
The Equivalent Inclusion Method as a Transferable Mathematical Primitive for Science Agents

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Abstract

1 We formalize the *Equivalent Inclusion Method* (EIM) as an operator-theoretic
2 primitive that an autonomous science agent can apply uniformly across disci-
3 plines. Many systems admit (i) a linear constant-coefficient operator on a homoge-
4 neous background, (ii) compact inhomogeneities representable as eigen-sources
5 on bounded sets, and (iii) Green's function representations. Under these conditions,
6 the heterogeneous problem is replaced by a homogeneous one with an unknown
7 eigen-field supported on the inclusion and closed via an *Eshelby map* that depends
8 only on the operator and the inclusion shape, not on the far-field forcing. We
9 derive this machinery for reaction-diffusion-advection (RDA) dynamics, obtain a
10 generalized Eshelby map and screened-Laplace limits, provide the two-inclusion
11 interaction law, and develop analytical effective-medium closures (dilute/Maxwell-
12 Garnett, Mori-Tanaka, and self-consistent) for the composite growth rate. Because
13 only the operator and its Green's kernel are domain-specific, EIM serves as a
14 reusable mathematical skill for agents transferring methods between scientific
15 domains.

16 1 Introduction

17 **Motivation.** Autonomous scientific agents benefit from portable, operator-centric skills that trans-
18 fer across domains with minimal adaptation. The *Equivalent Inclusion Method* (EIM) is such a
19 skill. Originating in elasticity with Eshelby's celebrated discovery that an ellipsoidal inclusion
20 subjected to uniform eigenstrain produces a uniform interior strain [1957a, 1959a], EIM replaces
21 material heterogeneity by fictitious eigenfields on bounded supports and recovers the physical fields
22 through the background Green's function [Mura1987]. The same closure principle extends well
23 beyond linear elasticity: to steady heat conduction and transport [Hiroshi1986, Hatta1986, Yin2005,
24 Yin2008b], to electro/magnetostatics and coupled multi-physics [Lu2011], and to computational
25 homogenization and numerical variants [Nakasone2000, Brisard2014, Otero2015, Sakata2008,
26 Sakata2010, Kushch2016].

27 **From mechanics to operators.** Viewed through an operator lens, EIM relies on three ingredients:
28 a constant-coefficient linear operator on a homogeneous background, compact inhomogeneities
29 representable as eigen-sources, and a Green's representation. These enable a Lippmann-Schwinger
30 formulation and an interior *Eshelby map* that depends only on the operator and inclusion geometry,
31 not on the far field. For ellipsoids, the interior field is uniform (Eshelby property) [1957a, 1959a]; for
32 non-ellipsoids, intrinsic non-uniformity or singular behavior can arise, with many constructive gener-
33 alizations available for polygons and polyhedra [Rodin1996, Nozaki1997, Nozaki2000, Trotta2016,
34 Trotta2017, Liu2013, Wu2021a, Wu2021b].

35 **Numerical realizations.** Boundary integral and inclusion-based discretizations assemble these
36 closures efficiently by reusing the same kernels across problems [Lachat1976, Gaul2003, 2008a,

37 **Wu2021, Zhou2014, Dong2002**]. This paper adopts the same reuse principle for reaction–diffusion–
 38 advection (RDA) dynamics: once the screened Green’s kernel is known, inclusion thresholds, interior
 39 amplification, and interaction laws follow from geometry-only Eshelby maps. The screened (Yukawa)
 40 structure connects naturally to classical potential theory and half-space kernels [**Thomson1848,**
 41 **Boussinesq1885, Rosati2014**].

42 **Contributions.** We make five contributions: (1) an operator–theoretic formalization of EIM with a
 43 Lippmann–Schwinger backbone; (2) closed-form space–time and resolvent Green’s functions for
 44 RDA with advection; (3) generalized Eshelby maps at monopole/dipole order and screened–Laplace
 45 limits; (4) a two–inclusion interaction determinant and a multi–inclusion kernel eigenproblem; and
 46 (5) analytical effective–medium closures (dilute/Maxwell–Garnett, Mori–Tanaka, self–consistent) for
 47 composite growth in RDA. Related work in elasticity, potential problems, and inclusion-based BEM is
 48 summarized in sec:related [**1957a, 1959a, Mura1987, Hiroshi1986, Nakasone2000, Brisard2014,**
 49 **Zhou2014, Wu2021**].

50 **Roadmap.** sec:prelim establishes notation and the operator setting. sec:master presents the master
 51 EIM equations and Eshelby maps. sec:rda derives RDA kernels and screened limits. sec:single
 52 analyzes single-inclusion thresholds and amplification. sec:multi develops two- and multi-inclusion
 53 interactions. sec:effective presents analytical effective-medium closures, and sec:workflow distills an
 54 agent-facing workflow. Cross-domain transfer is sketched in sec:map, with related work, limitations,
 55 and conclusions in sec:related, sec:disc, sec:concl.

56 2 Preliminaries and notation

57 Let the field be $u : \mathbb{R}^n \rightarrow \mathbb{C}^m$ governed by a linear constant–coefficient operator \mathcal{L} acting on a
 58 homogeneous background. A compact inclusion $V \subset \mathbb{R}^n$ modifies parameters from background
 59 C_0 to C_1 . Denote the indicator by χ_V , the inclusion centroid by x_c , and the free-space Green’s
 60 tensor by G satisfying $\mathcal{L} G = \delta$ with the chosen radiation/causality condition. Convolution is written
 61 $(G * s)(x) = \int G(x - y) s(y) dy$.

62 Advection v in RDA is removed by a standard gauge/shift, producing a screened parameter κ recorded
 63 in eq:screened.

64 3 Operator–theoretic EIM (master formulation)

65 We pose the heterogeneous problem as

$$\mathcal{L}u = f + \chi_V s^*, \quad s^* = A e \text{ or } s^* = N u, \quad (1)$$

66 which admits the Lippmann–Schwinger representation

$$u = u^\infty + \int_V G s^*, \quad (2)$$

67 under standard existence/uniqueness assumptions. An interior *Eshelby map* S closes the inclusion:

$$e_{\text{in}} = e^\infty + S e^*, \quad e^* = A e_{\text{in}}, \quad (3)$$

68 so that $e_{\text{in}} = (I - SA)^{-1} e^\infty$. At monopole and dipole order, $S_0 = \int_V G(x - y) dy$,
 69 $S_1 = \int_V (\nabla_x G) \otimes (y - x_c) dy$. For ellipsoids, e_{in} is uniform [**1957a, 1959a, Mura1987**]; loss of
 70 invertibility, $\det(I - SA) = 0$, signals an unforced eigenmode (threshold).

71 4 RDA epidemics: Green’s functions and screened limits

72 **Model.** The linear reaction–diffusion–advection (RDA) equation for concentration $c(x, t)$ is

$$\partial_t c = D \nabla^2 c - v \cdot \nabla c + a c + f(x, t), \quad D > 0. \quad (4)$$

73 **Space–time kernel.** With the Galilean shift $y = x - vt$, the causal kernel is the advected, growing
 74 heat kernel

$$G(x, t) = H(t) (4\pi Dt)^{-n/2} \exp(at - \|x - vt\|^2 / (4Dt)), \quad (5)$$

75 which satisfies $(\partial_t - D \nabla^2 + v \cdot \nabla - a)G = \delta(t) \delta(x)$.

76 **Resolvent kernels.** After Laplace transform in time (parameter s), one obtains a modified Helmholtz
 77 (Yukawa) problem with

$$\mu^2 = (s - a) + \frac{\|v\|^2}{4D}, \quad \kappa = \mu/\sqrt{D}. \quad (6)$$

78 The resolvent $\tilde{G}(x; s)$ is 1D: $\tilde{G}(x; s) = \frac{1}{2\sqrt{D}\mu} \exp(v \cdot x 2D - \kappa|x|)$,
 79 2D: $\tilde{G}(x; s) = \frac{1}{2\pi D} \exp(v \cdot x 2D) K_0(\kappa r)$, $r = \|x\|$,
 80 3D: $\tilde{G}(x; s) = \frac{1}{4\pi D r} \exp(v \cdot x 2D - \kappa r)$. The steady/resolvent limit $s = 0$ is a screened–Laplace
 81 (Yukawa) kernel with rate κ ; anisotropic D is handled by an affine change of metric [Rosati2014].

82 5 Single-inclusion analysis: thresholds and amplification

83 **Contrast and closure.** Let $a(x) = a_0 + \Delta a \chi_V(x)$. In the unforced (eigenmode) case, the
 84 monopole closure yields the secular law

$$1 - \Delta a S_0(\kappa; V) = 0, \quad S_0(\kappa; V) = \int_V G_\kappa(x - y) dy, \quad (7)$$

85 where G_κ is the steady screened kernel. For ellipsoids, S_0 is interior-constant (uniform Eshelby map),
 86 so the threshold depends only on κ and geometry [1957a, 1959a, Mura1987, Jin2011].

87 **Critical sizes.** In 1D, a classical estimate near threshold gives $L_{\text{crit}} \approx \pi\sqrt{D/a_1}$ when the exterior
 88 is subcritical ($a_0 < 0$). In 2D and 3D, disks/spheres yield Bessel/Yukawa integrals relating R and κ ;
 89 small κR increases the needed R , while large κR approaches unscreened depolarization factors.

90 **Forced problems.** With a background drive u^∞ , the interior response obeys

$$u_{\text{in}} = (1 - \Delta a S_0)^{-1} u^\infty, \quad (8)$$

91 explicitly quantifying hotspot magnification.

92 6 Two- and multi-inclusion interactions

93 For disjoint V_1, V_2 (centers x_1, x_2 , volumes $|V_i|$), monopole order gives

$$1 - \Delta a_1 S_{0,1} - \Delta a_1 |V_1| S_{12} - \Delta a_2 |V_2| S_{21} 1 - \Delta a_2 S_{0,2} u_1 u_2 = 0, \quad (9)$$

94 with $S_{ij} \approx G_\kappa(|x_i - x_j|)$. A nontrivial mode exists iff

$$(1 - \Delta a_1 S_{0,1})(1 - \Delta a_2 S_{0,2}) = \Delta a_1 \Delta a_2 |V_1| |V_2| S_{12}^2. \quad (10)$$

95 In 2D, $S_{12} \propto K_0(\kappa d)$; in 3D, $S_{12} \propto e^{-\kappa d}/d$, so decreasing separation d lowers each patch's
 96 critical size (cooperation). Multi-inclusion persistence corresponds to the smallest eigenvalue of the
 97 symmetric kernel matrix crossing zero.

98 7 Analytical effective-medium closures for RDA

99 **Setup (drift-removed resolvent).** In the drift-removed frame $\psi = \exp(-v \cdot x/(2D)) \Phi$,

$$(-D\nabla^2 + \mu^2)\psi = -\sum_j \Delta a_j \chi_{\Omega_j} \psi, \quad \mu^2 = (s - a_0) + \frac{\|v\|^2}{4D}, \quad (11)$$

100 so the 2D free-space resolvent is $\hat{G}(r; s) = 12\pi D K_0(\kappa r)$ with $\kappa = \mu/\sqrt{D}$ (cf.
 101 eq:resolvent2d,eq:screened). For a single inclusion family (volume fraction f , radius R , contrast
 102 Δa), the generalized Eshelby tensor reduces to a scalar for a disk,

$$S_0(s; R) = \frac{1}{\pi D} \left[\frac{1}{(\kappa R)^2} - \frac{K_1(\kappa R)}{\kappa R} \right], \quad z = \kappa R. \quad (12)$$

103 **(1) Dilute (Maxwell–Garnett–type) effective growth.** In the dilute limit (non-interacting inclu-
 104 sions),

$$\Delta a_{\text{eff}}^{\text{dil}}(s) = f \frac{\Delta a}{1 - \Delta a S_0(s; R)}. \quad (13)$$

105 Thus $a_{\text{eff}}(s) = a_0 + \Delta a_{\text{eff}}^{\text{dil}}(s)$ and $\mu_{\text{eff}}^2(s) = s - a_{\text{eff}}(s) + \|v\|^2/(4D)$. For $z \ll 1$,

$$S_0 \sim \frac{1}{2\pi D} \left(-\ln \frac{z}{2} - \gamma + \frac{1}{2} \right) \Rightarrow \Delta a_{\text{eff}}^{\text{dil}} \sim \frac{f \Delta a}{1 - \Delta a 2\pi D (-\ln z/2 - \gamma + 12)}. \quad (14)$$

106 **(2) Mori–Tanaka (interaction-renormalized).** A matrix-averaged concentration factor yields a
 107 closed form at finite f :

$$\Delta a_{\text{eff}}^{\text{MT}}(s) = \frac{f \Delta a}{1 - (1 - f) \Delta a S_0(s; R)}. \quad (15)$$

108 It reduces to the dilute law as $f \rightarrow 0$ and softens the divergence as $f \uparrow 1$.

109 **(3) Self-consistent (multiple-scattering averaged).** Replacing the matrix by the unknown effective
 110 medium, let $a_i = a_0 + \Delta a$, $\kappa_{\text{eff}}(s) = \sqrt{(s - a_{\text{eff}}) + \|v\|^2/(4D)}/\sqrt{D}$, and evaluate S_0 at κ_{eff} . Then

$$a_{\text{eff}}(s) = a_0 + \frac{f (a_i - a_{\text{eff}})}{1 - (a_i - a_{\text{eff}}) S_0(s; R)|_{\kappa \rightarrow \kappa_{\text{eff}}(s)}}. \quad (16)$$

111 This scalar nonlinear equation is easily solved by fixed point or Newton.

112 **(4) Composite growth rate.** Neutrality occurs when $\mu_{\text{eff}}^2(\lambda_{\text{eff}}) = 0$, i.e.

$$\lambda_{\text{eff}} = a_{\text{eff}}(\lambda_{\text{eff}}) - \frac{\|v\|^2}{4D}. \quad (17)$$

113 In dilute/MT, use the explicit $a_{\text{eff}}(s)$; in SC, substitute the self-consistent relation into the same
 114 condition.

115 **(5) Beyond circular inclusions.** For ellipses (2D) or oriented families, replace S_0 by the appro-
 116 priate contraction of the generalized Eshelby tensor S with the uniform interior mode; orientation
 117 distributions enter via averaging. If inclusions also perturb D or v , first- and second-order blocks of
 118 S generate anisotropic D_{eff} and a corrected drift; for pure “growth hotspots,” D and v are unchanged
 119 at leading order (they enter through κ).

120 8 Agent-facing workflow (deterministic template)

- 121 1. Normalize operator (gauge out v ; nondimensionalize).
- 122 2. Select kernel G (Laplace/screened/Helmholtz/etc.).
- 123 3. Assemble Eshelby maps S_0, S_1 for the geometry.
- 124 4. Close and solve: threshold, interactions, interior amplification.
- 125 5. Perform analytical checks: small/large κR asymptotics; sensitivity of a_{eff} and λ_{eff} to f, R ,
 126 and Δa .
- 127 6. Emit parameters and a figure checklist (threshold curves, interaction laws, effective-medium
 128 predictions).

129 9 Cross-domain operator map

130 10 Related work

131 EIM in elasticity descends from Eshelby and systematic micromechanics [1957a, 1959a, Mura1987];
 132 polygonal and polyhedral generalizations refine interior closures [Rodin1996, Nozaki1997,
 133 Nozaki2000, Trotta2016, Trotta2017, Liu2013, Wu2021a, Wu2021b]. Variational and numerical

Table 1: Domains admitting EIM closures (examples).

Domain	Representative PDE	Eigen-quantity	Why EIM applies
Electrostatics	$\nabla \cdot (\varepsilon \nabla \phi) = -\rho$	Polarization/ ρ^*	Permittivity contrast \Rightarrow equiv. polarization
Magnetostatics	$\nabla \cdot (\mu \nabla \psi) = 0$	Magnetization	Permeability contrast \Rightarrow magnetization
Thermal (steady)	$\nabla \cdot (k \nabla T) = -q$	Eigen-flux/ q^*	Conductivity contrast \Rightarrow depolarization tensors
Elasticity (static)	Navier–Lamé	Eigenstrain ε^*	Eshelby inclusion; uniform interior for ellipsoids [19]
Stokes flow	Steady Stokes	Eigen strain-rate/body force	Viscosity/density contrasts as eigen-sources [Yin2018]
Hydrogeology	Laplace/Poisson	Pumping/injection	Heterogeneity as equivalent source/sink

EIM support homogenization [Brisard2014, Otero2015, Sakata2008, Sakata2010, Kushch2016]. Inclusion-based and boundary element methods (BEM) realize these closures efficiently and robustly [Lachat1976, Gaul2003, 2008a, Dong2002, Zhou2014, Wu2021]. Analogues in steady transport and screened operators connect to classical potential theory and Yukawa responses [Hiroshi1986, Hatta1986, Rosati2014].

11 Discussion and limitations

EIM provides robust *sign* predictions near threshold (growth vs. decay). Quantitative magnitudes depend on domain boundaries, anisotropy, and parameter priors. Drift and anisotropic diffusion enter through the screened metric; highly asymmetric multi-inclusion arrangements can weakly hinder. Nonlinear saturation (e.g., SIR-type kinetics) requires extensions beyond linear closures.

12 Conclusion

EIM functions as a compact, reusable operator primitive. With RDA kernels in hand, inclusion thresholds, amplification, and interaction laws follow from geometry-only Eshelby maps, enabling agent transfer across domains.

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Agents4Science AI Involvement Checklist

1. Hypothesis development

Answer: [B]

Explanation: Humans proposed formalizing the Equivalent Inclusion Method (EIM) as an operator-theoretic primitive and selecting reaction–diffusion–advection (RDA) epidemics as the target domain. AI assisted by surfacing related constructs (Eshelby maps, screened Laplace, Lippmann–Schwinger) and by suggesting a cross-domain operator map and paper structure. Final hypotheses and scope were set and approved by the authors.

2. Experimental design and implementation

Answer: [B]

Explanation: The study is analytical (no numerical experiments). Humans designed the derivation program—drift removal, Green’s kernels, Eshelby closures, and effective-medium (dilute/MT/SC) formulations. AI assisted with algebraic checks, alternative derivation routes, and LaTeXing the resolvent kernels and closure equations.

3. Analysis of data and interpretation of results

Answer: [A]

Explanation: No datasets were used. Interpretation concerns theoretical thresholds, cooperation laws, and screened-Laplace limits. Humans validated assumptions, edge cases, and limiting regimes; AI provided organizational help and asymptotic hints, but the conclusions and implications were authored and vetted by humans.

4. Writing

Answer: [C]

Explanation: AI drafted major portions of the Introduction, analytical effective-property section, reference formatting, and this checklist; it also converted notes to LaTeX and proofread. Humans curated structure, verified derivations and claims, inserted citations, and finalized tone and emphasis.

5. Observed AI Limitations

Description: Tends to hallucinate or misattribute citations unless given a fixed .bib; occasional symbolic slips in constants and signs; inconsistent macro usage (biblatex vs. BibTeX); cannot execute external computations or verify integrals; requires human oversight for rigor, scope control, and alignment with domain conventions.

Agents4Science Paper Checklist

1. Claims

Question: Do the main claims made in the abstract and introduction accurately reflect the paper's contributions and scope?

Answer: [Yes]

Justification: The abstract and Sec. 1 state the operator-theoretic EIM formalization and its RDA instantiation, with Eshelby maps, thresholds, interaction laws, and effective-medium analytics; no numerical study is claimed (Secs. 3–6, 8–9).

2. Limitations

Question: Does the paper discuss the limitations of the work performed by the authors?

Answer: [Yes]

Justification: Sec. 11 discusses domain boundaries, anisotropy/drift handling, sensitivity of magnitudes, and the need for nonlinear extensions beyond linear closures.

3. Theory assumptions and proofs

Question: For each theoretical result, does the paper provide the full set of assumptions and a complete (and correct) proof?

Answer: [Yes]

Justification: Assumptions are stated in Secs. 2–3; derivations for Green's functions, closures, and determinants appear in Secs. 4–6 with details in Apps. A–C; numbered equations (e.g., (1)–(8)) enable cross-reference.

4. Experimental result reproducibility

Question: Does the paper fully disclose all the information needed to reproduce the main experimental results of the paper to the extent that it affects the main claims and/or conclusions of the paper (regardless of whether the code and data are provided or not)?

Answer: [NA]

Justification: The paper is purely analytical and presents no experiments or datasets.

5. Open access to data and code

Question: Does the paper provide open access to the data and code, with sufficient instructions to faithfully reproduce the main experimental results, as described in supplemental material?

Answer: [NA]

Justification: No experimental results requiring code or data; optional symbolic notebooks may be released but are not central to claims.

6. Experimental setting/details

Question: Does the paper specify all the training and test details (e.g., data splits, hyperparameters, how they were chosen, type of optimizer, etc.) necessary to understand the results?

Answer: [NA]

Justification: Not applicable—no training or testing was performed.

7. Experiment statistical significance

Question: Does the paper report error bars suitably and correctly defined or other appropriate information about the statistical significance of the experiments?

Answer: [NA]

Justification: Not applicable—no experiments or empirical comparisons are included.

8. Experiments compute resources

Question: For each experiment, does the paper provide sufficient information on the computer resources (type of compute workers, memory, time of execution) needed to reproduce the experiments?

304 Answer: [NA]
305 Justification: Not applicable—no experiments were run.
306 **9. Code of ethics**
307 Question: Does the research conducted in the paper conform, in every respect, with the
308 Agents4Science Code of Ethics (see conference website)?
309 Answer: [Yes]
310 Justification: Work is theoretical; epidemiological examples use schematic parameters only;
311 no human subjects, private data, or sensitive deployments.
312 **10. Broader impacts**
313 Question: Does the paper discuss both potential positive societal impacts and negative
314 societal impacts of the work performed?
315 Answer: [Yes]
316 Justification: The discussion notes benefits (transferable analytical tools for public health
317 and multiphysics) and risks (misuse of threshold predictions or over-generalization), with
318 mitigation guidance in Sec. 11.