

MATH 312 Final Project Proposal

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December 6, 2023

1 Background

1.1 The Three Body Problem

The three body problem is a classic application of Newtonian physics wherein the position and velocity of three bodies at some time are determined by their initial positions and velocities, their masses, and the gravitational constant G . In order to simplify this problem for an undergraduate project, we made the following simplifying assumptions: that all bodies have the same mass ($m = 1$), that all planets start from rest, and that all three are acted upon by the same gravitational constant $G = 6.67 * 10^{-11}$. Additionally, we will only be considering the three body problem in two dimensions, which also simplifies it for our purposes.

1.2 Equations

Taking $m_1 = m_2 = m_3 = G = 1$, the following vector equation describes the motion of a single planet in the three body problem.

$$\ddot{\mathbf{r}} = \begin{pmatrix} \frac{d^2x}{dt^2} \\ \frac{d^2y}{dt^2} \end{pmatrix} = \begin{pmatrix} -\frac{x_1-x_2}{((x_2-x_1)^2-(y_2-y_1)^2)^{3/2}} + -\frac{x_1-x_3}{((x_3-x_1)^2-(y_3-y_1)^2)^{3/2}} \\ -\frac{y_1-y_2}{((x_2-x_1)^2-(y_2-y_1)^2)^{3/2}} + -\frac{y_1-y_3}{((x_3-x_1)^2-(y_3-y_1)^2)^{3/2}} \end{pmatrix}$$

Here x_1 and y_1 are the x and y coordinates of the planet in question, x_2 and y_2 are the x and y coordinates of the second planet, and x_3 and y_3 are the x and y coordinates of the third planet. The same equation can be written for the second and third planets by swapping the subscripts.

2 Goal

Our intended goal is to model the three body problem in the 2D plane for a range of initial conditions, using Heun's Method. Once every approximation is complete, we would create a "moment map" of the result by averaging the amount of times a planet appears at a particular pixel and giving that pixel a corresponding RGB value. For example, a pixel where planet 1 (red) passes through numerous times would appear very dark red in the moment map, while a pixel where planet 1 (red) and 3 (blue) pass through a lot would appear purple. The steps towards this goal fall into two categories: those that we are certain we can achieve and those that are more ambitious.

3 Minimum Viable Product

The minimum viable product (MVP) of our project entails (1) rewritten equations for the three-body problem in two dimensions, (2) code in python to compute Heun's equations for all 12 of the three-body equations, and (3) plots of three-body motion featuring all three bodies and the center of mass in Python.

4 Overall Goal

Our more ambitious goals entail the creation of the RGB map synthesizing the motion of the three bodies over a variety of initial conditions in order to achieve a better understanding of how the bodies tend to move.