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```

Basic

1.1 vimrc

```
set ts=4 sw=4 nu rnu et hls mouse=a
filetype indent on
sy on
inoremap jk <Esc>
inoremap {<CR> {<CR>}<C-o>0
nnoremap J 5j
nnoremap K 5k
nnoremap <F1> :w<bar>!g++ '%' -o run -std=c++20 -DLOCAL
      -Wfatal-errors -fsanitize=address,undefined -g -02
     && echo done. && time ./run<CR>
```

1.2 default

```
#include <bits/stdc++.h>
using namespace std;
#ifdef LOCAL
template<class... T> void dbg(T... x) { char e{}; ((
    cerr << e << x, e = ' '), ...); }
template<class T> void org(T l, T r) { while (l != r)
    cerr << ' ' << *l++; cerr << '\n'; }
#define debug(x...) dbg(#x, '=', x, '\n')
#define orang(x...) dbg(#x, '='), org(x)
#also</pre>
#else
#pragma GCC optimize("03,unroll-loops")
#pragma GCC target("avx2,bmi,bmi2,lzcnt,popcnt")
#define debug(...) ((void)0)
#define orange(...) ((void)0)
#endif
#define ff first
#define ss second
#define all(v) (v).begin(), (v).end()
#define rall(v) (v).rbegin(), (v).rend()
template<class T> bool chmin(T &a, T b) { return b < a}</pre>
and (a = b, true); }
template<class T> bool chmax(T &a, T b) { return a < b</pre>
        and (a = b, true); }
```

1.3 judge

```
set -e
g++ -03 a.cpp -o a
g++ -03 ac.cpp -o c
g++ -03 gen.cpp -o g
for ((i=0;;i++))
  echo "case $i"
  ./g > inp
  time ./a < inp > wa.out
  time ./c < inp > ac.out
  diff ac.out wa.out || break
```

1.4 Random

```
mt19937 rng(random_device{}());
i64 \text{ rand}(i64 \text{ l} = -\text{lim}, i64 \text{ r} = \text{lim})  {
  return uniform_int_distribution<i64>(l, r)(rng);
double randr(double l, double r) {
  return uniform_real_distribution<double>(l, r)(rng);
```

1.5 Increase stack size

|ulimit -s

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2 Matching and Flow

2.1 Dinic

```
template<class Cap>
struct Dinic {
  struct Edge { int v; Cap w; int rev; };
  vector<vector<Edge>> G;
  int n, S, T;
Dinic(int _n, int _S, int _T) : n(_n), S(_S), T(_T),
     G(_n) \{ \}
  void add_edge(int u, int v, Cap w) {
  G[u].push_back({v, w, (int)G[v].size()});
  G[v].push_back({u, 0, (int)G[u].size() - 1});
  vector<int> dep;
  bool bfs() {
     dep.assign(n, 0);
     dep[S] = 1;
     queue<int> que;
     que.push(S);
     while (!que.empty()) {
       int u = que.front(); que.pop();
       for (auto [v, w, _] : G[u])
if (!dep[v] and w) {
             dep[v] = dep[u] + 1;
```

```
que.push(v);
                                                                      };
                                                                        2.3 HopcroftKarp
     return dep[T] != 0;
                                                                       // 1, r <= 1e5
                                                                       struct HK {
  Cap dfs(int u, Cap in) {
                                                                          vector<int> g, l, r;
     if (u == T) return in;
                                                                          int ans;
                                                                          HK(int n, int m, const vector<pair<int, int>> &e)
     Cap out = 0:
     for (auto &[v, w, rev] : G[u]) {
                                                                             : g(e.size()), l(n, -1), r(m, -1), ans{} {
       if (w and dep[v] == dep[u] + 1) {
  Cap f = dfs(v, min(w, in));
                                                                            vector<int> deg(n + 1);
for (auto [x, y] : e) deg[x]++;
partial_sum(all(deg), deg.begin());
          w -= f, G[v][rev].w += f;
in -= f, out += f;
if (!in) break;
                                                                             for (auto [x, y] : e) g[--deg[x]] = y;
                                                                             vector<int> que(n);
       }
                                                                             for (;;) {
                                                                               vector<int> a(n, -1), p(n, -1);
     if (in) dep[u] = 0;
                                                                               for (int i = 0; i < n; i++) if (l[i] == -1)
     return out;
                                                                                 que[t++] = a[i] = p[i] = i;
  Cap maxflow() {
                                                                               bool match = false;
                                                                               for (int i = 0; i < t; i++) {
     Cap ret = 0;
     while (bfs()) {
                                                                                  int x = que[i];
                                                                                 if (~l[a[x]]) continue;
for (int j = deg[x]; j < deg[x + 1]; j++) {</pre>
       ret += dfs(S, INF);
                                                                                    int y = g[j];
     return ret;
                                                                                    if (r[y] == -1) {
   while (~y) r[y] = x, swap(l[x], y), x = p[x
};
                                                                             ];
2.2 zkwDinic
                                                                                      match = true, ans++;
template<class Cap>
                                                                                      break;
struct zkwDinic {
   struct Edge { int v; Cap w, f; int rev; };
                                                                                    if (p[r[y]] == -1)_{{}}
   vector<vector<Edge>> G;
                                                                                      que[t++] = y = r[y]
   int n, S, T;
                                                                                      p[y] = x, a[y] = a[x];
  zkwDinic(int _n, int _S, int _T) : n(_n), S(_S), T(_T
  ), G(_n) {}
void add_edge(int u, int v, Cap w, Cap f) {
  G[u].push_back({v, w, f, (int)G[v].size()});
  G[v].push_back({u, -w, 0, (int)G[u].size() - 1});
                                                                               if (!match) break;
                                                                          }
  vector<Cap> dis;
                                                                       };
  vector<bool> vis;
                                                                        2.4
                                                                               KM
  bool spfa() {
     queue<int> que;
                                                                       i64 KM(vector<vector<int>> W) {
                                                                          const int n = W.size();
     dis.assign(n, INF);
vis.assign(n, false);
                                                                          vector<int> fl(n, -1), fr(n, -1), hr(n), hl(n);
for (int i = 0; i < n; ++i) {</pre>
     que.push(S);
     vis[S] = 1;
                                                                            hl[i] = *max_element(W[i].begin(), W[i].end());
     dis[S] = 0;
     while (!que.empty()) {
                                                                          auto Bfs = [&](int s) {
                                                                            vector<int> slk(n, INF), pre(n);
vector<bool> vl(n, false), vr(n, false);
       int u = que.front(); que.pop();
       vis[u] = 0;
       for (auto [v, w, f, _] : G[u])
  if (f and chmin(dis[v], dis[u] + w))
                                                                             queue<int> que;
                                                                             que.push(s);
            if (!vis[v]) que.push(v), vis[v] = 1;
                                                                             vr[s] = true;
                                                                            auto Check = [&](int x) -> bool {
  if (vl[x] = true, fl[x] != -1) {
     return dis[T] != INF;
                                                                                 que.push(fl[x]);
  Cap dfs(int u, Cap in) {
                                                                                 return vr[fl[x]] = true;
     if (u == T) return in;
     vis[u] = 1;
                                                                               while (x != -1) swap(x, fr[fl[x] = pre[x]]);
     Cap out = 0;
                                                                               return false;
     for (auto &[v, w, f, rev] : G[u])
  if (f and !vis[v] and dis[v] == dis[u] + w) {
                                                                             while (true) {
          Cap x = dfs(v, min(in, f));
                                                                               while (!que.empty()) {
          in -= x, out += x;
                                                                                 int y = que.front(); que.pop();
for (int x = 0, d = 0; x < n; ++x) {</pre>
          f \rightarrow x, G[v][rev].f += x;
          if (!in) break;
                                                                                    if (!vl[x] \text{ and } slk[x] >= (d = hl[x] + hr[y] -
                                                                              W[x][y]))
     if (in) dis[u] = INF;
                                                                                       if (pre[x] = y, d) slk[x] = d;
                                                                                       else if (!Check(x)) return;
     vis[u] = 0;
     return out;
                                                                                 }
  pair<Cap, Cap> maxflow() {
  Cap a = 0, b = 0;
                                                                               }
                                                                               int d = INF;
     while (spfa()) {
                                                                               for (int x = 0; x < n; ++x) {
                                                                                 if (!vl[x] \text{ and } d > slk[x]) d = slk[x];
       Cap x = dfs(S, INF);
       a += x;
       b += x^* dis[T];
                                                                               for (int x = 0; x < n; ++x) {
                                                                                 if (vl[x]) hl[x] += d;
     return {a, b};
                                                                                  else slk[x] -= d;
                                                                                 if (vr[x]) hr[x] -= d;
```

```
auto &e = g[u];
                                                                                 const int v = e[rng() % e.size()];
       for (int x = 0; x < n; ++x) {
         if (!vl[x] \text{ and } !slk[x] \text{ and } !Check(x)) return;
                                                                                 mat[u] = v;
                                                                                  swap(u, mat[v]);
    }
                                                                                 if (u == -1) break;
  for (int i = 0; i < n; ++i) Bfs(i);
                                                                               if (u != -1) {
                                                                                 mat[u] = -1:
  i64 \text{ res} = 0;
  for (int i = 0; i < n; ++i) res += W[i][fl[i]];</pre>
                                                                                  unmat.emplace(hit[u] * 100ULL / (g[u].size() +
                                                                            1),
  return res;
                                                                                 u):
2.5 SW
                                                                             int siz = 0;
int w[kN][kN], g[kN], del[kN], v[kN];
                                                                            for (auto e : mat) siz += (e != -1);
                                                                             return siz / 2;
void AddEdge(int x, int y, int c) {
  w[x][y] += c;
                                                                       };
  w[y][x] += c;
pair<int, int> Phase(int n) {
  fill(v, v + n, 0), fill(g, g + n, 0);
  int s = -1, t = -1;
                                                                        3
                                                                             Graph
                                                                       3.1
                                                                             2-SAT
  while (true) {
                                                                       struct TwoSAT {
     int c = -1;
for (int i = 0; i < n; ++i) {
   if (del[i] || v[i]) continue;</pre>
                                                                          vector<vector<int>> G;
                                                                          int n
                                                                          TwoSAT(int _n) : n(_n), G(_n * 2) {}
       if (c == -1 || g[i] > g[c]) c = i;
                                                                          int ne(int x) { return x < n ? x + n : x - n; }
void add_edge(int u, int v) { // u or v</pre>
     if (c == -1) break;
    v[c] = 1, s = t, t = c;
for (int i = 0; i < n; ++i) {
  if (del[i] || v[i]) continue;</pre>
                                                                             G[ne(u)].push_back(v);
                                                                            G[ne(v)].push_back(u);
                                                                          vector<int> solve() {
  vector<int> ans(n * 2, -1), id(n * 2), stk, \
    low(n * 2), dfn(n * 2), vis(n * 2);
       g[i] += w[c][i];
  }
                                                                             int _t = 0, scc_cnt = 0;
  return make_pair(s, t);
                                                                             function<void(int)> dfs = [&](int u) {
                                                                               dfn[u] = low[u] = _t++;
int GlobalMinCut(int n) {
                                                                               stk.push_back(u);
  int cut = kInf;
fill(del, 0, sizeof(del));
for (int i = 0; i < n - 1; ++i) {</pre>
                                                                               vis[u] = 1;
                                                                               for (int v : G[u]) {
                                                                                 if (!vis[v])
     int s, t; tie(s, t) = Phase(n);
                                                                                 dfs(v), chmin(low[u], low[v]);
else if (vis[v] == 1)
    del[t] = 1, cut = min(cut, g[t]);
for (int j = 0; j < n; ++j) {
  w[s][j] += w[t][j];</pre>
                                                                                    chmin(low[u], dfn[v]);
       w[j][s] += w[j][t];
                                                                               if (dfn[u] == low[u]) {
     }
                                                                                 for (int x = -1; x != u; ) {
  x = stk.back(); stk.pop_back();
  return cut;
                                                                                    vis[x] = 2, id[x] = scc\_cnt;
                                                                                    if (ans[x] == -1) {
                                                                                      ans[x] = 1;
2.6 GeneralMatching
                                                                                      ans [ne(x)] = 0;
struct GeneralMatching { // n <= 500</pre>
                                                                                    }
  const int BLOCK = 1\bar{0};
  int n;
                                                                                 scc_cnt++;
  vector<vector<int> > g;
                                                                               }
  vector<int> hit, mat;
  std::priority_queue<pair<i64, int>, vector<pair<i64,
                                                                             for (int i = 0; i < n + n; i++)
     int>>, greater<pair<i64, int>>> unmat;
                                                                             if (!vis[i]) dfs(i);
for (int i = 0; i < n; i++)</pre>
  GeneralMatching(int _n): n(_n), g(_n), mat(n, -1),
     hit(n) {}
                                                                               if (id[i] == id[ne(i)])
  void add_edge(int a, int b) \{ // \emptyset \le a != b < n \}
                                                                                 return {};
     g[a].push_back(b);
                                                                             ans.resize(n);
     g[b].push_back(a);
                                                                             return ans;
                                                                          }
  int get_match() {
                                                                       };
     for (int i = 0; i < n; i++) if (!g[i].empty()) {</pre>
       unmat.emplace(0, i);
                                                                        3.2
                                                                              Manhattan MST
     // If WA, increase this
                                                                       vector<tuple<int, int, int>> ManhattanMST(vector<Pt> P)
     // there are some cases that need >=1.3*n^2 steps
     for BLOCK=1
                                                                          vector<int> id(P.size());
                                                                          iota(all(id), 0);
     // no idea what the actual bound needed here is.
     const int MAX_STEPS = 10 + 2 * n + n * n / BLOCK /
                                                                          vector<tuple<int, int, int>> edges;
                                                                          for (int k = 0; k < 4; ++k) {
  sort(all(id), [&](int i, int j) -> bool {
    return (P[i] - P[j]).ff < (P[j] - P[i]).ss;</pre>
     mt19937 rng(random_device{}());
     for (int i = 0; i < MAX_STEPS; ++i) {
       if (unmat.empty()) break;
                                                                             });
       int u = unmat.top().second;
                                                                            map<int, int> sweep;
       unmat.pop();
                                                                             for (int i : id) {
       if (mat[u] != -1) continue;
                                                                               for (auto it = sweep.lower_bound(-P[i].ss); \
       for (int j = 0; j < BLOCK; j++) {
    ++hit[u];</pre>
                                                                                    it != sweep.end(); sweep.erase(it++)) {
```

int j = it->ss;

for (int j = 1; j <= n; ++j) {

```
Pt d = P[i] - P[j];
                                                                       for (int k = 1; k \le n; ++k) {
                                                                        dp[i][k] = min(dp[i - 1][j] + d[j][k], dp[i][k]);
         if (d.ss > d.ff) break;
         edges.emplace_back(d.ss + d.ff, i, j);
       sweep[-P[i].ss] = i;
                                                                    long long au = 1ll << 31, ad = 1;
for (int i = 1; i <= n; ++i) {
    for (Pt &p : P) {
                                                                      if (dp[n][i] == 0x3f3f3f3f3f3f3f3f3f) continue;
       if (k % 2) p.ff = -p.ff;
                                                                     long long u = 0, d = 1;

for (int j = n - 1; j >= 0; --j) {

   if ((dp[n][i] - dp[j][i]) * d > u * (n - j)) {

      u = dp[n][i] - dp[j][i];
       else swap(p.ff, p.ss);
  return edges;
}
                                                                        d = n - j;
3.3
     TreeHash
                                                                      if (u * ad < au * d) au = u, ad = d;
u64 TreeHash(const vector<vector<int>> &G) {
  const int n = G.size();
                                                                    long long q = \_\_qcd(au, ad);
  vector<int> cen;
                                                                    return make_pair(au / g, ad / g);
  vector<u64> pw(n, 1);
  for (int i = 1; i < n; i++) pw[i] = pw[i - 1] * u64(1)
    e9 + 123)
                                                                   3.6 Block Cut Tree
  auto dfs = [&](auto self, int u, int fa) -> int {
                                                                   struct BlockCutTree {
    int siz = 1;
                                                                     int n;
    bool f = true;
                                                                      vector<vector<int>> adj;
    for (int v : G[u]) if (v != fa) {
  int s = self(self, v, u);
                                                                     BlockCutTree(int _n) : n(_n), adj(_n) {}
void addEdge(int u, int v) {
       f &= (s * 2 <= n);
                                                                        adj[u].push_back(v);
       siz += s;
                                                                        adj[v].push_back(u);
    f \&= ((n - siz) * 2 <= n);
                                                                     pair<int, vector<pair<int, int>>> work() {
  vector<int> dfn(n, -1), low(n), stk;
    if (f) cen.push_back(u);
return siz;
                                                                        vector<pair<int, int>> edg;
int cnt = 0, cur = 0;
  }; dfs(dfs, 0, -1);
auto cal = [&](auto self, int u, int fa) -> pair<u64,</pre>
                                                                        function<void(int)> dfs = [&](int x) {
      int> {
                                                                          stk.push_back(x);
    vector<pair<u64, int>> U;
                                                                          dfn[x] = low[x] = cur++;
    int siz = 1;
                                                                          for (auto y : adj[x]) {
  if (dfn[y] == -1) {
    u64 h = G[u].size();
    for (int \bar{v} : G[u]) if (v != fa) {
                                                                               dfs(y);
      U.push_back(self(self, v, u));
                                                                               low[x] = min(low[x], low[y]);
                                                                               if (low[y] == dfn[x]) {
    sort(all(U));
                                                                                 int v;
    for (auto [v, s] : U) {
  h = h * pw[s] + v;
                                                                                 do {
                                                                                   v = stk.back();
       siz += s;
                                                                                   stk.pop_back():
                                                                                   edg.emplace_back(n + cnt, v);
    return {h, siz};
                                                                                 } while (v != y);
                                                                                 edg.emplace_back(x, n + cnt);
  vector<u64> H;
                                                                                 cnt++;
  for (int c : cen) H.push_back(cal(cal, c, -1).ff);
  return ranges::min(H);
                                                                            } else {
};
                                                                               low[x] = min(low[x], dfn[y]);
3.4 Maximum IndependentSet
// n <= 40, (*500)
set<int> MI(const vector<vector<int>> &adj) {
                                                                        for (int i = 0; i < n; i++) {
  set<int> I, V;
                                                                          if (dfn[i] == -1) {
  for (int i = 0; i < adj.size(); i++)</pre>
                                                                            stk.clear();
    V.insert(i)
                                                                            dfs(i);
  while (!V.empty()) {
    auto it = next(V.begin(), rng() % V.size());
     int cho = *it;
                                                                        return {cnt, edg};
    I.insert(cho)
                                                                     }
    V.extract(cho)
                                                                  };
    for (int i : adj[cho]) {
  if (auto j = V.find(i); j != V.end())
                                                                   3.7 Heavy Light Decomposition
         V.erase(j);
                                                                   struct HLD {
    }
                                                                      int n:
  }
                                                                      vector<int> siz, top, dep, pa, in, out, seq;
  return I;
                                                                      vector<vector<int>> G;
                                                                      HLD(int _n) : n(_n), G(_n) {}
                                                                      int cur{};
3.5 Min Mean Weight Cycle
                                                                      void addEdge(int u, int v) {
// d[i][j] == 0 if {i,j} !in E
                                                                        G[u].push_back(v);
long long d[1003][1003], dp[1003][1003];
                                                                        G[v].push_back(u);
pair<long long, long long> MMWC() {
                                                                      void work(int root = 0) {
 memset(dp, 0x3f, sizeof(dp));
                                                                        siz = top = dep = pa = in = out = seq = vector<int
 for (int i = 1; i <= n; ++i) dp[0][i] = 0;
for (int i = 1; i <= n; ++i) {</pre>
                                                                        >(n);
```

cur = 0;

top[root] = root;

d = v[l];

```
dep[root] = 0;
                                                                        return;
    pa[root] = -1;
    dfs1(root);
                                                                      int mid = l + r \gg 1;
                                                                      ls = new Seg(l, mid, v)
    dfs2(root);
                                                                     rs = new Seg(mid, r, v);
  void dfs1(int u) {
                                                                     pull();
    if (pa[u] != -1) {
      G[u].erase(find(all(G[u]), pa[u]));
                                                                   void upd(const T &g) {
                                                                     g(d), g(f);
    siz[u] = 1;
    for (auto &v : G[u]) {
                                                                   void pull() {
      pa[v] = u;
                                                                     d = ls -> d + rs -> d;
      dep[v] = dep[u] + 1;
      dfs1(v);
                                                                   void push() {
                                                                     ls->upd(f);
      siz[u] += siz[v];
      if (siz[v] > siz[G[u][0]]) {
                                                                     rs->upd(f);
        swap(v, G[u][0]);
                                                                      f = T{};
                                                                   S prod(int x, int y) {
    }
                                                                      if (y <= l or r <= x) return S{};</pre>
                                                                      if (x \ll 1) and r \ll y) return d;
  void dfs2(int u) {
                                                                      push();
    in[u] = cur++;
    seq[in[u]] = u;
                                                                      return ls->prod(x, y) + rs->prod(x, y);
    for (int v : G[u]) {
                                                                   void apply(int x, int y, const T &g) {
  if (y <= l or r <= x) return;</pre>
      top[v] = (v == G[u][0] ? top[u] : v);
      dfs2(v);
                                                                      if (x \ll 1 \text{ and } r \ll y) {
    out[u] = cur;
                                                                        upd(g);
                                                                        return;
  int lca(int x, int y) {
  while (top[x] != top[y]) {
                                                                     push();
      if (dep[top[x]] < dep[top[y]]) swap(x, y);</pre>
                                                                     ls->apply(x, y, g);
rs->apply(x, y, g);
      x = pa[top[x]];
                                                                     pull();
    return dep[x] < dep[y] ? x : y;</pre>
                                                                 };
  int dist(int_x, int y) {
                                                                       Treap
    return dep[x] + dep[y] - 2 * dep[lca(x, y)];
                                                                 mt19937 rng(random_device{}());
  int jump(int x, int k) {
                                                                 template<class S, class T>
    if (dep[x] < k) return -1;</pre>
                                                                 struct Treap {
                                                                   struct Node {
  Node *ls{}, *rs{};
    int d = dep[x] - k;
    while (dep[top[x]] > d) {
      x = pa[top[x]];
                                                                      int pos, siz;
                                                                      u32 pri;
    return seq[in[x] - dep[x] + d];
                                                                      S d{}, e{};
                                                                     T f{};
 bool isAnc(int x, int y) {
                                                                     Node(int p, S x) : d\{x\}, e\{x\}, pos\{p\}, siz\{1\}, pri\{
    return in[x] <= in[y] and in[y] < out[x];</pre>
                                                                      rng()} {}
                                                                      void upd(T &g) {
  int rootPar(int r, int x) {
                                                                       g(d), g(e), g(f);
    if (r == x) return r;
    if (!isAnc(x, r)) return pa[x];
                                                                      void pull() {
                                                                        siz = Siz(ls) + Siz(rs);
    auto it = upper_bound(all(G[x]), r, [&](int a, int
    b) -> bool {
                                                                        d = Get(ls) + e + Get(rs);
      return in[a] < in[b];</pre>
    });
                                                                      void push() {
                                                                        if (ls) ls->upd(f);
if (rs) rs->upd(f);
    return *it;
                                                                        f = T{};
  int rootSiz(int r, int x) {
    if (r == x) return n;
if (!isAnc(x, r)) return siz[x];
                                                                   } *root{};
    return n - siz[rootPar(r, x)];
                                                                   static int Siz(Node *p) { return p ? p->siz : 0; }
                                                                   static S Get(Node *p) { return p ? p->d : S{}; }
                                                                   Treap() : root{} {}
Node* Merge(Node *a, Node *b) {
 int rootLca(int a, int b, int c) {
    return lca(a, b) ^ lca(b, c) ^ lca(c, a);
                                                                      if (!a or !b) return a ? a : b;
                                                                      if (a->pri < b->pri) {
                                                                        a->push();
4
     Data Structure
                                                                        a \rightarrow rs = Merge(a \rightarrow rs, b);
                                                                        a->pull();
4.1 Lazy Segtree
                                                                        return a;
template<class S, class T>
                                                                     } else {
struct Seg {
  Seg<S, T> *ls{}, *rs{};
                                                                        b->push();
                                                                        b->ls = Merge(a, b->ls);
  int l, r;
                                                                        b->pull();
  S d{};
                                                                        return b;
  Seg(int _l, int _r, const vector<Info> &v) : l{_l}, r
    {_r} {
if (r - l == 1) {
                                                                   void Split(Node *p, Node *&a, Node *&b, int k) {
                                                                      if (!p) return void(a = b = nullptr);
```

p->push();

void pull() {

```
if (p->pos \ll k) {
                                                                      sum = ls -> sum + rs -> sum;
                                                                   Seg* modify(int p, int v) {
      Split(p->rs, a->rs, b, k);
                                                                      Seg* ret = new Seg(this);
      a->pull();
    } else {
                                                                      if(r - l == 1) {
      b = p;
                                                                        ret->sum = v;
      Split(p->ls, a, b->ls, k);
                                                                        return ret;
      b->pull();
                                                                      if (p < (l + r >> 1)) ret->ls = ret->ls->modify(p,
                                                                      v);
                                                                      else ret->rs = ret->rs->modify(p, v);
  void insert(int p, S x) {
    Node *L, *R;
                                                                      ret->pull();
    Split(root, L, R, p);
                                                                      return ret;
    root = Merge(Merge(L, new Node(p, x)), R);
                                                                   i64 query(int x, int y) {
                                                                     if (y <= l or r <= x) return 0;
if (x <= l and r <= y) return sum;
  void erase(int x) {
  Node *L, *M, *R;
    Split(root, M, R, x);
                                                                      return ls->query(x, y) + rs->query(x, y);
    Split(M, L, M, x' - 1);
                                                                   }
                                                                };
    if (M) M = Merge(M->ls, M->rs);
    root = Merge(Merge(L, M), R);
                                                                 4.5
                                                                        Blackmagic
  S query() {
                                                                 #include <bits/extc++.h>
    return Get(root);
                                                                 #include <ext/pb_ds/assoc_container.hpp>
                                                                 #include <ext/pb_ds/tree_policy.hpp>
                                                                 #include <ext/pb_ds/hash_policy.hpp>
                                                                 #include <ext/pb_ds/priority_queue.hpp>
4.3 LiChao Segtree
                                                                 using namespace __gnu_pbds;
struct Line {
    i64 k, m; // y = k + mx;
                                                                 template<class T>
                                                                 using BST = tree<T, null_type, less<T>, rb_tree_tag,
  Line(): k{INF}, m{} {}
Line(i64 _k, i64 _m): k(_k), m(_m) {}
                                                                      tree_order_statistics_node_update>;
                                                                 gnu_pbds::priority_queue<node, decltype(cmp),</pre>
  i64 get(i64 x) {
                                                                      pairing_heap_tag> pq(cmp);
    return k + m * x;
                                                                 gp_hash_table<int, gnu_pbds::priority_queue<node>::
                                                                      point_iterator> pqPos;
                                                                 bst.insert((x << 20) + i)
};
struct Seg {
   Seg *ls{}, *rs{};
   int l, r, mid;
                                                                 bst.erase(bst.lower_bound(x << 20));</pre>
                                                                 bst.order_of_key(x << 20) + 1;
                                                                 *bst.find_by_order(x - 1) >> 20;
*--bst.lower_bound(x << 20) >> 20;
  Line line{};
  Seg(int _l, int _r) : l(_l), r(_r), mid(_l + _r >> 1)
                                                                 *bst.upper_bound((x + 1) \ll 20) >> 20;
                                                                 4.6 Centroid Decomposition
    if (r - l == 1) return;
    ls = new Seg(l, mid);
                                                                 struct CenDec {
    rs = new Seg(mid, r);
                                                                   vector<vector<pair<int, int>>> anc;
                                                                   vector<int> Mdis;
  void insert(Line L) {
                                                                   CenDec(const vector<vector<int>> &G) : anc(G.size()),
    if (line.get(mid) > L.get(mid))
                                                                       Mdis(G.size(), INF)
    swap(line, L);
if (r - l == 1) return;
                                                                      const int n = G.size();
                                                                      vector<int> siz(n);
    if (L.m < line.m) {</pre>
                                                                      vector<bool> vis(n);
      rs->insert(L);
                                                                      function<int(int, int)> getsiz = [&](int u, int f)
    } else {
      ls->insert(L);
                                                                        siz[u] = 1;
                                                                        for (int v : G[u]) if (v != f and !vis[v])
                                                                          siz[u] += getsiz(v, u);
  i64 query(int p) {
                                                                        return siz[u];
    if (p < l or r <= p) return INF;
if (r - l == 1) return line.get(p);</pre>
                                                                      function<int(int, int, int)> find = [&](int u, int
                                                                      f, int s) {
  for (int v : G[u]) if (v != f and !vis[v])
    return min({line.get(p), ls->query(p), rs->query(p)
    });
                                                                          if (siz[v] * 2 >= s) return find(v, u, s);
  }
};
                                                                        return u:
4.4 Persistent SegmentTree
                                                                      function<void(int, int, int, int)> caldis = [&](int
struct Seg {
                                                                       u, int f, int a, int d) {
                                                                        anc[u].emplace_back(a, d);
for (int v : G[u]) if (v != f and !vis[v])
  Seg *ls{}, *rs{};
  int l, r;
  i64 sum{}
                                                                          caldis(v, u, a, d + 1);
  Seg(Seg* p) { (*this) = *p; }
Seg(int _l, int _r, const vector<int> &v) : l{_l}, r{
                                                                      function<void(int)> build = [&](int u) {
                                                                        u = find(u, u, getsiz(u, u));
    if (r - l == 1) {
                                                                        vis[u] = 1;
      sum = v[l];
                                                                        for (int v : G[u]) if (!vis[v]) {
                                                                          caldis(v, u, u, 1);
      return;
                                                                          build(v);
    int mid = l + r >> 1;
ls = new Seg(l, mid, v);
                                                                        vis[u] = 0;
    rs = new Seg(mid, r, v);
                                                                      }:
    pull();
                                                                      build(0);
```

void add(int p) {

```
Mdis[p] = 0;
      for (auto [v, d] : anc[p])
         chmin(Mdis[v], d);
   int que(int p) {
     int r = Mdis[p];
for (auto [v, d] : anc[p])
    chmin(r, Mdis[v] + d);
      return r;
  }
};
```

5 **Dynamic Programming**

5.1 CDQ

```
auto cmp2 = [&](int a, int b) -> bool { return P[a][1]
sort(l, mid, cmp2);
  sort(mid, r, cmp2);
for (auto i = l, j = mid; j < r; j++) {
   while (i != mid and P[*i][1] < P[*j][1]) {</pre>
       bit.add(P[*i][2], dp[*i]);
        i++;
     dp[*j].upd(bit.qry(P[*j][2]));
   for (auto i = 1; i < mid; i++) bit.reset(P[*i][2]);</pre>
copy(all(tmp), mid);
self(self, mid, r);
}; cdq(cdq, all(ord));
```

Math

6.1 Theorem

· Pick's theorem

$$A = i + \frac{b}{2} - 1$$

· Laplacian matrix

$$L = D - A$$

· Extended Catalan number

$$\frac{1}{(k-1)n+1} \binom{kn}{n}$$

• Derangement $D_n = (n-1)(D_{n-1} + D_{n-2})$

$$\sum_{i\mid n}\mu(i)=[n=1]\sum_{i\mid n}\phi(i)=n$$

$$\begin{split} f(n) &= \sum_{i=0}^n {n \choose i} g(i) \; g(n) = \sum_{i=0}^n (-1)^{n-i} {n \choose i} f(i) \\ f(n) &= \sum_{d\mid n} g(d) \; g(n) = \sum_{d\mid n} \mu(\frac{n}{d}) f(d) \end{split}$$

· Sum of powers

$$\begin{split} \sum_{k=1}^{n} k^m &= \frac{1}{m+1} \sum_{k=0}^{m} \binom{m+1}{k} B_k^+ \, n^{m+1-k} \\ \sum_{j=0}^{m} \binom{m+1}{j} B_j^- &= 0 \\ \text{note} : B_1^+ &= -B_1^- \, B_i^+ = B_i^- \end{split}$$

· Cipolla's algorithm

$$\left(\frac{u}{p}\right) = u^{\frac{p-1}{2}}$$

$$1. \left(\frac{a^2 - n}{p}\right) = -1$$

2.
$$x = (a + \sqrt{a^2 - n})^{\frac{p+1}{2}}$$

• Cayley's formula number of trees on n labeled vertices: n^{n-2} Let $T_{n,k}$ be the number of labelled forests on n vertices with ${\bf k}$ connected components, such that vertices 1, 2, ..., k all belong to different connected components. Then $T_{n,k}=kn^{n-k-1}$.

· High order residue

$$[d^{\frac{p-1}{(n,p-1)}} \equiv 1]$$

· Packing and Covering $|\mathsf{Maximum\ Independent\ Set}| + |\mathsf{Minimum\ Vertex\ Cover}| = |V|$

· Kőnia's theorem

|maximum matching| = |minimum vertex cover|

· Dilworth's theorem

 $\mbox{width} = |\mbox{largest antichain}| = |\mbox{smallest chain decomposition}|$

· Mirsky's theorem

 $\mbox{height} \quad = \quad |\mbox{longest chain}| \quad = \quad |\mbox{smallest antichain decomposition}|$ |minimum anticlique partition|

· Triangle center

-
$$G:(1,)$$

- $O:(a^2(b^2+c^2-a^2),)=(sin2A,)$
- $I:(a,)=(sinA)$

-
$$E:(-a,b,c)=(-sinA,sinB,sinC)$$

-
$$H: (\frac{1}{h^2+c^2-a^2},) = (tan A,)$$

• Lucas'Theorem : For $n,m\in\mathbb{Z}^*$ and prime P , $C(m,n)\mod P=\Pi(C(m_i,n_i))$ where m_i is the i-th digit of m in base P.

• Stirling approximation:

$$n! \approx \sqrt{2\pi n} \left(\frac{n}{e}\right)^n e^{\frac{1}{12n}}$$

• Stirling Numbers(permutation |P|=n with k cycles): $S(n,k) = \text{coefficient of } x^k \text{ in } \Pi_{i=0}^{n-1}(x+i)$

• Stirling Numbers(Partition n elements into k non-empty set):

$$S(n,k) = \frac{1}{k!} \sum_{j=0}^{k} (-1)^{k-j} {k \choose j} j^n$$

• Pick's Theorem : A = i + b/2 - 1A: Area \cdot i: grid number in the inner \cdot b: grid number on the side

• Catalan number : $C_n = \binom{2n}{n}/(n+1)$ $C_n^{n+m} - C_{n+1}^{n+m} = (m+n)! \frac{n-m+1}{n+1}$ for $n \ge m$ $C_n = \frac{1}{n+1} {2n \choose n} = \frac{(2n)!}{(n+1)!n!}$ $\begin{array}{lll} C_0 = 1 & and & C_{n+1} = 2(\frac{2n+1}{n+2})C_n \\ C_0 = 1 & and & C_{n+1} = \sum_{i=0}^n C_i C_{n-i} & for & n \geq 0 \end{array}$

• Euler Characteristic:

planar graph: V-E+F-C=1 convex polyhedron: V-E+F=2

V, E, F, C: number of vertices, edges, faces(regions), and components

· Kirchhoff's theorem:

 $A_{ii} = deg(i), A_{ij} = (i,j) \in E \,?\,-\,1:0$, Deleting any one row, one column,

- Polya' theorem (c is number of color • m is the number of cycle size): $\left(\sum_{i=1}^{m} c^{\gcd(i,m)}\right)/m$

- Burnside lemma:
$$|X/G| = \tfrac{1}{|G|} \sum_{g \in G} |X^g|$$

・ 錯排公式: (
$$n$$
 個人中,每個人皆不再原來位置的組合數): $dp[0]=1; dp[1]=0;$ $dp[i]=(i-1)*(dp[i-1]+dp[i-2]);$

• Bell 數 (有 n 個人, 把他們拆組的方法總數):

$$B_0 = 1$$

$$B_n = \sum_{k=0}^{n} s(n, k) \quad (second - stirling)$$

$$B_{n+1} = \sum_{k=0}^{n} {n \choose k} B_k$$

· Wilson's theorem :

$$(p-1)! \equiv -1 \pmod{p}$$

• Fermat's little theorem : $a^p \equiv a \pmod{p}$

· Euler's totient function:

$$A^{B^C} \mod p = pow(A, pow(B, C, p - 1)) \mod p$$

• 歐拉函數降冪公式: $A^B \mod C = A^{B \mod \phi(c) + \phi(c)} \mod C$

• 環相鄰塗異色:

$$(k-1)(-1)^n + (k-1)^n$$

• 6 的倍數: $(a-1)^3 + (a+1)^3 + (-a)^3 + (-a)^3 = 6a$ if (b == 0) return $\{1, 0\}$;

6.2 Exgcd

```
auto [x, y] = exgcd(b, a % b);
return {y, x - a / b * y};
};

6.3 CRT

| i64 CRT(vector<pair<i64, i64>> E) {
    i128 R = 0, M = 1;
    for (auto [r, m] : E) {
        i128 d = r - R, g = gcd<i64>(M, m);
        if (d % g != 0) return -1;
        i128 x = exgcd(M / g, m / g).ff * d / g;
        R += M * x;
        M = M * m / g;
        R = (R % M + M) % M;
    }
    return R;
}
```

pair<i64, i64> exgcd(i64 a, i64 b) $\{ // ax + by = 1 \}$

6.4 Factorize

```
struct Factorize {
  i64 fmul(i64 a, i64 b, i64 p) {
     return (i128)a * b % p;
  i64 fpow(i64 a, i64 b, i64 p) {
     i64 res = 1;
     for (; b; b >>= 1, a = fmul(a, a, p))
       if (b & 1) res = fmul(res, a, p);
     return res;
  bool Check(i64 a, i64 u, i64 n, int t) {
     a = fpow(a, u, n);
     if (a == 0) or a == 1 or a == n - 1) return true;
for (int i = 0; i < t; i++) {
       a = fmul(a, a, n);
       if (a == 1) return false;
       if (a == n - 1) return true;
     return false;
  bool IsPrime(i64 n) {
     constexpr array<i64, 7> kChk{2, 235, 9375, 28178,
     450775, 9780504, 1795265022};
     // for int: {2, 7, 61}
     if (n < 2) return false;
     if (n % 2 == 0) return n == 2;
     i64 u = n - 1;
     int t = 0;
     while (u \% 2 == 0) u >>= 1, t++;
     for (auto v : kChk) if (!Check(v, u, n, t)) return
     false;
     return true;
  i64 PollardRho(i64 n) {
    if (n % 2 == 0) return 2;

i64 x = 2, y = 2, d = 1, p = 1;

auto f = [](i64 x, i64 n, i64 p) -> i64 {

return ((i128)x * x % n + p) % n;
     while (true) {
       x = f(x, n, p);
y = f(f(y, n, p), n, p);
d = __gcd(abs(x - y), n);
if (d != n and d != 1) return d;
       if (d == n) ++p;
};
```

6.5 NTT Prime List

```
Prime
             Root
                                    Root
7681
             17
                      167772161
12289
             11
                      104857601
40961
                      985661441
65537
                      998244353
             10
                      1107296257
5767169
                      2013265921
7340033
                      2810183681
                                   11
23068673
                      2885681153
469762049
                      605028353
```

6.6 NTT

```
constexpr i64 cpow(i64 a, i64 b, i64 m) {
   i64 ret = 1;
   for (; b; b >>= 1, a = a * a % m)
     if (b & 1) ret = ret * a % m;
   return ret:
};
template<i64 M, i64 G>
struct NTT {
   static constexpr i64 iG = cpow(G, M - 2, M);
   void operator()(vector<i64> &v, bool inv) {
     int n = v.size();
for (int i = 0, j = 0; i < n; i++) {</pre>
       if (i < j) swap(v[ij, v[j]);
for (int k = n / 2; (j ^= k) < k; k /= 2);</pre>
     for (int mid = 1; mid < n; mid *= 2) {</pre>
       i64 \text{ w} = \text{cpow}((inv ? iG : G), (M - 1) / (mid + mid))
     ), M);
       for (int i = 0; i < n; i += mid * 2) {
          i64 \text{ now} = 1;
          for (int j = i; j < i + mid; j++, now = now * w
      % M) {
            i64 x = v[j], y = v[j + mid];
v[j] = (x + y * now) % M;
            v[j + mid] = (x - y * now) % M;
       }
     if (inv) {
       i64 in = cpow(n, M - 2, M);
       for (int i = 0; i < n; i++) v[i] = v[i] * in % M;
  }
};
template<i64 M, i64 G>
vector<i64> convolution(vector<i64> f, vector<i64> g) {
   NTT<M, G> ntt;
   int sum = f.size() + g.size() - 1;
   int len = bit_ceil((u64)sum);
   f.resize(len); g.resize(len);
   ntt(f, 0), ntt(g, 0);
   for (int i = 0; i < len; i++) (f[i] *= g[i]) %= M;
   ntt(f, 1);
   f.resize(sum)
   for (int i = 0; i < sum; i++) if (f[i] < 0) f[i] += M
   return f;
vector<i64> convolution_ll(const vector<i64> &f, const
     vector<i64> &g) {
   constexpr i64 \text{ M1} = 998244353, G1 = 3;
   constexpr i64 M2 = 985661441, G2 = 3;
   constexpr i64 M1M2 = M1 * M2;
   constexpr i64 M1m1 = M2 * cpow(M2, M1 - 2, M1);
constexpr i64 M2m2 = M1 * cpow(M1, M2 - 2, M2);
   auto c1 = convolution<M1, G1>(f, g);
   auto c2 = convolution<M2, G2>(f, g);
   for (int i = 0; i < c1.size(); i++)
     c1[i] = ((i128)c1[i] * M1m1 + (i128)c2[i] * M2m2) %
      M1M2;
   return c1;
}
```

6.7 FWT

- 1. XOR Convolution
 - $f(A) = (f(A_0) + f(A_1), f(A_0) f(A_1))$ • $f^{-1}(A) = (f^{-1}(\frac{A_0 + A_1}{2}), f^{-1}(\frac{A_0 - A_1}{2}))$
- 2. OR Convolution
 - $f(A) = (f(A_0), f(A_0) + f(A_1))$ • $f^{-1}(A) = (f^{-1}(A_0), f^{-1}(A_1) - f^{-1}(A_0))$
- 3. AND Convolution
 - $f(A) = (f(A_0) + f(A_1), f(A_1))$ • $f^{-1}(A) = (f^{-1}(A_0) - f^{-1}(A_1), f^{-1}(A_1))$

```
6.8 FWT
void FWT(vector<int> &f, int 1, int r, auto &op) {
  if (r - l == 1) return;
  int m = 1 + r >> 1;
  FWT(f, l, m, op), FWT(f, m, r, op);
for (int i = l, j = m; i < m; i++, j++)</pre>
    op(f[i], f[j]);
void iFWT(vector<int> &f, int 1, int r, auto &op) {
  if (r - l == 1) return;
  int m = l + r >> 1;
  for (int i = l, j = m; i < m; i++, j++)
    op(f[i], f[j]);
  iFWT(f, l, m, op), iFWT(f, m, r, op);
vector<int> BitConv(int n, vector<int> f, vector<int> g
    , const auto &op, const auto &iop) {
  const int N = 1 \ll n;
  FWT(f, 0, N, op);
FWT(g, 0, N, op);
for (int i = 0; i < N; i++)</pre>
    f[i] = mul(f[i], g[i]);
  iFWT(f, 0, N, iop);
  return f;
6.9 Lucas
// C(N, M) mod D
i64 Lucas(i64 N, i64 M, i64 D) {
  auto Factor = [&](i64 x) -> vector<pair<i64, i64>> {
    vector<pair<i64, i64>> r;
    for (i64 i = 2; x > 1; i++)
```

```
if (x \% i == 0) {
      i64 c = 0;
      while (x \% i == 0) x /= i, c++;
      r.emplace_back(i, c);
    }
  return r;
};
auto Pow = [\&](i64 a, i64 b, i64 m) -> i64 {
  for (; b; b >>= 1, a = a * a % m)
    if (b & 1) r = r * a % m;
  return r;
}:
vector<pair<i64, i64>> E;
for (auto [p, q] : Factor(D)) {
  const i64 \text{ mod} = Pow(p, q, 1 << 30);
  auto CountFact = [\&](i64 x) \rightarrow i64 \{
    i64 c = 0;
    while (x) c += (x \neq p);
    return c;
  };
  auto CountBino = [&](i64 x, i64 y) { return
  CountFact(x) - CountFact(y) - CountFact(x - y); };
  auto Inv = [&](i64 x) -> i64 { return (exgcd(x, mod
).ff % mod + mod) % mod; };
  vector<i64> pre(mod + 1);
  pre[0] = pre[1] = 1;
  for (i64 i = 2; i \leq mod; i++) pre[i] = (i % p == 0
   ? 1 : i) * pre[i - 1] % mod;
  function < i64(i64) > FactMod = [&](i64 n) -> i64 {
    if (n == 0) return 1;
    return FactMod(n / p) * Pow(pre[mod], n / mod,
  mod) % mod * pre[n % mod] % mod;
  auto BinoMod = [\&](i64 x, i64 y) \rightarrow i64 \{
    return FactMod(x) * Inv(FactMod(y)) % mod * Inv(
  FactMod(x - y)) \% mod;
  i64 r = BinoMod(N, M) * Pow(p, CountBino(N, M), mod
  ) % mod:
  E.emplace_back(r, mod);
};
return CRT(E);
```

6.10 Berlekamp Massey

```
|template <int P>
```

```
vector<int> BerlekampMassey(vector<int> x) {
 vector<int> cur, ls;
 int lf = 0, ld = 0;
 for (int i = 0; i < (int)x.size(); ++i) {</pre>
  int t = 0;
  for (int j = 0; j < (int)cur.size(); ++j)
  (t += 1LL * cur[j] * x[i - j - 1] % P) %= P;</pre>
  if (t == x[i]) continue;
  if (cur.empty()) {
   cur.resize(i + 1);
   lf = i, ld = (t + P - x[i]) \% P;
  int k = 1LL * fpow(ld, P - 2, P) * (t + P - x[i]) % P
  vector<int> c(i - lf - 1);
  c.push_back(k);
for (int j = 0; j < (int)ls.size(); ++j)
  c.push_back(1LL * k * (P - ls[j]) % P);</pre>
  if (c.size() < cur.size()) c.resize(cur.size());</pre>
  for (int j = 0; j < (int)cur.size(); ++j)</pre>
  c[j] = (c[j] + cur[j]) % P;
if (i - lf + (int)ls.size() >= (int)cur.size()) {
   ls = cur, lf = i;
   ld = (t + P - x[i]) \% P;
  cur = c;
 return cur:
```

6.11 Gauss Elimination

```
double Gauss(vector<vector<double>> &d) {
 int n = d.size(), m = d[0].size();
 double det = 1;
 for (int i = 0; i < m; ++i) {
  int p = -1;
  for (int j = i; j < n; ++j) {
   if (fabs(d[j][i]) < kEps) continue;
   if (p == -1 || fabs(d[j][i]) > fabs(d[p][i])) p = j;
  if (p == -1) continue;
  if (p != i) det *= -1;
  for (int j = 0; j < m; ++j) swap(d[p][j], d[i][j]);
  for (int j = 0; j < n; ++j) {
    if (i == j) continue;
   double z = d[j][i] / d[i][i];
   for (int k = 0; k < m; ++k) d[j][k] -= z * d[i][k];
 for (int i = 0; i < n; ++i) det *= d[i][i];</pre>
 return det;
```

6.12 Linear Equation

```
void linear_equation(vector<vector<double>> &d, vector<</pre>
     double> &aug, vector<double> &sol) {
  int n = d.size(), m = d[0].size();
  vector<int> r(n), c(m);
  iota(r.begin(), r.end(), 0);
  iota(c.begin(), c.end(), 0);
for (int i = 0; i < m; ++i) {</pre>
    int p = -1, z = -1;
    for (int j = i; j < n; ++j) {
  for (int k = i; k < m; ++k) {
         if (fabs(d[r[j]][c[k]]) < eps) continue;</pre>
         if (p == -1 \mid | fabs(d[r[j]][c[k]]) > fabs(d[r[p
     ]][c[z]])) p = j, z = k;
      }
    if (p == -1) continue;
    swap(r[p], r[i]), swap(c[z], c[i]);
     for (int j = 0; j < n; ++j) {
       if (i == j) continue
       double z = d[r[j]][c[i]] / d[r[i]][c[i]]
       for (int k = 0; k < m; ++k) d[r[j]][c[k]] -= z *
    d[r[i]][c[k]];
      aug[r[j]] -= z * aug[r[i]];
  vector<vector<double>> fd(n, vector<double>(m));
  vector<double> faug(n), x(n);
```

```
for (int i = 0; i < n; ++i) {
    for (int j = 0; j < m; ++j) fd[i][j] = d[r[i]][c[j
    ]];
    faug[i] = aug[r[i]];
}
d = fd, aug = faug;
for (int i = n - 1; i >= 0; --i) {
    double p = 0.0;
    for (int j = i + 1; j < n; ++j) p += d[i][j] * x[j
    ];
    x[i] = (aug[i] - p) / d[i][i];
}
for (int i = 0; i < n; ++i) sol[c[i]] = x[i];
}</pre>
```

6.13 LinearRec

```
template <int P>
int LinearRec(const vector<int> &s, const vector<int> &
    coeff, int k) {
  int n = s.size()
  auto Combine = [&](const auto &a, const auto &b) {
    vector<int> res(n * 2 + 1);
    for (int i = 0; i <= n; ++i) {
      for (int j = 0; j <= n; ++j)
  (res[i + j] += 1LL * a[i] * b[j] % P) %= P;</pre>
    for (int i = 2 * n; i > n; --i) {
      for (int j = 0; j < n; ++j)
(res[i - 1 - j] += 1LL * res[i] * coeff[j] % P)
    res.resize(n + 1);
    return res;
 vector<int> p(n + 1), e(n + 1);
 p[0] = e[1] = 1;
  for (; k > 0; k >>= 1) {
    if (k \& 1) p = Combine(p, e);
    e = Combine(e, e);
  int res = 0;
  for (int i = 0; i < n; ++i) (res += 1LL * p[i + 1] *
    s[i] % P) %= P;
  return res;
```

6.14 SubsetConv

```
vector<int> SubsetConv(int n, const vector<int> &f,
    const vector<int> &g) {
 const int m = 1 \ll n;
vector<vector<int>> a(n + 1, vector<int>(m)), b(n + 1, vector<int>(m))
      vector<int>(m));
for (int i = 0; i < m; ++i) {
 a[__builtin_popcount(i)][i] = g[i];
for (int i = 0; i <= n; ++i) {
  for (int j = 0; j < n; ++j) {</pre>
   for (int s = 0; s < m; ++s) {
    if (s >> j & 1) {
    a[i][s] += a[i][s ^ (1 << j)];
     b[i][s] += b[i][s \wedge (1 << j)];
   }
  }
 vector<vector<int>>> c(n + 1, vector<int>(m));
for (int s = 0; s < m; ++s) {
  for (int i = 0; i <= n; ++i) {
   for (int j = 0; j <= i; ++j) c[i][s] += a[j][s] * b[
    i - j][s];
 for (int i = 0; i <= n; ++i) {
  for (int j = 0; j < n; ++j) {
for (int s = 0; s < m; ++s) {
    if (s >> j & 1) c[i][s] -= c[i][s ^ (1 << j)];</pre>
   }
vector<int> res(m);
```

```
for (int i = 0; i < m; ++i) res[i] = c[
       _builtin_popcount(i)][i];
 return res;
6.15 SqrtMod
int SqrtMod(int n, int P) \{ // \emptyset \le x < P \}
  if (P == 2 or n == 0) return n;
if (pow(n, (P - 1) / 2, P) != 1) return -1;
  mt19937 rng(12312);
  i64 z = 0, w;
  while (pow(w = (z * z - n + P) % P, (P - 1) / 2, P)
     != P - 1)
    z = rng() % P;
  const auto M = [P, w](auto &u, auto &v) {
    return make_pair(
       (u.ff * v.ff + u.ss * v.ss % P * w) % P,
       (u.ff * v.ss + u.ss * v.ff) % P
    );
  pair<i64, i64> r(1, 0), e(z, 1);
for (int w = (P + 1) / 2; w; w >>= 1, e = M(e, e))
    if (w \& 1) r = M(r, e);
  return r.ff; // sqrt(n) mod P where P is prime
6.16 FloorSum
// sigma 0 ~ n-1: (a * i + b) / m
i64 floor_sum(i64 n, i64 m, i64 a, i64 b) {
  u64 \text{ ans} = 0;
  if (a < 0) {
    u\hat{6}4 a2 = (a % m + m) % m;

ans -= 1ULL * n * (n - 1) / 2 * ((a2 - a) / m);
    a = a2;
  if (b < 0) {
    u64 b2 = (b \% m + m) \% m;
    ans -= 1ULL * n * ((b2 - b) / m);
    b = b2;
  while (true) {
    if (a >= m) {
 ans += n * (n - 1) / 2 * (a / m);
       a \% = m;
    if (b >= m) {
       ans += n * (b / m);
       b %= m:
    u64 y_max = a * n + b;
    if (y_max < m) break;</pre>
    n = y_max / m;
    b = y_max \% m;
    swap(m, a);
  return ans:
}
```

7 Geometry

7.1 2D Point

```
using Pt = pair<double, double>;
using numbers::pi;
constexpr double eps = 1e-9;
Pt operator+(Pt a, Pt b) { return {a.ff + b.ff, a.ss +
    b.ss}; }
Pt operator-(Pt a, Pt b) { return {a.ff - b.ff, a.ss -
    b.ss}; }
Pt operator*(Pt a, double b) { return {a.ff * b, a.ss *
     b}; }
Pt operator/(Pt a, double b) { return {a.ff / b, a.ss /
     b}; }
double operator*(Pt a, Pt b) { return a.ff * b.ff + a.
    ss * b.ss; }
double operator (Pt a, Pt b) { return a.ff * b.ss - a.
    ss * b.ff; }
double abs(Pt a) { return sqrt(a * a); }
double cro(Pt a, Pt b, Pt c) { return (b - a) ^ (c - a)
int sig(double x) { return (x > -eps) - (x < eps); }</pre>
Pt rot(Pt u, double a) {
```

```
Pt v\{\sin(a), \cos(a)\}
                                                                    return Inter(a, b, A[1 % n], A[r % n]);
  return {u ^ v, u * v};
                                                                  };
                                                                  vector<T> LineIntersect(T a, T b) { // long double
Pt Inter(Pt a, Pt b, Pt c, Pt d) {
  double s = cro(c, d, a), t = -cro(c, d, b);
  return (a * t + b * s) / (s + t);
                                                                    int l = tangent(a - b), r = tangent(b - a);
if (sig(cro(a, b, A[1])) * sig(cro(a, b, A[r])) >=
                                                                    0) return {}
                                                                    return {Find(l, r, a, b), Find(r, l, a, b)};
struct Line {
  Pt a{}, b{};
Line() {}
                                                               };
  Line(Pt _a, Pt _b) : a{_a}, b{_b} {}
                                                                7.4 Dynamic Convex Hull
                                                                template<class T, class Comp = less<T>>
Pt Inter(Line L, Line R) {
                                                                struct DynamicHull {
  return Inter(L.a, L.b, R.a, R.b);
                                                                  set<T, Comp> H;
                                                                  DynamicHull() {}
void insert(T p) {
7.2 Convex Hull
                                                                    if (inside(p)) return;
vector<Pt> Hull(vector<Pt> P) {
                                                                    auto it = H.insert(p).ff;
  sort(all(P));
                                                                    while (it != H.begin() and prev(it) != H.begin() \
  P.erase(unique(all(P)), P.end());
                                                                         and cross(*prev(it, 2), *prev(it), *it) <= 0) {</pre>
  P.insert(P.end(), rall(P));
                                                                       it = H.erase(--it);
  vector<Pt> stk;
  for (auto p : P)
                                                                    while (it != --H.end() and next(it) != --H.end() `
    while (stk.size() >= 2 and \
                                                                         and cross(*it, *next(it), *next(it, 2)) <= 0) {</pre>
         cro(*++stk.rbegin(), stk.back(), p) <= 0 and \</pre>
                                                                       it = --H.erase(++it);
         (*++stk.rbegin() < stk.back()) == (stk.back() <
                                                                    }
      p)) {
      stk.pop_back();
                                                                  bool inside(T p) {
                                                                    auto it = H.lower_bound(p);
    stk.push_back(p);
                                                                    if (it == H.end()) return false;
                                                                    if (it == H.begin()) return p == *it;
  stk.pop_back();
                                                                    return cross(*prev(it), p, *it) <= 0;
  return stk:
                                                                  }
}
                                                               };
7.3 Convex Hull trick
                                                                7.5 Half Plane Intersection
template<class T>
                                                                vector<Pt> HPI(vector<Line> P) {
struct Convex {
                                                                  const int n = P.size();
  int n:
                                                                  sort(all(P), [\&](Line L, Line R) \rightarrow bool {
  vector<T> A, V, L, U;
                                                                    Pt u = L.b - L.a, v = R.b - R.a;
  Convex(const vector<T> &_A) : A(_A), n(_A.size()) {
                                                                    bool f = Pt(sig(u.ff), sig(u.ss)) < Pt{};</pre>
     // n >= 3
                                                                    bool g = Pt(sig(v.ff), sig(v.ss)) < Pt{};</pre>
    auto it = max_element(all(A));
                                                                    if (f != g) return f
    L.assign(A.begin(), it + 1);
                                                                    return (sig(u ^ v) ? sig(u ^ v) : sig(cro(L.a, R.a,
    U.assign(it, A.end()), U.push_back(A[0]);
for (int i = 0; i < n; i++) {</pre>
                                                                     R.b))) > 0;
      V.push_back(A[(i + 1) % n] - A[i]);
                                                                  auto Same = [&](Line L, Line R) {
                                                                    Pt u = L.b - L.a, v = R.b - R.a;
                                                                    return sig(u \wedge v) == 0 and sig(u * v) == 1;
  int inside(T p, const vector<T> &h, auto f) { // 0:
    out, 1: on, 2: in
                                                                  deque <Pt> inter;
    auto it = lower_bound(all(h), p, f);
                                                                  deque <Line> seg;
     if (it == h.end()) return 0;
                                                                  for (int i = 0; i < n; i++) if (i == 0 or !Same(P[i -
    if (it == h.begin()) return p == *it;
                                                                      1], P[i])) {
    return 1 - sig(cro(*prev(it), p, *it));
                                                                    while (seg.size() >= 2 and sig(cro(inter.back(), P[
                                                                     i].b, P[i].a)) == 1) {
  int inside(T p) {
                                                                       seg.pop_back(), inter.pop_back();
    return min(inside(p, L, less{}), inside(p, U,
     greater{}));
                                                                    while (seg.size() >= 2 and sig(cro(inter[0], P[i].b
                                                                     , P[i].a)) == 1) {
  static bool cmp(T a, T b) { return sig(a \land b) > 0; }
                                                                       seg.pop_front(), inter.pop_front();
  int tangent(T v) {
    auto l = V.begin(), r = V.begin() + L.size() - 1;
                                                                    if (!seg.empty()) inter.push_back(Inter(seg.back(),
    if (v < T()) l = r, r = V.end();
                                                                      P[i]));
    return (lower_bound(l, r, v, cmp) - V.begin()) % n;
                                                                    seg.push_back(P[i]);
  array<int, 2> tangent2(T p) {
  array<int, 2> t{-1, -1};
                                                                  while (seg.size() >= 2 and sig(cro(inter.back(), seg
                                                                    [0].b, seg[0].a) == 1) {
     if (inside(p)) return t
                                                                    seg.pop_back(), inter.pop_back();
    for (int i = 0; i != t[0]; i = tangent((A[t[0] = i]
      - p)));
                                                                  inter.push_back(Inter(seg[0], seg.back()));
    for (int i = 0; i != t[1]; i = tangent((p - A[t[1]
                                                                  return vector<Pt>(all(inter));
     = i])));
                                                               }
    return t;
                                                                7.6 Minimal Enclosing Circle
  T Find(int l, int r, T a, T b) {
  if (r < l) r += n;
  int s = sig(cro(a, b, A[l % n]));</pre>
                                                                using circle = pair<Pt, double>;
                                                                struct MES {
    while (r - l > 1) {
                                                                  MES() {}
      (sig(cro(a, b, A[(l + r) / 2 % n])) == s ? l : r)
                                                                  bool inside(const circle &c, Pt p) {
      = (l + r) / 2;
                                                                    return abs(p - c.ff) <= c.ss + eps;</pre>
                                                                  };
```

```
circle get_cir(Pt a, Pt b) {
     return circle((a + b) / 2., abs(a - b) / 2.);
  circle get_cir(Pt a, Pt b, Pt c) {
  Pt p = (b - a) / 2.;
     p = Pt(-p.ss, p.ff);
     double t = ((c - a) * (c - b)) / (2 * (p * (c - a)))
     p = ((a + b) / 2.) + (p * t);
     return circle(p, abs(p - a));
   circle get_mes(vector<Pt> P) {
     if (P.empty()) return circle{Pt(0, 0), 0};
     mt19937 rng(random_device{}());
     shuffle(all(P), rng);
     circle C{P[0], 0};
for (int i = 1; i < P.size(); i++) {
   if (inside(C, P[i])) continue;</pre>
        C = get_cir(P[i], P[0]);
        for (int j = 1; j < i; j++) {
  if (inside(C, P[j])) continue;</pre>
           C = get_cir(P[i], P[j]);
for (int k = 0; k < j; k++) {
   if (inside(C, P[k])) continue;</pre>
              C = get_cir(P[i], P[j], P[k]);
        }
     return C;
};
```

7.7 Minkowski

```
vector<Pt> Minkowski(vector<Pt> P, vector<Pt> Q) {
    auto reorder = [&](auto &R) -> void {
        auto cmp = [&](Pt a, Pt b) -> bool {
            return Pt(a.ss, a.ff) < Pt(b.ss, b.ff);
        };
        rotate(R.begin(), min_element(all(R), cmp), R.end()
        );
        R.push_back(R[0]), R.push_back(R[1]);
        };
        const int n = P.size(), m = Q.size();
        reorder(P), reorder(Q);
        vector<Pt> R;
        for (int i = 0, j = 0, s; i < n or j < m; ) {
            R.push_back(P[i] + Q[j]);
            s = sig((P[i + 1] - P[i]) ^ (Q[j + 1] - Q[j]));
            i += (s >= 0), j += (s <= 0);
        }
        return R;
}</pre>
```

7.8 TriangleCenter

```
Pt TriangleCircumCenter(Pt a, Pt b, Pt c) {
Pt res;
double a1 = atan2(b.y - a.y, b.x - a.x) + pi / 2;
double a2 = atan2(c.y - b.y, c.x - b.x) + pi / 2;
double ax = (a.x + b.x) / 2;
double ay = (a.y + b.y) / 2;
double bx = (c.x + b.x) / 2
return Pt(ax + r1 * cos(a1), ay + r1 * sin(a1));
Pt TriangleMassCenter(Pt a, Pt b, Pt c) {
return (a + b + c) / 3.0;
}
Pt TriangleOrthoCenter(Pt a, Pt b, Pt c) {
return TriangleMassCenter(a, b, c) * 3.0 -
    TriangleCircumCenter(a, b, c) * 2.0;
Pt TriangleInnerCenter(Pt a, Pt b, Pt c) {
Pt res;
double la = abs(b - c);
double lb = abs(a - c);
double lc = abs(a - b);
```

```
res.x = (la * a.x + lb * b.x + lc * c.x) / (la + lb +
lc);
res.y = (la * a.y + lb * b.y + lc * c.y) / (la + lb +
lc);
return res;
}
```

8 Stringology

8.1 KMP

```
vector<int> build_fail(string s) {
   const int len = s.size();
   vector<int> f(len, -1);
   for (int i = 1, p = -1; i < len; i++) {
     while (~p and s[p + 1] != s[i]) p = f[p];
     if (s[p + 1] == s[i]) p++;
     f[i] = p;
   }
   return f;
}</pre>
```

8.2 Z-algorithm

```
vector<int> zalgo(string s) {
   if (s.empty()) return {};
   int len = s.size();
   vector<int> z(len);
   z[0] = len;
   for (int i = 1, l = 1, r = 1; i < len; i++) {
      z[i] = i < r ? min(z[i - l], r - i) : 0;
      while (i + z[i] < len and s[i + z[i]] == s[z[i]]) z
      [i]++;
      if (i + z[i] > r) l = i, r = i + z[i];
   }
   return z;
}
```

8.3 Manacher

```
vector<int> manacher(const string &s) {
   string p = "@#";
   for (char c : s) p += c + '#';
   p += '$';
   vector<int> dp(p.size());
   int mid = 0, r = 1;
   for (int i = 1; i < p.size() - 1; i++) {
      auto &k = dp[i];
      k = i < mid + r ? min(dp[mid * 2 - i], mid + r - i)
            : 0;
      while (p[i + k + 1] == p[i - k - 1]) k++;
      if (i + k > mid + r) mid = i, r = k;
   }
   return vector<int>(dp.begin() + 2, dp.end() - 2);
}
```

8.4 SuffixArray

```
namespace sfx {
#define fup(a, b) for (int i = a; i < b; i++)
#define fdn(a, b) for (int i = b - 1; i >= a; i--)
   constexpr int N = 5e5 + 5;
   bool _t[N * 2];
  int H[N], RA[N], x[N], _p[N];
int SA[N * 2], _s[N * 2], _c[N * 2], _q[N * 2];
void pre(int *sa, int *c, int n, int z) {
     fill_n(sa, n, \acute{0}), copy_n(c, z, x);
   void induce(int *sa, int *c, int *s, bool *t, int n,
     int z) {
     copy_n(c, z - 1, x + 1);
fup(0, n) if (sa[i] and !t[sa[i] - 1])
        sa[x[s[sa[i] - 1]]++] = sa[i] - 1;
     copy_n(c, z, x);
fdn(0, n) if (sa[i] and t[sa[i] - 1])
        sa[--x[s[sa[i] - 1]]] = sa[i] - 1;
   void sais(int *s, int *sa, int *p, int *q, bool *t,
      int *c, int n, int z) {
     bool uniq = t[n - 1] = true;
int nn = 0, nmxz = -1, *nsa = sa + n, *ns = s + n,
      last = -1;
     fill_n(c, z, 0);
fup(0, n) uniq &= ++c[s[i]] < 2;
     partial_sum(c, c + z, c);
```

```
National Central University - __builtin_orz()
     if (uniq) {    fup(0, n) sa[--c[s[i]]] = i;    return;    }
                                                                              fup(0, n) if (sa[i] and t[sa[i]] and !t[sa[i] - 1])
     fdn(0, n-1)
       t[i] = (s[i] == s[i + 1] ? t[i + 1] : s[i] < s[i]
                                                                                bool neq = last < 0 or !equal(s + sa[i], s + p[q[
                                                                              sa[i]] + 1], s + last);
ns[q[last = sa[i]]] = nmxz += neq;
     + 1]);
    pre(sa, c, n, z);
fup(1, n) if (t[i] and !t[i - 1])
     sa[--x[s[i]]] = p[q[i] = nn++] = i;
induce(sa, c, s, t, n, z);
fup(0, n) if (sa[i] and t[sa[i]] and !t[sa[i] - 1])
                                                                              sais(ns, nsa, p + nn, q + n, t + n, c + z, nn, nmxz
                                                                               + 1);
                                                                              pre(sa, c, n, z);
                                                                              fdn(0, nn) sa[--x[s[p[nsa[i]]]] = p[nsa[i]];
       bool neq = last < 0 or !equal(s + sa[i], s + p[q[
                                                                              induce(sa, c, s, t, n, z);
     sa[i]] + 1], s + last);
                                                                            vector<int> build(vector<int> s, int n) {
  copy_n(begin(s), n, _s), _s[n] = 0;
       ns[q[last = sa[i]]] = nmxz += neq;
     sais(ns, nsa, p + nn, q + n, t + n, c + z, nn, nmxz
                                                                              vector<int> sa(n);
      + 1);
     pre(sa, c, n, z);
fdn(0, nn) sa[--x[s[p[nsa[i]]]]] = p[nsa[i]];
                                                                              return sa;
     induce(sa, c, s, t, n, z);
  vector<int> build(vector<int> s, int n) {
                                                                              ) {
     copy_n(begin(s), n, _s), _s[n] = 0;
     sais(_s, SA, _p, _q, _t, _c, n + 1, 256);
vector<int> sa(n);
                                                                              vector<int> rnk(n)
     fup(0, n) sa[i] = SA[i + 1];
     return sa;
                                                                              int h = 0;
                                                                              fup(0, n) {
  vector<int> lcp_array(vector<int> &s, vector<int> &sa
                                                                                if (h > 0) h--;
     ) {
     int n = int(s.size());
     vector<int> rnk(n);
     fup(0, n) rnk[sa[i]] = i;
     vector<int> lcp(n - 1);
     int h = 0;
     fup(0, n) {
                                                                              return lcp;
       if (h > 0) h--;
if (rnk[i] == 0) continue;
                                                                           }
                                                                        }
       int j = sa[rnk[i] - 1];
for (; j + h < n and i + h < n; h++)
  if (s[j + h]! = s[i + h]) break;</pre>
                                                                         struct PAM {
       lcp[rnk[i] - 1] = h;
                                                                            struct Node {
                                                                              int fail, len, dep;
     return lcp;
                                                                              array<int, 26> ch;
}
8.5 SimpleSuffixArray
                                                                           vector<Node> g;
namespace sfx {
                                                                            vector<int> id;
                                                                            int odd, even, lst;
#define fup(a, b) for (int i = a; i < b; i++)
#define fdn(a, b) for (int i = b' - 1; i' >= a; i--)
                                                                            string S;
  constexpr int N = 5e5 + 5;
                                                                              g.emplace_back(len);
  bool _t[N * 2];
  int H[N], RA[N], x[N], _p[N];
int SA[N * 2], _s[N * 2], _c[N * 2], _q[N * 2];
void pre(int *sa, int *c, int n, int z) {
                                                                              return g.size() - 1;
     fill_n(sa, n, \acute{0}), copy_n(c, z, x);
                                                                            int up(int p) {
  void induce(int *sa, int *c, int *s, bool *t, int n,
     int z) {
    copy_n(c, z - 1, x + 1);
fup(0, n) if (sa[i] and !t[sa[i] - 1])
  sa[x[s[sa[i] - 1]]++] = sa[i] - 1;
                                                                                p = g[p].fail;
                                                                              return p;
                                                                            int add(char c) {
     copy_n(c, z, x);
fdn(0, n) if (sa[i] and t[sa[i] - 1])
                                                                              S += c;
                                                                              lst = up(lst);
c -= 'a';
       sa[--x[s[sa[i] - 1]]] = sa[i] - 1;
  void sais(int *s, int *sa, int *p, int *q, bool *t,
   int *c, int n, int z) {
   bool uniq = t[n - 1] = true;
```

int nn = 0, nmxz = -1, *nsa = sa + n, *ns = s + n,

partial_sum(c, c + z, c);
if (uniq) { fup(0, n) sa[--c[s[i]]] = i; return; }

fdn(0, n - 1) t[i] = (s[i] == s[i + 1] ? t[i + 1] : s[i] < s[i]

last = -1;

+ 1]);

fill_n(c, z, 0);

fup(0, n) uniq &= ++c[s[i]] < 2;

pre(sa, c, n, z);
fup(1, n) if (t[i] and !t[i - 1])
 sa[--x[s[i]]] = p[q[i] = nn++] = i;

induce(sa, c, s, t, n, z);

```
sais(_s, SA, _p, _q, _t, _c, n + 1, 256);
     fup(0, n) sa[i] = SA[i + 1];
  vector<int> lcp_array(vector<int> &s, vector<int> &sa
     int n = int(s.size());
     fup(0, n) rnk[sa[i]] = i;
     vector<int> lcp(n - 1);
       if (rnk[i] == 0) continue;
       int j = sa[rnk[i] - 1];
for (; j + h < n and i + h < n; h++)</pre>
        if (s[j + h] != s[i + h]) break;
       lcp[rnk[i] - 1] = h;
8.6 PalindromicTree
    Node(int _len) : len{_len}, fail{}, ch{}, dep{} {};
  int new_node(int len) {
  PAM() : odd(new_node(-1)), even(new_node(0)) {
    lst = g[even].fail = odd;
    while (S.rbegin()[g[p].len + 1] != S.back())
     if (!g[lst].ch[c]) g[lst].ch[c] = new_node(g[lst].
     int p = g[lst].ch[c];
     g[p].fail = (lst == odd ? even : g[up(g[lst].fail)]
     ].ch[c]);
     lst = p;
     g[lst].dep = g[g[lst].fail].dep + 1;
     id.push_back(lst);
    return lst;
  void del() {
     S.pop_back();
     id.pop_back();
     lst = id.empty() ? odd : id.back();
};
```

8.7 SmallestRotation

```
string Rotate(const string &s) {
  int n = s.length();
  string t = s + s;
  int i = 0, j = 1;
  while (i < n && j < n) {
    int k = 0;
    while (k < n && t[i + k] == t[j + k]) ++k;
    if (t[i + k] <= t[j + k]) j += k + 1;
    else i += k + 1;
    if (i == j) ++j;
  }
  int pos = (i < n ? i : j);
  return t.substr(pos, n);
}</pre>
```

9 Misc

9.1 HilbertCurve

```
long long hilbert(int n, int x, int y) {
  long long res = 0;
  for (int s = n / 2; s; s >>= 1) {
    int rx = (x & s) > 0;
    int ry = (y & s) > 0;
    res += s * 1ll * s * ((3 * rx) ^ ry);
    if (ry == 0) {
        if (rx == 1) x = s - 1 - x, y = s - 1 - y;
        swap(x, y);
    }
    return res;
}
```

9.2 DLX

```
namespace dlx {
int lt[maxn], rg[maxn], up[maxn], dn[maxn], cl[maxn],
     rw[maxn], bt[maxn], s[maxn], head, sz, ans;
void init(int c) {
  for (int i = 0; i < c; ++i) {</pre>
  up[i] = dn[i] = bt[i] = i;
lt[i] = i == 0 ? c : i - 1;
rg[i] = i == c - 1 ? c : i + 1;
  s[i] = 0;
 rg[c] = 0, lt[c] = c - 1;
 up[c] = dn[c] = -1;
head = c, sz = c + 1;
void insert(int r, const vector<int> &col) {
 if (col.empty()) return;
 int f = sz;
for (int i = 0; i < (int)col.size(); ++i) {</pre>
  int c = col[i], v = sz++;
  dn[bt[c]] = v;
up[v] = bt[c], bt[c] = v;
  rg[v] = (i + 1 == (int)col.size() ? f : v + 1);
  rw[v] = r, cl[v] = c;
  ++s[c];
  if (i > 0) lt[v] = v - 1;
 lt[f] = sz - 1;
void remove(int c) {
lt[rg[c]] = lt[c], rg[lt[c]] = rg[c];
for (int i = dn[c]; i != c; i = dn[i]) {
   for (int j = rg[i]; j != i; j = rg[j])
   up[dn[j]] = up[j], dn[up[j]] = dn[j], --s[cl[j]];
++s[cl[j]], up[dn[j]] = j, dn[up[j]] = j;
 lt[rg[c]] = c, rg[lt[c]] = c;
// Call dlx::make after inserting all rows.
void make(int c) {
for (int i = 0; i < c; ++i)
  dn[bt[i]] = i, up[i] = bt[i];
```

```
14
void dfs(int dep) {
 if (dep >= ans) return;
 if (rg[head] == head) return ans = dep, void();
 if (dn[rg[head]] == rg[head]) return;
 int c = rg[head];
 int w = c;
 for (int x = c; x != head; x = rg[x]) if (s[x] < s[w])
      W = X;
 remove(w);
for (int i = dn[w]; i != w; i = dn[i]) {
  for (int j = rg[i]; j != i; j = rg[j]) remove(cl[j]);
  dfs(dep + 1);
  for (int j = lt[i]; j != i; j = lt[j]) restore(cl[j])
 restore(w);
int solve() {
 ans = 1e9, dfs(0);
 return ans;
}}
9.3 NextPerm
i64 next_perm(i64 x) \{
  i64 y = x | (x - 1)
  return (y + 1) | (((~y & -~y) - 1) >> (__builtin_ctz(
     x) + 1));
9.4 FastIO
struct FastI0 {
  const static int ibufsiz = 4<<20, obufsiz = 18<<20;</pre>
  char ibuf[ibufsiz], *ipos = ibuf, obuf[obufsiz],
  FastIO() { fread(ibuf, 1, ibufsiz, stdin); }
~FastIO() { fwrite(obuf, 1, opos - obuf, stdout); }
  template<class T> FastIO& operator>>(T &x) {
     bool sign = 0; while (!isdigit(*ipos)) { if (*ipos
     == '-') sign = 1; ++ipos; }
     x = *ipos++ & 15;
     while (isdigit(*ipos)) x = x * 10 + (*ipos++ & 15);
     if (sign) x = -x;
     return *this;
  template<class T> FastIO& operator<<(T n) {</pre>
     static char _buf[18];
     char* _pos = _buf;
     if (n < 0) *opos++ = '-', n = -n;
do *_pos++ = '0' + n % 10; while (n /= 10);
     while (_pos != _buf) *opos++ = *--_pos;
     return *this:
  FastIO& operator<<(char ch) { *opos++ = ch; return *
     this; }
} FIO;
#define cin FIO
#define cout FIO
9.5 Python FastIO
import sys
sys.stdin.readline()
sys.stdout.write()
9.6 trick
dp[61][0][0][0][7] = 1;
for (int h = 60; h >= 0; h--) {
  int s = (n >> h & 1) * 7;
  for (int x = 0; x < 8; x++) if (__builtin_parity(x)
     == 0) {
     for (int y = 0; y < 8; y++)
if (((y & ~s) & x) == 0) {
          for (int a = 0; a < A[0]; a++)
            for (int u = 0, u < A[0], u++)

for (int b = 0; b < A[1]; b++)

for (int c = 0; c < A[2]; c++) {
   if (dp[h + 1][a][b][c][y] == 0) continue;
   i64 i = ((x >> 2 & 1LL) << h) % A[0];
   i64 j = ((x >> 1 & 1LL) << h) % A[1];
```

i64 k = ((x >> 0 & 1LL) << h) % A[2];

dp[h][(i + a) % A[0]][(j + b) % A[1]][(k

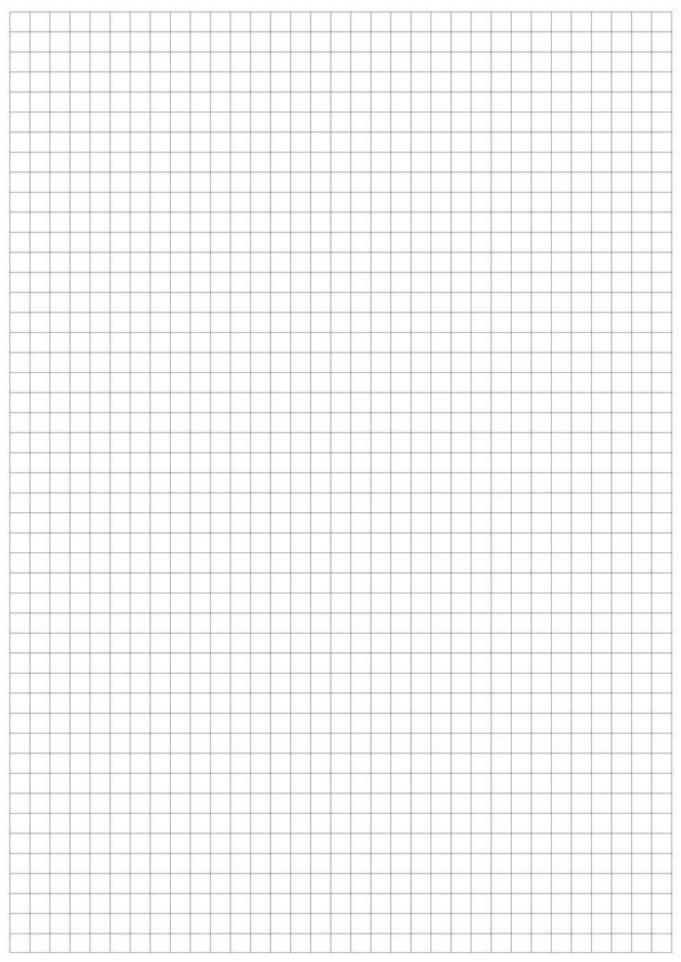
auto &val =

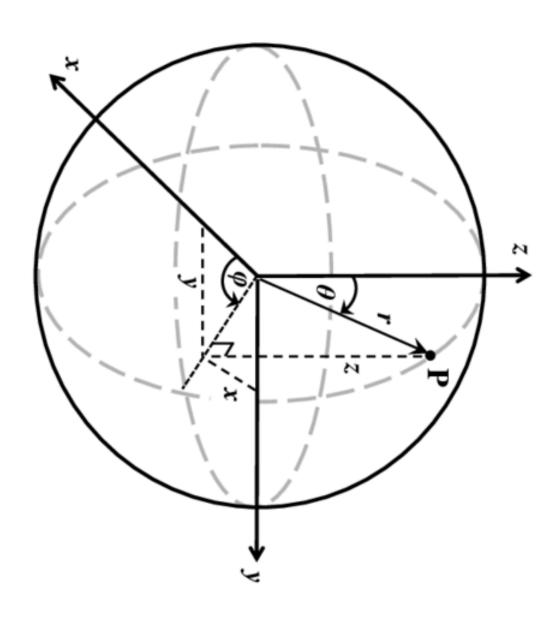
+ c) % A[2][y & \sim (s \wedge x)];

```
val = add(val, dp[h + 1][a][b][c][y]);
}
}

pair<i64, i64> Split(i64 x) {
    if (x == 1) return {0, 0};
    i64 h = __lg(x);
    i64 fill = (1LL << (h + 1)) - 1;
    i64 l = (1LL << h) - 1 - max(0LL, fill - x - (1LL << (h - 1)));
    i64 r = x - 1 - l;
    return {1, r};
};

auto [ls, l] = DP(lo);
    auto [rs, r] = DP(hi);
    if (r < K) {
        cout << "Impossible\n";
        return;
    }
    if (l == K) cout << ls << '\n';
    else if (r == K) cout << rs << '\n';
    else {
        cout << (ls * (r - K) + rs * (K - l)) / (r - l) << '\n';
    }
}</pre>
```





$$\varphi = tan^{-1}(y/x)$$

 $\theta = \cos^{-1}(z/r)$

$$r = \sqrt{x^2 + y^2 + z^2}$$

$$z = r \cos \theta$$

$$y = r \sin \theta \sin \varphi$$

 $x = r \sin \theta \cos \phi$