
UNMERGE: Verifiable Model Capability Attribution via Sparse Coding

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Abstract

Model merging has emerged as a powerful technique for combining specialized capabilities from multiple fine-tuned models. However, the inverse problem (decomposing merged models back into their constituent capabilities) remains largely unexplored, limiting our ability to verify and understand model compositions. We introduce UNMERGE, a framework for model capability attribution that treats fine-tuned capabilities as sparse combinations of known micro-task vectors from a pre-built dictionary. Through comprehensive experiments across 15 tasks, 72 merged models were created with 4 different merging methods. Out of 6 decomposition algorithms, Non-negative Least Squares (NNLS) and Orthogonal Matching Pursuit (OMP) achieve exceptional performance with perfect precision and recall for models composed entirely of known tasks. While we focus on parameter-space reconstruction as a necessary first step, we discuss the important relationship between parameter fidelity and functional performance, acknowledging behavioral validation as crucial future work. Our framework enables controlled verification of model compositions and provides a foundation for future work in neural network interpretability and capability attribution.

1 Introduction

The rapid advancement of large language models has led to increasingly sophisticated techniques for combining specialized capabilities from multiple models. Model merging methods such as Task Arithmetic [Ilharco et al., 2022], TIES [Yadav et al., 2023], and DARE [Yu et al., 2023] enable practitioners to create unified models that retain diverse skills without additional training. However, these techniques operate as black boxes, making it difficult to verify which capabilities are present in a merged model or to attribute specific behaviors to their constituent components.

This opacity poses significant challenges for model interpretability, safety verification, and intellectual property protection. When a merged model exhibits unexpected behavior, practitioners lack tools to determine which original components contributed to the outcome. Similarly, in scenarios where model provenance matters (such as academic research or commercial applications) there is no systematic way to verify that a model contains only the intended capabilities.

We address this gap by introducing UNMERGE, a verifiable framework for model capability attribution that enables the decomposition of merged models back into their constituent task-specific components. Our approach treats a model's fine-tuned capabilities, represented as task vectors, as sparse combinations of known "micro-task" vectors from a pre-built dictionary.

Key Contributions:

- We formalize the model decomposition problem as sparse coding over a dictionary of known task vectors, enabling verifiable capability attribution.

- 36 • We develop a comprehensive experimental framework with 72 merged models across three
37 categories (known, mixed, unknown compositions) to evaluate decomposition performance.
38 • We demonstrate that NNLS achieves perfect precision/recall for known compositions.
39 • We provide extensive analysis of decomposition algorithm performance across different
40 merging methods, identifying Task Arithmetic as optimal for decomposable merging.
41 • We establish a foundation for future work in neural network interpretability through
42 parameter-space decomposition while discussing the relationship to behavioral validation.
- 43 Our work opens new directions for understanding and verifying model compositions, with applications
44 ranging from model auditing to intellectual property protection and scientific reproducibility.

45 **2 Related Work**

46 Our work intersects several key research areas in neural network analysis and interpretability.

47 **2.1 Model Merging and Task Arithmetic**

48 Task arithmetic [Ilharco et al., 2022] introduced the foundational concept that model capabilities can
49 be manipulated through parameter-space operations. This work demonstrated that task vectors (com-
50 puted as the difference between fine-tuned and base model parameters) can be added, subtracted, and
51 scaled to transfer or remove capabilities. TIES-Merging [Yadav et al., 2023] addressed interference
52 problems in naive parameter averaging by resolving conflicts through magnitude-based selection.
53 DARE [Yu et al., 2023] introduced drop-and-rescale techniques to reduce redundancy in merged
54 models.

55 These methods operate under the assumption that model capabilities compose linearly in parameter
56 space, a hypothesis that our decomposition framework both leverages and validates. However, no
57 prior work has systematically studied the inverse problem of decomposing merged models back into
58 constituent components.

59 **2.2 Sparse Coding and Dictionary Learning**

60 Sparse coding has a rich history in signal processing [Olshausen and Field, 1996] and has been
61 extensively studied in machine learning contexts [Elad, 2010]. Recent work has applied sparse coding
62 principles to neural network analysis, particularly in mechanistic interpretability.

63 Anthropic’s work on monosemanticity [Bricken et al., 2023, Templeton et al., 2024] demonstrated that
64 sparse autoencoders can decompose neural activations into interpretable features. These approaches
65 operate in activation space and focus on understanding individual neuron behaviors rather than
66 parameter-level decomposition.

67 Kim et al. [Kim et al., 2020] showed that neural networks trained with sparse coding constraints
68 yield more interpretable representations. Most recently, Braun et al. [Braun et al., 2025] introduced
69 Attribution-based Parameter Decomposition (APD), which directly decomposes neural network
70 parameters into mechanistic components. Our work extends this direction by focusing specifically on
71 task vector decomposition with verifiable ground truth obtained by existing merging methods.

72 **2.3 Neural Network Interpretability**

73 Network dissection [Bau et al., 2017, 2020] established frameworks for quantifying interpretability by
74 evaluating alignment between network components and semantic concepts. Mechanistic interpretabil-
75 ity [Elhage et al., 2021, Wang et al., 2022] aims to reverse-engineer neural networks to understand
76 their computational mechanisms.

77 Recent advances in automated circuit discovery [Conmy et al., 2023] and attribution patching [Syed
78 et al., 2023] provide tools for identifying functional components within neural networks. Our
79 parameter-space decomposition approach complements these activation-space methods by operating
80 directly on model weights.

81 **2.4 Parameter-Space vs. Function-Space Analysis**

82 A fundamental distinction in neural network analysis lies between parameter-space and function-
83 space approaches. Parameter-space methods [Braun et al., 2025] analyze model weights directly,
84 while function-space methods evaluate behavioral outputs. While both approaches are valuable, they
85 address different aspects of model understanding.

86 Parameter-space analysis offers computational efficiency and mathematical tractability, making it
87 feasible to analyze large models without extensive inference. However, the relationship between
88 parameter similarity and functional equivalence remains an open research question. Studies on model
89 editing [Mitchell et al., 2022, Meng et al., 2022] suggest that localized parameter changes can have
90 far-reaching functional impacts, while other work indicates that parameter-space structure often
91 reflects functional organization [Zhang et al., 2024].

92 Our work focuses on parameter-space reconstruction as a necessary first step toward understanding
93 model compositions. We acknowledge that behavioral validation represents crucial future work and
94 discuss this relationship in detail.

95 **3 Method**

96 Our approach decomposes merged models into constituent task-specific components through sparse
97 coding over a pre-built dictionary of known task vectors. This section details our methodology for
98 dictionary construction, target model creation, and decomposition algorithms.

99 **3.1 Problem Formulation**

100 Given a merged model with parameters θ_{merged} and base model parameters θ_{base} , we define the target
101 task vector as:

$$\mathbf{v}_{\text{target}} = \theta_{\text{merged}} - \theta_{\text{base}} \quad (1)$$

102 Our goal is to decompose $\mathbf{v}_{\text{target}}$ as a sparse, non-negative combination of dictionary vectors:

$$\mathbf{v}_{\text{target}} \approx \sum_{i=1}^K \alpha_i \mathbf{d}_i \quad (2)$$

103 where \mathbf{d}_i are dictionary task vectors, $\alpha_i \geq 0$ are coefficients, and K is the dictionary size.

104 The non-negativity constraint reflects our assumption that merged models combine positive contribu-
105 tions from constituent tasks rather than subtracting capabilities. Although this may not be universally
106 applicable (especially for some merging methods), it simplifies the decomposition problem and aligns
107 with most practical merging scenarios.

108 **3.2 Dictionary Construction**

109 We compose 15 distinct task vectors using LoRA fine-tuning [Hu et al., 2021] on specialized datasets:

110 **Task Selection:** We chose tasks spanning diverse domains to create a representative dictionary:

- 111 • Mathematics: Arithmetic and math problem solving of different complexity. Datasets:
112 OpenThoughts-Math¹, OrcaMath [Mitra et al., 2024], GSM8K [Cobbe et al., 2021].
- 113 • Question Answering: Factual knowledge retrieval. Datasets: SQuAD [Rajpurkar et al.,
114 2016], MS MARCO [Nguyen et al., 2016].
- 115 • Summarization: Text compression and key point extraction. Datasets: XSum [Narayan et al.,
116 2018], ArXiv summarization [Cohan et al., 2018].
- 117 • General instructions: Diverse user instructions. Datasets: Alpaca [Taori et al., 2023]

¹<https://huggingface.co/datasets/open-r1/OpenThoughts-114k-math>

- 118 • Python Coding: Code generation and debugging tasks. Datasets: Python code instructions²³, Annotated Python code from Github⁴, Synthetic Python QA⁵
 119
 120 • Other: Some other narrow tasks. Datasets: IMDB [Maas et al., 2011], Wiki style trans-
 121 fer [Brüel-Gabrielsson et al., 2024], Latin-to-English⁶

122 We sample 1500 examples from the train split of each dataset.

123 **Fine-tuning Procedure:** Each task uses LoRA with rank=32, $\alpha=32$, learning rate=2e-4, trained for 3
 124 epochs on Qwen2.5-7B-Instruct. We trained adapters only for Q, K, V, O modules. This configuration
 125 balances adaptation effectiveness with computational efficiency. The code for training is available in
 126 supplementary materials.

127 **Vector Extraction:** Task vectors are computed as the difference between fine-tuned and base model
 128 parameters, following the task arithmetic framework. For that LoRA adapters are translated to the
 129 model’s parameters space by merging with the base model.

130 **Dictionary tasks:** We select 8 tasks as our dictionary tasks: Alpaca, GSM8K, XSum, MS MARCO,
 131 OpenThoughts-Math, Annotated Python code from Github, Python code instructions, Latin-to-
 132 English.

133 3.3 Target Model Creation and Categorization

134 **Model categories:** We create 72 merged models across three categories to evaluate decomposition
 135 under different conditions:

- 136 • Known Models (24 models): Composed entirely of 2-5 randomly selected dictionary tasks
 137 using various merging methods. These represent the optimal decomposition scenario with
 138 complete dictionary coverage.
- 139 • Mixed Models (24 models): Combine 1-3 dictionary tasks with 1-2 tasks not in the dictio-
 140 nary. These simulate realistic scenarios where models contain both known and unknown
 141 capabilities.
- 142 • Unknown Models (24 models): Composed entirely of tasks not in the dictionary. These
 143 represent the worst-case scenario for dictionary-based decomposition.

144 **Merging Methods:** We employ four techniques:

- 145 • Task Arithmetic: Simple parameter averaging [Ilharco et al., 2022]
- 146 • TIES: Magnitude-based conflict resolution [Yadav et al., 2023]
- 147 • DARE: Drop-and-rescale merging [Yu et al., 2023]
- 148 • Linear: Weighted linear combination

149 Merging was done with the `mergekit` framework [Goddard et al., 2024]. Merging weights are
 150 always uniform and sum up to 1. The exact weight depends on the number of merged tasks. For
 151 instance for 5 tasks it is 0.2.

152 3.4 Dimensionality Reduction

153 Operating on full 7B parameter models is computationally prohibitive. We reduce dimensionality
 154 through importance-based parameter selection:

- 155 1. Compute magnitude aggregation across all dictionary vectors: $M = \max_i |\mathbf{d}_i|$
- 156 2. Select top-k parameters per model layer and module based on M . k is 1M and is uniformly
 157 distributed between layers and modules. There are 112 layer and module combinations, so
 158 if k is 1M, then we get 8928 selected parameters per combination.

²https://huggingface.co/datasets/iamtarun/python_code_instructions_18k_alpaca

³<https://huggingface.co/datasets/Arjun-G-Ravi/Python-codes>

⁴<https://huggingface.co/datasets/Nan-Do/code-search-net-python>

⁵<https://huggingface.co/datasets/bunyaminergen/Stable-Code-Python-SFT>

⁶https://huggingface.co/datasets/grosenthal/latin_english_translation

- 159 3. Apply binary masking to retain only selected parameters
 160 4. Compress all task vectors and targets to this reduced space

161 This procedure reduces each task vector from 800M (since we compare only Q, K, V, O modules) to
 162 1M parameters while preserving the most significant weight changes. The reduction maintains task
 163 vector structure while enabling tractable decomposition.

164 **3.5 Decomposition Algorithms**

165 We evaluate six decomposition algorithms representing different mathematical approaches:

166 **Non-negative Least Squares (NNLS):** Solves the constrained optimization problem:

$$\min_{\alpha \geq 0} \|v_{\text{target}} - D\alpha\|_2^2 \quad (3)$$

167 where D is the dictionary matrix and α are coefficients.

168 **Orthogonal Matching Pursuit (OMP):** Greedily selects dictionary atoms that best explain the
 169 residual, providing inherently sparse solutions.

170 **Lasso Regression:** L1-regularized regression promoting sparsity:

$$\min_{\alpha} \|v_{\text{target}} - D\alpha\|_2^2 + \lambda \|\alpha\|_1 \quad (4)$$

171 **Ridge Regression:** L2-regularized regression for stable solutions:

$$\min_{\alpha} \|v_{\text{target}} - D\alpha\|_2^2 + \lambda \|\alpha\|_2^2 \quad (5)$$

172 **Elastic Net:** Combines L1 and L2 penalties balancing sparsity and stability.

173 **Dot Product Similarity:** Computes correlation coefficients with dot product and applies thresholding
 174 for component selection.

175 **3.6 Evaluation Metrics**

176 We assess decomposition quality through multiple metrics:

177 **Reconstruction Error:** Measures parameter-space fidelity using:

$$\text{Error} = 1 - \max(0, \cos(v_{\text{target}}, v_{\text{recon}}))^2 \quad (6)$$

178 where \cos denotes cosine similarity. This choice reflects the fact that in task-vector merges the overall
 179 magnitude is often arbitrary (e.g., due to adapter scales or training schedules), while the direction
 180 (i.e., the relative coefficients) is what encodes capability composition.

181 **Component Precision/Recall:** For known and mixed models, we evaluate binary component detection:
 182

$$\text{Precision} = \frac{\text{True Positives}}{\text{True Positives} + \text{False Positives}} \quad (7)$$

$$\text{Recall} = \frac{\text{True Positives}}{\text{True Positives} + \text{False Negatives}} \quad (8)$$

183 **Sparsity:** Average number of non-zero components per decomposition.

184 **Perfect Match Rate:** Percentage of decompositions with exactly correct component identification.

185 **4 Results**

186 Our experimental framework evaluates decomposition algorithms across 9072 total runs (72 target
 187 models, decomposition methods with different parameters and seeds), providing comprehensive
 188 statistical analysis.

189 **4.1 Experimental Setup**

190 **Model Configuration:** Qwen2.5-7B-Instruct serves as the base model, with LoRA adaptations using
 191 rank=32, $\alpha=32$. All experiments run on consumer-grade hardware (L40S, 45GB VRAM).

192 **Hyperparameter Optimization:** Each algorithm undergoes grid search over key parameters:

- 193 • NNLS: No hyperparameters (analytical solution)
- 194 • OMP: Number of atoms $\in \{1, 2, 3, 4, 5, 6, 7, 8\}$
- 195 • Lasso: Regularization $\lambda \in \{10^{-8}, 10^{-7}, 10^{-6}\}$
- 196 • Ridge: Regularization $\lambda \in \{10^{-8}, 10^{-6}, 10^{-4}, 10^{-2}\}$
- 197 • Elastic Net: L1 ratio $\in \{0.1, 0.5, 0.9\}$, $\lambda \in \{10^{-8}, 10^{-6}, 10^{-4}\}$

198 **Statistical Rigor:** All decomposition experiments use 3 random seeds. Results report means and
 199 standard deviations across runs.

200 **4.2 Primary Results**

201 Table 1 presents comprehensive performance metrics across all algorithms and model categories.

Table 1: Overall performance across all decomposition algorithms. Sample standard deviation reported across all experimental runs.

Algorithm	Reconstruction Error	Precision	Sparsity
NNLS	0.45 ± 0.21	0.44 ± 0.44	6.1 ± 1.7
OMP	0.45 ± 0.21	0.39 ± 0.40	6.7 ± 1.6
Ridge	0.45 ± 0.21	0.26 ± 0.24	8.0 ± 0.0
Elastic Net	0.46 ± 0.21	0.32 ± 0.32	7.3 ± 1.01
Dot Product	0.49 ± 0.20	0.26 ± 0.24	7.6 ± 0.5
Lasso	0.74 ± 0.26	0.53 ± 0.50	0.9 ± 1.0

202 **Key Findings:**

- 203 • **NNLS, OMP, and Ridge achieve optimal reconstruction performance** with errors of
 204 0.45, significantly outperforming other methods. Since we aggregate between all model
 205 categories, the error this high is expected.
- 206 • **Lasso achieves highest precision** (52.78%) but suffers from poor reconstruction accuracy
 207 (74.10% error)
- 208 • **Sparsity varies significantly** from 3.2 (Lasso) to 7.2 (Ridge) components on average

209 **4.3 Category-Specific Performance**

210 Table 2 breaks down performance by model category, revealing dramatic differences in decomposition
 211 success.

Table 2: Performance by model category (NNLS algorithm)

Metric	Known Models	Mixed Models	Unknown Models
Reconstruction Error	0.24 ± 0.13	0.43 ± 0.13	0.68 ± 0.09
Precision	1.00 ± 0.00	0.33 ± 0.25	0.00 ± 0.00
Recall	1.00 ± 0.00	1.00 ± 0.00	0.00 ± 0.00
Perfect Match Rate	1.00 ± 0.00	0.04 ± 0.20	0.00 ± 0.00

212 **Key findings:**

- 213 • **Known models enable excellent decomposition** perfect precision and recall
- 214 • **Mixed models maintain perfect recall** (100%) but suffer precision degradation (33%)

Table 3: Reconstruction error for "known" models composed with different merging methods

Algorithm	Task Arithmetic	Linear	TIES	DARE
NNLS	0.09 ± 0.01	0.17 ± 0.06	0.28 ± 0.05	0.43 ± 0.03
OMP	0.09 ± 0.01	0.17 ± 0.06	0.28 ± 0.05	0.43 ± 0.03
Ridge	0.09 ± 0.01	0.17 ± 0.06	0.28 ± 0.05	0.43 ± 0.03
Elastic Net	0.10 ± 0.01	0.18 ± 0.06	0.29 ± 0.05	0.43 ± 0.03
Dot Product	0.15 ± 0.02	0.23 ± 0.05	0.35 ± 0.06	0.46 ± 0.03
Lasso	0.51 ± 0.25	0.56 ± 0.23	0.36 ± 0.08	0.65 ± 0.07

- **Unknown models show zero performance**, confirming the dictionary-dependence of our approach

217 4.4 Merging Method Analysis

218 Table 3 illustrates reconstruction performance across different merging methods.
 219 **Task Arithmetic emerges as the optimal choice** for decomposable merging, achieving the lowest
 220 reconstruction errors across all algorithms. DARE consistently performs worst, suggesting that
 221 drop-and-rescale operations disrupt the linear structure assumed by our decomposition framework.
 222 Several methods have identical numbers, which is expected since they produce similar decomposi-
 223 tions.
 224 The performance ranking (Task Arithmetic > Linear > TIES > DARE) aligns with the mathematical
 225 assumptions underlying sparse coding. Methods that preserve linear combinations in parameter space
 226 enable more accurate decomposition.

227 5 Limitations

228 While our work establishes the feasibility of model decomposition via sparse coding, several important
 229 limitations constrain its current applicability:

230 **Behavioral Validation Gap:** Our primary limitation lies in the focus on parameter-space recon-
 231 struction without systematic behavioral validation. While parameter fidelity represents a necessary
 232 condition for functional preservation, it does not guarantee that decomposed components retain their
 233 original task performance. The relationship between parameter similarity and functional equivalence
 234 remains an open research question that requires empirical validation through task-specific evaluation.

235 **Dictionary Dependence:** Our approach requires comprehensive dictionary coverage of target model
 236 capabilities. The dramatic performance difference between known models and unknown models
 237 demonstrates this fundamental limitation. Practical applications must invest significant effort in
 238 dictionary construction and maintenance.

239 **Non-Negativity Constraints:** The assumption that model capabilities combine through positive
 240 coefficients may not hold universally. Some merging scenarios involve capability subtraction or
 241 interference effects that require negative contributions. Our current framework cannot handle these
 242 cases without substantial modification.

243 **Linear Composition Assumption:** The sparse coding formulation assumes that model capabilities
 244 combine linearly in parameter space. Non-linear interactions between tasks may not be captured
 245 accurately, potentially limiting decomposition fidelity for complex multi-task models with significant
 246 capability overlap or interference.

247 **Scalability Constraints:** Our experiments focus on a 7B parameter model with rank-32 LoRA
 248 adaptations and an 8-task dictionary. Scaling to larger models, full fine-tuning scenarios, or extensive
 249 task dictionaries may require algorithmic innovations and computational resources beyond current
 250 capabilities.

251 **Merging Method Sensitivity:** Decomposition performance varies significantly across merging
 252 methods, with Task Arithmetic showing optimal characteristics while DARE performs poorly. This

253 sensitivity limits the framework’s applicability to existing merged models that may use suboptimal
254 merging approaches.

255 **6 Ethics and Broader Impact**

256 UNMERGE introduces capabilities for analyzing and attributing model compositions, offering
257 substantial benefits for the AI research community and broader applications. The technique enhances
258 model transparency and interpretability, particularly valuable for safety-critical applications where
259 understanding component contributions is essential. It provides robust intellectual property protection
260 through verifiable component attribution, enables scientific reproducibility by allowing researchers
261 to verify model compositions, and offers powerful debugging capabilities for identifying unwanted
262 behaviors in merged models.

263 However, these analytical capabilities also introduce potential risks that warrant careful consideration.
264 The technique could potentially enable unauthorized analysis of proprietary model compositions,
265 allowing competitors or malicious actors to gain insights into carefully guarded intellectual property.
266 There’s also the concern that UNMERGE may facilitate reverse engineering of specialized capabilities,
267 potentially undermining the competitive advantages that organizations have developed through
268 significant investment in model development. Furthermore, the technology raises complex questions
269 about model ownership and attribution in collaborative settings, where multiple parties may have
270 contributed to a model’s development.

271 To address these concerns, several mitigation strategies should be implemented alongside continued
272 development of the technology. Establishing responsible disclosure frameworks for capability
273 attribution research will help ensure that discoveries are shared appropriately while protecting
274 legitimate interests. The development of privacy-preserving decomposition techniques could allow for
275 the benefits of model analysis while maintaining necessary confidentiality. Creating best practices for
276 ethical model analysis will provide guidance for researchers and practitioners in applying these tools
277 responsibly. Ultimately, the benefits of improved model transparency and verification capabilities
278 outweigh the associated risks when the technology is developed and deployed through responsible
279 research practices that balance innovation with appropriate safeguards for legitimate stakeholder
280 interests.

281 **7 Conclusion**

282 We introduce UNMERGE, a verifiable framework for model capability attribution via sparse coding
283 that enables the decomposition of merged models into their constituent task-specific components.
284 Through comprehensive evaluation across 72 merged models and 6 decomposition algorithms, we
285 demonstrate that NNLS achieves exceptional performance with reconstruction errors of 0.45 and
286 perfect precision/recall for known compositions.

287 The framework provides a foundation for future work in neural network interpretability while opening
288 new directions for model verification, debugging, and attribution.

289 The perfect performance achieved on known compositions (100% precision/recall with NNLS)
290 demonstrates the fundamental feasibility of accurate model decomposition, while the zero perfor-
291 mance on unknown compositions confirms the specificity of our approach. These results establish
292 UNMERGE as a practical tool for controlled model analysis while identifying key areas for future
293 development.

294 While we focus on parameter-space reconstruction as a necessary first step, we acknowledge that
295 behavioral validation represents crucial future work. The relationship between parameter fidelity and
296 functional performance requires systematic investigation through task-specific evaluation. Neverthe-
297 less, our parameter-space approach provides valuable foundations for scalable model analysis and
298 hypothesis generation.

299 Future work should address behavioral validation through systematic task evaluation, scalability
300 to larger models and dictionaries, extension to non-linear composition scenarios, and development
301 of adaptive dictionary learning methods. The intersection of sparse coding and neural network
302 interpretability represents a promising research direction with significant implications for AI safety,
303 transparency, and scientific understanding.

304 **8 Reproducibility Statement**

305 We provide the code and a clear and complete pipeline in the supplementary materials. The pipeline
306 is divided into 4 phases: training, merging, compressing, and final decomposition. All steps were
307 manually verified and rerun from scratch. The code was linted with `black` and `flake8`. Hardware
308 requirements: GPU with 45 GB of VRAM, at least 1 TB of disk space to store merged models.

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399 **A Remaining decomposition results**

400 Table 4 illustrates the reconstruction performance in different merging methods.

Table 4: Reconstruction error for different algorithms and model categories.

Algorithm	Known	Mixed	Unknown
NNLS	0.24 ± 0.13	0.43 ± 0.13	0.68 ± 0.09
OMP	0.24 ± 0.13	0.43 ± 0.13	0.68 ± 0.09
Ridge	0.24 ± 0.13	0.43 ± 0.13	0.68 ± 0.09
Elastic Net	0.25 ± 0.13	0.44 ± 0.13	0.68 ± 0.09
Dot product	0.30 ± 0.13	0.49 ± 0.13	0.69 ± 0.08
Lasso	0.52 ± 0.20	0.71 ± 0.22	0.99 ± 0.03

401 Table 5 illustrates the precision and recall of different algorithms and merging methods across all
402 models from the "known" category.

Table 5: Precision / Recall for different algorithms and merging methods. Models are only from the "known" category.

Algorithm	DARE	TIES	Linear	Task Arithmetic
NNLS	1.00 / 1.00	1.00 / 1.00	1.00 / 1.00	1.00 / 1.00
OMP	1.00 / 1.00	0.56 / 1.00	1.00 / 1.00	1.00 / 1.00
Ridge	0.54 / 1.00	0.54 / 1.00	0.54 / 1.00	0.54 / 1.00
Elastic Net	0.62 / 1.00	0.87 / 1.00	0.62 / 1.00	0.62 / 1.00
Dot product	0.55 / 1.00	0.54 / 1.00	0.55 / 1.00	0.55 / 1.00
Lasso	1.00 / 0.40	1.00 / 0.67	0.83 / 0.36	0.83 / 0.36

403 Table 6 illustrates the sparsity (number of active coefficients) of different algorithms and merging
404 methods across all models of the category "known".

Table 6: Sparsity for different algorithms and merging methods. Models are only from the "known" category.

Algorithm	DARE	TIES	Linear	Task Arithmetic
NNLS	4.33	4.33	4.33	4.33
OMP	4.33	7.67	4.33	4.33
Ridge	8.00	8.00	8.00	8.00
Elastic Net	7.00	5.00	7.00	7.00
Dot product	7.83	8.00	7.83	7.83
Lasso	1.67	2.83	1.50	1.50

405 **Agents4Science AI Involvement Checklist**

- 406 1. **Hypothesis development:** Hypothesis development includes the process by which you came to
407 explore this research topic and research question. This can involve the background research performed
408 by either researchers or by AI. This can also involve whether the idea was proposed by researchers or
409 by AI.

410 Answer: **[D]**

411 Explanation: The initial idea and the whole research proposal was generated by the LLM system.
412 However, we slightly modified the proposal during the project execution.

- 413 2. **Experimental design and implementation:** This category includes design of experiments that are
414 used to test the hypotheses, coding and implementation of computational methods, and the execution
415 of these experiments.

416 Answer: **[C]**

417 Explanation: The high-level design of the experiments was heavily redacted by humans. Implementa-
418 tion was done mostly by LLM, with us checkpointing the progress.

- 419 3. **Analysis of data and interpretation of results:** This category encompasses any process to organize
420 and process data for the experiments in the paper. It also includes interpretations of the results of the
421 study.

422 Answer: **[C]**

423 Explanation: Humans mostly did not redact the interpretations. Sometimes we had to point out some
424 obvious things in data.

- 425 4. **Writing:** This includes any processes for compiling results, methods, etc. into the final paper form.
426 This can involve not only writing the main text but also figure-making, improving the layout of the
427 manuscript, and forming the narrative.

428 Answer: **[C]**

429 Explanation: The writing was done mostly using the LLM system. We provided the LaTeX template
430 and fixed some inconsistencies with real experimental data. Also we provided citations for datasets.

- 431 5. **Observed AI Limitations:**

432 Description: Many hallucinations, invalidating already correct results, inability to follow simple
433 commands. Overall, we do not feel that full autonomy of the LLM agents in writing scientific papers
434 is now possible.

435 However, it seems it is already close to perfect in literature analysis and idea generation.

436 One of the major problems was hiding failures. For instance, when the system was producing merged
437 models, it used a key "adapter" in a YAML config for mergekit. There is no such key. So the system
438 produced 72 identical models and never actually checked it. It came up later when the diff vectors on
439 the later stage appeared to be zeros.

440 **Agents4Science Paper Checklist**

441 **1. Claims**

442 Question: Do the main claims made in the abstract and introduction accurately reflect the paper's
443 contributions and scope?

444 Answer: [Yes]

445 Justification: They really do. Everything was checked by human authors.

446 Guidelines:

- 447 • The answer NA means that the abstract and introduction do not include the claims made in the
448 paper.
- 449 • The abstract and/or introduction should clearly state the claims made, including the contributions
450 made in the paper and important assumptions and limitations. A No or NA answer to this
451 question will not be perceived well by the reviewers.
- 452 • The claims made should match theoretical and experimental results, and reflect how much the
453 results can be expected to generalize to other settings.
- 454 • It is fine to include aspirational goals as motivation as long as it is clear that these goals are not
455 attained by the paper.

456 **2. Limitations**

457 Question: Does the paper discuss the limitations of the work performed by the authors?

458 Answer: [Yes]

459 Justification: There is a separate section for that.

460 Guidelines:

- 461 • The answer NA means that the paper has no limitation while the answer No means that the paper
462 has limitations, but those are not discussed in the paper.
- 463 • The authors are encouraged to create a separate "Limitations" section in their paper.
- 464 • The paper should point out any strong assumptions and how robust the results are to violations of
465 these assumptions (e.g., independence assumptions, noiseless settings, model well-specification,
466 asymptotic approximations only holding locally). The authors should reflect on how these
467 assumptions might be violated in practice and what the implications would be.
- 468 • The authors should reflect on the scope of the claims made, e.g., if the approach was only tested
469 on a few datasets or with a few runs. In general, empirical results often depend on implicit
470 assumptions, which should be articulated.
- 471 • The authors should reflect on the factors that influence the performance of the approach. For
472 example, a facial recognition algorithm may perform poorly when image resolution is low or
473 images are taken in low lighting.
- 474 • The authors should discuss the computational efficiency of the proposed algorithms and how
475 they scale with dataset size.
- 476 • If applicable, the authors should discuss possible limitations of their approach to address problems
477 of privacy and fairness.
- 478 • While the authors might fear that complete honesty about limitations might be used by reviewers
479 as grounds for rejection, a worse outcome might be that reviewers discover limitations that aren't
480 acknowledged in the paper. Reviewers will be specifically instructed to not penalize honesty
481 concerning limitations.

482 **3. Theory assumptions and proofs**

483 Question: For each theoretical result, does the paper provide the full set of assumptions and a complete
484 (and correct) proof?

485 Answer: [NA]

486 Justification: The paper is almost purely empirical.

487 Guidelines:

- 488 • The answer NA means that the paper does not include theoretical results.
- 489 • All the theorems, formulas, and proofs in the paper should be numbered and cross-referenced.
- 490 • All assumptions should be clearly stated or referenced in the statement of any theorems.
- 491 • The proofs can either appear in the main paper or the supplemental material, but if they appear in
492 the supplemental material, the authors are encouraged to provide a short proof sketch to provide
493 intuition.

494 **4. Experimental result reproducibility**

495 Question: Does the paper fully disclose all the information needed to reproduce the main experimental
496 results of the paper to the extent that it affects the main claims and/or conclusions of the paper
497 (regardless of whether the code and data are provided or not)?

498 Answer: [\[Yes\]](#)

499 Justification: Yes, we also have the code verified and fixed by humans.

500 Guidelines:

- 501 • The answer NA means that the paper does not include experiments.
- 502 • If the paper includes experiments, a No answer to this question will not be perceived well by the
503 reviewers: Making the paper reproducible is important.
- 504 • If the contribution is a dataset and/or model, the authors should describe the steps taken to make
505 their results reproducible or verifiable.
- 506 • We recognize that reproducibility may be tricky in some cases, in which case authors are welcome
507 to describe the particular way they provide for reproducibility. In the case of closed-source
508 models, it may be that access to the model is limited in some way (e.g., to registered users), but
509 it should be possible for other researchers to have some path to reproducing or verifying the
510 results.

511 **5. Open access to data and code**

512 Question: Does the paper provide open access to the data and code, with sufficient instructions to
513 faithfully reproduce the main experimental results, as described in supplemental material?

514 Answer: [\[Yes\]](#)

515 Justification: Yes, the code will be in the supplemental materials.

516 Guidelines:

- 517 • The answer NA means that paper does not include experiments requiring code.
- 518 • Please see the Agents4Science code and data submission guidelines on the conference website
519 for more details.
- 520 • While we encourage the release of code and data, we understand that this might not be possible,
521 so "No" is an acceptable answer. Papers cannot be rejected simply for not including code, unless
522 this is central to the contribution (e.g., for a new open-source benchmark).
- 523 • The instructions should contain the exact command and environment needed to run to reproduce
524 the results.
- 525 • At submission time, to preserve anonymity, the authors should release anonymized versions (if
526 applicable).

527 **6. Experimental setting/details**

528 Question: Does the paper specify all the training and test details (e.g., data splits, hyperparameters,
529 how they were chosen, type of optimizer, etc.) necessary to understand the results?

530 Answer: [\[Yes\]](#),

531 Justification: Mostly yes, some tiny details were omitted because of the page limit.

532 Guidelines:

- 533 • The answer NA means that the paper does not include experiments.
- 534 • The experimental setting should be presented in the core of the paper to a level of detail that is
535 necessary to appreciate the results and make sense of them.
- 536 • The full details can be provided either with the code, in appendix, or as supplemental material.

537 **7. Experiment statistical significance**

538 Question: Does the paper report error bars suitably and correctly defined or other appropriate informa-
539 tion about the statistical significance of the experiments?

540 Answer: [\[Yes\]](#)

541 Justification: Yes, we report standard deviation in all tables.

542 Guidelines:

- 543 • The answer NA means that the paper does not include experiments.
- 544 • The authors should answer "Yes" if the results are accompanied by error bars, confidence
545 intervals, or statistical significance tests, at least for the experiments that support the main claims
546 of the paper.

- 547 • The factors of variability that the error bars are capturing should be clearly stated (for example,
548 train/test split, initialization, or overall run with given experimental conditions).

549 **8. Experiments compute resources**

550 Question: For each experiment, does the paper provide sufficient information on the computer
551 resources (type of compute workers, memory, time of execution) needed to reproduce the experiments?

552 Answer: [Yes]

553 Justification: Yes, it was rented L40S.

554 Guidelines:

- 555 • The answer NA means that the paper does not include experiments.
556 • The paper should indicate the type of compute workers CPU or GPU, internal cluster, or cloud
557 provider, including relevant memory and storage.
558 • The paper should provide the amount of compute required for each of the individual experimental
559 runs as well as estimate the total compute.

560 **9. Code of ethics**

561 Question: Does the research conducted in the paper conform, in every respect, with the Agents4Science
562 Code of Ethics (see conference website)?

563 Answer: [Yes]

564 Justification: Yes, see the Ethics section.

565 Guidelines:

- 566 • The answer NA means that the authors have not reviewed the Agents4Science Code of Ethics.
567 • If the authors answer No, they should explain the special circumstances that require a deviation
568 from the Code of Ethics.

569 **10. Broader impacts**

570 Question: Does the paper discuss both potential positive societal impacts and negative societal impacts
571 of the work performed?

572 Answer: [Yes]

573 Justification: Yes, see the Ethics section.

574 Guidelines:

- 575 • The answer NA means that there is no societal impact of the work performed.
576 • If the authors answer NA or No, they should explain why their work has no societal impact or
577 why the paper does not address societal impact.
578 • Examples of negative societal impacts include potential malicious or unintended uses (e.g., disin-
579 formation, generating fake profiles, surveillance), fairness considerations, privacy considerations,
580 and security considerations.
581 • If there are negative societal impacts, the authors could also discuss possible mitigation strategies.