

quantum mechanics

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五大公设 { 波函数公设: 波函数完全描述粒子的状态
微观体系动力学演化公设: 状态波函数随空间和时间变化规律遵循薛定谔方程,
保持相干性且保持确定的因果性.
算符公设: 力学量用算符表示
测量公设: 观测值为本征值, 或者本征值的期望值.
全同性原理: 粒子的不可识别, 玻色子波函数满足交换对称性, 费米子满足交换反对称性

波函数性质 { 单值, 连续, 有限
归一化
满足态叠加原理
相位不定性

概率密度的连续性方程

$$\frac{\partial \rho}{\partial t} + \nabla \cdot \vec{j} = 0 \quad \rho = \psi^* \cdot \psi$$
$$\vec{j} = -\frac{i\hbar}{2m}(\psi^* \cdot \nabla \psi - \psi \cdot \nabla \psi^*) = \Re \left[\psi^* \left(-\frac{i\hbar \nabla}{m} \right) \psi \right]$$
$$i\hbar \frac{\partial}{\partial t} \psi = -\frac{\hbar^2}{2m} \nabla^2 \psi + V \psi$$
$$-i\hbar \frac{\partial}{\partial t} \psi^* = -\frac{\hbar^2}{2m} \nabla^2 \psi^* + V^* \psi^*$$

由连续性方程推出两个结论

1. 定态时, $\psi = \Psi(\vec{r}) \cdot A_0 \cdot e^{-\frac{i}{\hbar} E t} \Rightarrow \vec{j} = 0$
2. 波函数在演化中保持归一化.

$$\frac{\partial \rho}{\partial t} + \nabla \cdot \vec{j} = 0 \Rightarrow$$
$$\int \frac{\partial \rho}{\partial t} d\tau + \int \nabla \cdot \vec{j} d\tau = 0 \Rightarrow$$
$$\int \frac{\partial \rho}{\partial t} d\tau = c$$

测不准原理的证明:

$$\langle(\Delta A)^2\rangle\langle(\Delta B)^2\rangle \geq \frac{1}{4} |\langle[A, B]\rangle|^2 \quad \Delta A = A - \langle A \rangle$$

1. Schwarz:

$$\text{set } |\lambda\rangle = |\alpha\rangle + \lambda|\beta\rangle.$$

$$\langle\lambda|\lambda\rangle \geq 0 \implies \langle\alpha|\alpha\rangle + \lambda^*\langle\alpha|\beta\rangle + \lambda\langle\beta|\alpha\rangle + \lambda^*\lambda\langle\beta|\beta\rangle \geq 0$$

$$\begin{cases} \langle\alpha|\alpha\rangle + \lambda^*\langle\alpha|\beta\rangle + \lambda\langle\beta|\alpha\rangle + \lambda^*\lambda\langle\beta|\beta\rangle \geq 0 \\ \lambda = -\frac{\langle\alpha|\beta\rangle}{\langle\beta|\beta\rangle} \end{cases} \implies \langle\alpha|\alpha\rangle\langle\beta|\beta\rangle \geq |\langle\beta|\alpha\rangle|^2$$

$$\implies \langle(\Delta A)^2\rangle\langle(\Delta B)^2\rangle \geq |\langle\Delta A\Delta B\rangle|^2$$

2. 厄密算符的本征值为实数, 反厄密算符的本征值为纯虚数.

$$A = A^\dagger \implies \langle a|A|a\rangle = (\langle a|A|a\rangle)^* \implies a = a^*$$

$$\begin{cases} \Delta A \cdot \Delta B = \frac{1}{2}[\Delta A, \Delta B] + \frac{1}{2}[\Delta A, \Delta B]_+ \\ [\Delta A, \Delta B] = [A - \langle A \rangle, B - \langle B \rangle] = [A, B] \end{cases} \implies \Delta A \cdot \Delta B = \frac{1}{2}[A, B] + \frac{1}{2}[\Delta A, \Delta B]_+$$

$$\begin{cases} \langle\Delta A \cdot \Delta B\rangle = \frac{1}{2}\langle[A, B]\rangle + \frac{1}{2}\langle[\Delta A, \Delta B]_+\rangle \\ \langle[A, B]\rangle \text{实数}, \langle[\Delta A, \Delta B]_+\rangle \text{纯虚数} \end{cases} \implies |\langle\Delta A \cdot \Delta B\rangle|^2 = \frac{1}{4} |\langle[A, B]\rangle|^2 + \frac{1}{4} |\langle[\Delta A, \Delta B]_+\rangle|^2$$

$$\begin{cases} |\langle\Delta A \cdot \Delta B\rangle|^2 = \frac{1}{4} |\langle[A, B]\rangle|^2 + \frac{1}{4} |\langle[\Delta A, \Delta B]_+\rangle|^2 \\ \langle(\Delta A)^2\rangle\langle(\Delta B)^2\rangle \geq |\langle\Delta A\Delta B\rangle|^2 \end{cases} \implies \langle(\Delta A)^2\rangle\langle(\Delta B)^2\rangle \geq \frac{1}{4} |\langle[A, B]\rangle|^2 \quad \Delta A = A - \langle A \rangle$$

定态波函数的性质

定态波函数是量子微观体系的势函数不含时的波函数

$$i\hbar \frac{\partial}{\partial t} \psi = -\frac{\hbar^2}{2m} \nabla^2 \psi + V\psi \implies$$

$$i\hbar \frac{\partial}{\partial t} \Psi(\vec{r})T(t) = -\frac{\hbar^2}{2m} \nabla^2 \Psi(\vec{r})T(t) + V\Psi(\vec{r})T(t) \implies$$

$$\begin{cases} i\hbar \frac{\partial}{\partial t} T(t) = ET(t) \\ -\frac{\hbar^2}{2m} \nabla^2 \Psi(\vec{r}) + V(\vec{r})\Psi(\vec{r}) = E\Psi(\vec{r}) \end{cases} \implies$$

$$\psi(\vec{r}, t) = \Psi(\vec{r}) \cdot e^{-\frac{i}{\hbar} Et}$$

关于 $T(t)$ 部分的性质

$$1. \psi(\vec{r}, t) = \Psi(\vec{r}) \cdot A \cdot e^{-\frac{i}{\hbar} Et}.$$

$$2. \text{ 概率密度 } \rho \text{ 不随时间变化, } \frac{\partial \rho}{\partial t} = 0, \text{ 概率流密度 } \vec{j} = 0$$

3. 任何不显含时的力学量平均值不随时间变化
4. 任何力学量的测量值的概率分布不随时间变化

关于 $\Psi(\vec{r})$ 部分的性质

1. 若 ψ 是 $\psi'' + \frac{2m}{\hbar^2} [E - V(\vec{r})] \psi = 0$ 的解, 则 ψ^* 也是该方程的解.

$$\begin{cases} \text{能级不简并, 意味着 } \psi^* = c\psi, \implies \text{该 } E \text{ 所对应的本征函数一定可取实函数} \\ \text{能级简并} \implies \text{可以找到一组完全基(基都是实函数)} \end{cases}$$

2. 若 ψ 是 $\psi'' + \frac{2m}{\hbar^2} [E - V(\vec{r})] \psi = 0$ 的解, 则 $\psi(-\vec{r})$ 也是该方程的解

$$\begin{cases} \text{能级不简并} \implies \text{该 } E \text{ 对应的本征函数一定有确定宇称.} \\ \text{能级简并} \implies \text{可以找到一组完全基(基都有确定宇称)} \end{cases}$$

傅里叶变化

$$\begin{aligned} \psi(\vec{r}) &= \frac{1}{\sqrt{2\pi}} \int \phi(\vec{p}) \cdot e^{\frac{i}{\hbar} \vec{p} \cdot \vec{r}} d^3 \vec{p} \\ \phi(\vec{p}) &= \frac{1}{\sqrt{2\pi}} \int \psi(\vec{r}) \cdot e^{-\frac{i}{\hbar} \vec{p} \cdot \vec{r}} d^3 \vec{r} \end{aligned}$$

一维无限深方势阱(一)

$$\begin{aligned} V(x) &= \begin{cases} 0, & |x| < \frac{a}{2} \\ \infty, & |x| > \frac{a}{2} \end{cases} \\ E_n &= \frac{n^2 \pi^2 \hbar^2}{2ma^2} \\ \psi_n &= \begin{cases} \sqrt{\frac{2}{a}} \sin \frac{n\pi}{a} x, & n \neq 0, \text{偶数} \\ \sqrt{\frac{2}{a}} \cos \frac{n\pi}{a} x, & n \text{奇数} \end{cases} \end{aligned}$$

一维深方势阱(二)

$$\begin{aligned} V(x) &= \begin{cases} 0, & 0 < x < a \\ \infty \end{cases} \\ E_n &= \frac{n^2 \pi^2 \hbar^2}{2ma^2} \\ \psi_n &= \sqrt{\frac{2}{a}} \sin \frac{n\pi}{a} x, n = 1, 2, 3, \dots \end{aligned}$$

二维深方势阱

$$V(x, y) = \begin{cases} 0, & 0 < x < a, 0 < y < b \\ \infty \end{cases}$$

$$E_n = \frac{\pi^2 \hbar^2}{2m} \left(\frac{n_1^2}{a^2} + \frac{n_2^2}{b^2} \right)$$

$$\psi_{n_1, n_2} = \sqrt{\frac{2}{a}} \sqrt{\frac{2}{b}} \sin \frac{n_1 \pi}{a} x \sin \frac{n_2 \pi}{b} y$$

三维深方势阱

$$V(x, y, z) = \begin{cases} 0, & 0 < x < a, 0 < y < b, 0 < z < c \\ \infty & \end{cases}$$

$$E_n = \frac{\pi^2 \hbar^2}{2m} \left(\frac{n_1^2}{a^2} + \frac{n_2^2}{b^2} + \frac{n_3^2}{c^2} \right)$$

$$\psi_{n_1, n_2} = \sqrt{\frac{2}{a}} \sqrt{\frac{2}{b}} \sqrt{\frac{2}{c}} \sin \frac{n_1 \pi}{a} x \sin \frac{n_2 \pi}{b} y \sin \frac{n_3 \pi}{c} z$$

有限深方势阱

$$V(x) = \begin{cases} 0, & |x| < \frac{a}{2} \\ V_0, & |x| > \frac{a}{2} \end{cases}$$

1. $E < V_0$ 束缚态

$$\begin{cases} \text{阱外: } \psi'' - \frac{2m}{\hbar^2} (V_0 - E) \psi = 0 \\ \text{阱内: } \psi'' + \frac{2mE}{\hbar^2} \psi = 0 \end{cases}$$

$$\begin{cases} k_n \tan \frac{k_n a}{2} = \beta_n \\ \left(\frac{k_n a}{2} \right)^2 + \left(\frac{k_n \beta_n}{2} \right)^2 = \frac{ma^2}{2\hbar^2} V_0 \end{cases} \quad k_n^2 = \frac{2mE_n}{\hbar^2}, \beta_n^2 = \frac{2m}{\hbar^2} (V_0 - E_n), \quad n = 0, 2, 4, \dots$$

$$\begin{cases} k_n \cot \frac{k_n a}{2} = -\beta_n \\ \left(\frac{k_n a}{2} \right)^2 + \left(\frac{k_n \beta_n}{2} \right)^2 = \frac{ma^2}{2\hbar^2} V_0 \end{cases} \quad k_n^2 = \frac{2mE_n}{\hbar^2}, \beta_n^2 = \frac{2m}{\hbar^2} (V_0 - E_n), \quad n = 1, 2, 3, \dots$$

$$\text{偶宇称} \begin{cases} A \cos k_n x, & |x| < \frac{a}{2} \\ D e^{-\beta_n x}, & x > \frac{a}{2} \\ D e^{\beta_n x}, & x < -\frac{a}{2} \end{cases} \quad \text{奇宇称} \begin{cases} A \sin k_n x, & |x| < \frac{a}{2} \\ D e^{-\beta_n x}, & x > \frac{a}{2} \\ -D e^{\beta_n x}, & x < -\frac{a}{2} \end{cases}$$

2. $E > V_0$ 非束缚态

$$\begin{cases} \text{阱外: } \psi'' + \frac{2m}{\hbar^2} (E - V_0) \psi = 0 \\ \text{阱内: } \psi'' + \frac{2mE}{\hbar^2} \psi = 0 \end{cases}$$

一维方势垒

1.

$$\begin{cases} \text{区域I, III} : \psi'' + \frac{2mE}{\hbar^2} \psi = 0 \\ \text{区域II} : \psi'' - \frac{2m}{\hbar^2} (V_0 - E) \psi = 0 \end{cases}$$

$$\begin{cases} \text{区域I} : \psi = e^{ik_n x} + R e^{-ik_n x} & k_n^2 = \frac{2mE}{\hbar^2} \\ \text{区域II} : \psi = C_1 e^{-i\kappa_n x} + C_2 e^{i\kappa_n x} & \kappa_n^2 = \frac{2m}{\hbar^2} (V_0 - E) \\ \text{区域III} : \psi = S e^{ik_n x} & k_n^2 = \frac{2mE}{\hbar^2} \end{cases}$$

2.

δ -势阱

$$V(x) = -\gamma \delta(x) \begin{cases} -\gamma & x = 0 \\ 0, & x \neq 0 \end{cases}$$

$$-\frac{\hbar^2}{2m} \psi'' - \gamma \delta(x) \psi = E \psi \implies$$

$$\lim_{\varepsilon \rightarrow 0} \int_{-\varepsilon}^{\varepsilon} -\frac{\hbar^2}{2m} \psi'' dx - \lim_{\varepsilon \rightarrow 0} \int_{-\varepsilon}^{\varepsilon} \gamma \delta(x) \psi dx = 0 \implies$$

$$\psi'(0+) - \psi'(0-) = \frac{2m\gamma}{\hbar^2} \psi(0)$$

1. 自由态, $\psi(0) = 0$

2. 束缚态, $\psi(0) = C_1$

$$\psi'' - \kappa \psi = 0, \quad \kappa^2 =$$

一维势垒

一维谐振子:

$$-\frac{\hbar^2}{2m} \psi'' + \frac{1}{2} m \omega^2 x^2 \psi = E \psi$$

令

$$\begin{cases} \xi = \alpha x = \sqrt{\frac{m\omega}{\hbar}} x \\ \lambda = \frac{2E}{\hbar\omega} \end{cases}$$

$$\frac{d^2 \psi}{d\xi^2} + (\lambda - \xi^2) \psi = 0$$

猜测解为 $\psi = u(\xi) e^{-\frac{\xi^2}{2}}$, 将该解代入方程, 得到

$$\frac{d^2 u}{d\xi^2} - 2\xi \frac{du}{d\xi} + (\lambda - 1)u = 0$$

这种形式的方程被称为Hermite方程, 用级数解方程得

$$C_{k+2} = \frac{2k + (1 - \lambda)}{(k + 2)(k + 1)} C_k, k = 0, 1, 2, 3, \dots$$

$$\begin{cases} C_2 = \frac{1-\lambda}{2}C_0 \\ C_3 = \frac{2+1-\lambda}{3 \times 2}C_1 \\ C_4 = \frac{4+1-\lambda}{4 \times 3}C_2 \\ \vdots \end{cases}$$

对于固定的 $\lambda = \frac{2E}{\hbar\omega}$, 如果没有 k , 使得 $2k+1-\lambda=0$, 这个级数将不会截断.
只有当存在 k , 使得 $2k+1-\lambda=0$ 时, 这个级数才会截断, 所以可以取的能量值为

$$E_n = \frac{(2n+1)\hbar\omega}{2}$$

解为

$$\psi_n = N_n e^{-\frac{1}{2}\alpha^2 x^2} H_n(\alpha x), \quad \alpha = \sqrt{\frac{m\omega}{\hbar}}, \quad \xi = \alpha x$$

$$N_n = \sqrt{\frac{\alpha}{\sqrt{\pi} \cdot 2^n \cdot n!}}$$

$$\psi_{n_x, n_y, n_z} = N_{n_x} \cdot N_{n_y} \cdot N_{n_z} \cdot H_{n_x}(\alpha x) H_{n_y}(\alpha y) \cdot H_{n_z}(\alpha z) e^{-\frac{1}{2}\alpha^2(x^2+y^2+z^2)}$$

$$E_{n_x, n_y, n_z} = (n_x + n_y + n_z + \frac{3}{2})\hbar\omega$$

厄密特多项式的一些小性质.

1.

$$\frac{d^2 H_n(\xi)}{d\xi^2} - 2\xi \frac{dH_n(\xi)}{d\xi} + 2nH_n = 0$$

2.

$$H_{2n}(\xi) - 2\xi H_n + 2nH_{n-1} = 0$$

3.

$$\frac{dH_n(\xi)}{d\xi} = 2nH_{n-1}(\xi)$$

4.

$$\int_{-\infty}^{\infty} H_m(\xi) H_n(\xi) e^{-\xi^2} d\xi = \sqrt{\pi} \cdot 2^n \cdot n! \cdot \delta_{mn}$$

5.

$$H_n(\xi) = (-1)^n \cdot e^{\xi^2} \cdot \frac{d^n}{d\xi^n} (e^{-\xi^2})$$

$$H_n(-\xi) = (-1)^n \cdot H_n(\xi)$$

6.

$$\begin{cases} H_0(\xi) = 1 \\ H_1(\xi) = 2\xi \\ H_2(\xi) = 4\xi^2 - 2 \\ H_3(\xi) = 8\xi^3 - 12\xi \end{cases}$$

力学量算符的引入: 在求平均值的意义下, 力学量用算符来表示.

由于力学量算符的运算规则与矩阵的运算相同, 引入Hilbert 空间. (debat-able)

实验可测的力学量对应的算符都是厄密算符.

一个算符 \hat{A} 的厄密共轭算符 \hat{A}^\dagger 满足 $(\psi, \hat{A}^\dagger \psi) = (\hat{A} \psi, \psi) \iff (\psi, \hat{A}^\dagger \varphi) = (\hat{A} \psi, \varphi)$ 任何算符都可求其厄密共轭, 但是不是每一个算符都是厄密算符

一个算符 \hat{A} 是厄密算符的定义: 满足 $\hat{A}^\dagger = \hat{A}$.

厄密算符的性质

1. 定义也是性质

$$\hat{A}^\dagger = \hat{A}$$

2. 在任何量子态下, 厄密算符的平均值必为实数.

$$\begin{aligned} \bar{\hat{A}} &= (\psi, \hat{A} \psi) = (\hat{A}^\dagger \psi, \psi) \\ &= (\hat{A} \psi, \psi) \\ &= (\psi, \hat{A} \psi)^* \end{aligned} \tag{1}$$

$$\implies \bar{\hat{A}} \text{ 是实数}$$

3. 在任何量子态下, 平均值都为实数的算符必为厄密算符.

$$(\psi, \hat{A} \psi) = (\psi, \hat{A} \psi)^* \implies (\hat{A} \psi, \psi) = (\psi, \hat{A} \psi)$$

由算符的厄密共轭的定义: $(\hat{A} \psi, \psi) = (\psi, \hat{A}^\dagger \psi)$

$$\text{两相比较得 } \hat{A}^\dagger = \hat{A}$$

4. 本征函数正交归一完备

$$\begin{aligned} (\psi_m, \hat{A} \psi_n) &= (\hat{A}^\dagger \psi_m, \psi_n) = (\hat{A} \psi_m, \psi_n) \\ A_n(\psi_m, \psi_n) &= A_m^*(\psi_m, \psi_n) = A_m(\psi_m, \psi_n) \\ (A_n - A_m)(\psi_m, \psi_n) &= 0 \end{aligned}$$

算符对易的物理意义:

1. 若 A, B 有一组完备的共同本征矢, 则两个算符对易
2. 若两个算符对易, 有共同的完备的本征函数

力学量完全集

1. 定义: 为完全确定状态所需要的一组两两对易的力学量算符的最小集合.
2. 性质:
 - (a) 其中力学量的个数往往等于体系的自由度
 - (b) 其中所有的力学量具有共同的完备的本征函数

$\hat{x}, \hat{y}, \hat{z}$ 两两对易

$\hat{p}_x, \hat{p}_y, \hat{p}_z$ 两两对易

$$[\hat{x}_\alpha, \hat{p}_\beta] = i\hbar\delta_{\alpha\beta}$$

$$[A, BC] = [A, B]C + B[A, C]$$

$$[\hat{x}, \hat{p}_x^n] = i\hbar n \cdot \hat{p}_x^{n-1}$$

$$[\hat{p}_x, \hat{x}^n] = -i\hbar \cdot n \cdot \hat{x}^{n-1}$$

$$[\hat{p}_x, f(\hat{x})] = -i\hbar \frac{df}{dx}$$

$$[l_\alpha, l_\beta] = i\hbar\varepsilon_{\alpha\beta\gamma}\hat{l}_\gamma$$

$$[\hat{x}_\alpha, \hat{l}_\beta] = i\hbar\varepsilon_{\alpha\beta\gamma}\hat{x}_\gamma$$

$$[\hat{p}_\alpha, \hat{l}_\beta] = i\hbar\varepsilon_{\alpha\beta\gamma}\hat{p}_\gamma$$

$$\begin{cases} \hat{l}_x = y\hat{p}_z - z\hat{p}_y = i\hbar \left(\sin\varphi \frac{\partial}{\partial\theta} + \cot\theta \cos\varphi \frac{\partial}{\partial\varphi} \right) \\ \hat{l}_y = z\hat{p}_x - x\hat{p}_z = i\hbar \left(-\cos\varphi \frac{\partial}{\partial\theta} + \cot\theta \sin\varphi \frac{\partial}{\partial\varphi} \right) \\ \hat{l}_z = x\hat{p}_y - y\hat{p}_x = -i\hbar \frac{\partial}{\partial\varphi} \end{cases} \quad \text{下标, 两个不是下标, xyz, yzx, zxy}$$

$$\left[\hat{l}_z, \hat{l}^2 = \hat{l}_x^2 + \hat{l}_y^2 + \hat{l}_z^2 = -\hbar^2 \left[\frac{1}{\sin\theta} \frac{\partial}{\partial\theta} \left(\sin\theta \frac{\partial}{\partial\theta} \right) + \frac{1}{\sin^2\theta} \frac{\partial^2}{\partial\varphi^2} \right] \right] = 0$$

几个常见的力学量完全集

1. $\{\hat{p}_x, \hat{p}_y, \hat{p}_z\}$

$$\hat{p}\psi_p(\vec{r}) = p\psi_p(\vec{r}) \implies \psi_{p_x}(x) = A_x \cdot e^{-\frac{i}{\hbar}p_x \cdot x}$$

这三个力学量算符的共同本征函数为

$$\psi_p(\vec{r}) = A_x \cdot A_y \cdot A_z \cdot e^{-\frac{i}{\hbar}(\vec{p} \cdot \vec{r})}$$

归一化该波函数,

$$\begin{aligned}
& \int_{-\infty}^{+\infty} \psi_{p_x}(x)^* \cdot \psi_{p'_x}(x) dx = \delta(p_x - p'_x) \\
& \Rightarrow \int_{-\infty}^{+\infty} |A_x|^2 e^{-\frac{i}{\hbar}(p_x - p'_x) \cdot x} dx = \frac{1}{2\pi} \int_{-\infty}^{+\infty} e^{i(p_x - p'_x) \cdot x} dx \\
& \Rightarrow \int_{-\infty}^{+\infty} |A_x|^2 e^{-\frac{i}{\hbar}(p_x - p'_x) \cdot x} dx = \frac{1}{2\pi} \int_{-\infty}^{+\infty} e^{\frac{i}{\hbar}(p_x - p'_x) \cdot x} d\frac{x}{\hbar} \\
& \Rightarrow \int_{-\infty}^{+\infty} |A_x|^2 e^{-\frac{i}{\hbar}(p_x - p'_x) \cdot x} dx = \frac{1}{2\pi\hbar} \int_{-\infty}^{+\infty} e^{\frac{i}{\hbar}(p_x - p'_x) \cdot x} dx \\
& \Rightarrow A_x = A_y = A_z = \frac{1}{\sqrt{2\pi\hbar}}
\end{aligned}$$

2. $\{\hat{x}, \hat{y}, \hat{z}\}$.

$$\hat{x}\psi_r(\vec{r}) = r\psi_r(\vec{r}) \Rightarrow \psi_x(x) = \delta(x - x_0)$$

共同的本征波函数

$$\psi_r(\vec{r}) = \delta(x - x_0)\delta(y - y_0)\delta(z - z_0)$$

3. $\{\hat{l}_z, \hat{l}^2\}$

$$\begin{cases} \hat{l}_z\psi = l_z\psi \\ \hat{l}_z = -i\hbar\frac{\partial}{\partial\varphi}\psi \end{cases} \Rightarrow \psi = Ce^{\frac{i}{\hbar}l_z\varphi}$$

$$\begin{cases} \text{周期性: } \psi(\varphi) = \psi(\varphi + 2\pi) \\ \text{归一化: } C = \frac{1}{\sqrt{2\pi}} \end{cases} \Rightarrow l_z = m\hbar \quad m = 0, 1, 2, \dots \Rightarrow \psi = \frac{1}{\sqrt{2\pi}} e^{im\varphi}, \quad m = 0, 1, 2, \dots$$

$$\hat{l}^2\psi = \vec{l}^2\psi$$

设 $\psi = Y(\theta, \varphi)$, 特征值为 $\lambda\hbar^2$.

$$\left[\frac{1}{\sin^2\theta} \frac{\partial}{\partial\theta} \left(\sin\theta \frac{\partial}{\partial\theta} \right) + \frac{1}{\sin^2\theta} \frac{\partial^2}{\partial\varphi^2} \right] Y(\theta, \varphi) = -\lambda Y(\theta, \varphi)$$

分离变量解这个方程, 设 $Y(\theta, \varphi) = \Theta(\theta)\Phi(\varphi)$

$$\frac{\frac{\partial^2}{\partial\varphi^2}\Phi(\varphi)}{\Phi(\varphi)} = \frac{\sin\theta \frac{\partial}{\partial\theta} (\sin\theta \frac{d}{d\theta}\Theta) + \lambda^2 \sin^2\theta}{\Theta(\theta)}$$

由于我们的目的是找到共同本征波函数, 所以与一般的分离变量不同的是, 这里不随意设一个常数, 而是把由 \hat{l}_z 算出来的波函数带入左半边求常数, 得常数为上面的 m^2 .

所以右半边为

$$\frac{\sin \theta \frac{\partial}{\partial \theta} (\sin \theta \frac{d}{d\theta} \Theta) + \lambda^2 \sin^2 \theta}{\Theta(\theta)} = m^2$$

$$\iff \frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{d}{d\theta} \Theta \right) + \left(\lambda - \frac{m^2}{\sin^2 \theta} \right) \Theta = 0$$

解这个方程, 要花稍微多一点的功夫

(a) 变量代换 $x = \cos \theta$

$$(1 - x^2) \frac{d^2 \Theta}{dx^2} - 2x \frac{d\Theta}{dx} + \left(\lambda - \frac{m^2}{1 - x^2} \right) \Theta = 0$$

该方程被称为 associated Legendre equation.

(b) 这个方程有两个奇点 $x = \pm 1$

(c) 为解这个方程, 首先讨论 $m = 0$ 的情况, 即

$$(1 - x^2) \frac{d^2 \Theta}{dx^2} - 2x \frac{d\Theta}{dx} + \lambda \Theta = 0$$

该方程被称为 Legendre equation.

用级数来求这个方程的解, 得到

$$C_{k+2} = \frac{k(k+1) - \lambda}{(k+1)(k+2)} C_k, \quad k = 0, 1, 2, \dots$$

$$k \rightarrow \infty, \quad \frac{C_{k+2}}{C_k} =$$

反正最终得到关联勒让德方程的解

$$Y_{lm}(\theta, \varphi) = N_{lm} \cdot P_l^{|m|}(\cos \theta) \cdot e^{im\varphi}$$

$$N_m = \sqrt{\frac{(l - |m|)!(2l + 1)}{4\pi \cdot (l + |m|)!}}$$

$$P_l^{|m|}(\xi) = (1 - \xi^2)^{\frac{|m|}{2}} \cdot \frac{d^{|m|}}{d\xi^{|m|}} P_l(\xi) \quad P_l(\xi) = \frac{1}{2^l \cdot l!} \frac{d^l}{d\xi^l} (\xi^2 - 1)^l$$

$$P_l^{-|m|}(\xi) = (-1)^{|m|} \cdot \frac{(l - |m|)!}{(l + |m|)!} P_l^{|m|}(\xi)$$

$$Y_{0,0} = \frac{1}{\sqrt{4\pi}}$$

$$\begin{aligned}
Y_{1,1} &= -\sqrt{\frac{3}{8\pi}} \sin \theta \cdot e^{i\varphi} & Y_{1,0} &= \sqrt{\frac{3}{4\pi}} \cos \theta & Y_{1,-1} &= \sqrt{\frac{3}{8\pi}} \sin \theta \cdot e^{-i\varphi} \\
Y_{2,2} &= -\sqrt{\frac{15}{32\pi}} \sin^2 \theta \cdot e^{2i\varphi} & Y_{2,1} &= -\sqrt{\frac{15}{8\pi}} \sin \theta \cos \theta \cdot e^{i\varphi} \\
Y_{2,0} &= \sqrt{\frac{5}{16\pi}} (3 \cos^2 \theta - 1) \\
Y_{2,-2} &= \sqrt{\frac{15}{32\pi}} \sin^2 \theta \cdot e^{-2i\varphi} & Y_{2,-1} &= \sqrt{\frac{15}{8\pi}} \sin \theta \cos \theta \cdot e^{-i\varphi}
\end{aligned}$$

$$\begin{aligned}
[\hat{F}, \hat{G}] = i\hat{k} &\implies \overline{(\Delta \hat{F})^2} \cdot \overline{(\Delta \hat{G})^2} \geq \frac{\hat{k}^2}{4} \\
[\hat{x}, \hat{p}_x] = i\hbar &\implies \overline{(\Delta \hat{x})^2} \cdot \overline{(\Delta \hat{p}_x)^2} \geq \frac{\hbar^2}{4} \\
[\hat{l}_x, \hat{l}_y] = i\hbar \hat{l}_z &\implies \overline{(\Delta \hat{l}_x)^2} \cdot \overline{(\Delta \hat{l}_y)^2} \geq \frac{\hbar^2}{4} \hat{l}_z^2
\end{aligned}$$

薛定谔表象下: 力学量平均值的时间演化来自 ψ

$$\frac{d\langle \hat{A} \rangle}{dt} = \frac{1}{i\hbar} \langle [\hat{A}, \hat{H}] \rangle$$

$$\begin{aligned}
\frac{d\langle \hat{A} \rangle}{dt} &= \frac{d}{dt} (\psi, \hat{A} \psi) \\
&= \left(\frac{d}{dt} \psi, \hat{A} \psi \right) + \left(\psi, \hat{A} \frac{d}{dt} \psi \right) \\
&= \left(\frac{\hat{H}}{i\hbar} \psi, \hat{A} \psi \right) + \left(\psi, \hat{A} \cdot \frac{\hat{H}}{i\hbar} \psi \right) \\
&= -\frac{1}{i\hbar} (\psi, \hat{H} \hat{A} \psi) + \frac{1}{i\hbar} (\psi, \hat{A} \hat{H} \psi) \\
&= \frac{1}{i\hbar} \langle [\hat{A}, \hat{H}] \rangle
\end{aligned}$$

海森堡表象下: 力学量平均值随时间的演化来自算符.

$$\frac{d\hat{A}}{dt} = \frac{1}{i\hbar} [\hat{A}, \hat{H}]$$

$$\begin{aligned}
\frac{d\hat{A}}{dt} &= \frac{d}{dt}(\hat{U}^\dagger \cdot \hat{A}_0 \cdot \hat{U}) \quad \text{其中 } \hat{U} = e^{-\frac{i}{\hbar} \hat{H}_0 \cdot t} \\
&= \frac{i}{\hbar} \hat{H}_0 \cdot \hat{U}^\dagger \cdot \hat{A}_0 \cdot \hat{U} - \frac{i}{\hbar} \hat{U}^\dagger \cdot \hat{A}_0 \cdot \hat{H}_0 \cdot \hat{U} \\
&= \frac{i}{\hbar} \hat{U}^\dagger \cdot \hat{H}_0 \cdot \hat{A}_0 \cdot \hat{U} - \frac{i}{\hbar} \hat{U}^\dagger \cdot \hat{A}_0 \cdot \hat{H}_0 \cdot \hat{U} \\
&= \frac{i}{\hbar} (\hat{U}^\dagger \cdot \hat{H}_0 \cdot \hat{U}) \cdot (\hat{U}^\dagger \cdot \hat{A}_0 \cdot \hat{U}) - \frac{i}{\hbar} (\hat{U}^\dagger \cdot \hat{A}_0 \cdot \hat{U}) \cdot (\hat{U}^\dagger \cdot \hat{H}_0 \cdot \hat{U}) \\
&= \frac{i}{\hbar} \hat{H} \cdot \hat{A} - \frac{i}{\hbar} \hat{A} \cdot \hat{H} \\
&= \frac{1}{i\hbar} [\hat{A}, \hat{H}]
\end{aligned}$$

守恒量: 任意量子态下的平均值和观测值的概率不随时间改变. \hat{A} 不显含时, 且 $[\hat{A}, \hat{H}] = 0$

特点:

1. 系统在演化过程中, 守恒量的本征态和概率分布不变
2. 描述守恒量的量子数为好量子数
3. 若体系存在两个或两个以上的守恒量, 且彼此不对易, 则一般体系存在能级简并.

几个守恒及其对应的不变性

1. 空间平移不变性与动量守恒

首先求平移算符, 由于平移算符要满足式子 $D(\delta x)\psi(x) = \psi(x + \delta x)$.将右边泰勒展开, 得到平移算符的表达式为

$$D(\delta x) = e^{\frac{i}{\hbar} \delta x \cdot p_x}, \quad D(\delta \vec{r}) = e^{\frac{i}{\hbar} \delta \vec{r} \cdot \vec{p}}$$

在讨论平移不变性, 满足平移不变性的体系要满足 $D(\delta \vec{r})\psi(\vec{r}) = C \cdot \psi(\vec{r})$

$$\frac{i}{\hbar} \frac{\partial}{\partial t} \psi = \hat{H} \psi \implies \frac{i}{\hbar} \frac{\partial}{\partial t} (\hat{D} \psi) = \hat{H} (\hat{D} \psi) \implies$$

而本身将方程 $\frac{i}{\hbar} \frac{\partial}{\partial t} \psi = \hat{H} \psi$ 同左乘算符 \hat{D} 得到

$$\hat{D} \frac{i}{\hbar} \frac{\partial}{\partial t} \psi = \hat{D} \hat{H} \psi$$

得到 $[\hat{H}, \hat{D}] = 0$

$$[\hat{H}, \hat{D}] = [\hat{H}, e^{\frac{i}{\hbar} \delta \vec{r} \cdot \vec{p}}] \implies [\hat{H}, \hat{P}] = 0$$

2. 空间转动不变性与角动量守恒

先讨论 z 轴旋转, 求 z 轴旋转算符的表达式, z 轴旋转算符要满足 $\hat{R}_z(\delta\varphi)\psi(r, \theta, \varphi) = \psi(r, \theta, \varphi + \delta\varphi)$, 推出 z 轴旋转算符的表达式为

$$\hat{R}_z(\delta\varphi) = e^{\frac{i}{\hbar}\delta\varphi \cdot L_z}$$

$$\hat{R}(\vec{n}, \delta\varphi) = e^{\frac{i}{\hbar}\delta\varphi \cdot (\vec{L} \cdot \vec{n})}$$

求出表达式后, 空间旋转不变性要求体系有 $[\hat{R}(\vec{n}, \delta\varphi), \hat{H}] = 0$, 推出 $[\hat{H}, \hat{L}] = 0$, 角动量守恒.

3. 时间平移不变性与能量守恒

时间平移算符即演化算符: $\hat{U}(\delta t) = e^{-\frac{i}{\hbar}\delta t \hat{H}}$

满足时间平移的体系要满足 $[\hat{U}(t), \hat{H}] = 0$, 推出 $[\hat{H}, \hat{H}] = 0$

4. 空间反射不变性与全同粒子波函数的交换对称性

空间反射算符为 \hat{P}_{ij} , 其满足 $\hat{P}_{ij}\psi(\vec{r}) = \psi(-\vec{r})$.

空间反射不变性要求体系满足 $[\hat{P}_{ij}, \hat{H}] = 0$, 推出交换对称性守恒.

投影算符: $\{|Q_n\rangle\langle Q_n|\}$, 作用到任一态矢 $|\psi\rangle$. 相当于把 $|\psi\rangle$ 投影到一个基矢 $|Q_n\rangle$ 上.

$$|\psi\rangle = \sum_n |Q_n\rangle (\langle Q_n|\psi\rangle)$$

$$|\psi\rangle = \begin{pmatrix} \langle Q_1|\psi\rangle \\ \langle Q_2|\psi\rangle \\ \langle Q_3|\psi\rangle \\ \vdots \\ \langle Q_n|\psi\rangle \end{pmatrix} = \psi(\hat{F}) \quad \hat{F} \text{的基矢组为 } \{|Q_n\rangle\}$$

矩阵元:

1. \hat{L} 在 \hat{F} 的表象下, $L_{kn} = \langle Q_k|\hat{L}|Q_n\rangle$.

2. \hat{F} 在 \hat{F} 表象下, $F_{kn} = \langle Q_k|\hat{F}|Q_n\rangle$. 将会对角阵.

3. 若 $[\hat{L}, \hat{F}] = 0$, 则 $L_{kn} = \langle Q_k|\hat{L}|Q_n\rangle$ 将是对角阵.

平均值

1. 无表象

$$\bar{L} = \langle \psi|\hat{L}|\psi\rangle$$

2. 有表象

$$\begin{aligned} \bar{L} &= \langle \psi|\left(\sum_k |Q_k\rangle\langle Q_k|\right)\hat{L}\left(\sum_n |Q_n\rangle\langle Q_n|\right)|\psi\rangle \\ &= \sum_k \sum_n (\langle \psi|Q_k\rangle) \langle Q_k|\hat{L}|Q_n\rangle (\langle Q_n|\psi\rangle) \end{aligned}$$

本征方程:

1. 无表象

$$\hat{L}|\psi\rangle = \lambda|\psi\rangle$$

2. 有表象

$$\hat{L}\left(\sum_n |Q_n\rangle\langle Q_n|\right)|\psi\rangle = \lambda\left(\sum_n |Q_n\rangle\langle Q_n|\right)|\psi\rangle$$

上述方程左乘 $\langle Q_k|$ $k = 1, 2, \dots$, 得到一系列方程

$$\sum_n \langle Q_k|\hat{L}|Q_n\rangle\langle Q_n|\psi\rangle = \lambda\sum_n \langle Q_k|Q_n\rangle\langle Q_n|\psi\rangle = \lambda\langle Q_k|\psi\rangle \quad k = 1, 2, 3 \dots$$

即

$$\sum_n \langle Q_k|\hat{L}|Q_n\rangle\langle Q_n|\psi\rangle = \lambda\langle Q_k|\psi\rangle \quad k = 1, 2, 3 \dots$$

定态薛定谔方程:

1. 无表象

$$i\hbar\frac{\partial}{\partial t}|\psi\rangle = \hat{H}|\psi\rangle$$

2. 有表象

$$i\hbar\frac{\partial}{\partial t}\left(\sum_n |Q_n\rangle\langle Q_n|\right)|\psi\rangle = \hat{H}\left(\sum_n |Q_n\rangle\langle Q_n|\right)|\psi\rangle$$

上述方程左乘 $\langle Q_k|$ $k = 1, 2, \dots$, 得到一系列方程

$$i\hbar\frac{\partial}{\partial t}\sum_n \langle Q_k|Q_n\rangle\langle Q_n|\psi\rangle = i\hbar\frac{\partial}{\partial t}\langle Q_k|\psi\rangle = \sum_n \langle Q_k|\hat{H}|Q_n\rangle\langle Q_n|\psi\rangle \quad k = 1, 2, 3 \dots$$

即

$$i\hbar\frac{\partial}{\partial t}\langle Q_k|\psi\rangle = \sum_n \langle Q_k|\hat{H}|Q_n\rangle\langle Q_n|\psi\rangle \quad k = 1, 2, 3 \dots$$

表象变换: 用幺正变换矩阵

幺正变换矩阵的性质:

1. 幺正性: $S^\dagger S = I$ 保内积

$$\psi^\dagger(\hat{F})\psi(\hat{F}) = \psi^\dagger(\hat{F})(S^\dagger S)\psi(\hat{F}) = \left(S\psi(\hat{F})\right)^\dagger \left(S\psi(\hat{F})\right) = \psi^\dagger(\hat{F}')\psi(\hat{F}')$$

即是

$$\psi^\dagger(\hat{F})\psi(\hat{F}) = \psi^\dagger(\hat{F}')\psi(\hat{F}')$$

2. 么正变换不改变算符的本征值

$$\begin{aligned}\hat{L}|\psi\rangle &= \lambda|\psi\rangle \implies \\ S\hat{L}S^\dagger|\psi\rangle &= \lambda S|\psi\rangle \implies \\ \hat{L}'(S|\psi\rangle) &= \lambda(S|\psi\rangle)\end{aligned}$$

3. 么正变换不改变矩阵的迹

$$\text{Tr}(\hat{F}) = \sum (\text{本征值})$$

4. 么正变换不改变厄密矩阵的厄密性

5. 么正变换的物理意义: 概率守恒

态矢作表象变换

已知两个表象 $\hat{F} \sim \{Q_n\}$ 和 $\hat{F}' \sim \{P_n\}$

$$S_{\alpha\beta} = \langle P_\alpha | Q_\beta \rangle$$

$$S_{\alpha\beta} = \langle \text{后来表象的本征矢} | \text{开始表象的本征矢} \rangle$$

$$| \text{后来表象下的态矢} \rangle = S | \text{开始表象的态矢} \rangle$$

力学量作表象变换:

已知两个表象 $\hat{F} \sim \{Q_n\}$, $\hat{F}' \sim \{P_n\}$. 可求

$$S_{\alpha\beta} = \langle \text{后来表象的本征矢} | \text{开始表象的本征矢} \rangle$$

$$[\text{后来表象下的矩阵}] = S[\text{开始表象下的矩阵}]S^\dagger$$

$$[\text{开始表象下的矩阵}] = S^\dagger[\text{后来表象下的矩阵}]S$$

求坐标表象下 \hat{p} 的表达式 $\langle x | \hat{p}$:

$$\begin{aligned}\langle x | \hat{p} | p \rangle &= p \langle x | p \rangle = p \psi_p(x) \\ &= p \left(\frac{1}{\sqrt{2\pi\hbar}} e^{\frac{i}{\hbar} p \cdot x} \right) \\ &= \left(-i\hbar \frac{\partial}{\partial x} \right) \left(\frac{1}{\sqrt{2\pi\hbar}} e^{\frac{i}{\hbar} p \cdot x} \right) \\ &= \left(-i\hbar \frac{\partial}{\partial x} \right) (\langle x | p \rangle)\end{aligned}$$

随后将本征矢 $|p\rangle$ 换成普通矢 $|\psi\rangle$ 几乎一样的步骤

$$\begin{aligned}
\langle x|\hat{p}|\psi\rangle &= \langle x|\hat{p} \int dp |p\rangle \langle p|\psi\rangle \\
&= \int dp \langle x|\hat{p}|p\rangle \langle p|\psi\rangle \\
&= \int dp (-i\hbar \frac{\partial}{\partial x}) \langle x|p\rangle \langle p|\psi\rangle \\
&= (-i\hbar \frac{\partial}{\partial x}) \int dp \langle x|p\rangle \langle p|\psi\rangle \\
&= (-i\hbar \frac{\partial}{\partial x}) \langle x| \int dp |p\rangle \langle p|\psi\rangle \\
&= -i\hbar \frac{\partial}{\partial x} \langle x|\psi\rangle
\end{aligned}$$

对比可得 $\langle x|\hat{p} = -i\hbar \frac{\partial}{\partial x} \langle x|$.

求动量表象下 \hat{x} 的表达式 $\langle p|\hat{x}$:

$$\begin{aligned}
\langle p|\hat{x}|x\rangle &= x \langle x|xp \\
&= x \psi_x(p) \\
&= x \left(\frac{1}{\sqrt{2\pi\hbar}} e^{-\frac{i}{\hbar} p \cdot x} \right) \\
&= i\hbar \frac{\partial}{\partial p} \psi_x(p) \\
&= i\hbar \frac{\partial}{\partial p} \langle p|x\rangle
\end{aligned}$$

随后将本征矢 $|x\rangle$ 换成 $|\psi\rangle$ 几乎一样的步骤:

$$\begin{aligned}
\langle p|\hat{x}|\psi\rangle &= \langle p|\hat{x} \int dx |x\rangle \langle x|\psi\rangle \\
&= \int dx \langle p|\hat{x}|x\rangle \langle x|\psi\rangle \\
&= \int dx \left(i\hbar \frac{\partial}{\partial p} \langle p|x\rangle \right) \langle x|\psi\rangle \\
&= i\hbar \frac{\partial}{\partial p} \langle p| \int dx |x\rangle \langle x|\psi\rangle \\
&= i\hbar \frac{\partial}{\partial p} \langle p|\psi\rangle
\end{aligned}$$

对比得到 $\langle p|\hat{x} = i\hbar \frac{\partial}{\partial p} \langle p|$

谐振子的升降算符法:

$$\hat{a}_- = \sqrt{\frac{m\omega}{2\hbar}} \hat{x} + \frac{i}{\sqrt{2m\omega\hbar}} \hat{p}_x$$

$$\hat{a}_+ = \sqrt{\frac{m\omega}{2\hbar}}\hat{x} - \frac{i}{\sqrt{2m\omega\hbar}}\hat{p}_x$$

$$\hat{x} = \sqrt{\frac{\hbar}{2m\omega}}(\hat{a}_+ + \hat{a}_-)$$

$$\hat{p}_x = i\sqrt{\frac{m\omega\hbar}{2}}(\hat{a}_+ - \hat{a}_-)$$

$$\hat{H} = (\hat{a}_+\hat{a}_- + \frac{1}{2})\hbar\omega = (\hat{a}_-\hat{a}_+ - \frac{1}{2})\hbar\omega$$

$$[\hat{a}_-, \hat{a}_+] = 1$$

$$[\hat{a}_-, \hat{H}] = \hbar\omega\hat{a}_-$$

$$[\hat{a}_+, \hat{H}] = -\hbar\omega\hat{a}_+$$

$$\hat{a}_-|n\rangle = \sqrt{n}|n-1\rangle$$

$$\hat{a}_+|n\rangle = \sqrt{n+1}|n+1\rangle$$

$$\hat{x}|n\rangle = \sqrt{\frac{\hbar}{2m\omega}}(\sqrt{n+1}|n+1\rangle + \sqrt{n}|n-1\rangle)$$

$$\hat{p}|n\rangle = i\sqrt{\frac{m\omega\hbar}{2}}(\sqrt{n+1}|n+1\rangle - \sqrt{n}|n-1\rangle)$$

$$\begin{aligned}\hat{x}^2|n\rangle &= \left(\sqrt{\frac{\hbar}{2m\omega}}\right)^2 \left(\sqrt{(n+1)(n+2)}|n+2\rangle\right. \\ &\quad \left.+ (2n+1)|n\rangle + \sqrt{n(n-1)}|n-2\rangle\right)\end{aligned}$$

$$\begin{aligned}\hat{x}^3|n\rangle &= \left(\sqrt{\frac{\hbar}{2m\omega}}\right)^3 \left(\sqrt{(n+3)(n+2)(n+1)}|n+3\rangle\right. \\ &\quad \left.+ 3(n+1)\sqrt{n+1}|n+1\rangle + 2n\sqrt{n}|n-1\rangle + \sqrt{n(n-1)(n-2)}|n-3\rangle\right)\end{aligned}$$

$$\begin{aligned}\hat{p}^2|n\rangle &= \left(i\sqrt{\frac{m\omega\hbar}{2}}\right)^2 \left(\sqrt{(n+2)(n+1)}|n+2\rangle\right. \\ &\quad \left.- (2n+1)|n\rangle + \sqrt{n(n-1)}|n-2\rangle\right)\end{aligned}$$

$$\begin{aligned}\hat{p}^3 |n\rangle = & \left(i\sqrt{\frac{m\omega\hbar}{2}}\right)^3 \left(\sqrt{(n+3)(n+2)(n+1)} |n+3\rangle \right. \\ & \left. - 3(n+1)\sqrt{n+1} |n+1\rangle + 3n\sqrt{n} |n-1\rangle - \sqrt{n(n-1)(n-2)} |n-3\rangle\right)\end{aligned}$$

中心力场: 中心力场对应着特殊的 \hat{H} :

$$[\hat{H}, \hat{H}] = 0, \quad [\hat{l}^2, \hat{H}] = 0 \quad [\hat{l}_x, \hat{H}] = 0, [\hat{l}_y, \hat{H}] = 0, \quad [\hat{l}_z, \hat{H}] = 0$$

解方程

$$\begin{aligned}-\frac{\hbar^2}{2m}\nabla^2\psi + V(r)\psi &= E\psi \implies \\ \nabla_r^2\psi + \frac{2m}{\hbar^2}(E - V(r))\psi &= -\nabla_{\theta,\varphi}^2\psi \\ \frac{\{\nabla_r^2 + \frac{2m}{\hbar^2}(E - V(r))\}R(r)}{R(r)} &= \frac{-\nabla_{\theta,\varphi}^2 Y(\theta, \varphi)}{Y(\theta, \varphi)} \implies \\ \frac{\{\frac{\partial}{\partial r}(r^2 \frac{\partial R}{\partial r}) + \frac{2mr^2}{\hbar^2}[E - V(r)]\}R}{R} &= l(l+1)\end{aligned}$$

解这个方程, 首先换元 $\chi = r \cdot R(r)$.

$$\frac{d^2\chi}{dr^2} + \frac{2m}{\hbar^2} \left\{ E - V(r) - \frac{\hbar^2}{2m} \frac{l(l+1)}{r^2} \right\} \chi = 0$$

中心场

$$V(r) = \begin{cases} 0, & 0 < r < a \\ \infty, & r > a \end{cases}$$

$0 < r < a$ 时, 方程为 $V = 0$

$$\frac{d^2\chi}{dr^2} + \frac{2m}{\hbar^2} \left[E - \frac{\hbar^2}{2m} \frac{l(l+1)}{r^2} \right] \chi = 0$$

角向波函数

$$Y_{l,m_l}(\theta, \varphi) = C_{l,m_l} P_l^{m_l}(\cos\theta) e^{im_l\varphi}$$

where

$$P_l^{m_l}(\xi) = (1 - \xi^2)^{\frac{|m_l|}{2}} \frac{d^{|m_l|}}{d\xi^{|m_l|}} P_l(\xi)$$

$$P_l(\xi) = \frac{1}{2^l \cdot l!} \frac{d^l}{d\xi^l} (\xi^2 - 1)^l$$

$$P_l^{-|m_l|} = (-1)^m \frac{(l - |m_l|)!}{(l + |m_l|)!} P_l^{|m_l|}(\xi)$$

$$C_{l,m_l} = \sqrt{\frac{(l - |m_l|)!(2l + 1)}{(l + |m_l|)!4\pi}}$$

径向波函数

$$R_{n,l}(r) = N_{n,l} e^{-\frac{r}{2na_0}} \left(\frac{2r}{na_0} \right)^l F(-n + l + 1, 2l + 2, \frac{2r}{na_0})$$

$$E_n = -\frac{\mu Z^2 e^4}{2\hbar n^2}$$

径向几率分布:

$$W_{n,l,m_l}(r)dr = \int_0^{2\pi} d\varphi \int_0^\pi |R_{n,l}(r)Y_{l,m_l}(\theta, \varphi)|^2 r^2 \sin\theta d\theta d\varphi$$

角向几率分布

$$W_{n,l,m}(\theta, \varphi)d\Omega = |Y_{l,m}(\theta, \varphi)|^2 d\Omega \int_0^\infty |R_{n,l}(r)|^2 r^2 dr$$

电流分布和磁矩

$$j_r = -\frac{i\hbar}{2m_e} e \left(\psi^* \cdot \frac{\partial}{\partial r} \psi - \psi \cdot \frac{\partial}{\partial r} \psi^* \right) = 0$$

$$\begin{aligned} j_\varphi &= -\frac{i\hbar}{2m_e} e \left(\psi^* \cdot \frac{1}{r \cdot \sin\theta} \frac{\partial}{\partial \varphi} \psi - \psi \cdot \frac{1}{r \sin\theta} \frac{\partial}{\partial \varphi} \psi^* \right) \\ &= -\frac{ie\hbar}{2m_e} \cdot \frac{1}{r \sin\theta} \cdot (2im_l) |\psi_{n,l,m_l}|^2 \\ &= -\frac{e\hbar m_l}{m_e \cdot r \sin\theta} \end{aligned}$$

$$j_\theta = -\frac{i\hbar}{2m_e} e \left(\psi^* \frac{1}{r} \frac{\partial}{\partial \theta} \psi - \psi \frac{1}{r} \frac{\partial}{\partial \theta} \psi^* \right) = 0$$

$$a_0 = \frac{\hbar^2}{\mu_H e^2} \approx 0.529 \cdot 10^{-10} \text{m}$$

$$d\mu_z = \frac{1}{c} S dI = \frac{1}{c} \cdot \pi r^2 \cdot \sin^2 \theta dI$$

$$\begin{aligned} \mu_z &= \frac{1}{c} \int \pi r^2 \sin^2 \theta \cdot j_\varphi d\sigma \\ &= -\frac{\hbar m_l e}{2c\mu_0} \int |\psi_{n,l,m_l}|^2 \cdot 2\pi r \sin\theta d\sigma \\ &= -\frac{\hbar m_l e}{2c\mu_0} \int |\psi_{n,l,m_l}|^2 \cdot 2\pi r \sin\theta \cdot r \cdot d\theta dr \\ &= -\frac{\hbar m_l e}{2c\mu_0} = -\mu_B m_l \quad \mu_B = \frac{\hbar|e|}{2c\mu_0} \end{aligned}$$

角动量的定义: $\hat{L} \times \hat{L} = i\hbar\hat{L}$ (隐含性质 $[\hat{L}_\alpha, \hat{L}^2] = 0$)
升降算符:

$$\begin{aligned}\hat{J}_+ &= \hat{J}_x + i\hat{J}_y & \hat{J}_- &= \hat{J}_x - i\hat{J}_y \\ \hat{J}_x &= \frac{1}{2}(\hat{J}_+ + \hat{J}_-) & \hat{J}_y &= \frac{i}{2}(\hat{J}_- - \hat{J}_+)\end{aligned}$$

矩阵表示

$$\langle j', m' | \hat{J}_z | j, m \rangle = m\hbar\delta_{j,j'}\delta_{m,m'}$$

$$\langle j', m' | \hat{J}^2 | j, m \rangle = j(j+1)\hbar^2\delta_{j,j'}\delta_{m,m'}$$

$$\begin{aligned}\hat{J}_+ | j, m \rangle &= \hbar\sqrt{(j+m+1)(j-m)} | j, m+1 \rangle \\ &= \hbar\sqrt{j(j+1) - m(m+1)} | j, m+1 \rangle\end{aligned}$$

$$\begin{aligned}\hat{J}_- | j, m \rangle &= \hbar\sqrt{(j-m+1)(j+m)} | j, m-1 \rangle \\ &= \hbar\sqrt{j(j+1) - m(m-1)}\end{aligned}$$

$$\begin{aligned}\hat{J}_x | j, m \rangle &= \frac{\hbar}{2} \left(\sqrt{(j+m+1)(j-m)} | j, m+1 \rangle \right. \\ &\quad \left. + \sqrt{(j-m+1)(j+m)} | j, m-1 \rangle \right)\end{aligned}$$

$$\begin{aligned}\hat{J}_y | j, m \rangle &= \frac{i\hbar}{2} \left(-\sqrt{(j+m+1)(j-m)} | j, m+1 \rangle \right. \\ &\quad \left. + \sqrt{(j-m+1)(j+m)} | j, m-1 \rangle \right)\end{aligned}$$

$$[\hat{J}^2, f(\hat{J})] = 0$$

$$[\hat{J}_z, \hat{J}_-] = -\hbar\hat{J}_- \quad [\hat{J}_z, \hat{J}_+] = \hbar\hat{J}_+$$

$$\hat{J}^2 - \hat{J}_z + \hbar\hat{J}_z = \hat{J}_+\hat{J}_- \quad \hat{J}^2 - \hat{J}_z^2 - \hbar\hat{J}_z = \hat{J}_-\hat{J}_+$$

$$\begin{aligned}\hat{J}_x^2 | j, m \rangle &= \left(\frac{\hbar}{2} \right)^2 \sqrt{(j+m+2)(j+m+1)(j-m)(j-m-1)} | j, m+2 \rangle \\ &\quad + 2(j^2 - m^2 + j) | j, m \rangle \\ &\quad + \sqrt{(j-m+2)(j-m+1)(j+m)(j+m-1)} | j, m-2 \rangle\end{aligned}$$

$$\begin{aligned}\hat{J}_y^2 |j, m\rangle = & \left(\frac{i\hbar}{2}\right)^2 \sqrt{(j+m+2)(j+m+1)(j-m)(j-m-1)} |j, m+2\rangle \\ & - 2(j^2 - m^2 + j) |j, m\rangle \\ & + \sqrt{(j-m+2)(j-m+1)(j+m)(j+m+1)} |j, m-2\rangle\end{aligned}$$

自旋角动量

1. 每个电子都有自旋角动量, 它在空间任何方向上的投影只能取两个数值
2. 每个电子都有自旋磁矩, 与自旋角动量的关系, $\text{vec}\mu_s = -\frac{e}{\mu c}\vec{s}$

$$\mu_{s_z} = \pm \frac{e\hbar}{2\mu c} = \pm\mu_B$$

自旋角动量算符

$$|s_x, +\rangle = \frac{1}{\sqrt{2}} (|s_z, +\rangle + |s_z, -\rangle)$$

$$|s_x, -\rangle = \frac{1}{\sqrt{2}} (|s_z, +\rangle - |s_z, -\rangle)$$

$$|s_y, +\rangle = \frac{1}{\sqrt{2}} (|s_z, +\rangle + i|s_z, -\rangle)$$

$$|s_y, -\rangle = \frac{1}{\sqrt{2}} (|s_z, +\rangle - i|s_z, -\rangle)$$

$$\hat{S} = \frac{\hbar}{2}\hat{\sigma}$$

$$[\hat{S}_i, \hat{S}_j] = i\hbar\epsilon_{ijk}\hat{s}_k$$

$$[\hat{S}_i, \hat{S}_j]_+ = \hbar\delta_{ij}$$

$$[\hat{\sigma}_\alpha, \hat{\sigma}_\beta] = 2i\epsilon_{\alpha\beta\gamma}\hat{\sigma}_\gamma$$

$$\hat{\sigma}_x^2 = \frac{4}{\hbar^2}\hat{S}_x^2 = 1 \quad \hat{\sigma}_x^2 = \hat{\sigma}_y^2 = \hat{\sigma}_z^2 = 1$$

$$[\hat{\sigma}_\alpha, \hat{\sigma}_\beta]_+ = 2\delta_{\alpha\beta} \quad [\hat{\sigma}_\alpha, \hat{\sigma}_\beta] = 2i\epsilon_{\alpha\beta\gamma}\hat{\sigma}_\gamma$$

$$\hat{\sigma}_x \left| \frac{1}{2} \right\rangle = \left| -\frac{1}{2} \right\rangle \quad \hat{\sigma}_x \left| -\frac{1}{2} \right\rangle = \left| \frac{1}{2} \right\rangle$$

$$\hat{\sigma}_y \left| \frac{1}{2} \right\rangle = i \left| -\frac{1}{2} \right\rangle \quad \hat{\sigma}_y \left| -\frac{1}{2} \right\rangle = -i \left| \frac{1}{2} \right\rangle$$

$$\hat{\sigma}_z \left| \frac{1}{2} \right\rangle = \left| \frac{1}{2} \right\rangle \quad \hat{\sigma}_z \left| -\frac{1}{2} \right\rangle = - \left| -\frac{1}{2} \right\rangle$$

$$\hat{\sigma}_\alpha \hat{\sigma}_\beta = \delta_{\alpha\beta} + i\varepsilon_{\alpha\beta\gamma} \hat{\sigma}_\gamma \quad \hat{\sigma}_\alpha \hat{\sigma}_\beta = -\hat{\sigma}_\beta \hat{\sigma}_\alpha$$

$$\hat{\sigma}_x = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \quad \lambda = 1, \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \lambda = -1, \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$\hat{\sigma}_y = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \quad \lambda = 1, \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ i \end{pmatrix}, \lambda = -1, \frac{1}{\sqrt{2}} \begin{pmatrix} -1 \\ i \end{pmatrix}$$

$$\hat{\sigma}_z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \quad \lambda = 1, \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \lambda = -1, \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$R_x(\theta) = \begin{pmatrix} \cos \frac{\theta}{2} & -i \sin \frac{\theta}{2} \\ -i \sin \frac{\theta}{2} & \cos \frac{\theta}{2} \end{pmatrix}$$

$$R_y(\theta) = \begin{pmatrix} \cos \frac{\theta}{2} & -\sin \frac{\theta}{2} \\ \sin \frac{\theta}{2} & \cos \frac{\theta}{2} \end{pmatrix}$$

$$R_z(\theta) = \begin{pmatrix} e^{-\frac{i\theta}{2}} & 0 \\ 0 & e^{\frac{i\theta}{2}} \end{pmatrix}$$

$$R(\varphi, \theta) = \begin{pmatrix} e^{\frac{i\varphi}{2} \cos \frac{\theta}{2}} & -e^{\frac{i\varphi}{2} \sin \frac{\theta}{2}} \\ e^{-\frac{i\varphi}{2} \sin \frac{\theta}{2}} & e^{\frac{-i\varphi}{2} \cos \frac{\theta}{2}} \end{pmatrix}$$

角动量耦合

$$\begin{cases} \hat{J}_1 \times \hat{J}_1 = i\hbar \hat{J}_1 \\ \hat{J}_2 \times \hat{J}_2 = i\hbar \hat{J}_2 \\ [\hat{J}_1, \hat{J}_2] = 0 \end{cases} \implies \hat{J} = \hat{J}_1 + \hat{J}_2 \text{ 满足角动量的定义}$$

无耦合表象: $\{ \hat{J}_1^2, \hat{J}_{1z}, \hat{J}_2^2, \hat{J}_{2z} \}$, 基矢 $|j_1, m_1, j_2, m_2\rangle$.

$$\hat{J}_1^2 |j_1, m_1, j_2, m_2\rangle = j_1(j_1 + 1)\hbar^2 |j_1, m_1, j_2, m_2\rangle$$

$$\hat{J}_{1z} |j_1, m_1, j_2, m_2\rangle = m_1\hbar |j_1, m_1, j_2, m_2\rangle$$

耦合表象: $\{ \hat{J}^2, \hat{J}_z, \hat{J}_1^2, \hat{J}_2^2 \}$, 基矢 $|j_1, j_2, j, m\rangle$

$$\hat{J}^2 |j_1, j_2, j, m\rangle = j(j + 1)\hbar^2 |j_1, j_2, j, m\rangle$$

$$\hat{J}_z |j_1, j_2, j, m\rangle = m\hbar |j_1, j_2, j, m\rangle$$

CG系数特指由开始表象(耦合表象)转换为后来表象(无耦合表象)的变换矩阵的矩阵元 $\langle m_1, m_2 | j, m \rangle$

计算CG系数的方法

1. $m_1 + m_2 \neq m$ 时, $\langle m_1, m_2 | j, m \rangle = 0$

$$\hat{J}_z = \hat{J}_{1z} + \hat{J}_{2z}$$

$$|j, m\rangle = \sum_{m_1, m_2} |m_1, m_2\rangle \langle m_1, m_2 | j, m\rangle$$

$$\begin{aligned} \hat{J}_z |j, m\rangle &= \sum_{m_1, m_2} \hat{J}_{1z} |m_1, m_2\rangle \langle m_1, m_2 | j, m\rangle \\ &+ \sum_{m_1, m_2} \hat{J}_{2z} |m_1, m_2\rangle \langle m_1, m_2 | j, m\rangle \Rightarrow \end{aligned}$$

$$\begin{aligned} m\hbar |j, m\rangle &= \sum_{m_1, m_2} m_1 \hbar |m_1, m_2\rangle \langle m_1, m_2 | j, m\rangle \\ &+ \sum_{m_1, m_2} m_2 \hbar |m_1, m_2\rangle \langle m_1, m_2 | j, m\rangle \Rightarrow \end{aligned}$$

$$|j, m\rangle = \sum_{m_1, m_2} \frac{m_1 + m_2}{m} |m_1, m_2\rangle \langle m_1, m_2 | j, m\rangle$$

将这个式子和

$$|j, m\rangle = \sum_{m_1, m_2} |m_1, m_2\rangle \langle m_1, m_2 | j, m\rangle$$

可得出

$$m_1 + m_2 \neq m \Rightarrow \langle m_1, m_2 | j, m\rangle = 0$$

2. 用升降算符 $\hat{J}_+ = \hat{J}_{1+} + \hat{J}_{2+}$, $\hat{J}_- = \hat{J}_{1-} + \hat{J}_{2-}$. 和态矢的正交归一性求解其他位置.

具体CG系数的求解题目, 题目中会给出 j_1, j_2 的值.

1. j_1, j_2 的值给出后, $m_1 = -j_1, -j_1 + 1 \dots j_1 - 1, j_1$, $m_2 = -j_2, -j_2 + 1 \dots j_2 - 1, j_2$
2. j_1, j_2 的值给出后, $j = |j_1 - j_2| \dots j_1 + j_2$. 每一个 j 的取值, 都有一串 m 的取值.
3. 列出所有可能的 $|j, m\rangle$ 和可能的 $|m_1, m_2\rangle$.
4. 接下来就是计算 $\langle m_1, m_2 | j, m\rangle$.
5. 列出方程组 $|j, m\rangle = \sum_{m_1, m_2} |m_1, m_2\rangle \langle m_1, m_2 | j, m\rangle$.

6.

$$\begin{cases} m_1 + m_2 \neq m \implies \langle m_1, m_2 | j, m \rangle = 0 \\ |j = j_1 + j_2, m = j_1 + j_2\rangle = |m_1 = j_1, m_2 = j_2\rangle \\ |j = j_1 + j_2, m = -(j_1 + j_2)\rangle = |m_1 = -j_1, m_2 = -j_2\rangle \end{cases}$$

7. 利用上面的三个已知, 可简化方程组,

$$\begin{cases} \text{由上面已知式, 两边作用 } \hat{J}_- \text{ 然后对比方程} \\ \text{利用正交归一性求其他系数} \end{cases}$$

电子的自旋 \hat{S} 和轨道耦合 \hat{L}

$\{\hat{J}^2, \hat{L}^2, \hat{J}_z\}$ 的共同本征函数 $\psi = C_1 Y_{l_1, m_{l_1}} \cdot \chi_{\frac{1}{2}} + C_2 Y_{l_2, m_{l_2}} \cdot \chi_{-\frac{1}{2}}, |l, m_l, m_s\rangle$.

$$\hat{J}^2 = \hat{L}^2 + \hat{S}^2 + 2\hat{L} \cdot \hat{S}$$

设 $\psi_{l, m_l, m_s} = a Y_{l_1, m_{l_1}} \chi_{\frac{1}{2}}(S_z) + b Y_{l_2, m_{l_2}} \chi_{-\frac{1}{2}}(S_z)$. 在 S_z 的表象下

$$\psi_{l, m_l, m_s} = \begin{pmatrix} a Y_{l_1, m_{l_1}} \\ b Y_{l_2, m_{l_2}} \end{pmatrix}$$

下面求本征值

$$\begin{aligned} \hat{l}^2 \psi_{l, m_l, m_s} &= \begin{pmatrix} \hat{l}^2 & 0 \\ 0 & \hat{l}^2 \end{pmatrix} \begin{pmatrix} a Y_{l_1, m_{l_1}} \\ b Y_{l_2, m_{l_2}} \end{pmatrix} = \begin{pmatrix} a \hat{l}^2 Y_{l_1, m_{l_1}} \\ b \hat{l}^2 Y_{l_2, m_{l_2}} \end{pmatrix} \\ &= \begin{pmatrix} a \cdot l_1(l_1 + 1) \hbar^2 Y_{l_1, m_{l_1}} \\ b \cdot l_2(l_2 + 1) \hbar^2 Y_{l_2, m_{l_2}} \end{pmatrix} \end{aligned}$$

要想所设为 \hat{l}^2 的本征值, 必须有 $l_1 = l_2 = l$.

$$\hat{l}^2 \psi_{l, m_l, m_s} = l(l + 1) \hbar^2 \psi_{l, m_l, m_s}$$

$$\begin{aligned} \hat{J}_z \psi_{l, m_l, m_s} &= \begin{pmatrix} \hat{J}_z & 0 \\ 0 & \hat{J}_z \end{pmatrix} \begin{pmatrix} a Y_{l, m_l} \\ b Y_{l, m'_l} \end{pmatrix} \\ &= \begin{pmatrix} \hat{l}_z + \hat{s}_z & 0 \\ 0 & \hat{l}_z + \hat{s}_z \end{pmatrix} \begin{pmatrix} a Y_{l, m_l} \\ b Y_{l, m'_l} \end{pmatrix} \\ &= \begin{pmatrix} a(m_l \hbar + \frac{\hbar}{2}) Y_{l, m_l} \\ b(m'_l - \frac{\hbar}{2}) Y_{l, m'_l} \end{pmatrix} \end{aligned} \quad (2)$$

要想提出常数, 必须有 $m_l + \frac{1}{2} = m'_l - \frac{1}{2}$.

$$\hat{J}^2 \psi_{l,m_l,m_s} = \begin{pmatrix} \hat{l}^2 + \hat{s}^2 + 2\hat{l} \cdot \hat{s} & 0 \\ 0 & \hat{l}^2 + \hat{s}^2 + 2\hat{l} \cdot \hat{s} \end{pmatrix} \begin{pmatrix} aY_{l,m_l,m_s} \\ bY_{l,(m_l+1),m_s} \end{pmatrix} \quad (3)$$

$$\begin{aligned} \begin{pmatrix} \hat{l} \cdot \hat{s} & 0 \\ 0 & \hat{l} \cdot \hat{s} \end{pmatrix} &= \frac{\hbar}{2} \begin{pmatrix} l_x & 0 \\ 0 & l_x \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} + \frac{\hbar}{2} \begin{pmatrix} l_y & 0 \\ 0 & l_y \end{pmatrix} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \\ &+ \frac{\hbar}{2} \begin{pmatrix} l_z & 0 \\ 0 & l_z \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \\ &= \frac{\hbar}{2} \begin{pmatrix} l_z & l_x - il_y \\ l_x + il_y & -l_z \end{pmatrix} \end{aligned} \quad (4)$$

$$\begin{aligned} \begin{pmatrix} \hat{l} \cdot \hat{s} & 0 \\ 0 & \hat{l} \cdot \hat{s} \end{pmatrix} \begin{pmatrix} aY_{l,m_l,m_s} \\ bY_{l,(m_l+1),m_s} \end{pmatrix} &= \frac{\hbar}{2} \begin{pmatrix} l_z & l_x - il_y \\ l_x + il_y & -l_z \end{pmatrix} \begin{pmatrix} aY_{l,m_l,m_s} \\ bY_{l,(m_l+1),m_s} \end{pmatrix} \\ &= \frac{\hbar}{2} \begin{pmatrix} [am_l\hbar + b\sqrt{l(l+1) - (m_l+1)m_l}\hbar] Y_{l,m_l,m_s} \\ [a\sqrt{l(l+1) - m_l(m_l+1)}\hbar - b(m_l+1)\hbar] Y_{l,m_l,m_s} \end{pmatrix} \end{aligned} \quad (5)$$

要能够提出常数, 必须有

$$\begin{cases} am_l\hbar + b\sqrt{l(l+1) - (m_l+1)m_l}\hbar = a\sqrt{l(l+1) - m_l(m_l+1)}\hbar - b(m_l+1)\hbar \\ a^2 + b^2 = 1 \end{cases}$$

因此 $\{\hat{J}^2, \hat{L}^2, \hat{J}_z\}$ 的共同本征函数 $Y_{l,m_l,m_s} = aY_{l,m_l}\chi_{\frac{1}{2}} + bY_{l,(m_l+1)}\chi_{-\frac{1}{2}}$. 且其中的 a, b 可以用 l, m_l 来表示.

自旋与自旋耦合: 二电子自旋态 $\{\hat{S}, \hat{S}_z, \hat{S}^2\}$.

$$\begin{cases} \chi_{1,1}^S = \chi_{\frac{1}{2}}(s_{1z}) \cdot \chi_{\frac{1}{2}}(s_{2z}) \\ \chi_{1,-1}^S = \chi_{-\frac{1}{2}}(s_{1z}) \cdot \chi_{-\frac{1}{2}}(s_{2z}) \\ \chi_{1,0}^S = \frac{1}{\sqrt{2}} [\chi_{-\frac{1}{2}}(s_{1z}) \cdot \chi_{\frac{1}{2}}(s_{2z}) + \chi_{\frac{1}{2}}(s_{1z}) \cdot \chi_{-\frac{1}{2}}(s_{2z})] \\ \chi_{0,0}^A = \frac{1}{\sqrt{2}} [\chi_{\frac{1}{2}}(s_{1z}) \cdot \chi_{-\frac{1}{2}}(s_{2z}) - \chi_{-\frac{1}{2}}(s_{1z}) \cdot \chi_{\frac{1}{2}}(s_{2z})] \end{cases}$$

带电粒子在外场中的运动

$$\begin{cases} \hat{H} = \frac{1}{2m}(\hat{p} - \frac{q}{c}\hat{A})^2 + q\varphi \\ \vec{j} = -\frac{i\hbar}{2m}(\psi^* \cdot \nabla \psi - \psi \cdot \nabla \psi^*) - \frac{q}{mc}\vec{A}\psi^*\psi \end{cases}$$

其中

$$\begin{cases} \nabla \times \vec{A} = \vec{B} \\ \vec{E} = -\nabla\varphi - \frac{1}{c}\frac{\partial \vec{A}}{\partial t} \end{cases}$$

$$i\hbar \frac{\partial}{\partial t} |\psi\rangle = \hat{H} |\psi\rangle \implies$$

$$i\hbar \frac{\partial}{\partial t} \psi(\vec{r}, t) = \left[\frac{1}{2m} (-i\hbar \nabla - \frac{q}{c} \vec{A})^2 + q\varphi \right] \psi(\vec{r}, t)$$

用对称规范 $\vec{A} = \frac{1}{2} \vec{B} \times \vec{r} = -\frac{1}{2} B \cdot y \vec{i} + \frac{1}{2} B \cdot x \vec{j}$, 其中我们设 $\vec{B} = B \cdot \vec{k}$.
这样薛定谔方程变为

$$\begin{aligned} i\hbar \frac{\partial}{\partial t} \psi(\vec{r}, t) &= \left\{ \frac{1}{2m} \left[(p_x - \frac{q}{c} A_x)^2 + (p_y - \frac{q}{c} A_y)^2 + (p_z - \frac{q}{c} A_z)^2 \right] + q\varphi \right\} \psi(\vec{r}, t) \\ &= \left\{ \frac{1}{2m} \left[(p_x - \frac{q}{c} A_x)^2 + (p_y - \frac{q}{c} A_y)^2 + p_z^2 \right] + q\varphi \right\} \psi(\vec{r}, t) \\ &= \left\{ \frac{1}{2m} \left[\hat{p}^2 + \frac{q^2 B^2}{4c^2} (\hat{x}^2 + \hat{y}^2) + \frac{qB}{c} (\hat{p}_x \hat{y} - \hat{p}_y \hat{x}) \right] + q\varphi \right\} \psi(\vec{r}, t) \\ &= \left\{ \frac{1}{2m} \hat{p}^2 + q\varphi + \frac{q^2 B^2}{8mc^2} (\hat{x}^2 + \hat{y}^2) - \frac{qB}{2mc} \hat{l}_z \right\} \psi(\vec{r}, t) \end{aligned}$$

0 其中的顺磁项 $-\frac{qB}{2mc} \hat{l}_z$. 如果令 $\vec{\mu}_{l_z} = \frac{q}{2mc} \vec{l}_z$, 该项即为 $-\vec{\mu}_{l_z} \cdot \vec{B}$.
反磁项 $\frac{q^2 B^2}{8mc^2} (\hat{x}^2 + \hat{y}^2)$.

1. 赛曼效应: 轨道角动量和外磁场的耦合, m 量子数的显现.

氢原子: $\hat{H} = \frac{1}{2m} \hat{p}^2 + q\varphi + \frac{q^2 B^2}{8mc^2} (\hat{x}^2 + \hat{y}^2) - \frac{qB}{2mc} \hat{l}_z$. 其中 $q = -e$, $\varphi = \frac{e}{r}$.
根据原子的尺寸 $x^2 + y^2 \sim 10^{-20} \text{m}$, 而最强磁场 $B \sim 10 \text{T}$.

$$\frac{\frac{q^2 B^2}{8mc^2} (\hat{x}^2 + \hat{y}^2)}{-\frac{qB}{2mc} \hat{l}_z} \sim 10^{-5}$$

从而忽略 $\frac{q^2 B^2}{8mc^2} (\hat{x}^2 + \hat{y}^2)$.

从而 $\hat{H} = \frac{1}{2m} \hat{p}^2 + q\varphi - \frac{qB}{2mc} \hat{l}_z$.

本征态为 $\psi_{n,l,m_l} = R_{n,l}(r) Y_{l,m_l}(\theta, \varphi)$

$$\hat{H} \psi_{n,l,m_l} = E_{n,l} \psi_{n,l,m_l} + \frac{eB}{2mc} m_l \hbar, m_l = -1, 0, 1$$

2. 精细结构: 电子自旋和轨道耦合, j 量子数的显现(必须保证不加外磁场, 加外磁场会使这个耦合消失, 自旋是相对论效应)

$$\hat{H} = \frac{1}{2m} \hat{p}^2 + q\varphi + f(r) \vec{s} \cdot \vec{l} = \frac{1}{2m} \hat{p}^2 + q\varphi + \left[\frac{1}{2m_e c^2} \frac{1}{r} \frac{d}{dr} \left(-\frac{e}{r^2} \right) \right] \vec{s} \cdot \vec{l}$$

$$\begin{aligned} \hat{T} &= \frac{1}{2m_e} \hat{p}^2 = -\frac{\hbar^2}{2m_e} \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial}{\partial r} \right) + \frac{\hat{l}^2}{2m_e r^2} \\ \vec{l} \cdot \vec{s} &= \frac{\hat{j}^2 - \hat{l}^2 - \hat{s}^2}{2} \end{aligned}$$