

If  $f$  is integrable on  $[0, b]$ ,  $0 < b < \infty$ , and

$f$  is of exponential order,  $|f(x)| \leq M e^{cx}$ ,

then  $f$  has a Laplace transform  $F(p)$  for  $p > c$

and  $F(p) \rightarrow 0$  as  $p \rightarrow \infty$ .

**Rmk.** In fact, if  $F(p)$  exists, then  $F(q)$  exists for all  $q > p$

and  $F(q) \rightarrow 0$  as  $q \rightarrow \infty$ .

$$L[f(x)] = \int_0^{\infty} f(x) e^{-px} dx$$

[relies on integration by parts + dominated convergence]

**Consequence:**  $p^n$ ,  $\sin(p)$  cannot be the Laplace transform of any function  $f$ .

## §50 Inverse Laplace Transform

Suppose that  $f, g$  are continuous and  $L[f] = L[g]$ , i.e.  $F(p) = G(p)$  for all  $p$  <sup>(large)</sup>.

$$\rightarrow \int_0^{\infty} f(x) e^{-px} dx = \int_0^{\infty} g(x) e^{-px} dx$$

$$\rightarrow \int_0^{\infty} (f(x) - g(x)) e^{-px} dx = 0 \quad \text{for all } p \text{ (large)}$$

$$\rightarrow \int_0^{\infty} (f(x) - g(x)) (a e^{-p_1 x} + b e^{-p_2 x}) dx = 0 \quad \text{for all } p_1, p_2 \text{ and } a, b \in \mathbb{R}$$

(not obvious)  $\rightarrow \int_0^{\infty} (f(x) - g(x)) \varphi(x) dx = 0$

$\varphi(x)$  continuous, decays sufficiently fast

$$\rightarrow f(x) = g(x)$$

i.e. a continuous  $f$  is uniquely determined by its Laplace transform

$$L[f(x)] = F(p)$$

$$f(x) = L^{-1}[F(p)]$$

$L^{-1}$  inverse Laplace transform

Properties : ①  $L$  linear  $\rightarrow L^{-1}$  linear

$$L^{-1}[a \cdot F(p) + b \cdot G(p)] = a \cdot L^{-1}[F(p)] + b \cdot L^{-1}[G(p)]$$

$$\textcircled{2} L[e^{ax} f(x)] = F(p-a)$$

$$\Rightarrow e^{ax} f(x) = L^{-1}[F(p-a)]$$

$$\textcircled{3} L[f(x-a)] = e^{-ap} F(p)$$

$$\Rightarrow f(x-a) = L^{-1}[e^{-ap} F(p)]$$

Ex. (i)  $L^{-1}\left[\frac{1}{p^2}\right] = x$

$$\Leftrightarrow L[x] = \frac{1}{p^2}$$

(ii)  $L^{-1}\left[\frac{1}{(p-a)^2}\right] = e^{ax} \cdot x$

(iii) Similarly,  $L^{-1}\left[\frac{1}{(p-a)^{n+1}}\right] = \frac{1}{n!} e^{ax} x^n$

$$\frac{n!}{p^{n+1}} = L[x^n] \quad (\text{exercise! by convention: } f(x)=0 \text{ for } x<0)$$

$\rightarrow$  we can use linearity + partial fractions to compute  $L^{-1}$  of rational functions

### Thm. Fundamental Theorem of Algebra

Every polynomial  $q(z) = b_0 + b_1 z + \dots + b_n z^n$  with  $n \geq 1$ ,  $b_0, \dots, b_n \in \mathbb{C}$  has a root, i.e. there is  $w \in \mathbb{C}$  such that  $q(w) = 0$ .

Cor.  $q(z) = c(z-z_1)^{k_1} \cdot \dots \cdot (z-z_m)^{k_m}$

where  $z_1, \dots, z_m$  are the distinct roots of  $q$ ,  $c \in \mathbb{C}$ . ( $n = \sum_{i=1}^m k_i$ )

Proof: long division

Cor. Partial Fraction Decomposition

Let  $k < n$ ,  $a_i, b_i \in \mathbb{C}$ ,  $q$  as above,

$$R(z) = \frac{a_0 + a_1 z + \dots + a_k z^k}{b_0 + b_1 z + \dots + b_n z^n} \\ = \frac{A_{11}}{z-z_1} + \frac{A_{12}}{(z-z_1)^2} + \dots + \frac{A_{1k_1}}{(z-z_1)^{k_1}}$$

$$+ \dots + \frac{A_{m1}}{z-z_m} + \dots + \frac{A_{mk_m}}{(z-z_m)^{k_m}}$$

**Rmk.** (i) If  $q(x) = b_0 + \dots + b_n x^n$  has only real coefficients  $b_i \in \mathbb{R}$ ,  $q(w) = 0$ ,  
then  $0 = \bar{0} = \overline{q(w)} = q(\bar{w})$  ( $\bar{\cdot}$  = complex conjugate)

i.e. complex roots always appear in pairs  $w, \bar{w}$ .

(ii) If also  $a_0, \dots, a_k \in \mathbb{R}$ , then we obtain a partial fraction decomposition with real coefficients as follows:

$$\begin{aligned} \frac{A}{(x-w)^k} + \frac{\bar{A}}{(x-\bar{w})^k} &= \frac{A(x-\bar{w})^k + \bar{A}(x-w)^k}{(x-w)(x-\bar{w})^k} & \begin{matrix} w = \alpha + i\beta \\ \bar{w} = \alpha - i\beta \end{matrix} \quad \alpha, \beta \in \mathbb{R} \\ &= \frac{2\operatorname{Re}(A(x-\alpha+i\beta)^k)}{(x-\alpha)^2 + \beta^2)^k} \\ &= \sum_{l \leq k} \frac{\gamma_l^k + \delta_l}{((x-\alpha)^2 + \beta^2)^l} \end{aligned}$$

**Ex.**  $R(x) = \frac{36x}{(x+3)^2(x^2+9)} = \frac{A}{x+3} + \frac{B}{(x+3)^2} + \frac{C}{x+3i} + \frac{D}{x-3i}$

$$B = R(x) \cdot (x+3)^2 - \left( \frac{A}{x-3} - \frac{C}{x+3i} - \frac{D}{x-3i} \right) (x+3)^2 \quad \text{for all } x$$

$$x = -3 \rightarrow B = \frac{36(-3)}{9+9} = -6$$

$$C = \frac{36(-3i)}{(-3i+3)^2(-3i-3i)} = \dots = \frac{1}{-i} = i$$

$$D = \dots = -i \quad (\text{so } \bar{C} = D)$$

$$x = 0 \rightarrow A = 0$$

$$\text{So } R(x) = \frac{-6}{(x+3)^2} + \frac{i}{x+3i} + \frac{-i}{x-3i}$$