

EE5138 Project

Submitted By:

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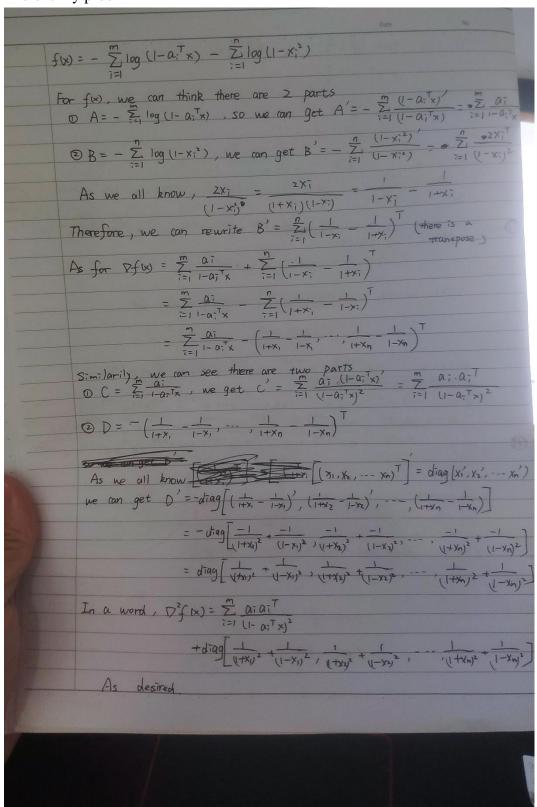
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There is my proof

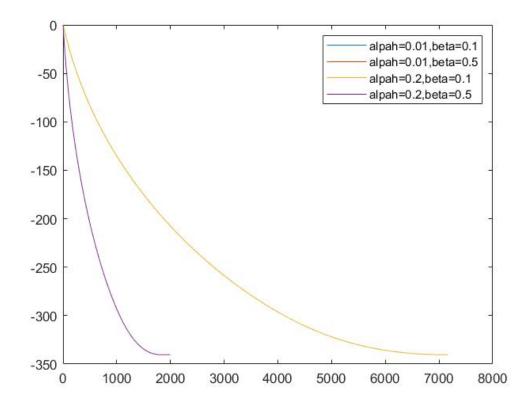


(b) Based on the proof of the gradient function of f(x), we get the first order and second order gradient function, and in this part, we use the gradient method to finish this problem. There are four groups of parameters.

(1) We get four optimal value from four groups

optimal value	parameters
-340.4403	Alpha=0.01, beta=0.1
-340.4402	Alpha=0.01, beta=0.5
-340.4403	Alpha=0.2, beta=0.1
-340.4402	Alpha=0.2, beta=0.5

(2) I plot four cases in one figure, here is the performance of gradient method in different groups of parameters.



In conclusions:

From the figure, we found the performance of same alpha is similar because the curve is covered. However, in fact, this suggest that the gradient method works better with fairly large alpha. That is because the first order of object function can more easily reach the optimal point.

As for beta, bigger beta can reduce the number of iterations because it can make the step size fairly bigger than that of smaller beta. Therefore, beta make a great difference in performance of reducing iterations.

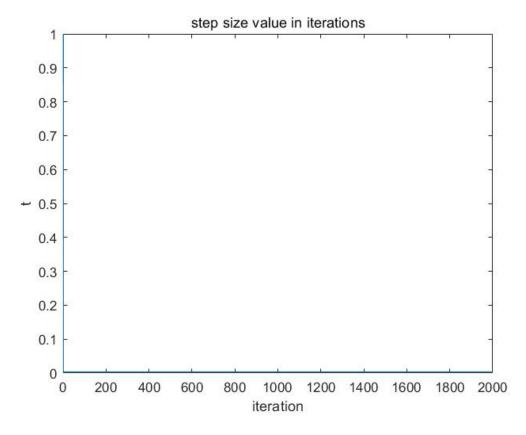
Here is the code

```
%% Clear all variables and close all
close all
clear
clc
alpha=0.01;
beta=0.1;
[f recording1] = get optimal(alpha, beta);
alpha=0.01;
beta=0.5;
[f recording2] = get optimal(alpha, beta);
alpha=0.2;
beta=0.1;
[f recording3] = get optimal(alpha, beta);
alpha=0.2;
beta=0.5;
[f recording4] = get optimal(alpha, beta);
%% plot the performance
figure(1)
x=1:length(f recording1);
plot(x',f recording1);
hold on
x=1:length(f recording2);
plot(x',f recording2);
hold on
x=1:length(f recording3);
plot(x',f recording3);
hold on
x=1:length(f recording4);
plot(x',f recording4);
hold on
legend('alpah=0.01,beta=0.1','alpah=0.01,beta=0.5',
'alpah=0.2, beta=0.1', 'alpah=0.2, beta=0.5');
function f recording=get optimal(alpha, beta)
%% intialize
m = 300;
n = 200;
x = zeros(n, 1);
[f0,g] = gradient function(x);
p star=-340.4402;
t = 1;
f recording = f0;
while norm(g) > 10^{(-3)}
   dx = -g/norm(g);
```

```
f = gradient function(x+t*dx);
   f1 = f0 + alpha*t*g'*dx;
   while abs(f-f1) >= 1
      t = beta*t;
      f = gradient function(x+t*dx);
      f1 = f0 + alpha*t*q'*dx;
   end
   x = x+t*dx;
   [f0,g] = gradient function(x);
   f recording = [f recording;f0];
   f0
   if f0
      break
   end
   if length(f recording) > 10000
      break
   end
end
end
%% get the gradient function
function [f f 1] = gradient function(x);
   A=dlmread('A.txt');
   m = 300;
   n = 200;
   fi = - \log(1 - x.^2);
   for i = 1 : m
      di(i) = - log(1 - A(i,:)*x);
   end
   % get the intial f(x)
   f = sum(fi) + sum(di);
   for i = 1 : m
      fii(i,:) = A(i,:)/(1 - A(i,:)*x);
   end
   dii = 1./(1+x)-1./(1-x);
   % get the first order gradient
   f 1 = sum(fii)' - dii;
end
```

(3) For the case of alpha=0.01, beta=0.5

Using the result from part (2), I plot the change of step size in iterations.



Here is the code.

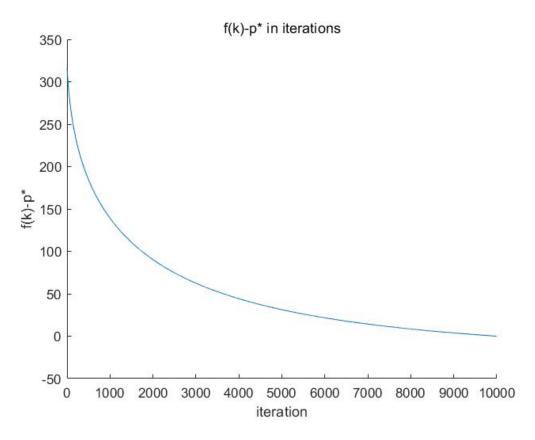
```
%% Clear all variables and close all
close all
clear
clc
%% intialize
m = 300;
n = 200;
x = zeros(n, 1);
alpha=0.01;
beta=0.5;
[f0,g] = gradient function(x);
p star=-340.4402;
t = 1;
t recording = t;
while norm(g) > 10^{(-3)}
   dx = -g/norm(g);
   f = gradient function(x+t*dx);
   f1 = f0 + alpha*t*g'*dx;
   while abs(f-f1) >= 1
       t = beta*t;
       f = gradient function(x+t*dx);
       f1 = f0 + alpha*t*g'*dx;
```

```
end
   x = x+t*dx;
   [f0,g] = gradient function(x);
   t recording = [t recording;t];
   f0
   if f0
      break
   end
end
%% plot the performance
figure(1)
x=1:length(t recording);
plot(x',t recoding);
xlabel("iteration");
ylabel("t");
title("step size value in iterations");
%% Get the gradient function
function [f f 1] = gradient function(x);
   A=dlmread('A.txt');
   m = 300;
   n = 200;
   fi = - \log(1 - x.^2);
   for i = 1 : m
      di(i) = - log(1 - A(i,:)*x);
   end
   f = sum(fi) + sum(di);
   for i = 1 : m
      fii(i,:) = A(i,:)/(1 - A(i,:)*x);
   end
   dii = 1./(1+x)-1./(1-x);
   f 1 = sum(fii)' - dii;
end
```

- (c) Based on the proof of the gradient function of f(x), we get the first order and second order gradient function, and in this part, we use the Newton method to finish this problem.
- (1) From Newton's method, I got this optimal value

optimal value	parameters
-316.3919	Alpha=0.01, beta=0.5

Using the result from part (1), I plot the change of f(k)-p* in iterations.



Here is the code

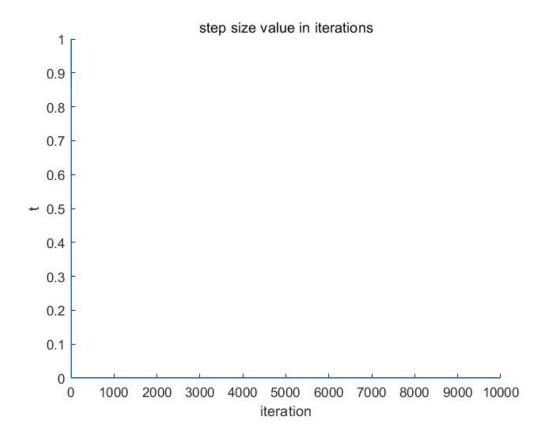
```
%% Clear all variables and close all
close all
clear
clc
%% intialize
m = 300;
n = 200;
x = zeros(n, 1);
alpha=0.01;
beta=0.5;
[f0,g1,g2] = gradient function(x);
t = 1;
p star = -316.3885;
f recording = f0 - p star;
t recording = t;
lambda = g1'*pinv(g2)*g1;
%% Newton's method
while lambda > 10^{(-8)}
   dx = -pinv(g2)*g1;
   f = gradient function(x+t*dx);
   f1 = f0 + alpha*t*q1'*dx;
```

```
while abs(f-f1) >= 1
      t = beta*t;
      f = gradient function(x+t*dx);
      f1 = f0 + alpha*t*q1'*dx;
   end
   x = x + t*dx;
   [f0 g1 g2] = gradient_function(x);
   lambda = g1'*pinv(g2)*g1;
   f0
   t recording = [t recording;t];
   f recording = [f recording;f0 - p star];
   if length(t recording) > 10000
      break
   end
   if f0
      break
   end
end
%% plot the performance
figure(1);
hold on;
x=1:length(f recording);
plot(x',f recording);
xlabel("iteration");
ylabel("f(k) - p*");
title("f(k)-p* in iterations");
hold off;
figure(2);
hold on;
x=1:length(t recording);
plot(x',t recording);
xlabel("iteration");
ylabel("t");
title("step size value in iterations");
hold off;
%% get the gradient function
function [f df ddf] = gradient function(x);
   A=dlmread('A.txt');
   m = 300;
   n = 200;
   fi = - log(1 - x.^2);
```

```
for i = 1 : m
       di(i) = - log(1 - A(i,:)*x);
   end
   f = sum(fi) + sum(di);
   for i = 1 : m
       fii(i,:) = A(i,:)/(1 - A(i,:)*x);
   end
   dii = 1./(1+x)-1./(1-x);
   df = sum(fii)' - dii;
   for i = 1 : m
       fiii(:,:,i) = A(i,:)*A(i,:)'/(1 -
A(i,:)*x).^2;
   end
   diii = (1./(1+x).^2) + (1./(1-x).^2);
   ddf = sum(fiii,3) + diag(diii);
end
```

(3)

I plot the change of step size versus iterations.



As for this part of code, I use part(2) code to plot this performance.