

# KSBound: Kernel Stick-Breaking Prior Distribution for Spatial Boundary Detection

## Statistical Model

$$Y_i | E_i, \lambda_i \stackrel{\text{ind}}{\sim} \text{Poisson}(E_i \lambda_i), \ln(\lambda_i) = \mathbf{x}_i^T \boldsymbol{\beta} + \eta_i, \quad i = 1, \dots, n;$$

$$\eta_i | \mathbf{p}_i, \boldsymbol{\theta} \stackrel{\text{ind}}{\sim} G_i, \quad G_i(\cdot) \stackrel{d}{=} \sum_{j=1}^{\infty} p_{ij} \delta_{\theta_j}(\cdot), \quad i = 1, \dots, n;$$

$$p_{i1} = w_{i1} V_1, \quad p_{ij} = w_{ij} V_j \prod_{k=1}^{j-1} (1 - w_{ik} V_k) \quad \text{for } j \geq 2;$$

- $V_k | \alpha \stackrel{\text{iid}}{\sim} \text{Beta}(1, \alpha);$
- $\theta_j | \sigma_\theta^2 \stackrel{\text{iid}}{\sim} N(0, \sigma_\theta^2);$

$$w_{ij} = 1 \left( R_i \in \partial_{R_{\psi_j}} \right), \quad \partial_{R_{\psi_j}} = \{R_{\psi_j}\} \cup \{R_k : R_k \text{ and } R_{\psi_j} \text{ are neighbors}\},$$

$$\psi_j \stackrel{\text{iid}}{\sim} \text{Discrete Uniform } \{1, n\}.$$

## Prior Information

$$\beta_j \stackrel{\text{iid}}{\sim} N(0, \sigma_\beta^2), \quad j = 1, \dots, p;$$

- $p$ : Length of  $\mathbf{x}_i$  vector (same for all  $i$ );
- Default setting:  $\sigma_\beta^2 = 10,000$ .

$$\sigma_\theta^2 \sim \text{Inverse Gamma}(a_{\sigma_\theta^2}, b_{\sigma_\theta^2});$$

- Default setting:  $a_{\sigma_\theta^2} = 0.01, b_{\sigma_\theta^2} = 0.01$ .

$$\alpha \sim \text{Gamma}(a_\alpha, b_\alpha);$$

- Default setting:  $a_\alpha = 0.01, b_\alpha = 0.01$ .

## Default Initial Values

- $\beta_j = 0$  for all  $j$ ;
- $\theta_j = 0$  for all  $j$ ;
- $\sigma_\theta^2 = 1.00$ ;
- $\alpha = 1.00$ ;
- $V_j = 0.99$  for all  $j$ ;
- $\psi_j = j$  for all  $j$ .

## Alternate Likelihood: Binomial

$$Y_i | \boldsymbol{\beta}, \eta_i, r \stackrel{\text{ind}}{\sim} \text{Binomial}\{c_i, p_i(\boldsymbol{\beta}, \eta_i)\}, \quad i = 1, \dots, n;$$

$$\ln \left\{ \frac{p_i(\boldsymbol{\beta}, \eta_i)}{1 - p_i(\boldsymbol{\beta}, \eta_i)} \right\} = \mathbf{x}_i^T \boldsymbol{\beta} + \eta_i.$$

### Alternate Likelihood: Gaussian

$Y_i | \beta, \eta_i, \sigma_\epsilon^2 \stackrel{\text{ind}}{\sim} \text{Normal}(\mathbf{x}_i^T \beta + \eta_i, \sigma_\epsilon^2), \quad i = 1, \dots, n.$

- $\sigma_\epsilon^2 \sim \text{Inverse Gamma}(a_{\sigma_\epsilon^2}, b_{\sigma_\epsilon^2})$ ;
- Default setting:  $a_{\sigma_\epsilon^2} = 0.01, b_{\sigma_\epsilon^2} = 0.01$ ;
- Default initial value:  $\sigma_\epsilon^2 = \text{variance}(\mathbf{Y})$ .

### Alternate Likelihood: Negative Binomial

$Y_i | \beta, \eta_i, r \stackrel{\text{ind}}{\sim} \text{Negative Binomial}\{r, \lambda_i(\beta, \eta_i)\}, \quad i = 1, \dots, n;$

$\ln \left\{ \frac{\lambda_i(\beta, \eta_i)}{1 - \lambda_i(\beta, \eta_i)} \right\} = \ln(E_i) + \mathbf{x}_i^T \beta + \eta_i.$

- $r \sim \text{Discrete Uniform}[a_r, b_r]$ ;
- Default setting:  $a_r = 1, b_r = 100$ ;
- Default initial value:  $r = b_r$ .

### Likelihood Indicator

- likelihood\_indicator = 0: Poisson;
- likelihood\_indicator = 1: Binomial;
- likelihood\_indicator = 2: Gaussian;
- likelihood\_indicator = 3: Negative binomial.