{f}_{K-1}]\theta$$

- Filters have guaranteed K -hops support
- No explicit computation of forward and inverse Fourier transforms $\Rightarrow O(K|\mathcal{E}|)$

Graph Convolution networks (GCN)

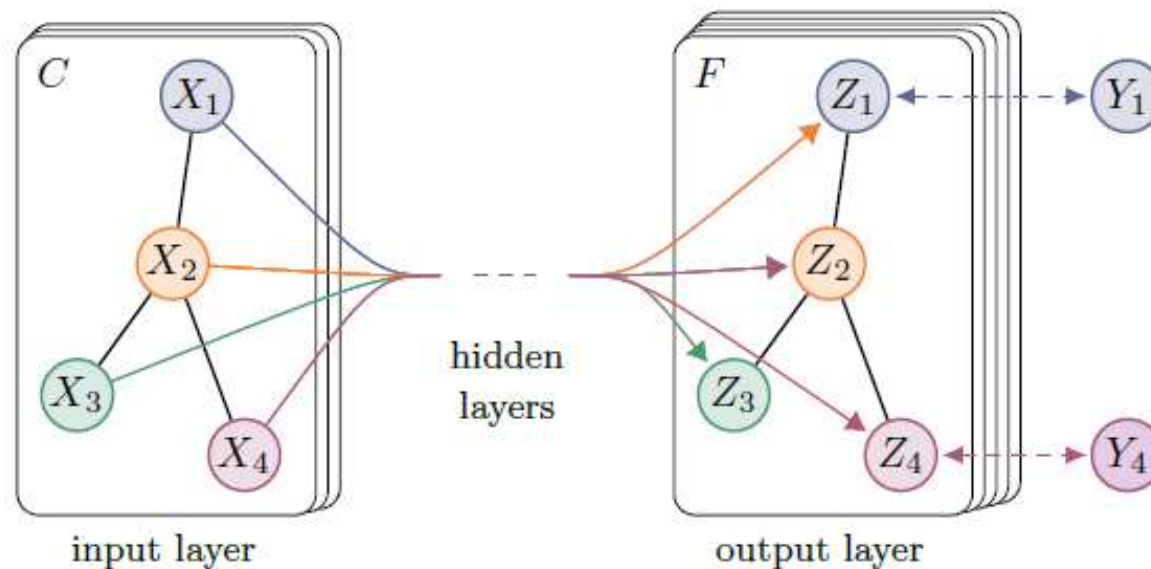
Linear approximation: $\lambda_{max} \approx 2, K = 1$

$$g * f \approx \theta_0 f + \theta_1 (L - I_n) f = \theta_0 f - \theta_1 D^{-1/2} A D^{-1/2} f$$

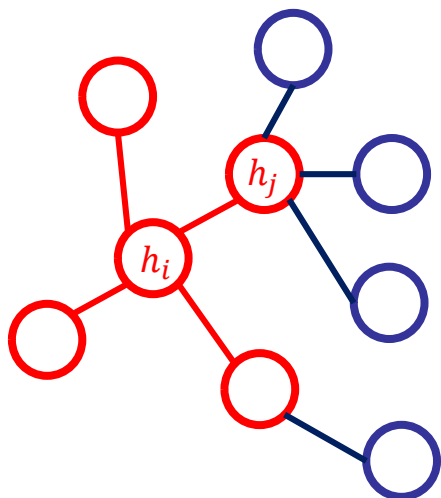
2 params per layer

$$\theta_0 = -\theta_1 = \theta \quad g * f \approx \theta (I_n + D^{-1/2} A D^{-1/2}) f$$

1 param per layer



2、图注意力网络



Node features $\mathbf{h} = \{\vec{h}_1, \vec{h}_2, \dots, \vec{h}_N\}, \vec{h}_i \in \mathbb{R}^F$



Linear transformation $\mathbf{h}' = \mathbf{W}\mathbf{h} = \{\vec{h}_1, \vec{h}_2, \dots, \vec{h}_N\}, \vec{h}_i \in \mathbb{R}^{F'}$

Attention coefficients $e_{ij} = a(\mathbf{W}\vec{h}_i, \mathbf{W}\vec{h}_j)$

Normalized coefficients $\alpha_{ij} = \text{softmax}_j(e_{ij}) = \frac{\exp(e_{ij})}{\sum_{k \in \mathcal{N}_i} \exp(e_{ik})}$

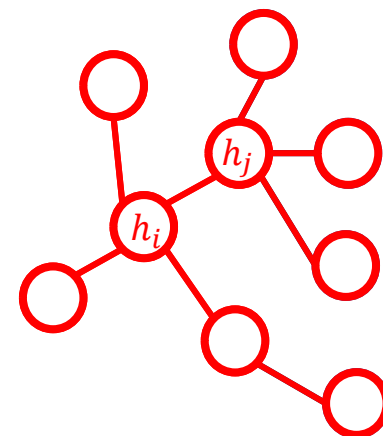
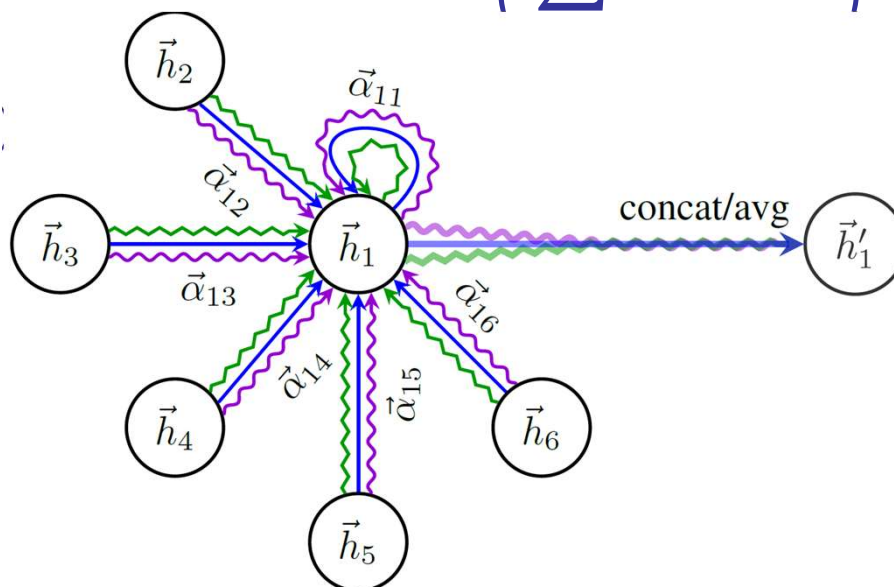
$$\alpha_{ij} = \frac{\exp\left(\text{LeakyReLU}(\vec{a}^T [\mathbf{W}\vec{h}_i || \mathbf{W}\vec{h}_j])\right)}{\sum_{k \in \mathcal{N}_i} \exp\left(\text{LeakyReLU}(\vec{a}^T [\mathbf{W}\vec{h}_i || \mathbf{W}\vec{h}_k])\right)}$$

Attention layer output $\vec{h}'_i = \sigma(\sum_{j \in \mathcal{N}_i} \alpha_{ij} \mathbf{W} \vec{h}_j)$

Multi-head attention^[1]

$$\vec{h}'_i = \parallel_{k=1}^K \sigma \left(\sum \alpha_{ij}^k \mathbf{W}^k \vec{h}_j \right)$$

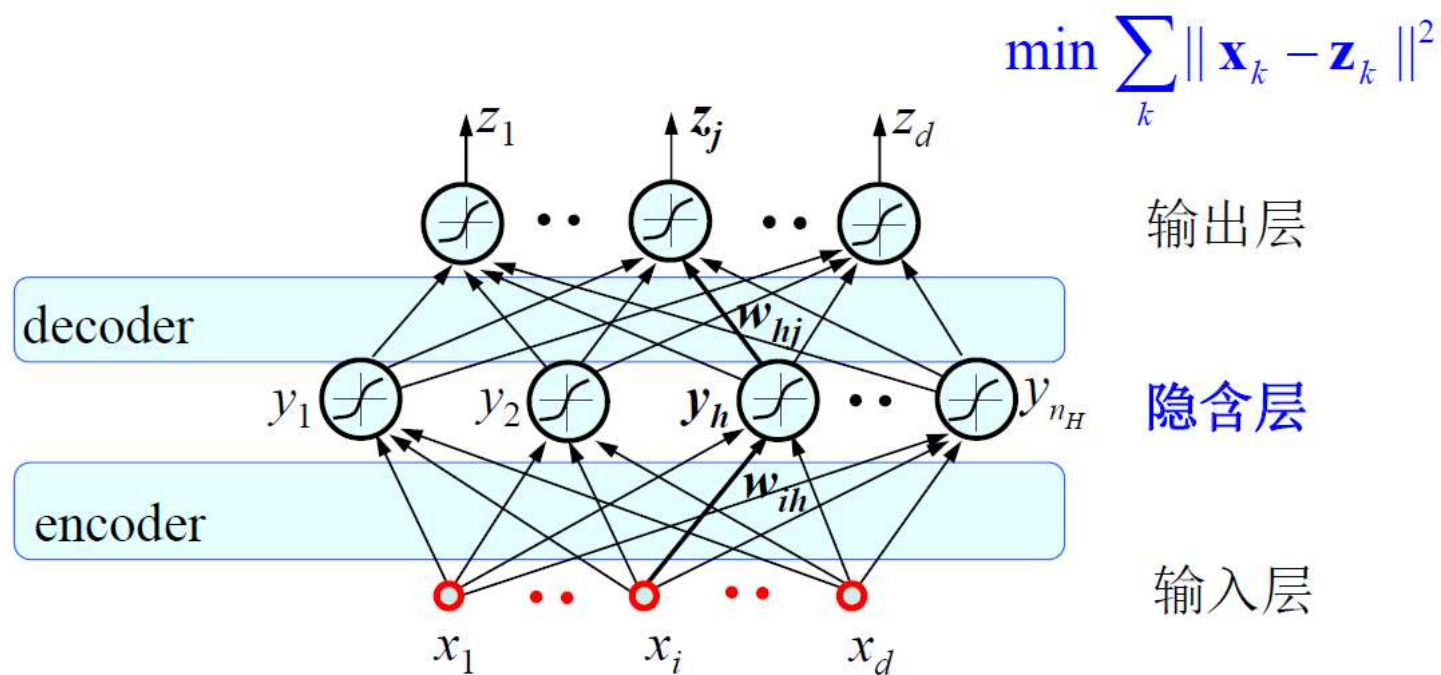
Final (prediction)



[1] Vaswani A, Shazeer N, Parmar N, et al. Attention is all you need. *NIPS* 2017.

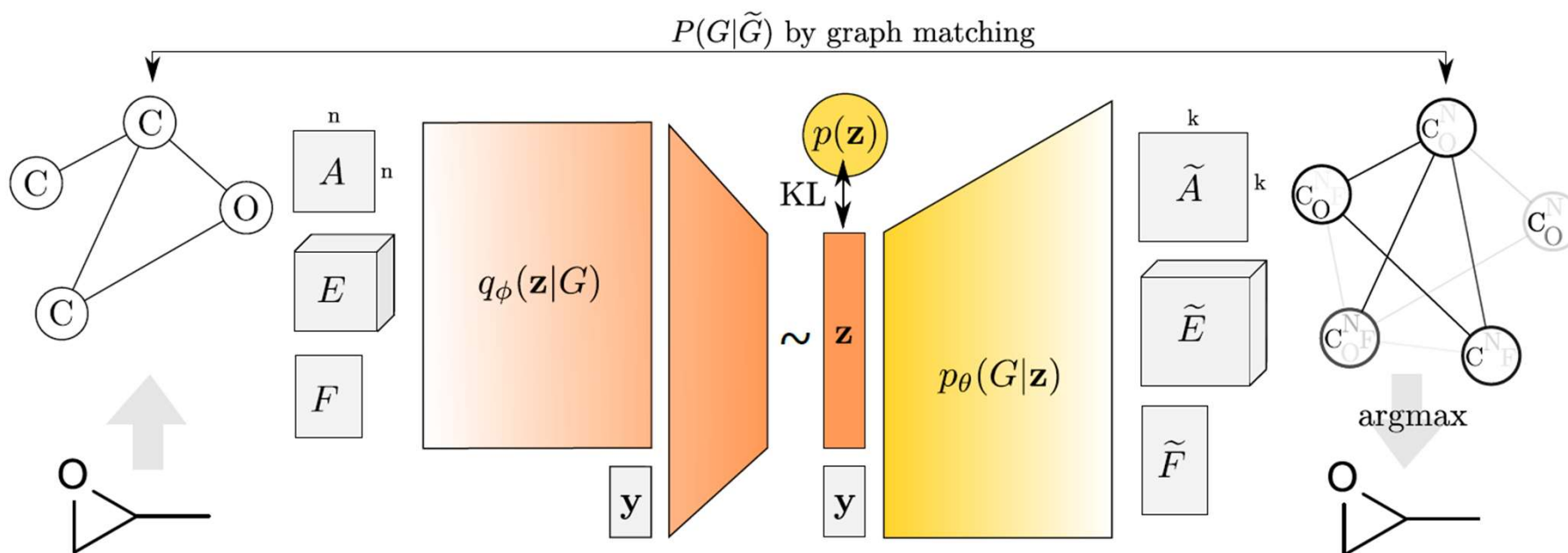
3、图自编码器

自编码器



自动编码器是一种尽可能重构输入信号的神经网络

图编码器



$G (A, E, F)$: Input graph. A : Adjacency matrix; E : Edge attribute tensor; F : Node attribute matrix

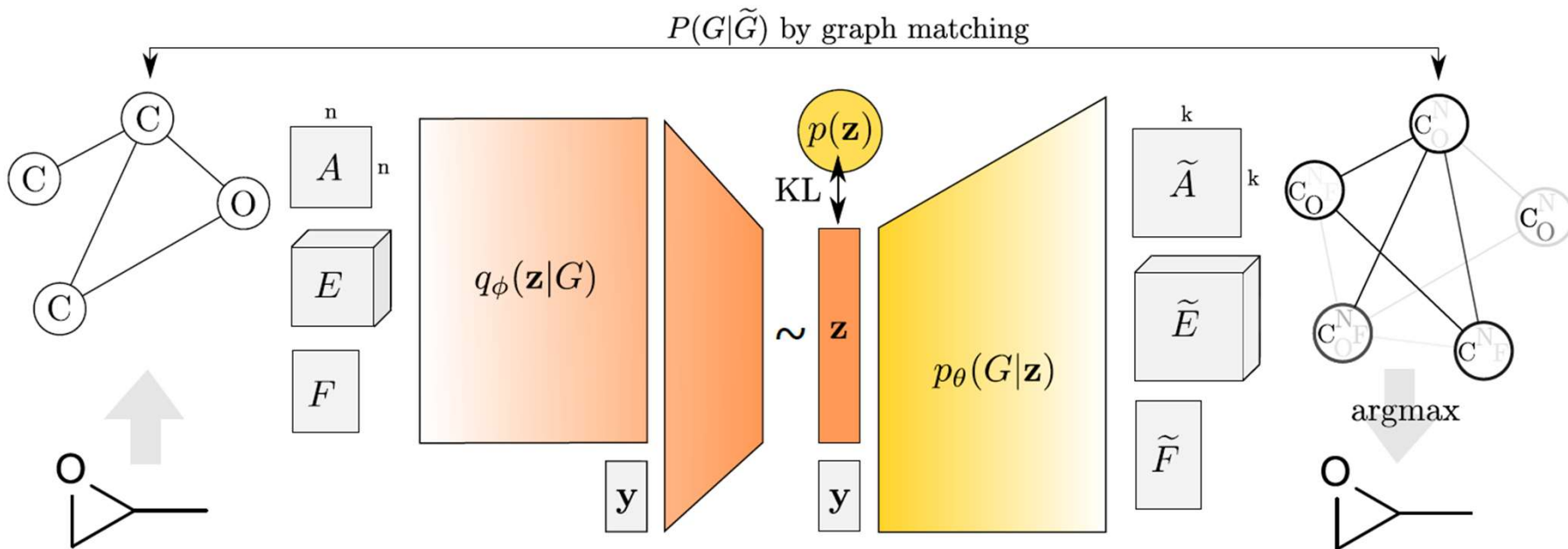
q_ϕ : Stochastic graph encoder

p_θ : Graph decoder

$\tilde{G} (\tilde{A}, \tilde{E}, \tilde{F})$: Output graph

Simonovsky M, Komodakis N. Graphvae: Towards generation of small graphs using variational autoencoders[C]//International Conference on Artificial Neural Networks. Springer, Cham, 2018: 412-422.

图编码器

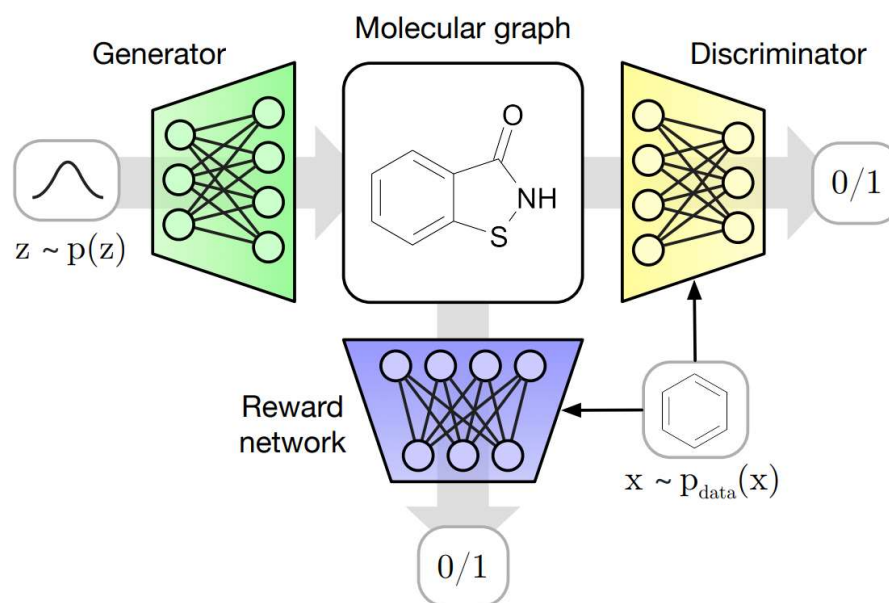


$$\begin{aligned}
 \log p(A'|\mathbf{z}) &= \\
 &= 1/k \sum_a A'_{a,a} \log \tilde{A}_{a,a} + (1 - A'_{a,a}) \log(1 - \tilde{A}_{a,a}) + \\
 &+ 1/k(k-1) \sum_{a \neq b} A'_{a,b} \log \tilde{A}_{a,b} + (1 - A'_{a,b}) \log(1 - \tilde{A}_{a,b}) \\
 \log p(F|\mathbf{z}) &= 1/n \sum_i \log F_{i,\cdot}^T \tilde{F}'_{i,\cdot} \\
 \log p(E|\mathbf{z}) &= 1/(\|A\|_1 - n) \sum_{i \neq j} \log E_{i,j}^T \tilde{E}'_{i,j,\cdot}, \quad (2)
 \end{aligned}$$

$$\begin{aligned}
 -\log p(G|\mathbf{z}) &= -\lambda_A \log p(A'|\mathbf{z}) - \lambda_F \log p(F|\mathbf{z}) - \\
 &- \lambda_E \log p(E|\mathbf{z}) \quad (3)
 \end{aligned}$$

4、图生成网络

MoIGAN



Generator: generating molecules from a prior distribution

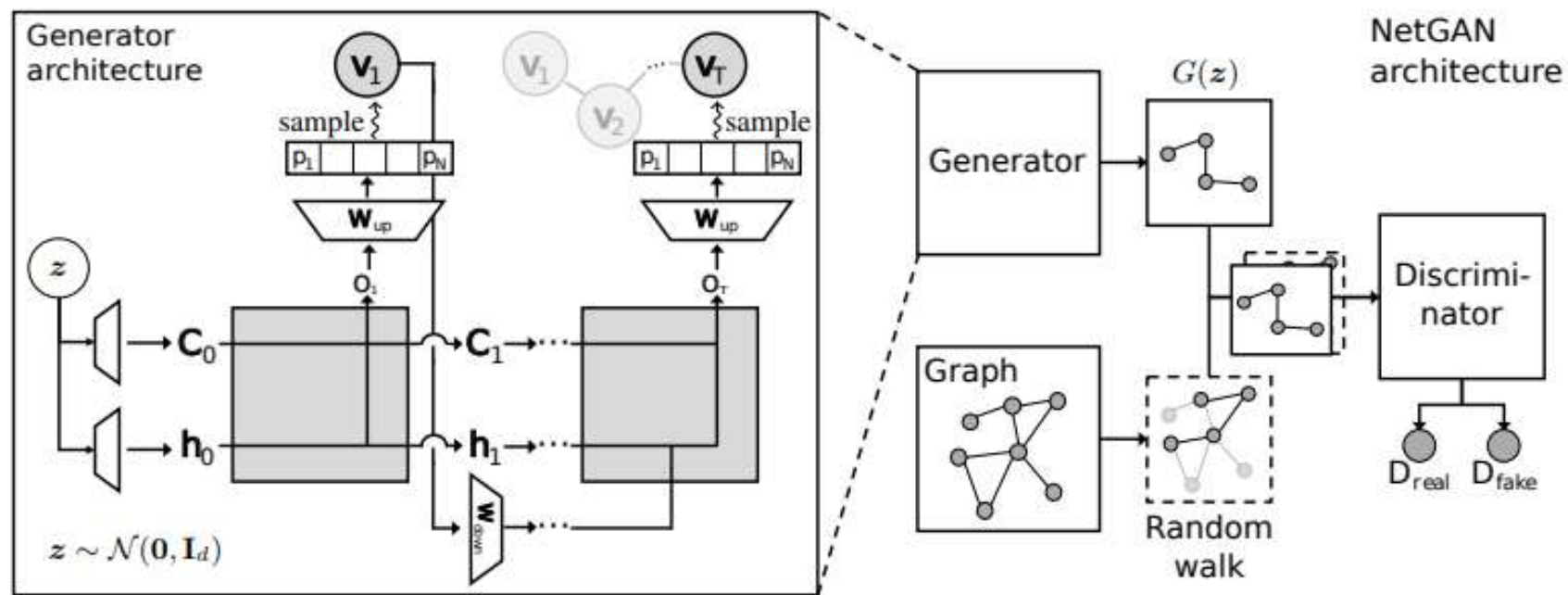
Discriminator: distinguishing the generated samples and real samples

Reward network:

Learns to assign a reward to each molecule to match a score provided by an external software. Invalid molecules always receive zero rewards.

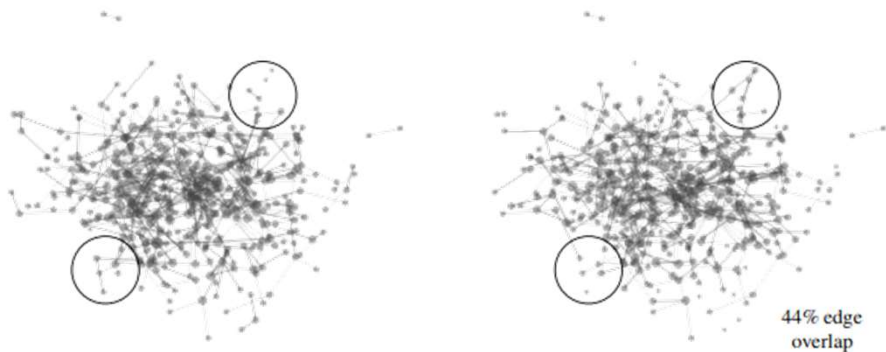
De Cao N , Kipf T . MolGAN: An implicit generative model for small molecular graphs. 2018.

NetGAN



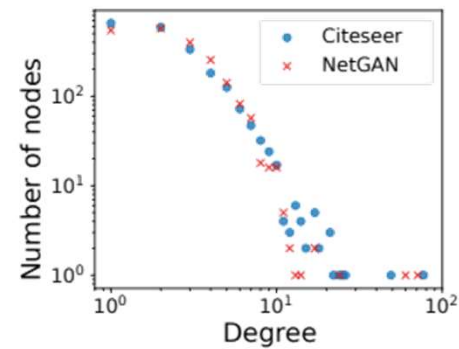
(a) Generator architecture

(b) NetGAN architecture



(a) Original graph

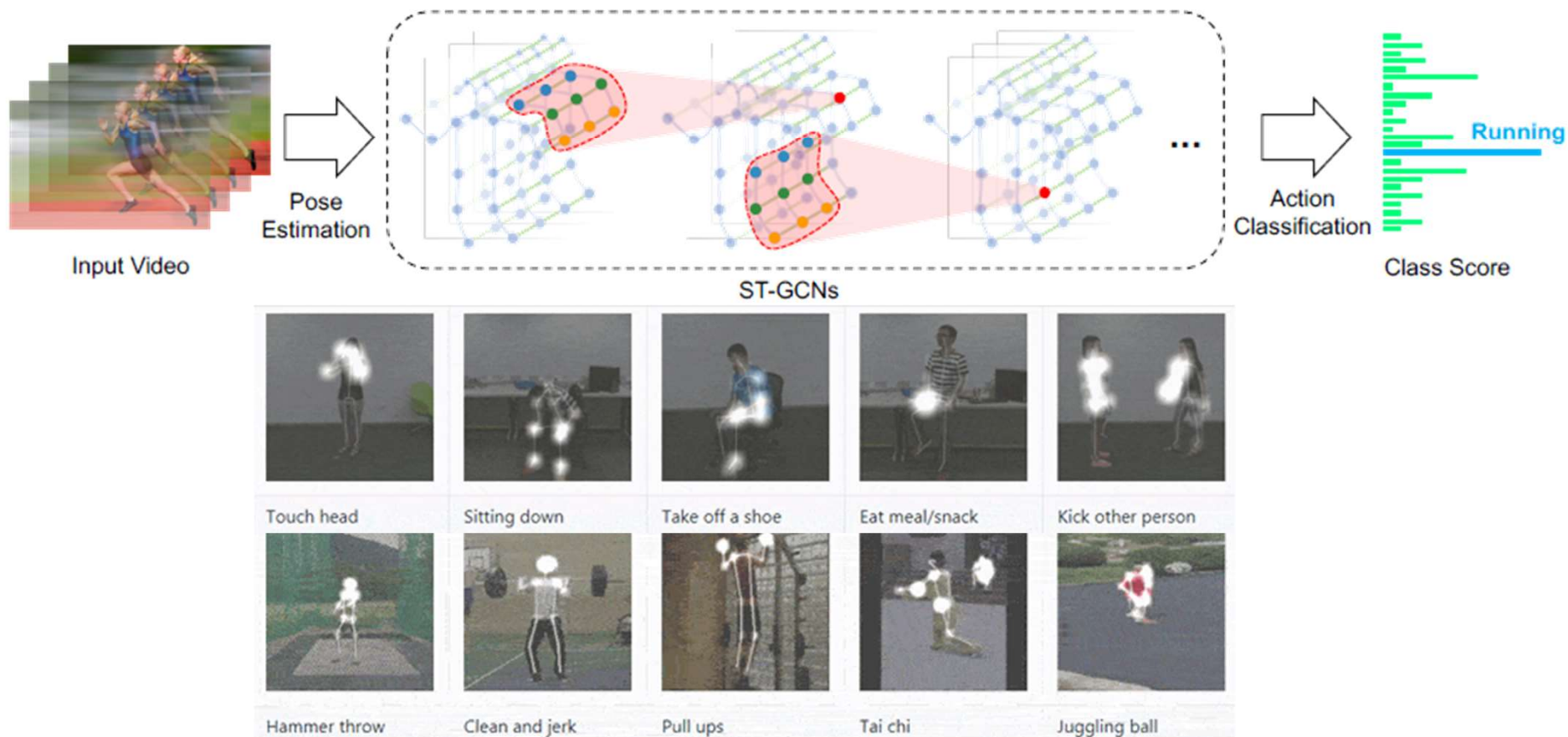
(b) Graph generated by NetGAN



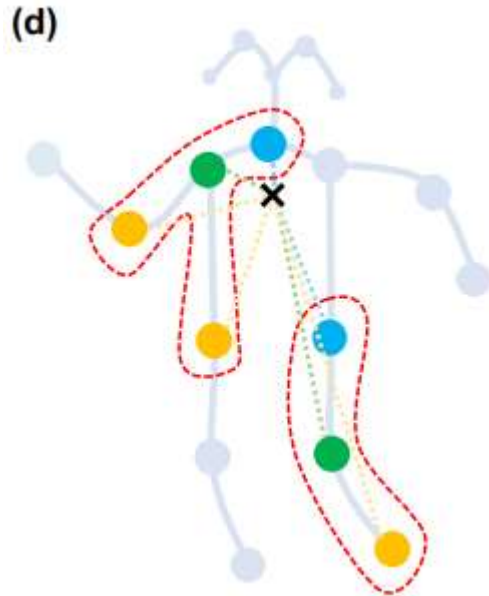
(c) Degree distribution comparison

5、时空图网络

ST-GCN



Spatial Temporal Graph Convolutional Networks for Skeleton-Based Action Recognition. Sijie Yan, Yuanjun Xiong and Dahua Lin, AAAI 2018.



Spatial configuration partitioning

- the root node itself
- centripetal group: the neighboring nodes that are closer to the gravity center of the skeleton than the root node
- otherwise the centrifugal group

$$l_{ti}(v_t j) = \begin{cases} 0 & \text{if } r_j = r_i \\ 1 & \text{if } r_j < r_i \\ 2 & \text{if } r_j > r_i \end{cases}$$

$$\mathbf{f}_{out} = \Lambda^{-\frac{1}{2}} (\mathbf{A} + \mathbf{I}) \Lambda^{-\frac{1}{2}} \mathbf{f}_{in} \mathbf{W} \quad \Rightarrow \quad \mathbf{f}_{out} = \sum_j \Lambda_j^{-\frac{1}{2}} \mathbf{A}_j \Lambda_j^{-\frac{1}{2}} \mathbf{f}_{in} \mathbf{W}_j$$



讲课提纲

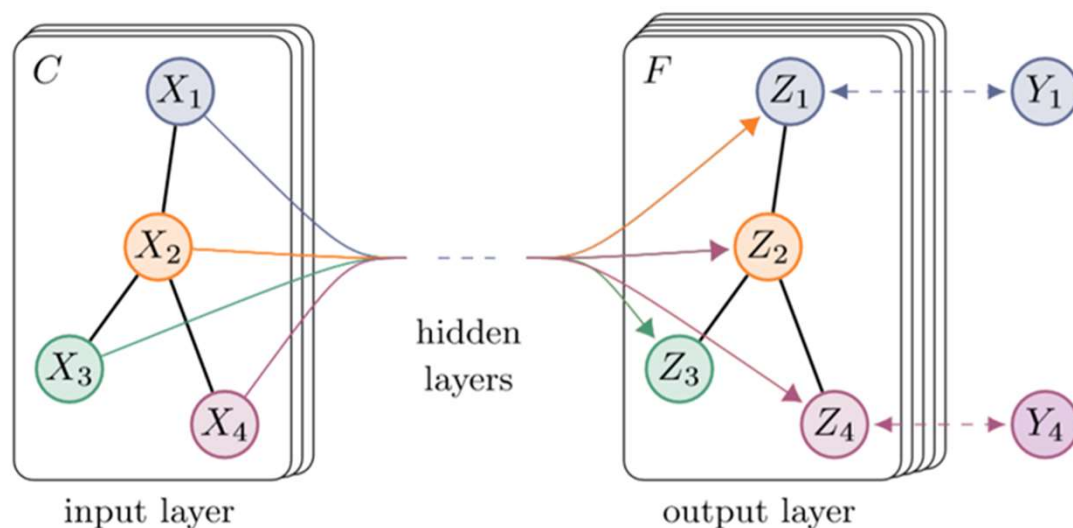
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1、引文网络节点半监督分类

节点分类



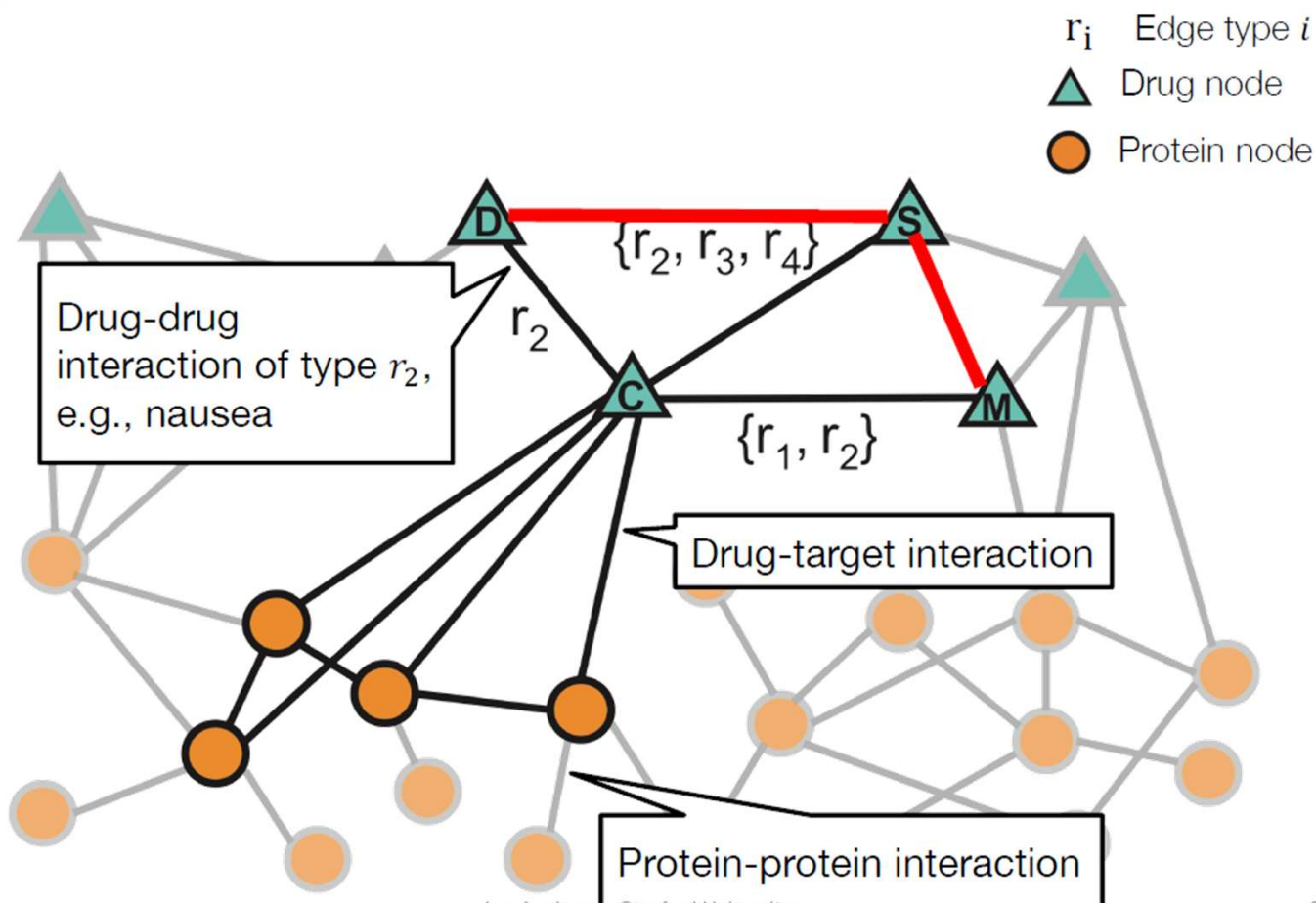
给定图结构和部分节点的标签，通常标注率较小(Citeseer 0.036, Cora 0.052, Pubmed 0.003)

目标：对未给出标签的节点进行分类

$$\mathcal{L} = - \sum_{i \in L} \sum_{j=1}^c Y_{ij} \ln Z_{ij}$$

2、多药物副作用预测

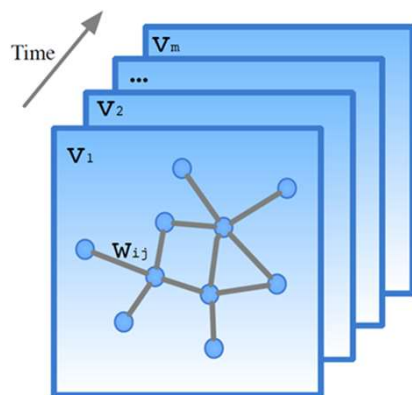
链接预测



Marinka Z , Monica A , Jure L . Modeling polypharmacy side effects with graph convolutional networks[J]. Bioinformatics, 2018, 34(13):i457-i466.

3、交通预测

交通预测



$$G = (\mathcal{V}, \varepsilon, W)$$

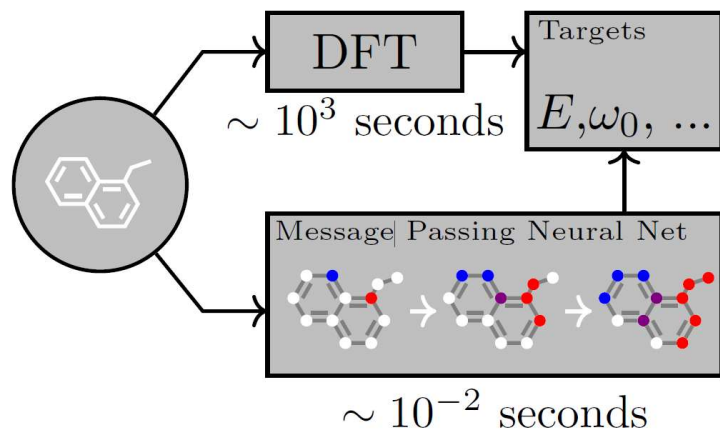
The purpose of traffic prediction task is to use previously observed road speed records to forecast the future status in a certain period of a specified region. Historical traf-

在第 t 时刻，在图 $G = (\mathcal{V}, \varepsilon, W)$ 中， \mathcal{V} 是一个有限的顶点集合，对应于交通网络中 n 个监测站的观测值； ε 是一组边，表示站点之间的连通性； W 表示 G 的加权邻接矩阵

4、分子特性预测

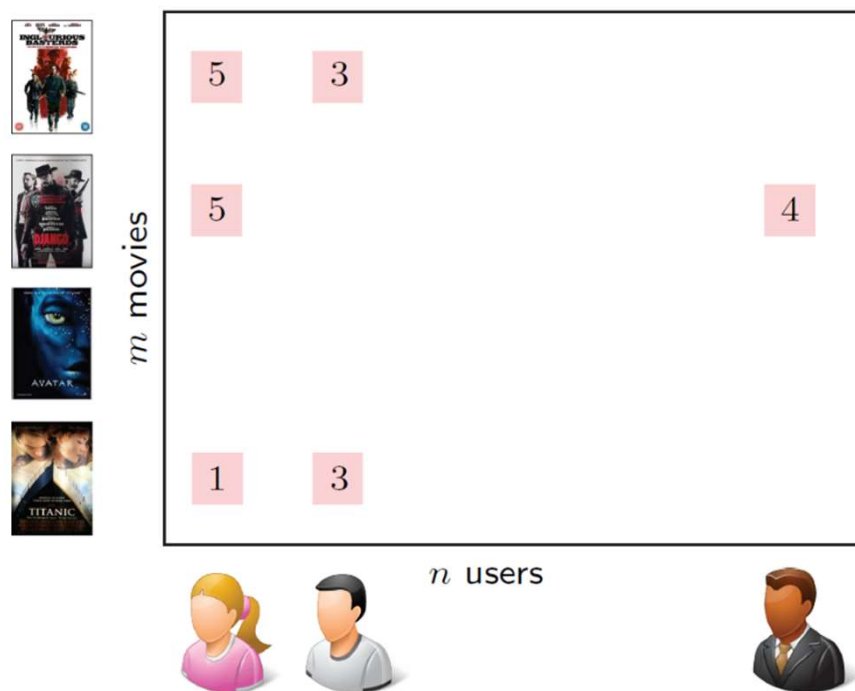
图分类

- 目标：预测分子的化学/物理特性，如原子化能 (atomization energy)、基本振动 (fundamental vibrations)、电子能隙 (electron-energy gap)等
- 传统方法：量子力学模拟方法DFT (Density Functional Theory)
计算复杂度高 ($\mathcal{O}(N_e^3)$), 难以扩展到大分子结构!
- 图神经网络方法：Message Passing Neural Network



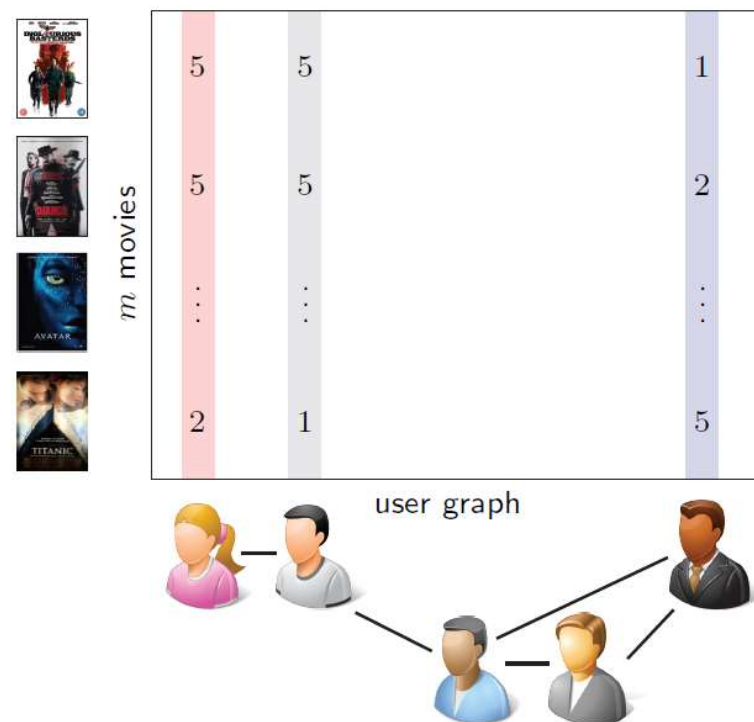
在QM9数据集上MPNN的推理时间比传统DFT方法快300k倍

5、推荐系统



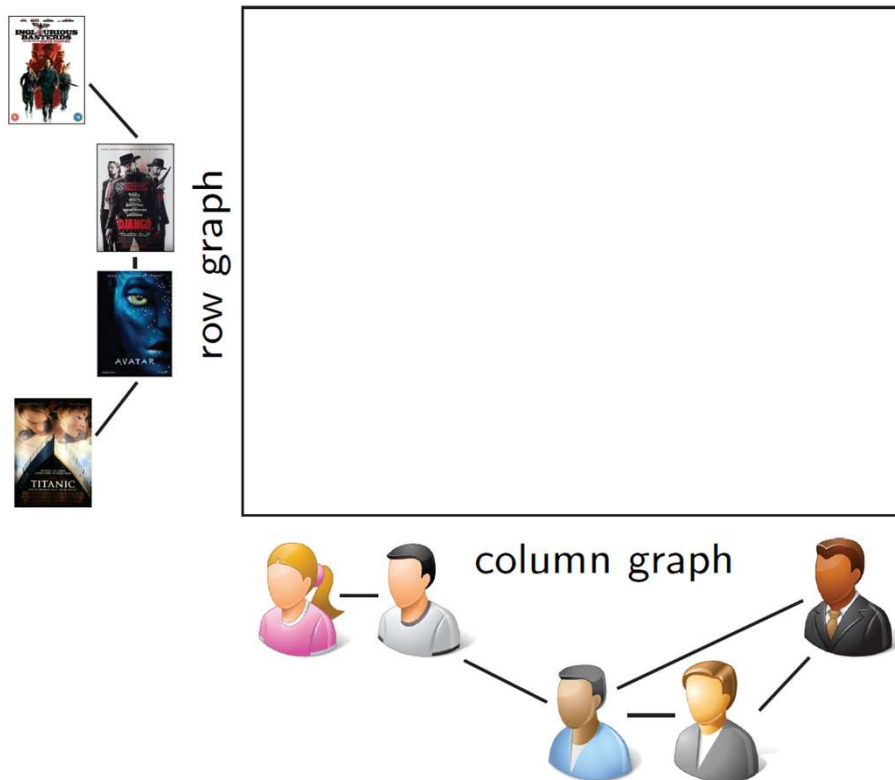
$$\min_{\mathbf{X} \in \mathbb{R}^{m \times n}} \|\mathbf{X}\|_* + \mu \|\Omega \circ (\mathbf{X} - \mathbf{A})\|_F^2$$

Candès. 2008



$$\min_{\mathbf{X} \in \mathbb{R}^{m \times n}} \mu \|\Omega \circ (\mathbf{X} - \mathbf{A})\|_F^2 + \underbrace{\mu_c \text{tr}(\mathbf{X} \Delta_c \mathbf{X}^T)}_{\|\mathbf{X}\|_{\mathcal{G}_c}^2}$$

Kalofolias et al. 2014



Multi-graph Fourier transform

$$\hat{\mathbf{X}} = \Phi_r^T \mathbf{X} \Phi_c$$

Multi-graph spectral convolution

$$\mathbf{X} \star \mathbf{G} = \Phi_r \left((\Phi_r^T \mathbf{X} \Phi_c) \circ (\Phi_r^T \mathbf{G} \Phi_c) \right) \Phi_c^T$$

$$\mathbf{X} \star \mathbf{G} = \Phi_r (\hat{\mathbf{X}} \circ \hat{\mathbf{G}}) \Phi_c^T$$

Multi-graph bi-variate polynomial filter

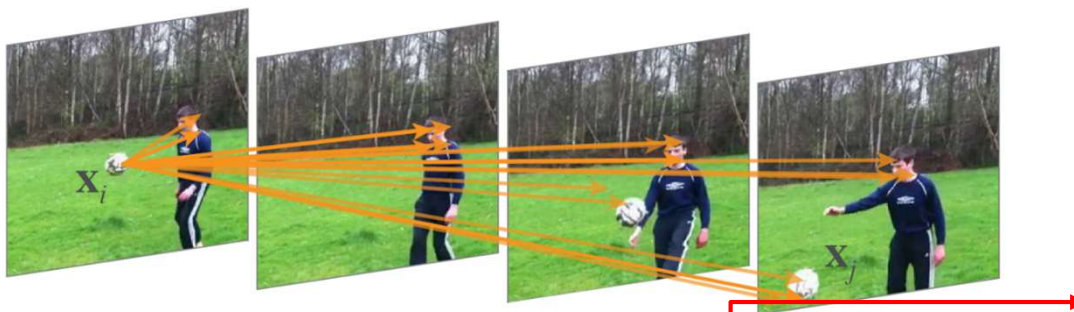
$$\mathbf{Y} = \tau_{\Theta}(\mathbf{X}) = \sum_{j,j'=1}^r \theta_{jj'} \Delta_r^j \mathbf{X} \Delta_c^{j'}$$

$\Theta = (\theta_{jj'})$ 是 $r \times r$ 的滤波器参数矩阵

Monti F, Bronstein M, Bresson X. Geometric matrix completion with recurrent multi-graph neural networks[C]//Advances in Neural Information Processing Systems. 2017: 3697-3707.

6、视频分类

Non-local Neural Networks



Non-local Operation
$$\mathbf{y}_i = \frac{1}{\mathcal{C}(\mathbf{x})} \sum_{\forall j} [f(\mathbf{x}_i, \mathbf{x}_j)] g(\mathbf{x}_j)$$

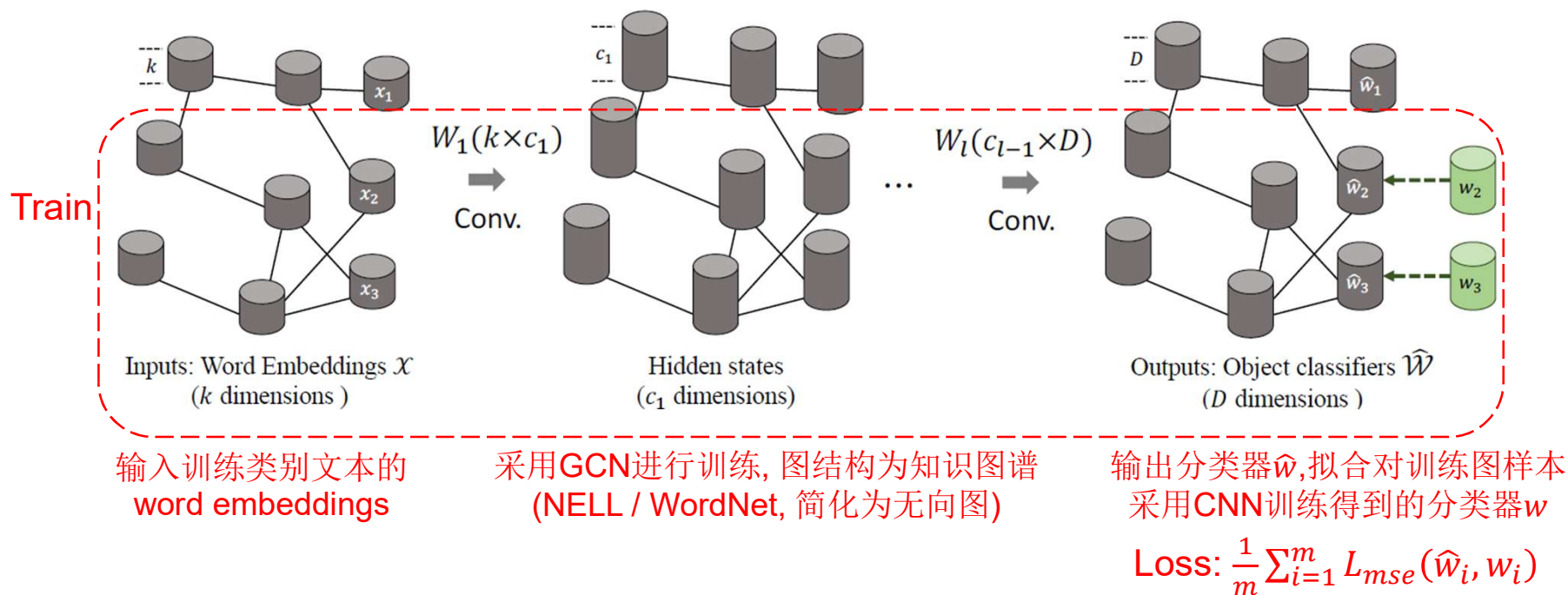
建立视频中某一位置与其他所有位置 (时间、空间) 之间的关联，构成“图模型”，捕捉数据间的长距离依赖关系

Gaussian
$f(\mathbf{x}_i, \mathbf{x}_j) = e^{\mathbf{x}_i^T \mathbf{x}_j}$
Embedded Gaussian
$f(\mathbf{x}_i, \mathbf{x}_j) = e^{\theta(\mathbf{x}_i)^T \phi(\mathbf{x}_j)}$
Dot product
$f(\mathbf{x}_i, \mathbf{x}_j) = \theta(\mathbf{x}_i)^T \phi(\mathbf{x}_j)$
Concatenation
$f(\mathbf{x}_i, \mathbf{x}_j) = \text{ReLU}(\mathbf{w}_f^T [\theta(\mathbf{x}_i), \phi(\mathbf{x}_j)])$

Non-local Neural Networks 可以视为不同“self-attention”方法的统一形式

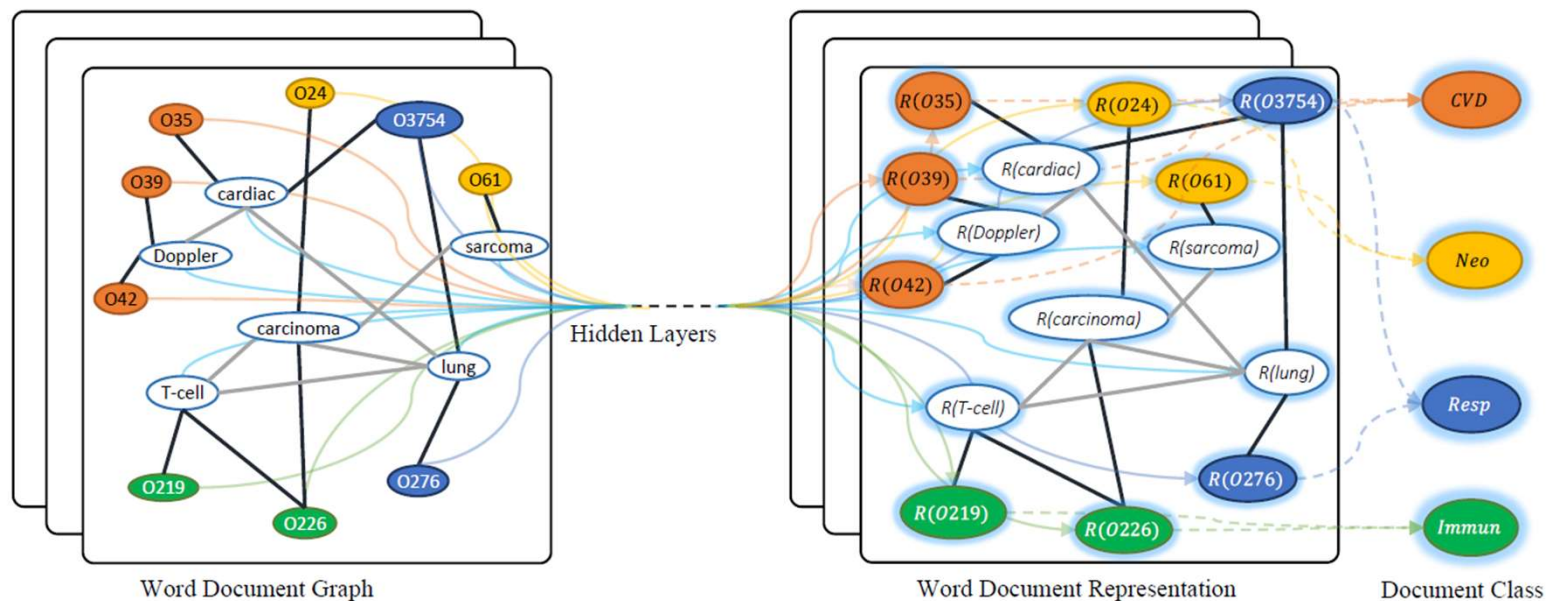
7、Zero-shot图像分类

Zero-shot图像分类任务：对训练集中没有出现过的图像进行分类



Wang X, Ye Y, Gupta A. Zero-shot recognition via semantic embeddings and knowledge graphs[C]//Proceedings of the IEEE Conference on Computer Vision and Pattern Recognition. 2018: 6857-6866.

8、文本分类



$$A_{ij} = \begin{cases} \text{PMI}(i, j) & i \text{ and } j \text{ are words and } \text{PMI}(i, j) > 0 \\ \text{TFIDF}_{ij} & i \text{ is a document and } j \text{ is a word} \\ 1 & i = j \\ 0 & \text{otherwise} \end{cases}$$

$$\text{PMI}(i, j) = \log \frac{p(i, j)}{p(i)p(j)}$$

$$p(i, j) = \frac{\#W(i, j)}{\#W}$$

$$p(i) = \frac{\#W(i)}{\#W}$$

Yao L, Mao C, Luo Y. Graph convolutional networks for text classification. AAAI 2019.



Github代码链接

GCN

<https://github.com/tkipf/gcn>

GAT

<https://github.com/PetarV-/GAT>

GraphSAGE

<https://github.com/williamleif/GraphSAGE>

Text-GCN

https://github.com/yao8839836/text_gcn

Graph Nets Library

https://github.com/deepmind/graph_nets

Deep Graph Library (DGL)

<https://github.com/dmlc/dgl>

PyTorch Geometric

https://github.com/rusty1s/pytorch_geometric

感谢大家!

欢迎批评指正