

Contractibility of space of stability conditions on \mathbb{P}^2 via global dimension function

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Part I. Motivation

\mathcal{D} : a triangulated category. For example,

- ▶ $\mathcal{D}(X) = \mathcal{D}^b(\text{Coh}(X))$ for smooth projective variety X over \mathbb{C} ;
- ▶ $\mathcal{D}(Q) = \mathcal{D}^b(\text{Rep}(Q))$ for quiver Q .

$\text{Stab}(\mathcal{D})$: Bridgeland stability manifold on \mathcal{D} .

It is a complex manifold.

$\text{Stab}^\dagger(\mathcal{D})$: the principal connected component.

Conjecture

$\text{Stab}^\dagger(\mathcal{D})$ is contractible. More ambitious, $\text{Stab}(\mathcal{D})$ is contractible.

Known cases of the Conjecture for $\mathcal{D} = \mathcal{D}(X)$ or $\mathcal{D}(Q)$

- ▶ smooth projective curves [Okada 06, Bridgeland 07, Macrì 07].
- ▶ K3 surfaces with Picard rank one [Bayer-Bridgeland 17].
- ▶ local \mathbb{P}^1 [Ishii-Ueda-Uehara 10]; local \mathbb{P}^2 [Bayer-Macrì 11].
- ▶ \mathbb{P}^2 [Li 17].
- ▶ Abelian surfaces [Bridgeland 08] and Abelian threefolds with Picard rank one [Bayer-Macrì-Stellari 16].
- ▶ ADE Dynkin quiver [Qiu-Woolf 18] and some new classes of examples [August-Wemyss 19].
- ▶ Calabi–Yau-3 affine type A quiver [Qiu 16].
- ▶ acyclic triangular quiver [Dimitrov-Katzarkov 16].
- ▶ wild Kronecker quiver [Dimitrov-Katzarkov 19].
- ▶ ...

The proofs in each case are quite different.

New idea via gldim

Ikeda and the fourth-named author [Qiu 18, Ikeda-Qiu 18] introduce the global dimension function gldim on $\text{Stab}(\mathcal{D})$,

$$\text{gldim}: \text{Stab}(\mathcal{D}) \rightarrow \mathbb{R}_{\geq 0} \cup \{+\infty\},$$

which sends $\sigma = (Z, \mathcal{P}) \in \text{Stab}(\mathcal{D})$ to

$$\text{gldim } \sigma = \text{gldim } \mathcal{P} := \sup\{\phi_2 - \phi_1 \mid \text{Hom}(\mathcal{P}(\phi_1), \mathcal{P}(\phi_2)) \neq 0\}.$$

Such a function is

- ▶ continuous,
- ▶ invariant under the natural left action by $\text{Aut}(\mathcal{D})$ and the right action of \mathbb{C} ,

and thus descends to a continuous function

$$\text{gldim}: \text{Aut}(\mathcal{D}) \backslash \text{Stab}(\mathcal{D}) / \mathbb{C} \rightarrow \mathbb{R}_{\geq 0} \cup \{+\infty\}.$$

Philosophy: stability manifold contracts along the values of the global dimension function.

- (i) The infimum of gldim on $\text{Stab}(\mathcal{D})$ (or the principal component of it) should be considered as the global dimension $\text{gd } \mathcal{D}$ of the category \mathcal{D} .
- (ii) If the subspace $\text{gldim}^{-1}(\text{gd } \mathcal{D})$ is non-empty, then it is contractible. Moreover, $\text{gldim}^{-1}([\text{gd } \mathcal{D}, x])$ contracts to $\text{gldim}^{-1}(\text{gd } \mathcal{D})$ for any real number $\text{gd } \mathcal{D} < x$.
- (iii) When $\text{gldim}^{-1}(\text{gd } \mathcal{D})$ is empty, $\text{gldim}^{-1}(\text{gd } \mathcal{D}, x)$ contracts to $\text{gldim}^{-1}(\text{gd } \mathcal{D}, y)$ for any real number $\text{gd } \mathcal{D} < y < x$.

Note that for a Calabi–Yau category, the global dimension function is constant. If the global dimension function gldim is not constant, it sheds some lights on why $\text{Stab}(\mathcal{D})$ should be contractible.

Main Theorem

The above philosophy is true for the projective plane \mathbb{P}^2 .

Main Theorem

Consider the global dimension function

$$\mathrm{gldim}: \mathrm{Stab}^\dagger(\mathbb{P}^2) \rightarrow \mathbb{R}_{\geq 0}$$

on the principal component $\mathrm{Stab}^\dagger(\mathbb{P}^2)$ of the space of stability conditions on the bounded derived category $\mathcal{D}^b(\mathrm{Coh} \mathbb{P}^2)$ of coherent sheaves on \mathbb{P}^2 . Then $\mathrm{gd}(\mathcal{D}(\mathbb{P}^2)) = 2$,

- ▶ $\mathrm{gldim} \mathrm{Stab}^\dagger(\mathbb{P}^2) = [2, \infty)$,
- ▶ the subspace $\mathrm{gldim}^{-1}[2, x)$ contracts to $\mathrm{gldim}^{-1}(2)$, for any $x \geq 2$,
- ▶ the subspace $\mathrm{gldim}^{-1}(2)$ is contractible and is contained in $\mathrm{Stab}^{\mathrm{Geo}}(\mathbb{P}^2)$, where $\mathrm{Stab}^{\mathrm{Geo}}(\mathbb{P}^2)$ consists of geometric stability conditions.

Part II: What is $\text{Stab}(\mathcal{D})$?

Definition

A *slicing* \mathcal{P} is a collect. of subcategories $\mathcal{P}(\phi) \subset \mathcal{D}$ for $\phi \in \mathbb{R}$ s.t.

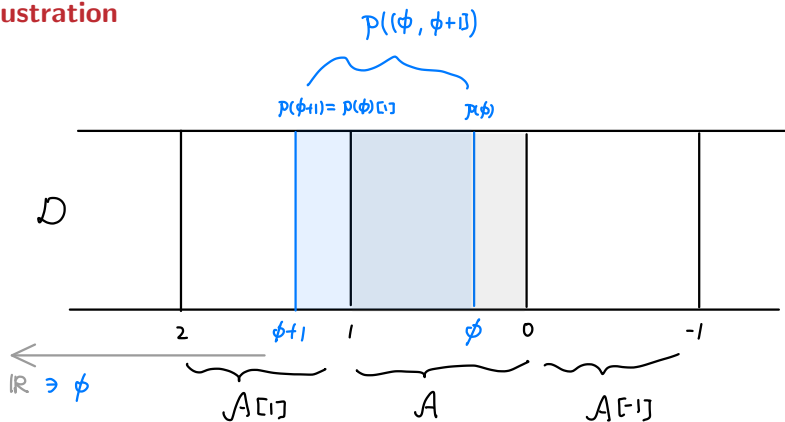
- ▶ $\mathcal{P}(\phi)[1] = \mathcal{P}(\phi + 1)$,
- ▶ if $\phi_1 > \phi_2$ and $A_i \in \mathcal{P}(\phi_i)$, then $\text{Hom}(A_1, A_2) = 0$,
- ▶ for all $E \in \mathcal{D}$ there are real numbers $\phi^+(E) := \phi_1 > \dots > \phi_m =: \phi^-(E)$, and objects $E_i \in \mathcal{D}$ for $i = 1, \dots, m$, and a collection of triangles

$$\begin{array}{ccccccc} 0 = E_0 & \longrightarrow & E_1 & \longrightarrow & E_2 & \longrightarrow & \dots \longrightarrow E_{m-1} \longrightarrow E_m = E \\ & & \downarrow & & \downarrow & & \downarrow \\ & & A_1 & & A_2 & & A_{m-1} \\ & \nearrow & & \nearrow & & \nearrow & \\ & & & & & & A_m \end{array}$$

where $A_i \in \mathcal{P}(\phi_i)$.

Let $\mathcal{A} := \mathcal{P}((0, 1])$ to be the extension closure of the subcategories $\{\mathcal{P}(\phi) : \phi \in (0, 1]\}$, we get the heart of a bounded t-structure. So a slicing is \mathbb{R} -indexed refinement of \mathbb{Z} -indexed t-structure of \mathcal{D} .

Illustration



Definition

A *stability condition* $\sigma = (Z, \mathcal{P})$ on \mathcal{D} consists of

- ▶ a group homomorphism $Z: K(\mathcal{D}) \rightarrow \mathbb{C}$ (called the *central charge*, where $K(\mathcal{D})$ is the Grothendieck group) and
- ▶ a slicing \mathcal{P}

satisfying

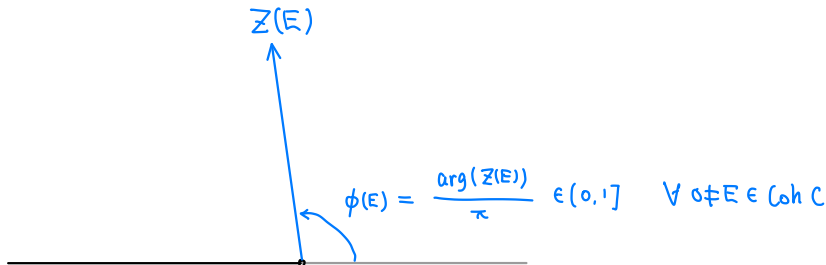
- ▶ (compatibility) $\forall 0 \neq E \in \mathcal{P}(\phi) \implies Z(E) \in \mathbb{R}_{>0} \cdot e^{\sqrt{-1}\pi\phi}$
- ▶ (support property)
$$C_\sigma := \inf \left\{ \frac{|Z(E)|}{\|E\|} : 0 \neq E \in \mathcal{P}(\phi), \phi \in \mathbb{R} \right\} > 0.$$

There is an equivalent definition by using $\sigma = (Z, \mathcal{A})$ with $\mathcal{A} = \mathcal{P}((0, 1])$. Denote $\phi(E) := \arg(Z(E))/\pi$, then

- ▶ (Positivity) $0 \neq E \in \mathcal{A} \implies \phi(E) \in (0, 1]$,
- ▶ $0 \neq E \in \mathcal{A}$ is *Z-semistable* if any nonzero $F \subset E$ admits $\phi(F) \leq \phi(E)$,
- ▶ for $\phi \in (0, 1]$, $\mathcal{P}(\phi) = \langle E \in \mathcal{A} \text{ is } Z\text{-semistable of phase } \phi \rangle$.

Examples

Let C be a smooth projective curve and let $\mathcal{A} := \text{Coh}(C)$ and $Z(E) := -\deg(E) + \sqrt{-1} \text{rank}(E)$ for $E \in \mathcal{A}$. Then $\sigma = (Z, \mathcal{A})$ is a Bridgeland stability condition.



Definition: $\text{Stab}(\mathcal{D})$

Let $\text{Stab}(\mathcal{D})$ be the set of all Bridgeland stability conditions on \mathcal{D} . It can be equipped with the *coarsest topology* s.t. for any $E \in \mathcal{D}$, the maps $(Z, \mathcal{P}) \mapsto Z(E)$, $(Z, \mathcal{P}) \mapsto \phi^+(E)$ and $(Z, \mathcal{P}) \mapsto \phi^-(E)$ are continuous.

Group actions

There are two natural group actions on $\text{Stab}(\mathcal{D})$:

- ▶ a left action by $\text{Aut}(\mathcal{D})$,
- ▶ a right action by the universal cover $\widetilde{\text{GL}}^+(2, \mathbb{R})$ of $\text{GL}^+(2, \mathbb{R})$.

Bridgeland's deformation theorem

The forgetful map $\mathcal{Z}: \text{Stab}(\mathcal{D}) \rightarrow \text{Hom}(K(\mathcal{D}), \mathbb{C})$ given by $(Z, \mathcal{P}) \mapsto Z$ is a local homeomorphism. In particular, assume that $K(\mathcal{D})$ is of finite rank, then $\text{Stab}(\mathcal{D})$ is a complex manifold of dimension $\text{rank}(K(\mathcal{D}))$.

Part III: What is $\text{Stab}(\mathbb{P}^2)$?

It is a complex manifold of dimension 3. We don't know whether it is connected or not.

Conjecture [Li 17]: $\text{Stab}(\mathbb{P}^2)$ is connected.

We know a connected component $\text{Stab}^\dagger(\mathbb{P}^2)$ that containing geometric Bridgeland stability conditions. Recall that a $\sigma \in \text{Stab}(X)$ is called *geometric* if all skyscraper sheaves are σ -stable of the same phase. Denote the set of all geometric stability conditions by $\text{Stab}^{\text{Geo}}(X)$.

Theorem [Li 17]: $\text{Stab}^\dagger(\mathbb{P}^2) = \text{Stab}^{\text{Geo}}(\mathbb{P}^2) \cup \text{Stab}^{\text{Alg}}(\mathbb{P}^2)$.

- ▶ We will give the definition of $\text{Stab}^{\text{Alg}}(\mathbb{P}^2)$ soon.
- ▶ The final goal is to compute the global dimension function gldim on $\text{Stab}^\dagger(\mathbb{P}^2)$ (see **Propositions A & B** below) and to show that $\text{Stab}^\dagger(\mathbb{P}^2)$ contracts along the values of gldim .

Geometric stability condition $\sigma_{s,q}$

Reduced Chern characters $\{1, \frac{ch_1}{ch_0}, \frac{ch_2}{ch_0}\}$ -plane

For $E \in \mathcal{D}$, we can identify $ch_1(E)$ as a **number**, and we have $ch(E) = (ch_0(E), ch_1(E), ch_2(E)) \in \mathbb{R}^3$, and its reduced Chern character in $\{1, \frac{ch_1}{ch_0}, \frac{ch_2}{ch_0}\}$ -plane. By abuse of notations, we also denote the reduced Chern character by E . For example,

- ▶ line bundle $\mathcal{O}(p)$ will be the point $(1, p, \frac{p^2}{2})$,
- ▶ the tangent bundle $T_{\mathbb{P}^2}$ will be the point $(1, \frac{3}{2}, \frac{3}{4})$.

Definition

Define $\sigma_{s,q} := (Z_{s,q}, \mathcal{A})$ with $\mathcal{A} = \text{Coh}_{\#s} := \langle \text{Coh}_{\leq s}[1], \text{Coh}_{>s} \rangle$ and

$$Z_{s,q}(E) := (-ch_2(E) + q \cdot ch_0(E)) + i(ch_1(E) \cdot H - s \cdot ch_0(E)).$$



$$\begin{aligned} \text{Coh}_{>s} &= \langle E \in \text{Coh}(\mathbb{P}^2) \mid \mu(E) > s \rangle \\ \text{Coh}_{\le s} &= \langle E \in \text{Coh}(\mathbb{P}^2) \mid \mu(E) \leq s \rangle \end{aligned}$$

$\mu = \frac{ch_1(-) \cdot H}{ch_0(-)}$

A fractal curve: the Le Potier Curve C_{LP}

Dyadic integers and exceptional bundles

An object $E \in \mathcal{D}$ is called **exceptional** if $\text{Hom}(E, E[k]) = 0$ for $k \neq 0$; $= \mathbb{C}$ for $k = 0$. There is a **one-to-one correspondence** between the **dyadic integers** $\frac{p}{2^m}$ ($p \in \mathbb{Z}$ and $m \in \mathbb{Z}_{\geq 0}$) and **exceptional bundles** $E(\frac{p}{2^m})$. For example, $E(p) = \mathcal{O}(p)$, $E(\frac{3}{2}) = T_{\mathbb{P}^2}$, $E(\frac{p}{2^m} + 1) = E(\frac{p}{2^m}) \otimes \mathcal{O}(1)$.

Three points E^+ , e^l , e^r associated to $E = E(\frac{p}{2^m})$

In the $\{1, \frac{ch_1}{ch_0}, \frac{ch_2}{ch_0}\}$ -plane, we define

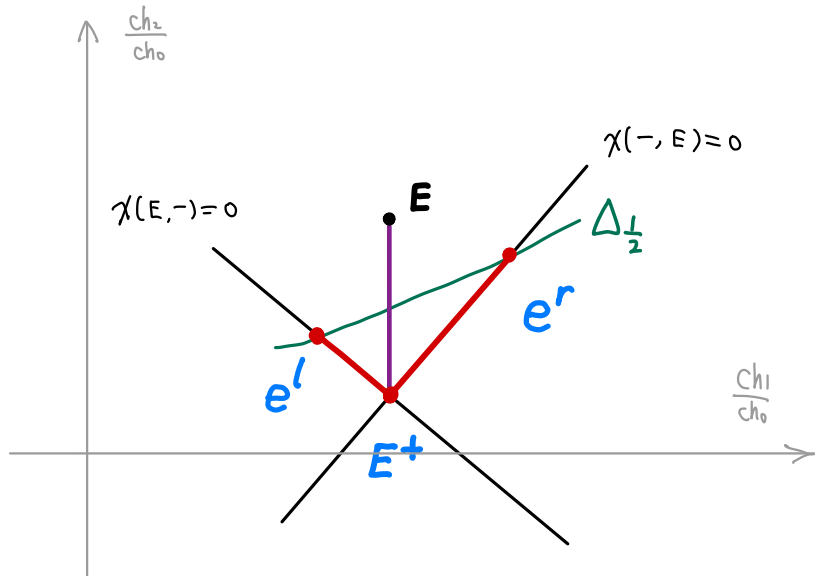
$$E^+ := \{\chi(E, -) = 0\} \cap \{\chi(-, E) = 0\},$$

$$e^l := \{\chi(E, -) = 0\} \cap \Delta_{\frac{1}{2}}, \quad e^r := \{\chi(-, E) = 0\} \cap \Delta_{\frac{1}{2}},$$

where Δ_a is the parabola $\frac{1}{2} (ch_1/ch_0)^2 - (ch_2/ch_0) = a$.

$$C_{LP} := \coprod_{\{E=E(\frac{p}{2^m}) \mid p \in \mathbb{Z}, m \in \mathbb{Z}_{\geq 0}\}} \left(\overline{E^+ e^l} \cup \overline{E^+ e^r} \right) \coprod \{\text{Cantor pieces of } \Delta_{\frac{1}{2}}\}.$$

Illustration in reduced char. plane



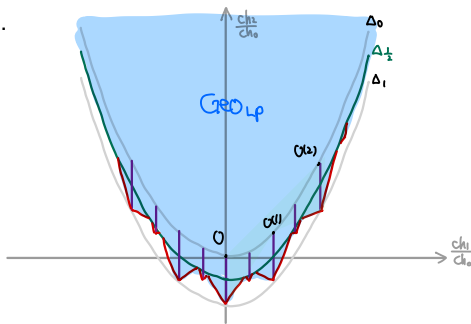
Geometric stability conditions $\text{Stab}^{\text{Geo}}(\mathbb{P}^2)$

Lemma [Bayer-Macri 11]

The $\widetilde{\text{GL}^+(2, \mathbb{R})}$ acts freely on $\text{Stab}^{\text{Geo}}(\mathbb{P}^2)$ with quotient

$$\text{Stab}^{\text{Geo}}(\mathbb{P}^2) / \widetilde{\text{GL}^+(2, \mathbb{R})} \cong \text{Geo}_{\text{LP}},$$

where the region $\text{Geo}_{\text{LP}} := \{(1, s, q) \in \{1, \frac{\text{ch}_1}{\text{ch}_0}, \frac{\text{ch}_2}{\text{ch}_0}\}\text{-plane} \mid (1, s, q) \text{ is above } C_{\text{LP}} \text{ and not on line segment } \overline{EE^+} \text{ for any exceptional bundle } E\}$.

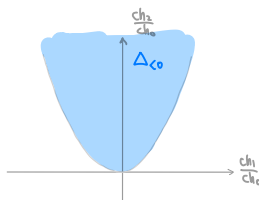


gldim on $\text{Stab}^{\text{Geo}} \mathbb{P}^2$

Proposition A

Let $\sigma = \sigma_{s,q}$ be a geometric stability condition in the region $\Delta_{<0}$ on the $\{1, \frac{\text{ch}_1}{\text{ch}_0}, \frac{\text{ch}_2}{\text{ch}_0}\}$ -plane. Then

$$\text{gldim } \sigma_{s,q} = 2.$$



Proof.

The Serre duality is the isomorphism

$$\text{Hom}(E, F) = \text{Hom}(F, \mathbb{S}(E))^*, \quad \mathbb{S} := (-) \otimes \mathcal{O}_{\mathbb{P}^2}(-3)[2].$$

Now skyscraper sheaf \mathcal{O}_x is σ -stable and $\text{Hom}(\mathcal{O}_x, \mathcal{O}_x[2]) = \text{Hom}(\mathcal{O}_x[2], \mathcal{O}_x[2])^* = \mathbb{C}$. Since $\phi(\mathcal{O}_x[2]) - \phi(\mathcal{O}_x) = 2$, so $\text{gldim } \sigma_{s,q} \geq 2$.

We need to show $\text{gldim } \sigma_{s,q} \leq 2$. Let E, F be σ -stable with $0 < \phi(E) < \phi(F) - 2 \leq 1$, $\text{ch}_0(E) \neq 0$, and σ is left to E , we could show $\text{Hom}(E, F) = 0$.



Algebraic stability conditions $\text{Stab}^{\text{Alg}}(\mathbb{P}^2)$

Definition

We call an ordered set of exceptional objects $\mathcal{E} = \{E_1, E_2, E_3\}$ *exceptional triple* on $\mathcal{D}^b(\mathbb{P}^2)$ if \mathcal{E} is a full strong exceptional collection of coherent sheaves on $\mathcal{D}^b(\mathbb{P}^2)$ i.e.

$$\text{Hom}(E_i, E_j[k]) = 0 \text{ for any } i > j \text{ and for all } k \in \mathbb{Z};$$

$$\text{Hom}(E_i, E_j[k]) = 0, \text{ for } k \neq 0 \text{ and for all } i, j.$$

The exceptional triples have been classified by **Gorodentsev and Rudakov**. Up to a cohomological shift, the exceptional triples are labeled by $\{\frac{p-1}{2^m}, \frac{p}{2^m}, \frac{p+1}{2^m}\}$ or their mutations $\{\frac{p}{2^m}, \frac{p+1}{2^m}, \frac{p-1}{2^m} + 3\}$, $\{\frac{p+1}{2^m} - 3, \frac{p-1}{2^m}, \frac{p}{2^m}\}$.

Proposition [Macrì 07]

Let \mathcal{E} be an exceptional triple on $\mathcal{D}^b(\mathbb{P}^2)$. For any positive real numbers m_1, m_2, m_3 and real numbers ϕ_1, ϕ_2, ϕ_3 such that:

$$\phi_1 < \phi_2 < \phi_3, \text{ and } \phi_1 + 1 < \phi_3,$$

there is a unique stability condition $\sigma = (Z, \mathcal{P})$ such that

1. each E_j is stable with phase ϕ_j ;
2. $Z(E_j) = m_j e^{i\pi\phi_j}$.

Definition

Given an exceptional triple $\mathcal{E} = \{E_1, E_2, E_3\}$ on $\mathcal{D}^b(\mathbb{P}^2)$, we write $\Theta_{\mathcal{E}}$ as the space of all stability conditions above. We denote

$$\text{Stab}^{\text{Alg}}(\mathbb{P}^2) := \bigcup_{\mathcal{E} \text{ exc triples}} \Theta_{\mathcal{E}}$$

and call the elements of it as the algebraic stability conditions.

Glue: $\Theta_{\mathcal{E}}^{\text{Geo}} := \Theta_{\mathcal{E}} \cap \text{Stab}^{\text{Geo}}(\mathbb{P}^2)$

For an exceptional triple $\mathcal{E} = \{E_1, E_2, E_3\}$, Li [Li 17] shows

$$\Theta_{\mathcal{E}}^{\text{Geo}} = \widetilde{\text{GL}^+(2, \mathbb{R})} \cdot \text{MZ}_{\mathcal{E}}.$$

Define some subsets of $\Theta_{\mathcal{E}}$ as follows.

- ▶ $\Theta_{\mathcal{E}}^{\text{Pure}} := \{\sigma \in \Theta_{\mathcal{E}} \mid \phi_2 - \phi_1 \geq 1 \text{ and } \phi_3 - \phi_2 \geq 1\};$
- ▶ $\Theta_{\mathcal{E}, E_3}^{\text{left}} := \{\sigma \in \Theta_{\mathcal{E}} \mid \phi_2 - \phi_1 < 1 \text{ and } E_3(3) \text{ is not } \sigma\text{-stable}\};$
- ▶ $\Theta_{\mathcal{E}, E_1}^{\text{right}} := \{\sigma \in \Theta_{\mathcal{E}} \mid \phi_3 - \phi_2 < 1 \text{ and } E_1(-3) \text{ is not } \sigma\text{-stable}\}.$

Lemma

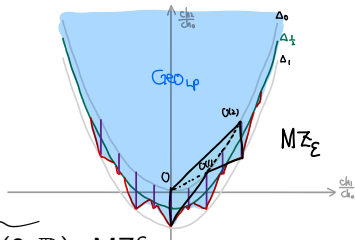
Given exceptional triples \mathcal{E} and \mathcal{E}' on $\mathcal{D}^b(\mathbb{P}^2)$ with the same $E_3 = E'_3 = E$, then $\Theta_{\mathcal{E}, E_3}^{\text{left}} = \Theta_{\mathcal{E}', E'_3}^{\text{left}}$. We denote *this subspace* by $\Theta_{E_3}^{\text{left}}$.

In a similar way, we define the subspace $\Theta_{E_1}^{\text{right}} := \Theta_{\mathcal{E}, E_1}^{\text{right}}$.

Similarly, denote $\Theta_{E_3}^- = \Theta_{\mathcal{E}, E_3}^- = \Theta_{\mathcal{E}}(\phi_2 - \phi_1 < 1) \setminus \Theta_{\mathcal{E}}^{\text{Geo}}$;
 $\Theta_{E_1}^+ = \Theta_{\mathcal{E}, E_1}^+ = \Theta_{\mathcal{E}}(\phi_3 - \phi_2 < 1) \setminus \Theta_{\mathcal{E}}^{\text{Geo}}$.

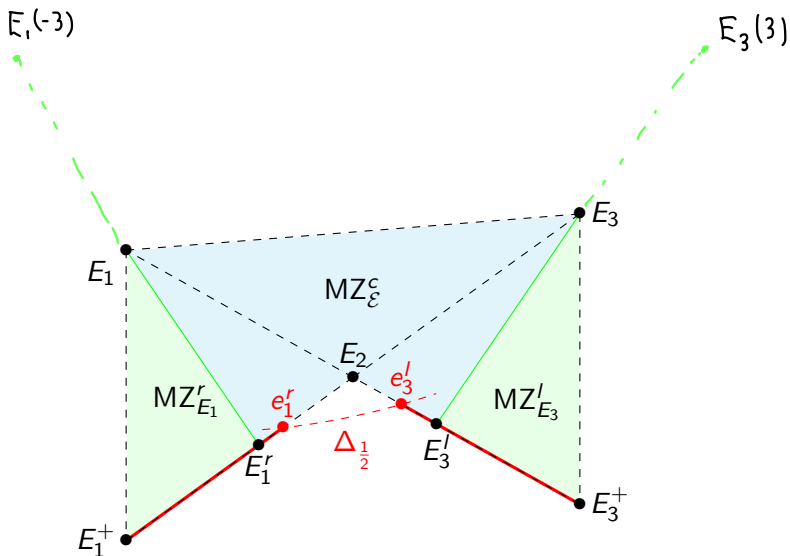
Lemma.

- ▶ $\Theta_{E_3}^{\text{left}} = \Theta_{E_3}^- \amalg \widetilde{\text{GL}^+(2, \mathbb{R})} \cdot \text{MZ}_{E_3}^I,$
- ▶ $\Theta_{E_1}^{\text{right}} = \Theta_{E_1}^+ \amalg \widetilde{\text{GL}^+(2, \mathbb{R})} \cdot \text{MZ}_{E_1}^r,$
- ▶ $\Theta_{\mathcal{E}} \setminus (\Theta_{E_1}^{\text{right}} \cup \Theta_{E_3}^{\text{left}} \cup \Theta_{\mathcal{E}}^{\text{Pure}}) = \widetilde{\text{GL}^+(2, \mathbb{R})} \cdot \text{MZ}_{\mathcal{E}}^c,$
- ▶ $\text{MZ}_{\mathcal{E}} = \text{MZ}_{E_1}^r \amalg \text{MZ}_{\mathcal{E}}^c \amalg \text{MZ}_{E_3}^I.$



Picture

$$\text{line } \overline{E_2 E_3} = \{ \chi(-, E_1) = 0 \}$$



gldim on $\Theta_{\mathcal{E}}$

The Serre functor on $\mathcal{D}(\mathbb{P}^2)$ is given by $\mathbb{S} := (-) \otimes \mathcal{O}_{\mathbb{P}^2}(-3)[2]$. The right and left mutations of an object F with respect to an exceptional object E are defined by

$$R_E(F) := \text{Cone}\left(F \xrightarrow{\text{ev}} E \otimes \text{Hom}(F, E)^*\right)[-1],$$

$$L_E(F) := \text{Cone}\left(E \otimes \text{Hom}(E, F) \xrightarrow{\text{ev}} F\right).$$

Proposition B

The value of the global dimension function $\text{gldim}(\sigma) =$

$$\begin{cases} 2, & \text{when } \sigma \in \Theta_{\mathcal{E}} \setminus \left(\Theta_{E_1}^{\text{right}} \cup \Theta_{E_3}^{\text{left}} \cup \Theta_{\mathcal{E}}^{\text{Pure}}\right); \\ \phi(R_{E_1}(\mathbb{S}E_1)) - \phi_1, & \text{when } \sigma \in \Theta_{E_1}^{\text{right}}; \\ \phi_3 - \phi(L_{E_3}(\mathbb{S}^{-1}E_3)), & \text{when } \sigma \in \Theta_{E_3}^{\text{left}}; \\ \phi_3 - \phi_1, & \text{when } \sigma \in \Theta_{\mathcal{E}}^{\text{Pure}}. \end{cases}$$

Proposition A + Proposition B \implies Main Theorem.

Thank you!