

XS\_ETH\_12DI7DO arduino 2560工控板 配合TH-S71 多合一环境传感器使用。

准备器件:

XS\_ETH\_12DI7DO 工控板\*1

TH-S71 传感器模块\*1

方口USB线\*1

以太网线\*1

杜邦线\*4

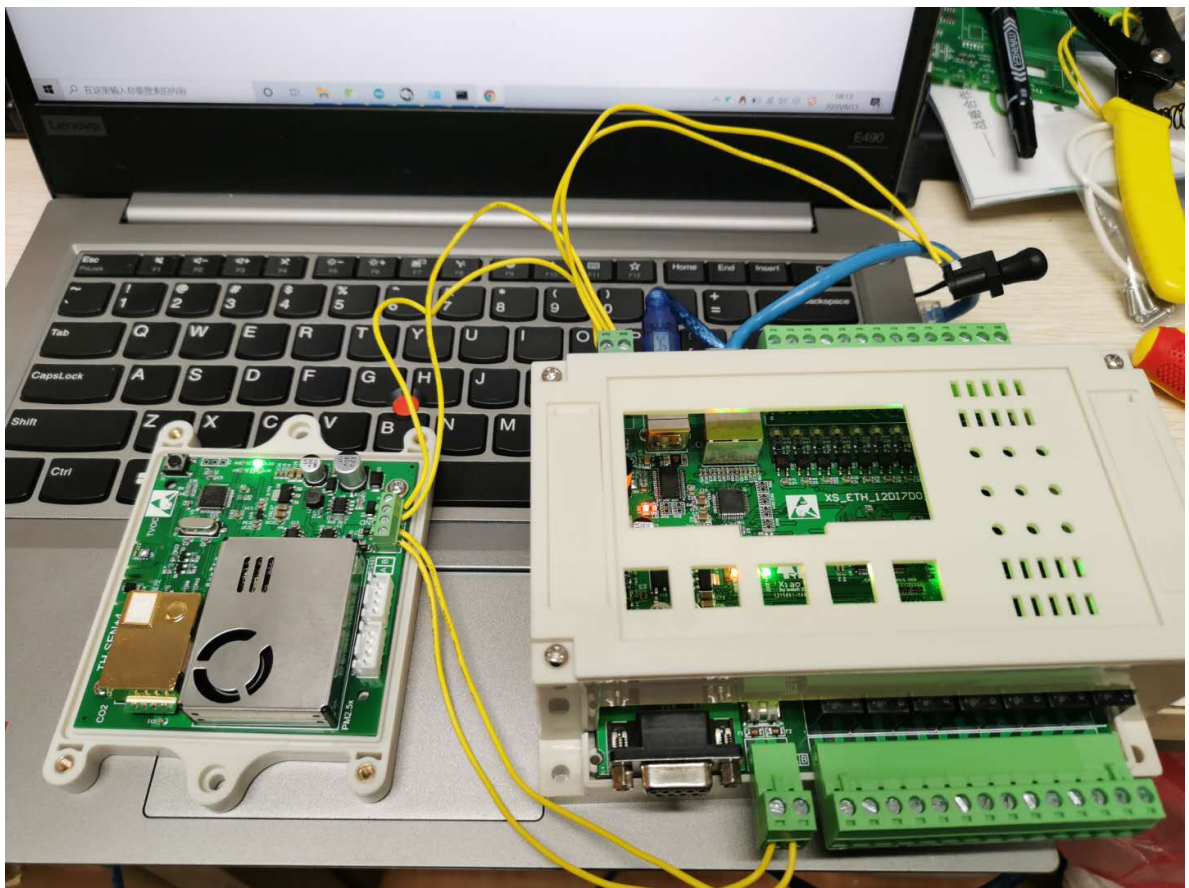
24V 直流电源\*1

arduino 2560工控板 通过RS485 连接TH-S71环境传感器，使用了标准的MODBUS-RTU协议读取传感器数值，传感器协议文档

可通过以下链接下载（<https://github.com/watchzhong/TH-S71-SENSOR-ALL-file/blob/master/002-Modbus-RTU%E5%A4%9A%E4%BC%A0%E6%84%9F%E5%99%A8%E7%9B%91%E6%8E%A7.md>）。

2560工控板 通过以太网把数据上传到局域网进行实时查看。

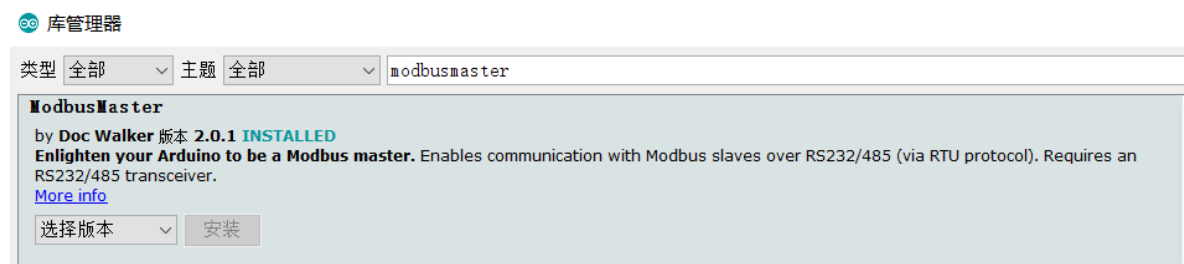
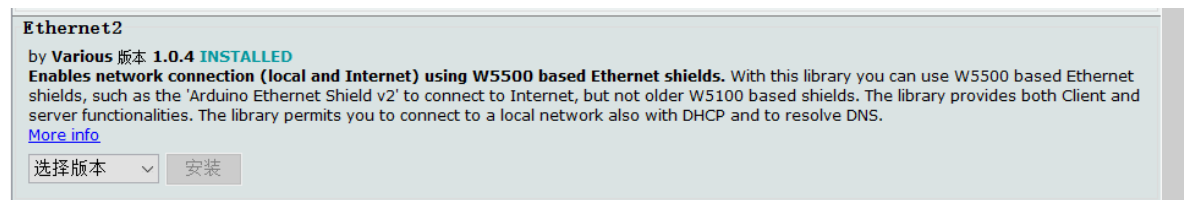
接线方式如下：



XS\_ETH\_12DI7DO 和TH-S71 两根RS485线连接，输入24V电源。XS\_ETH\_12DI7DO USB连接电脑，网线也连接电脑的以太网 网口。

程序代码如下：

先要安装ethernet2和modbusmaster库，打开arduino ide 在线安装便可。



```
#include <Dhcp.h>
#include <Dns.h>
#include <Ethernet2.h>
#include <EthernetClient.h>
#include <EthernetServer.h>
#include <EthernetUdp2.h>
#include <Twitter.h>
#include <util.h>

#include <ModbusMaster.h>

ModbusMaster node;

#define MODBUS_EN 6

// Enter a MAC address and IP address for your controller below.
// The IP address will be dependent on your local network:
byte mac[] = {
  0xDE, 0xAD, 0xBE, 0xEF, 0xFE, 0xED
};
IPAddress ip(192, 168, 1, 177);

// Initialize the Ethernet server library
// with the IP address and port you want to use
// (port 80 is default for HTTP):
EthernetServer server(80);

void ethernet_init()
{
```

```

// start the Ethernet connection and the server:
Ethernet.begin(mac, ip);
server.begin();
Serial.print("server is at ");
Serial.println(Ethernet.localIP());
}

void preTransmission()
{
    digitalWrite(MODBUS_EN, 1);
}

void postTransmission()
{
    digitalWrite(MODBUS_EN, 0);
}

void modbus_init()
{
    // use Serial (port 0); initialize Modbus communication baud rate
    Serial2.begin(9600);

    pinMode(MODBUS_EN, OUTPUT);
    digitalWrite(MODBUS_EN, 1);

    // communicate with Modbus slave ID 2 over Serial (port 0)
    node.begin(1, Serial2);
    node.preTransmission(preTransmission);
    node.postTransmission(postTransmission);
}

void modbus_test()
{
    static uint32_t i;
    uint8_t j, result;
    uint16_t data[6];

    i++;

    // set word 0 of TX buffer to least-significant word of counter (bits 15..0)
    // node.setTransmitBuffer(0, lowWord(i));

    // set word 1 of TX buffer to most-significant word of counter (bits 31..16)
    // node.setTransmitBuffer(1, 0x3344);

    // slave: write TX buffer to (2) 16-bit registers starting at register 0
    // result = node.writeMultipleRegisters(0, 2);

    // slave: read (6) 16-bit registers starting at register 2 to RX buffer

    delay(600);
    Serial.println("read holding register");
    result = node.readInputRegisters(1, 8);

    // do something with data if read is successful
    if (result == node.ku8MBSuccess)
    {

```

```

        Serial.println("get resp:");
        for (j = 0; j < 8; j++)
        {
            data[j] = node.getResponseBuffer(j);
            Serial.println(data[j]);
        }
        Serial.println();

    }
}

void setup() {
    // put your setup code here, to run once:
    pinMode(LED_BUILTIN,OUTPUT);

    Serial.begin(9600);

    ethernet_init();

    modbus_init();
}

void loop() {
    // put your main code here, to run repeatedly:

    //modbus get data

    uint8_t j, result;
    uint16_t data[8];

    // Serial.println("read holding register");
    // result = node.readInputRegisters(1, 8);

    // listen for incoming clients
    EthernetClient client = server.available();
    if (client) {
        Serial.println("new client");
        // an http request ends with a blank line
        boolean currentLineIsBlank = true;
        while (client.connected()) {
            if (client.available()) {
                char c = client.read();

                //
                Serial.write(c);

```

```

                // if you've gotten to the end of the line (received a newline
                // character) and the line is blank, the http request has ended,
                // so you can send a reply
                if (c == '\n' && currentLineIsBlank) {
                    // send a standard http response header
                    client.println("HTTP/1.1 200 OK");
                    client.println("Content-Type: text/html");
                    client.println("Connection: close"); // the connection will be closed
                    after completion of the response
                    client.println("Refresh: 2"); // refresh the page automatically every 5
                    sec

```

```
client.println();
client.println("<!DOCTYPE HTML>");
client.println("<html>");
```

```
// transmit data to TCP-w5500
```

```
// if (result == node.ku8MBSuccess)
{
```

```
    Serial.println("get modbus resp>");
```

```
    // Serial.println("read holding register");
    result = node.readInputRegisters(1, 8);
```

```
    for (j = 0; j < 8; j++)
    {
        data[j] = node.getResponseBuffer(j);
    }
```

```
    uint16_t data_temp = data[0];
    uint16_t data_humi = data[1];
```

```
    uint16_t data_sgpcO2 = data[2];
    uint16_t data_sgpvoc = data[3];
```

```
    uint16_t data_mhco2 = data[4];
    uint16_t data_pm1 = data[5];
    uint16_t data_pm25 = data[6];
    uint16_t data_pm10 = data[7];
```

```
    client.print("<center>");
    client.print("<h3>Multiple sensor monitor</h3>");
    client.print("<h5>Modbus RTU with W5500 nethernet</h5>");
```

```
    client.print("<table border='1'>");
    client.print("<tr>");
    client.print("<th>sensor</th>");
    client.print("<th>value</th>");
    client.print("</tr>");
```

```
    client.print("<tr>");
    client.print("<td>");
    client.print("SHT30 Temp");
    client.print("</td>");
    client.print("<td>");
    client.print(data_temp/100.00);
    client.print(" C");
    client.print("</td>");
    client.print("</tr>");
```

```
    Serial.print("SHT30 Temp:");
    Serial.println(data_temp/100.00);
```

```
    client.print("<tr>");
    client.print("<td>");
```

```
client.print("SHT30 Humi");
client.print("</td>");
client.print("<td>");
client.print(data_humi/100.00);
client.print(" %");
client.print("</td>");
client.print("</tr>");

Serial.print("SHT30 Humi:");
Serial.println(data_humi/100.00);

client.print("<tr>");
client.print("<td>");
client.print("SGP30 eCO2");
client.print("</td>");
client.print("<td>");
client.print(data_sgpcO2/10.0);
client.print(" ppm");
client.print("</td>");
client.print("</tr>");

Serial.print("SGP30 eCO2:");
Serial.println(data_sgpcO2/10.0);

client.print("<tr>");
client.print("<td>");
client.print("SGP30 TVOC");
client.print("</td>");
client.print("<td>");
client.print(data_sgpvoc/10.0);
client.print(" ppb");
client.print("</td>");
client.print("</tr>");

Serial.print("SGP30 TVOC:");
Serial.println(data_sgpvoc/10.0);

client.print("<tr>");
client.print("<td>");
client.print("MHZ19B CO2");
client.print("</td>");
client.print("<td>");
client.print(data_mhco2*10.0);
client.print(" ppm");
client.print("</td>");
client.print("</tr>");

Serial.print("MHZ19B CO2:");
Serial.println(data_mhco2*10);

client.print("<tr>");
client.print("<td>");
client.print("PM1.0");
client.print("</td>");
client.print("<td>");
client.print(data_pm1);
client.print(" ug/m3");
client.print("</td>");
```

```

        client.print("</tr>");

        Serial.print("PM1.0:");
        Serial.println(data_pm1);

        client.print("<tr>");
        client.print("<td>");
        client.print("PM2.5");
        client.print("</td>");
        client.print("<td>");
        client.print(data_pm25);
        client.print(" ug/m3");
        client.print("</td>");
        client.print("</tr>");

        Serial.print("PM2.5:");
        Serial.println(data_pm25);

        client.print("<tr>");
        client.print("<td>");
        client.print("PM10");
        client.print("</td>");
        client.print("<td>");
        client.print(data_pm10);
        client.print(" ug/m3");
        client.print("</td>");
        client.print("</tr>");

        Serial.print("PM10:");
        Serial.println(data_pm10);

        client.print("</table>");
        client.print("</center>");

        Serial.println();

    }

    // output the value of each analog input pin

```

```

// for (int analogChannel = 0; analogChannel < 6; analogChannel++) {
//     int sensorReading = analogRead(analogChannel);
//     client.print("analog input ");
//     client.print(analogChannel);
//     client.print(" is ");
//     client.print(sensorReading);
//     client.println("
");
// }

```

```

        client.println("</html>");
        break;
    }
    if (c == '\n') {
        // you're starting a new line
        currentLineIsBlank = true;
    }

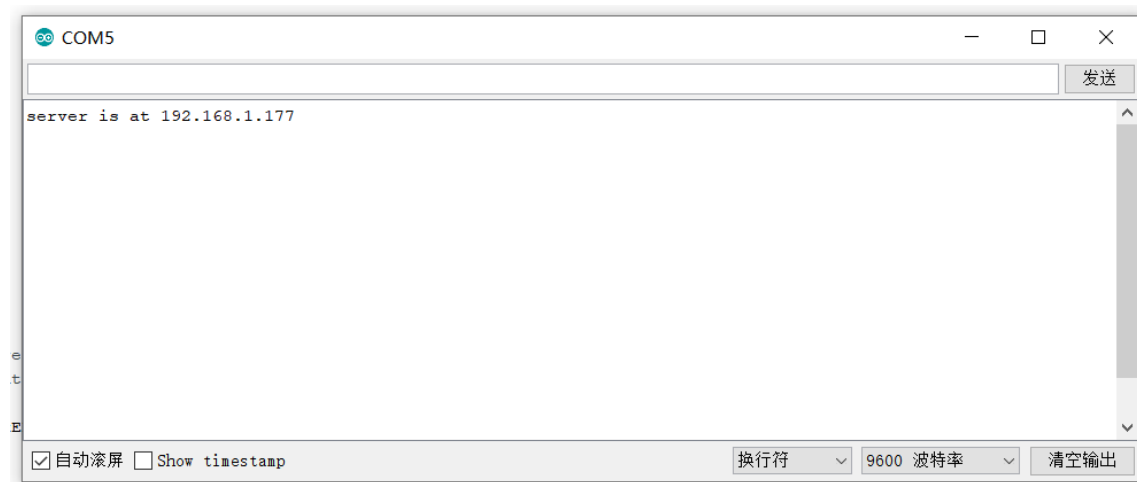
```

```

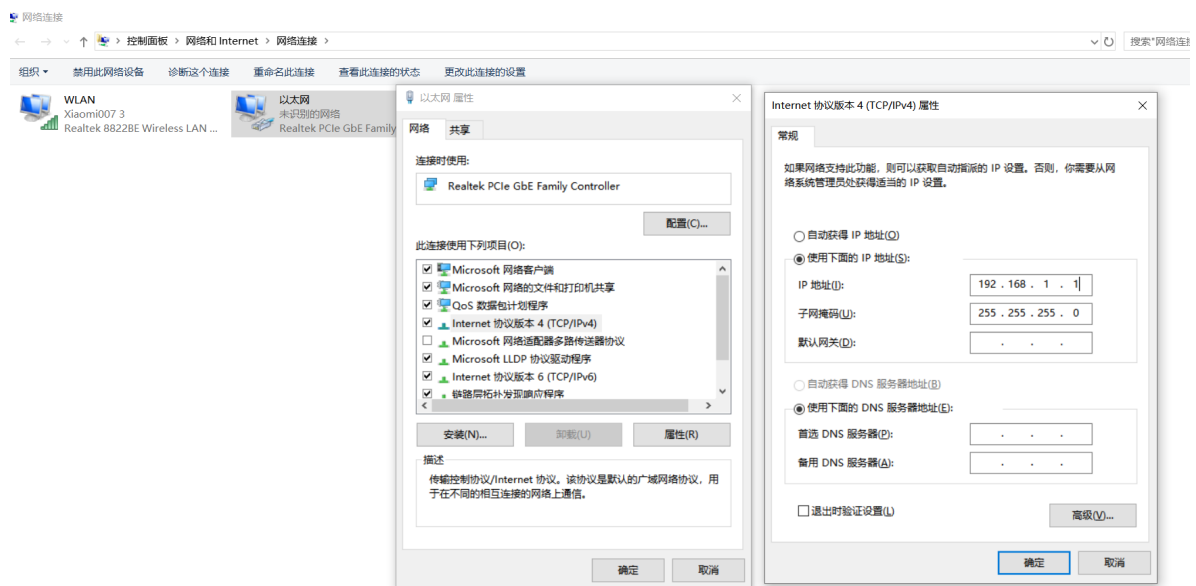
    }
    else if (c != '\r') {
        // you've gotten a character on the current line
        currentLineIsBlank = false;
    }
}
}
// give the web browser time to receive the data
delay(1);
// close the connection:
client.stop();
Serial.println("client disconnected");
}
}

```

把代码通过USB烧录到 2560工控板，打开串口调试窗，显示本地局域网的IP地址。



这时，我们先要对电脑进行IP设置。



然后连接尝试...



```
C:\Windows\system32\cmd.exe
Microsoft Windows [版本 10.0.18362.959]
(c) 2019 Microsoft Corporation. 保留所有权利。

C:\Users\watch>ping 192.168.1.177

正在 Ping 192.168.1.177 具有 32 字节的数据:
来自 192.168.1.177 的回复: 字节=32 时间<1ms TTL=128
来自 192.168.1.177 的回复: 字节=32 时间<1ms TTL=128
来自 192.168.1.177 的回复: 字节=32 时间<1ms TTL=128
来自 192.168.1.177 的回复: 字节=32 时间<1ms TTL=128

192.168.1.177 的 Ping 统计信息:
    数据包: 已发送 = 4, 已接收 = 4, 丢失 = 0 (0% 丢失),
往返行程的估计时间(以毫秒为单位):
    最短 = 0ms, 最长 = 0ms, 平均 = 0ms

C:\Users\watch>ping 192.168.1.177

正在 Ping 192.168.1.177 具有 32 字节的数据:
来自 192.168.1.177 的回复: 字节=32 时间<1ms TTL=128
来自 192.168.1.177 的回复: 字节=32 时间<1ms TTL=128
来自 192.168.1.177 的回复: 字节=32 时间<1ms TTL=128
来自 192.168.1.177 的回复: 字节=32 时间<1ms TTL=128

192.168.1.177 的 Ping 统计信息:
    数据包: 已发送 = 4, 已接收 = 4, 丢失 = 0 (0% 丢失),
往返行程的估计时间(以毫秒为单位):
    最短 = 0ms, 最长 = 0ms, 平均 = 0ms

C:\Users\watch>
```

如图所示，电脑端和2560以太网连接正常，即可以进行下一步的操作，在浏览器输入192.168.1.177 回车，传感器的数值如下所示。

## Multiple sensor monitor

### Modbus RTU with W5500 nethernet

sensor	value
SHT30 Temp	28.52 C
SHT30 Humi	53.80 %
SGP30 eCO2	458.00 ppm
SGP30 TVOC	27.00 ppb
MHZ19B CO2	1130.00 ppm
PM1.0	135 ug/m3
PM2.5	206 ug/m3
PM10	213 ug/m3

同时，传感器数值也在串口端显示，再次打开串口调试助手即可。

```
client disconnected  
new client  
get modbus resp>  
SHT30 Temp:28.76  
SHT30 Humi:53.02  
SGP30 eCO2:403.00  
SGP30 TVOC:8.00  
MHZ19B CO2:1150  
PM1.0:135  
PM2.5:214  
PM10:232
```