### Contents

```
Basic
1.1
1.3
 Matching and Flow
2.5
  Graph
 3.3
  3.5
 Data Structure

  4.5
  Blackmagic

  4.6
  Centroid Decomposition

Dynamic Programming
6.6 NTT
6.7 FWT
6.8 FWT

      6.10
      Berlekamp Massey

      6.11
      Gauss Elimination

      6.12
      Linear Equation

      6.13
      LinearRec

      6.14
      SubsetConv

      6.15
      SqrtMod

      6.16
      FloorSum

Geometry
Stringology
 8.1 KMP .
8.3
 SimpleSuffixArray
PalindromicTree
SmallestRotation
8.7
9.1 HilbertCurve
9.2 DLX
9.3 NextPerm
9.4 FastIO
9.5 Python FastIO
                             13
```

### Basic

#### 1.1 vimrc

```
set ts=4 sw=4 nu rnu et hls mouse=a
filetype indent on
sy on
inoremap jk <Esc>
inoremap {<CR> {<CR>}<C-o>0
nnoremap J 5j
nnoremap K 5k
nnoremap <F1> :w<bar>!g++ '%' -o run -std=c++20 -DLOCAL
      -Wfatal-errors -fsanitize=address,undefined -g -02
     && echo done. && time ./run<CR>
```

#### 1.2 default

```
#include <bits/stdc++.h>
using namespace std;
#ifdef LOCAL
template<class... T> void dbg(T... x) { char e{}; ((
    cerr << e << x, e = ' '), ...); }
template<class T> void org(T l, T r) { while (l != r)
    cerr << ' ' << *l++; cerr << '\n'; }
#define debug(x...) dbg(#x, '=', x, '\n')
#define orang(x...) dbg(#x, '='), org(x)
#also</pre>
#else
#pragma GCC optimize("03,unroll-loops")
#pragma GCC target("avx2,bmi,bmi2,lzcnt,popcnt")
#define debug(...) ((void)0)
#define orange(...) ((void)0)
#endif
#define ff first
#define ss second
#define all(v) (v).begin(), (v).end()
#define rall(v) (v).rbegin(), (v).rend()
template<class T> bool chmin(T &a, T b) { return b < a}</pre>
and (a = b, true); }
template<class T> bool chmax(T &a, T b) { return a < b</pre>
        and (a = b, true); }
1.3
         judge
```

```
set -e
g++ -03 a.cpp -o a
g++ -03 ac.cpp -o c
g++ -03 gen.cpp -o g
for ((i=0;;i++))
  echo "case $i"
  ./g > inp
  time ./a < inp > wa.out
  time ./c < inp > ac.out
  diff ac.out wa.out || break
```

# 1.4 Random

10

11

```
mt19937 rng(random_device{}());
i64 \text{ rand}(i64 \text{ l} = -\text{lim}, i64 \text{ r} = \text{lim})  {
  return uniform_int_distribution<i64>(l, r)(rng);
double randr(double l, double r) {
  return uniform_real_distribution<double>(l, r)(rng);
```

#### Increase stack size

|ulimit -s

#### 2 Matching and Flow

#### 2.1 Dinic

```
template<class Cap>
struct Dinic {
  struct Edge { int v; Cap w; int rev; };
  vector<vector<Edge>> G;
  int n, S, T;
Dinic(int _n, int _S, int _T) : n(_n), S(_S), T(_T),
     G(_n) \{ \}
  void add_edge(int u, int v, Cap w) {
  G[u].push_back({v, w, (int)G[v].size()});
  G[v].push_back({u, 0, (int)G[u].size() - 1});
  vector<int> dep;
  bool bfs() {
     dep.assign(n, 0);
     dep[S] = 1;
     queue<int> que;
     que.push(S);
     while (!que.empty()) {
       int u = que.front(); que.pop();
       for (auto [v, w, _] : G[u])
if (!dep[v] and w) {
             dep[v] = dep[u] + 1;
```

```
que.push(v);
                                                                      };
                                                                        2.3 HopcroftKarp
     return dep[T] != 0;
                                                                       // 1, r <= 1e5
                                                                       struct HK {
  Cap dfs(int u, Cap in) {
                                                                          vector<int> g, l, r;
     if (u == T) return in;
                                                                          int ans;
                                                                          HK(int n, int m, const vector<pair<int, int>> &e)
     Cap out = 0:
     for (auto &[v, w, rev] : G[u]) {
                                                                             : g(e.size()), l(n, -1), r(m, -1), ans{} {
       if (w and dep[v] == dep[u] + 1) {
  Cap f = dfs(v, min(w, in));
                                                                            vector<int> deg(n + 1);
for (auto [x, y] : e) deg[x]++;
partial_sum(all(deg), deg.begin());
          w -= f, G[v][rev].w += f;
in -= f, out += f;
if (!in) break;
                                                                             for (auto [x, y] : e) g[--deg[x]] = y;
                                                                             vector<int> que(n);
       }
                                                                             for (;;) {
                                                                               vector<int> a(n, -1), p(n, -1);
     if (in) dep[u] = 0;
                                                                               for (int i = 0; i < n; i++) if (l[i] == -1)
     return out;
                                                                                 que[t++] = a[i] = p[i] = i;
  Cap maxflow() {
                                                                               bool match = false;
                                                                               for (int i = 0; i < t; i++) {
     Cap ret = 0;
     while (bfs()) {
                                                                                  int x = que[i];
                                                                                 if (~l[a[x]]) continue;
for (int j = deg[x]; j < deg[x + 1]; j++) {</pre>
       ret += dfs(S, INF);
                                                                                    int y = g[j];
     return ret;
                                                                                    if (r[y] == -1) {
   while (~y) r[y] = x, swap(l[x], y), x = p[x
};
                                                                             ];
2.2 zkwDinic
                                                                                      match = true, ans++;
template<class Cap>
                                                                                      break;
struct zkwDinic {
   struct Edge { int v; Cap w, f; int rev; };
                                                                                    if (p[r[y]] == -1)_{{}}
   vector<vector<Edge>> G;
                                                                                      que[t++] = y = r[y]
   int n, S, T;
                                                                                      p[y] = x, a[y] = a[x];
  zkwDinic(int _n, int _S, int _T) : n(_n), S(_S), T(_T
  ), G(_n) {}
void add_edge(int u, int v, Cap w, Cap f) {
  G[u].push_back({v, w, f, (int)G[v].size()});
  G[v].push_back({u, -w, 0, (int)G[u].size() - 1});
                                                                               if (!match) break;
                                                                          }
  vector<Cap> dis;
                                                                       };
  vector<bool> vis;
                                                                        2.4
                                                                               KM
  bool spfa() {
     queue<int> que;
                                                                       i64 KM(vector<vector<int>> W) {
                                                                          const int n = W.size();
     dis.assign(n, INF);
vis.assign(n, false);
                                                                          vector<int> fl(n, -1), fr(n, -1), hr(n), hl(n);
for (int i = 0; i < n; ++i) {</pre>
     que.push(S);
     vis[S] = 1;
                                                                            hl[i] = *max_element(W[i].begin(), W[i].end());
     dis[S] = 0;
     while (!que.empty()) {
                                                                          auto Bfs = [&](int s) {
                                                                            vector<int> slk(n, INF), pre(n);
vector<bool> vl(n, false), vr(n, false);
       int u = que.front(); que.pop();
       vis[u] = 0;
       for (auto [v, w, f, _] : G[u])
  if (f and chmin(dis[v], dis[u] + w))
                                                                             queue<int> que;
                                                                             que.push(s);
            if (!vis[v]) que.push(v), vis[v] = 1;
                                                                             vr[s] = true;
                                                                            auto Check = [&](int x) -> bool {
  if (vl[x] = true, fl[x] != -1) {
     return dis[T] != INF;
                                                                                 que.push(fl[x]);
  Cap dfs(int u, Cap in) {
                                                                                 return vr[fl[x]] = true;
     if (u == T) return in;
     vis[u] = 1;
                                                                               while (x != -1) swap(x, fr[fl[x] = pre[x]]);
     Cap out = 0;
                                                                               return false;
     for (auto &[v, w, f, rev] : G[u])
  if (f and !vis[v] and dis[v] == dis[u] + w) {
                                                                             while (true) {
          Cap x = dfs(v, min(in, f));
                                                                               while (!que.empty()) {
          in -= x, out += x;
                                                                                 int y = que.front(); que.pop();
for (int x = 0, d = 0; x < n; ++x) {</pre>
          f \rightarrow x, G[v][rev].f += x;
          if (!in) break;
                                                                                    if (!vl[x] \text{ and } slk[x] >= (d = hl[x] + hr[y] -
                                                                              W[x][y]))
     if (in) dis[u] = INF;
                                                                                       if (pre[x] = y, d) slk[x] = d;
                                                                                       else if (!Check(x)) return;
     vis[u] = 0;
     return out;
                                                                                 }
  pair<Cap, Cap> maxflow() {
  Cap a = 0, b = 0;
                                                                               }
                                                                               int d = INF;
     while (spfa()) {
                                                                               for (int x = 0; x < n; ++x) {
                                                                                 if (!vl[x] \text{ and } d > slk[x]) d = slk[x];
       Cap x = dfs(S, INF);
       a += x;
       b += x^* dis[T];
                                                                               for (int x = 0; x < n; ++x) {
                                                                                 if (vl[x]) hl[x] += d;
     return {a, b};
                                                                                  else slk[x] -= d;
                                                                                 if (vr[x]) hr[x] -= d;
```

```
auto &e = g[u];
                                                                                 const int v = e[rng() % e.size()];
       for (int x = 0; x < n; ++x) {
         if (!vl[x] \text{ and } !slk[x] \text{ and } !Check(x)) return;
                                                                                 mat[u] = v;
                                                                                  swap(u, mat[v]);
    }
                                                                                 if (u == -1) break;
  for (int i = 0; i < n; ++i) Bfs(i);
                                                                               if (u != -1) {
                                                                                 mat[u] = -1:
  i64 \text{ res} = 0;
  for (int i = 0; i < n; ++i) res += W[i][fl[i]];</pre>
                                                                                  unmat.emplace(hit[u] * 100ULL / (g[u].size() +
                                                                            1),
  return res;
                                                                                 u):
2.5 SW
                                                                             int siz = 0;
int w[kN][kN], g[kN], del[kN], v[kN];
                                                                            for (auto e : mat) siz += (e != -1);
                                                                             return siz / 2;
void AddEdge(int x, int y, int c) {
  w[x][y] += c;
                                                                       };
  w[y][x] += c;
pair<int, int> Phase(int n) {
  fill(v, v + n, 0), fill(g, g + n, 0);
  int s = -1, t = -1;
                                                                        3
                                                                             Graph
                                                                       3.1
                                                                             2-SAT
  while (true) {
                                                                       struct TwoSAT {
     int c = -1;
for (int i = 0; i < n; ++i) {
   if (del[i] || v[i]) continue;</pre>
                                                                          vector<vector<int>> G;
                                                                          int n
                                                                          TwoSAT(int _n) : n(_n), G(_n * 2) {}
       if (c == -1 || g[i] > g[c]) c = i;
                                                                          int ne(int x) { return x < n ? x + n : x - n; }
void add_edge(int u, int v) { // u or v</pre>
     if (c == -1) break;
    v[c] = 1, s = t, t = c;
for (int i = 0; i < n; ++i) {
  if (del[i] || v[i]) continue;</pre>
                                                                             G[ne(u)].push_back(v);
                                                                            G[ne(v)].push_back(u);
                                                                          vector<int> solve() {
  vector<int> ans(n * 2, -1), id(n * 2), stk, \
    low(n * 2), dfn(n * 2), vis(n * 2);
       g[i] += w[c][i];
  }
                                                                             int _t = 0, scc_cnt = 0;
  return make_pair(s, t);
                                                                             function<void(int)> dfs = [&](int u) {
                                                                               dfn[u] = low[u] = _t++;
int GlobalMinCut(int n) {
                                                                               stk.push_back(u);
  int cut = kInf;
fill(del, 0, sizeof(del));
for (int i = 0; i < n - 1; ++i) {</pre>
                                                                               vis[u] = 1;
                                                                               for (int v : G[u]) {
                                                                                 if (!vis[v])
     int s, t; tie(s, t) = Phase(n);
                                                                                 dfs(v), chmin(low[u], low[v]);
else if (vis[v] == 1)
    del[t] = 1, cut = min(cut, g[t]);
for (int j = 0; j < n; ++j) {
  w[s][j] += w[t][j];</pre>
                                                                                    chmin(low[u], dfn[v]);
       w[j][s] += w[j][t];
                                                                               if (dfn[u] == low[u]) {
     }
                                                                                 for (int x = -1; x != u; ) {
  x = stk.back(); stk.pop_back();
  return cut;
                                                                                    vis[x] = 2, id[x] = scc\_cnt;
                                                                                    if (ans[x] == -1) {
                                                                                      ans[x] = 1;
2.6 GeneralMatching
                                                                                      ans [ne(x)] = 0;
struct GeneralMatching { // n <= 500</pre>
                                                                                    }
  const int BLOCK = 1\bar{0};
  int n;
                                                                                 scc_cnt++;
  vector<vector<int> > g;
                                                                               }
  vector<int> hit, mat;
  std::priority_queue<pair<i64, int>, vector<pair<i64,
                                                                             for (int i = 0; i < n + n; i++)
     int>>, greater<pair<i64, int>>> unmat;
                                                                             if (!vis[i]) dfs(i);
for (int i = 0; i < n; i++)</pre>
  GeneralMatching(int _n): n(_n), g(_n), mat(n, -1),
     hit(n) {}
                                                                               if (id[i] == id[ne(i)])
  void add_edge(int a, int b) \{ // \emptyset \le a != b < n \}
                                                                                 return {};
     g[a].push_back(b);
                                                                             ans.resize(n);
     g[b].push_back(a);
                                                                             return ans;
                                                                          }
  int get_match() {
                                                                       };
     for (int i = 0; i < n; i++) if (!g[i].empty()) {</pre>
       unmat.emplace(0, i);
                                                                        3.2
                                                                              Manhattan MST
     // If WA, increase this
                                                                       vector<tuple<int, int, int>> ManhattanMST(vector<Pt> P)
     // there are some cases that need >=1.3*n^2 steps
     for BLOCK=1
                                                                          vector<int> id(P.size());
                                                                          iota(all(id), 0);
     // no idea what the actual bound needed here is.
     const int MAX_STEPS = 10 + 2 * n + n * n / BLOCK /
                                                                          vector<tuple<int, int, int>> edges;
                                                                          for (int k = 0; k < 4; ++k) {
  sort(all(id), [&](int i, int j) -> bool {
    return (P[i] - P[j]).ff < (P[j] - P[i]).ss;</pre>
     mt19937 rng(random_device{}());
     for (int i = 0; i < MAX_STEPS; ++i) {
       if (unmat.empty()) break;
                                                                             });
       int u = unmat.top().second;
                                                                            map<int, int> sweep;
       unmat.pop();
                                                                             for (int i : id) {
       if (mat[u] != -1) continue;
                                                                               for (auto it = sweep.lower_bound(-P[i].ss); \
       for (int j = 0; j < BLOCK; j++) {
    ++hit[u];</pre>
                                                                                    it != sweep.end(); sweep.erase(it++)) {
```

int j = it->ss;

for (int j = 1; j <= n; ++j) {

```
Pt d = P[i] - P[j];
                                                                       for (int k = 1; k \le n; ++k) {
                                                                        dp[i][k] = min(dp[i - 1][j] + d[j][k], dp[i][k]);
         if (d.ss > d.ff) break;
         edges.emplace_back(d.ss + d.ff, i, j);
       sweep[-P[i].ss] = i;
                                                                    long long au = 1ll << 31, ad = 1;
for (int i = 1; i <= n; ++i) {
    for (Pt &p : P) {
                                                                      if (dp[n][i] == 0x3f3f3f3f3f3f3f3f3f) continue;
       if (k % 2) p.ff = -p.ff;
                                                                     long long u = 0, d = 1;

for (int j = n - 1; j >= 0; --j) {

   if ((dp[n][i] - dp[j][i]) * d > u * (n - j)) {

      u = dp[n][i] - dp[j][i];
       else swap(p.ff, p.ss);
  return edges;
}
                                                                        d = n - j;
3.3
     TreeHash
                                                                      if (u * ad < au * d) au = u, ad = d;
u64 TreeHash(const vector<vector<int>> &G) {
  const int n = G.size();
                                                                    long long q = \_\_qcd(au, ad);
  vector<int> cen;
                                                                    return make_pair(au / g, ad / g);
  vector<u64> pw(n, 1);
  for (int i = 1; i < n; i++) pw[i] = pw[i - 1] * u64(1)
    e9 + 123)
                                                                   3.6 Block Cut Tree
  auto dfs = [&](auto self, int u, int fa) -> int {
                                                                   struct BlockCutTree {
    int siz = 1;
                                                                     int n;
    bool f = true;
                                                                      vector<vector<int>> adj;
    for (int v : G[u]) if (v != fa) {
  int s = self(self, v, u);
                                                                     BlockCutTree(int _n) : n(_n), adj(_n) {}
void addEdge(int u, int v) {
       f &= (s * 2 <= n);
                                                                        adj[u].push_back(v);
       siz += s;
                                                                        adj[v].push_back(u);
    f \&= ((n - siz) * 2 <= n);
                                                                     pair<int, vector<pair<int, int>>> work() {
  vector<int> dfn(n, -1), low(n), stk;
    if (f) cen.push_back(u);
return siz;
                                                                        vector<pair<int, int>> edg;
int cnt = 0, cur = 0;
  }; dfs(dfs, 0, -1);
auto cal = [&](auto self, int u, int fa) -> pair<u64,</pre>
                                                                        function<void(int)> dfs = [&](int x) {
      int> {
                                                                          stk.push_back(x);
    vector<pair<u64, int>> U;
                                                                          dfn[x] = low[x] = cur++;
    int siz = 1;
                                                                          for (auto y : adj[x]) {
  if (dfn[y] == -1) {
    u64 h = G[u].size();
    for (int \bar{v} : G[u]) if (v != fa) {
                                                                               dfs(y);
      U.push_back(self(self, v, u));
                                                                               low[x] = min(low[x], low[y]);
                                                                               if (low[y] == dfn[x]) {
    sort(all(U));
                                                                                 int v;
    for (auto [v, s] : U) {
  h = h * pw[s] + v;
                                                                                 do {
                                                                                   v = stk.back();
       siz += s;
                                                                                   stk.pop_back():
                                                                                   edg.emplace_back(n + cnt, v);
    return {h, siz};
                                                                                 } while (v != y);
                                                                                 edg.emplace_back(x, n + cnt);
  vector<u64> H;
                                                                                 cnt++;
  for (int c : cen) H.push_back(cal(cal, c, -1).ff);
  return ranges::min(H);
                                                                            } else {
};
                                                                               low[x] = min(low[x], dfn[y]);
3.4 Maximum IndependentSet
// n <= 40, (*500)
set<int> MI(const vector<vector<int>> &adj) {
                                                                        for (int i = 0; i < n; i++) {
  set<int> I, V;
                                                                          if (dfn[i] == -1) {
  for (int i = 0; i < adj.size(); i++)</pre>
                                                                            stk.clear();
    V.insert(i)
                                                                            dfs(i);
  while (!V.empty()) {
    auto it = next(V.begin(), rng() % V.size());
     int cho = *it;
                                                                        return {cnt, edg};
    I.insert(cho)
                                                                     }
    V.extract(cho)
                                                                  };
    for (int i : adj[cho]) {
  if (auto j = V.find(i); j != V.end())
                                                                   3.7 Heavy Light Decomposition
         V.erase(j);
                                                                   struct HLD {
    }
                                                                      int n:
  }
                                                                      vector<int> siz, top, dep, pa, in, out, seq;
  return I;
                                                                      vector<vector<int>> G;
                                                                      HLD(int _n) : n(_n), G(_n) {}
                                                                      int cur{};
3.5 Min Mean Weight Cycle
                                                                      void addEdge(int u, int v) {
// d[i][j] == 0 if {i,j} !in E
                                                                        G[u].push_back(v);
long long d[1003][1003], dp[1003][1003];
                                                                        G[v].push_back(u);
pair<long long, long long> MMWC() {
                                                                      void work(int root = 0) {
 memset(dp, 0x3f, sizeof(dp));
                                                                        siz = top = dep = pa = in = out = seq = vector<int
 for (int i = 1; i <= n; ++i) dp[0][i] = 0;
for (int i = 1; i <= n; ++i) {</pre>
                                                                        >(n);
```

cur = 0;

top[root] = root;

d = v[l];

```
dep[root] = 0;
                                                                        return;
    pa[root] = -1;
    dfs1(root);
                                                                      int mid = l + r \gg 1;
                                                                      ls = new Seg(l, mid, v)
    dfs2(root);
                                                                     rs = new Seg(mid, r, v);
  void dfs1(int u) {
                                                                     pull();
    if (pa[u] != -1) {
      G[u].erase(find(all(G[u]), pa[u]));
                                                                   void upd(const T &g) {
                                                                     g(d), g(f);
    siz[u] = 1;
    for (auto &v : G[u]) {
                                                                   void pull() {
      pa[v] = u;
                                                                     d = ls -> d + rs -> d;
      dep[v] = dep[u] + 1;
      dfs1(v);
                                                                   void push() {
                                                                     ls->upd(f);
      siz[u] += siz[v];
      if (siz[v] > siz[G[u][0]]) {
                                                                     rs->upd(f);
        swap(v, G[u][0]);
                                                                      f = T{};
                                                                   S prod(int x, int y) {
    }
                                                                      if (y <= l or r <= x) return S{};</pre>
                                                                      if (x \ll 1) and r \ll y) return d;
  void dfs2(int u) {
                                                                      push();
    in[u] = cur++;
    seq[in[u]] = u;
                                                                      return ls->prod(x, y) + rs->prod(x, y);
    for (int v : G[u]) {
                                                                   void apply(int x, int y, const T &g) {
  if (y <= l or r <= x) return;</pre>
      top[v] = (v == G[u][0] ? top[u] : v);
      dfs2(v);
                                                                      if (x \le 1 \text{ and } r \le y) {
    out[u] = cur;
                                                                        upd(g);
                                                                        return;
  int lca(int x, int y) {
  while (top[x] != top[y]) {
                                                                     push();
      if (dep[top[x]] < dep[top[y]]) swap(x, y);</pre>
                                                                     ls->apply(x, y, g);
rs->apply(x, y, g);
      x = pa[top[x]];
                                                                     pull();
    return dep[x] < dep[y] ? x : y;</pre>
                                                                 };
  int dist(int_x, int y) {
                                                                       Treap
    return dep[x] + dep[y] - 2 * dep[lca(x, y)];
                                                                 mt19937 rng(random_device{}());
  int jump(int x, int k) {
                                                                 template<class S, class T>
    if (dep[x] < k) return -1;</pre>
                                                                 struct Treap {
                                                                   struct Node {
  Node *ls{}, *rs{};
    int d = dep[x] - k;
    while (dep[top[x]] > d) {
      x = pa[top[x]];
                                                                      int pos, siz;
                                                                      u32 pri;
    return seq[in[x] - dep[x] + d];
                                                                      S d{}, e{};
                                                                     T f{};
 bool isAnc(int x, int y) {
                                                                     Node(int p, S x) : d\{x\}, e\{x\}, pos\{p\}, siz\{1\}, pri\{
    return in[x] <= in[y] and in[y] < out[x];</pre>
                                                                      rng()} {}
                                                                      void upd(T &g) {
  int rootPar(int r, int x) {
                                                                       g(d), g(e), g(f);
    if (r == x) return r;
    if (!isAnc(x, r)) return pa[x];
                                                                      void pull() {
                                                                        siz = Siz(ls) + Siz(rs);
    auto it = upper_bound(all(G[x]), r, [&](int a, int
    b) -> bool {
                                                                        d = Get(ls) + e + Get(rs);
      return in[a] < in[b];</pre>
    });
                                                                      void push() {
                                                                        if (ls) ls->upd(f);
if (rs) rs->upd(f);
    return *it;
                                                                        f = T{};
  int rootSiz(int r, int x) {
    if (r == x) return n;
if (!isAnc(x, r)) return siz[x];
                                                                   } *root{};
    return n - siz[rootPar(r, x)];
                                                                   static int Siz(Node *p) { return p ? p->siz : 0; }
                                                                   static S Get(Node *p) { return p ? p->d : S{}; }
                                                                   Treap() : root{} {}
Node* Merge(Node *a, Node *b) {
 int rootLca(int a, int b, int c) {
    return lca(a, b) ^ lca(b, c) ^ lca(c, a);
                                                                      if (!a or !b) return a ? a : b;
                                                                      if (a->pri < b->pri) {
                                                                        a->push();
4
     Data Structure
                                                                        a \rightarrow rs = Merge(a \rightarrow rs, b);
                                                                        a->pull();
4.1 Lazy Segtree
                                                                        return a;
template<class S, class T>
                                                                     } else {
struct Seg {
  Seg<S, T> *ls{}, *rs{};
                                                                        b->push();
                                                                        b->ls = Merge(a, b->ls);
  int l, r;
                                                                        b->pull();
  S d{};
                                                                        return b;
  Seg(int _l, int _r, const vector<Info> &v) : l{_l}, r
    {_r} {
if (r - l == 1) {
                                                                   void Split(Node *p, Node *&a, Node *&b, int k) {
                                                                      if (!p) return void(a = b = nullptr);
```

p->push();

void pull() {

```
if (p->pos <= k) {
                                                                      sum = ls -> sum + rs -> sum;
                                                                   Seg* modify(int p, int v) {
      Split(p->rs, a->rs, b, k);
                                                                      Seg* ret = new Seg(this);
      a->pull();
    } else {
                                                                      if(r - l == 1) {
      b = p;
                                                                        ret->sum = v;
      Split(p->ls, a, b->ls, k);
                                                                        return ret;
      b->pull();
                                                                      if (p < (l + r >> 1)) ret->ls = ret->ls->modify(p,
                                                                      v);
                                                                      else ret->rs = ret->rs->modify(p, v);
  void insert(int p, S x) {
    Node *L, *R;
                                                                      ret->pull();
    Split(root, L, R, p);
                                                                     return ret;
    root = Merge(Merge(L, new Node(p, x)), R);
                                                                   i64 query(int x, int y) {
                                                                     if (y <= l or r <= x) return 0;
if (x <= l and r <= y) return sum;
  void erase(int x) {
  Node *L, *M, *R;
    Split(root, M, R, x);
                                                                      return ls->query(x, y) + rs->query(x, y);
    Split(M, L, M, x' - 1);
                                                                   }
                                                                };
    if (M) M = Merge(M->ls, M->rs);
    root = Merge(Merge(L, M), R);
                                                                 4.5
                                                                        Blackmagic
  S query() {
                                                                 #include <bits/extc++.h>
    return Get(root);
                                                                 #include <ext/pb_ds/assoc_container.hpp>
                                                                 #include <ext/pb_ds/tree_policy.hpp>
                                                                 #include <ext/pb_ds/hash_policy.hpp>
                                                                 #include <ext/pb_ds/priority_queue.hpp>
4.3 LiChao Segtree
                                                                 using namespace __gnu_pbds;
struct Line {
    i64 k, m; // y = k + mx;
                                                                 template<class T>
                                                                 using BST = tree<T, null_type, less<T>, rb_tree_tag,
  Line(): k{INF}, m{} {}
Line(i64 _k, i64 _m): k(_k), m(_m) {}
                                                                      tree_order_statistics_node_update>;
                                                                 gnu_pbds::priority_queue<node, decltype(cmp),</pre>
  i64 get(i64 x) {
                                                                      pairing_heap_tag> pq(cmp);
    return k + m * x;
                                                                 gp_hash_table<int, gnu_pbds::priority_queue<node>::
                                                                      point_iterator> pqPos;
                                                                 bst.insert((x << 20) + i)
};
struct Seg {
   Seg *ls{}, *rs{};
   int l, r, mid;
                                                                 bst.erase(bst.lower_bound(x << 20));</pre>
                                                                 bst.order_of_key(x << 20) + 1;
                                                                 *bst.find_by_order(x - 1) >> 20;
*--bst.lower_bound(x << 20) >> 20;
  Line line{};
  Seg(int _l, int _r) : l(_l), r(_r), mid(_l + _r >> 1)
                                                                 *bst.upper_bound((x + 1) << 20) >> 20;
                                                                 4.6 Centroid Decomposition
    if (r - l == 1) return;
    ls = new Seg(l, mid);
                                                                 struct CenDec {
    rs = new Seg(mid, r);
                                                                   vector<vector<pair<int, int>>> anc;
                                                                   vector<int> Mdis;
  void insert(Line L) {
                                                                   CenDec(const vector<vector<int>> &G) : anc(G.size()),
    if (line.get(mid) > L.get(mid))
                                                                       Mdis(G.size(), INF)
    swap(line, L);
if (r - l == 1) return;
                                                                      const int n = G.size();
                                                                      vector<int> siz(n);
    if (L.m < line.m) {</pre>
                                                                      vector<bool> vis(n);
      rs->insert(L);
                                                                      function<int(int, int)> getsiz = [&](int u, int f)
    } else {
      ls->insert(L);
                                                                        siz[u] = 1;
                                                                        for (int v : G[u]) if (v != f and !vis[v])
                                                                          siz[u] += getsiz(v, u);
  i64 query(int p) {
                                                                        return siz[u];
    if (p < l or r <= p) return INF;
if (r - l == 1) return line.get(p);</pre>
                                                                      function<int(int, int, int)> find = [&](int u, int
                                                                      f, int s) {
  for (int v : G[u]) if (v != f and !vis[v])
    return min({line.get(p), ls->query(p), rs->query(p)
    });
                                                                          if (siz[v] * 2 >= s) return find(v, u, s);
  }
};
                                                                        return u:
4.4 Persistent SegmentTree
                                                                      function<void(int, int, int, int)> caldis = [&](int
struct Seg {
                                                                       u, int f, int a, int d) {
                                                                        anc[u].emplace_back(a, d);
for (int v : G[u]) if (v != f and !vis[v])
  Seg *ls{}, *rs{};
  int l, r;
  i64 sum{}
                                                                          caldis(v, u, a, d + 1);
  Seg(Seg* p) { (*this) = *p; }
Seg(int _l, int _r, const vector<int> &v) : l{_l}, r{
                                                                      function<void(int)> build = [&](int u) {
                                                                        u = find(u, u, getsiz(u, u));
    if (r - l == 1) {
                                                                        vis[u] = 1;
      sum = v[l];
                                                                        for (int v : G[u]) if (!vis[v]) {
                                                                          caldis(v, u, u, 1);
      return;
                                                                          build(v);
    int mid = l + r >> 1;
ls = new Seg(l, mid, v);
                                                                        vis[u] = 0;
    rs = new Seg(mid, r, v);
                                                                     }:
    pull();
                                                                     build(0);
```

void add(int p) {

```
Mdis[p] = 0;
      for (auto [v, d] : anc[p])
         chmin(Mdis[v], d);
   int que(int p) {
     int r = Mdis[p];
for (auto [v, d] : anc[p])
    chmin(r, Mdis[v] + d);
      return r;
  }
};
```

#### 5 **Dynamic Programming**

#### 5.1 CDQ

```
auto cmp2 = [&](int a, int b) -> bool { return P[a][1]
sort(l, mid, cmp2);
  sort(mid, r, cmp2);
for (auto i = l, j = mid; j < r; j++) {
   while (i != mid and P[*i][1] < P[*j][1]) {</pre>
       bit.add(P[*i][2], dp[*i]);
        i++;
     dp[*j].upd(bit.qry(P[*j][2]));
   for (auto i = 1; i < mid; i++) bit.reset(P[*i][2]);</pre>
copy(all(tmp), mid);
self(self, mid, r);
}; cdq(cdq, all(ord));
```

# Math

#### 6.1 Theorem

· Pick's theorem

$$A = i + \frac{b}{2} - 1$$

· Laplacian matrix

$$L = D - A$$

· Extended Catalan number

$$\frac{1}{(k-1)n+1} \binom{kn}{n}$$

• Derangement  $D_n = (n-1)(D_{n-1} + D_{n-2})$ 

$$\sum_{i\mid n}\mu(i)=[n=1]\sum_{i\mid n}\phi(i)=n$$

$$\begin{split} f(n) &= \sum_{i=0}^n {n \choose i} g(i) \; g(n) = \sum_{i=0}^n (-1)^{n-i} {n \choose i} f(i) \\ f(n) &= \sum_{d\mid n} g(d) \; g(n) = \sum_{d\mid n} \mu(\frac{n}{d}) f(d) \end{split}$$

· Sum of powers

$$\begin{split} \sum_{k=1}^{n} k^m &= \frac{1}{m+1} \sum_{k=0}^{m} \binom{m+1}{k} B_k^+ \, n^{m+1-k} \\ \sum_{j=0}^{m} \binom{m+1}{j} B_j^- &= 0 \\ \text{note} : B_1^+ &= -B_1^- \, B_i^+ = B_i^- \end{split}$$

· Cipolla's algorithm

$$\left(\frac{u}{p}\right) = u^{\frac{p-1}{2}}$$

$$1. \left(\frac{a^2 - n}{p}\right) = -1$$

2. 
$$x = (a + \sqrt{a^2 - n})^{\frac{p+1}{2}}$$

• Cayley's formula number of trees on n labeled vertices:  $n^{n-2}$ Let  $T_{n,k}$  be the number of labelled forests on n vertices with  ${\bf k}$  connected components, such that vertices 1, 2, ..., k all belong to different connected components. Then  $T_{n,k}=kn^{n-k-1}$  .

· High order residue

$$[d^{\frac{p-1}{(n,p-1)}} \equiv 1]$$

· Packing and Covering  $|\mathsf{Maximum\ Independent\ Set}| + |\mathsf{Minimum\ Vertex\ Cover}| = |V|$ 

· Kőnia's theorem

|maximum matching| = |minimum vertex cover|

· Dilworth's theorem

 $\mbox{width} = |\mbox{largest antichain}| = |\mbox{smallest chain decomposition}|$ 

· Mirsky's theorem

 $\mbox{height} \quad = \quad |\mbox{longest chain}| \quad = \quad |\mbox{smallest antichain decomposition}|$ |minimum anticlique partition|

· Triangle center

- 
$$G:(1,)$$
  
-  $O:(a^2(b^2+c^2-a^2),)=(sin2A,)$   
-  $I:(a,)=(sinA)$ 

- 
$$E:(-a,b,c)=(-sinA,sinB,sinC)$$

- 
$$H: (\frac{1}{h^2+c^2-a^2},) = (tan A,)$$

• Lucas'Theorem : For  $n,m\in\mathbb{Z}^*$  and prime P ,  $C(m,n)\mod P=\Pi(C(m_i,n_i))$  where  $m_i$ is the i-th digit of m in base P.

• Stirling approximation:

$$n! \approx \sqrt{2\pi n} \left(\frac{n}{e}\right)^n e^{\frac{1}{12n}}$$

• Stirling Numbers(permutation |P|=n with k cycles):  $S(n,k) = \text{coefficient of } x^k \text{ in } \Pi_{i=0}^{n-1}(x+i)$ 

• Stirling Numbers(Partition n elements into k non-empty set):

$$S(n,k) = \frac{1}{k!} \sum_{j=0}^{k} (-1)^{k-j} {k \choose j} j^n$$

• Pick's Theorem : A = i + b/2 - 1A: Area  $\cdot$  i: grid number in the inner  $\cdot$  b: grid number on the side

• Catalan number :  $C_n = \binom{2n}{n}/(n+1)$  $C_n^{n+m} - C_{n+1}^{n+m} = (m+n)! \frac{n-m+1}{n+1}$  for  $n \ge m$  $C_n = \frac{1}{n+1} {2n \choose n} = \frac{(2n)!}{(n+1)!n!}$  $\begin{array}{lll} C_0 = 1 & and & C_{n+1} = 2(\frac{2n+1}{n+2})C_n \\ C_0 = 1 & and & C_{n+1} = \sum_{i=0}^n C_i C_{n-i} & for & n \geq 0 \end{array}$ 

• Euler Characteristic:

planar graph: V-E+F-C=1 convex polyhedron: V-E+F=2

V, E, F, C: number of vertices, edges, faces(regions), and components

· Kirchhoff's theorem:

 $A_{ii} = deg(i), A_{ij} = (i,j) \in E \,?\,-\,1:0$ , Deleting any one row, one column,

- Polya' theorem (c is number of color • m is the number of cycle size):  $\left(\sum_{i=1}^{m} c^{\gcd(i,m)}\right)/m$ 

- Burnside lemma: 
$$|X/G| = \tfrac{1}{|G|} \sum_{g \in G} |X^g|$$

・ 錯排公式: (
$$n$$
 個人中,每個人皆不再原來位置的組合數):  $dp[0]=1; dp[1]=0;$   $dp[i]=(i-1)*(dp[i-1]+dp[i-2]);$ 

• Bell 數 (有 n 個人, 把他們拆組的方法總數):

$$B_0 = 1$$

$$B_n = \sum_{k=0}^{n} s(n, k) \quad (second - stirling)$$

$$B_{n+1} = \sum_{k=0}^{n} {n \choose k} B_k$$

· Wilson's theorem :

$$(p-1)! \equiv -1 \pmod{p}$$

• Fermat's little theorem :  $a^p \equiv a \pmod{p}$ 

· Euler's totient function:

$$A^{B^C} \mod p = pow(A, pow(B, C, p - 1)) \mod p$$

• 歐拉函數降冪公式:  $A^B \mod C = A^{B \mod \phi(c) + \phi(c)} \mod C$ 

• 環相鄰塗異色:

$$(k-1)(-1)^n + (k-1)^n$$

• 6 的倍數:  $(a-1)^3 + (a+1)^3 + (-a)^3 + (-a)^3 = 6a$  if (b == 0) return  $\{1, 0\}$ ;

### 6.2 Exgcd

```
auto [x, y] = exgcd(b, a % b);
return {y, x - a / b * y};
};

6.3 CRT

| i64 CRT(vector<pair<i64, i64>> E) {
    i128 R = 0, M = 1;
    for (auto [r, m] : E) {
        i128 d = r - R, g = gcd<i64>(M, m);
        if (d % g != 0) return -1;
        i128 x = exgcd(M / g, m / g).ff * d / g;
        R += M * x;
        M = M * m / g;
        R = (R % M + M) % M;
    }
    return R;
}
```

pair<i64, i64> exgcd(i64 a, i64 b)  $\{ // ax + by = 1 \}$ 

# 6.4 Factorize

```
struct Factorize {
  i64 fmul(i64 a, i64 b, i64 p) {
     return (i128)a * b % p;
  i64 fpow(i64 a, i64 b, i64 p) {
     i64 res = 1;
     for (; b; b >>= 1, a = fmul(a, a, p))
       if (b & 1) res = fmul(res, a, p);
     return res;
  bool Check(i64 a, i64 u, i64 n, int t) {
     a = fpow(a, u, n);
     if (a == 0) or a == 1 or a == n - 1) return true;
for (int i = 0; i < t; i++) {
       a = fmul(a, a, n);
       if (a == 1) return false;
       if (a == n - 1) return true;
     return false;
  bool IsPrime(i64 n) {
     constexpr array<i64, 7> kChk{2, 235, 9375, 28178,
     450775, 9780504, 1795265022};
     // for int: {2, 7, 61}
     if (n < 2) return false;
     if (n % 2 == 0) return n == 2;
     i64 u = n - 1;
     int t = 0;
     while (u \% 2 == 0) u >>= 1, t++;
     for (auto v : kChk) if (!Check(v, u, n, t)) return
     false;
     return true;
  i64 PollardRho(i64 n) {
    if (n % 2 == 0) return 2;

i64 x = 2, y = 2, d = 1, p = 1;

auto f = [](i64 x, i64 n, i64 p) -> i64 {

return ((i128)x * x % n + p) % n;
     while (true) {
       x = f(x, n, p);
y = f(f(y, n, p), n, p);
d = __gcd(abs(x - y), n);
if (d != n and d != 1) return d;
       if (d == n) ++p;
};
```

# 6.5 NTT Prime List

```
Prime
             Root
                                    Root
7681
             17
                      167772161
12289
             11
                      104857601
40961
                      985661441
65537
                      998244353
             10
                      1107296257
5767169
                      2013265921
7340033
                      2810183681
                                   11
23068673
                      2885681153
469762049
                      605028353
```

#### 6.6 NTT

```
constexpr i64 cpow(i64 a, i64 b, i64 m) {
   i64 ret = 1;
   for (; b; b >>= 1, a = a * a % m)
     if (b & 1) ret = ret * a % m;
   return ret:
};
template<i64 M, i64 G>
struct NTT {
   static constexpr i64 iG = cpow(G, M - 2, M);
   void operator()(vector<i64> &v, bool inv) {
     int n = v.size();
for (int i = 0, j = 0; i < n; i++) {</pre>
       if (i < j) swap(v[ij, v[j]);
for (int k = n / 2; (j ^= k) < k; k /= 2);</pre>
     for (int mid = 1; mid < n; mid *= 2) {</pre>
       i64 \text{ w} = \text{cpow}((inv ? iG : G), (M - 1) / (mid + mid))
     ), M);
       for (int i = 0; i < n; i += mid * 2) {
          i64 \text{ now} = 1;
          for (int j = i; j < i + mid; j++, now = now * w
      % M) {
            i64 x = v[j], y = v[j + mid];
v[j] = (x + y * now) % M;
            v[j + mid] = (x - y * now) % M;
       }
     if (inv) {
       i64 in = cpow(n, M - 2, M);
       for (int i = 0; i < n; i++) v[i] = v[i] * in % M;
  }
};
template<i64 M, i64 G>
vector<i64> convolution(vector<i64> f, vector<i64> g) {
   NTT<M, G> ntt;
   int sum = f.size() + g.size() - 1;
   int len = bit_ceil((u64)sum);
   f.resize(len); g.resize(len);
   ntt(f, 0), ntt(g, 0);
   for (int i = 0; i < len; i++) (f[i] *= g[i]) %= M;
   ntt(f, 1);
   f.resize(sum)
   for (int i = 0; i < sum; i++) if (f[i] < 0) f[i] += M
   return f;
vector<i64> convolution_ll(const vector<i64> &f, const
     vector<i64> &g) {
   constexpr i64 \text{ M1} = 998244353, G1 = 3;
   constexpr i64 M2 = 985661441, G2 = 3;
   constexpr i64 M1M2 = M1 * M2;
   constexpr i64 M1m1 = M2 * cpow(M2, M1 - 2, M1);
constexpr i64 M2m2 = M1 * cpow(M1, M2 - 2, M2);
   auto c1 = convolution<M1, G1>(f, g);
   auto c2 = convolution<M2, G2>(f, g);
   for (int i = 0; i < c1.size(); i++)
     c1[i] = ((i128)c1[i] * M1m1 + (i128)c2[i] * M2m2) %
      M1M2;
   return c1;
}
```

# 6.7 FWT

- 1. XOR Convolution
  - $f(A) = (f(A_0) + f(A_1), f(A_0) f(A_1))$ •  $f^{-1}(A) = (f^{-1}(\frac{A_0 + A_1}{2}), f^{-1}(\frac{A_0 - A_1}{2}))$
- 2. OR Convolution
  - $f(A) = (f(A_0), f(A_0) + f(A_1))$ •  $f^{-1}(A) = (f^{-1}(A_0), f^{-1}(A_1) - f^{-1}(A_0))$
- 3. AND Convolution
  - $f(A) = (f(A_0) + f(A_1), f(A_1))$ •  $f^{-1}(A) = (f^{-1}(A_0) - f^{-1}(A_1), f^{-1}(A_1))$

```
6.8 FWT
void FWT(vector<int> &f, int 1, int r, auto &op) {
  if (r - l == 1) return;
  int m = 1 + r >> 1;
  FWT(f, l, m, op), FWT(f, m, r, op);
for (int i = l, j = m; i < m; i++, j++)</pre>
    op(f[i], f[j]);
void iFWT(vector<int> &f, int 1, int r, auto &op) {
  if (r - l == 1) return;
  int m = l + r >> 1;
  for (int i = l, j = m; i < m; i++, j++)
    op(f[i], f[j]);
  iFWT(f, l, m, op), iFWT(f, m, r, op);
vector<int> BitConv(int n, vector<int> f, vector<int> g
    , const auto &op, const auto &iop) {
  const int N = 1 \ll n;
  FWT(f, 0, N, op);
FWT(g, 0, N, op);
for (int i = 0; i < N; i++)</pre>
    f[i] = mul(f[i], g[i]);
  iFWT(f, 0, N, iop);
  return f;
6.9 Lucas
// C(N, M) mod D
i64 Lucas(i64 N, i64 M, i64 D) {
  auto Factor = [&](i64 x) -> vector<pair<i64, i64>> {
    vector<pair<i64, i64>> r;
    for (i64 i = 2; x > 1; i++)
```

```
if (x \% i == 0) {
      i64 c = 0;
      while (x \% i == 0) x /= i, c++;
      r.emplace_back(i, c);
    }
  return r;
};
auto Pow = [\&](i64 a, i64 b, i64 m) -> i64 {
  for (; b; b >>= 1, a = a * a % m)
    if (b & 1) r = r * a % m;
  return r;
}:
vector<pair<i64, i64>> E;
for (auto [p, q] : Factor(D)) {
  const i64 \text{ mod} = Pow(p, q, 1 << 30);
  auto CountFact = [\&](i64 x) \rightarrow i64 \{
    i64 c = 0;
    while (x) c += (x \neq p);
    return c;
  };
  auto CountBino = [&](i64 x, i64 y) { return
  CountFact(x) - CountFact(y) - CountFact(x - y); };
  auto Inv = [&](i64 x) -> i64 { return (exgcd(x, mod
).ff % mod + mod) % mod; };
  vector<i64> pre(mod + 1);
  pre[0] = pre[1] = 1;
  for (i64 i = 2; i \leftarrow mod; i++) pre[i] = (i % p == 0
   ? 1 : i) * pre[i - 1] % mod;
  function < i64(i64) > FactMod = [&](i64 n) -> i64 {
    if (n == 0) return 1;
    return FactMod(n / p) * Pow(pre[mod], n / mod,
  mod) % mod * pre[n % mod] % mod;
  auto BinoMod = [\&](i64 x, i64 y) \rightarrow i64 \{
    return FactMod(x) * Inv(FactMod(y)) % mod * Inv(
  FactMod(x - y)) \% mod;
  i64 r = BinoMod(N, M) * Pow(p, CountBino(N, M), mod
  ) % mod:
  E.emplace_back(r, mod);
};
return CRT(E);
```

#### 6.10 Berlekamp Massey

```
|template <int P>
```

```
vector<int> BerlekampMassey(vector<int> x) {
 vector<int> cur, ls;
 int lf = 0, ld = 0;
 for (int i = 0; i < (int)x.size(); ++i) {</pre>
  int t = 0;
  for (int j = 0; j < (int)cur.size(); ++j)
  (t += 1LL * cur[j] * x[i - j - 1] % P) %= P;</pre>
  if (t == x[i]) continue;
  if (cur.empty()) {
   cur.resize(i + 1);
   lf = i, ld = (t + P - x[i]) \% P;
  int k = 1LL * fpow(ld, P - 2, P) * (t + P - x[i]) % P
  vector<int> c(i - lf - 1);
  c.push_back(k);
for (int j = 0; j < (int)ls.size(); ++j)
  c.push_back(1LL * k * (P - ls[j]) % P);</pre>
  if (c.size() < cur.size()) c.resize(cur.size());</pre>
  for (int j = 0; j < (int)cur.size(); ++j)</pre>
  c[j] = (c[j] + cur[j]) % P;
if (i - lf + (int)ls.size() >= (int)cur.size()) {
   ls = cur, lf = i;
   ld = (t + P - x[i]) \% P;
  cur = c;
 return cur:
```

#### 6.11 Gauss Elimination

```
double Gauss(vector<vector<double>> &d) {
 int n = d.size(), m = d[0].size();
 double det = 1;
 for (int i = 0; i < m; ++i) {
  int p = -1;
  for (int j = i; j < n; ++j) {
   if (fabs(d[j][i]) < kEps) continue;
   if (p == -1 || fabs(d[j][i]) > fabs(d[p][i])) p = j;
  if (p == -1) continue;
  if (p != i) det *= -1;
  for (int j = 0; j < m; ++j) swap(d[p][j], d[i][j]);
  for (int j = 0; j < n; ++j) {
    if (i == j) continue;
   double z = d[j][i] / d[i][i];
   for (int k = 0; k < m; ++k) d[j][k] -= z * d[i][k];
 for (int i = 0; i < n; ++i) det *= d[i][i];</pre>
 return det;
```

#### 6.12 Linear Equation

```
void linear_equation(vector<vector<double>> &d, vector<</pre>
     double> &aug, vector<double> &sol) {
  int n = d.size(), m = d[0].size();
  vector<int> r(n), c(m);
  iota(r.begin(), r.end(), 0);
  iota(c.begin(), c.end(), 0);
for (int i = 0; i < m; ++i) {</pre>
    int p = -1, z = -1;
    for (int j = i; j < n; ++j) {
  for (int k = i; k < m; ++k) {
         if (fabs(d[r[j]][c[k]]) < eps) continue;</pre>
         if (p == -1 \mid | fabs(d[r[j]][c[k]]) > fabs(d[r[p
     ]][c[z]])) p = j, z = k;
      }
    if (p == -1) continue;
    swap(r[p], r[i]), swap(c[z], c[i]);
     for (int j = 0; j < n; ++j) {
       if (i == j) continue
       double z = d[r[j]][c[i]] / d[r[i]][c[i]]
       for (int k = 0; k < m; ++k) d[r[j]][c[k]] -= z *
    d[r[i]][c[k]];
      aug[r[j]] -= z * aug[r[i]];
  vector<vector<double>> fd(n, vector<double>(m));
  vector<double> faug(n), x(n);
```

```
for (int i = 0; i < n; ++i) {
  for (int j = 0; j < m; ++j) fd[i][j] = d[r[i]][c[j]
  faug[i] = aug[r[i]];
d = fd, aug = faug;
for (int i = n - 1; i >= 0; --i) {
  double p = 0.0;
  for (int j = i + 1; j < n; ++j) p += d[i][j] * x[j]
  x[i] = (aug[i] - p) / d[i][i];
for (int i = 0; i < n; ++i) sol[c[i]] = x[i];
```

#### 6.13 LinearRec

```
template <int P>
int LinearRec(const vector<int> &s, const vector<int> &
    coeff, int k) {
  int n = s.size()
  auto Combine = [&](const auto &a, const auto &b) {
    vector<int> res(n * 2 + 1);
    for (int i = 0; i <= n; ++i) {
      for (int j = 0; j <= n; ++j)
(res[i + j] += 1LL * a[i] * b[j] % P) %= P;
    for (int i = 2 * n; i > n; --i) {
      for (int j = 0; j < n; ++j)
(res[i - 1 - j] += 1LL * res[i] * coeff[j] % P)
    res.resize(n + 1);
    return res;
 vector<int> p(n + 1), e(n + 1);
 p[0] = e[1] = 1;
  for (; k > 0; k >>= 1) {
    if (k \& 1) p = Combine(p, e);
    e = Combine(e, e);
  int res = 0;
  for (int i = 0; i < n; ++i) (res += 1LL * p[i + 1] *
    s[i] % P) %= P;
  return res;
```

#### SubsetConv

```
vector<int> SubsetConv(int n, const vector<int> &f,
    const vector<int> &g) {
 const int m = 1 \ll n;
vector<vector<int>> a(n + 1, vector<int>(m)), b(n + 1,
     vector<int>(m));
for (int i = 0; i < m; ++i) {
 a[__builtin_popcount(i)][i] = g[i];
for (int i = 0; i <= n; ++i) {
  for (int j = 0; j < n; ++j) {</pre>
   for (int s = 0; s < m; ++s) {
    if (s >> j & 1) {
  a[i][s] += a[i][s ^ (1 << j)];</pre>
     b[i][s] += b[i][s \wedge (1 << j)];
   }
  }
 vector<vector<int>>> c(n + 1, vector<int>(m));
for (int s = 0; s < m; ++s) {
  for (int i = 0; i <= n; ++i) {
   for (int j = 0; j \le i; ++j) c[i][s] += a[j][s] * b[
    i - j][s];
 for (int i = 0; i <= n; ++i) {
  for (int j = 0; j < n; ++j) {
for (int s = 0; s < m; ++s) {
    if (s >> j & 1) c[i][s] -= c[i][s ^ (1 << j)];</pre>
   }
vector<int> res(m);
```

```
for (int i = 0; i < m; ++i) res[i] = c[
     _builtin_popcount(i)][i];
return res;
6.15 SqrtMod
 if (P == 2 or n == 0) return n;
 auto check = [&](int x) {
```

```
int get_root(int n, int P) { // ensure 0 <= n < p</pre>
 return modpow(x, (P - 1) / 2, P); }; if (check(n) != 1) return -1; mt19937 rnd(7122); lld z = 0, w;
 while (check(w = (z * z - n + P) \% P) != P - 1)
  z = rnd() \% P;
 const auto M = [P, w](auto &u, auto &v) {
  auto [a, b] = u; auto [c, d] = v;
  return make_pair((a * c + b * d % P * w) % P,
      (a * d + b * c) % P);
 pair<lld, lld> r(1, 0), e(z, 1);
for (int w = (P + 1) / 2; w; w >>= 1, e = M(e, e))
  if (w \& 1) r = M(r, e);
 return r.first; // sqrt(n) mod P where P is prime
```

#### 6.16 FloorSum

```
// sigma 0 \sim n-1: (a * i + b) / m
i64 floor_sum(i64 n, i64 m, i64 a, i64 b) {
  u64 \text{ ans} = 0;
  if (a < 0) {
    u64 a2 = (a \% m + m) \% m;
    ans -= 1ULL * n * (n - 1) / 2 * ((a2 - a) / m);
    a = a2;
  if (b < 0) 
    u64 b2 = (b \% m + m) \% m;
    ans -= 1ULL * n * ((b2 - b) / m);
    b = b2;
  while (true) {
    if (a >= m) {
      ans += n * (n - 1) / 2 * (a / m);
       a \% = m:
    if (b >= m) {
  ans += n * (b / m);
       b \% = m;
    u64 y_max = a * n + b;
    if (y_max < m) break;</pre>
    n = y_max / m;
    b = y_max \% m;
    swap(m, a);
  return ans;
}
```

#### 7 Geometry

#### 2D Point

```
using Pt = pair<double, double>;
using numbers::pi;
constexpr double eps = 1e-9;
Pt operator+(Pt a, Pt b) { return {a.ff + b.ff, a.ss +
    b.ss}; }
Pt operator-(Pt a, Pt b) { return {a.ff - b.ff, a.ss -
    b.ss}; }
Pt operator*(Pt a, double b) { return {a.ff * b, a.ss *
     b}; }
Pt operator/(Pt a, double b) { return {a.ff / b, a.ss /
     b}; }
double operator*(Pt a, Pt b) { return a.ff * b.ff + a.
    ss * b.ss; }
double operator^(Pt a, Pt b) { return a.ff * b.ss - a.
    ss * b.ff; }
double abs(Pt a) { return sqrt(a * a); }
double cro(Pt a, Pt b, Pt c) { return (b - a) ^ (c - a)
int sig(double x) { return (x > -eps) - (x < eps); }</pre>
Pt rot(Pt u, double a) {
 Pt v{sin(a), cos(a)};
```

```
return {u ^ v, u * v};
}
Pt Inter(Pt a, Pt b, Pt c, Pt d) {
   double s = cro(c, d, a), t = -cro(c, d, b);
   return (a * t + b * s) / (s + t);
}
struct Line {
   Pt a{}, b{};
   Line() {}
   Line(Pt _a, Pt _b) : a{_a}, b{_b} {}
};
Pt Inter(Line L, Line R) {
   return Inter(L.a, L.b, R.a, R.b);
}
```

#### 7.2 Convex Hull

#### 7.3 Convex Hull trick

# 7.4 Dynamic Convex Hull

```
template<class T, class Comp = less<T>>
struct DynamicHull {
  set<T, Comp> H;
  DynamicHull() {}
void insert(T p) {
    if (inside(p)) return;
    auto it = H.insert(p).ff;
while (it != H.begin() and prev(it) != H.begin() \
         and cross(*prev(it, 2), *prev(it), *it) <= 0) {</pre>
       it = H.erase(--it);
    while (it != --H.end() and next(it) != --H.end()
         and cross(*it, *next(it), *next(it, 2)) <= 0) {</pre>
       it = --H.erase(++it);
    }
  bool inside(T p) {
    auto it = H.lower_bound(p);
    if (it == H.end()) return false;
        (it == H.begin()) return p == *it;
     return cross(*prev(it), p, *it) <= 0;
};
```

# 7.5 Half Plane Intersection

```
vector<Pt> HPI(vector<Line> P) {
  const int n = P.size();
  sort(all(P), [\&](Line L, Line R) \rightarrow bool {
    Pt u = L.b - L.a, v = R.b - R.a;
    bool f = Pt(sig(u.ff), sig(u.ss)) < Pt{};</pre>
    bool g = Pt(sig(v.ff), sig(v.ss)) < Pt{};</pre>
    if (f != g) return f < g;</pre>
    return (sig(u ^ v) ? sig(u ^ v) : sig(cro(L.a, R.a,
     R.b))) > 0;
  auto Same = [&](Line L, Line R) {
  Pt u = L.b - L.a, v = R.b - R.a;
    return sig(u \wedge v) == 0 and sig(u * v) == 1;
  deaue <Pt> inter:
  deque <Line> seg;
  for (int i = 0; i < n; i++) if (i == 0 or !Same(P[i - 1], P[i])) {
    while (seg.size() >= 2 and sig(cro(inter.back(), P[
    i].b, P[i].a)) == 1) {
      seg.pop_back(), inter.pop_back();
    while (seg.size() >= 2 and sig(cro(inter[0], P[i].b
     , P[i].a)) == 1) {
      seg.pop_front(), inter.pop_front();
    if (!seg.empty()) inter.push_back(Inter(seg.back(),
     P[i]));
    seg.push_back(P[i]);
  while (seg.size() >= 2 and sig(cro(inter.back(), seg
    [0].b, seg[0].a) == 1) {
    seg.pop_back(), inter.pop_back();
  inter.push_back(Inter(seg[0], seg.back()));
  return vector<Pt>(all(inter));
```

#### 7.6 Minimal Enclosing Circle

```
using circle = pair<Pt, double>;
struct MES {
   MES() {}
   bool inside(const circle &c, Pt p) {
      return abs(p - c.ff) <= c.ss + eps;</pre>
   circle get_cir(Pt a, Pt b) {
      return circle((a + b) / 2., abs(a - b) / 2.);
   circle get_cir(Pt a, Pt b, Pt c) {
      Pt p = (b - a) / 2.;
      p = Pt(-p.ss, p.ff);
double t = ((c - a) * (c - b)) / (2 * (p * (c - a))
      p = ((a + b) / 2.) + (p * t);
      return circle(p, abs(p - a));
   circle get_mes(vector<Pt> P) {
      if (P.empty()) return circle{Pt(0, 0), 0};
      mt19937 rng(random_device{}());
      shuffle(all(P), rng);
      circle ({P[0], 0};
for (int i = 1; i < P.size(); i++) {
   if (inside(C, P[i])) continue;
   C = get_cir(P[i], P[0]);
   for (int i = 1: i < i: i++) {</pre>
         for (int j = 1; j < i; j++) {
  if (inside(C, P[j])) continue;</pre>
           C = get_cir(P[i], P[j]);
for (int k = 0; k < j; k++) {</pre>
              if (inside(C, P[k])) continue;
              C = get_cir(P[i], P[j], P[k]);
        }
      return C;
};
```

#### 7.7 Minkowski

```
vector<Pt> Minkowski(vector<Pt> P, vector<Pt> Q) {
  auto reorder = [&](auto &R) -> void {
```

```
auto cmp = [&](Pt a, Pt b) -> bool {
    return Pt(a.ss, a.ff) < Pt(b.ss, b.ff);
};
rotate(R.begin(), min_element(all(R), cmp), R.end()
);
R.push_back(R[0]), R.push_back(R[1]);
};
const int n = P.size(), m = Q.size();
reorder(P), reorder(Q);
vector<Pt> R;
for (int i = 0, j = 0, s; i < n or j < m; ) {
    R.push_back(P[i] + Q[j]);
    s = sig((P[i + 1] - P[i]) ^ (Q[j + 1] - Q[j]));
    i += (s >= 0), j += (s <= 0);
}
return R;
}</pre>
```

### 7.8 TriangleCenter

```
Pt TriangleCircumCenter(Pt a, Pt b, Pt c) {
    Pt res;
    double a1 = atan2(b.y - a.y, b.x - a.x) + pi / 2;
    double a2 = atan2(c.y - b.y, c.x - b.x) + pi / 2;
double ax = (a.x + b.x) / 2;
    double ay = (a.y + b.y) / 2;
    double bx = (c.x + b.x) / 2;
    double by = (c.y + b.y) / 2;
double r1 = (\sin(a2) * (ax - bx) + \cos(a2) * (by - ay)
                 ) / (sin(a1) * cos(a2) - sin(a2) * cos(a1));
    return Pt(ax + r1 * cos(a1), ay + r1 * sin(a1));
 Pt TriangleMassCenter(Pt a, Pt b, Pt c) {
   return (a + b + c) / 3.0;
Pt TriangleOrthoCenter(Pt a, Pt b, Pt c) {
  return TriangleMassCenter(a, b, c) * 3.0 -
  TriangleCircumCenter(a, b, c) * 2.0;
 Pt TriangleInnerCenter(Pt a, Pt b, Pt c) {
   Pt res;
double la = abs(b - c);
    double lb = abs(a - c);
    double lc = abs(a - b);

res.x = (la * a.x + lb * b.x + lc * c.x) / (la + lb + b.x + lc * c.x) / (la + lb + b.x + lc * c.x) / (la + lb + b.x + lc * c.x) / (la + lb + b.x + lc * c.x) / (la + lb + b.x + lc * c.x) / (la + lb + b.x + lc * c.x) / (la + lb + b.x + lc * c.x) / (la + lb + b.x + lc * c.x) / (la + lb + b.x + lc * c.x) / (la + lb + b.x + lc * c.x) / (la + lb + b.x + lc * c.x) / (la + lb + b.x + lc * c.x) / (la + lb + b.x + lc * c.x) / (la + lb + b.x + lc * c.x) / (la + lb + b.x + lc * c.x) / (la + lb + b.x + lc * c.x) / (la + lb + b.x + lc * c.x) / (la + lb + b.x + lc * c.x) / (la + lb + b.x + lc * c.x) / (la + lb + b.x + lc * c.x) / (la + lb + b.x + lc * c.x) / (la + lb + b.x 
                lc);
    res.y = (la * a.y + lb * b.y + lc * c.y) / (la + lb +
                 lc);
    return res;
}
```

# 8 Stringology

# 8.1 KMP

```
vector<int> build_fail(string s) {
  const int len = s.size();
  vector<int> f(len, -1);
  for (int i = 1, p = -1; i < len; i++) {
    while (~p and s[p + 1] != s[i]) p = f[p];
    if (s[p + 1] == s[i]) p++;
    f[i] = p;
  }
  return f;
}</pre>
```

#### 8.2 Z-algorithm

```
vector<int> zalgo(string s) {
   if (s.empty()) return {};
   int len = s.size();
   vector<int> z(len);
   z[0] = len;
   for (int i = 1, l = 1, r = 1; i < len; i++) {
      z[i] = i < r ? min(z[i - l], r - i) : 0;
      while (i + z[i] < len and s[i + z[i]] == s[z[i]]) z
      [i]++;
      if (i + z[i] > r) l = i, r = i + z[i];
   }
   return z;
}
```

### 8.3 Manacher

```
vector<int> manacher(const string &s) {
    string p = "@#";
    for (char c : s) p += c + '#';
    p += '$';
    vector<int> dp(p.size());
    int mid = 0, r = 1;
    for (int i = 1; i < p.size() - 1; i++) {
        auto &k = dp[i];
        k = i < mid + r ? min(dp[mid * 2 - i], mid + r - i)
            : 0;
        while (p[i + k + 1] == p[i - k - 1]) k++;
        if (i + k > mid + r) mid = i, r = k;
    }
    return vector<int>(dp.begin() + 2, dp.end() - 2);
}
```

```
8.4 SuffixArray
namespace sfx {
#define fup(a, b) for (int i = a; i < b; i++)
#define fdn(a, b) for (int i = b - 1; i >= a; i--)
  constexpr int N = 5e5 + 5;
bool _t[N * 2];
  int H[N], RA[N], x[N], _p[N];
int SA[N * 2], _s[N * 2], _c[N * 2], _q[N * 2];
void pre(int *sa, int *c, int n, int z) {
     fill_n(sa, n, 0), copy_n(c, z, x);
  void induce(int *sa, int *c, int *s, bool *t, int n,
     int z) {
     copy_n(c, z - 1, x + 1);
fup(0, n) if (sa[i] and !t[sa[i] - 1])
       sa[x[s[sa[i] - 1]] ++] = sa[i] - 1;
     copy_n(c, z, x);
fdn(0, n) if (sa[i] and t[sa[i] - 1])
        sa[--x[s[sa[i] - 1]]] = sa[i] - 1;
  void sais(int *s, int *sa, int *p, int *q, bool *t,
  int *c, int n, int z) {
     bool uniq = t[n - 1] = true;
     int nn = 0, nmxz = -1, *nsa = sa + n, *ns = s + n,
     last = -1;
     fill_n(c, z, 0);
fup(0, n) uniq &= ++c[s[i]] < 2;
     partial_sum(c, c + z, c);
     if (uniq) { fup(0, n) sa[--c[s[i]]] = i; return; }
fdn(0, n - 1)
        t[i] = (s[i] == s[i + 1] ? t[i + 1] : s[i] < s[i]
     + 1]);
     pre(sa, c, n, z);
fup(1, n) if (t[i] and !t[i - 1])
    sa[--x[s[i]]] = p[q[i] = nn++] = i;
induce(sa, c, s, t, n, z);
fup(0, n) if (sa[i] and t[sa[i]] and !t[sa[i] - 1])
       bool neq = last < 0 or !equal(s + sa[i], s + p[q[
     sa[i]] + 1], s + last);
       ns[q[last = sa[i]]] = nmxz += neq;
     sais(ns, nsa, p + nn, q + n, t + n, c + z, nn, nmxz
      + 1);
     pre(sa, c, n, z);
     fdn(0, nn) sa[--x[s[p[nsa[i]]]] = p[nsa[i]];
     induce(sa, c, s, t, n, z);
  vector<int> build(vector<int> s, int n) {
  copy_n(begin(s), n, _s), _s[n] = 0;
  coic(s, sh n, _s), _s[n] = 1;
}
     sais(_s, SA, _p, _q, _t, _c, n + 1, 256);
vector<int> sa(n);
     fup(0, n) sa[i] = SA[i + 1];
     return sa;
  vector<int> lcp_array(vector<int> &s, vector<int> &sa
     int n = int(s.size());
     vector<int> rnk(n)
     fup(0, n) rnk[sa[i]] = i;
```

vector<int> lcp(n - 1);

if (h > 0) h--;

int h = 0;

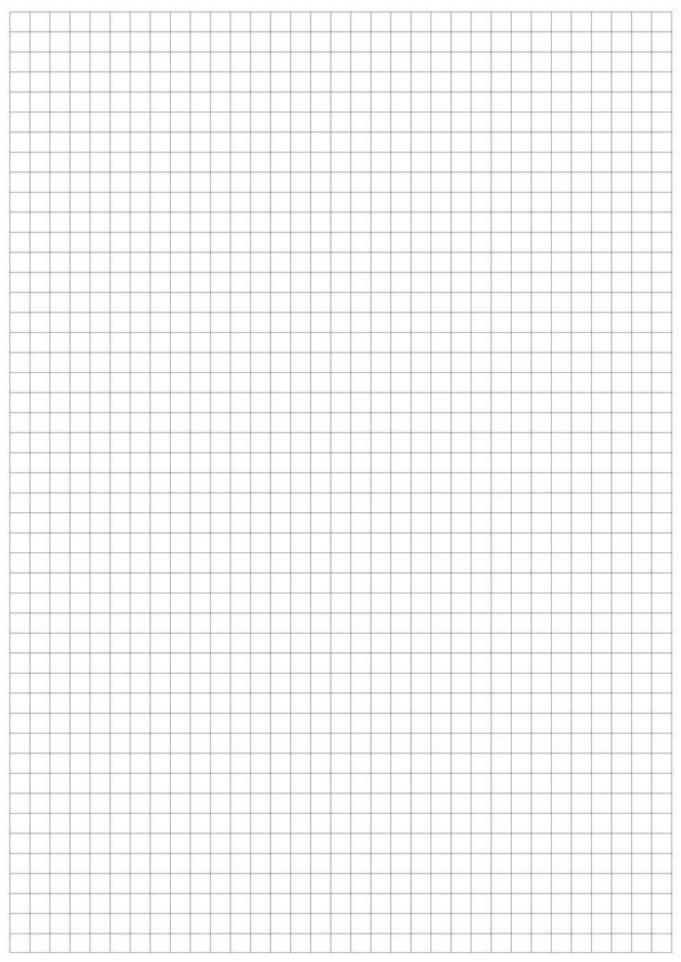
 $fup(0, n) {$ 

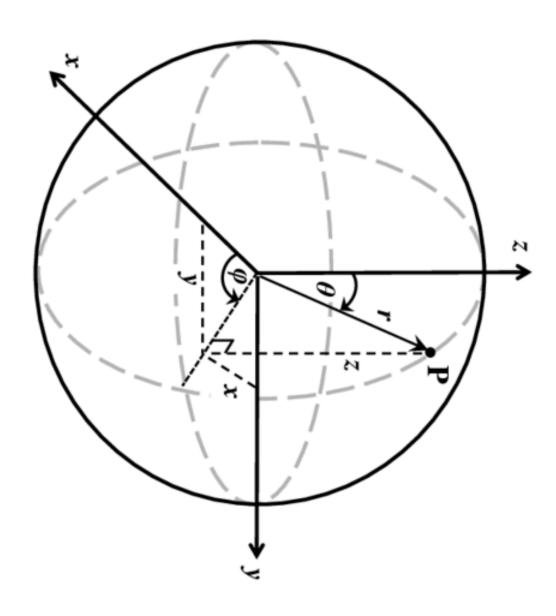
```
if (rnk[i] == 0) continue;
                                                                   |}
       int j = sa[rnk[i] - 1];
for (; j + h < n and i + h < n; h++)
  if (s[j + h] != s[i + h]) break;</pre>
                                                                    8.6 PalindromicTree
       lcp[rnk[i] - 1] = h;
                                                                    struct PAM {
                                                                       struct Node {
     return lcp;
                                                                         int fail, len, dep;
  }
                                                                         array<int, 26> ch;
Node(int _len) : len{_len}, fail{}, ch{}, dep{} {};
}
8.5
      SimpleSuffixArray
                                                                       vector<Node> g;
namespace sfx {
                                                                       vector<int> id:
#define fup(a, b) for (int i = a; i < b; i++)
#define fdn(a, b) for (int i = b - 1; i >= a; i--)
                                                                       int odd, even, lst;
                                                                       string S;
  constexpr int N = 5e5 + 5;
                                                                       int new_node(int len) {
  bool _t[N * 2]
                                                                         g.emplace_back(len);
  int H[N], RA[N], x[N], _p[N];
int SA[N * 2], _s[N * 2], _c[N * 2], _q[N * 2];
void pre(int *sa, int *c, int n, int z) {
                                                                         return g.size() - 1;
                                                                       PAM() : odd(new_node(-1)), even(new_node(0)) {
    fill_n(sa, n, \emptyset), copy_n(c, z, x);
                                                                         lst = g[even].fail = odd;
  void induce(int *sa, int *c, int *s, bool *t, int n,
                                                                       int up(int p) {
     int z) {
                                                                         while (S.rbegin()[g[p].len + 1] != S.back())
     copy_n(c, z - 1, x + 1);
fup(0, n) if (sa[i] and !t[sa[i] - 1])
                                                                           p = g[p].fail;
                                                                         return p;
       sa[x[s[sa[i] - 1]]++] = sa[i] - 1;
     copy_n(c, z, x);
fdn(0, n) if (sa[i] and t[sa[i] - 1])
                                                                       int add(char c) {
                                                                         S += c;
       sa[--x[s[sa[i] - 1]]] = sa[i] - 1;
                                                                         lst = up(lst);
c -= 'a';
  void sais(int *s, int *sa, int *p, int *q, bool *t,
                                                                         if (!g[lst].ch[c]) g[lst].ch[c] = new_node(g[lst]).
     int *c, int n, int z) {
                                                                          len + 2);
     bool uniq = t[n - 1] = true;
                                                                         int p = g[lst].ch[c];

g[p].fail = (lst == odd ? even : g[up(g[lst].fail)]
     int nn = 0, nmxz = -1, *nsa = sa + n, *ns = s + n,
     last = -1;
                                                                          ].ch[c]);
     fill_n(c, z, 0);
fup(0, n) uniq &= ++c[s[i]] < 2;
                                                                         lst = p;
                                                                         g[lst].dep = g[g[lst].fail].dep + 1;
     partial_sum(c, c + z, c);
                                                                         id.push_back(lst);
     if (uniq) { fup(0, n) sa[--c[s[i]]] = i; return; }
                                                                         return lst;
     fdn(0, n - 1)
       t[i] = (s[i] == s[i + 1] ? t[i + 1] : s[i] < s[i]
                                                                       void del() {
     + 1]);
                                                                         S.pop_back()
     pre(sa, c, n, z);
fup(1, n) if (t[i] and !t[i - 1])
                                                                         id.pop_back();
                                                                         lst = id.empty() ? odd : id.back();
       sa[--x[s[i]]] = p[q[i] = nn++] = i;
     induce(sa, c, s, t, n, z);
fup(0, n) if (sa[i] and t[sa[i]] and !t[sa[i] - 1])
                                                                    };
                                                                    8.7 SmallestRotation
       bool neq = last < 0 or !equal(s + sa[i], s + p[q[
     sa[i]] + i], s + last);
                                                                    string Rotate(const string &s) {
       ns[q[last = sa[i]]] = nmxz += neq;
                                                                      int n = s.length();
                                                                      string t = s + s;
     sais(ns, nsa, p + nn, q + n, t + n, c + z, nn, nmxz
                                                                      int i = 0, j = 1;
      + 1);
                                                                      while (i < n && j < n) {
     pre(sa, c, n, z);
fdn(0, nn) sa[--x[s[p[nsa[i]]]]] = p[nsa[i]];
                                                                       int k = 0;
                                                                       while (k < n \& t[i + k] == t[j + k]) ++k;
     induce(sa, c, s, t, n, z);
                                                                       if (t[i + k] \leftarrow t[j + k]) j += k + 1;
                                                                       else i += k + 1;
  vector<int> build(vector<int> s, int n) {
                                                                       if (i == j) ++ j;
     copy_n(begin(s), n, _s), _s[n] = 0;
     sais(_s, SA, _p, _q, _t, _c, n + 1, 256);
vector<int> sa(n);
                                                                      int pos = (i < n ? i : j);</pre>
                                                                      return t.substr(pos, n);
     fup(0, n) sa[i] = SA[i + 1];
     return sa;
  vector<int> lcp_array(vector<int> &s, vector<int> &sa
                                                                    9
                                                                          Misc
     int n = int(s.size());
                                                                     9.1 HilbertCurve
     vector<int> rnk(n)
                                                                    long long hilbert(int n, int x, int y) {
     fup(0, n) rnk[sa[i]] = i;
                                                                      long long res = 0;
     vector<int> lcp(n - 1);
                                                                      for (int s = n / 2; s; s >>= 1) {
     int h = 0;
                                                                       int rx = (x \& s) > 0;
     fup(0, n) {
                                                                       int ry = (y & s) > 0;
res += s * 1ll * s * ((3 * rx) ^ ry);
       if (h > 0) h--;
       if (rnk[i] == 0) continue;
                                                                       if (ry == 0) {
       int j = sa[rnk[i] - 1];
for (; j + h < n and i + h < n; h++)
  if (s[j + h] != s[i + h]) break;</pre>
                                                                        if (rx == 1) x = s - 1 - x, y = s - 1 - y;
                                                                        swap(x, y);
       lcp[rnk[i] - 1] = h;
                                                                      return res;
     return lcp;
                                                                    }
```

```
National Central University - __builtin_orz()
9.2 DLX
namespace dlx {
int lt[maxn], rg[maxn], up[maxn], dn[maxn], cl[maxn],
     rw[maxn], bt[maxn], s[maxn], head, sz, ans;
void init(int c) {
  for (int i = 0; i < c; ++i) {</pre>
  up[i] = dn[i] = bt[i] = i;
lt[i] = i == 0 ? c : i - 1;
  rg[i] = i == c - 1 ? c : i' + 1;
  s[i] = 0;
 rg[c] = 0, lt[c] = c - 1;
 up[c] = dn[c] = -1;
 head = c, sz = c + 1;
void insert(int r, const vector<int> &col) {
 if (col.empty()) return;
 int f = sz;
for (int i = 0; i < (int)col.size(); ++i) {</pre>
  int c = col[i], v = sz++;
  dn[bt[c]] = v;
  up[v] = bt[c], bt[c] = v;
  rg[v] = (i + 1 == (int)col.size() ? f : v + 1);
  rw[v] = r, cl[v] = c;
  ++s[c];
  if (i > 0) lt[v] = v - 1;
 lt[f] = sz - 1;
void remove(int_c) {
 lt[rg[c]] = lt[c], rg[lt[c]] = rg[c];
for (int i = dn[c]; i != c; i = dn[i]) {
    for (int j = rg[i]; j != i; j = rg[j])
    refdr[i]    ref[i];    for (int j = rg[j])
    up[dn[j]] = up[j], dn[up[j]] = dn[j], --s[cl[j]];
void restore(int c) {
  for (int i = up[c]; i != c; i = up[i]) {
    for (int j = lt[i]; j != i; j = lt[j])
    ++s[cl[j]], up[dn[j]] = j, dn[up[j]] = j;
 lt[rg[c]] = c, rg[lt[c]] = c;
// Call dlx::make after inserting all rows.
void make(int c) {
  for (int i = 0; i < c; ++i)
   dn[bt[i]] = i, up[i] = bt[i];</pre>
void dfs(int dep) {
 if (dep >= ans) return;
 if (rg[head] == head) return ans = dep, void();
 if (dn[rg[head]] == rg[head]) return;
 int c = rg[head];
 int w = c:
 for (int x = c; x != head; x = rg[x]) if (s[x] < s[w])
 remove(w):
 for (int i = dn[w]; i != w; i = dn[i]) {
  for (int j = rg[i]; j != i; j = rg[j]) remove(cl[j]);
  dfs(dep + 1);
  for (int j = lt[i]; j != i; j = lt[j]) restore(cl[j])
 restore(w);
int solve() {
 ans = 1e9, dfs(0);
 return ans;
9.3 NextPerm
i64 next_perm(i64 x) {
  i64 y = x | (x - 1);
  return (y + 1) | (((~y & -~y) - 1) >> (__builtin_ctz(
     x) + 1));
}
9.4 FastIO
struct FastI0 {
   const static int ibufsiz = 4<<20, obufsiz = 18<<20;
   char ibuf[ibufsiz], *ipos = ibuf, obuf[obufsiz],
     opos = obuf;
```

```
FastIO() { fread(ibuf, 1, ibufsiz, stdin); }
~FastIO() { fwrite(obuf, 1, opos - obuf, stdout); }
   template<class T> FastIO& operator>>(T &x) {
     bool sign = 0; while (!isdigit(*ipos)) { if (*ipos
     == '-') sign = 1; ++ipos; }
     x = *ipos++ & 15;
     while (isdigit(*ipos)) x = x * 10 + (*ipos++ & 15);
     if (sign) x = -x;
     return *this;
   template<class T> FastIO& operator<<(T n) {</pre>
     static char _buf[18];
     char* _pos = _buf;
     if (n < 0) *opos++ = '-'
                                  n = -n;
     do *_pos++ = '0' + n % 10; while (n /= 10);
     while (_pos != _buf) *opos++ = *--_pos;
return *this;
   FastIO& operator<<(char ch) { *opos++ = ch; return *
     this: }
} FIO;
#define cin FIO
#define cout FIO
      Python FastIO
import sys
sys.stdin.readline()
sys.stdout.write()
9.6 trick
dp[61][0][0][0][7] = 1;
for (int h = 60; h >= 0; h--) {
  int s = (n >> h & 1) * 7;
   for (int x = 0; x < 8; x++) if (__builtin_parity(x)
      == 0) {
     for (int y = 0; y < 8; y++)
       if (((y \& \sim s) \& x) = 0) {
          for (int a = 0; a < A[0]; a++)
            for (int b = 0; b < A[1]; b++)
              for (int c = 0; c < A[2]; c++)
                 if (dp[h + 1][a][b][c][y] == 0) continue;
                 i64 i = ((x >> 2 \& 1LL) << h) % A[0];
                 i64 j = ((x >> 1 \& 1LL) << h) % A[1];
                 i64 k = ((x >> 0 & 1LL) << h) % A[2];
                 auto &val =
                 dp[h][(i + a) % A[0]][(j + b) % A[1]][(k
     + c) % A[2]][y & \sim(s ^ x)];
                val = add(val, dp[h + 1][a][b][c][y]);
       }
   }
pair<i64, i64> Split(i64 x) {
   if (x == 1) return \{0, 0\};
   i64 h = __lg(x);
   i64 fill = (1LL << (h + 1)) - 1;
   i64 l = (1LL \ll h) - 1 - max(0LL, fill - x - (1LL \ll h))
     (h - 1)));
   i64 r = x - 1 - l;
return {l, r};
   auto [ls, l] = DP(lo);
auto [rs, r] = DP(hi);
   if (r < K) {
     cout << "Impossible\n";</pre>
     return;
   if (l == K) cout << ls << '\n';
else if (r == K) cout << rs << '\n';</pre>
     cout << (ls * (r - K) + rs * (K - l)) / (r - l) <<
      \n';
}
```





$$\varphi = tan^{-1}(y/x)$$

 $\theta = \cos^{-1}(z/r)$ 

$$r = \sqrt{x^2 + y^2 + z^2}$$

$$y = r \sin \theta \sin \phi$$
  
 $z = r \cos \theta$ 

 $x = r \sin \theta \cos \phi$