# Design and Performance User Manual



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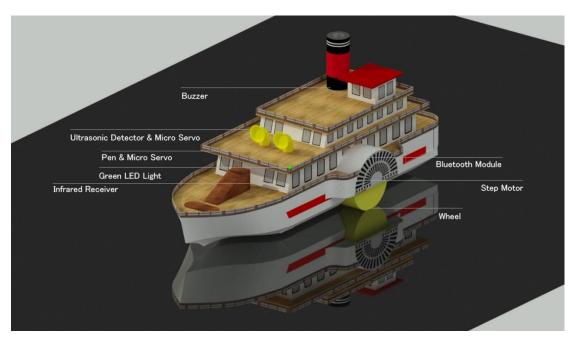
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# **Included in the Package**



- A ship-shaped drawing robot.
- Two 3.7V rechargeable batteries.
- A battery charger.
- An infrared remote controller.

# **Description of Parts**



Parts	Function	
Green LED light	Show operation state via lighting and	
	twinkling	
Ultrasonic detector	Measure distance	
Step motor	Spin two wheels	
Wheel	Control the robot movement	
Buzzer	Play music and warn	
Bluetooth module	Transmit and receive the Bluetooth signal	
Infrared receiver	Receiver the infrared signal	
Micro servo	Control the pen	
Pen	Draw the diagram you want	

Table 1

#### How to Use

#### Enter into Infrared Remote Control Mode

- 1. Install two batteries.
- 2. Press the corresponding key in infrared remote controller towards infrared receiver according to keyboard functions table.
- 3. If two wheels are rotating or the robot is playing music, the green LED light will keep lighting.
- 4. If two wheels stop, the green LED light will twinkle once.
- 5. If the robot enters into Bluetooth mode, the green LED light will twinkle twice.
- 6. If the robot enters into ultrasonic obstacle avoidance mode, the green LED light will twinkle three times.
- 7. If infrared receiver receives the wrong signal, the buzzer will warn.
- 8. Keyboard Functions Table

	Key	Function
Draw a diagram	1	Draw a triangle
	2	Draw a circle
	3	Draw a square
	4	Draw a rectangle
Play music	5	Play a song
User custom drawing	<b>A</b>	Walk forward
	▼	Walk backward
	•	Turn left
	<b>&gt;</b>	Turn right
	OK	Stop
	7	Lift the pen
	8	Put down the pen
Switch mode	*	Enter into Bluetooth mode
	#	Enter into ultrasonic
		obstacle avoidance mode

Table 2

#### Enter into Bluetooth Mode

- 1. Ensure that you are already in infrared remote control mode.
- 2. Press \* key to switch to Bluetooth mode.
- 3. If you can see the green LED light twinkle twice, you are in Bluetooth mode.
- 4. Download a Bluetooth software on your device.
- 5. Open Bluetooth on your device and search the robot Bluetooth named HC06, the default password is 0000.

- 6. After successfully connecting to Bluetooth, enter the appropriate letter in the dialog window or press appropriate key according to the Bluetooth functions table.
- 7. You will receive a response after every instruction.
- 8. Bluetooth Functions Table

	Key	Function
Draw a diagram	Т	Draw a triangle
	С	Draw a circle
	Z	Draw a square
	J	Draw a rectangle
Play music	М	Play a song
User custom drawing	W	Walk forward
	В	Walk backward
	L	Turn left
	R	Turn right
	S	Stop
	Q	Lift the pen
	D	Put down the pen
Switch mode	U	Enter into ultrasonic
		obstacle avoidance mode
Exit	Е	Exit Bluetooth mode and
		back to infrared remote
		control mode

Table 3

#### Enter into Ultrasonic Obstacle Avoidance Mode

- 1. You can enter into this mode via infrared remote control mode or Bluetooth mode.
- 2. Robot in this mode can automatically avoid obstacles to walk.
- 3. This mode doesn't support music.

### **Additional Function**

- 1. User custom drawing.
- 2. Support Bluetooth mode.
- 3. Realize ultrasonic obstacle avoidance.
- 4. Play music.

## **Troubleshooting**

Issue	Possible Problem	Solution	
Wheel doesn't rotate.	Something wrong with the	Check that the stepper	
	connection.	motor and the wheel are	
		connected correctly	
Infrared remote control	The power of controller is	Charge the battery fully.	
doesn't work.	running out.		
	Something wrong with the	Check the receiver	
	receiver connection.	connection.	
Green LED light doesn't	Something wrong with the	Check the connection.	
work.	connection or the light is	If the connection is correct,	
	burned out.	change a light.	

Table 4

## **Specification**

Item	Description
Operation Temperature	-20°C~50°C
Dimension	37.5cm×13cm×26.5cm
Operating Voltage	7.4V

Table 5

## **Cautions**

- 1. **DO NOT** repair or disassemble it by yourself.
- 2. **DO NOT** be near water and fire.
- 3. **DO NOT** drop it.
- 4. **DO NOT** put it in high voltage circumstance.
- 5. It can only be used within the permissible temperature range.
- 6. Must remove the batteries when it is not in use.