

# CNN for plot function detection

Applied Machine Learning Group Project

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### 1 Introduction

The aim of this project is to design a machine learning model able to recognize a mathematical function from its graph. This is showed in Fig. 1.

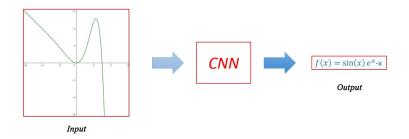


Figure 1: Final result to achieve

This problem can be approached as an image classification task. A common method for solving this type of problem is to use Convolutional Neural Networks (CNN).

#### 2 Data Generation

Neural Networks models need a large amount of training data. The first challenge was to retrieve that data.

For this project we developed an algorithm to generate and classify data, since no graph function datasets were available. This algorithm allowed to retrieve an arbitrary large amount of data. It is described in the following section.

#### 2.1 Algorithm

The algorithm is based on two main groups. A list of basic functions and a list of binary operators to combine them. They are shown in table 1.

Basic functions1
$$\exp(x)$$
 $\sin(x)$  $x^2$  $\tan(x)$  $\log(x)$  $|x|$  $a$  $x$ Basic operators $a+b$  $a-b$  $a \cdot b$  $\frac{a}{b}$  $a^b$ 

Table 1: Basic functions and binary operators

The idea is to choose random basic functions and combine them with some operators. Since this could lead to infinite possibilities it was necessary to do some design choices.

#### Representation

The functions are represented as Computational Graphs. Fig. 2 gives an example of such a representation. It refers to the function  $f(x) = \sin(x) \cdot e^x - x$  of Fig. 1.

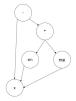


Figure 2: Computational graph example

#### Simplifications

The first simplification is referred to the maximum number of children at each node, which is two. The result is a binary graph.

The second simplification is the graph depth. This limits the possible number of functions that can be generated. It is kept less or equal to three. The depth is directly proportional to the function's complexity. Here are some examples for different complexity levels.

Complexity level 1 | Complexity level 2 | Complexity level 3 | 
$$f(x) = \sin(x) + x$$
 |  $f(x) = \tan(\sin(x) + x)$  |  $f(x) = \tan(\sin(x) + x)x^2$ 

Table 2: Complexity Levels

#### Generation

The generation is made with different levels. More precisely, 10% is depth 1, 30% depth 2 and 60% depth 3. The precentage is proportional to the number of possible resulting functions.

Two datasets are generated, a reduced one with 2000 samples to do preliminary training and a larger one with 50000 samples.

#### Adjustments

Some further adjustments were made to the algorithm in order to get better datasets. The first problem was the huge presence of constant functions, e.g. a function like  $f(x) = \sin(x) - \sin(x)$ . These simple solutions were filtered out.

An different problem was given by equivalent representations, e.g. f(x) = x + x and f(x) = 2x. They are the same functions with different representation. This could lead to model confusion. Also these functions are strongly reduced, but not deleted.

#### 2.2 Plots

The mathematical functions are always evaluated in the interval  $x \in [-8, 8]$ , the y-axis is automatically scaled, so that relevant data are not cut off. Each image is saved with a fixed size (250 x 100 pixel). The axes, as well as the grid, are removed, since it's not useful for the classification. An actual input to the CNN of a function randomly selected from the dataset  $f(x) = \sin(x) + |x|$  is shown in Fig. 3.

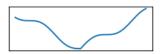


Figure 3: Generated image example

#### 2.3 Labeling

In order to be able to classify the images by means of CNN, it is necessary to label them correctly. The solution chosen is based on the Polish notation. First of all, a numerical value is assigned to each basic function and each basic operator to encode the mathematical functions as vectors.

A new operator is introduced and it's the one with code 6. This operator represents the function application, e.g. "6, 12, 9" means "application of function 12 to function 9". Here 12 stands for  $\log(x)$  and 9 for  $\sin(x)$ , so it translates into " $\log(\sin(x))$ ".

a + b	a-b	$\frac{a}{b}$	$a \cdot b$	$a^b$	a	x	1	$\exp(x)$	$\sin(x)$	$x^2$	$\tan(x)$	$\log(x)$	x
0	1	2	3	4	5	6	7	8	9	10	11	12	13

Table 3: Labeling of vector elements

With this choices, each vector has a maximum length of 15, which is reached with a full binary graph of depth 3. Each entry of the vector can have a number between 0 and 13 corresponing to table 3. Functions with less entries are padded. This is given by sequences of 6 and 7 towards the end of the vector. This does not change the actual function. Thereby it is reached that all vectors posses 15 entries. The following is an example of such a labeling.  $f(x) = \sin(x) + |x| \Rightarrow x, 1, x, 1, x, 1, x, 1, x, 1, +, \sin(x), |x|$ 

$$\Rightarrow$$
 (13, 9, 0, 7, 6, 7, 6, 7, 6, 7, 6, 7, 6, 7, 6)

However, from the data generation it was noticed that the maximum length was never achieved, adding some useless cells. For this reason the output dimension is detected dynamically during the generation and saved in the file at the end.

#### 3 CNN model

#### 3.1 Architecture

As stated at the beginning, a CNN is used. The architecture of the network is showed in Figure 4.

There is a first convulutional part, formed by three sets of  $CON \Rightarrow RELU \Rightarrow MaxPool$ . The second part is the classification, given by three fully connected layers activated by RELU.

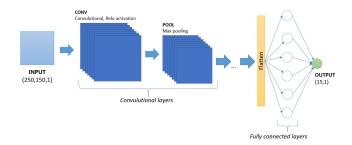


Figure 4: CNN's basic architecture.

### 3.2 Implementation

The implementation of this CNN is made in Python using the framework PyTorch. The definition is showed in the following code.

```
Conv2d(numChannels, 16, kernel size=2, padding=1),
 \begin{smallmatrix}2&3&4&5&6\\7&8&9\end{smallmatrix}
                               ReLU(),
                               MaxPool2d(2, 2),
                               {\tt Conv2d\,(16\,,\ 32\,,\ kernel\_size=2\,,\ padding=1)\,,}
                               ReLU(),
                               MaxPool2d(2, 2),
                               \operatorname{Conv2d}(32, 64, \ker \operatorname{nel}_{\operatorname{size}} = 2, \operatorname{padding} = 0),
                               MaxPool2d(2, 2),
10
11
                               Flatten(),
12
                               Linear (23808, 1012),
13
                               ReLU(),
14
                               Linear (1012, 512),
15
                              ReLU(),
16
                               {\tt Linear}\,(5\,1\,2\,,\ {\tt output\_size}\,)
```

## 4 Data Processing & Training

#### 4.1 Data Processing

Before training the model, the images are converted from 4-channel to grey scale. The main reason is to make the training process faster. The labels are also scaled by a factor of 1000000, to get more margin between each code value.

#### 4.2 Training

The training is done by splitting the dataset into 70% for train set, 15% validation and 15% test. The training execution was GPU-based on Google Colab.

A first training was done on the smaller data set consisting of 2000 images, to get a first look on the performances and change the model parameters to achieve the best performances with the model used. After this preliminary tunings it was used the full dataset of 50000 samples. The loss for each epoch is showed in figure 5.

The validation loss was used to tune the hyperparameters, that are learning rate, number of epochs and batch size. The best emerged values are learning rate 0.001, 10 epochs and batch size 500.

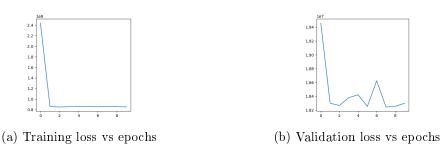


Figure 5: Loss vs epochs

### 5 Experimental Results

From the obtained model, the accuracy is 0.3% for both training and validation data. The performances are very poor, but doing more analysis it can be seen that the performances increases a lot comparing sub-vectors. More precisely, the comparison is made for all components except the first  $n_{shift}$  entries, that could be considered less relevant, since more deeper in the computational graph.

This was done on test data, with output size 7, that were never used before, obtaining the values in table 4. It's possible to see that the network learned how to classify images except the first two entries.

$\overline{n_{shift}}$	0	2	4
Accuracy	0.4%	25.89%	86.41%

Table 4: Accuracy vs shift comparison

After a review of the work done, two main candidate reasons came out:

- 1. Image representation: The main problem is the presence of different ways to express the same mathematical function that are not managed yet, e.g.  $f(x) = \log(e^x)$  and f(x) = x are equivalent but with different encoding.
- 2. Not suitable CNN architecture, that does not allow to achieve low training loss. Different architecture should be explored.
- 3. Regression approach: The problem is basically a classification task, but, due to the hight number of possible classes, a regression approach was done in order to overcome that limit. This was a first approach, but with different approaches it might be possible to imporove significantly.

# 6 Conclusions

The general idea of this project has demonstrated to work, with still significant limits. Furthermore, for computational resources, the dataset size is kept low with respect to the number of possible classes. Ongoing work could focus on the limits presented in the previous section, but the model demonestrated some learning capabilities.