

Event-related potentials to landmarks during "Yellow Cab" – a virtual spatial navigation task

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Introduction

Previous findings

- P300 (target recognition) with parietal maximum for target > non-target (Donchin & Coles, 1988).
- P3a (orienting/arousal for non-targets) with frontal maximum for non-target > target (Squires et al., 1975; Courchesne et al., 1975; Katayama & Polich, 1998).

Hypotheses

- Our major question was whether eventrelated potentials (ERPs) that have previously been linked to novelty detection and to explicit recognition of old vs. new items would differentiate between the viewing of target and non-target landmarks in Yellow Cab – a virtual taxi-driver game.
- A secondary question was whether these hypothesized ERP differences would vary with subjects ability to efficiently navigate to their target landmarks.

We used high-density scalp EEG to assess the electrophysiological correlates of implicit landmark recognition in Yellow Cab.

The Yellow Cab Task

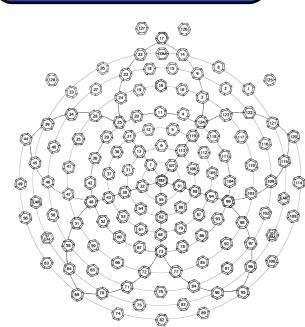


- Participants played the role of a taxi-driver in a virtual town, looking for specific destinations to which passengers ask to be delivered ("goal-seeking"), called target stores (Newman et al., in press).
- \bullet Each town: 6 \times 6 grid, with a single store or building on each block (36 landmarks). 5 stores and 31 buildings in a town, each with a unique façade.
- During the delivery, the 4 stores that are not the target store are considered non-target

Definitions:

- Fast delivery: < 1 block above optimal path (M=-0.19 excess blocks)
- Slow delivery: > 1 block above optimal path (M=6.0 excess blocks)

Scalp EEG





- 128-channel system from Electrical Geodesics, Inc.
- \bullet 200 M Ω high-impedance amplifier.
- Recorded at 500 Hz.
- 20 young adults (ages 19 to 27; eleven male, nine
- Right-handed; normal or corrected-to-normal vision.

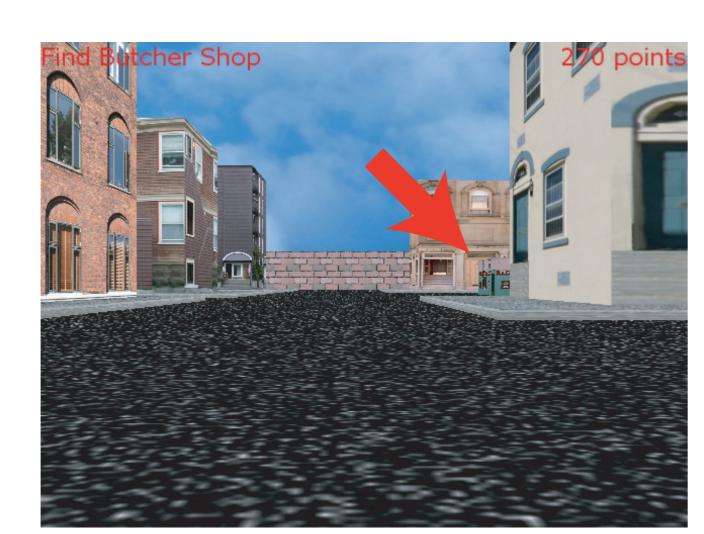
Analytical Methods

Selecting events

- All events are from periods in which participants have picked up a passenger and are searching for the target store.
- Do not know where a participant is looking on the screen; consequently, some latency variability may exist in the appearance of the store and the participant's recognition of a store.

Standardized event selection

- -Set a screen threshold to mark when an object is considered "seen".
- -At a screen threshold of 0.35%, 95% of brief target store appearances would not be counted as seen.
- -Since we don't know when a subject actually sees a store, ERPs do not line up exactly.

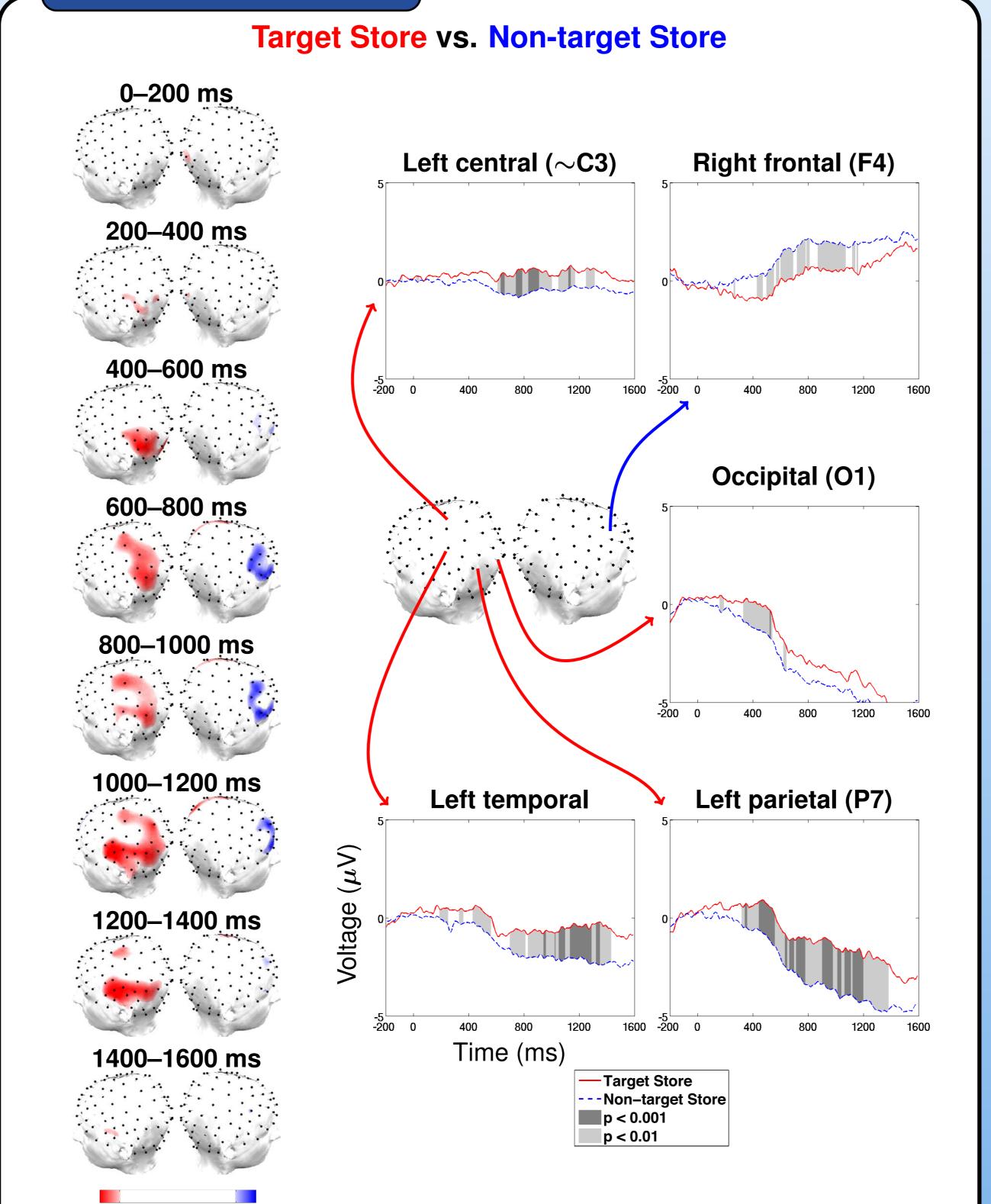


0.35% of the screen is occupied by the store.

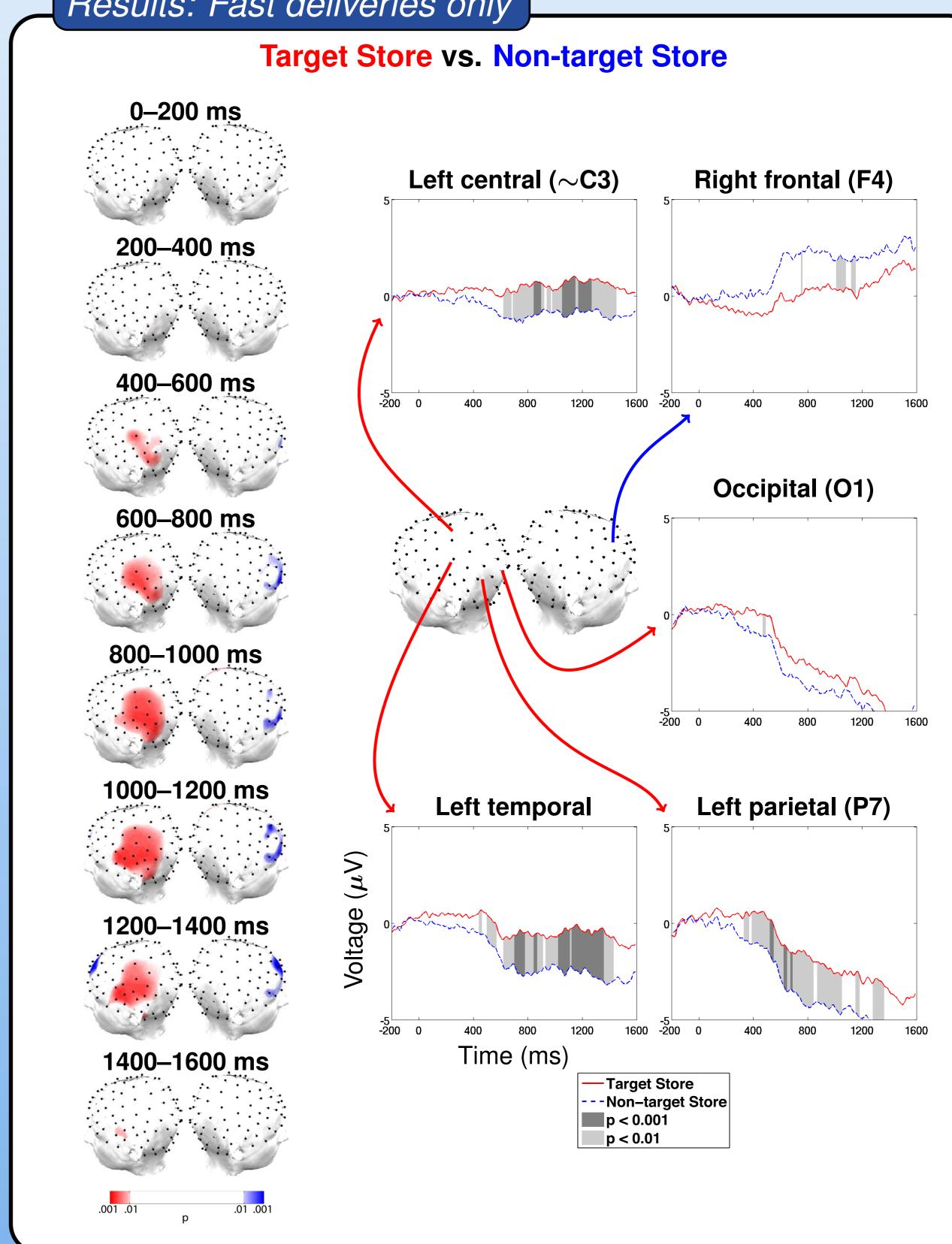
Post-processing EEG data

- Eye-movement artifact detection (electrooculogram $> 100 \mu V$)
- Bad-channel detection (manual inspection of the EEG)
- Average rereference

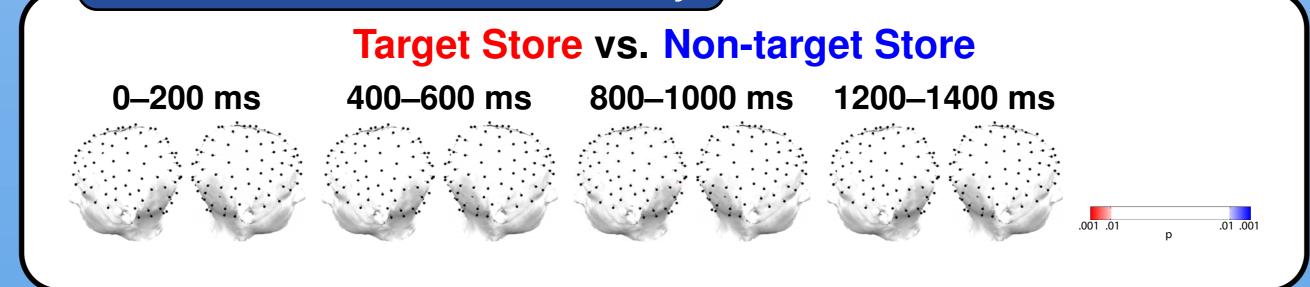
Results: All deliveries



Results: Fast deliveries only



Results: Slow deliveries only



References

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Conclusions

- The P3 differentiates viewing of target and non-target landmarks during navigation.
- get store (match), and an increase in right frontal signals for recognition of a nontarget store (mismatch).
- This P3 profile only appears when subjects navigate efficiently to their destination.
- This dependence on navigation efficiency suggests that the P3 effects are modulated by attentional state.
- This manifests itself as an increase in left parietal voltage for recognition of a tar- By time locking the voltage signal to the appearance of targets on the screen during navigation we were able to report the first analysis of ERPs in a virtual navigation
 - Future studies could use eye-tracking technology to more precisely lock electrophysiological signals to visual events.