DLfuse: Distributed Lag Data Fusion for Estimating Ambient Air **Pollution**

DLfuse Statistical Model

$$Y(\mathbf{s}_{ij}) = \widetilde{\boldsymbol{\beta}}_{0}(\mathbf{s}_{ij}) + \widetilde{\boldsymbol{\beta}}_{1}(\mathbf{s}_{ij}) \sum_{l=0}^{L} \bar{\mathbf{x}}_{B_{i},l} \left(\frac{\pi_{B_{i},l}}{\sum_{k=0}^{L} \pi_{B_{i},k}} \right) + \epsilon(\mathbf{s}_{ij}), \ \epsilon(\mathbf{s}_{ij}) | \sigma_{\epsilon}^{2} \stackrel{\text{iid}}{\sim} \mathrm{N}\left(0, \sigma_{\epsilon}^{2}\right);$$

$$\pi_{B_{i},l} = \Phi\left(\mu + \alpha_{B_{i}}\right)^{l}, \ l = 0, ..., L;$$

$$\alpha_{B_{i}} | \boldsymbol{\alpha}_{-B_{i}}, \tau^{2} \stackrel{\text{ind}}{\sim} \mathrm{N}\left(\frac{\sum_{j=1}^{m} w_{ij} \alpha_{B_{j}}}{\sum_{j=1}^{m} w_{ij}}, \frac{\tau^{2}}{\sum_{j=1}^{m} w_{ij}}\right), \ i = 1, ..., m;$$

$$\widetilde{\boldsymbol{\beta}}_{k}(\mathbf{s}_{ij}) = \boldsymbol{\beta}_{k} + \boldsymbol{\beta}_{k}(\mathbf{s}_{ij}), \ k = 0, 1;$$

$$\begin{pmatrix} \boldsymbol{\beta}_{0}(\mathbf{s}_{ij}) \\ \boldsymbol{\beta}_{1}(\mathbf{s}_{ij}) \end{pmatrix} = A\begin{pmatrix} \boldsymbol{w}_{0}(\mathbf{s}_{ij}) \\ \boldsymbol{w}_{1}(\mathbf{s}_{ij}) \end{pmatrix}; \ A = \begin{pmatrix} A_{11} & 0 \\ A_{21} & A_{22} \end{pmatrix};$$

$$\boldsymbol{w}_{k} = \{\boldsymbol{w}_{k}(\mathbf{s}_{11}), ..., \boldsymbol{w}_{k}(\mathbf{s}_{mn_{m}})\}^{\mathrm{T}} | \boldsymbol{\phi}_{k} \stackrel{\mathrm{ind}}{\sim} \mathrm{MVN}\left\{0, \boldsymbol{\Sigma}_{k}(\boldsymbol{\phi}_{k})\right\}, \ k = 0, 1;$$

$$Corr \{\boldsymbol{w}_{k}(\mathbf{s}_{k}), \boldsymbol{w}_{k}(\mathbf{s}_{k})\}, \ \boldsymbol{w}_{k}(\mathbf{s}_{k})\} = \exp\left\{-\boldsymbol{\phi}_{k} | | \mathbf{s}_{k} - \mathbf{s}_{k} | \mathbf{s}_{k}$$

$$\operatorname{Corr} \left\{ w_k \left(\mathbf{s}_{ij} \right), w_k \left(\mathbf{s}_{i'j'} \right) \right\} = \exp \left\{ -\phi_k ||\mathbf{s}_{ij} - \mathbf{s}_{i'j'}|| \right\};$$

- i = 1,, m;
- $j = 1, ..., n_i$

Prior Information

$$\beta_k \stackrel{\text{iid}}{\sim} \mathcal{N}\left(0, \sigma_\beta^2\right), \ k = 0, 1;$$

• Default setting: $\sigma_{\beta}^2 = 10,000$.

 $\sigma_{\epsilon}^2 \sim \text{Inverse Gamma}\left(a_{\sigma_{\epsilon}^2}, b_{\sigma_{\epsilon}^2}\right);$

• Default setting: $a_{\sigma_a^2} = 0.01, b_{\sigma_a^2} = 0.01.$

 $\tau^2 \sim \text{Inverse Gamma}(a_{\tau^2}, b_{\tau^2});$

• Default setting: $a_{\sigma_a^2} = 3$, $b_{\sigma_a^2} = 2$.

 $\ln (A_{11}), \ln (A_{22}), A_{21} \stackrel{\text{iid}}{\sim} N (0, \sigma_A^2);$

• Default setting: $\sigma_A^2 = 1$.

 $\mu \sim N(0,1)$;

 $\phi_k \stackrel{\text{iid}}{\sim} \text{Gamma}(\alpha_{\phi_k}, \beta_{\phi_k}), \ k = 0, 1,$

• Default setting: $a_{\phi_k} = 1$, $b_{\phi_k} = 1$.

Default Initial Values

- $\beta_k = 0$ for all k;
- $\sigma_{\epsilon}^2 = 1$;
- $A_{11} = A_{22} = 1, \ A_{21} = 0;$
- $\mu = 0;$
- $\alpha_{B_i} = 0$ for all i;
- $\tau^2 = 1;$
- $w_k(\mathbf{s}_{ij}) = 0$ for all k, i, j;
- $\phi_k = -\ln(0.05) / \max\{||\mathbf{s}_{ij} \mathbf{s}_{i'j'}||\}$ for all k.