ACMICPC Standard Code Library

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1 Math

1.1 fft

```
// Copyright [2017] <dmnsn7>
 2
 3
   #include <bits/stdc++.h>
    using std;
 5
   const double PI = acos(-1);
 6
    struct Complex {
 7
      double x, y;
Complex() {
 8
 9

\begin{array}{ll}
x &=& 0; \\
y &=& 0;
\end{array}

10
11
12
      Complex (double _x, double _y) {
13
        x = \underline{x};

y = \underline{y};
14
15
16
      Complex operator - (const Complex &b) const {
17
18
        return Complex (x - b.x, y - b.y);
19
      Complex operator+(const Complex &b) const {
20
21
        return Complex (x + b.x, y + b.y);
22
23
      Complex operator*(const Complex &b) const {
24
        return Complex(x * b.x - y * b.y, x * b.y + y * b.x);
25
26
    };
27
    void change (Complex y [], int len) {
28
      for (int i = 1, j = len / 2; i < len - 1; i++) {
29
        if (i < j) 
30
          swap(y[i], y[j]);
31
32
33
        int k = len / 2;
34
35
        while (j >= k) {
36
           j = k;
          k /= 2;
37
38
39
        if (j < k) 
40
          j += k;
41
42
43
      }
44
    }
45
    void fft (Complex y[], int len, int on) {
46
      change (y, len);
47
48
      for (int h = 2; h \le len; h \le 1) {
        Complex wn(cos(-on * 2 * PI / h), sin(-on * 2 * PI / h));
49
50
51
        for (int j = 0; j < len; j += h) {
52
           Complex w(1, 0);
53
           for (int k = j; k < j + h / 2; k++) {
54
             Complex u = y[k];
55
56
             Complex t = w * y[k + h / 2];
57
             y[k] = u + t;
             y[k + h / 2] = u - t;
58
59
             w = w * wn;
60
        }
61
62
      }
63
64
      if (on = -1) {
        for (int i = 0; i < len; i++) {
65
```

```
66
          y[i].x /= len;
67
68
69
   }
        String
   2.1
         \mathbf{sa}
    // Copyright [2017] <dmnsn7>
 1
 3
   int r[maxn], wa[maxn], wb[maxn], wv[maxn], ws[maxn], sa[maxn];
 4
    int rank [maxn], height [maxn];
 5
 6
7
    /*
             nn -10
 8
               sasa[1] \sim sa[n]
     *
 9
            rankrank [0]~rank [n
     *
                                  -1],
         h\,e\,i\,g\,h\,t\,i\,i
10
                         −12~ nsa
     *
11
12
    inline bool cmp(int *r, int a, int b, int 1) {
13
14
      return r[a] = r[b] \&\& r[a+1] = r[b+1];
15
   }
16
17
    void da(int n, int m) {
18
      int i, j, p, *x = wa, *y = wb;
19
20
      for (i = 0; i < m; i++) {
21
        ws[i] = 0;
22
23
24
      for (i = 0; i < n; i++) {
25
        ws[x[i] = r[i]]++;
26
27
      for (i = 1; i < m; i++) {
28
29
        ws[i] += ws[i - 1];
30
31
32
      for (i = n - 1; i >= 0; i--) {
33
        \operatorname{sa}[--\operatorname{ws}[x[i]]] = i;
34
35
      for (j = 1, p = 1; p < n; j <<= 1, m = p) {
36
37
        for (p = 0, i = n - j; i < n; i++) {
38
          y[p++] = i;
39
40
        for (i = 0; i < n; i++)
41
          if(sa[i] >= j) \{ y[p++] = sa[i] - j;
42
43
44
45
        for (i = 0; i < n; i++) {
46
          wv[i] = x[y[i]];
47
48
49
        for (i = 0; i < m; i++) {
50
51
          ws[i] = 0;
52
53
        for (i = 0; i < n; i++) {
54
55
          ws[wv[i]]++;
56
57
        for (i = 1; i < m; i++) {
58
59
          ws[i] += ws[i - 1];
60
```

```
61
62
        for (i = n - 1; i >= 0; i--) {
63
          \operatorname{sa}[--\operatorname{ws}[\operatorname{wv}[i]]] = \operatorname{y}[i];
64
65
66
        swap(x, y);
67
        for (p = 1, x[sa[0]] = 0, i = 1; i < n; i++) {
68
69
          x[sa[i]] = cmp(y, sa[i-1], sa[i], j) ? p - 1 : p++;
70
71
      }
72
73
      return;
74
75
76
    void calheitght(int n) {
      int\ i\ ,\ j\ ,\ k\ =\ 0\,;
77
78
79
      for (i = 1; i < n; i++) {
        rank[sa[i]] = i;
80
81
82
83
      // print(rank, n);
84
      for (i = 0; i < n; height [rank[i++]] = k)
85
        for (k ? k - : 0, j = sa[rank[i] - 1]; r[i + k] = r[j + k]; k++)
86
87
88
      return;
   }
89
   2.2 sam
    // Copyright [2017] <dmnsn7>
 3
    void copy(int x, int y) {
 4
      pre[x] = pre[y];
 5
      len[x] = len[y];
      memcpy(son[x], son[y], sizeof son[0]);
 6
 7
 8
9
    void insert(int c, int l) {
10
      int p = tail, np = ++tot;
11
      len[np] = 1;
12
      tail = np;
13
      while (p \&\& son[p][c] == 0) {
14
15
        son[p][c] = np, p = pre[p];
16
17
18
      if (p = 0) {
19
        pre[np] = root;
20
      } else {
21
        int q = son[p][c];
22
23
        if (len[p] + 1 = len[q]) {
24
           pre[np] = q;
25
          else {
           int n\dot{q} = ++tot;
26
27
           copy(nq, q);
28
           len[nq] = len[p] + 1;
29
           pre[np] = pre[q] = nq;
30
31
           while (p \&\& son[p][c] = q) {
32
             son[p][c] = nq, p = pre[p];
33
        }
34
      }
35
36
37
   void build(int n) {
```

```
39
      for (int i = 1; i \le tot; i++) {
40
         cnt [len[i]]++;
41
42
43
      for (int i = 1; i \le n; i++) {
         \operatorname{cnt}[i] += \operatorname{cnt}[i-1];
44
45
46
47
      for (int i = 1; i \le tot; i++) {
48
        b[--cnt[len[i]]] = i;
49
50
51
      for (int i = tot - 1; i >= 0; i--) {
52
         int_{p} = b[i], k = 0;
        g[p] = 1;
53
54
         for (int j = 0; j < 26; j++)
55
56
           if (son[p][j]) {
             int v = son[p][j];
57
58
             g[p] += g[v];
59
             son[p][k] = v;
             \operatorname{gao}[v] = j + 'a';
60
61
             k++;
62
63
64
         son[p][k] = 0;
65
   }
66
    2.3 kmp
    // Copyright [2017] <dmnsn7>
 2
 3
    void getFail() {
 4
      m = strlen(s);
      f[0] = f[1] = 0;
 6
 7
      for (int i = 1; i < m; i++) {
 8
         int j = f[i];
 9
10
         while (j \&\& s[i] != s[j]) \{
11
           j = f[j];
12
13
14
         f[i + 1] = s[i] == s[j] ? j + 1 : 0;
15
16
   }
    2.4 ac
    // Copyright [2017] <dmnsn7>
 2
    void init() {
 3
 4
      sz = 1;
 5
      ch[0].init();
 6
    void build() {
 7
      queue\langle int \rangle q;
ch [0]. fail = 0;
 8
9
10
11
      for (int c = 0; c < 4; c++) {
12
         int u = ch[0].next[c];
13

if (u) {
 ch[u]. fail = 0;}

14
15
           q. push(u);
16
17
18
      }
19
```

```
20
      while (!q.empty()) {
21
         int r = q.front();
22
         q.pop();
23
24
         for (int c = 0; c < 4; c++) {
25
           int u = ch[r].next[c];
26
27
           if (!u) {
28
              \operatorname{ch}[r].\operatorname{next}[c] = \operatorname{ch}[\operatorname{ch}[r].\operatorname{fail}].\operatorname{next}[c];
29
              continue;
30
           }
31
32
           q. push(u);
           int v = ch[r].fail;
33
34
35
           while (v \&\& ! ch[v]. next[c]) {
36
              v = ch[v]. fail;
37
38
           ch[u]. fail = ch[v]. next[c];
39
           ch[u].isend = ch[ch[u].fail].isend;
40
41
42
   }
43
        Geometry
    3.1 c2c
    // Copyright [2017] <dmnsn7>
 3
   Point rotate (const Point &p, double cost, double sint) {
 4
      double x = p.x, y = p.y;
 5
      return Point(x * cost - y * sint, x * sint + y * cost);
 6
 8
    void circle_cross_circle(Circle a, Circle b, Point cro[]) {
      double d = (a.o - b.o).len();
 9
10
      double cost = (a.r * a.r + d * d - b.r * b.r) / (2 * a.r * d);
      double sint = sqrt(max(1.0 - cost * cost, 0.0));
11
      Point v = (b.o - a.o) * (a.r / d);
      \operatorname{cro}[0] = \operatorname{a.o} + \operatorname{rotate}(v, \operatorname{cost}, -\operatorname{sint});
14
      \operatorname{cro}[1] = \operatorname{a.o} + \operatorname{rotate}(v, \operatorname{cost}, \operatorname{sint});
15
    3.2 c2l
    // Copyright [2017] <dmnsn7>
 1
    Point crosspt (const Point &a, const Point &b, const Point &p, const Point &q) {
 3
      4
 5
 6
 7
    double sector_area (const Point &a, const Point &b) {
 8
 9
      double theta = atan2(a.y, a.x) - atan2(b.y, b.x);
10
11
      while (theta \leq 0) {
12
         theta += 2 * PI;
13
14
15
      while (theta > 2 * PI) {
16
         theta -= 2 * PI;
17
18
19
      theta = min(theta, 2 * PI - theta);
20
      return r * r * theta / 2;
21
    double sqr(double x) \{ return x * x; \}
```

```
void circle_cross_line(Point a, Point b, Point o, double r, Point ret[],
23
24
                                const int &num) {
      double x0 = o.x, y0 = o.y;
25
      double x1 = a.x, y1 = a.y; double x2 = b.x, y2 = b.y;
26
27
      double dx = x2 - x1, dy = y2 - y1;
28
29
      double A = dx * dx + dy * dy;
30
      double B = 2 * dx * (x1 - x0) + 2 * dy * (y1 - y0);
31
      double C = sqr(x1 - x0) + sqr(y1 - y0) - sqr(r);
32
      double delta = B * B - 4 * A * C;
33
      num = 0;
34
35
      if (dlcmp(delta) >= 0) {
36
         double t1 = (-B - \operatorname{sqrt}(\max(\operatorname{delta}, 0.0))) / (2 * A);
37
         double t2 = (-B + \operatorname{sqrt}(\max(\operatorname{delta}, 0.0))) / (2 * A);
38
         if (dlcmp(t1 - 1) \le 0 \&\& dlcmp(t1) >= 0) {
39
40
           ret[num++] = Point(x1 + t1 * dx, y1 + t1 * dy);
41
42
         if (dlcmp(t2 - 1) \le 0 \&\& dlcmp(t2) >= 0) {
43
44
           ret[num++] = Point(x1 + t2 * dx, y1 + t2 * dy);
45
      }
46
47
48
    double calc (const Point &a, const Point &b) {
49
      Point p[2];
50
      int num = 0;
      int ina = dlcmp(a.len() - r) < 0;
51
      int inb = dlcmp(b.len() - r) < 0;
52
53
54
      if (ina)
55
         if (inb)
56
           return fabs (a * b) / 2;
57
         } else {
58
           circle_cross_line(a, b, Point(0, 0), r, p, num);
59
           return sector_area(b, p[0]) + fabs(a * p[0]) / 2;
60
61
      } else {
62
         if (inb) {
            \begin{array}{l} circle\_cross\_line(a,\ b,\ Point(0,\ 0),\ r,\ p,\ num);\\ return\ sector\_area(p[0],\ a)\ +\ fabs(p[0]\ *\ b)\ /\ 2; \end{array} 
63
64
65
         } else {
           circle_cross_line(a, b, Point(0, 0), r, p, num);
66
67
68
           if (false) {
              return sector\_area(a, p[0]) + sector\_area(p[1], b) +
69
70
                      fabs(p[0] * p[1]) / 2;
71
           } else {
72
             return sector_area(a, b);
73
           }
74
         }
      }
75
76
77
    double area() {
      double ret = 0;
78
79
80
      for (int i = 0; i < n; i++) {
81
         int sgn = dlcmp(res[i] * res[i + 1]);
82
         if (sgn != 0) {
83
84
           ret += sgn * calc(res[i], res[i+1]);
85
86
87
88
      return ret;
89
```

3.3 halfplaneintersection

```
// Copyright [2017] <dmnsn7>
3
   struct Halfplane {
      Point a, b;
4
5
      Halfplane() {}
      Halfplane (Point a, Point b) : a(a), b(b) {}
 6
 7
8
      bool satisfy (const Point &rhs) const { return sgn((rhs - a) * (b - a)) \le 0; }
9
     bool operator < (const Halfplane &rhs) const {
10
        int res = sgn((b - a).arg() - (rhs.b - rhs.a).arg());
11
        return res = 0? rhs.satisfy(a): res < 0;
12
13
   };
14
   Point crosspoint (const Halfplane &a, const Halfplane &b) {
15
     double k = (b.a - b.b) * (a.a - b.b);
16
     k = k / (k - ((b.a - b.b) * (a.b - b.b));
17
18
      return a.a + (a.b - a.a) * k;
19
   }
20
21
   vector < Point > halfplaneIntersection (vector < Halfplane > v) {
22
      sort (v. begin (), v. end ());
      deque < Halfplane > q;
23
     deque<Point> ans;
24
25
     q.push_back(v[0]);
26
27
      for (int i = 1; i < v.size(); i++) {
28
        if (sgn((v[i-1].b-v[i-1].a)*(v[i].b-v[i].a)) = 0) {
29
          continue;
30
31
32
        while (ans. size() > 0 \&\& !v[i]. satisfy(ans.back())) {
33
          ans.pop_back();
34
          q.pop_back();
35
36
37
        while (ans.size() > 0 \&\& !v[i].satisfy(ans.front())) {
38
          ans.pop_front();
39
          q.pop_front();
40
41
42
        ans.push_back(crosspoint(q.back(), v[i]));
43
        q.push_back(v[i]);
     }
44
45
46
      while (ans.size() > 0 && !q.front().satisfy(ans.back())) {
47
        ans.pop_back();
48
        q.pop_back();
     }
49
50
51
      while (ans.size() > 0 && !q.back().satisfy(ans.front())) 
52
        ans.pop_front();
53
        q.pop_front();
54
55
56
     ans.push_back(crosspoint(q.back(), q.front()));
57
      return vector < Point > (ans.begin(), ans.end());
58
59
   double area (const vector < Point > &p, int ansi) {
60
61
      double res = 0;
62
      for (int i = ansi; i + 1 < p.size(); i++) {
63
        res += p[i] * p[i + 1];
64
65
66
67
     res += p.back() * p[ansi];
```

```
68
      return fabs (res) / 2;
69
    }
70
71
    double ptol(Point a, Point b, Point c) {
       double are = fabs((b - a) * (c - a));
72
       return are / (b - c).len();
73
74
75
    int\ \underline{\mathrm{main}}\left(\right)\ \{
76
      int T_T, n, nc = 0; cin >> T_T;
77
78
       Point _{0}(0, 0), _{1}(1, 0), _{2}(1, 1), _{3}(0, 1);
79
80
       while (T T--) {
81
         printf("Case #%d:\n", ++nc);
82
83
         scanf("%d", &n);
84
85
         for (int i = 0; i < n; i++) {
86
           p[i].input();
87
88
89
         for (int i = 0; i < n; i++) {
90
           vector < Halfplane > v;
           v.push_back(Halfplane(__0, __1));
91
92
           v.push_back(Halfplane(__1, __2));
           v.push_back(Halfplane(__2, __3));
93
           v.push_back(Halfplane(__3, __0));
94
95
           for (int j = 0; j < n; j++)
96
             if (i != j) {
97
                Point a = (p[i] + p[j]) / 2;
98
                Point b = a + (p[i] - p[j]) \cdot rev();
99
100
101
                if (!Halfplane(a, b).satisfy(p[i])) {
102
                  swap(a, b);
103
104
105
                v.push_back(Halfplane(a, b));
106
107
108
           vector < Point > ans = halfplaneIntersection(v);
109
110
           double ret = 0, low = 1e100;
111
           int ansi = 0;
112
           for (int j = 0; j < ans.size(); j++)
113
114
             if (ans[j].z() < low) {
115
               low = ans[j].z(), ansi = j;
116
117
118
           for (int j = 0; j < ansi; j++) {
             ans.push_back(ans[j]);
119
120
121
122
           ret = area(ans, ansi) * low;
123
           for (int j = ansi + 1; j + 1 < ans.size(); j++) {
124
125
             double ll = (ans[j] - ans[j + 1]).len();
126
127
             if (11 < eps) {
128
                continue;
129
130
             double s = (ans[j].z() + ans[j + 1].z() - low * 2) * ll / 2;
131
             double h = ptol(ans[ansi], ans[j], ans[j + 1]);
132
133
             ret += s * h / 3;
134
135
           printf("\%.6f\n", ret);
136
```

```
137
           }
138
139
140
         return 0;
141
           DataStruct
           \mathbf{lct}
      4.1
      // Copyright [2017] <dmnsn7>
      \label{eq:channel} \operatorname{int} \ \operatorname{ch}\left[\operatorname{MAXN}\right]\left[\,2\,\right] \;, \ \operatorname{pre}\left[\operatorname{MAXN}\right] \;, \ \operatorname{key}\left[\operatorname{MAXN}\right] \;;
  3
      \label{eq:maxn} \verb"int" add [MAXN"] \;,\;\; \verb"Max [MAXN"] \;,\;\; \verb"rev" [MAXN] \;,\;\; n\;;
  4
      bool rt [MAXN];
  6
      void update_add(int r, int d) {
  7
         if (!r) {
            return;
  9
 10
        \begin{array}{lll} \ker \, [\, r \,] & +\!\!\! = d \, ; \\ \operatorname{add} \, [\, r \,] & +\!\!\! = d \, ; \end{array}
 11
 12
        \operatorname{Max}[r] += d;
 13
 14
      void update_rev(int r) {
 15
         if (!r) {
 16
17
           return;
 18
 19
 20
         swap(ch[r][0], ch[r][1]);
 21
         rev[r] = 1;
 22
 23
      void push_down(int r) {
 24
         if (add[r])
 25
            update_add(ch[r][0], add[r]);
            update_add(ch[r][1], add[r]);
26
27
            add[r] = 0;
 28
         }
 29
         if (rev[r]) {
 30
 31
            update_rev(ch[r][0]);
 32
            update_rev(ch[r][1]);
 33
            rev[r] = 0;
 34
         }
 35
 36
      void display()
        37
 38
 39
 40
 41
      void \ push\_up(int \ r) \ \{ \ Max[r] = max(max(Max[ch[r][0]] \ , \ Max[ch[r][1]]) \ , \ key[r]); \ \}
 42
 43
      void rotate(int x) {
         int y = pre[x], kind = ch[y][1] == x;
 44
         \operatorname{ch}[y][\operatorname{kind}] = \operatorname{ch}[x][!\operatorname{kind}];
 45
 46
         pre[ch[y][kind]] = y;
 47
         pre[x] = pre[y];
 48
         pre[y] = x;
 49
         ch[x][!kind] = y;
 50
         if \quad (\,rt\,[\,y\,]\,) \quad \{\,
 51
            rt[y] = 0, rt[x] = 1;
 52
 53
         } else {
            ch[pre[x]][ch[pre[x]][1] == y] = x;
 54
 55
 56
 57
         push_up(y);
 58
```

```
void P(int r) {
59
       if (!rt[r]) {
60
61
        P(pre[r]);
62
63
64
      push_down(r);
65
66
    void splay(int r) {
67
      P(r);
68
69
      while (!rt[r]) {
         int \hat{f} = pre[r], ff = pre[f];
70
71
         if (rt[f]) {
72
73
           rotate(r);
          else if ((ch[ff][1] = f) = (ch[f][1] = r)) {
74
75
           rotate(f), rotate(r);
76
          else {
77
           rotate(r), rotate(r);
78
79
      }
80
81
      push_up(r);
82
83
    int access(int x)  {
84
      int y = 0;
85
86
       for (; x; x = pre[y = x]) {
87
         splay(x);
         rt[ch[x][1]] = 1, rt[ch[x][1] = y] = 0;
88
89
        push\_up(x);
90
91
92
      return y;
93
    bool judge(int u, int v) {
94
95
       while (pre[u]) {
96
        u = pre[u];
97
98
99
      while (pre[v]) {
100
        v = pre[v];
101
102
      return u == v;
103
104
105
    void mroot(int r) {
106
      access(r);
107
      splay(r);
108
      update_rev(r);
109
    void lca (const int &u, const int &v) {
110
111
       access(v), v = 0;
112
                         ----");display();
113
       // puts("---
       while (u) {
114
115
         splay(u);
116
         if (!pre[u]) {
117
          return;
118
119
120
121
         rt[ch[u][1]] = 1;
         rt[ch[u][1] = v] = 0;
122
123
         push_up(u);
124
         u = pre[v = u];
125
126
    }
```

```
127
     void link(int u, int v) {
128
        if (judge(u, v)) {
129
           puts ("-1");
130
           return;
131
132
133
        mroot(u);
134
        pre[u] = v;
135
     void cut(int u, int v) {
136
        if (\mathbf{u} = \mathbf{v} \mid | ! \mathbf{j} \mathbf{u} \mathbf{d} \mathbf{g} \mathbf{e} (\mathbf{u}, \mathbf{v}))  {
137
           puts ("-1");
138
139
           return;
        }
140
141
142
        mroot(u);
143
        splay(v);
144
        \operatorname{pre}\left[\operatorname{ch}\left[\mathbf{v}\right]\left[0\right]\right] = \operatorname{pre}\left[\mathbf{v}\right];
145
        pre[v] = 0;
        rt[ch[v][0]] = 1;
146
147
        ch[v][0] = 0;
148
        push\_up(v);
149
150
     void ADD(int u, int v, int w) {
151
        if (!judge(u, v)) {
152
           puts ("-1");
153
           return;
154
155
156
        lca(u, v);
157
        update\_add(ch[u][1], w);
158
        update_add(v, w);
159
        \text{key}[\mathbf{u}] += \mathbf{w};
160
        push_up(u);
161
162
     void query(int u, int v) {
163
        if (!judge(u, v)) {
164
           puts("-1");
165
           return;
166
167
168
        lca(u, v);
169
        printf("\%d\n", max(max(Max[v], Max[ch[u][1]]), key[u]));
170
     vector <int> G[MAXN];
171
172
     int que [MAXN];
     void bfs() {
173
174
        int front = 0, rear = 0;
175
        que [rear++] = 1;
        pre[1] = 0;
176
177
178
        while (front < rear) {
179
           int u = que[front++];
180
181
           for (int i = 0; i < G[u].size(); i++) {
             int v = G[u][i];
182
183
184
              if (v = pre[u]) {
185
                continue;
186
187
188
             pre[v] = u;
189
             que[rear++] = v;
190
191
192
193
     int main() {
194
        int \ q\,,\ u\,,\ v\,;
```

```
195
        while (~scanf("%d", &n)) {
196
197
           memset(add, 0, sizeof add);
          memset(pre, 0, sizeof pre);
memset(rev, 0, sizeof rev);
memset(ch, 0, sizeof ch);
198
199
200
201
202
           for (int i = 0; i \le n; i++) {
             G[i].clear();
203
204
             rt[i] = 1;
205
206
207
          Max[0] = -INF;
208
209
           for (int i = 1; i < n; i++) {
             scanf("%d%d", &u, &v);
210
211
             G[u]. push_back(v);
212
             G[v]. push_back(u);
213
214
           for (int i = 1; i \le n; i++) {
215
             scanf("%d", &key[i]);
216
217
             Max[i] = key[i];
218
219
           scanf("%d", &q);
220
221
           bfs();
222
223
           int op, x, y, w;
224
           while (q--) {
    scanf("%d", &op);
225
226
227
228
             if (op == 1)
                scanf("%d%d", &x, &y);
229
             \begin{array}{c} link(x, y); \\ link(x, p) = 2) \end{array}
230
231
                scanf("%d%d", &x, &y);
232
               \begin{array}{c} \operatorname{cut}(x, y); \\ \operatorname{else} & \operatorname{if} (\operatorname{op} = 3) \end{array} \{
233
234
                \operatorname{scanf}(\text{"%d\%d\%d"}, \&w, \&x, \&y);
235
236
                ADD(x, y, w);
237
               else {
                scanf("%d%d", &x, &y);
238
239
                query(x, y);
240
241
242
             // display();
243
244
245
           puts("");
246
247
248
        return 0;
249
     4.2 kdt
  1
     // Copyright [2017] <dmnsn7>
     bool cmpx(const Node &a, const Node &b) { return a.x < b.x;
  3
     bool cmpy (const Node &a, const Node &b) { return a.y < b.y;
  4
     LL dis(const Node &a, const Node &b) { return sqr(a.x - b.x) + sqr(a.y - b.y); }
     void build(int l, int r) {
  8
        if (1 > r) {
  9
 10
          return;
 11
```

```
12
      \label{eq:llminx} LL \ minx = min\_element(p + l \,, \ p + r \,+\, 1 \,, \ cmpx) -> x \,;
13
14
      LL maxx = \max_{e} element (p + l, p + r + 1, empx) -> x;
15
      LL miny = \min_{\text{element}}(p + l, p + r + 1, \text{cmpy}) -> y;
      LL maxy = \max_{p} = \max_{p} \left( p + l, p + r + 1, cmpy \right) -> y;
16
      int mid = 1 + (r - 1) / 2;
17
18
      d[mid] = maxx - minx > maxy - miny;
      nth\_element(p + 1, p + mid, p + r + 1, d[mid] ? cmpx : cmpy);
19
20
21
      build(l, mid -1);
22
      build (mid + 1, r);
23
    }
24
25
    void query(int 1, int r, const Node &a) {
26
      if (1 > r) {
27
        return;
28
29
      int mid = 1 + (r - 1) / 2;
30
31
      LL dist = dis(a, p[mid]);
32
      LL d1 = d[mid] ? a.x - p[mid].x : a.y - p[mid].y;
33
34
      if (dist > 0) {
35
        res = min(res, dist);
36
37
      int 11 = 1, r1 = mid - 1;
38
39
      int 12 = mid + 1, r2 = r;
40
41
      if (d1 > 0) {
        swap(11, 12);
42
43
        swap(r1, r2);
44
45
46
      query(l1, r1, a);
47
      if (d1 * d1 < res) {
48
49
        query(12, r2, a);
50
51
    5
        Graph
        targan point connecting
    // Copyright [2017] <dmnsn7>
 2
 3
    void Tarjan(int u, int pre) {
```

```
Low[u] = DFN[u] = ++Index;
 4
      \operatorname{Stack}[\operatorname{top}++] = u;
 5
 6
      Instack[u] = true;
 7
 8
      for (int i = head[u]; i != -1; i = edge[i].next) {
 9
         int v = edge[i].to;
10
         if (v = pre) {
11
12
           continue;
13
14
         if (!DFN[v]) 
15
16
           Tarjan(v, u);
17
           if (Low[u] > Low[v]) {
18
19
             Low[u] = Low[v];
20
21
22
           if (\text{Low}[v] >= DFN[u]) {
23
              block++;
24
              int vn;
```

```
25
             cc = 0;
26
             memset(ok, false, sizeof(ok));
27
28
29
               vn = Stack[--top];
30
               Belong[vn] = block;
               Instack [vn] = false;
31
32
               ok[vn] = true;
               tmp[cc++] = vn;
33
             \} while (vn != v);
34
35
36
             ok[u] = 1;
37
             memset(color, -1, sizeof(color));
38
39
             if (!dfs(u, 0)) {
40
               can[u] = true;
41
42
                while (cc--) {
43
                  can[tmp[cc]] = true;
44
45
46
           }
47
          else if (Instack[v] \&\& Low[u] > DFN[v]) {
48
49
          Low[u] = DFN[v];
50
51
52
53
           targan
      if (Low[u] = DFN[u]) {
54
55
        scc++;
56
57
           v = \operatorname{Stack}[--\operatorname{top}];
58
           Instack[v] = false;
59
           Belong [v] = scc;
60
          \operatorname{num}[\operatorname{scc}]++;
61
          while (v != u);
62
      }
63
64
      */
65
   }
   5.2 cut point bridge
   // Copyright [2017] <dmnsn7>
 2
 3
   const int MAXN = 10010;
 4
   const int MAXM = 100010;
 5
    struct Edge {
      int to, next;
bool cut; //
 6
 7
   } edge [MAXM];
   int head [MAXN], tot;
   int Low [MAXN], DFN [MAXN], Stack [MAXN];
10
    int Index, top
   bool Instack [MAXN];
12
13
    bool cut [MAXN];
14
    int add_block[MAXN]; //
    int bridge;
15
    void addedge(int u, int v) {
16
17
      edge[tot].to = v;
      edge [tot]. next = head [u];
18
      edge [tot].cut = false;
19
20
      head[u] = tot++;
21
22
    void Tarjan (int u, int pre) {
23
      Low[u] = DFN[u] = ++Index;
24
      Stack[top++] = u;
```

```
25
      Instack[u] = true;
26
      int son = 0;
27
28
      for (int i = head[u]; i != -1; i = edge[i].next) {
        int v = edge[i].to;
29
30
31
        if (v = pre) {
32
          continue;
33
34
        if \quad (\,!DFN[\,v\,]\,) \quad \{\,
35
36
          son++;
37
          Tarjan(v, u);
38
          if (Low[u] > Low[v]) {
39
            Low[u] = Low[v];
40
41
42
43
          if (Low[v] > DFN[u]) \{ //
44
             bridge++;
             edge[i].cut = true;
45
46
             edge[i^{\uparrow}] \cdot cut = true;
47
48
          if (u != pre \&\& Low[v] >= DFN[u]) \{ //
49
             cut[u] = true;
50
51
             add_block[u]++;
52
53
          else if (Low[u] > DFN[v]) {
54
          Low[u] = DFN[v];
55
56
57
58
            else if ( Instack[v] && Low[u] > DFN[v] )
59
                Low[u] = DFN[v];
         *
60
         *
            if(Low[u] = DFN[u])
61
62
                block++;
         *
63
                do
64
         *
                {
65
         *
                     v = Stack[--top];
                     Instack[v] = false;
66
         *
                     Belong[v] = block;
67
         *
68
         *
                \} while (v!=u);
69
         *
70
         */
71
72
73
      if (u = pre \&\& son > 1) {
        cut[u] = true; //
74
75
76
      if (u = pre) {
77
78
        add\_block[u] = son - 1;
79
80
81
      Instack[u] = false;
82
      top --;
83
   void solve(int N) {
84
      memset(DFN, 0, sizeof(DFN));
85
86
      memset(Instack, false, sizeof(Instack));
87
      memset(add_block, 0, sizeof(add_block));
88
      memset(cut, false, sizeof(cut));
89
      Index = top = 0;
90
      bridge = 0;
91
92
      for (int i = 1; i \le N; i++)
93
        if (!DFN[i]) {
```

```
94
           Tarjan(i, i);
95
96
       printf("%d critical links\n", bridge);
97
98
    void init() {
99
100
         tot = 0:
101
         memset (head, -1, size of (head));
102
    5.3 hungary
    // Copyright [2017] <dmnsn7>
 3
    bool dfs(int u) {
       for (int i = head[u]; i != -1; i = edge[i].next) {
 4
 5
         int v = edge[i].to;
 6
 7
         if (!used[v]) {
 8
           used[v] = true;
 9
 10
           if (\operatorname{linker}[v] = -1 \mid | \operatorname{dfs}(\operatorname{linker}[v])) {
 11
             linker[v] = u;
12
              return true;
13
14
       }
15
16
17
       return false;
18
19
    int hungary() {
      memset(linker, -1, sizeof(linker));
20
21
22
       for (int u = 0; u < uN; u++) { //
                                                 0~uN-1
23
         memset(used, false, sizeof(used));
24
25
         if (dfs(u)) {
26
           res++;
 27
 28
29
30
       return res;
31
    5.4 maxflow
    // Copyright [2017] <dmnsn7>
 3
    #include <bits/stdc++.h>
    using std;
 5
 6
    const int MAXN = 100010;
    const int MAXM = 400010;
 7
    const\ int\ oo\ =\ 0\,x\,3\,f\,3\,f\,3\,f\,3\,f\,;
 9
    struct Edge {
 10
       int to, next, cap, flow;
     } edge [MAXM] ;
                    // MAXM
 11
12
    int tol;
13
    int head [MAXN];
    int gap[MAXN], dep[MAXN], cur[MAXN];
14
    void init() {
15
16
       tol = 0;
      memset (head, -1, size of (head));
17
18
    void addedge(int u, int v, int w, int rw = 0) {
19
20
       edge[tol].to = v;
21
       edge[tol].cap = w;
22
       edge[tol].flow = 0;
23
       edge[tol].next = head[u];
24
       head[u] = tol++;
```

```
25
       edge[tol].to = u;
26
       edge[tol].cap = rw;
27
       edge[tol].flow = 0;
28
       edge[tol].next = head[v];
29
       head[v] = tol++;
30
31
    int Q[MAXN];
32
    void BFS(int ss, int tt) {
       \begin{array}{ll} \operatorname{memset} \big( \operatorname{dep} \,, & -1, & \operatorname{sizeof} \big( \operatorname{dep} \big) \big) \,; \\ \operatorname{memset} \big( \operatorname{gap} \,, & 0, & \operatorname{sizeof} \big( \operatorname{gap} \big) \big) \,; \end{array}
33
34
35
       gap[0] = 1;
36
       int front = 0, rear = 0;
       dep[tt] = 0;
37
38
       Q[rear++] = tt;
39
40
       while (front != rear) {
41
          int u = Q[front++];
42
          for (int i = head[u]; i != -1; i = edge[i].next) {
43
44
            int v = edge[i].to;
45
46
             if (dep[v] != -1) {
47
               continue;
48
49
50
            Q[rear++] = v;
51
            dep[v] = dep[u] + 1;
52
            \operatorname{gap}\left[\operatorname{dep}\left[v\right]\right]++;
53
54
       }
55
    int S[MAXN];
56
57
    int sap(int ss, int tt, int N) {
58
       BFS(ss, tt);
59
       memcpy(cur, head, sizeof(head));
60
       int top = 0;
61
       int u = ss;
62
       int ans = 0;
63
64
       while (dep[ss] < N) {
65
          if (u = tt) {
66
             int mi = oo;
67
             int inser;
68
69
             for (int i = 0; i < top; i++)
               if \ (mi > edge[S[i]].cap - edge[S[i]].flow) \ \{\\
70
                  mi = edge[S[i]].cap - edge[S[i]].flow;
71
72
                  inser = i;
73
               }
74
             for (int i = 0; i < top; i++) {
75
               edge[S[i]].flow += mi;
76
77
               edge[S[i] ^ 1].flow = mi;
78
79
80
            ans += mi;
81
            top = inser;
82
            u = edge[S[top] ^ 1].to;
83
            continue;
84
85
86
          bool flag = false;
87
          int v;
88
89
          for (int i = cur[u]; i != -1; i = edge[i].next) {
90
            v = edge[i].to;
91
             if (edge[i]. cap - edge[i]. flow && dep[v] + 1 == dep[u]) {
92
93
               flag = true;
```

```
94
               \operatorname{cur}[\mathbf{u}] = \mathbf{i};
95
               break;
 96
 97
98
          if (flag) {
99
            S[top++] = cur[u];
100
101
            u = v;
102
            continue;
103
104
105
          int mi = N;
106
107
          for (int i = head[u]; i != -1; i = edge[i].next)
            if (edge[i].cap - edge[i].flow && dep[edge[i].to] < mi) {
108
               mi = dep[edge[i].to];
109
110
               \operatorname{cur}[\mathbf{u}] = \mathbf{i};
111
112
113
          \operatorname{gap} \left[ \operatorname{dep} \left[ \mathbf{u} \right] \right] - -;
114
115
          if (!gap[dep[u]]) {
116
            return ans;
117
118
119
          dep[u] = mi + 1;
120
          \operatorname{gap}\left[\operatorname{dep}\left[\mathbf{u}\right]\right]++;
121
          if \ (u \mathrel{!=} ss) \ \{
122
            u = edge[\hat{S}[-top] ^ 1].to;
123
124
125
126
127
       return ans;
128
     5.5 costflow
     // Copyright [2017] <dmnsn7>
  3
     const int MAXN = 10000;
     const int MAXM = 100000;
     5
  6
     struct Edge {
     int head [MAXN], tol;
  9
                      dis [MAXN];
     int pre [MAXN]
 10
     bool vis [MAXN];
 11
                         ,0 \sim N-1
     int N; //
 12
13
     void init(int n) {
14
       N = n;
       tol = 0;
 15
 16
       memset (head, -1, size of (head));
 17
 18
     void addedge(int u, int v, int cap, int cost) {
 19
       edge[tol].to = v;
       edge[tol]. cap = cap;
20
       edge[tol].cost = cost;
 21
       edge[tol].flow = 0;
 22
 23
       edge[tol].next = head[u];
       head[u] = tol++;
 24
 25
       edge[tol].to = u;
 26
       edge[tol].cap = 0;
       edge[tol].cost = -cost;
 27
 28
       edge[tol]. flow = 0;
29
       edge[tol].next = head[v];
 30
       head[v] = tol++;
 31
```

```
bool spfa(int s, int t) {
32
33
      queue<int> q;
34
35
      for (int i = 0; i < N; i++) {
36
        dis[i] = INF;
37
        vis[i] = false;
        \operatorname{pre}\left[i\right] = -1;
38
39
40
41
      dis[s] = 0;
42
      vis[s] = true;
43
      q. push(s);
44
45
      while (!q.empty()) {
        int u = q. front();
46
47
        q.pop();
        vis[u] = false;
48
49
50
        for (int i = head[u]; i != -1; i = edge[i].next) {
51
           int v = edge[i].to;
52
           if (edge[i].cap > edge[i].flow && dis[v] > dis[u] + edge[i].cost) {
53
             dis[v] = dis[u] + edge[i].cost;

pre[v] = i;
54
55
56
             if (!vis[v]) {
57
58
                vis[v] = true;
59
               q.push(v);
60
          }
61
62
        }
63
      }
64
      if (pre[t] = -1) {
65
66
        return false;
67
        else {
68
        return true;
69
70
71
                cost
72
    int minCostMaxflow(int s, int t, const int &cost) {
73
      int flow = 0;
74
      cost = 0;
75
      while (spfa(\underline{s},\underline{t})) {
76
77
        int Min = INF;
78
79
        for (int i = pre[t]; i != -1; i = pre[edge[i ^ 1].to]) {
80
           if (Min > edge[i].cap - edge[i].flow) {
81
             Min = edge[i].cap - edge[i].flow;
82
83
        }
84
        for (int i = pre[t]; i != -1; i = pre[edge[i ^ 1].to]) {
85
           edge[i].flow += Min;
edge[i ^ 1].flow -= Min;
86
87
88
           cost += edge[i].cost * Min;
89
90
91
        flow += Min;
92
93
      return flow;
94
95
   }
    5.6 min tree graph
    // Copyright [2017] <dmnsn7>
```

```
const int INF = 0 \times 3f3f3f3f3f;
   const\ int\ MAXN=\ 1010;
 4
 5
    const int MAXM = 40010;
 6
    struct Edge {
 7
      int u, v, cost;
 8
9
   Edge edge [MAXM];
   int pre [MAXN], id [MAXN], visit [MAXN], in [MAXN];
10
11
    int zhuliu(int root, int n, int m, Edge edge []) {
12
      int res = 0, u, v;
13
      while (1) {
14
15
        for (int i = 0; i < n; i++) {
          in[i] = INF;
16
17
18
19
        for (int i = 0; i < m; i++)
           if \ (edge\,[\,i\,]\,.\,u \ != \ edge\,[\,i\,]\,.\,v \ \&\& \ edge\,[\,i\,]\,.\,cost \ < \ in\,[\,edge\,[\,i\,]\,.\,v\,]\,) \ \ \{
20
21
             pre[edge[i].v] = edge[i].u;
22
             in[edge[i].v] = edge[i].cost;
23
24
25
        for (int i = 0; i < n; i++)
26
           if (i != root && in[i] == INF) {
27
             return -1;
           }
28
29
30
        int tn = 0;
        memset(id, -1, sizeof(id));
31
        memset(visit, -1, sizeof(visit));
32
        in[root] = 0;
33
34
35
        for (int i = 0; i < n; i++) {
36
           res += in[i];
37
          v = i;
38
39
           while (visit [v] != i \&\& id[v] == -1 \&\& v != root) {
40
             visit[v] = i;
41
             v = pre[v];
42
43
           if (v != root \&\& id[v] == -1) {
44
45
             for (int u = pre[v]; u != v; u = pre[u]) {
46
               id[u] = tn;
47
48
             id[v] = tn++;
49
50
51
52
        if (tn == 0) {
53
54
          break;
55
56
        for (int i = 0; i < n; i++)
57
           if (id [i] = -1) {
58
             id[i] = tn++;
59
60
61
        for (int i = 0; i < m;) {
62
63
          v = edge[i].v;
64
           edge[i].u = id[edge[i].u];
65
           edge[i].v = id[edge[i].v];
66
           if (edge[i].u != edge[i].v) {
67
68
             edge[i++].cost = in[v];
69
           } else {
70
             swap(edge[i], edge[--m]);
```

```
71
72
73
74
        n = tn;
75
        root = id[root];
76
77
78
      return res;
79
   }
   5.7 flowertree
   // Copyright [2017] <dmnsn7>
3
   const int MAXN = 250;
4
            //
   int N;
                     1N
5
   bool Graph [MAXN] [MAXN];
 6
   int Match [MAXN]
   bool InQueue [MAXN], InPath [MAXN], InBlossom [MAXN];
   int Head, Tail;
   int Queue [MAXN];
9
10
   int Start, Finish;
   int NewBase;
   int Father [MAXN], Base [MAXN];
12
13
   int Count; //
                         , Count /2
   void CreateGraph()
14
      int u, v;
memset(Graph, false, sizeof(Graph));
15
16
      scanf("%d", &N);
17
18
      while (scanf("%d%d", &u, &v) == 2) {
19
20
        Graph[u][v] = Graph[v][u] = true;
21
22
23
   void Push(int u) {
24
      Queue [Tail] = u;
25
      Tail++;
26
      InQueue[u] = true;
27
28
   int Pop()  {
29
      int res = Queue [Head];
30
      Head++;
31
      return res;
32
33
   int FindCommonAncestor(int u, int v)
34
      memset(InPath, false, sizeof(InPath));
35
36
      while (true) {
37
        u = Base[u];
38
        InPath[u] = true;
39
40
        if (u = Start) {
41
          break;
42
43
        u = Father[Match[u]];
44
45
46
      while (true) {
47
        v = Base[v];
48
49
50
        if (InPath[v]) {
51
          break;
52
53
        v = Father[Match[v]];
54
55
56
57
      return v;
58
```

```
void ResetTrace(int u) {
59
60
       while (Base[u] != NewBase) {
61
         int v = Match[u];
62
         InBlossom [Base [u]] = InBlossom [Base [v]] = true;
63
         u = Father[v];
64
         if (Base[u] != NewBase) {
65
           Father[u] = v;
66
67
68
    }
69
70
    void BloosomContract(int u, int v) {
      NewBase = FindCommonAncestor(u, v);
71
72
      memset(InBlossom, false, sizeof(InBlossom));
73
       ResetTrace(u);
74
       ResetTrace(v);
75
76
       if (Base[u] != NewBase) {
77
         Father[u] = v;
78
79
80
       if (Base[v] != NewBase) {
         Father [v] = u;
81
82
83
84
       for (int tu = 1; tu \ll N; tu++)
85
         if (InBlossom [Base [tu]]) {
86
           Base[tu] = NewBase;
87
88
           if (!InQueue[tu]) {
89
             Push(tu);
90
         }
91
92
    }
93
94
    void FindAugmentingPath() {
95
      memset(InQueue, false, sizeof(InQueue));
96
      memset(Father, 0, sizeof(Father));
97
       for (int i = 1; i \le N; i++) {
98
99
         Base [i] = i;
100
101
102
      Head = Tail = 1;
103
      Push (Start);
104
       Finish = 0;
105
       while (Head < Tail) {
106
107
         int u = Pop();
108
109
         for (int v = 1; v \le N; v++)
           if (Graph[u][v] \&\& (Base[u] != Base[v]) \&\& (Match[u] != v))
110
             if ((v = Start) \mid | ((Match[v] > 0) \&\& Father[Match[v]] > 0)) {
111
               BloosomContract(u, v);
112
               else if (Father[v] = 0) {
113
                Father [v] = u;
114
115
116
                if (Match[v] > 0) {
117
                  Push (Match [v]);
118
                  else {
                  Finish = v;
119
120
                  return;
121
             }
122
           }
123
124
      }
125
126
    void AugmentPath() {
```

```
127
       int u = Finish;
128
129
       while (u > 0) {
130
         int v = Father [u];
         int w = Match[v];
131
132
         Match[v] = u;
133
         Match[u] = v;
134
         u = w;
135
136
    void Edmonds() {
137
138
      memset (Match, 0, size of (Match));
139
       for (int u = 1; u \le N; u++)
140
         if (Match[u] == 0)  {
141
           Start = u;
142
143
           FindAugmentingPath();
144
           if (Finish > 0) {
145
146
              AugmentPath();
147
148
149
150
    void PrintMatch() {
151
       Count = 0;
152
       for (int u = 1; u \le N; u++)
153
154
         if (Match[u] > 0) {
155
           Count++;
156
157
158
       printf("%d\n", Count);
159
160
       for (int u = 1; u \le N; u++)
161
         if (u < Match[u]) {
162
           printf("%d %d\n", u, Match[u]);
163
164
165
    int main() {
       CreateGraph();
166
167
       Edmonds ();
168
       PrintMatch();
169
       return 0;
    }
170
    5.8
         2-sat
    // Copyright [2017] <dmnsn7>
 2
 3
    const int MAXN = 20020;
    const int MAXM = 100010;
 4
 5
    struct Edge {
       int to, next;
    \} \ \ \mathrm{edge}\left[ \mathrm{M\!A\!X\!M}\right] ;
 7
 8
    int head [MAXN], tot;
    void init() {
 9
 10
       tot = 0;
       memset(head, -1, sizeof(head));
 11
12
    void addedge(int u, int v) {
13
       edge[tot].to = v;
14
       edge [tot]. next = head [u];
15
16
       head[u] = tot++;
17
18
    bool vis [MAXN];
                                  true
    int S[MAXN], top;
20
    bool dfs(int u) {
       if (vis [u ^ 1])
21
22
         return false;
```

```
23
      }
24
25
      if (vis[u]) {
26
        return true;
27
28
29
      vis[u] = true;
30
     S[top++] = u;
31
      for (int i = head[u]; i != -1; i = edge[i].next)
32
        if (!dfs(edge[i].to)) {
33
34
          return false;
35
36
37
      return true;
38
   bool Twosat(int n) {
39
40
     memset(vis, false, sizeof(vis));
41
42
      for (int i = 0; i < n; i += 2) {
        if (vis[i] || vis[i ^ 1]) {
43
44
          continue;
45
46
        top = 0;
47
48
        if (!dfs(i)) {
49
50
          while (top) {
51
            vis[S[--top]] = false;
52
53
          if (!dfs(i ^ 1)) {
54
55
            return false;
56
57
        }
      }
58
59
60
      return true;
61
62
   int main() {
63
      int n, m;
64
      int u, v;
65
      66
        init();
67
68
69
        while (m--)
70
          scanf("%d%d", &u, &v);
71
          u--;
72
73
          addedge(u, v ^1);
          addedge (v, u ^ 1);
74
75
76
        if \ (Twosat(2\ *\ n))\ \{
77
          for (int i = 0; i < 2 * n; i++)
78
            if (vis[i]) {
  printf("%d\n", i + 1);
79
80
81
82
        } else {
          printf("NIE\n");
83
84
85
86
87
      return 0;
88
   5.9 \text{ km}
1 // Copyright [2017] <dmnsn7>
```

```
3
   bool DFS(int x) {
4
      visx[x] = true;
5
6
      for (int y = 0; y < ny; y++) {
        if (visy[y]) {
7
8
          continue;
9
10
11
        int tmp = lx[x] + ly[y] - g[x][y];
12
        if (tmp == 0) {
13
          visy[y] = true;
14
15
          if (linker[y] = -1 \mid | DFS(linker[y])) {
16
17
             linker[y] = x;
18
             return true;
19
20
        else if (slack[y] > tmp) {
21
          slack[y] = tmp;
22
23
24
25
      return false;
26
27
   int KM()
28
      memset(linker, -1, sizeof(linker));
29
      memset(ly, 0, size of(ly));
30
31
      for (int i = 0; i < nx; i++) {
32
        lx[i] = -INF;
33
34
        for (int j = 0; j < ny; j++)
35
          if (g[i][j] > lx[i]) {
36
            lx[i] = g[i][j];
37
38
39
40
      for (int x = 0; x < nx; x++) {
        for (int i = 0; i < ny; i++) {
41
42
          slack[i] = INF;
43
44
        while (true) {
45
46
          memset(visx, false, sizeof(visx));
47
          memset(visy, false, sizeof(visy));
48
          if (DFS(x)) {
49
50
             break;
51
52
          int d = INF;
53
54
55
          for (int i = 0; i < ny; i++)
             if (!visy[i] && d > slack[i]) {
56
57
               d = \operatorname{slack}[i];
58
59
          for (int i = 0; i < nx; i++)
60
             if (visx[i]) {
61
              lx[i] = d;
62
63
64
65
          for (int i = 0; i < ny; i++) {
66
             if (visy[i]) {
67
               ly [i] += d;
             } else {
68
               \operatorname{slack}[i] = d;
69
70
```