

Zishuo Wang

Adaptive Computing Laboratory

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RESEARCH INTERESTS

My current research topics cover 2D & 3D visual understanding, navigation, and autonomous system design. My research vision is to develop intelligent robots capable of perceiving and acting sensibly in dynamic, uncertain real-world environment.

EDUCATION

National University of Singapore

Aug 2022 - Jun 2024 (Expected)

M.S. student in Computing (AI track), GPA: 4.67/5.0

Advisor: [Prof. David Hsu](#)

Harbin Institute of Technology

Aug 2018 - Jun 2022

B.E. in Automation and B.E. in Artificial Intelligence, GPA: 90.57/100

Advisor: [Prof. Huijun Gao](#)

RESEARCH

Out-of-distribution Detection for Robust Navigation with Learned Controllers

Jan 2023 – present

Graduate RA with [Prof. David Hsu](#)

Adaptive Computing Laboratory, NUS

- Utilized VAE structure within imitation learning to develop a controller which can handle both multi-behavior navigation and anomaly detection.
- Designed behavior recovery framework with anomaly detection. (In progress)
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Hatch Identification Method for Bulk Carrier

Aug 2021 – Jun 2022

Undergraduate RA with [Prof. Huijun Gao](#)

Research Institute of Intelligent Control and System, HIT

- Merged point cloud data collected from multiple lidars using geometric transformation matrix to reconstruct the entire ship and calculate its pose. Built a ship part segmentation dataset with the reconstructed ship model.
- Designed a novel algorithm combining PointNet-based 3D point cloud segmentation with classic 2D image processing method for hatch identification and localization.
- Contributed to the perception module for automatic coal loading at Tianjin Port, demonstrating the practical applicability of the developed approach.

Anti-photographic Detection Algorithm Based on Semi-supervised Learning

Aug 2021 – Jun 2022

Undergraduate RA with [Prof. Hongzhi Zhang](#)

Center on Machine Learning Research, HIT

- Constructed an object detection dataset of photographic devices by crawling search engines and simulating photographic scenarios then trained a basic detection network based on FCOS.
- Fine-tuned and retrained the network based on pseudo-label algorithm, which improved the accuracy and robustness of the system, expanding the range of detectable devices.
- Developed a system with good generalizability and accuracy for detecting various photographic equipment, including different styles of phones, cameras, monitors, etc.

PROJECT

Table Curling Robot

Sep 2020 – Sep 2021

Project Lead; Advisor: [Prof. Dandan Li](#)

Nvidia A.I. & Control Research Center, HIT

- Devised hierarchical control strategy: High-level planning with vision and low-level PID steer control.
- Detected and localized the existing stones with image processing algorithm, containing auto-perspective transformation, edge detection, and circle detection. Subsequent strategic maneuvers were planned in accordance with the spatial distribution of stones within the house.
- Enabled the robot to autonomously return to the starting point by using a road-following algorithm based on Resnet18 which can predict the next direction, and accelerated the inference using TensorRT.

Biomedical Image Segmentation for Brain Tumour

July 2021 – Aug 2021

Team Lead in [Imperial data science summer school](#)

Data Science Institute, Imperial College London

- Proposed medical image segmentation approach for raw MRI dataset based on modified U-net.
- Performed data preprocessing and augmentation techniques on 3D MRI data to enhance model generalization.

- Designed a loss function with dice coefficient, leading to a significant improvement of 16.3% in dice score on the validation set compared to the baseline. The project received a grade A in the summer school.

Intelligent Vision PTZ for Face Tracking and Alerting

Nov 2019 – Nov 2020

Project Lead; Advisor: Prof. Jiawei Wang

Center for Experimental Flight Vehicle Control Education, HIT

- Built a 2-Dof Vision PTZ with two servos for controlling the PTZ's pose and one camera for tracking the face.
- Implemented the Cascade Classifier algorithm for human face detection and applied a PD controller for accurate tracking.
- Face recognition. Extracted face descriptor from the detected face through Resnet34, comparing with a database for identification. The system alerted the user in case of a stranger and captured the face image, sending a message to the host.

Multi-legged Bionic Robot

Sep 2018 – Sep 2019

Project Lead; Advisor: Prof. Jiawei Wang

Center for Experimental Flight Vehicle Control Education, HIT

- Built a quadrupedal/hexapedal robot system capable of avoiding obstacles with ultrasonic distance measurer and following lines with gray-scale measurer based on Arduino.
- Developed a biomimetic gait control algorithm for legged locomotion and deployed it on a real robot.

SELECTED AWARDS AND HONORS

- 8841 Impact Scholarship *2021*
- Excellent Student Leader *2019, 2020*
- Merit Student *2021*
- Individual Scholarship *2020, 2021*

SKILLS

- **Programming:** Python, C/C++, MATLAB, Verilog, HTML
- **Software & Tools:** ROS, PyTorch, OpenCV, AutoCAD, Multism, Altium Designer, ISE Design, Git, L^AT_EX
- **Hardware:** Multiple Motors and Sensors, Arduino, Raspberry Pi, Nvidia Jetson, Basic Mechanical Design
- **Languages:** Chinese: Native. English: IELTS: 7, GRE: 326+3.5