

Numerical Optimization

Lecture 8: Subgradient Descent Method

Hao Wang

Email: wanghao1@shanghaitech.edu.cn

- 1 Algorithm
- 2 Convergence
- 3 Example
- 4 Subgradient Projection Method

- 1 Algorithm
- 2 Convergence
- 3 Example
- 4 Subgradient Projection Method

Suppose $\min_x f(x)$

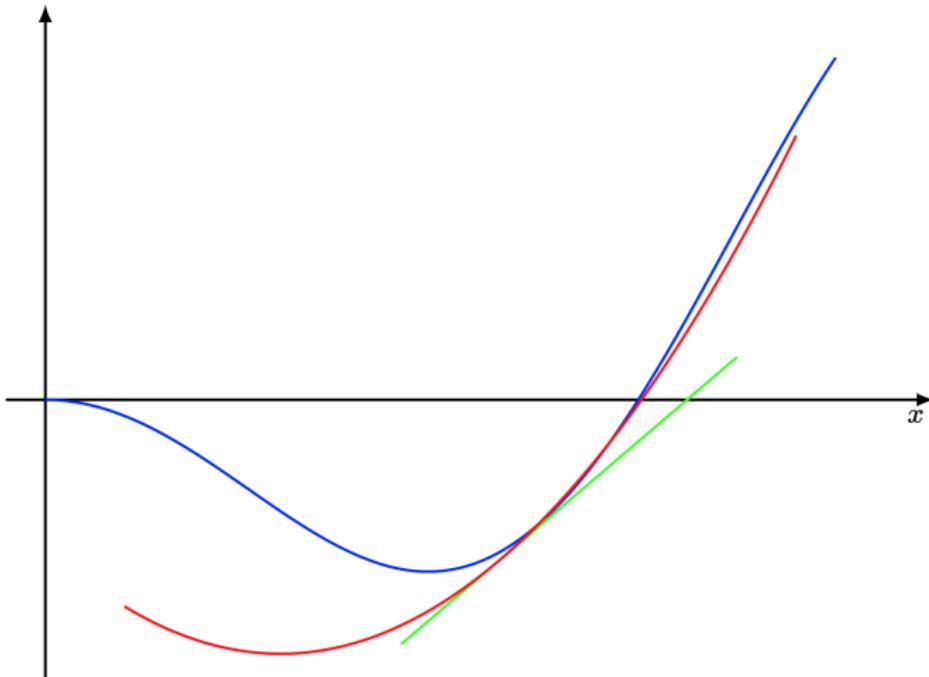
Construct local approximation at x^k :

$$\begin{aligned}x^{k+1} &\leftarrow \min_x f(x^k) + \nabla f(x^k)^T (x - x^k) + \frac{1}{2t} \|x - x^k\|_2^2 \\ \implies x^{k+1} &\leftarrow x^k - t \nabla f(x^k)\end{aligned}$$

Interpretation:

- Go along the steepest descent direction with a stepsize t
- Linear model but not too far away from x^k
- Local quadratic approximation model at x^k
- Newton method, quasi-Newton method also use local models.

$$x^{k+1} \leftarrow \min_x \quad f(x^k) + \nabla f(x^k)^T (x - x^k) + \frac{1}{2t} \|x - x^k\|_2^2$$



Now suppose $f(x)$ is convex but not necessarily differentiable.

$$\begin{aligned}x^{k+1} &\leftarrow \min_x f(x^k) + \langle g^k, x - x^k \rangle + \frac{1}{2t} \|x - x^k\|_2^2, \quad g^k \in \partial f(x^k) \\ \implies x^{k+1} &\leftarrow x^k - t g^k\end{aligned}$$

Does this still work? — the answer is NO!

Subgradient method is not descent

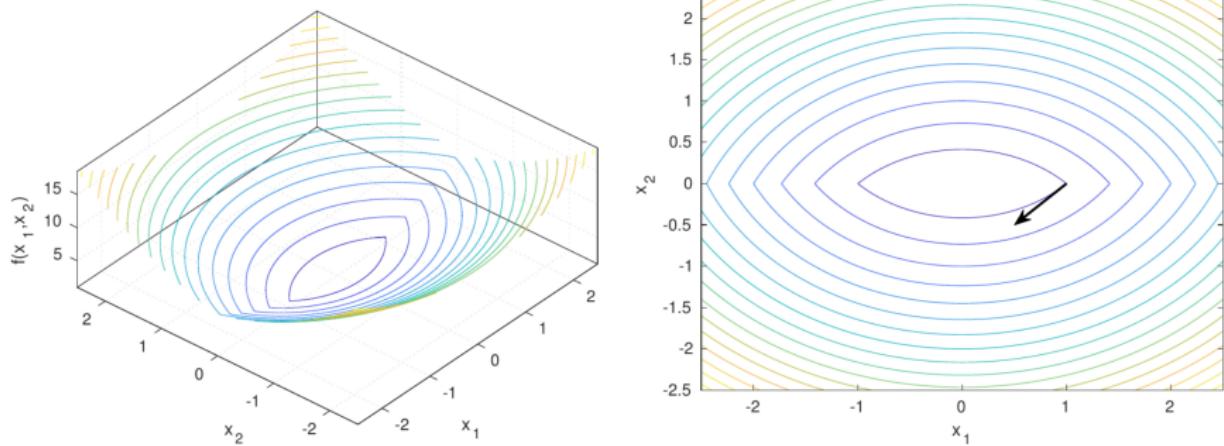


Figure 2. 3D plot (left) and level sets (right) of $f(x) = \max[x_1^2 + (x_2 + 1)^2, x_1^2 + (x_2 - 1)^2]$. The negative subgradient is indicated by the black arrow.

Constant stepsize does not work

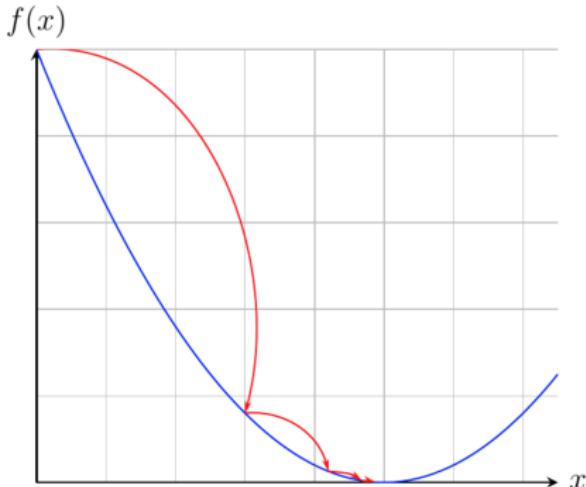
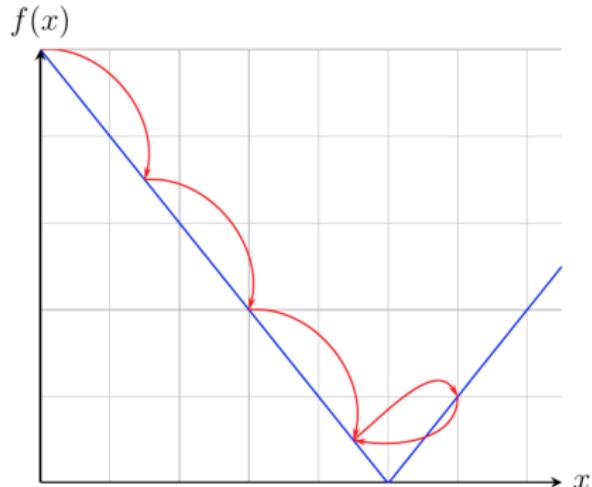


Figure 3. The effect of a constant stepsize on non-differentiable (left) and smooth (right) functions.

Now suppose $f(x)$ is convex but not necessarily differentiable.

$$\begin{aligned}x^{k+1} &\leftarrow \min_x f(x^k) + \langle g^k, x - x^k \rangle + \frac{1}{2\alpha_k} \|x - x^k\|_2^2, \quad g^k \in \partial f(x^k) \\ \implies x^{k+1} &\leftarrow x^k - \alpha_k g^k\end{aligned}$$

Stepsize:

- Fixed stepsize: $\alpha_k = \alpha$;
- Fixed $\|x^{k+1} - x^k\|$, i.e., $\alpha_k \|g^k\|$ is constant;
- Diminishing $\alpha_k \rightarrow 0$ and $\sum_{k=0}^{\infty} \alpha_k = +\infty$.

- 1 Algorithm
- 2 Convergence
- 3 Example
- 4 Subgradient Projection Method

Assumption 1

Suppose $f(x)$ satisfies

- ① f is convex.
- ② f has at least one minimizer x^* , and $f(x^*) > -\infty$.
- ③ f is Lipschitz continuous,

$$|f(x) - f(y)| \leq G\|x - y\|, \quad \forall x, y \in \mathbb{R}^n,$$

where $G > 0$ is Lipschitz constant.

Lemma 2

Suppose $f(x)$ is convex. $f(x)$ is G -Lipschitz continuous if and only if f has bounded subgradients, i.e.,

$$\|g\| \leq G, \quad \forall g \in \partial f(x), \quad x \in \mathbb{R}^n.$$

Proof.

(\Rightarrow) Suppose $\|g\| \leq G$ for any subgradient. Now choose $g_y \in \partial f(y)$, $g_x \in \partial f(x)$, it follows from convexity that

$$g_x^T(x - y) \geq f(x) - f(y) \geq g_y^T(x - y).$$

Cauchy-Schwartz inequality yields

$$\begin{aligned} g_x^T(x - y) &\leq \|g_x\| \|x - y\| \leq G \|x - y\|, \\ g_y^T(x - y) &\geq -\|g_y\| \|x - y\| \geq -G \|x - y\|. \end{aligned}$$

This leads

$$|f(x) - f(y)| \leq G \|x - y\|.$$

(\Leftarrow) Suppose $f(x)$ is Lipschitz continuous. Suppose by contradiction that there exists x and $g \in \partial f(x)$ such that $\|g\| > G$. Now choose $y = x + \frac{g}{\|g\|}$, it holds that

$$f(y) \geq f(x) + g^T(y - x) = f(x) + \|g\| > f(x) + G,$$

contradicting with the Lipschitz continuity. □

Theorem 3

Let x^* be a minimizer of f , $f^* = f(x^*)$, and $\{x^k\}$ be generated by SG, for any $k \geq 0$,

$$2 \left(\sum_{i=0}^k \alpha_i \right) \left(\min_{0 \leq i \leq k} f(x^i) - f^* \right) \leq \|x^0 - x^*\|^2 + \sum_{i=0}^k \alpha_i^2 G^2.$$

Proof.

The SG iteration yields

$$\begin{aligned} \|x^{i+1} - x^*\|^2 &= \|x^i - \alpha g^i - x^*\|^2 \\ &= \|x^i - x^*\|^2 - 2\alpha_i \langle g^i, x^i - x^* \rangle + \alpha_i^2 \|g^i\|^2 \\ &\leq \|x^i - x^*\|^2 - 2\alpha_i (f(x^i) - f^*) + \alpha_i^2 G^2, \end{aligned}$$

The last inequality follows from the definition of subgradient and $\|g^i\| \leq G$. □

Proof.

It follows that

$$2\alpha_i(f(x^i) - f^*) \leq \|x^i - x^*\|^2 - \|x^{i+1} - x^*\|^2 + \alpha_i^2 G^2.$$

Summing up both sides,

$$\begin{aligned} 2 \sum_{i=0}^k \alpha_i(f(x^i) - f^*) &\leq \|x^0 - x^*\|^2 - \|x^{k+1} - x^*\|^2 + G^2 \sum_{i=0}^k \alpha_i^2 \\ &\leq \|x^0 - x^*\|^2 + G^2 \sum_{i=0}^k \alpha_i^2. \end{aligned}$$

On the other hand,

$$\sum_{i=0}^k \alpha_i(f(x^i) - f^*) \geq \left(\sum_{i=0}^k \alpha_i \right) \left(\min_{0 \leq i \leq k} f(x^i) - f^* \right).$$

Combining above two inequalities yields the result.

$$2 \left(\sum_{i=0}^k \alpha_i \right) (\min_{0 \leq i \leq k} f(x^i) - f^*) \leq \|x^0 - x^*\|^2 + \sum_{i=0}^k \alpha_i^2 G^2.$$

Corollary 4

- Fix $\alpha_i = t$. Then

$$\min_{0 \leq i \leq k} f(x^i) - f^* \leq \frac{\|x^0 - x^*\|^2}{2kt} + \frac{G^2 t}{2} \rightarrow \frac{G^2 t}{2}$$

- Fix $\|x^{k+1} - x^k\| = \alpha_i \|g^i\| = s$. Then

$$\min_{0 \leq i \leq k} f(x^i) - f^* \leq \frac{G\|x^0 - x^*\|^2}{2ks} + \frac{Gs}{2} \rightarrow \frac{Gs}{2}$$

- For diminishing α_i satisfying $\sum_{i=0}^{\infty} \alpha_i = \infty$ and $\sum_{i=0}^{\infty} \alpha_i^2 < \infty$, it holds

$$\min_{0 \leq i \leq k} f(x^i) - f^* \leq \frac{\|x^0 - x^*\|^2 + G^2 \sum_{i=0}^k \alpha_i^2}{2 \sum_{i=0}^k \alpha_i} \rightarrow 0.$$

Suppose total budget k is given. Let $\|x^0 - x^*\| = R$, the first case yields

$$\min_{0 \leq i \leq k} f(x^i) - f^* \leq \frac{R^2}{2kt} + \frac{G^2t}{2} \leq \frac{R^2}{2kt} + \frac{G^2t}{2}$$

If t satisfying $\frac{R^2}{2kt} = \frac{G^2t}{2}$ and $t = \frac{R}{G\sqrt{k}}$, then

$$\min_{0 \leq i \leq k} f(x^i) - f^* \leq \frac{GR}{\sqrt{k}}.$$

To get $\min_{0 \leq i \leq k} f(x^i) - f^* \leq \epsilon$, need choose

$$k = O(1/\epsilon^2) \quad \text{and} \quad \alpha_k = O(1/\sqrt{k}).$$

The second case has similar result.

- 1 Algorithm
- 2 Convergence
- 3 Example
- 4 Subgradient Projection Method

Example

LASSO regression:

$$\min_x f(x) = \frac{1}{2} \|Ax - b\|^2 + \mu \|x\|_1$$

The subgradient of f is given

$$g = A^T(Ax - b) + \mu \text{sign}(x)$$

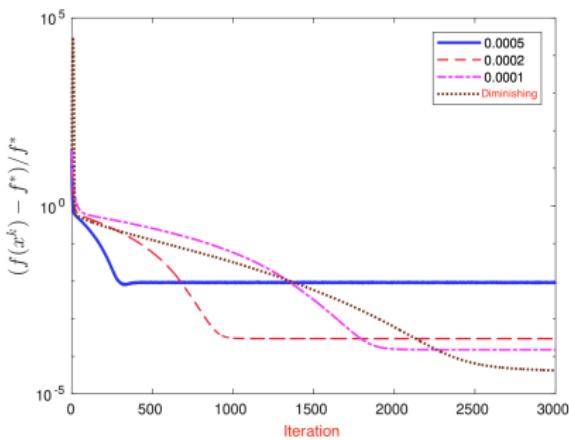
The algorithm is

$$x^{k+1} = x^k - \alpha_k(A^T(Ax^k - b) + \mu \text{sign}(x^k))$$

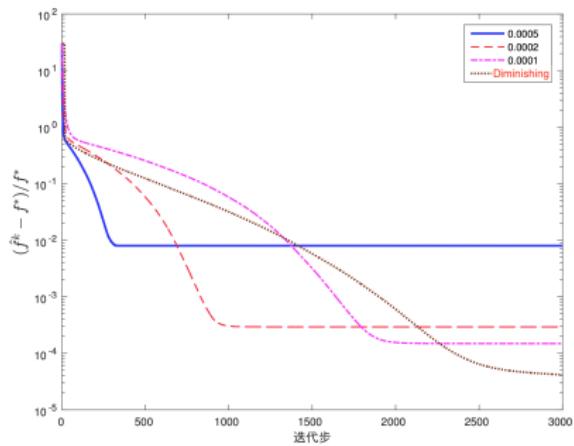
Stepsize choices:

$$\alpha_k = 0.0005, 0.0002, 0.0001, \quad \alpha_k = \frac{0.002}{\sqrt{k}}.$$

Example



(a) $f(x^k) - f^*$



(b) $\hat{f}^k - f^*$

- 1 Algorithm
- 2 Convergence
- 3 Example
- 4 Subgradient Projection Method

Constraint case:

$$\min f(x) \quad \text{s.t. } x \in \Omega$$

Subgradient Projection Method: choose $\mathbf{g}^k \in \partial f(x^k)$,

$$\begin{aligned} x^{k+1} &\leftarrow \arg \min_{x \in \Omega} \langle \mathbf{g}^k, x \rangle + \frac{1}{2\eta_k} \|x^k - x\|_2^2 \\ &= \arg \min_{x \in \Omega} \|\eta_k \mathbf{g}^k\|_2^2 + 2\eta_k \langle \mathbf{g}^k, x - x^k \rangle + \|x^k - x\|_2^2 \\ &= \arg \min_{x \in \Omega} \|x - x^k - \eta_k \mathbf{g}^k\|_2^2 \\ &= P_\Omega(x^k - \eta_k \mathbf{g}^k), \end{aligned}$$

Theorem 5

Let $\Omega \subset \mathbb{R}^d$ be a closed non-empty convex set with diameter D , i.e., $\max_{x,y \in \Omega} \|x - y\| \leq D$. Let f be a convex function from $\Omega \subset \mathbb{R}^d$ to \mathbb{R} . Set $x^1 \in \Omega$. Set $g^k \in \partial f(x^k)$. Then, $\forall u \in \Omega$, the following convergence bounds hold:

$$f\left(\frac{1}{T} \sum_{k=1}^T x^k\right) - f(x^*) \leq \frac{D^2}{\eta_T} + \frac{\sum_{k=1}^T \eta_k \|g^k\|_2^2}{2T},$$

$$f\left(\frac{\sum_{k=1}^T \eta_k x^k}{\sum_{k=1}^T \eta_k}\right) - f(x^*) \leq \frac{\|x^1 - u\|_2^2 + \sum_{k=1}^T \eta_k^2 \|g^k\|_2^2}{2 \sum_{k=1}^T \eta_k},$$

$$\min_{1 \leq k \leq T} f(x^k) - f(x^*) \leq \min\left(\frac{D^2}{\eta_T} + \frac{\sum_{k=1}^T \eta_k \|g^k\|_2^2}{2T}, \frac{\|x^1 - u\|_2^2 + \sum_{k=1}^T \eta_k^2 \|g^k\|_2^2}{2 \sum_{k=1}^T \eta_k}\right).$$