

## Topics

- Numerical solution of ODEs
- Iterative solutions of linear systems of eqns
- Solution of over- and under-determined systems of eqns
- Discrete Fourier transforms, fast Fourier transforms

### 5.1 Initial Value Problems (IVPs)

IVP: find a function  $y(t)$  such that the ODE

$$\begin{cases} y'(t) = f(t, y(t)) & a \leq t \leq b \\ y(a) = \alpha & \text{initial condition} \end{cases}$$

is satisfied.

**Rmk.** The IVP arises in many applications,  
e.g. optimal control, machine learning.

**Ex.** Given IVP  $\begin{cases} y'(t) = \lambda(y - \frac{1}{3}) & 0 \leq t \leq b \\ y(0) = \frac{1}{3} \end{cases}$

Find the explicit form of the solution.

**Sol.** This is an autonomous ODE:

$$y(t) = \frac{dy}{dt} = \lambda(y - \frac{1}{3})$$

$$\int \frac{dy}{y - \frac{1}{3}} = \int \lambda dt$$

$$\rightarrow \ln(y - \frac{1}{3}) = \lambda t + C_1$$

$$y(t) = \frac{1}{3} + Ce^{\lambda t}$$

$$y(0) = \frac{1}{3} : C = 0$$

$$\rightarrow y(t) = \frac{1}{3}$$

### Review of basic ODE theory:

**Def.** A function  $f(t, y)$  is said to be

Lipschitz continuous in the variable  $y$

on a set  $D \subset \mathbb{R}^2$  if

$\forall (t, y_1)$  and  $(t, y_2)$ ,  $\exists L > 0$  s.t.

$$|f(t, y_1) - f(t, y_2)| \leq L|y_2 - y_1|$$

a Lipschitz' constant for  $f$

**Rmk.** Lipschitz constant for  $f$  is not unique,  
but we care about its existence.

**Ex.** Let  $f(t, y) = t|y|$  and  $\Omega = \{(t, y) \mid 1 \leq t \leq 2, -3 \leq y \leq 4\}$

$$\begin{aligned} \text{Then } |f(t_1, y_1) - f(t_2, y_2)| &= |t_1|y_1| - |t_2|y_2| \\ &= t_1|y_1| - |y_2| \\ (\text{reverse } \Delta \text{ ineq.}) \quad &\leq t_1|y_1 - y_2| \\ &\leq 2|y_1 - y_2| \end{aligned}$$

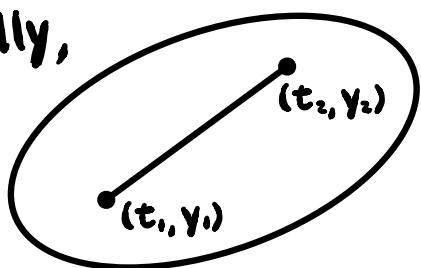
$\rightarrow f$  is Lipschitz continuous in  $y$   
with Lipschitz constant  $L = 2$ .

**Def.** A set  $D \subset \mathbb{R}^2$  is called **convex** if for all  $(y_1, y_2)$  and  $(t_1, y_1)$  in  $D$ ,

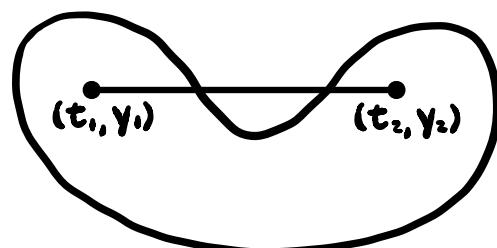
$$\begin{bmatrix} (1-\lambda)t_1 + \lambda t_2 \\ (1-\lambda)y_1 + \lambda y_2 \end{bmatrix} = [(1-\lambda)t_1 + \lambda t_2, (1-\lambda)y_1 + \lambda y_2]$$

is also in  $D$  for all  $\lambda \in [0, 1]$

Geometrically,



convex



not convex

**Rmk.** Convexity is usually used to show uniqueness of solutions.

**Thm. I** Let  $f(t, y)$  be defined on a convex set  $D \subset \mathbb{R}^2$ .  
 If there exists  $L > 0$  such that  
 $|\frac{\partial f}{\partial y}(t, y)| \leq L$  for all  $(t, y) \in D$   
 then  $f$  is Lipschitz continuous in  $y$  on  $D$   
 with Lipschitz constant  $L$ .

### Def. (Well-posedness of IVP)

The IVP

$$\begin{cases} y'(t) = f(t, y(t)) & a \leq t \leq b \\ y(a) = a \end{cases} \quad (*)$$

is well-posed if:

- ① A unique solution,  $y(t)$ , to  $(*)$  exists
- ② There exists  $\varepsilon_0 > 0$  and  $k > 0$  such that  
 for all  $\cdot \varepsilon \in (0, \varepsilon_0)$ 
  - $\cdot \delta(t)$  continuous with  $|\delta(t)| < \varepsilon$   
 for all  $t \in [a, b]$
  - $\cdot \delta_0$  with  $|\delta_0| < \varepsilon$

The perturbed problem

$$z'(t) = f(t, z(t)) + \delta(t), \quad a \leq t \leq b$$

$$z(a) = a + \delta_0$$

has a unique solution  $z(t)$  satisfying  
 $|z(t) - y(t)| < k\varepsilon$  for all  $t \in [a, b]$

- Rmk.** - ② implies that small perturbations to (\*) lead to nearby solutions
- if the given IVP is well-posed, then round-off errors do not lead to huge errors in solution  $y(t)$ .

### Thm. 2 (Well-posedness)

Let  $D = [a, b] \times \mathbb{R}$  and  $f(t, y)$  be continuous and Lipschitz continuous in  $y$  on the set  $D$ .  
overall

Then the IVP

$$\begin{cases} y'(t) = f(t, y(t)) & a \leq t \leq b \\ y(a) = a \end{cases}$$

is well-posed with

$$|z(t) - y(t)| \leq e^{L|t-a|} (1 + |b-a|\varepsilon)$$

**Rmk.** For an IVP to be well-posed, only need Lipschitz continuity in  $y$ ! (and cont. in  $t$  / convexity of  $D$ )

**Ex.** Show that the IVP

$$\begin{cases} y'(t) = y - t^2 + 1 & 0 \leq t \leq 2 \\ y(0) = 0.5 \end{cases}$$

is well-posed on  $D = [0, 2] \times \mathbb{R}$

**Sol.** Since  $f(t, y) = y - t^2 + 1$ , we have

$$\left| \frac{\partial f}{\partial y}(t, y) \right| = 1 \\ = L$$

→  $f$  is Lipschitz continuous in  $y$ .

Moreover,  $f$  is continuous on  $D = [0, 2] \times \mathbb{R}$ .

→ By Thm. 2, IVP is well-posed.

## 5.2 Euler's Method

In Calculus / Diff. Eqns, we learn to solve an ODE analytically. But in real life applications, this is not possible.

∴ We must solve numerically.

### Outline of Numerical Methods to Solve IVPs

Given an IVP, the general procedure of Euler's method or other related methods is:

- approximate the solution  $y(t)$  at mesh points  $\{t\}_{i=0}^N$  (equidistant pts on  $[a, b]$ ),
  - $t_i = a + i \cdot h$ ,  $i = 0, 1, \dots, N$ , where  
 $h = t_{i+1} - t_i = \frac{b-a}{n}$  is the step size.
- use interpolation to find  $y(t)$  for any  $t \in [a, b]$ .

## Euler's Method

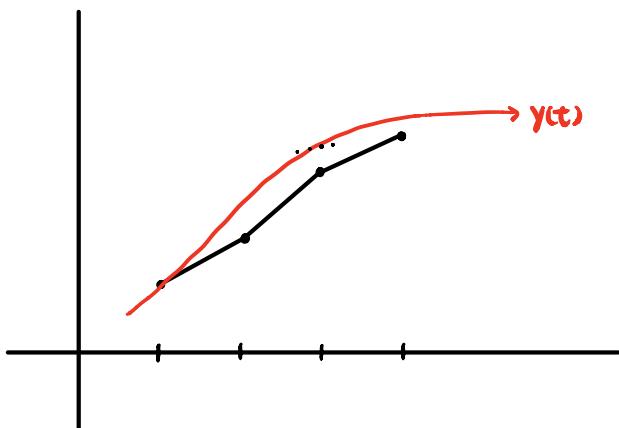
$$\left. \begin{array}{l} w_0 = a \\ w_{i+1} = w_i + h \cdot f(t_i, w_i) \end{array} \right\} \text{difference eqn}$$

Derivation: apply Taylor's Thm.

$$\begin{aligned} y(t_{i+1}) &= y(t_i) + (t_{i+1} - t_i) y'(t_i) + \frac{1}{2} h^2 y''(s_i) \\ \rightarrow y''(t_i) &= \frac{y(t_{i+1}) - y(t_i)}{h} + O(h) \\ &\approx \frac{w_{i+1} - w_i}{h} \end{aligned}$$

**Note:**  $w_0 = y(t_0)$ , but  $w_i \neq y(t_i)$ !

Geometric idea: move along tangent line  
with slope  $f(t_i, w_i)$



**Note:** error propagates along time  $t$   
(each step incurs error  $O(h)$ )

**Ex.** Use Euler's Method to solve the IVP

$$\begin{cases} y' = y - t^2 + 1 & 0 \leq t \leq 2 \\ y(0) = 0.5 \end{cases} \quad \text{with } N=10.$$

**Sol.** Step size:  $h = \frac{2-0}{10} = 0.2$

and  $w_0 = y(0) = 0.5$

By Euler's Method, we get:

$$w_{i+1} = w_i + h(w_i + t_i^2 - 1) = w_i + 0.2(w_i - (0.2i)^2 + 1)$$

Here, the actual solution is  $y(t) = (t+1)^2 - \frac{1}{2}e^t$ .

Can check error:

$$|y(0.2) - w_1| \approx 0.0293 \text{ and } |y(0.4) - w_2| \approx 0.0621$$

**Q:** Can we quantify error produced / propagated by Euler's Method?

## Lemma 5.8

If  $s, t$  are  $\oplus$  real numbers

- $\{a_i\}_{i=0}^k$  is a sequence such that  $a_0 > \frac{-t}{s}$ ,

- and  $a_{i+1} \leq (1+s) a_i + t$  for  $i = 0, 1, \dots, k-1$

Then  $a_{i+1} \leq e^{(i+1)s} (a_0 + \frac{t}{s}) - \frac{t}{s}$ .

**Pf.** For fixed integer  $i$ , we have:

$$a_{i+1} \leq (1+s)a_i + t$$

$$\leq (1+s)[(1+s)a_{i-1} + t] + t = (1+s)^2 a_{i-1} + [1 + (1+s)t]$$

$$\leq (1+s)^3 a_{i-2} + [1 + (1+s) + (1+s)^2]t$$

⋮

$$\leq (1+s)^{i+1} a_0 + [1 + (1+s) + (1+s)^2 + \dots + (1+s)^i]t$$

$\sum_{j=0}^i (1+s)^j$ : geometric series  
with ratio  $(1+s)$

**Note:**  $\sum_{j=0}^i (1+s)^j = \frac{1 - (1+s)^{i+1}}{1 - (1+s)} = \frac{1}{s} [(1+s)^{i+1} - 1]$

$$a_{i+1} \leq (1+s)^{i+1} a_0 + \frac{(1+s)^{i+1} - 1}{s} t$$

Now, using Taylor expansion for  $e^x$ :

$$e^x = 1 + x + \frac{x^2}{2} e^3 \quad 0 < g < x$$

$$\rightarrow 1 + x \leq e^x$$

$$(1+x)^{i+1} \leq e^{(i+1)x}$$

$$a_{i+1} \leq e^{(i+1)s} a_0 + e^{(i+1)s} \cdot \frac{t}{s} - \frac{t}{s}$$

$$= e^{(i+1)s} (a_0 + \frac{t}{s}) - \frac{t}{s}. \quad \square$$

### Thm. 5.9 (Error Analysis of Euler's Method)

- Suppose
- $f$  is continuous on  $D = [a, b] \times \mathbb{R}$
  - $f$  is Lipschitz continuous in  $y$  with constant  $L$
  - $|y''(t)| \leq M$  for all  $t \in [a, b]$ , and
  - $y(t)$  is unique sol. to IVP

$$\begin{cases} y'(t) = f(t, y(t)) & a \leq t \leq b \\ y(a) = \alpha \end{cases}$$

Then the sequence  $\{w_i\}_{i=0}^n$  generated by Euler's Method satisfies

$$|y(t_i) - w_i| \leq \frac{h \cdot M}{2L} (e^{L(t_i-a)} - 1)$$

**Pf.** For  $i=0$ ,  $w_0 = y(t_0) = \alpha$ .

For  $i \geq 1$ , Taylor's Thm. satisfies:

$$y(t_{i+1}) = y(t_i) + h \cdot f(t_i, y_i) + \frac{h^2}{2} y''(s_i),$$

$$t_i \leq s_i \leq t_{i+1}, \quad i=0, 1, \dots, N-1$$

By Euler's Method, we have:

$$w_{i+1} = w_i + h f(t_i, w_i)$$

Denoting  $y_i = y(t_i)$ , we have:

$$y_{i+1} - w_{i+1} = y_i - w_i + h [f(t_i, y_i) - f(t_i, w_i)] + \frac{h^2}{2} y''(s_i)$$

$$\rightarrow |y_{i+1} - w_{i+1}| \leq |y_i - w_i| + h |f(t_i, y_i) - f(t_i, w_i)| + \frac{Mh^2}{2}$$

$$\leq L |y_i - w_i|$$

$$\rightarrow |y_{i+1} - w_{i+1}| \leq (1 + hL) |y_i - w_i| + \frac{Mh^2}{2}$$

Let  $d_i = |y_i - w_i|$ ,  $s = hL$ ,  $t = \frac{Mh^2}{2}$ :

$$d_{i+1} \leq (1+s)d_i + t$$

$$\leq e^{(i+1)s} (d_0 + \frac{t}{s}) - \frac{t}{s} \text{ by Lemma 5.8}$$

**Note:**  $d_0 = 0 > -\frac{t}{s}$

$$|y_{i+1} - w_{i+1}| e^{(i+1)hL} \left[ |y_0 - w_0| + \frac{h^2 M}{2hL} \right] - \frac{hM}{2L}$$

$$\text{Since } (i+1)h = t_{i+1} - t_0 = t_{i+1} - a$$

$$a \quad a+h \quad a+2h \quad \dots$$

**Rmk.** 1. This theorem requires an upper bound  $M$  for 2nd order derivative, which is NOT always available.

Instead, consider:

$$\begin{aligned} y''(t) &= \frac{d}{dt} y'(t) = \frac{d}{dt} (f(t, y)) \\ &= \frac{\partial f}{\partial t}(t, y) + \frac{\partial f}{\partial y}(t, y) \cdot \frac{dy}{dt} \end{aligned} \quad \text{if } f$$

assuming  $f$  is differentiable.

2. Smaller step size  $h \Rightarrow$  smaller error,  $O(h)$ .
3. A similar error bound can be found for the perturbed IVP (see Thm. 5.10).

**Ex.** Find error bounds for Euler's Method with  $h=0.2$  for the IVP

$$\begin{cases} y'(t) = y(t) - t^2 + 1 & 0 \leq t \leq 2 \\ y(0) = 0.5 \end{cases} \quad (*)$$

**Sol.** Recall from previous example that sol. of  $(*)$  is:

$$y(t) = (t-1)^2 - \frac{1}{2}e^t \quad \text{and} \quad \frac{dy}{dt} = 1 \rightarrow L=1$$
$$|y''(t)| = |2 - \frac{1}{2}e^t| \leq \frac{1}{2}e^2 - 2 = M \quad t \in [0, 2]$$

The estimated error is thus

$$|y_i - w_i| \leq 0.1 \left(\frac{1}{2}e^2 - 2\right)(e^{t_i} - 1)$$

(by Thm. 5.9)