

DS221: Data Structure and Algorithm Final.

No. _____

Date: _____

• Binary Tree •

- root \Rightarrow node on top (indegree = 0)
- child \Rightarrow indegree $\neq 0$
- level \Rightarrow distance from root to node
- height \Rightarrow level + 1
- balance factor $\Rightarrow B = H_L - H_R$ (left - right)
balanced. only when B is in $\{-1, 0, 1\}$ only
- complete \Rightarrow if and only if every level is full
- nearly complete \Rightarrow if and only if every level excepts the last is full and last level are filled from left to right (consecutively)

• expression tree : parent = operator / leaf = operand.

- create tree & operator stack (high over low)
- if operand, push to tree stack
- if operator and such has priority than the top., push in operator stack
- if not, pop 2 from tree (first be right, second be left) and pop 1 from operator and built a tree
- repeat until operator stack is empty

• Traversal

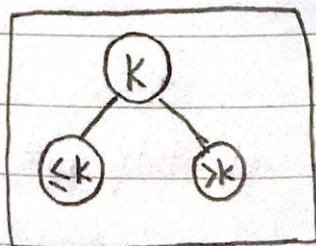
• Recursion

- Inorder : left root right
- Preorder : root left right
- Postorder : left right root

• First traversal

- BFT (Breadth) : use queue (left enq first)
(enq - print - enq)
- DFT (Depth) : use stack (right push first)
(pop - print - push)

• Binary Search Tree



• Insertion: find an appropriate spot.

• Deletion: if leaf; delete immediately

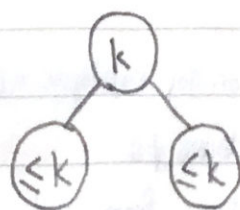
- if has 1 child; connect child to appropriate position
- if has 2 children; find maxleft then replace then reconnect.

Left subtree: less or equal

right subtree: greater.

• find smallest / largest: go all the way to left (small) / right (large)

- **Heap**
 - must be complete
 - parent must be greater than children
- Do it in array structure is easier / BFT Fashion



Parent of i is at index $\lfloor (i-1)/2 \rfloor$

left child of i is at index $(2*i)+1$

right child of i is at index $(2*i)+2$

- **Insertion**
 - insert at next position available
 - **Reheap Up!** if newNode is greater than its parent, swap. Repeat until Heap structure is received.
- **Deletion**
 - delete from the top
 - last element be replaced on the top.
 - **Reheap Down!** if replaced is less than its (maximal) child, swap. Repeat until heap structure is regained.

• Graph

- degree: number of lines incident to it
- outdegree: number of line "leaving" vertex
- indegree: number of line "coming" vertex
- path: sequence of vertex and edge start and end at different.
- cycle: path that have same endpoint as startpoint.

data can be stored in 2 type

- adjacency matrix
- adjacency list.

• Traversing a graph

- DFT: use stack
 - BFT: use queue
- } solution is not unique b/c order of data and starting point

• Spanning Tree

subtree underlying in a graph, spanning tree are not unique.
must contain no cycle.

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• Minimum spanning tree.

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• Prim-Jarhik's

- start anywhere
- pick next, by using minimum edge that adjacent to previous vertex.

• Kruskal's

- order all edges by weight from min to max
- choose minimum and check if it creates cycle or not, if yes, skip that.

* repeat until get $n-1$ edges for n vertex graph.

• Shortest path

• Dijkstra's Algorithm

- compute cumulative distance from starting point
- collect data as [from where, distance from starting point]
- if finish, backtrack using the collected data.

• AVL •

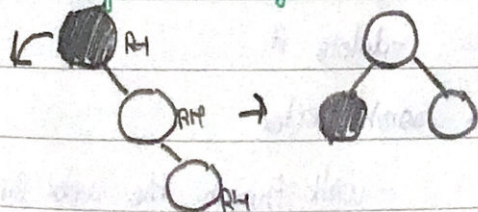
- height-balanced BST
- improving efficient by rotation until tree is balanced.

• must be BST and balanced factor of all node is between $[-1, 0, 1]$

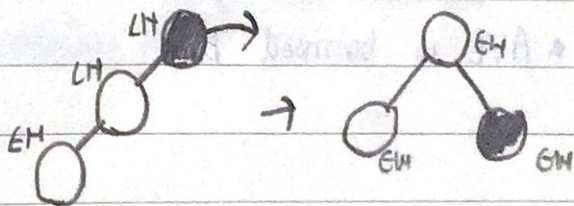
Terminology $RH \Rightarrow B < 0$, $LH \Rightarrow B > 0$, $EH \Rightarrow B = 0$

• do the normal operation but if becomes unbalanced, rotate appropriately.

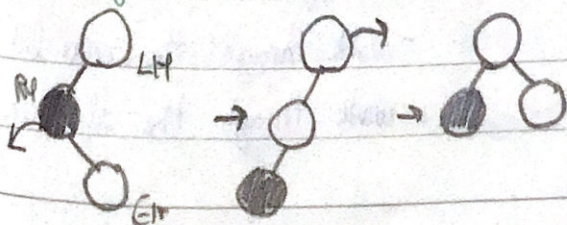
• Right of Right (\searrow)



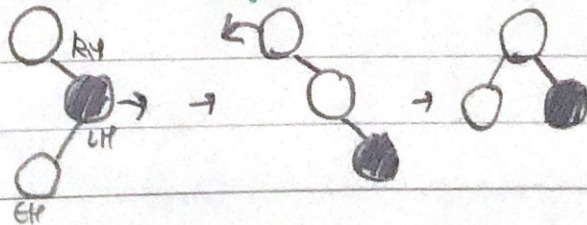
• Left of Left ($/$)



• Right of Left ($<$)



• Left of Right ($>$)



• Sometimes, deletion won't fall down in any of these, just ignore it will be fixed by itself

• Big-O Comparison •

• BST

	Balanced	Unbalanced
Insert	$O(\log n)$	$O(n)$
Delete	$O(\log n)$	$O(n)$
Search	$O(\log n)$	$O(n)$
Find Extrema	$O(\log n)$	$O(n)$

• Heap

Insert + Reheap Up	$O(\log n)$
Delete + Reheap Down	$O(\log n)$

• Graph

	of Vertex	of Edge
Insert	$O(n)$	$O(n)$
Delete	$O(n^2)$	$O(n^2)$
Search	$O(n)$	$O(n^2)$

• insert vertex at the end of list

• insert edge

- find vertex

- insert at the last

• delete vertex

- delete vertex list

- delete the entry of the vertex

• delete edge

- find edge

- delete it

• search vertex

- walk through the vertex list

• search edge

- walk through the vertex list

- walk through the edge list

• AVL

Insert	$O(\log n)$
Delete	$O(\log n)$
Search	$O(\log n)$
Find Extrema	$O(\log n)$

• AVL is balanced BST