

DLfuse: Distributed Lag Data Fusion for Estimating Ambient Air Pollution

DLfuse Statistical Model

$$Y(\mathbf{s}_{ij}) = \tilde{\beta}_0(\mathbf{s}_{ij}) + \tilde{\beta}_1(\mathbf{s}_{ij}) \sum_{l=0}^L \bar{x}_{B_i,l} \left(\frac{\pi_{B_i,l}}{\sum_{k=0}^L \pi_{B_i,k}} \right) + \epsilon(\mathbf{s}_{ij}), \quad \epsilon(\mathbf{s}_{ij}) | \sigma_\epsilon^2 \stackrel{\text{iid}}{\sim} \text{N}(0, \sigma_\epsilon^2);$$

Probit Weights:

$$\pi_{B_i,l} = \Phi(\mu + \alpha_{B_i})^l, \quad l = 0, \dots, L;$$

Spherical Weights:

$$\pi_{B_i,l} = \left\{ 1.00 - 1.50 \left(\frac{l}{\exp\{\mu + \alpha_{B_i}\}} \right) + 0.50 \left(\frac{l}{\exp\{\mu + \alpha_{B_i}\}} \right)^3 \right\} 1(l < \exp\{\mu + \alpha_{B_i}\}), \quad l = 0, \dots, L;$$

$$\alpha_{B_i} | \boldsymbol{\alpha}_{-B_i}, \tau^2 \stackrel{\text{ind}}{\sim} \text{N} \left(\frac{\sum_{j=1}^m w_{ij} \alpha_{B_j}}{\sum_{j=1}^m w_{ij}}, \frac{\tau^2}{\sum_{j=1}^m w_{ij}} \right), \quad i = 1, \dots, m;$$

$$\tilde{\beta}_k(\mathbf{s}_{ij}) = \beta_k + \beta_k(\mathbf{s}_{ij}), \quad k = 0, 1;$$

$$\begin{pmatrix} \beta_0(\mathbf{s}_{ij}) \\ \beta_1(\mathbf{s}_{ij}) \end{pmatrix} = A \begin{pmatrix} w_0(\mathbf{s}_{ij}) \\ w_1(\mathbf{s}_{ij}) \end{pmatrix}; \quad A = \begin{pmatrix} A_{11} & 0 \\ A_{21} & A_{22} \end{pmatrix};$$

$$\mathbf{w}_k = \{w_k(\mathbf{s}_{11}), \dots, w_k(\mathbf{s}_{mn_m})\}^T | \phi_k \stackrel{\text{ind}}{\sim} \text{MVN}\{0, \Sigma_k(\phi_k)\}, \quad k = 0, 1;$$

$$\text{Corr}\{w_k(\mathbf{s}_{ij}), w_k(\mathbf{s}_{i'j'})\} = \exp\{-\phi_k \|\mathbf{s}_{ij} - \mathbf{s}_{i'j'}\|\};$$

- $i = 1, \dots, m;$
- $j = 1, \dots, n_i$

Prior Information

$$\beta_k \stackrel{\text{iid}}{\sim} \text{N}(0, \sigma_\beta^2), \quad k = 0, 1;$$

- Default setting: $\sigma_\beta^2 = 10,000$.

$$\sigma_\epsilon^2 \sim \text{Inverse Gamma}(a_{\sigma_\epsilon^2}, b_{\sigma_\epsilon^2});$$

- Default setting: $a_{\sigma_\epsilon^2} = 0.01, b_{\sigma_\epsilon^2} = 0.01$.

$$\tau^2 \sim \text{Inverse Gamma}(a_{\tau^2}, b_{\tau^2});$$

- Default setting: $a_{\tau^2} = 3, b_{\tau^2} = 2$.

$$\ln(A_{11}), \ln(A_{22}), A_{21} \stackrel{\text{iid}}{\sim} \text{N}(0, \sigma_A^2);$$

- Default setting: $\sigma_A^2 = 1$.

$$\mu \sim \text{N}(0, 1);$$

$$\phi_k \stackrel{\text{iid}}{\sim} \text{Gamma}(\alpha_{\phi_k}, \beta_{\phi_k}), \quad k = 0, 1,$$

- Default setting: $a_{\phi_k} = 1, b_{\phi_k} = 1$.

Default Initial Values

- $\beta_k = 0$ for all k ;
- $\sigma_\epsilon^2 = 1$;
- $A_{11} = A_{22} = 1, A_{21} = 0$;
- $\mu = 0$;
- $\alpha_{B_i} = 0$ for all i ;
- $\tau^2 = 1$;
- $w_k(\mathbf{s}_{ij}) = 0$ for all k, i, j ;
- $\phi_k = -\ln(0.05) / \max\{||\mathbf{s}_{ij} - \mathbf{s}_{i'j'}||\}$ for all k .