

## Lecture 2

# Approximate Caratheodory's Theorem

### Convex sets and convex hulls

#### Definition 2.0.1: Convex sets

Let  $\mathcal{S} \subseteq \mathbb{R}^d$ .  $\mathcal{S}$  is a **convex set** if

$$\lambda \mathbf{x} + (1 - \lambda) \mathbf{y} \in \mathcal{S},$$

for any  $\mathbf{x}, \mathbf{y} \in \mathcal{S}$  and  $\lambda \in [0, 1]$ .

We call  $\mathbf{z}$  is a **convex combination** of  $\{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n\}$  if there exists  $\boldsymbol{\lambda} = (\lambda_i) \in \mathbb{R}^n$  such that

$$\mathbf{z} = \sum_{i=1}^n \lambda_i \mathbf{x}_i$$

satisfying  $\sum_{i=1}^n \lambda_i = 1$  and  $\lambda_i \geq 0$  for all  $i$ .

#### Definition 2.0.2: Convex hulls

Let  $\mathcal{S} \subseteq \mathbb{R}^d$ . We call a set **convex hull** of  $\mathcal{S}$ , denoted by  $\text{conv}(\mathcal{S})$  if any element of this set, can be expressed as a convex combination of points from  $\mathcal{S}$ . Mathematically, for any  $\mathbf{z} \in \text{conv}(\mathcal{S})$ , there exists a sequence  $\{\mathbf{x}_i\}_{i=1}^n \subseteq \mathcal{S}$  for  $n \in \mathbb{N}$  such that

$$\mathbf{z} = \sum_{i=1}^n \lambda_i \mathbf{x}_i$$

satisfying  $\sum_{i=1}^n \lambda_i = 1$  and  $\lambda_i \geq 0$  for all  $i$ .

**Remark.**

The convex hull  $\text{conv}(\mathcal{S})$  is the smallest convex set that contains  $\mathcal{S}$ , in the sense that  $\text{conv}(\mathcal{S})$  is a subset of any convex set that contains  $\mathcal{S}$ .

## Caratheodory's theorem and approximated Caratheodory's theorem

### Theorem 2.0.3: Caratheodory's theorem

Every point in the convex hull of a set  $\mathcal{S} \subseteq \mathbb{R}^d$  can be expressed as a convex combination of at most  $d + 1$  points from  $\mathcal{S}$ .

Caratheodory's theorem tells us the worst-case number of points needed to represent an element of a convex hull. Such worst-case number is dimensional-dependent and apparently cannot be improved.

What if we approximate  $\mathbf{z} \in \text{conv}(\mathcal{S})$  rather than exactly represent it as a convex combination of points from  $\mathcal{S}$ . We show that such approximation lead to the number of points needed for representation does not depend not the dimension  $d$ .

### Theorem 2.0.4: Approximate Caratheodory's theorem

Consider a bounded set  $\mathcal{S} \subset \mathbb{R}^d$ , i.e., there exists  $r > 0$  for any  $\mathbf{z} \in \mathcal{S}$ ,  $\|\mathbf{z}\| \leq r$ . For every point  $\mathbf{x} \in \text{conv}(\mathcal{S})$  and every integer  $k$ , there exists a sequence of points  $(\mathbf{x}_j)_{j=1}^k \subset \mathcal{S}$  such that

$$\left\| \mathbf{x} - \frac{1}{k} \sum_{j=1}^k \mathbf{x}_j \right\|_2 \leq \frac{r}{\sqrt{k}}.$$

**Proof.** Without loss of generality we assume that  $\|\mathbf{z}\| \leq 1$  for any  $\mathbf{z} \in \mathcal{S}$ .

Let  $\mathbf{x} \in \text{conv}(\mathcal{S})$ , then there exists a sequence of points  $(\mathbf{z}_i)_{i=1}^n$  for  $n \in \mathbb{N}$  and  $n \leq d + 1$  such that

$$\mathbf{x} = \sum_{i=1}^n \lambda_i \mathbf{z}_i$$

satisfying  $\sum_{i=1}^n \lambda_i = 1$  and  $\lambda_i \geq 0$ .

Since  $\boldsymbol{\lambda} = (\lambda_i)$  belongs to the probability simplex, we define a discrete probability distribution of a random variable  $Z$  as follows

$$\mathbb{P}\{Z = \mathbf{z}_i\} = \lambda_i,$$

with expectation  $\mathbb{E}Z = \mathbf{x}$ .

Generating a family of iid random variables from this distribution  $(Z_1, Z_2, \dots, Z_k)$  for

$k \in \mathbb{N}$ , we obtain their sample average as

$$\frac{1}{k} \sum_{i=1}^k Z_i,$$

and

$$\mathbb{E} \left[ \frac{1}{k} \sum_{i=1}^k Z_i \right] = \mathbf{x}.$$

We measure the derivation of the sample average from its expectation by

$$\mathbb{E} \left\| \frac{1}{k} \sum_{i=1}^k Z_i - \mathbf{x} \right\|_2^2$$

Since  $Z_i$  are iid and deriving from the inequality  $\mathbb{E}\|Z - \mathbb{E}Z\|_2^2 \leq \mathbb{E}\|Z\|_2^2$  (Check by Yourself) for a  $d$ -dimensional random variable, we have

$$\begin{aligned} \mathbb{E} \left\| \frac{1}{k} \sum_{i=1}^k Z_i - \mathbf{x} \right\|_2^2 &= \mathbb{E} \left\| \frac{1}{k} \sum_{i=1}^k (Z_i - \mathbf{x}) \right\|_2^2 \\ &= \frac{1}{k^2} \mathbb{E} \left\| \sum_{i=1}^k (Z_i - \mathbf{x}) \right\|_2^2 \\ &= \frac{1}{k^2} \sum_{i=1}^k \mathbb{E} \|Z_i - \mathbf{x}\|_2^2 \\ &= \frac{1}{k^2} \sum_{i=1}^k \mathbb{E} \|Z_i\|_2^2 \\ &\leq \frac{1}{k} \quad (\|Z_i\|_2 \leq 1) \end{aligned}$$

By concavity of  $\sqrt{\cdot}$  and Jensen's inequality, we obtain

$$\mathbb{E} \left\| \frac{1}{k} \sum_{i=1}^k Z_i - \mathbf{x} \right\|_2 \leq \sqrt{\mathbb{E} \left\| \frac{1}{k} \sum_{i=1}^k Z_i - \mathbf{x} \right\|_2^2} \leq \frac{1}{\sqrt{k}}.$$

Here there exists a realization of  $(Z_1, Z_2, \dots, Z_k)$  denotes as  $(\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_k)$  such that

$$\left\| \frac{1}{k} \sum_{i=1}^k \mathbf{x}_i - \mathbf{x} \right\|_2 \leq \frac{1}{\sqrt{k}}.$$

□

**Remark.**

Such realization is built from components of a convex combination of  $\mathbf{x}$  and repetitions are allowed.

## An application of approximated Caratheodory's theorem

### Definition 2.0.5: Covering numbers

The covering number of a set  $\mathcal{T} \subset \mathbb{R}^d$  is the smallest number of Euclidean balls of radius  $\epsilon$  needed to cover  $\mathcal{T}$ , denoted by  $N(\mathcal{T}, \epsilon)$ .

#### Remark.

- Covering numbers measure the complexity of  $\mathcal{T}$ .
- They suffer from the dimension  $d$ .
- Let the centers of a set of Euclidean balls with radius  $\epsilon$  be  $\{\mathbf{c}_i\}$ . Mathematically, we say these Euclidean balls cover  $\mathcal{T}$ , if for any  $x \in \mathcal{T}$ , there exists  $\mathbf{c}_k \in \{\mathbf{c}_i\}$  such that

$$\|\mathbf{x} - \mathbf{c}_k\| \leq \epsilon.$$

### Proposition 2.0.6

Let  $\mathcal{B} := \{\mathbf{x} \in \mathbb{R}^d : \|\mathbf{x}\|_2 \leq 1\}$  be a unit Euclidean ball, for any  $0 < \epsilon < 1$  we have

$$N(\mathcal{B}, \epsilon) \geq \left(\frac{1}{\epsilon}\right)^d.$$

**Proof.** Let  $\text{vol}(\mathcal{B})$  denote the volume of  $\mathcal{B}$  and  $\text{vol}(\epsilon\mathcal{B})$  denote the volume Euclidean ball of radius  $\epsilon$ .

By the definition of covering numbers, we have

$$\text{vol}(\mathcal{B}) \leq N(\mathcal{B}, \epsilon) \cdot \text{vol}(\epsilon\mathcal{B}) = N(\mathcal{B}, \epsilon) \cdot \epsilon^d \cdot \text{vol}(\mathcal{B}).$$

Hence,  $N(\mathcal{B}, \epsilon) \geq \left(\frac{1}{\epsilon}\right)^d$ . □

The proposition shows that the covering numbers of the unit Euclidean ball grows exponentially in dimensionality. Is there any set whose covering number is dimension-free?

### Theorem 2.0.7: Covering numbers of Polytopes

Let  $\mathcal{P} \subset \mathbb{R}^d$  be a polytope with  $m$  vertices and  $\text{diam}(\mathcal{P}) \leq r$ .<sup>a</sup> Then  $\mathcal{P}$  can be covered by at most  $m^{\lceil \frac{1}{\epsilon^2} \rceil}$  Euclidean balls of radius  $\epsilon > 0$ , i.e.,

$$N(\mathcal{P}, \epsilon) \leq m^{\lceil \frac{r^2}{\epsilon^2} \rceil}.$$

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<sup>a</sup> $\text{diam}(\mathcal{P}) = \sup_{\mathbf{x}, \mathbf{y} \in \mathcal{P}} \|\mathbf{x} - \mathbf{y}\|_2$

**Proof.** Without loss of generality we assume that  $\text{diam}(\mathcal{P}) \leq 1$  and  $\mathbf{0}$  belongs to the inside of  $\mathcal{P}$ .

Let  $\mathcal{T} = (z_i)_{i=1}^m$  be the vertices of  $\mathcal{P}$ . Note that  $\mathcal{P}$  is a subset of  $\text{conv}(\mathcal{T})$  and  $\mathcal{T}$  is bounded by 1.

By the approximate Caratheodory's theorem, for any  $\mathbf{x} \in \text{conv}(\mathcal{T})$ , there exists a sequence of vertices  $(z_{i_j})_{j=1}^k$  and  $z_{i_j} \in \mathcal{T}$ , such that

$$\|\mathbf{x} - \frac{1}{k} \sum_{j=1}^k z_{i_j}\|_2 \leq \frac{1}{\sqrt{k}}, \quad \text{for any } k \in \mathbb{N}. \quad (\text{ACT})$$

Let  $\frac{1}{\sqrt{k}} \leq \epsilon$ ,  $k \geq \frac{1}{\epsilon^2}$ , and take  $K = \lceil \frac{1}{\epsilon^2} \rceil$ .

Denote  $\mathcal{N} = \left\{ \frac{1}{K} \sum_{j=1}^K z_{i_j} : z_{i_j} \in \mathcal{T} \right\}$ . The cardinality of  $\mathcal{N}$  takes  $|\mathcal{N}| = m^K$ .

Let all elements of  $\mathcal{N}$  be the centers of Euclidean balls with radius of  $\epsilon$ . By (ACT), the union of these balls covers  $\text{conv}(\mathcal{T})$ , and hence  $\mathcal{P}$ .

Therefore the smallest number of Euclidean balls with radius  $\epsilon$  needed to cover  $\mathcal{P}$  is less than  $m^K$ .

In summary  $N(\mathcal{P}, \epsilon) \leq m^K = m^{\lceil \frac{1}{\epsilon^2} \rceil}$ . □

The following theorem shows an application of the above result.

### Theorem 2.0.8: Volume of Polytopes

Let  $\mathcal{B} \subset \mathbb{R}^d$  be the unit Euclidean ball, and  $\mathcal{P} \subset \mathcal{B}$  be a polytope with  $m$  vertices. Then

$$\frac{\text{vol}(\mathcal{P})}{\text{vol}(\mathcal{B})} \leq \left( 4 \sqrt{\frac{\log m}{d}} \right)^d.$$

**Proof.** Let  $\epsilon \mathcal{B}$  denote the Euclidean ball with radius  $\epsilon > 0$ . By the definition of covering numbers, we have

$$\text{vol}(\mathcal{P}) \leq N(\mathcal{P}, \epsilon) \cdot \text{vol}(\epsilon \mathcal{B}) \stackrel{\text{cov. \# of poly.}}{\leq} m^{\lceil \frac{1}{\epsilon^2} \rceil} \cdot \epsilon^d \cdot \text{vol}(\mathcal{B}).$$

Hence

$$\frac{\text{vol}(\mathcal{P})}{\text{vol}(\mathcal{B})} \leq m^{\lceil \frac{1}{\epsilon^2} \rceil} \cdot \epsilon^d \leq m^{\frac{2}{\epsilon^2}} \cdot \epsilon^d$$

Minimizing the right hand side w.r.t.  $\epsilon$  gives

$$\frac{\text{vol}(\mathcal{P})}{\text{vol}(\mathcal{B})} \leq e^{\frac{d}{2}} \left( \sqrt{\frac{4 \log m}{d}} \right)^d \leq \left( 4 \sqrt{\frac{\log m}{d}} \right)^d.$$

□

### Remark.

Let  $\delta = 4 \sqrt{\frac{\log m}{d}}$ , then  $\text{vol}(\mathcal{P}) \leq \delta^d \cdot \text{vol}(\mathcal{B}) = \text{vol}(\delta \mathcal{B})$ . If the dimensionality  $d$  is sufficiently large, the volume of a convex polytope with its vertices on the surface of a unit Euclidean is smaller than a tiny ball  $\delta \mathcal{B}$ .