

Lecture 1 § Review of linear systems

1.2.13. Ange (om möjligt) villkor på $a, b, c \in \mathbb{R}$ så att systemen nedan får

(i) entydig lösning, (ii) ingen lösning, (iii) oändligt många lösningar.

$$(a) \begin{cases} 3x - y + az = 3 \\ x + y - z = 2 \\ 2x - 2y + 3z = b \end{cases}, \quad (b) \begin{cases} x + ay = 0 \\ y + bz = 0 \\ cx + z = 0 \end{cases}$$

Quick review: $A\vec{x} = \vec{b}$ $A = ()_{m \times n}$ $\vec{x} = ()_{n \times 1}$ $\vec{b} = ()_{m \times 1}$

If $\vec{b} = \vec{0}$ then $A\vec{x} = \vec{0}$ is homogeneous linear sys
otherwise non homogen.

Baby case

$$m = n = 1.$$

$$1x = b \quad \text{or} \quad 0x = 0 \quad \text{or} \quad 0x = 1$$

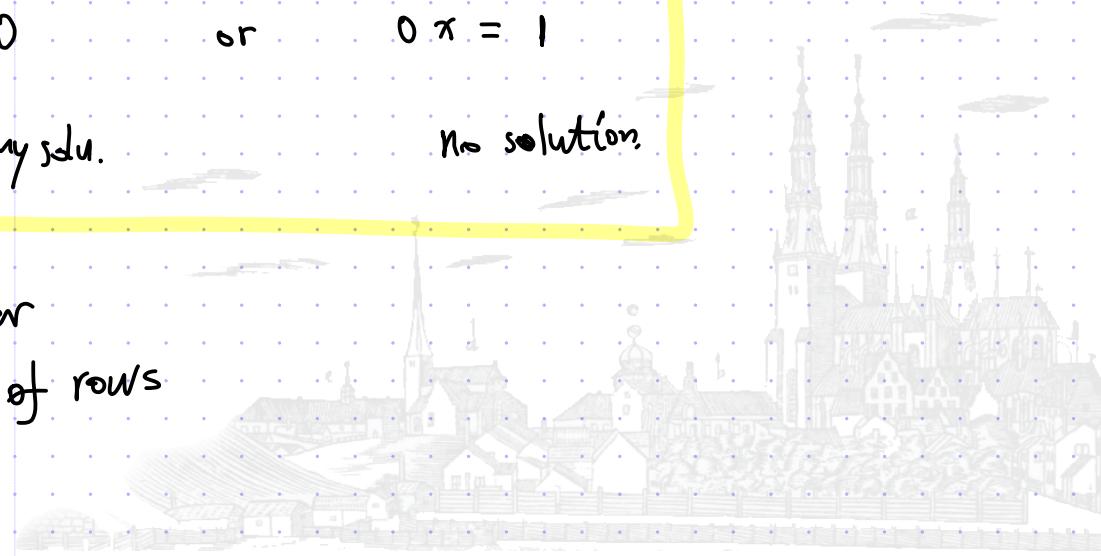
$x = b$
unique soln.

∞ -many soln.

No solution.

(a) Row operation

{
- addition
non-zero scalar
change order of rows



$$\left(\begin{array}{ccc|c} 3 & -1 & a & 3 \\ 1 & 1 & -1 & 2 \\ 2 & -2 & 3 & b \end{array} \right) \sim \left(\begin{array}{ccc|c} 1 & 1 & -1 & 2 \\ 3 & -1 & a & 3 \\ 2 & -2 & 3 & b \end{array} \right) \xrightarrow{\textcircled{2}} \left(\begin{array}{ccc|c} 1 & 1 & -1 & 2 \\ 0 & -4 & a+3 & -3 \\ 2 & -2 & 3 & b \end{array} \right) \xrightarrow{\textcircled{1}} \left(\begin{array}{ccc|c} 1 & 1 & -1 & 2 \\ 0 & -4 & a+3 & -3 \\ 0 & -4 & 5 & b-4 \end{array} \right) \xrightarrow{\textcircled{2}-3\times\textcircled{1}} \left(\begin{array}{ccc|c} 1 & 1 & -1 & 2 \\ 0 & 0 & a & 0 \\ 0 & 0 & 5 & b-4 \end{array} \right) \xrightarrow{\textcircled{3}-2\times\textcircled{1}}$$

$$\sim \left(\begin{array}{ccc|c} 1 & 1 & -1 & 2 \\ 0 & 1 & \frac{a+3}{-4} & \frac{-3}{-4} \\ 0 & 0 & 2-a & b-1 \end{array} \right) \xrightarrow{\textcircled{1}} \left(\begin{array}{ccc|c} 1 & 1 & -1 & 2 \\ 0 & 1 & \frac{a+3}{-4} & \frac{-3}{-4} \\ 0 & 0 & 2-a & b-1 \end{array} \right) \xrightarrow{\textcircled{2}\times(-\frac{1}{4})} \left(\begin{array}{ccc|c} 1 & 1 & -1 & 2 \\ 0 & 1 & \frac{a+3}{-4} & \frac{-3}{-4} \\ 0 & 0 & 2-a & b-1 \end{array} \right) \xrightarrow{\textcircled{3}-\textcircled{2}}$$

1) If $2-a = 0$ & $b-1 \neq 0$ " $0 z = b-1 \neq 0$ "

No solution.

2) If $2-a = 0$ & $b-1 = 0$ " $0 z = 0$ " ∞ -many solutions

3) If $2-a \neq 0$. $\Rightarrow z = \frac{b-1}{2-a}$ & "...": unique solution

$$\left(\begin{array}{ccc|c} 1 & 1 & -1 & 2 \\ 0 & 1 & \frac{a+3}{-4} & \frac{-3}{-4} \\ 0 & 0 & 1 & \frac{b-1}{2-a} \end{array} \right) \xrightarrow{\textcircled{1}} \left(\begin{array}{ccc|c} 1 & 1 & 0 & 2 + \frac{b-1}{2-a} \\ 0 & 1 & 0 & \frac{-3}{-4} + \frac{a+3}{4} \cdot \frac{b-1}{2-a} \\ 0 & 0 & 1 & \frac{b-1}{2-a} \end{array} \right) \xrightarrow{\textcircled{1}+\textcircled{3}} \left(\begin{array}{ccc|c} 1 & 1 & 0 & 2 + \frac{b-1}{2-a} \\ 0 & 1 & 0 & \frac{-3}{-4} + \frac{a+3}{4} \cdot \frac{b-1}{2-a} \\ 0 & 0 & 1 & \frac{b-1}{2-a} \end{array} \right) \xrightarrow{\textcircled{2}+\frac{(a+3)}{4}\textcircled{3}} \left(\begin{array}{ccc|c} 1 & 1 & 0 & 2 + \frac{b-1}{2-a} \\ 0 & 0 & 0 & \frac{-3}{-4} + \frac{a+3}{4} \cdot \frac{b-1}{2-a} \\ 0 & 0 & 1 & \frac{b-1}{2-a} \end{array} \right)$$

$$x = 2 + \frac{b-1}{2-a}$$

$$y = \frac{-3}{-4} + \frac{a+3}{4} \cdot \frac{b-1}{2-a}$$

$$z = \frac{b-1}{2-a}$$

2) again:

$$\left(\begin{array}{cccc} 1 & 1 & -1 & 2 \\ 0 & 1 & \frac{a+3}{-4} & \frac{-3}{-4} \\ 0 & 0 & 0 & 0 \end{array} \right)$$

$$\boxed{a = 2 \quad b = 1}$$

$$x_1 = x$$

$$x_2 = y$$

$$x_3 = z$$

$$x_2 + \left(\frac{a+3}{-4}\right)x_3 = +\frac{3}{4}$$

$$x_2 + \frac{5}{-4}x_3 = \frac{3}{4}$$

$$x_2 = \frac{3}{4} + \frac{5}{4}x_3$$

$$x_1 + x_2 - x_3 = 2$$

$$x_1 = 2 + x_3 - \frac{3}{4} - \frac{5}{4}x_3$$

$$\boxed{x_3 = t}$$

$$\begin{cases} x_1 = \frac{5}{4} - \frac{1}{4}t \\ x_2 = \frac{3}{4} + \frac{5}{4}t \\ x_3 = t \end{cases}$$

(b)

$$\begin{pmatrix} 1 & a & 0 & 0 \\ 0 & 1 & b & 0 \\ 0 & 0 & 1 & 0 \end{pmatrix}$$

$$\det A = 1 + abc$$

$$A \vec{x} = \vec{0}$$

$$\text{if } \det A \neq 0 \Rightarrow \exists A^{-1} \Rightarrow A^{-1}(A \vec{x}) = A^{-1} \vec{0}$$

$$\Rightarrow \vec{x} = \vec{0}$$

If $\det A = 0 \Rightarrow \infty$ many solution.

$$1 + abc \neq 0$$

$$\Leftrightarrow \dots$$

$$1 + abc = 0$$

$$abc = -1$$

3.2.4. Följande matriser är givna (se **Exempel 3.2.5**, sid 59):

$$A = \begin{pmatrix} 1 & 0 & 2 \\ -3 & 1 & 2 \end{pmatrix}, \quad B = \begin{pmatrix} 0 & 3 \\ 5 & 1 \\ 2 & 0 \end{pmatrix}, \quad C = \begin{pmatrix} 0 & 1 & 0 \\ 2 & 1 & 3 \\ 0 & 1 & 0 \end{pmatrix} \quad \text{och} \quad D = \begin{pmatrix} 0 \\ 1 \end{pmatrix}.$$

Utför nedanstående multiplikationer i de fall de är definierade:

- (a) AA , (b) AB , (c) CA , (d) CB , (e) $(AB)D$.

Gäller $AB = BA$?

Quick review:

$$A_{m \times n} = \left(\begin{array}{cccc} a_{11} & \dots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{m1} & \dots & a_{mn} \end{array} \right)_m^i$$

$$B_{n \times k} = \left(\begin{array}{cccc} & & & \\ \vdots & \ddots & \vdots & \\ & & & \end{array} \right)_n^j$$

$$C = A_{m \times n} \cdot B_{n \times k} = \left(\begin{array}{cccc} & & & \\ \vdots & \ddots & \vdots & \\ & & & \end{array} \right)_{m \times k}$$

Match

$$c_{ij} = (a_{11}, \dots, a_{in}) \cdot \begin{pmatrix} b_{1j} \\ \vdots \\ b_{nj} \end{pmatrix}$$

(a)

$$A_{3 \times 2} A_{3 \times 2} = ?$$

We cannot do it.

(b)

$$\begin{pmatrix} 1 & 0 & 2 \\ -3 & 1 & 2 \end{pmatrix} \begin{pmatrix} 0 & 3 \\ 5 & 1 \\ 2 & 0 \end{pmatrix} = \begin{pmatrix} 4 & 3 \\ 9 & -8 \end{pmatrix}_{2 \times 2}$$

$$(1, 0, 2) \begin{pmatrix} 0 \\ 5 \\ 2 \end{pmatrix} = 1 \cdot 0 + 0 \cdot 5 + 2 \cdot 2 = 4$$

(c) $C_{3 \times 3} \underline{A_{2 \times 3}} = \text{cannot compute}$

(d) $C_{3 \times 3} B_{3 \times 2} = ()_{3 \times 2}$

(e) $(A \ B) D = \begin{pmatrix} 4 & 3 \\ 9 & -8 \end{pmatrix}_{2 \times 2} \begin{pmatrix} 0 \\ 1 \end{pmatrix}_{2 \times 1} = \begin{pmatrix} 3 \\ -8 \end{pmatrix}_{2 \times 1}$

Associativity of multipl:

$$(A \ B) D = A (B D)$$

We don't have commutativity $AB \neq BA$

- $\text{if } AB = BA \Rightarrow A_{m \times n} B_{n \times k} = B_{n \times k} \underbrace{A_{m \times n}}$

$$\Rightarrow ()_{m \times m} = ()_{n \times n} \Rightarrow m = n = k \quad A, B \text{ should be same size square matrices}$$

this is a necessary condition.

3.6.4. (a) Bestäm inversen till matrisen

$$A = \begin{pmatrix} 1 & -2 & -3 & 1 \\ -1 & 3 & 5 & -1 \\ 2 & 1 & -1 & 3 \\ 3 & -1 & 1 & 4 \end{pmatrix}.$$

(b) Utnyttja resultatet i (a) till att lösa ekvationssystemet

$$\begin{cases} x_1 - 2x_2 - 3x_3 + x_4 = 7 \\ -x_1 + 3x_2 + 5x_3 - x_4 = -9 \\ 2x_1 + x_2 - x_3 + 3x_4 = 18 \\ 3x_1 - x_2 + x_3 + 4x_4 = 15 \end{cases}$$

Method:

Row operations for the computation of inverse matrix

$$(A, I_4) = \left(\begin{array}{cccc|cccc} 1 & -2 & -3 & 1 & 1 & 0 & 0 & 0 \\ -1 & 3 & 5 & -1 & 0 & 1 & 0 & 0 \\ 2 & 1 & -1 & 3 & 0 & 0 & 1 & 0 \\ 3 & -1 & 1 & 4 & 0 & 0 & 0 & 1 \end{array} \right)$$

\sim

$\left(\begin{array}{cccc|cccc} 1 & -2 & -3 & 1 & 1 & 0 & 0 & 0 \\ 0 & 1 & 2 & 0 & 1 & 1 & 0 & 0 \\ 0 & 5 & 5 & 1 & -2 & 0 & 1 & 0 \\ 0 & 5 & 10 & 1 & -3 & 0 & 0 & 1 \end{array} \right)$

row oper.

$\xrightarrow{(2)+1}$

$\xrightarrow{(3)-1 \times 2}$

$\xrightarrow{(4)-1 \times 3}$

$n=4$

$\left(I_4, A^{-1} \right)$

4.2.3 Radoperationer och kofaktorutveckling

4.2.9. Beräkna följande determinanter (se **Exempel 4.5.3'**, sid 91 och **Exempel 4.7.3'**, sid 91)

$$(a) \begin{vmatrix} 3 & -1 & 0 \\ 2 & 3 & 5 \\ -2 & 1 & 4 \end{vmatrix}, \quad (b) \begin{vmatrix} 1 & 2 & 3 & 4 \\ 0 & 1 & 2 & 3 \\ -1 & 0 & 2 & 2 \\ 4 & 3 & 2 & -1 \end{vmatrix}, \quad (c) \begin{vmatrix} 1 & 1 & 0 & 2 \\ 2 & 3 & 1 & 4 \\ 4 & 2 & 0 & 3 \\ 3 & 2 & 1 & 4 \end{vmatrix},$$

(b)

$$\begin{vmatrix} 1 & 2 & 3 & 4 \\ 0 & 1 & 2 & 3 \\ 0 & 2 & 5 & 6 \\ 0 & -5 & -10 & -17 \end{vmatrix} = 1 \cdot \begin{vmatrix} 1 & 2 & 3 \\ 2 & 5 & 6 \\ -5 & -10 & -17 \end{vmatrix} = \begin{vmatrix} 1 & 2 & 3 \\ 0 & 1 & 0 \\ 0 & 0 & -2 \end{vmatrix} \begin{matrix} \textcircled{2} - \textcircled{1} \times 2 \\ \textcircled{3} + \textcircled{1} \times 5 \end{matrix} = -2$$

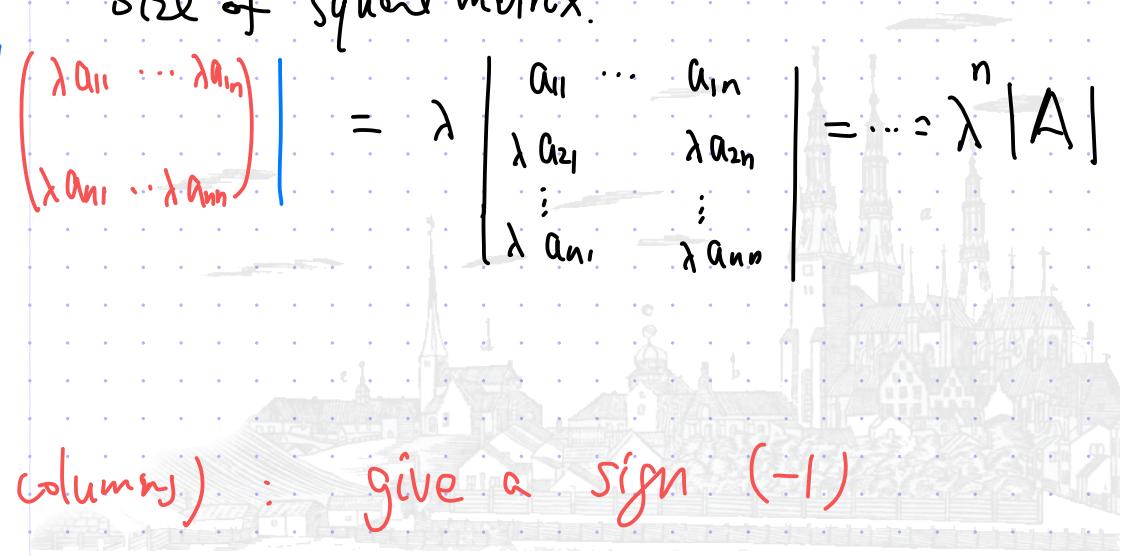
Quick review:

— do reduction from higher order det to a lower order size of square matrix.

- Scalar: $\lambda \cdot \underset{\substack{\uparrow \\ \text{Scalar product}}}{A_{n \times n}} = \begin{vmatrix} \lambda a_{11} & \cdots & \lambda a_{1n} \\ \lambda a_{21} & \cdots & \lambda a_{2n} \\ \vdots & \ddots & \vdots \\ \lambda a_{n1} & \cdots & \lambda a_{nn} \end{vmatrix} = \lambda \begin{vmatrix} a_{11} & \cdots & a_{1n} \\ a_{21} & \cdots & a_{2n} \\ \vdots & \ddots & \vdots \\ a_{n1} & \cdots & a_{nn} \end{vmatrix} = \dots = \lambda^n |A|$

$$|\lambda \cdot A| = \lambda^n |A|$$

- change order of rows (columns): give a sign (-1)



(a)

$$\left| \begin{array}{ccc} 3 & -1 & 0 \\ 2 & 3 & 5 \\ -2 & 1 & 4 \end{array} \right| \quad 3 \times 3$$

row expen.

$$\left| \begin{array}{cc} a & b \\ c & d \end{array} \right| = ad - bc$$

$3 (-1)$

place of the entry 3

$|+1|$

$$\left| \begin{array}{ccc} 3 & -1 & 0 \\ 2 & 3 & 5 \\ -2 & 1 & 4 \end{array} \right|$$

place of entry (-1)

$|+2|$

$+ (-1) \cdot (-1)$

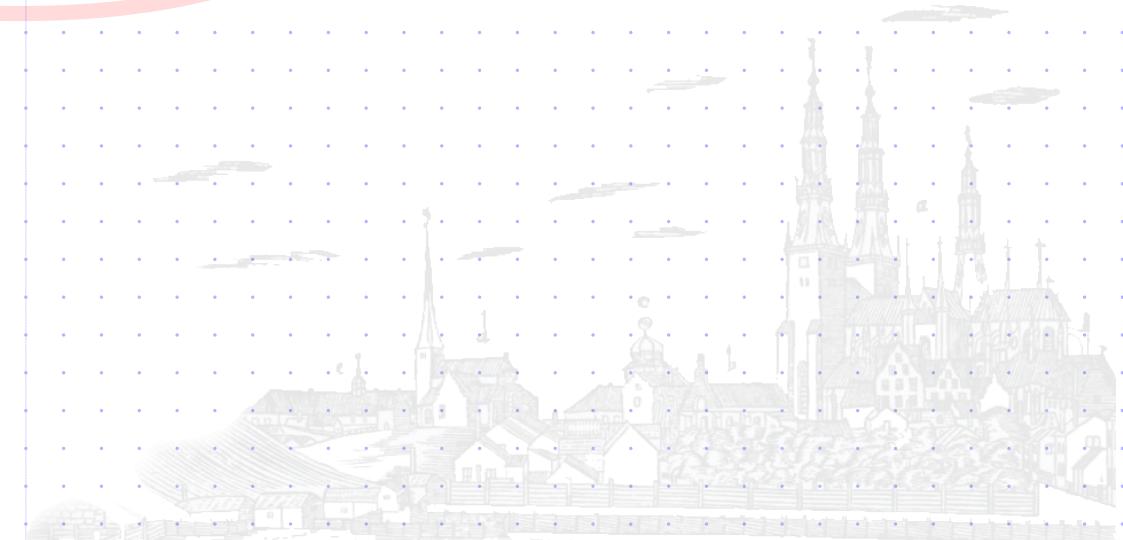
$$+ 0 \cdot (-1)$$

place of 0

$|+3|$

$$\left| \begin{array}{ccc} 3 & -1 & 0 \\ 2 & 3 & 5 \\ -2 & 1 & 4 \end{array} \right|$$

$$\left| \begin{array}{ccc} 3 & -1 & 0 \\ 2 & 3 & 5 \\ -2 & 1 & 4 \end{array} \right|$$



Cross-product of two "3-dim" vectors

row vectors here

$$i = (1, 0, 0)$$

$$j = (0, 1, 0)$$

$$k = (0, 0, 1)$$

$$(a, b, c) \times (d, e, f) = 3\text{-dim vector}$$

Pseudo-determinant:

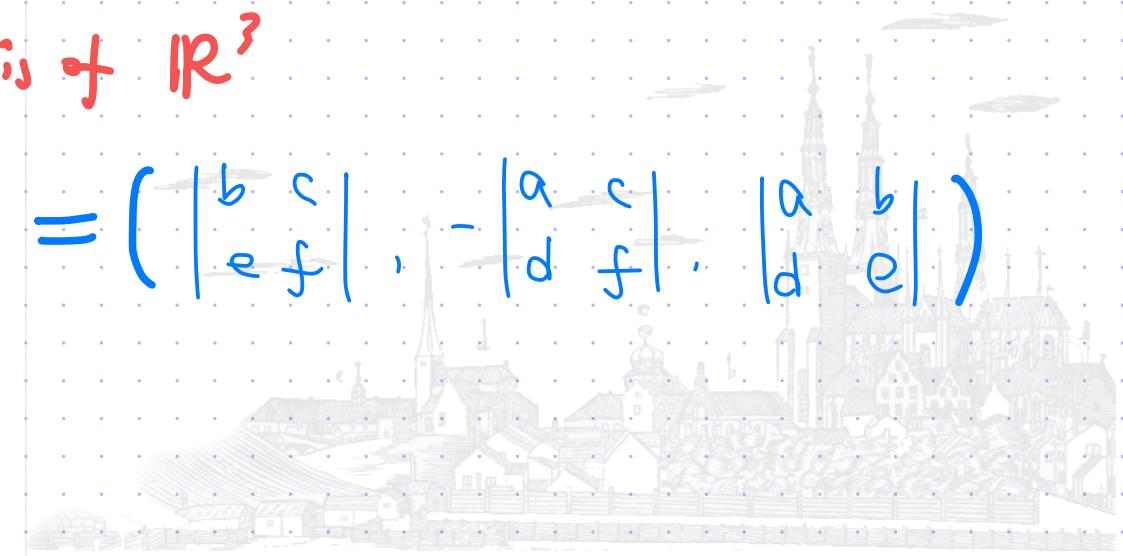
i, j, k as symbols

$$(a, b, c) \times (d, e, f) = \begin{vmatrix} i & j & k \\ a & b & c \\ d & e & f \end{vmatrix} = i \begin{vmatrix} b & c \\ e & f \end{vmatrix} - j \begin{vmatrix} a & c \\ d & f \end{vmatrix} + k \begin{vmatrix} a & b \\ d & e \end{vmatrix}$$

↖ formal computation
 ↖ numbers

think i, j, k as standard basis of \mathbb{R}^3

$$= (|b c|, -|a c|, |a b|)$$



§ Vector spaces

5.2.1. Avgör vilka av följande mängder som är vektorrum över de reella talen (addition och multiplikation med skalär är de vanliga på respektive mängd).

- { (a) $M_a = \{ \text{alla polynom} \}$ ✓
- (b) $M_b = \{ \text{alla polynom av grad exakt 3} \}$ ✗
- (c) $M_c = \{ \text{alla polynom av grad } \leq 3 \}$ ✓
- (d) $M_d = \{ \text{alla } 2 \times 2 \text{ matriser med reella element} \}$ ✓
- (e) $M_e = \{ \text{alla reella funktioner definierade på } [-1, 2] \}$
- (f) $M_f = C^0(0, 2) = \text{alla reellvärda kontinuerliga funktioner med definitionsmängd }]0, 2[$
- (g) $M_g = \{ f(x) \in C^0(0, 2) : f(1) = 1 \}$
- (h) $M_h = \{ f(x) \in C^0(0, 2) : f(1) = 0 \}$
- (i) $M_i = \mathbb{Z} = \text{de hela talen}$

set s.
We need to
find +
/ define ..
if possible.

What is a vector space over \mathbb{R}

Vert space = (set, +, ·)

axioms ...

0-vector $\vec{0} + \vec{x} = \vec{x} \quad \forall \vec{x} \in \text{set}$

Distribution law $\lambda(\vec{x} + \vec{y}) = \lambda\vec{x} + \lambda\vec{y}$

$M_a = \{ f = f(x) \text{ is a one-variable poly nom.} \}$

$$f, g \in M_a \quad + \quad f + g \stackrel{\text{def}}{=} f(x) + g(x)$$

↓
addition of
numbers.

It is a vect. space of ∞ -dim.

$$1, x, x^2 \notin \text{Span}\{1, x\}$$

$$\text{Span}\{1, x, x^2\}$$

$$\begin{matrix} x \\ \uparrow \\ 1 \end{matrix}$$

dim 3

$M_b = \{ f \text{ of deg exact 3} \}$

$$f(x) = 1 + x + x^3$$

$$g(x) = 1 + x + x^2 + x^3$$

$\text{span}\{1, x, \dots, x^{n-1}\}$ of dim n

⋮ ⋮ ⋮

no control of n . $n \rightarrow \infty$

then $f + (-1) \cdot g = f(x) - g(x) \approx -x^2$ is NOT a poly of deg 3.

the set M_b is not "closed" under either the "+" or "-".

$M_c := \{ \dots \text{ def } \leq 3 \}$ fine if it is a vec space

of dim 4 with basis 1. x, x^2, x^3

$M_e = \{ f : [-1, 2] \rightarrow \mathbb{R} \text{ Real fun.} \}$

$+ \quad f, g \in M_e \quad f + g \stackrel{\text{def}}{=} f(x) + g(x)$

$\lambda \cdot f \stackrel{\text{def}}{=} \lambda f(x)$

$(M_e, +, \cdot)$ is a vect space

$M_f = C^0(0, 2) = \{ f : (0, 2) \rightarrow \mathbb{R} \mid f \text{ is contin.} \}$

is a vec. space of ~~∞ -dim.~~

$M_g = C^0(0, 2) \cap \{ f(1) = 1 \}$
not a vect. space
↑ together

$$\begin{aligned} f_1 \in M_g \quad f_1(1) &= 1 \quad (f_1 + f_2)(1) \\ f_2 \in M_g \quad f_2(1) &= 1 \quad = f_1(1) + f_2(1) = 2 \neq 1 \end{aligned}$$

$$M_h = C^0([0,2]) \cap \{f(1) = 0\}$$

$f_1 \in M_h \quad f_1(1) = 0 \quad (f_1 + f_2)(1) = f_1(1) + f_2(1) = 0 + 0 = 0$

$f_2 \in M_h \quad f_2(1) = 0$

M_h is a vect. space.

M_h is a sub vect. space of M_f .

/

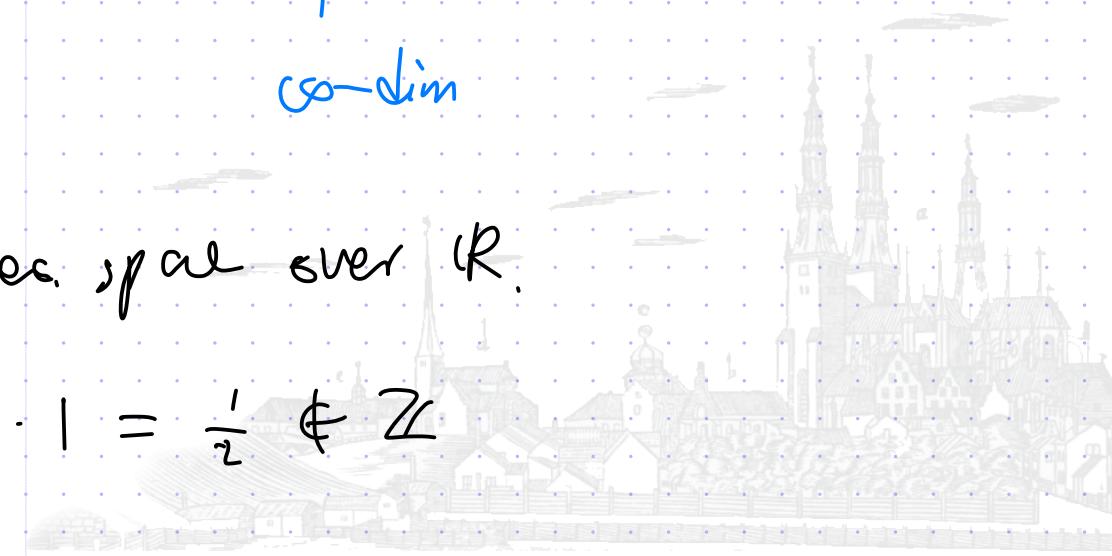
∞ -dim

/

∞ -dim

$M_i = \mathbb{Z}$ is NOT a vec. space over \mathbb{R} .

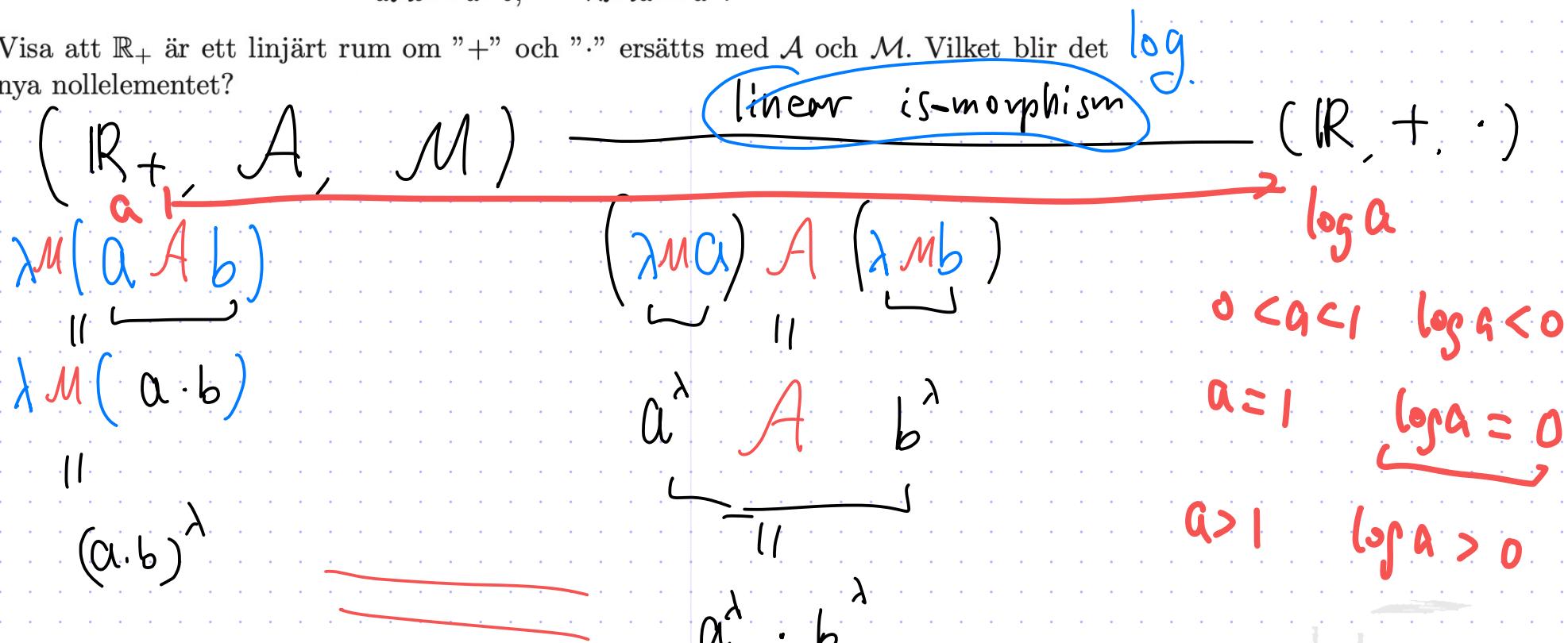
$$\lambda = \frac{1}{2} \in \mathbb{R} \quad \lambda \cdot 1 = \frac{1}{2} \notin \mathbb{Z}$$



5.2.2. Definiera nya additions- och multiplikationsoperationer, \mathcal{A} och \mathcal{M} på $\mathbb{R}_+ = \{x \in \mathbb{R}: x > 0\}$ enligt följande: $a, b \in \mathbb{R}_+, \lambda \in \mathbb{R}$

$$a\mathcal{A}b = a \cdot b, \quad \lambda \mathcal{M}a = a^\lambda.$$

Visa att \mathbb{R}_+ är ett linjärt rum om ”+” och ”.” ersätts med \mathcal{A} och \mathcal{M} . Vilket blir det nya nollelementet?



$$\vec{0} \wedge \vec{a} = \vec{0} \quad \forall \vec{a} \in \mathbb{R}^+$$

$$0 \cdot \overline{b} = \overline{b}$$

$$\vec{0} \cdot b = b \quad \forall b \in \mathbb{R}_+ \quad \Rightarrow \quad \vec{0} = 1 \in \mathbb{R}_+$$