

Project 2 Report

CSS322 Scientific Computing
Sirindhorn International Institute of Technology, Thammasat University
Semester 1 Academic Year 2021

Paphana Yiwsiw
6222780379
Section 3

December 5, 2021

Contents

1	Newton's method for unconstrained optimization	2
2	Naive Random Search Algorithm	2
3	Simulated Annealing Algorithm	2

1 Newton's method for unconstrained optimization

The following is the result from running newton's method for unconstrained optimization on $f(x) = \sin(x_1) - \cos(x_2)$. The value of $x^{(k)}$ and the corresponding $f(x^{(k)})$ at $k = 0, 5, 10, 15$.

- $k = 0, x^{(0)} = \begin{bmatrix} 0.5434 \\ 0.2784 \end{bmatrix}, f(x^{(0)}) = -0.4445.$
- $k = 5, x^{(5)} = \begin{bmatrix} 1.5708 \\ 0 \end{bmatrix}, f(x^{(5)}) = 0.$
- $k = 10, x^{(10)} = \begin{bmatrix} 1.5708 \\ 0 \end{bmatrix}, f(x^{(10)}) = 0.$
- $k = 15, x^{(15)} = \begin{bmatrix} 1.5708 \\ 0 \end{bmatrix}, f(x^{(15)}) = 0.$

2 Naive Random Search Algorithm

The following is the result from running naive random search algorithm on perturbed $f(x)$. The value of $x^{(k)}$ before picking candidate and corresponding value $Z(x^{(k)})$ at $k = 0, 25, 50, 75, 100$.

- $k = 0, x^{(0)} = \begin{bmatrix} 583 \\ 556 \end{bmatrix}, Z(x^{(0)}) = -0.9699.$
- $k = 25, x^{(25)} = \begin{bmatrix} 585 \\ 555 \end{bmatrix}, Z(x^{(25)}) = -1.5657.$
- $k = 50, x^{(50)} = \begin{bmatrix} 585 \\ 555 \end{bmatrix}, Z(x^{(50)}) = -1.5657.$
- $k = 75, x^{(75)} = \begin{bmatrix} 585 \\ 555 \end{bmatrix}, Z(x^{(75)}) = -1.5657.$
- $k = 100, x^{(100)} = \begin{bmatrix} 585 \\ 555 \end{bmatrix}, Z(x^{(100)}) = -1.5657.$

From observation, it seemed that it is currently stuck in a region around local optimizer, when neighborhood have larger objective function values than the current point.

3 Simulated Annealing Algorithm

The following is the result from running simulated annealing algorithm applied on perturbed $f(x)$. The value of $x^{(k)}$ before picking candidate and corresponding value $Z(x^{(k)})$ at $k = 0, 25, 50, 75, 100$.

- $k = 0, x^{(0)} = \begin{bmatrix} 40 \\ 44 \end{bmatrix}, Z(x^{(0)}) = 0.0648.$
- $k = 25, x^{(25)} = \begin{bmatrix} 37 \\ 58 \end{bmatrix}, Z(x^{(25)}) = -0.3207.$
- $k = 50, x^{(50)} = \begin{bmatrix} 32 \\ 65 \end{bmatrix}, Z(x^{(50)}) = 0.2214.$
- $k = 75, x^{(75)} = \begin{bmatrix} 40 \\ 41 \end{bmatrix}, Z(x^{(75)}) = -0.0050.$
- $k = 100, x^{(100)} = \begin{bmatrix} 47 \\ 39 \end{bmatrix}, Z(x^{(100)}) = 0.0570.$

Noted that the best-so-far point from running simulated annealing algorithm is at $x = \begin{bmatrix} 49 \\ 39 \end{bmatrix}$ and $Z(x) = -0.5004.$

MATLAB Code

Newton's Method for Unconstrained Optimization

```
1 % CSS322 Project 2: Optimization
2 % Paphana Yiwsiw 6222780379
3 % Part I: Newton's Method
4 % (Newton's method for unconstraint optimization)
5
6 function [xk,fxk] = newtons()
7     % set random seed
8     s = rng;
9     rng(100);
10    % Random initial value
11    xk = rand(2,1);
12    fxk = f(xk);
13    gfxk = gradientf(xk);
14    hfxk = hessianf(xk);
15    % Newton's method implementation
16    for k = 0:15
17        % solve linear system of equation for h(k)
18        hk = linearsolve(hfxk,-gfxk);
19        % calculate x(k+1)
20        xkp1 = xk + hk;
21        fxkp1 = f(xkp1);
22        % report value
23        if mod(k,5) == 0
24            fprintf("\nk = %d\n",k);
25            fprintf("x(k) = [ %.4f ; %.4f ]\n",xk);
26            fprintf("f(x(k)) = %.4f\n",fxk);
27            fprintf("x(k+1) = [ %.4f ; %.4f ]\n",xkp1);
28            fprintf("f(x(k+1)) = %.4f\n",fxkp1);
29        end
30        % update xk, gradient, and hessian matrix
31        xk = xkp1;
32        fxk = fxkp1;
33        hfxk = hessianf(xkp1);
34        gfxk = gradientf(xkp1);
35    end
36    % end session
37    rng(s);
38 end
39
40 % given function f(x)
41 function [fx] = f(x)
42     fx = sin(x(1))-cos(x(2));
43 end
44
45 % gradient of fx
46 function [gfx] = gradientf(x)
47     gfx = [cos(x(1));sin(x(2))];
48 end
49
50 % hessian matrix of fx
51 function [hfx] = hessianf(x)
52     hfx = [-sin(x(1)), 0; 0, cos(x(2))];
53 end
54
```

```

55 function [x] = linearsolve(A,b)
56     % PTLU factorization
57     [L,U,P] = lu(A);
58     % b_hat = P*b
59     b_hat = P*b;
60     % L*w=b_hat by forward substitution
61     w = forwarbsub(L,b_hat);
62     % U*x=w by backward substitution
63     x = backwardsub(U,w);
64 end
65
66 function w = forwarbsub(L,b)
67     [n,~] = size(b);
68     w = zeros(size(b));
69     for j = 1:n
70         w(j) = b(j)/L(j,j);
71         for k = j+1:n
72             b(k) = b(k) - (L(k,j)*w(j));
73         end
74     end
75 end
76
77 function x = backwardsub(U,b)
78     [n,~] = size(b);
79     x = zeros(size(b));
80     for j = n:-1:1
81         x(j) = b(j)/U(j,j);
82         for k = 1:j-1
83             b(k) = b(k) - (U(k,j)*x(j));
84         end
85     end
86 end

```

Naive Random Search Algorithm

```

1 % CSS322 Project 2: Optimization
2 % Paphana Yiwsiw 6222780379
3 % Part II: Naive random search
4 % Out : xk = last point
5 %       fxk = value of last point
6
7 function [xk,fxk] = naive_random()
8
9     % set random seed
10    s = rng;
11    rng(1000);
12    % create a perturbed f(x)
13    [X,Y] = meshgrid(0:0.01:2*pi,0:0.01:2*pi);
14    ZZ = rand(size(X));
15    Z = sin(X)-cos(Y) + ZZ;
16
17    % Naive random search implementation
18    % random initial starting point
19    xk = randi(629,2,1);
20    fxk = Z(xk(1),xk(2));
21    [neighborX,neighborY] = meshgrid(-2:2,-2:2);

```

```

22     for k = 0:100
23         % pick candiddade zk from neighbor of xk
24         while true
25             i = randi(24);
26             if i >= 13
27                 zk(1) = xk(1) + neighborX(i+1);
28                 zk(2) = xk(2) + neighborY(i+1);
29             else
30                 zk(1) = xk(1) + neighborX(i);
31                 zk(2) = xk(2) + neighborY(i);
32             end
33             % check if out of bound or not
34             if (zk(1) >= 1 && zk(1) <= 629) && ...
35                 (zk(2) >= 1 && zk(2) <= 629)
36                 break
37             end
38         end
39         % display candidate zk
40         fzk = Z(zk(1),zk(2));
41         % create x(k+1) for next round
42         if fzk < fxk
43             xkp1 = zk;
44         else
45             xkp1 = xk;
46         end
47         fxkp1 = Z(xkp1(1),xkp1(2));
48         % display when k = 0,25,50,75,100
49         if mod(k,25) == 0
50             fprintf("\nk = %d\n",k);
51             fprintf("x(k) = [ %d ; %d ]\nZ(x(k)) = %.4f\n",xk,fxk);
52             fprintf("z(k) = [ %d ; %d ]\nZ(z(k)) = %.4f\n",zk,fzk);
53             fprintf("x(k+1) = [ %d ; %d ]\nZ(x(k+1)) = %.4f\n",xk,fxkp1);
54             fprintf("-----\n");
55         end
56         % move to next round
57         xk = xkp1;
58         fxk = fxkp1;
59     end
60     % end session
61     rng(s);
62 end

```

Simulated Annealing Algorithm

```

1 % CSS322 Project 2: Optimization
2 % Paphana Yiwsiw 6222780379
3 % Part III (Extra Credit): Simulated annealing algorithm
4 % Out : best_state = best-so-far point
5 %       best_value = value of best-so-far point
6
7 function [best_state,best_value] = simulated_annealing()
8     % set random seed
9     s = rng;
10    rng(2000);
11
12    % create a perturbed f(x)

```

```

13 [X,Y] = meshgrid(0:0.01:2*pi,0:0.01:2*pi);
14 ZZ = rand(size(X));
15 Z = sin(X)-cos(Y) + ZZ;
16
17 % simulated annealing algorithm implementation
18 % random initial starting point
19 xk = randi(629,2,1);
20 fxk = Z(xk(1),xk(2));
21 best_state = xk;
22 best_value = fxk;
23
24 [neighborX,neighborY] = meshgrid(-2:2,-2:2);
25 for k = 0:100
26     tk = hajek_cooling(k);
27     if tk == 0
28         break
29     end
30     % pick candiddade zk from neighbor of xk
31     while true
32         i = randi(24);
33         if i >= 13
34             zk(1) = xk(1) + neighborX(i+1);
35             zk(2) = xk(2) + neighborY(i+1);
36         else
37             zk(1) = xk(1) + neighborX(i);
38             zk(2) = xk(2) + neighborY(i);
39         end
40         % check if out of bound or not
41         if (zk(1) >= 1 && zk(1) <= 629) && ...
42             (zk(2) >= 1 && zk(2) <= 629)
43             break
44         end
45     end
46     % display candidate zk
47     fzk = Z(zk(1),zk(2));
48     coin_toss = rand();
49     accpt_prob = acceptance_prob(tk,fzk,fxk);
50     % compare coin_toss with acceptance probability
51     if coin_toss < accpt_prob
52         xkp1 = zk;           % HEAD
53     else
54         xkp1 = xk;           % TAIL
55     end
56     fxkp1 = Z(xkp1(1),xkp1(2));
57     % display when k = 0,25,50,75,100
58     if mod(k,25) == 0
59         fprintf("\nk = %d\n",k);
60         fprintf("tk = %.4f\n",tk);
61         fprintf("x(k) = [ %d ; %d ]\nZ(x(k)) = %.4f\n",xk,fxk);
62         fprintf("z(k) = [ %d ; %d ]\nZ(z(k)) = %.4f\n",zk,fzk);
63         fprintf("coin toss = %.4f\n",coin_toss);
64         fprintf("acceptance prob. = %.4f\n",accpt_prob);
65         fprintf("x(k+1) = [ %d ; %d ]\nZ(x(k+1)) = %.4f\n",xkp1,fxkp1);
66         fprintf("-----\n");
67     end
68     % move to next round
69     xk = xkp1;
70     fxk = fxkp1;

```

```

71         % record best-so-far point
72         if fxk < best_value
73             best_state = xk;
74             best_value = fxk;
75         end
76     end
77
78     % end session
79     rng(s);
80
81     % display best value and best state
82     fprintf("best_state = [ %d ; %d ]\n",best_state);
83     fprintf("best_value = %.4f\n",best_value);
84 end
85
86 function [p] = acceptance_prob(tk,fzk,fxk)
87     prob = exp(-(fzk-fxk)/tk);
88     p = min([1,prob]);
89 end
90
91 function [tk] = hajek_cooling(k)
92     gamma = 2;
93     tk = gamma/log10(k+2);
94 end

```