

LEON ESHUIJS

PhD Student

@ leoneshuijs@gmail.com

watermeleon.github.io

in leoneshuijs

EDUCATION

PhD Student

Vrije Universiteit Amsterdam

Oct 2023 - present

Amsterdam, Netherlands

- Research on applying Reinforcement Learning to specialize NLP models
- Recently incorporating Mechanistic Interpretability
- In collaboration with the Universiteit Utrecht

Master Physics - M1

Sorbonne Université

- **Sep 2022 Jan 2023**
- Paris, France
- Erasmus following the first semester of the Physics Master.

Master Artificial Intelligence

University of Amsterdam

- **Sep 2020 Apr 2023**
- Amsterdam, Netherlands
- **Electives**: Specialized in advanced Machine Learning, Game Theory, Computer Vision and Reinforcement Learning.
- Thesis: "Knowledge Injection through Prompting (KIP): improving image captioning by leveraging knowledge graphs for Transformers". Grade: 8.0/10.0
- GPA: 8.3/10.0 Cum Laude

Bachelor Artificial Intelligence

University of Amsterdam

- **Sep 2017 Aug 2020**
- Amsterdam, Netherlands
- For the honours program I followed courses in Physics and Big History and Psychopharmacology.
- Minor: Electronics for Robotics TU Delft
- Thesis: Reinforcement learning for PID tuning of robot arm.
- GPA: 8.0/10.0 graduated Cum Laude and with Honours

EXPERIENCE

Al Engineer

Saivvy

- **Sep 2020 May 2021**
- Amsterdam, Netherlands
- Maintained and expanded the code base for the computer vision projects, including object detection.
- Assisted in the coordination and supervision of Master student projects.
- Constructed the control framework for a harvest robot in simulation.

PROJECTS

Al Safety Camp - Unsearch

- **i** Jan 2024 Apr 2024
- As a participant in the Al Safety Camp, I joined the <u>UnSearch</u> team to help understand search in Transformer models
- Investigated path following and world models in Transformer models for mazes via Mechanistic Interpretability technique Path Patching.

SpotMicroAl: RL for gait modulation - Sim2Real gap

- **J**un 2022 Feb 2023
- Based on the open-source SpotmicroAl platform, I 3D printed and built my robot dog, Jake, and then trained different Reinforcement Learning (RL) algorithms for the task of gait modulation.
- See website for more information and videos: link

EVENTS

Summer School: Human-aligned AI

Hackathon: Deception Detection (link)

Participant

Jun 2024

Online - Apart Research

 ${\bf Conference: EAGxUtrecht - Effective \ Altruism}$

Conference: BNAIC (link)

Demo and Poster Presentation

■ Nov 2023

■ TU Delft

TECHNICAL SKILLS

Comfortable with

 Python
 Pytorch
 Keras
 Slurm
 Conda

Familiar with

C R SQL MATLAB HTML CSS Docker
Azure Machine Learning GCP

PERSONAL INTERESTS

Memory Athlete Robotics

Effective Altruism Inclusive Al Al Safe

LANGUAGES

Dutch English French (B1)

