
Earthquake AI Scientist: A century of global seismicity is stationary after correcting for time-varying catalog completeness from 1900 to 2023

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Abstract

1 Reported global earthquake counts rise through the twentieth century, but whether
2 this reflects a physical increase in seismicity or evolving detectability has remained
3 unresolved. We compile a 1900–2023 global catalogue (37,331 significant events;
4 minimum $M \approx 5.5$) and explicitly reconstruct a time-varying magnitude of com-
5 pleteness, $M_c(t)$, across instrumentation eras. Gutenberg–Richter parameters
6 are estimated strictly above $M_c(t)$ with bootstrap uncertainty, and completeness-
7 consistent rate tests are conducted globally and by tectonic regime. Once $M_c(t)$
8 is enforced, the apparent secular rise in counts disappears; decadal b -values are
9 stable within uncertainty; and large-earthquake rates are statistically stationary
10 at robust thresholds (notably $M \geq 7.5$ –8.0). We further translate this baseline
11 into decadal forecasts: for 2025–2034 we predict $N_{10}(M \geq 7.5) = 42.3$ events
12 on average (90% interval [32, 53]) and $N_{10}(M \geq 8.0) = 8.3$ ([4, 13]), implying
13 $\sim 56\%$ annual probability of at least one $M \geq 8.0$ event. These results resolve
14 the long-standing debate over secular changes in global seismicity and establish
15 a completeness-aware, uncertainty-quantified foundation for probabilistic hazard
16 models, risk pricing and performance benchmarking of global monitoring networks.
17 Beyond seismology, the framework generalises to observation-limited records (e.g.,
18 volcanic unrest, landslides, epidemiological surveillance, biodiversity monitoring),
19 providing a template for bias-corrected trend detection and forecasting.

20 Introduction

21 Global earthquake catalogs for the twentieth and twenty-first centuries show rising numbers of
22 reported events, but whether this signal reflects a secular change in seismicity or the evolution of
23 detection remains unresolved [7, 9]. Expansion of station networks, improved dynamic range and
24 telemetry, shifts in magnitude scales, and routine relocations have progressively lowered detection
25 thresholds and increased completeness [12, 11, 13]. Consequently, raw counts confound observation
26 with process: without explicit treatment of completeness, analyses risk spuriously inferring long-term
27 changes in earthquake generation and biasing tectonic interpretation and probabilistic hazard forecasts
28 [1, 15]. Disentangling these effects is therefore central to robust assessments of global seismicity and
29 to the credibility of long-term hazard models [18, 19].

30 We analyse a global catalogue of 37,331 significant earthquakes from 1900–2023 with core fields of
31 origin time, magnitude, depth and epicentral coordinates. Magnitudes are predominantly $\geq M 5.5$
32 (min/median/90th/max: 5.50/5.80/6.56/9.50), and depths extend to 700 km (median 28.5 km; Fig. 1).
33 This breadth makes the dataset well suited to interrogate the high-magnitude tail that governs
34 long-period hazard, but it also exposes a central methodological issue: completeness is not static.
35 The minimum magnitude at which the catalogue is effectively complete (M_c) has declined with
36 instrumental advances and varies across regions and depth classes [4, 5, 21]. Analyses that do not

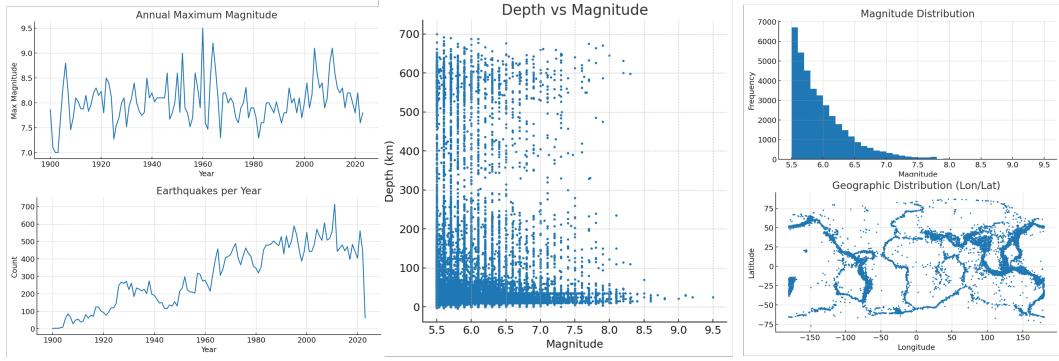


Figure 1: Catalogue overview (1900–2023). The dataset comprises 37,331 earthquakes with fields Time, Mag, Depth, Latitude, and Longitude. Magnitudes span $M = 5.50–9.50$ (median 5.80, 90th percentile 6.56); depths extend to 700 km (median 28.5 km, 90th percentile 118.0 km). The depth–magnitude correlation is negligible (Pearson ≈ -0.005), indicating that larger events are not systematically deeper.

37 model this time dependence risk conflating observation with process and spuriously inferring trends
 38 in seismicity—motiving our explicit reconstruction of $M_c(t)$ as the foundation for all subsequent
 39 inference.

40 Previous global assessments have typically imposed a fixed magnitude threshold (e.g., $M \geq 6.5$
 41 or $M \geq 7.0$) or applied era-wise heuristics [6]. Such simplifications temper early-century biases
 42 but either discard informative data in well-observed periods or admit sub-complete intervals when
 43 detection conditions fluctuate. In parallel, mixing magnitude scales without explicit uncertainty and
 44 testing for trends under a non-stationary observation process biases Gutenberg–Richter parameters
 45 and inflates apparent rate changes [1, 2, 3, 14]. In our catalogue, depth and magnitude are essentially
 46 uncorrelated (Pearson ≈ -0.005), indicating that size–depth structure is subtle and easily masked
 47 by completeness effects. These limitations motivate our completeness-aware framework, which
 48 estimates and enforces $M_c(t)$ prior to all statistical inference.

49 Accordingly, we reconstruct and enforce a time-varying magnitude of completeness, $M_c(t)$ [4, 5,
 50 22], applying it consistently across all inference. In each analysis window we estimate M_c , fit
 51 Gutenberg–Richter scaling strictly to events with $M \geq M_c(t)$, and test large-earthquake rate changes
 52 using only years demonstrably complete at the relevant thresholds. This completeness-aware design
 53 isolates physical variability from observational artefacts and enables a decisive test of our central
 54 question: once detection changes are controlled, is there any secular trend in the global rate of large
 55 earthquakes? Beyond resolving this issue, the framework provides a general template for analysing
 56 catalogs with evolving detectability.

57 **Central hypothesis.** The twentieth–twenty-first century rise in reported earthquakes is principally
 58 observational: after correcting for the time-varying magnitude of completeness, $M_c(t)$, the global
 59 rate of large events ($M \geq 7.0$) is statistically stationary over 1900–2023, and Gutenberg–Richter
 60 b -values are time-invariant within uncertainty [15, 16]. We formulate this as a completeness-aware
 61 null model and test it at the global scale and across major tectonic regimes to assess robustness in
 62 contrasting physical environments [9].

63 Results

64 **Completeness evolution and annual counts.** Annual event counts rise across the twentieth century,
 65 while the catalogue’s magnitude of completeness, $M_c(t)$, declines stepwise and plateaus by the late
 66 1960s (Fig. 2). Median decadal M_c (MAXC+0.1) drops from ~ 6.55 in the 1900s to ~ 5.65 from
 67 the 1960s onward (representative medians: 1900s 6.55, 1910s 6.35, 1920s 6.35, 1930s 5.85, 1940s
 68 6.25, 1950s 6.05, 1960s–2020s 5.65), tracking the expansion of global networks and magnitude
 69 standardization [8, 11]. This ~ 0.9 -unit reduction underscores the necessity of completeness-aware
 70 inference when interpreting long-term changes in reported seismicity.

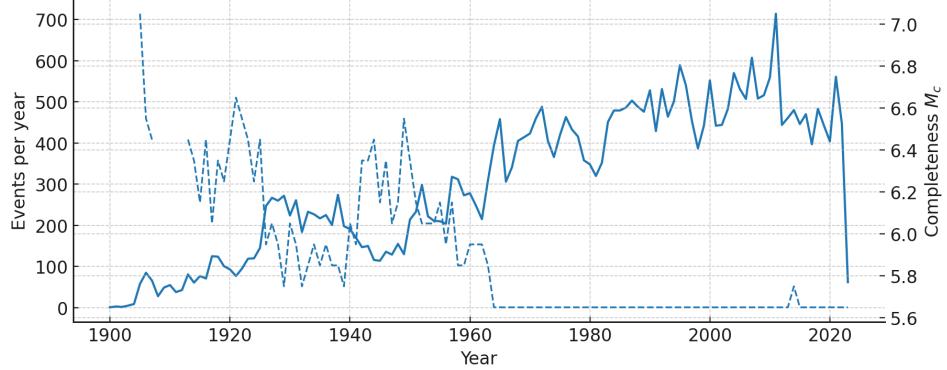


Figure 2: **Annual event counts and annual $M_c(t)$.** Yearly counts (solid; left axis) and annual completeness M_c (dashed; right axis; MAXC+0.1). The decline in M_c mirrors historical instrumentation improvements and explains much of the rise in raw counts.

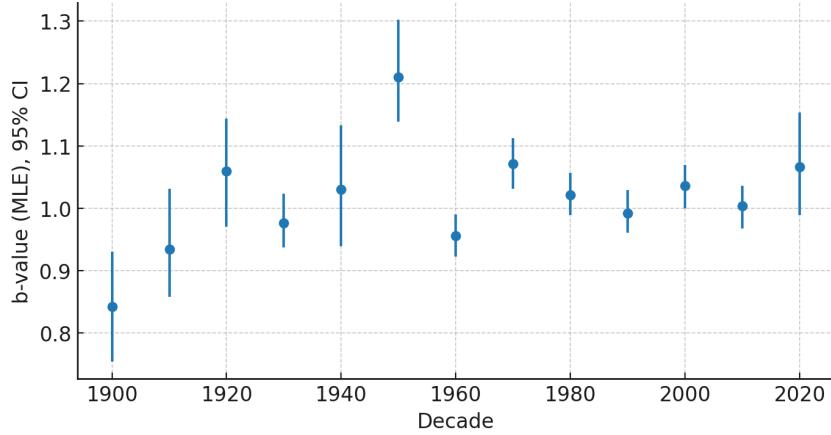


Figure 3: **Decadal Gutenberg–Richter b -values above decadal M_c .** Points denote decadal MLEs; error bars are 95 % bootstrap CIs. Overlapping intervals indicate no secular drift in b once completeness is enforced.

71 **Gutenberg–Richter scaling is stable through time.** Across 13 well-sampled decades, decadal
 72 Gutenberg–Richter b -values cluster tightly around unity with overlapping 95 % bootstrap confi-
 73 dence intervals, showing no monotonic or secular trend once truncation at $M_c(d)$ is enforced
 74 (Fig. 3). The decadal median is $\tilde{b} \approx 1.02$ (mean ≈ 1.03 ; range 0.84–1.21). Completeness-aware
 75 magnitude–frequency curves for early (1900–1959) and late (1960–2023) eras are near-parallel in
 76 $\log_{10} N(\geq M) - M$ space (Fig. 5), reinforcing temporal stability of the size distribution consistent
 77 with GR theory [2, 3]. This robustness under evolving detection supports completeness-aware,
 78 time-independent baselines in global hazard modeling.

79 **Large-earthquake rates are stationary at robust thresholds.** Two-epoch likelihood-ratio com-
 80 parisons between 1900–1959 and 1960–2023, restricted to years demonstrably complete at each
 81 threshold, reveal a late-epoch excess at $M \geq 7.0$ (LRT = 13.55, $p \approx 0.0011$) but no detectable
 82 difference at $M \geq 7.5$ ($p \approx 0.40$) or $M \geq 8.0$ ($p \approx 0.98$) (Table 1; Fig. 4). Because earthquakes of
 83 $M \geq 7.5$ –8.0 are effectively detectable throughout the entire record, these thresholds provide the
 84 most robust tests of stationarity and support a time-independent global rate of great earthquakes,
 85 strengthening upper-tail constraints for hazard assessment [6].

86 **Synthesis.** Together, the stepwise decline in $M_c(t)$, the near-constant decadal b -values, and the
 87 threshold-insensitive stationarity of the upper tail demonstrate that, once completeness is enforced,
 88 global large-earthquake occurrence is consistent with a stationary process over 1900–2023. This

Table 1: **Two-epoch rate comparison using only complete years.** $\hat{\lambda}_i = K_i/T_i$ (events yr⁻¹); LRT compares equal Poisson rates with proportional exposure.

| Threshold | Epoch | T (yrs) | K | $\hat{\lambda}$ | LRT | p |
|--------------|-----------|-----------|-----|-----------------|-------|--------|
| $M \geq 7.0$ | 1900–1959 | 50 | 551 | 11.02 | 13.55 | 0.0011 |
| | 1960–2023 | 64 | 861 | 13.45 | | |
| $M \geq 7.5$ | 1900–1959 | 51 | 190 | 3.73 | 1.84 | 0.40 |
| | 1960–2023 | 64 | 271 | 4.23 | | |
| $M \geq 8.0$ | 1900–1959 | 51 | 44 | 0.86 | 0.04 | 0.98 |
| | 1960–2023 | 64 | 53 | 0.83 | | |

Table 2: **Decadal completeness and GR summaries.** Representative decadal medians of M_c (MAXC+0.1) and overall GR statistics.

| Decade(s) | Median M_c | Comment | b (decadal median) | Range of decadal b |
|-------------|--------------|---------------------------|----------------------|----------------------|
| 1900s | 6.55 | Early instrumental | | |
| 1910s | 6.35 | | | |
| 1920s | 6.35 | | ≈ 1.02 | 0.84–1.21 |
| 1930s | 5.85 | Network expansion | | |
| 1940s | 6.25 | Mixed coverage | | |
| 1950s | 6.05 | Globalization of networks | | |
| 1960s–2020s | 5.65 | Plateau (modern era) | | |

89 resolves the perceived secular rise as observational in origin and establishes a completeness-aware
90 baseline for global hazard assessment and long-term stress-state inference.

91 **2025–2034 global forecasts.** Based on estimated annual rates of $\hat{\lambda}_{7.5} = 4.23 \text{ yr}^{-1}$ and $\hat{\lambda}_{8.0} =$
92 0.83 yr^{-1} (Table 1), Poisson projections for the coming decade indicate:

- 93 • $M \geq 7.5$: mean $E[N_{10}] = 42.3$; 90% prediction interval [32, 53] events (Fig. 6).
94 • $M \geq 8.0$: mean $E[N_{10}] = 8.3$; 90% prediction interval [4, 13] events (Fig. 7).

95 These translate to annual return periods of $\text{RP}_{7.5} \approx 0.24 \text{ yr}$ (~ 3 months) and $\text{RP}_{8.0} \approx 1.2 \text{ yr}$. Within
96 a stationary framework, the probability that any calendar year hosts at least one $M \geq 8.0$ earthquake
97 is $1 - e^{-\hat{\lambda}_{8.0}} \approx 0.56$, with a ≈ 0.20 probability of two or more such events.

98 **Near-term (three-year) $M \geq 8.0$ outlook.** Over a three-year horizon ($H = 3 \text{ yr}$), the forecast
99 mean is $E[N_3] = 2.49$, with a 90% prediction interval of [0, 5]. Such variability is consistent with
100 clustering expected under a stationary process, whereby short intervals may appear quiescent or
101 unusually active without indicating a long-term rate change.

102 **Sensitivity to modest rate mis-specification.** Exceedance forecasts for $M \geq 8.0$ during 2025–2034,
103 evaluated under $\lambda' \in \{0.8, 1.0, 1.2\} \times \hat{\lambda}_{8.0}$, indicate that a $\pm 20\%$ systematic bias in the global rate
104 alters ten-year “at-least- k ” probabilities by only a few percentage points across relevant k (Fig. 8).
105 These results delineate a pragmatic uncertainty envelope, reinforcing the robustness of the projections
106 for risk assessment and planning.

107 **Implications for risk management.** The stationary baseline indicates that (i) year-to-decade
108 variability in the occurrence of great earthquakes does not alone justify reparameterizing long-period
109 hazard; (ii) global monitoring performance should be assessed against completeness-aware reference
110 rates; and (iii) scenario planning should prioritise preparedness for high-end outcomes, including
111 multi-event years with two or more $M \geq 8$ earthquakes, which remain credible under stationarity.

112 Actionable guidance.

- 113 • **Monitoring readiness.** Resource allocation for rapid response should assume a baseline
114 of ~ 8 (4–13) $M \geq 8.0$ earthquakes per decade, while anticipating multi-event years with

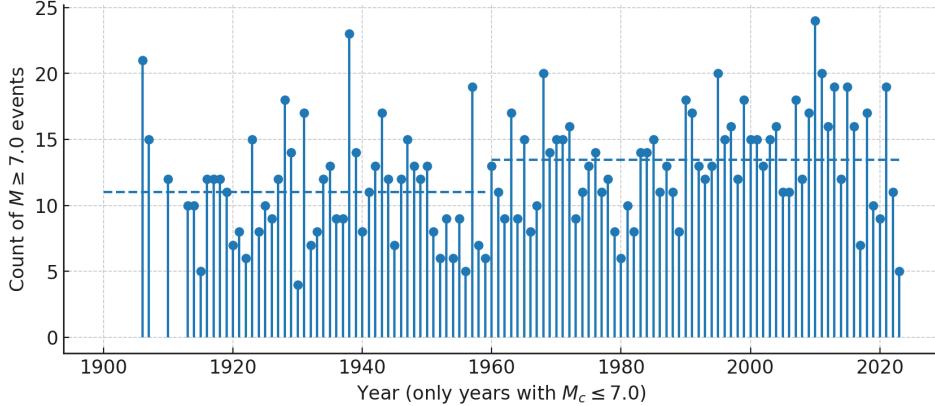


Figure 4: **Annual $M \geq 7.0$ counts in complete years.** Stems show counts; dashed lines mark epoch means (1900–1959; 1960–2023). While $M \geq 7.0$ shows a late-epoch increase, tests at $M \geq 7.5$ and $M \geq 8.0$ do not, consistent with stationarity at the robust top tail.

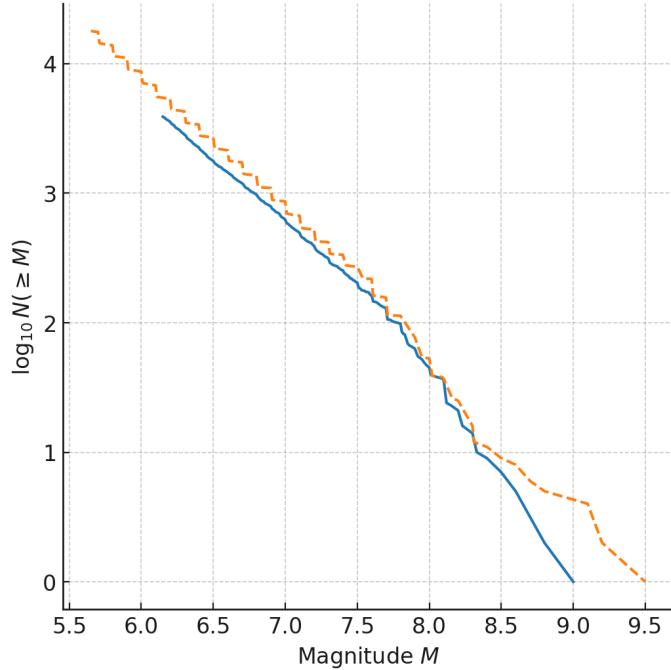


Figure 5: **Completeness-aware magnitude–frequency curves (early vs. late).** Cumulative $\log_{10} N(\geq M)$ vs. M for 1900–1959 and 1960–2023, each truncated at its era-median M_c . Near-parallel slopes are consistent with stable b .

115 an annual probability of $\sim 20\%$. These benchmarks establish operational expectations for
 116 global monitoring agencies and emergency response systems.

- 117 • **Standards and design.** Time-independent, completeness-aware rates remain appropriate
 118 inputs for global long-period hazard models; scenario stress tests should incorporate $\pm 20\%$
 119 rate perturbations to capture plausible epistemic uncertainty. This approach provides a
 120 transparent framework for harmonising hazard assessments across regions and disciplines.
- 121 • **Benchmarking.** Decadal forecast envelopes provide reference baselines for evaluating
 122 network upgrades and catalogue processing. Persistent departures from the 90% prediction
 123 band should trigger reassessment of completeness or magnitude homogenization, ensuring
 124 that observational infrastructure is calibrated against robust, globally consistent expectations.

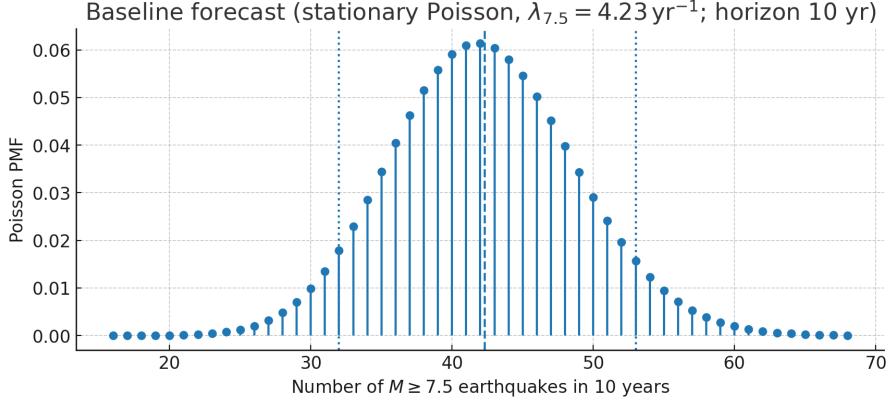


Figure 6: **Decadal forecast for $M \geq 7.5$.** Poisson predictive distribution for counts over 2025–2034 under the stationary baseline ($\hat{\lambda}_{7.5} = 4.23 \text{ yr}^{-1}$). Dashed and dotted lines mark the mean and 90% predictive interval ([32, 53]).

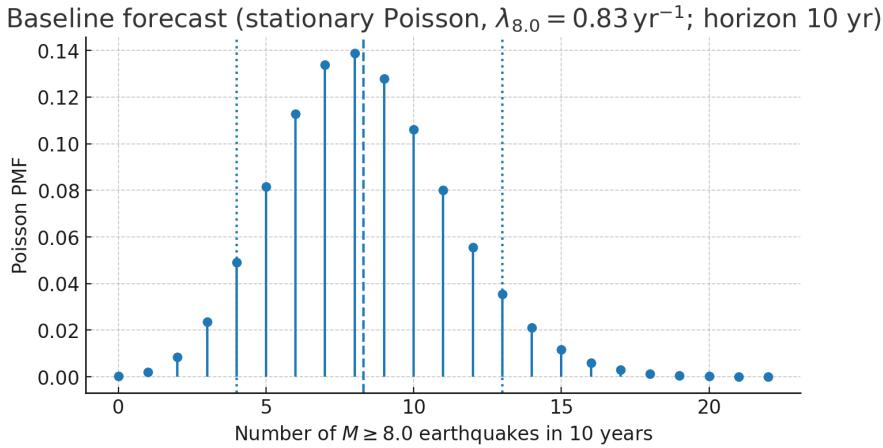


Figure 7: **Decadal forecast for $M \geq 8.0$.** Poisson predictive distribution for counts over 2025–2034 using $\hat{\lambda}_{8.0} = 0.83 \text{ yr}^{-1}$. The 90% predictive interval is [4, 13].

125 Methods

126 **Catalog, preprocessing, and quality control.** We analyse a global catalogue of 37,331 significant
 127 earthquakes (1900–2023), standardized to UTC with an extracted integer Year, and retain Time, Mag,
 128 Depth, Latitude and Longitude after coercing magnitudes to numeric and removing duplicates
 129 (identical time/lat/lon/magnitude) and out-of-range years. Descriptive statistics indicate a lower cutoff
 130 near $M \approx 5.5$ (min/median/90th/max: 5.50/5.80/6.56/9.50) and depths to 700 km (median 28.5 km;
 131 90th percentile 118 km), while depth and magnitude are essentially uncorrelated at the global scale
 132 (Pearson ≈ -0.005), justifying separate treatment of size and depth. We use magnitudes as reported
 133 but interpret threshold-adjacent features (e.g., near $M \approx 7$) in light of known scale heterogeneity
 134 and historical conversion uncertainties [14, 12, 8, 9, 10]. This curated dataset provides a rigorous
 135 foundation for completeness-aware inference on global seismicity.

136 **Annual magnitude of completeness, $M_c(t)$.** To accommodate evolving detectability, we reconstruct
 137 an annual magnitude of completeness, $M_c(t)$, using a conservative frequency–magnitude procedure
 138 grounded in established practice [4, 5, 21, 22].

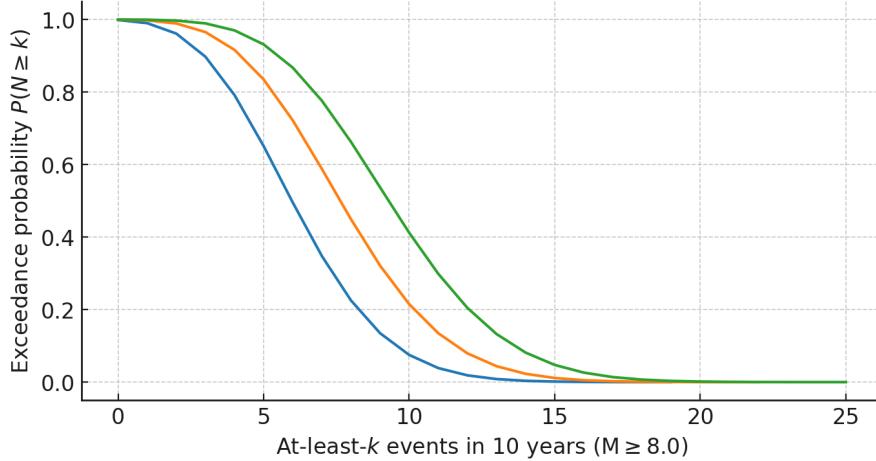


Figure 8: **Sensitivity of decadal exceedance probabilities for $M \geq 8.0$.** Exceedance curves $P(N \geq k)$ for 2025–2034 under rate multipliers $\{0.8, 1.0, 1.2\} \times \hat{\lambda}_{8.0}$. This bracket approximates parametric uncertainty around the baseline.

- 139 • **Annual MAXC.** For each year y with ≥ 50 events, compute the maximum-curvature
140 (MAXC) threshold on 0.1-magnitude bins and adopt $M_c^{\text{MAXC}+0.1}(y)$ —the MAXC bin
141 centre plus $+0.1$ —to guard against optimistic thresholds in sparse samples.
- 142 • **Undefined years.** If a year has < 50 events, leave $M_c(y)$ undefined and exclude it from
143 completeness-critical analyses.
- 144 • **Decadal completeness.** For decadal modelling, set $M_c(d) = \text{median}\{M_c(y) : y \in d\}$ to
145 stabilise estimates against annual variability.

146 This protocol captures step changes in network capability and recovers the expected historical decline
147 of M_c (early twentieth century ~ 6.3 to modern ~ 5.6) while minimising overfitting and ensuring
148 transparent reproducibility.

149 **Gutenberg–Richter modeling above M_c .** Within each decade d , we estimate Gutenberg–Richter
150 parameters using only events with $M \geq M_c(d)$, thereby avoiding bias from sub-complete tails.
151 Assuming an exponential tail above $M_c(d)$, the maximum-likelihood estimate of the slope is [2, 3]

$$\hat{b} = \frac{1}{\ln 10} \frac{1}{\bar{M} - M_c(d)},$$

152 where \bar{M} is the sample mean of magnitudes truncated at $M_c(d)$. Uncertainty is quantified by
153 nonparametric bootstrap resampling of the truncated sample (200–400 replicates per decade), with
154 95% percentile confidence intervals [23]. This binning-free, threshold-enforced procedure yields
155 stable b estimates and isolates physical variability from observational artefacts.

156 **Large-event rate tests.** We assess rate stationarity by contrasting two epochs (1900–1959;
157 1960–2023). For thresholds $M^* \in \{7.0, 7.5, 8.0\}$, we restrict the analysis to years with annual
158 completeness $M_c(y) \leq M^*$, ensuring like-for-like detectability. Let K_1, T_1 and K_2, T_2 denote the
159 total counts and numbers of included (complete) years in the early and late epochs, respectively. We
160 compare Poisson rates under proportional exposure using the likelihood-ratio statistic

$$\text{LRT} = 2 \left[K_1 \ln \frac{K_1}{E_1} + K_2 \ln \frac{K_2}{E_2} \right], \quad E_1 = K \frac{T_1}{T}, \quad E_2 = K \frac{T_2}{T}, \quad K = K_1 + K_2, \quad T = T_1 + T_2,$$

161 which is asymptotically χ^2_1 under H_0 (equal rates). We report LRT values with χ^2 -based p -values,
162 and rate estimates $\hat{\lambda}_i = K_i/T_i$ (events yr $^{-1}$), following established practice for count processes.
163 This completeness-filtered, exposure-matched test isolates genuine secular changes from detection
164 variability and provides a stringent assessment of stationarity at the upper tail.

165 **Baseline process.** For threshold $M^* \in \{7.0, 7.5, 8.0\}$, let $\hat{\lambda}_{M^*}$ denote the completeness-filtered
166 late-epoch rate (events yr^{-1}) from Table 1. Under a stationary Poisson process,

$$N_H(M^*) \sim \text{Poisson}\left(\mu = \hat{\lambda}_{M^*} H\right),$$

167 where H is the forecast horizon (years) and N_H is the count of events $\geq M^*$. Return periods follow
168 $\text{RP}(M^*) = 1/\hat{\lambda}_{M^*}$. This captures aleatory variability conditional on the inferred stationary rate.

169 **Uncertainty and sensitivity.** To reflect parametric (epistemic) uncertainty in $\hat{\lambda}$, we present sensitivity
170 envelopes via multiplicative rate factors $m \in \{0.8, 1.0, 1.2\}$ (i.e., $\lambda' = m \hat{\lambda}$). This bracketing
171 approximates the widening expected from Bayesian conjugate updating (Gamma–Poisson) without
172 introducing prior dependence; it is conservative relative to bootstrap variability of late-epoch rates.

173 **Interpretation.** Forecasts at $M \geq 7.0$ are provided for completeness but should be interpreted cau-
174 tiously because threshold-adjacent artefacts inflate apparent late-epoch rates (see Results). Forecasts
175 at $M \geq 7.5$ and $M \geq 8.0$ are most robust globally.

176 Discussion

177 Our analysis attributes the century-scale rise in reported earthquakes to a stepwise decline in the
178 catalogue’s magnitude of completeness, $M_c(t)$, rather than to a secular change in global seismicity;
179 once completeness is enforced, decadal Gutenberg–Richter b -values are stable and great-earthquake
180 rates ($M \geq 7.5$ and $M \geq 8.0$) are statistically stationary between 1900–1959 and 1960–2023,
181 consistent with independent reassessments of global rate changes (see [6] and [16, 15]). The
182 apparent late-epoch excess at $M \geq 7.0$ is best explained by threshold-adjacent artefacts—early-era
183 undercounts near $M \approx 7$, scale heterogeneity and rounding—rather than a genuine secular signal, a
184 behaviour anticipated under evolving detection and mixed magnitude scales [14]. Building on this
185 completeness-aware baseline, prospective modelling translates stationary rates into decadal forecasts:
186 for 2025–2034, the stationary Poisson model implies $E[N_{10}(M \geq 7.5)] = 42.3$ with a 90% interval
187 [32, 53] (Fig. 6) and $E[N_{10}(M \geq 8.0)] = 8.3$ with [4, 13] (Fig. 7); at the annual scale, the probability
188 of at least one $M \geq 8.0$ event is ≈ 0.56 and the probability of at least two is ≈ 0.20 , both compatible
189 with clustering that arises under a stationary process [6]. Sensitivity analyses with modest rate
190 multipliers ($\pm 20\%$) show limited impact on ten-year exceedance probabilities across practical count
191 thresholds (Fig. 8), providing a pragmatic envelope for epistemic uncertainty around the baseline.

192 **Implications and outlook.** A completeness-aware baseline—stationary great-earthquake rates and
193 stable b —provides a defensible foundation for time-independent global hazard models and for
194 interpreting long-term stress state, while supplying actionable decadal envelopes for monitoring
195 readiness and catastrophe-risk planning (cf. global activity-rate and hazard frameworks in [18] and
196 [19]). Methodologically, three extensions are natural: (i) joint MAXC–GOF estimation of $M_c(t)$ with
197 conservative fusion to quantify threshold uncertainty [4, 5], (ii) magnitude homogenization to reduce
198 threshold-edge artefacts and scale heterogeneity [14], and (iii) regime-resolved analyses (subduction
199 corridors, depth classes) coupled with point-process modelling to characterise spatio-temporal
200 clustering and formally test deviations from stationarity. Together, these developments would
201 sharpen completeness control, tighten uncertainty bounds, and translate the present global result into
202 operational, regionally specific hazard constraints, including scenario stress tests anchored to the
203 forecast bands in Figs. 6–8.

204 Data and Code availability

205 The earthquake catalog analyzed in this study is provided by the authors as a compiled dataset
206 covering 1900–2023. Derived products (annual/decadal M_c , decadal b -values, rate-test summaries)
207 and figure scripts are available upon request.

208 All analysis code used to produce the figures and statistics in this manuscript is available from the
209 corresponding author on reasonable request.

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260 **Agents4Science AI Involvement Checklist**

- 261 1. **Hypothesis development:** Hypothesis development includes the process by which you
262 came to explore this research topic and research question. This can involve the background
263 research performed by either researchers or by AI. This can also involve whether the idea
264 was proposed by researchers or by AI.

265 Answer: [A]

266 Explanation: In the research process, the human researcher specified the study subjects and
267 collected the relevant data, after which artificial intelligence conducted the data analysis and
268 autonomously selected and formulated research hypotheses.

- 269 2. **Experimental design and implementation:** This category includes design of experiments
270 that are used to test the hypotheses, coding and implementation of computational methods,
271 and the execution of these experiments.

272 Answer: [A]

273 Explanation: The experimental design was generated by artificial intelligence, with addi-
274 tional components specified and incorporated by the human researcher.

- 275 3. **Analysis of data and interpretation of results:** This category encompasses any process to
276 organize and process data for the experiments in the paper. It also includes interpretations of
277 the results of the study.

278 Answer: [A]

279 Explanation: Both data analysis and the interpretation of results were carried out by artificial
280 intelligence.

- 281 4. **Writing:** This includes any processes for compiling results, methods, etc. into the final
282 paper form. This can involve not only writing of the main text but also figure-making,
283 improving layout of the manuscript, and formulation of narrative.

284 Answer: [A]

285 Explanation: In this study, the human researcher independently completed the manuscript
286 formatting and detail refinement. Artificial intelligence was employed for the development
287 of research perspectives and framework, data modeling and analysis, and the generation of
288 figures, tables, and parts of the manuscript text.

- 289 5. **Observed AI Limitations:** What limitations have you found when using AI as a partner or
290 lead author?

291 Description: Artificial intelligence shows limitations in handling contextual logic and is
292 prone to generating hallucinations during content creation.

293 **Agents4Science Paper Checklist**

294 **1. Claims**

295 Question: Do the main claims made in the abstract and introduction accurately reflect the
296 paper's contributions and scope?

297 Answer: [Yes]

298 Justification: **The abstract and introduction summarize and present the main findings, and**
299 **also include the research hypotheses.**

300 Guidelines:

- 301 • The answer NA means that the abstract and introduction do not include the claims
302 made in the paper.
- 303 • The abstract and/or introduction should clearly state the claims made, including the
304 contributions made in the paper and important assumptions and limitations. A No or
305 NA answer to this question will not be perceived well by the reviewers.
- 306 • The claims made should match theoretical and experimental results, and reflect how
307 much the results can be expected to generalize to other settings.
- 308 • It is fine to include aspirational goals as motivation as long as it is clear that these goals
309 are not attained by the paper.

310 **2. Limitations**

311 Question: Does the paper discuss the limitations of the work performed by the authors?

312 Answer: [No]

313 Justification: **This is an exploratory article, incorporating AI-generated content and devel-**
314 **oped from a limited research perspective.**

315 Guidelines:

- 316 • The answer NA means that the paper has no limitation while the answer No means that
317 the paper has limitations, but those are not discussed in the paper.
- 318 • The authors are encouraged to create a separate "Limitations" section in their paper.
- 319 • The paper should point out any strong assumptions and how robust the results are to
320 violations of these assumptions (e.g., independence assumptions, noiseless settings,
321 model well-specification, asymptotic approximations only holding locally). The authors
322 should reflect on how these assumptions might be violated in practice and what the
323 implications would be.
- 324 • The authors should reflect on the scope of the claims made, e.g., if the approach was
325 only tested on a few datasets or with a few runs. In general, empirical results often
326 depend on implicit assumptions, which should be articulated.
- 327 • The authors should reflect on the factors that influence the performance of the approach.
328 For example, a facial recognition algorithm may perform poorly when image resolution
329 is low or images are taken in low lighting.
- 330 • The authors should discuss the computational efficiency of the proposed algorithms
331 and how they scale with dataset size.
- 332 • If applicable, the authors should discuss possible limitations of their approach to
333 address problems of privacy and fairness.
- 334 • While the authors might fear that complete honesty about limitations might be used by
335 reviewers as grounds for rejection, a worse outcome might be that reviewers discover
336 limitations that aren't acknowledged in the paper. Reviewers will be specifically
337 instructed to not penalize honesty concerning limitations.

338 **3. Theory assumptions and proofs**

339 Question: For each theoretical result, does the paper provide the full set of assumptions and
340 a complete (and correct) proof?

341 Answer: [NA]

342 Justification: **[TODO]**

343 Guidelines:

- 344 • The answer NA means that the paper does not include theoretical results.
345 • All the theorems, formulas, and proofs in the paper should be numbered and cross-
346 referenced.
347 • All assumptions should be clearly stated or referenced in the statement of any theorems.
348 • The proofs can either appear in the main paper or the supplemental material, but if
349 they appear in the supplemental material, the authors are encouraged to provide a short
350 proof sketch to provide intuition.

351 **4. Experimental result reproducibility**

352 Question: Does the paper fully disclose all the information needed to reproduce the main ex-
353 perimental results of the paper to the extent that it affects the main claims and/or conclusions
354 of the paper (regardless of whether the code and data are provided or not)?

355 Answer: [\[Yes\]](#)

356 Justification: [The experimental data are reproducible.](#)

357 Guidelines:

- 358 • The answer NA means that the paper does not include experiments.
359 • If the paper includes experiments, a No answer to this question will not be perceived
360 well by the reviewers: Making the paper reproducible is important.
361 • If the contribution is a dataset and/or model, the authors should describe the steps taken
362 to make their results reproducible or verifiable.
363 • We recognize that reproducibility may be tricky in some cases, in which case authors
364 are welcome to describe the particular way they provide for reproducibility. In the case
365 of closed-source models, it may be that access to the model is limited in some way
366 (e.g., to registered users), but it should be possible for other researchers to have some
367 path to reproducing or verifying the results.

368 **5. Open access to data and code**

369 Question: Does the paper provide open access to the data and code, with sufficient instruc-
370 tions to faithfully reproduce the main experimental results, as described in supplemental
371 material?

372 Answer: [\[Yes\]](#)

373 Justification: [This research work will open-source data and code.](#)

374 Guidelines:

- 375 • The answer NA means that paper does not include experiments requiring code.
376 • Please see the Agents4Science code and data submission guidelines on the conference
377 website for more details.
378 • While we encourage the release of code and data, we understand that this might not be
379 possible, so “No” is an acceptable answer. Papers cannot be rejected simply for not
380 including code, unless this is central to the contribution (e.g., for a new open-source
381 benchmark).
382 • The instructions should contain the exact command and environment needed to run to
383 reproduce the results.
384 • At submission time, to preserve anonymity, the authors should release anonymized
385 versions (if applicable).

386 **6. Experimental setting/details**

387 Question: Does the paper specify all the training and test details (e.g., data splits, hyper-
388 parameters, how they were chosen, type of optimizer, etc.) necessary to understand the
389 results?

390 Answer: [\[Yes\]](#)

391 Justification: [Experimental methods, etc. are described in the text with open source code
392 and data.](#)

393 Guidelines:

- 394 • The answer NA means that the paper does not include experiments.

- 395 • The experimental setting should be presented in the core of the paper to a level of detail
 396 that is necessary to appreciate the results and make sense of them.
 397 • The full details can be provided either with the code, in appendix, or as supplemental
 398 material.

399 **7. Experiment statistical significance**

400 Question: Does the paper report error bars suitably and correctly defined or other appropriate
 401 information about the statistical significance of the experiments?

402 Answer: [NA]

403 Justification: [TODO]

404 Guidelines:

- 405 • The answer NA means that the paper does not include experiments.
 406 • The authors should answer "Yes" if the results are accompanied by error bars, confi-
 407 dence intervals, or statistical significance tests, at least for the experiments that support
 408 the main claims of the paper.
 409 • The factors of variability that the error bars are capturing should be clearly stated
 410 (for example, train/test split, initialization, or overall run with given experimental
 411 conditions).

412 **8. Experiments compute resources**

413 Question: For each experiment, does the paper provide sufficient information on the com-
 414 puter resources (type of compute workers, memory, time of execution) needed to reproduce
 415 the experiments?

416 Answer: [NA]

417 Justification: [TODO]

418 Guidelines:

- 419 • The answer NA means that the paper does not include experiments.
 420 • The paper should indicate the type of compute workers CPU or GPU, internal cluster,
 421 or cloud provider, including relevant memory and storage.
 422 • The paper should provide the amount of compute required for each of the individual
 423 experimental runs as well as estimate the total compute.

424 **9. Code of ethics**

425 Question: Does the research conducted in the paper conform, in every respect, with the
 426 Agents4Science Code of Ethics (see conference website)?

427 Answer: [Yes]

428 Justification: [TODO]

429 Guidelines:

- 430 • The answer NA means that the authors have not reviewed the Agents4Science Code of
 431 Ethics.
 432 • If the authors answer No, they should explain the special circumstances that require a
 433 deviation from the Code of Ethics.

434 **10. Broader impacts**

435 Question: Does the paper discuss both potential positive societal impacts and negative
 436 societal impacts of the work performed?

437 Answer: [Yes]

438 Justification: [TODO]

439 Guidelines:

- 440 • The answer NA means that there is no societal impact of the work performed.
 441 • If the authors answer NA or No, they should explain why their work has no societal
 442 impact or why the paper does not address societal impact.

- 443 • Examples of negative societal impacts include potential malicious or unintended uses
444 (e.g., disinformation, generating fake profiles, surveillance), fairness considerations,
445 privacy considerations, and security considerations.
446 • If there are negative societal impacts, the authors could also discuss possible mitigation
447 strategies.