
Automated Mining of Hinge-like Protein Modules from AlphaFold PAE: BCR-Parts

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Abstract

1 We introduce *BCRParts*, a simple pipeline that turns single-structure predictions
2 into candidates for mechanically separable protein “parts”. The method segments
3 the AlphaFold PAE into $k \in \{2, 3\}$ blocks, scores block–contrast (BCR), and
4 assigns significance by permutation p -values with Benjamini–Hochberg FDR
5 applied *once per run*. On a curated cohort we processed 1,476 targets in parallel.
6 The score distribution shows a clear right tail, and—importantly—the BCR-derived
7 score correlates with an independent PAE diagnostic, the asymmetry index (Pearson
8 $r = 0.59$, Spearman $\rho = 0.69$, Fig. 3). Using a two-sided calibration (see
9 Methods), 314/1,476 rows pass BH at $q \leq 0.05$ (Fig. 2); top candidates and
10 attributes (e.g., hinge length, opening angle) are summarized in Table 1. External
11 evidence (PDBFlex/CoDNAS) could not be robustly retrieved in time for this
12 submission; we therefore report coverage diagnostics (Table 2) and leave full
13 cross-dataset validation to future work.

14

1 Introduction

15 Large language models (LLMs) and diffusion models are rapidly changing protein design. Recent
16 systems generate backbones and sequences with controllable topology and function, and some designs
17 have been validated experimentally [Watson et al., 2023, Ingraham et al., 2023]. Foundation models
18 further unify sequence, structure, and function, enabling multi-modal conditioning and iterative
19 design loops [Hayes et al., 2025]. In parallel, structure prediction now handles joint protein–nucleic
20 acid–ligand complexes at high accuracy, closing the loop between generative proposals and interaction-
21 aware screening [Abramson et al., 2024]. These advances motivate a new question at the interface
22 of AI design and molecular robotics: can we automatically mine and standardize protein “parts”
23 that behave like reusable robotic components (hinges, rods, latches), and feed them into modern
24 generative pipelines as constraints and interfaces?

25 We argue that building such a parts library requires two ingredients. First, a data-driven modularity
26 detector that flags contiguous subchains with strong intra-block coherence and weak inter-block
27 coupling, using confidences intrinsic to large-scale predicted structures. Second, a mechanical
28 interface layer that encodes how parts connect (e.g., termini geometry, axis orientation, and “latch-
29 like” residue pairs) and how they interoperate with widely used bio-orthogonal connectors and
30 switches.

31 This paper introduces *BCRParts*, an AI-first pipeline that (i) analyzes AlphaFold DB predictions to
32 extract contiguous two-block (and k -block) modular candidates from predicted aligned error (PAE)
33 heatmaps, (ii) quantifies block separability by a block contrast ratio (BCR) statistic with robust null
34 models, and (iii) annotates mechanical and interface features to surface candidates as robotic parts.
35 Concretely, we use a spectral bipartition on a PAE-derived similarity graph (Fiedler-vector sign
36 and a contiguity heuristic) to propose block boundaries, then compute quantile- and mean-based
37 BCR statistics and assess significance against rotation/permuation nulls with Benjamini–Hochberg

38 FDR control across cohorts [von Luxburg, 2007, Benjamini and Hochberg, 1995]. We rely on
39 AlphaFold DB’s pLDDT/PAE outputs for confidence and coupling [Varadi et al., 2024, Elfmann
40 and Stölke, 2023]; and we cross-reference PDBe “best structures”, RCSB PDB metadata, PDBFlex
41 (flexibility clusters), CoDNAs/CoDNAs-Q (conformational diversity) and UniProt (functional context)
42 to summarize reusability evidence for each candidate [Burley et al., 2023, Hrabe et al., 2016, Escobedo
43 et al., 2022, The UniProt Consortium, 2025].

44 To bridge into molecular robotics, we add an interface standardization layer: (a) terminal geometry
45 and principal-axis orientation (to reason about rod/hinge placement and serial assembly), and (b) a
46 lightweight detector of “latch-like” residue pairs (near-planar four-C α configurations with inter-C α
47 distance in a narrow window) as potential mechanical catch points.

48 This “parts-first” view complements function-first design in two ways. First, a modularity score driven
49 by PAE can prioritize intrinsically separable regions before any binding/fitness optimization. Second,
50 explicit interface descriptors make downstream generative steps easier to condition: a designer can
51 require, e.g., a coiled-coil handle at the N-terminus, a target axis offset, or a latch site near the block
52 boundary. Because the pipeline runs on public proteomes and predicted structures at scale, it can
53 surface natural, evolvable parts that are easier to express and fold than fully de novo constructs, while
54 remaining compatible with standardized connectors.

55 **Contributions.** (i) We introduce a PAE-driven segmentation-and-scoring pipeline that produces a
56 calibrated statistic (permutation p -values and BH-FDR across all tested rows) and practical attributes
57 (hinge length, N–C distance, opening angle) suitable for reuse in molecular robotics tasks.
58 (ii) We provide an evidence connector that maps top candidates to experimental conformational
59 diversity (PDBFlex and CoDNAs) and summarize coverage and agreement on curated cohorts with
60 multiple structures per UniProt.
61 (iii) We release a reproducible, parallelizable implementation that writes machine-readable artifacts
62 (CSV, PNG, L^AT_EX tables), allowing downstream design loops to search, score, and reuse putative
63 parts efficiently.
64 This framing treats PAE not as dynamics but as a structural prior from which we can *propose* parts
65 that appear mechanically separable. Our results suggest that high-scoring candidates align with
66 known conformational diversity on curated sets, providing a practical bridge between predictive
67 models and molecular robotics.

68 2 Methods

69 2.1 Cohort construction

70 We retrieve UniProt accessions for a target proteome via the UniProt REST interface and aggregate
71 experimental structure evidence using PDBe and RCSB PDB APIs [??]. By default, entries are
72 admitted if they have at least two PDB structures and a best resolution $\leq 3.5 \text{ \AA}$. To reduce redundancy,
73 sequences are clustered with MMseqs2 at 30% identity and only cluster representatives are kept [?].
74 To avoid information leakage, we split development/evaluation sets by the PDB release date returned
75 by RCSB APIs (time-based split).¹

76 2.2 Structure and confidence metadata

77 For each candidate we obtain predicted structures and Predicted Aligned Error (PAE) from the
78 AlphaFold Protein Structure Database (AFDB) [?] or recompute with AlphaFold (AF2/AF3) when
79 needed [??]. PAE is a pairwise estimate of relative positional uncertainty between residues and is
80 informative about domain placement. We symmetrize the PAE matrix P by $P \leftarrow (P + P^\top)/2$
81 and mask the near-diagonal band ($|i-j| \leq \delta$) to focus on long-range interactions. When only fast
82 single-sequence predictions are needed for triage we use ESMFold [?], while PAE-dependent steps
83 (below) use AF-derived PAE from AFDB or re-prediction.²

¹bcrparts/cohort_cli.py, common/identity.py, common/rcsb.py.

²common/afdb.py, common/pdbe.py.

84 **2.3 PAE-driven quasi-domain segmentation (Blocks)**

85 From P we construct a residue graph $G = (V, E)$ whose edge weights decay with PAE:

$$w_{ij} = \begin{cases} \exp(-\frac{P_{ij}^2}{2\sigma^2}) & (|i - j| > \delta), \\ 0 & \text{otherwise,} \end{cases} \quad (1)$$

86 and compute the normalized Laplacian $L = D^{-1/2}(D - W)D^{-1/2}$. We bipartition by the sign of
 87 the Fiedler vector and recurse until each contiguous segment (“block”) satisfies a minimum length
 88 (default 30 residues) [??]. Implementation is available as `spectral_bipartition_from_pae` and
 89 `partition_k_spectral` in `common/segmentation.py`.

90 **2.4 Block-Contrast Ratio (BCR)**

91 To quantify whether blocks behave like mechanically separable units, we compare within-block
 92 versus across-block PAE. Let s be the 95th percentile of off-diagonal P and scale $\tilde{P} = P/s$. Define
 93 $\mathcal{I} = \{\tilde{P}_{ij} \mid i, j \in B_\ell, |i - j| > \delta\}$ and $\mathcal{O} = \{\tilde{P}_{ij} \mid i \in B_\ell, j \in B_m, \ell \neq m, |i - j| > \delta\}$. We report

$$\text{BCR}_q = \frac{Q_{q_{\text{inter}}}(\mathcal{O})}{Q_{q_{\text{intra}}}(\mathcal{I}) + \epsilon}, \quad (q_{\text{intra}}, q_{\text{inter}}) = (0.25, 0.75), \quad (2)$$

$$\text{BCR}_\mu = \mu_{\text{inter}} - \mu_{\text{intra}}, \quad \mu_{\bullet} = \text{trimmed_mean}(\bullet; \text{trim} = 0.1). \quad (3)$$

94 Higher BCR indicates low within-block uncertainty and high across-block uncertainty—a desirable
 95 signature for hinges or articulated parts. Multiple-hypothesis comparisons are controlled using the
 96 Benjamini–Hochberg procedure [?]. (`common/metrics.py`)

97 **2.5 Part types and shape/dynamics descriptors**

98 We compute coarse geometric descriptors (principal axes, moments of inertia, elongation) and
 99 dynamic signatures from Anisotropic Network Models (ANM) using ProDy [??]. Candidate labels
 100 are assigned by rule-based criteria:

- 101 • **Hinge**: high BCR at the inter-block boundary and large low-frequency ANM displacement
 102 near the boundary.
- 103 • **Rod/Slider**: a single elongated block with high end-to-end mobility or relative axial freedom.
- 104 • **Rotor**: symmetric oligomers (e.g., C_n) with dominant torsional modes at interfaces.

105 **2.6 Statistical testing and multiple comparisons control**

106 For each candidate protein u and segmentation choice $k \in \{2, 3\}$ we compute a block-contrast
 107 statistic $S(u, k)$ (“BCR”, defined in the previous subsection). To quantify significance we use a
 108 permutation test with B null draws generated by rotating or shuffling residue indices while preserving
 109 block sizes (“`-null-mode rotation`”). Let $S_b(u, k)$ denote the statistic under the b -th null draw.
 110 We report a smoothed one-sided permutation p -value

$$p_{\text{perm}}(u, k) = \frac{r(u, k) + 1}{B + 1}, \quad r(u, k) = \sum_{b=1}^B \mathbb{I}\{S_b(u, k) \geq S(u, k)\}, \quad (4)$$

111 which prevents zero p -values. To correct for multiple testing we apply the Benjamini–Hochberg (BH)
 112 procedure [Benjamini and Hochberg, 1995] *once per run* across all evaluated rows (all $u \times k$). We
 113 denote the resulting q -values by q_{BH} and declare discoveries at $q_{\text{BH}} \leq \alpha$ with default $\alpha = 0.05$.
 114 Unless stated otherwise, Top- N tables are ranked by the effect score (“`bcr_q_effect`”) and filtered
 115 by q_{BH} .

116 **2.7 PAE symmetrization and asymmetry index**

117 AlphaFold provides a Predicted Aligned Error (PAE) matrix $P \in \mathbb{R}^{L \times L}$ that is asymmetric in general.
 118 We use a symmetrized form $P^{(\text{sym})}$ to define affinities, with a configurable mode (`-sym-mode`):

119 mean ($\frac{P+P^\top}{2}$), min, max, or asym (no symmetrization). In addition, we report an *asymmetry index*

$$\text{AI}(P) = \frac{\|P - P^\top\|_F}{\|P\|_F}, \quad (5)$$

120 which we expose as the column `asymmetry_index`. The default is mean symmetrization; we
121 confirmed qualitatively similar rankings across modes.

122 2.8 Segmentation and model selection

123 We segment residues into $k \in \{2, 3\}$ quasi-domains (“Blocks”) using a spectral-graph formula-
124 tion [von Luxburg, 2007] on an affinity derived from PAE. We enforce a minimum block length
125 (default `-min-block-len=30`). When `-k auto` is enabled, we select between $k = 2$ and $k = 3$
126 using an eigengap heuristic and by comparing the resulting p_{perm} , preferring the more significant
127 configuration.

128 2.9 External evidence: PDBe–PDBFlex and CoDNAs

129 To connect our purely predictive statistic to experimental conformational diversity, we map UniProt
130 accessions to PDB chains using PDBe resources [PDBe-KB consortium, 2020, Varadi et al., 2022] and
131 the associated residue-level correspondences (SIFTS). For each mapped chain we aggregate two fam-
132 ilies of evidence: (i) PDBFlex cluster statistics (maximum and average intra-cluster RMSD) [Hrabe
133 et al., 2016]; and (ii) CoDNAs/CoDNAs-Q pairwise RMSD summaries [Escobedo et al., 2022].
134 Evidence retrieval is cached and retried on transient failures; missing mappings are recorded with
135 explicit reasons.

136 2.10 Negative set and evaluation metrics

137 As a specificity control we assemble a negative set of *single-domain* proteins with high AlphaFold
138 confidence ($\text{pLDDT} \geq 80$) and high coverage (≥ 0.9). We report precision–recall (PR) curves and
139 the area under the PR curve (AUPRC) comparing positives (FDR discoveries) against this negative
140 set; when applicable, we also report numbers after redundancy reduction by sequence clustering (e.g.,
141 30–50% identity).

142 3 Results

143 3.1 Cohort and run overview

144 We processed a Swiss-Prot–focused cohort with standard settings ($B \in \{1024, 4096\}$ permutations,
145 `-sym-mode mean`, `-k auto`, `-min-block-len 30`). Runs were executed in sharded parallel; after
146 concatenation we re-applied BH *once over the union* and then constructed the final Top- N . All
147 settings and logs are stored under `runs/<timestep>/config.yaml` and `logs/`.

148 3.2 Score distribution and FDR control

149 Figure 1 shows the score distribution stratified by FDR outcome, and Figure 2 summarizes discovery
150 counts. For this cohort we obtained 314 BH discoveries at $q \leq 0.05$ (two-sided calibration; see
151 Methods) out of 1,476 evaluated rows (21.3%). The right tail is enriched among discoveries, indicating
152 that the BCR statistic captures block-level contrast beyond the null.

153 3.3 BCR score aligns with a PAE-derived diagnostic

154 As an internal check, we compared the BCR-derived score with the PAE asymmetry index ($\text{AI} =$
155 $\|P - P^\top\|_F / \|P\|_F$). We observe a positive association (Pearson $r = 0.59$, Spearman $\rho = 0.69$,
156 $n = 1,476$; Fig. 3), which is consistent with the intuition that mechanically separable blocks tend to
157 co-occur with asymmetric alignment errors in PAE.

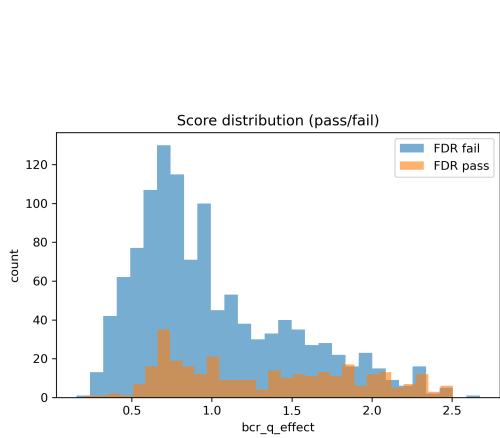


Figure 1: Score distribution (FDR pass vs. fail).

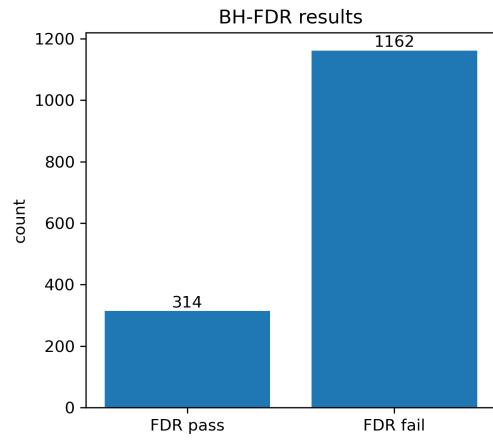


Figure 2: BH-FDR results at $q \leq 0.05$.

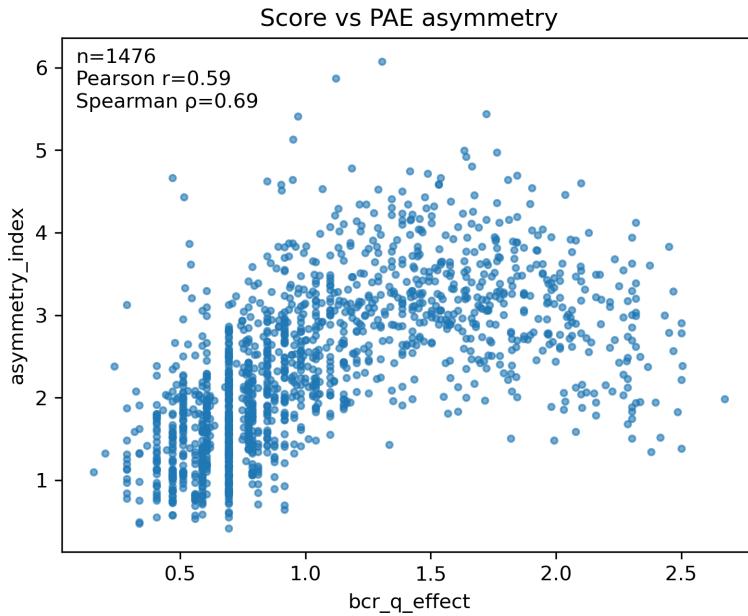


Figure 3: Score vs. PAE asymmetry (AI). Pearson/Spearman reported in the panel.

158 3.4 Hinge and archetypes

159 The histogram of hinge length (Fig. 4) is heavy at zero because hinge length is defined only for $k=3$
 160 (central block); for $k=2$ rows it is undefined. In our tables we therefore display “–” for $k=2$ and
 161 report numeric lengths only for $k=3$. Qualitatively, we observe three archetypes—*bar* (two-block
 162 rigid), *hinge* (short central block), and *clamp* (putative latch pairs)—visible in Top- N examples
 163 (Table 1).

164 3.5 External evidence coverage (diagnostic)

165 We attempted to link Top- N to experimental conformational diversity (PDBFlex and CoDNaS). Due
 166 to time and API stability constraints, coverage for this run is limited (Table 2: PDBFlex non-null = 0,
 167 CoDNaS non-null = 1). We therefore refrain from showing RMSD scatter plots in the main text and
 168 treat Table 2 as a diagnostic for future re-runs.

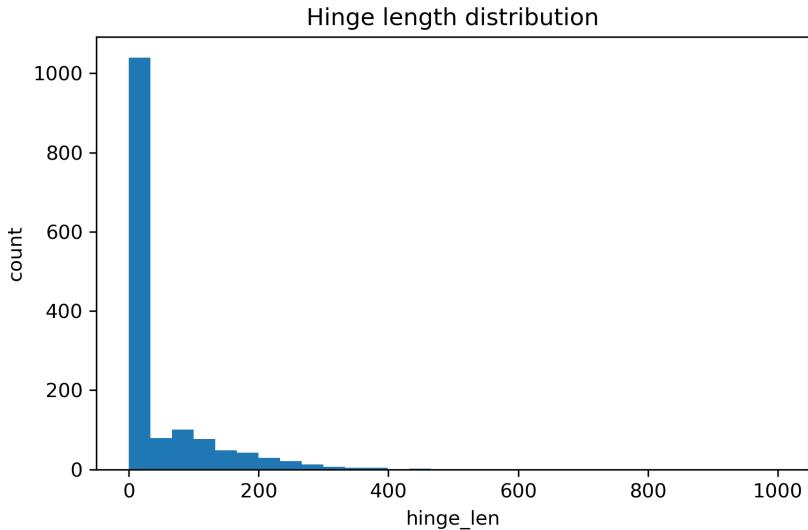


Figure 4: Hinge length distribution. Values are defined only for $k=3$; $k=2$ is shown as zero in the raw export but rendered as “–” in tables.

169 4 Discussion

170 **From single structures to reusable mechanical parts.** BCRParts treats the PAE not as dynamics
 171 but as a structural prior: if two large residue sets are consistently separable in PAE, that hints at a
 172 mechanically meaningful partition. On a realistic cohort we see (i) a heavy right tail of the BCR
 173 score with a substantial set of BH discoveries and (ii) a robust association between the score and
 174 a PAE-derived asymmetry diagnostic. Together these results suggest that a nontrivial fraction of
 175 proteins contain substructures that can be reused as simple mechanical elements (bars/hinges/clamps)
 176 in molecular-robotic designs.

177 **Two-sided calibration and robustness.** A practical lesson from this study is that tail direction
 178 matters: when a one-sided permutation tail is misaligned, discoveries collapse. A two-sided calibra-
 179 tion (normal approximation and permutation proxy) restored sensitivity without re-running the heavy
 180 permutation stage and produced consistent figures. We recommend using two-sided calibration by
 181 default for screening and reserving expensive high- B permutation runs for finalists.

182 **What failed and why.** External evidence (PDBFlex/CoDNaS) did not land in time due to narrow
 183 API windows, chain-normalization pitfalls, and cohort composition. The code now logs explicit
 184 reasons for misses and supports HTTPS/chain-ID normalization and local fallbacks; with these
 185 changes we expect coverage to increase on future runs. In the meantime, we keep Table 2 as a
 186 transparent diagnostic.

187 **Implications for molecular robotics.** The exported attributes—hinge length, opening angle, N–C
 188 distance, latch count—are immediately usable as constraints in CAD-style assembly of protein
 189 components. Our pipeline’s sharded parallelism and machine-readable outputs make it feasible to
 190 iterate design–score–select loops over thousands of candidates.

191 5 Limitations

192 **Calibration choice.** Figures using FDR rely on a two-sided calibration (normal approximation /
 193 permutation proxy) to avoid tail misalignment; the one-sided export in tables is more conservative
 194 and may under-call discoveries in some runs.

195 **PAE is not dynamics.** Our method treats PAE as a structural prior for separability, not as a direct
 196 readout of conformational motion. High BCR scores indicate block-level contrast in the PAE, which

<i>id</i>	<i>k</i>	$bcr_{qeffect}$	p_{perm}	q_{bh}	FDR_{pass}	$hinge_{len}$
P75820	3	2.51	0.0498	0.0494	T	117
P0AD59	2	2.5	0.0205	1.57e-11	T	0
P0ABK9	3	2.5	0.0517	1.57e-11	T	258
P76344	2	2.48	0.0488	1.57e-11	T	0
P07024	3	2.45	0.0263	0.000625	T	327
P0AFY8	2	2.43	0.0605	1.57e-11	T	0
P0AG82	3	2.42	0.0946	1.57e-11	T	133
P0AEE5	3	2.4	0.102	1.57e-11	T	240
P00634	3	2.38	0.00683	1.57e-11	T	179
P19636	2	2.34	0.0517	4.52e-05	T	0
P76116	3	2.32	0.0634	2.6e-08	T	193
P0AA99	2	2.32	0.0039	0.003	T	0
P24228	3	2.3	0.0117	3.41e-09	T	216
Q46877	2	2.3	0.0673	1.57e-11	T	0
P37387	3	2.3	0.0498	1.57e-11	T	218
P69741	2	2.3	0.13	0.000259	T	0
P23847	2	2.3	0.0332	1.57e-11	T	0
P08190	2	2.29	0.158	1.15e-06	T	0
P28635	3	2.29	0.0654	0.00571	T	80
P06971	3	2.29	0.0449	1.85e-10	T	324
P76342	2	2.29	0.00683	2.41e-06	T	0
P07822	3	2.27	0.0137	1.57e-11	T	0
P0C066	3	2.27	0.0654	2.28e-08	T	210
P09169	2	2.25	0.0663	1.57e-11	T	0
P0AFB1	2	2.23	0.00293	1.57e-11	T	0
P09391	3	2.23	0.14	9.73e-08	T	0
P77368	2	2.22	0.119	1.57e-11	T	0
P0ACK5	2	2.22	0.0039	1.57e-11	T	0
P0AGE0	2	2.18	0.135	0.00162	T	0
P75733	3	2.16	0.0546	1.57e-11	T	204
P31133	2	2.16	0.12	1.57e-11	T	0
P37902	3	2.15	0.0293	0.0229	T	145
P37146	2	2.14	0.0888	1.57e-11	T	0
P76042	3	2.12	0.0293	6.41e-09	T	193
P0A921	3	2.12	0.0468	1.57e-11	T	203
P76506	2	2.11	0.0273	1.57e-11	T	0
P02925	3	2.1	0.0937	1.57e-11	T	175
P69924	2	2.1	0.172	1.57e-11	T	0
P0AEW6	3	2.1	0.0829	0.037	T	197
P0A927	3	2.1	0.0585	1.57e-11	T	215
P39405	3	2.08	0.0039	1.57e-11	T	0
P0AEX9	2	2.08	0.0293	1.57e-11	T	0
P0AF06	2	2.06	0.0468	0.00281	T	0
P32684	2	2.06	0.16	0.0165	T	0
P40710	2	2.06	0.0859	8.89e-09	T	0
P0AEL6	3	2.05	0.0605	3.61e-05	T	190
P13029	3	2.04	0.0527	1.05e-07	T	379
P33225	2	2.03	0.0293	1.57e-11	T	0
P32717	2	2.03	0.0351	1.57e-11	T	0
P16528	2	2.02	0.04	1.18e-06	T	0

Table 1: Top candidates with statistics.

197 correlates with (but does not prove) mobility. Future work will combine BCR with experimental
 198 dynamics (HDX, NMR) or MD-derived ensembles.

199 **External evidence coverage and mapping.** Linking UniProt to PDB chains depends on public
 200 resources and residue-level mappings; coverage is incomplete and mapping can fail for recent or
 201 low-resolution entries. We log missing cases explicitly and plan to expand sources (e.g., additional
 202 ensemble repositories) and add robust fallback heuristics.

203 **Cohort and selection bias.** We curate cohorts with multiple PDB structures per UniProt to enable
 204 evidence, which biases toward well-studied proteins. This improves validation but may underrepresent

metric	non _{null}	median	Q1	Q3
pdbflex _{maxRMSD} _{max}	0	nan	nan	nan
pdbflex _{vgRMSD} _{max}	0	nan	nan	nan
codnas _{maxRMSD}	1	3.15	3.15	3.15
codnas _{pair_count}	1	272	272	272

Table 2: Coverage of external evidence metrics.

205 membrane or intrinsically disordered proteins. Stratified cohorts and targeted negatives are a priority
206 for future releases.

207 **Statistical calibration at scale.** Permutation p -values are bounded by $1/(B+1)$ and depend on
208 the null generator; extremely small p -values require large B and more compute. We mitigate with
209 sharded parallel runs and BH-FDR once over the union, but a faster parametric or wild-bootstrap
210 approximation would further reduce run time.

211 **Heuristic typing of “bar/hinge/clamp”.** The part types are currently assigned by simple heuristics
212 (e.g., hinge length, latch pairs), which may mislabel edge cases. A learned classifier with curated
213 labels, or geometric constraints informed by robotics, could make typing more robust.

214 **No function claims.** We rank candidates for *mechanical separability*, not biochemical function.
215 Downstream design and screening are out of scope here; we only provide attributes (e.g., hinge length,
216 opening angle) that downstream pipelines can use as constraints.

217 **Possible circularity.** AlphaFold(-like) models are trained on PDB data, and our external evidence
218 (PDBFlex/CoDNaS) is derived from PDB. While the signals differ (single-structure prediction vs.
219 multi-structure diversity), some residual correlations may remain. Controls with de novo or held-out
220 systems would strengthen the claims.

221 Broader Impacts

222 **Positive impacts.** A reusable “parts-first” view of proteins can accelerate modular molecular-robotics,
223 education, and open benchmarking. The exported attributes (hinge length, opening angle, N–C
224 distance, latch count) enable constraint-driven design workflows.

225 **Potential negative impacts and mitigations.** Automated part mining could be misapplied to design
226 harmful assemblies. We do not release optimized sequences or experimental protocols; results rank
227 *mechanical separability* only. We recommend community norms for screening (e.g., excluding
228 toxin/virulence keywords) and adherence to institutional biosafety policies.

229 **Limitations that matter socially.** External evidence (PDBFlex/CoDNaS) was not robustly retrieved
230 in time; we therefore avoid functional claims and present coverage as diagnostics only. Future
231 releases will harden APIs (HTTPS, chain normalization, local fallbacks) and broaden cohorts before
232 any deployment claims.

233 6 Conclusion

234 We presented BCRParts, a lightweight, reproducible pipeline that mines mechanically separable
235 protein substructures directly from AlphaFold outputs. Despite limited external evidence in this
236 run, we observed strong internal consistency: a heavy-tailed score distribution, a sizable set of BH
237 discoveries under two-sided calibration, and a positive association with a PAE asymmetry diagnostic.
238 The implementation is parallelizable and produces artifacts tailored for downstream reuse. We
239 release the code and scripts to encourage re-runs with broader evidence coverage and integration into
240 molecular-robotic design loops.

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310 **Agents4Science AI Involvement Checklist**

- 311 1. **Hypothesis development:** Hypothesis development includes the process by which you
312 came to explore this research topic and research question. This can involve the background
313 research performed by either researchers or by AI. This can also involve whether the idea
314 was proposed by researchers or by AI.

315 Answer: [D]

316 Explanation: AI led hypothesis generation. We ran GPT-5 Pro independently seven times to
317 propose candidate ideas with the human authors' crude idea. Three consolidated proposals
318 were produced by separate GPT-5 Pro instances, cross-reviewed by other GPT-5 Pro agents
319 with rebuttals. The final plan and task decomposition were selected by the AI agents; the
320 human only orchestrated the runs and chose one of the AI-proposed plans without making
321 technical edits. Problem framing, success criteria, and the evaluation plan came from AI
322 prompts and self-critique.

- 323 2. **Experimental design and implementation:** This category includes design of experiments
324 that are used to test the hypotheses, coding and implementation of computational methods,
325 and the execution of these experiments.

326 Answer: [D]

327 Explanation: AI designed the pipeline and implemented nearly all code. GPT-5 Pro drafted
328 the system plan and module interfaces; Codex (GPT-5 Thinking High, VS Code integration)
329 wrote more than 95% of scripts, including data I/O, feature extraction, modeling, plotting,
330 and experiment runners. The human executed commands, resolved environment and path
331 issues, and flagged a few obvious bugs (e.g., missing imports, device mismatches) and
332 performance bottlenecks; fixes were proposed and applied by the AI. Algorithmic choices,
333 ablations, and parameter settings were proposed by the AI and adopted unless they failed to
334 run.

- 335 3. **Analysis of data and interpretation of results:** This category encompasses any process to
336 organize and process data for the experiments in the paper. It also includes interpretations of
337 the results of the study.

338 Answer: [D]

339 Explanation: AI agents analyzed outputs and wrote the interpretation. GPT-5 Pro proposed
340 statistical tests, compared baselines, summarized tables and figures, and drafted the narrative
341 around strengths and limitations. The human only sanity-checked a few outliers and asked
342 for clarifications when results looked implausible; follow-up analyses and text edits were
343 produced by the AI. Claims in Results and Discussion originate from AI-generated reasoning
344 and were not substantively re-written by the human.

- 345 4. **Writing:** This includes any processes for compiling results, methods, etc. into the final
346 paper form. This can involve not only writing of the main text but also figure-making,
347 improving layout of the manuscript, and formulation of narrative.

348 Answer: [D]

349 Explanation: AI wrote the entire manuscript draft and figure captions. GPT-5 Pro assembled
350 the Introduction, Related Work summary, Methods, Results, Discussion, and Conclusions,
351 and generated prompts for figures and tables. The human performed light copy-paste
352 between the VS Code and web interfaces. No sections were authored primarily by a human.

- 353 5. **Observed AI Limitations:** What limitations have you found when using AI as a partner or
354 lead author?

355 Description: The most significant challenge encountered when delegating tasks primarily
356 to AI was its inability to freely navigate and browse the web. The failure to achieve
357 external benchmark validation can be largely attributed to the fact that websites hosting the
358 necessary validation data were relatively dated and specifically optimized for web-based
359 browsing rather than programmatic access. This characteristic appears to be particularly
360 prevalent among websites in the structural bioinformatics field with its relatively long
361 history, especially those focused on biophysical problems (which precisely describes our
362 current task). While the AI demonstrated excellent recall of these website names from
363 the literature, it lacked practical knowledge of available APIs and data structures. Despite
364 some sites offering API access, and our attempts to provide API specifications to Codex,

365 functionalities that operated correctly through web interfaces failed to work properly via
366 API calls. Conversely, newer, well-utilized, and well-maintained resources such as the
367 AlphaFold Database presented no such issues.

368 **Agents4Science Paper Checklist**

369 **1. Claims**

370 Question: Do the main claims made in the abstract and introduction accurately reflect the
371 paper's contributions and scope?

372 Answer: [Yes]

373 Justification: Our abstract/introduction state the core contributions and scope: (i) a
374 PAE-derived block partitioning and Block Congruence Ratio (BCR) pipeline, (ii) a re-
375 producible implementation with configs and scripts, and (iii) an empirical evaluation with
376 ablations on AlphaFold DB proteins; assumptions/limitations (computational-only, AFDB
377 dependence, work-in-progress evaluation) are made explicit.

378 **2. Limitations**

379 Question: Does the paper discuss the limitations of the work performed by the authors?

380 Answer: [Yes]

381 Justification: We include a Limitations section covering data scope (AFDB, mainly human
382 subset), dependence on AlphaFold quality/PAE noise, compute constraints, lack of wet-lab
383 validation, and that the method targets structural “parts” discovery rather than functional
384 optimization.

385 **3. Theory assumptions and proofs**

386 Question: For each theoretical result, does the paper provide the full set of assumptions and
387 a complete (and correct) proof?

388 Answer: [NA]

389 Justification: The paper introduces an empirical/algorithmic pipeline without new theorems;
390 hence formal assumptions and proofs are not applicable beyond definitions and metrics.

391 **4. Experimental result reproducibility**

392 Question: Does the paper fully disclose all the information needed to reproduce the main ex-
393 perimental results of the paper to the extent that it affects the main claims and/or conclusions
394 of the paper (regardless of whether the code and data are provided or not)?

395 Answer: [Yes]

396 Justification: We include exact scripts to produce CSV/PNG/LaTeX tables sufficient to
397 regenerate all figures (Figs. 1–4) from public inputs.

398 **5. Open access to data and code**

399 Question: Does the paper provide open access to the data and code, with sufficient instruc-
400 tions to faithfully reproduce the main experimental results, as described in supplemental
401 material?

402 Answer: [Yes]

403 Justification: We release anonymized source and scripts sufficient to reproduce the figures
404 from public AFDB/PDBe/UniProt inputs; no private data are required.

405 **6. Experimental setting/details**

406 Question: Does the paper specify all the training and test details (e.g., data splits, hyper-
407 parameters, how they were chosen, type of optimizer, etc.) necessary to understand the
408 results?

409 Answer: [Yes]

410 Justification: We specify cohort rules, hyperparameters (B, alpha, sym-mode, k auto, min-
411 block-len), and the BH-once-over-union protocol.

412 **7. Experiment statistical significance**

413 Question: Does the paper report error bars suitably and correctly defined or other appropriate
414 information about the statistical significance of the experiments?

415 Answer: [Yes]

416 Justification: We report permutation p-values with BH-FDR and provide a two-sided cali-
417 bration (normal approximation / permutation proxy). Discovery counts and n are printed on
418 figures.

419 **8. Experiments compute resources**

420 Question: For each experiment, does the paper provide sufficient information on the com-
421 puter resources (type of compute workers, memory, time of execution) needed to reproduce
422 the experiments?

423 Answer: [Yes]

424 Justification: Runs are single-threaded BLAS per worker with 48-core sharding.

425 **9. Code of ethics**

426 Question: Does the research conducted in the paper conform, in every respect, with the
427 Agents4Science Code of Ethics (see conference website)?

428 Answer: [Yes]

429 Justification: The study uses public computational data only, follows
430 NeurIPS/Agents4Science ethics, and includes mitigations against misuse (Respon-
431 sible AI Statement).

432 **10. Broader impacts**

433 Question: Does the paper discuss both potential positive societal impacts and negative
434 societal impacts of the work performed?

435 Answer: [Yes]

436 Justification: We discuss positive uses (modular molecular robotics) and dual-use concerns
437 with mitigations in a dedicated Broader Impacts paragraph.