

Graphics Term Project

Sphere Packing

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Roles

Sphere Packing Algorithm (Normal and Dense Packing)

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OpenGL Graphics/Sphere Viewing/Animations

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Introduction

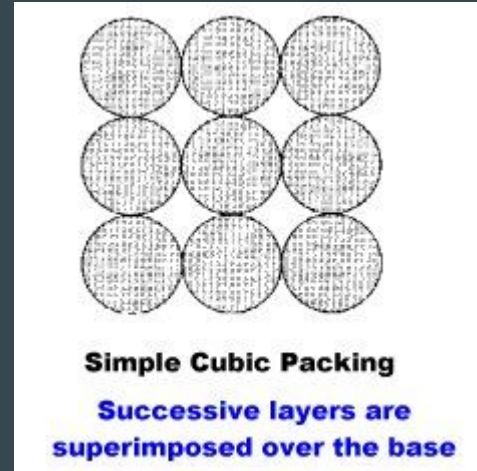
Problem Statement

Given a cubic volume and a sphere radius, determine how many spheres can fit in the cubic volume and visualize them.

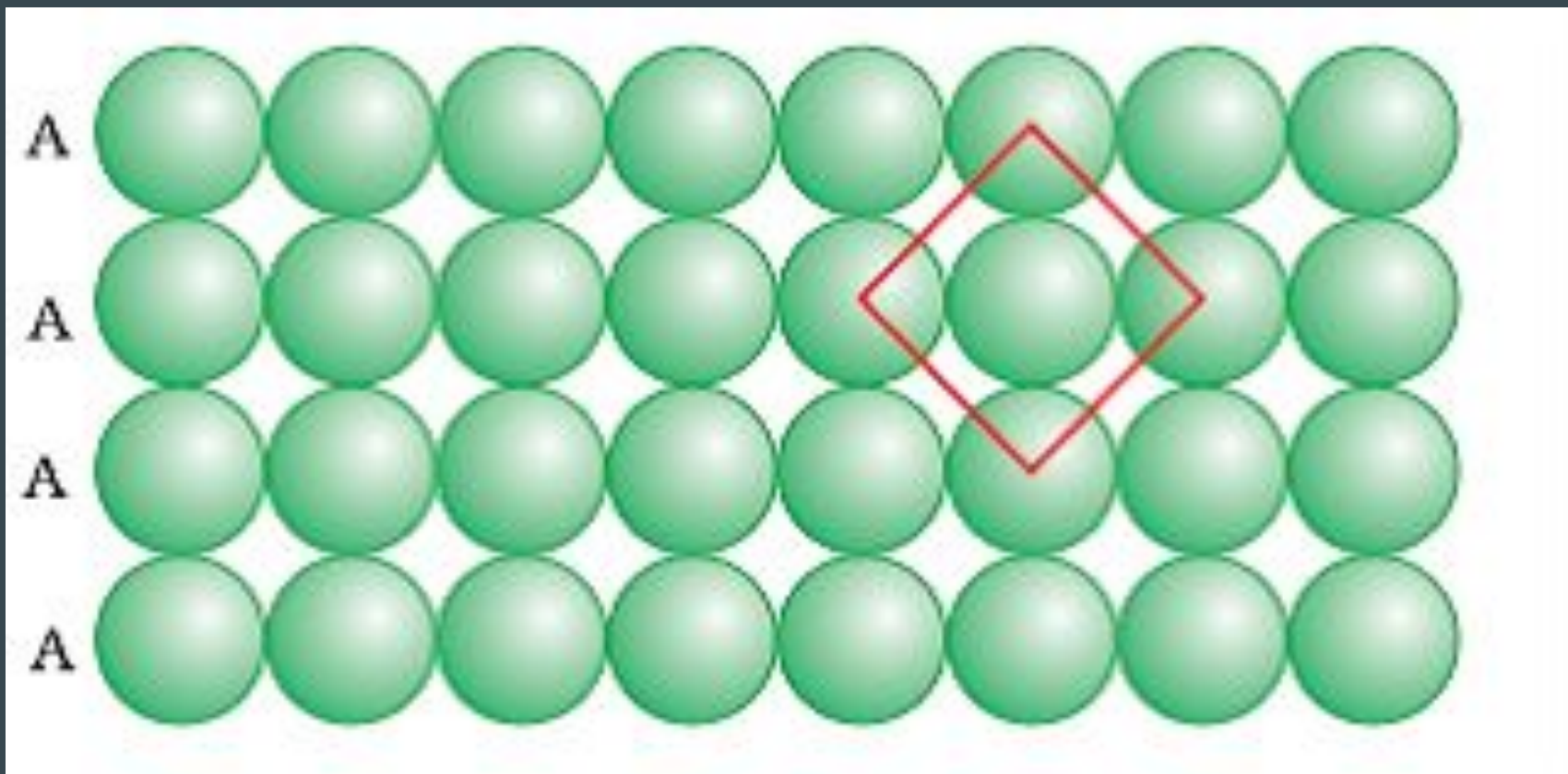
Method/Theory

Normal Packing

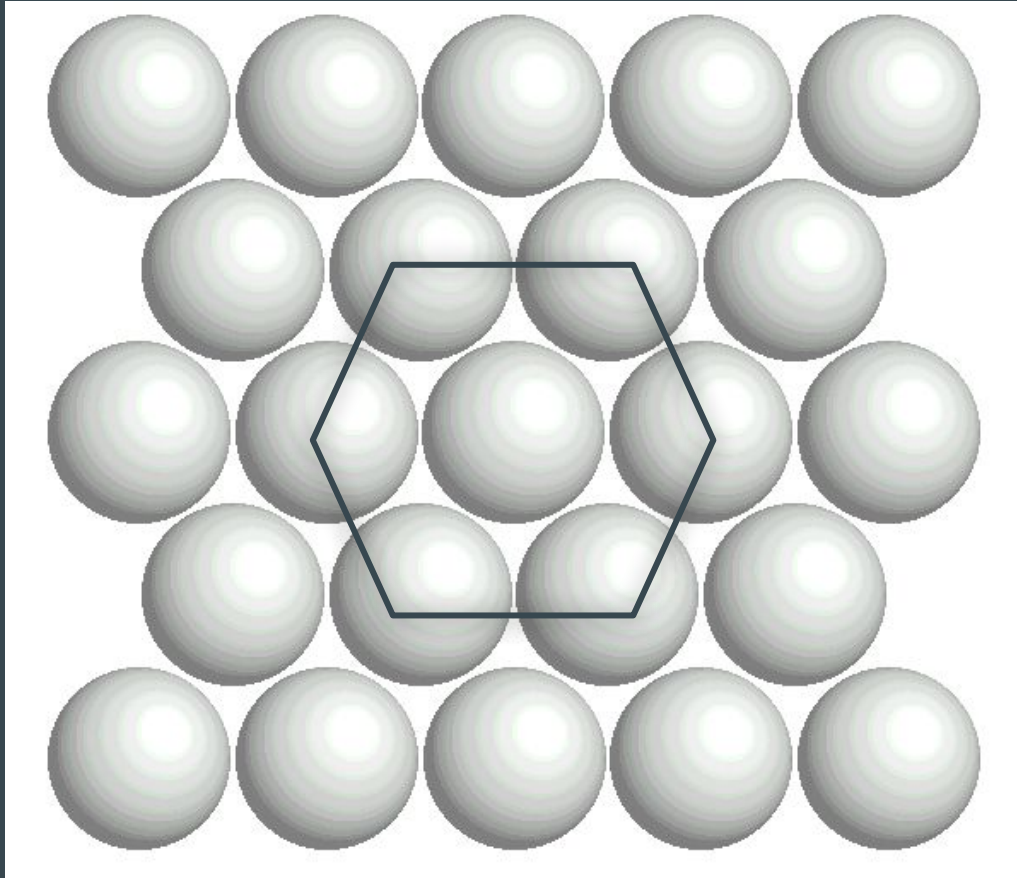
- **Packing Method:**
 - Cubic Crystalline Lattice Packing
- **Thought Processes:**
 - Visualize the most normal pack to maximize number of spheres
 - Place the spheres in straight up, down, left and right positions $2r$ away
 - Use 2D array to hold centers of each array and its radius
- **Equations for finding centers:**
 - Start with first center being at $\{r, r, r\}$ away
 - Proceed to update by $\{2r, r, r\}$ until far wall is reached (length)
 - Then update by $\{r, 2r, r\}$ once to shift row back each time the wall is reached (width)
 - Finally once the current layer is filled, update by $\{r, r, 2r\}$ to move the row upwards and begin to find centers at the new level (height)



Sphere Normal Packing



Sphere Dense Packing

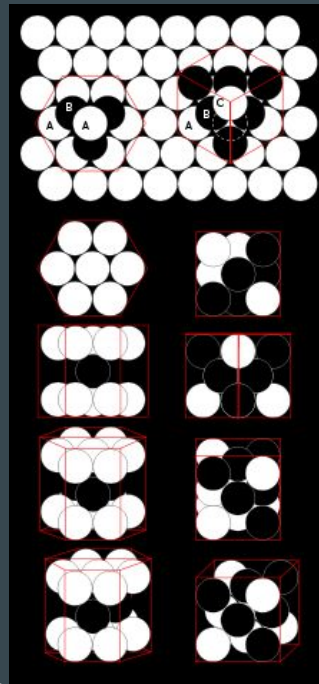


Dense Packing - Initial Thoughts/Research

- Thought Process:
 - Initially we needed to determine how many spheres can fit in the box if they are packed as densely as possible using Hexagonal Close Packing (HCP).
 - Once we find out the number of spheres we can then place them into the box and know when to stop adding spheres based on how many will fit.
- Equation:
 - $(\text{Volume of Box} / \text{Volume of a sphere}) * \text{Average Density} = \text{Number of Spheres}$
 - $\text{Average Density} = \pi / (3 * \sqrt{2}) \approx 0.74048$

Dense Packing - Finalized Thoughts/Research

- Packing Method:
 - Hexagonal Close Packing
- Thought Process:
 - We needed to then find out the distance each sphere center is from the sides of the box in terms of their radius (r).
 - We then place the center into a 2D array based on layer and center coordinates.
- Equation for each Sphere Center:
 - Even Layers:
 - Even Rows: $(2r, r, r), (4r, r, r), (6r, r, r), \dots$
 - Odd Rows: $(r, r + \sqrt{3}r, r), (3r, r + \sqrt{3}r, r), (5r, r + \sqrt{3}r, r), \dots$
 - Odd Layer:
 - Even Rows: $(r, r + (\sqrt{3}r)/3, r + (\sqrt{6}r^2)/3), (3r, r + (\sqrt{3}r)/3, r + (\sqrt{6}r^2)/3), \dots$
 - Odd Rows: $(2r, r + (4\sqrt{3}r)/3, r + (\sqrt{6}r^2)/3), (4r, r + (4\sqrt{3}r)/3, r + (\sqrt{6}r^2)/3), \dots$



OpenGL Viewing

The spheres are stored in two 2D arrays which are:

```
[numNormalPack][4] & [numDensePack][4]
```

We render the spheres first (*drawSpheres()*), then the walls (*drawWalls()*).

In *drawSpheres()*, we used the following functions from the OpenGL library, on each sphere in the array.

- *glutSolidSphere(radius, slices, stacks)*
- *glTranslatef(x, y, z)*

In *drawWalls()*, we used the following functions from the OpenGL library.

- *glBegin(GL_POLYGON)* and *glEnd()*
- *glVertex3f(x, y, z)*

Transparency Technique

- The walls are drawn transparently so the spheres can be seen more clearly.
- Multi-layer transparency in OpenGL requires careful consideration of render order
- Opaque surfaces are rendered first
- For the most realistic appearance, overlapping transparent surfaces should be rendered from front to back
 - `setWallOrder()` uses camera position to determine render order for the walls and ceiling of the box

OpenGL Animations

When the size of the box changes in `keyboard()`, we:

1. Call `translateSpheres()` to determine the new number of spheres that can fit in the new box.
 - a. Calls `getCoordsNormalPack()` and `getCoordsDensePack()`
2. Call `glutPostRedisplay()`
 - a. Calls `drawSpheres()` and `drawWalls()`

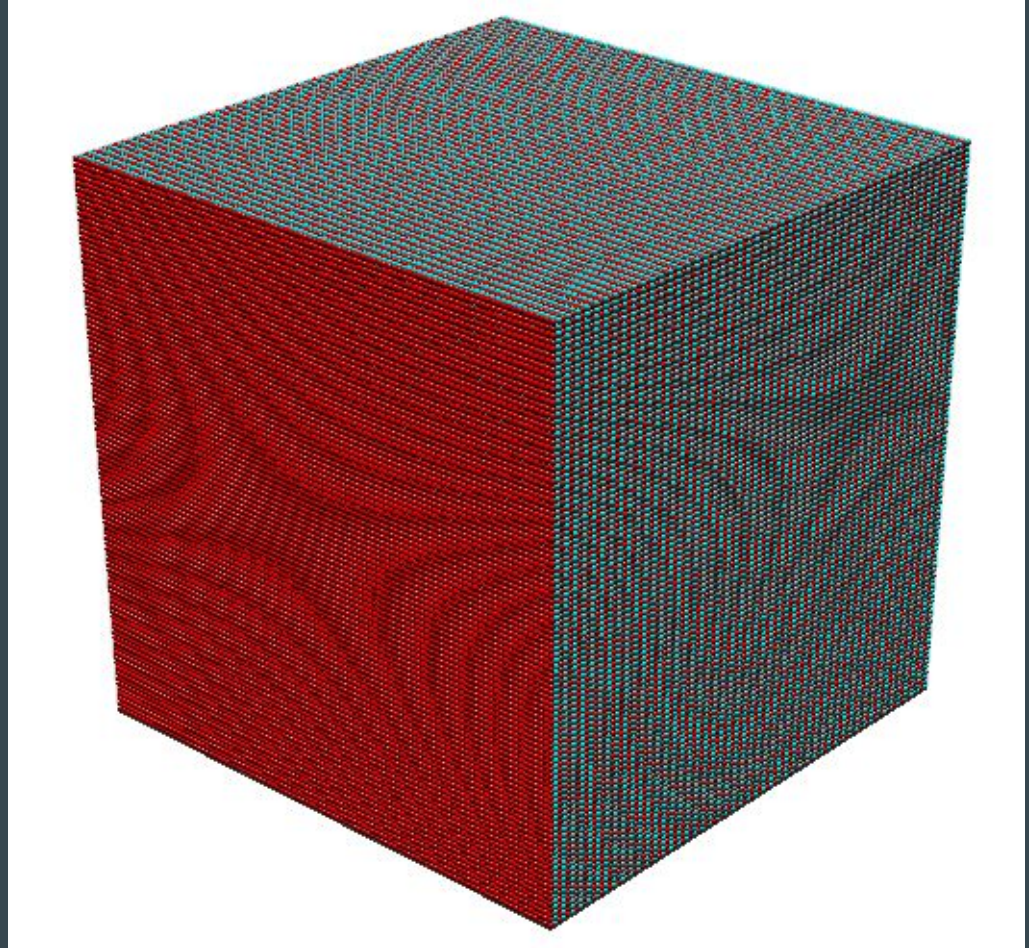
We also have included an option to switch between Normal and Dense Packing by switching `packingMode` and re-rendering.

We used Double Rendering (`GLUT_DOUBLE`) to make the animations smoother.

Results

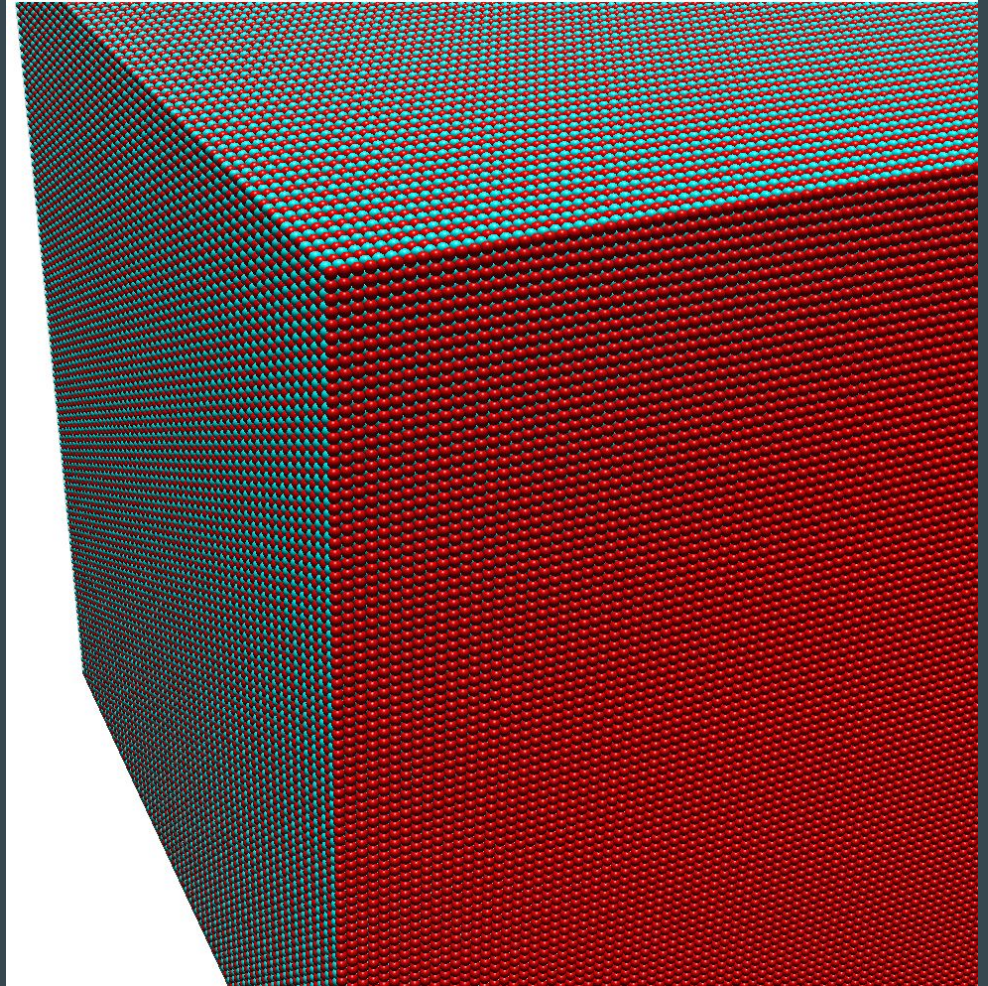
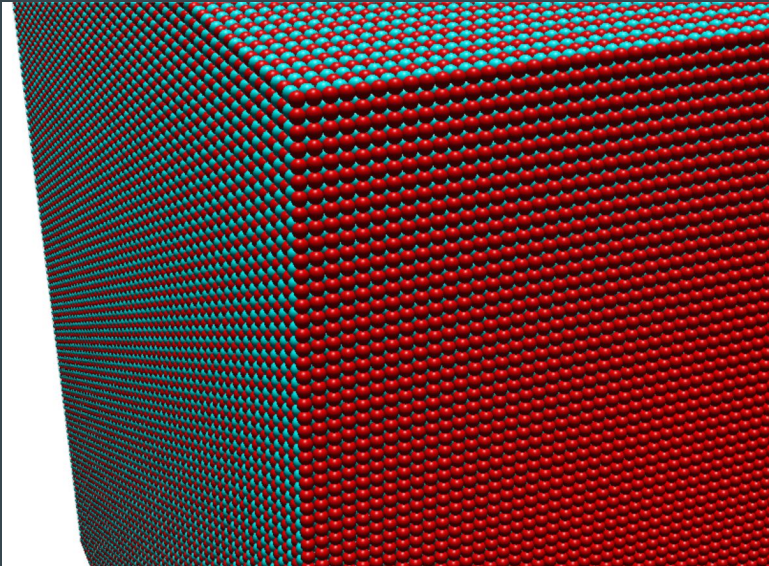
Normal Packing

- 200 x 200 x 200 box
- Sphere Radius = 1
- 1 million spheres



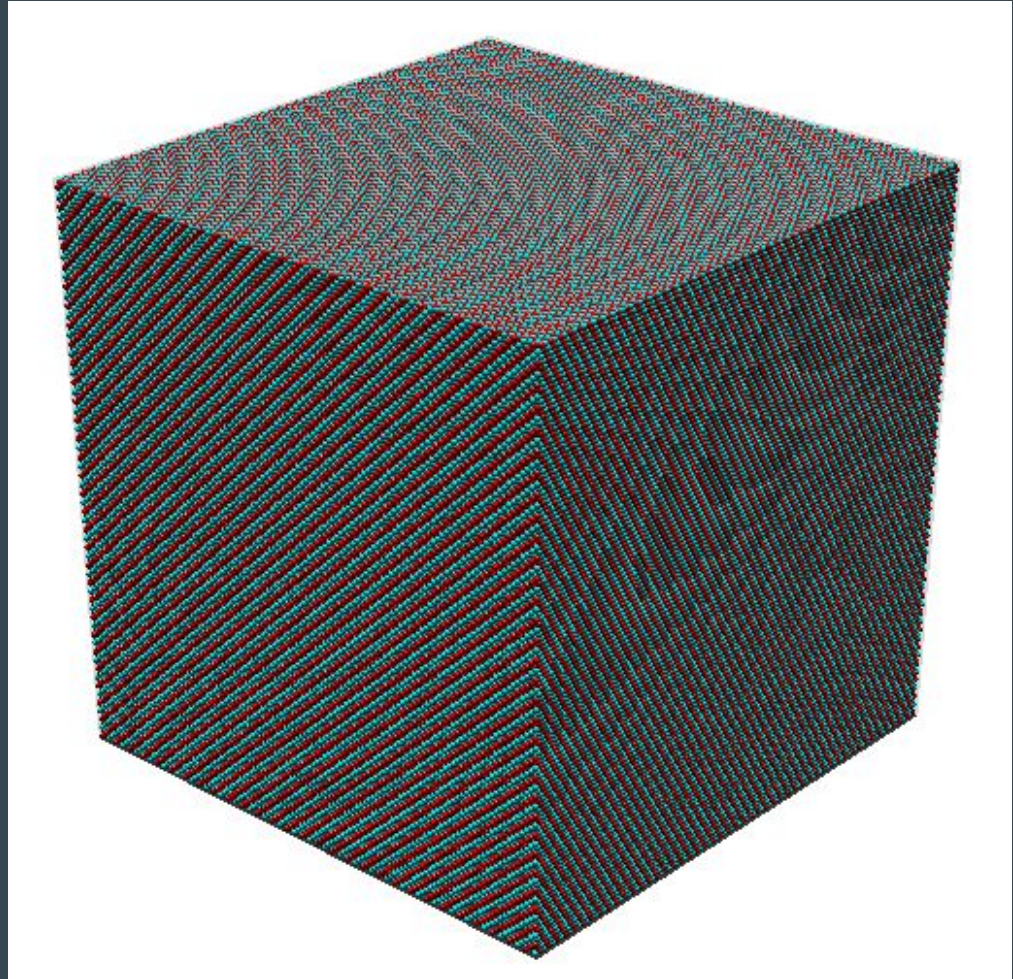
Normal Packing

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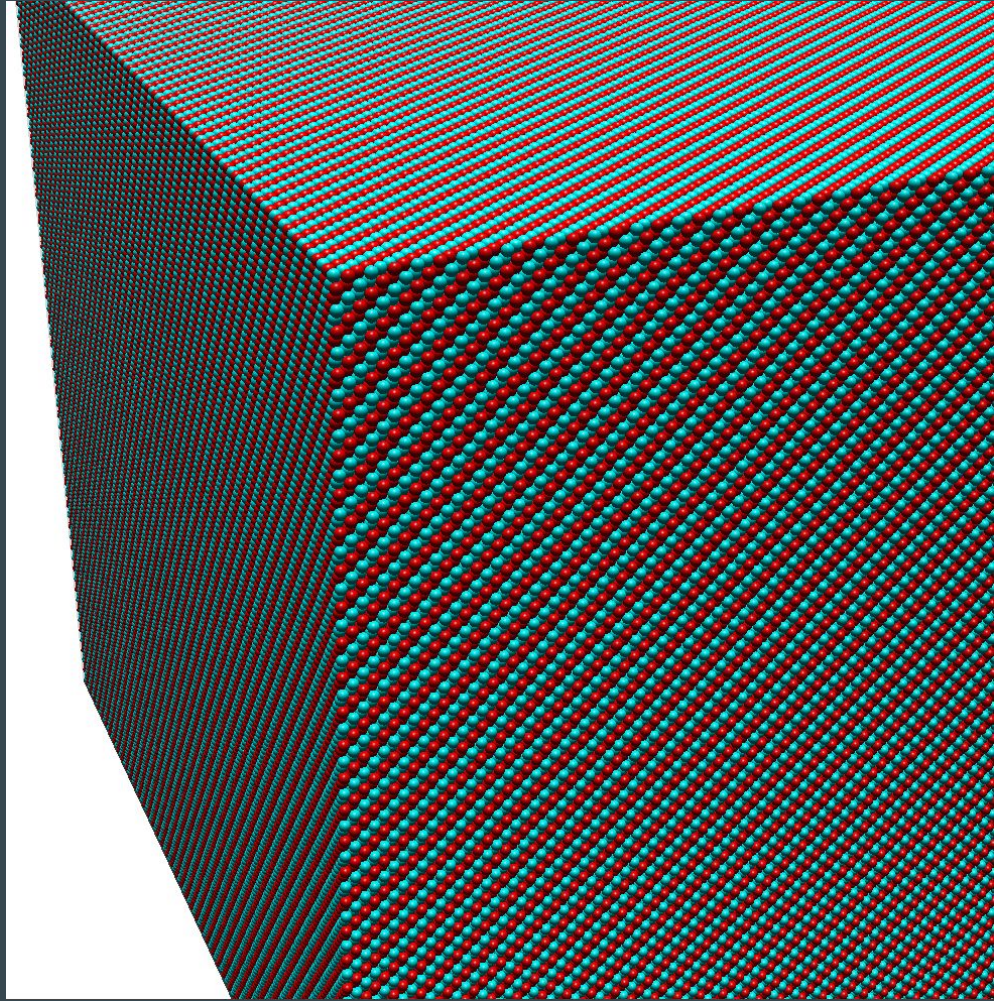
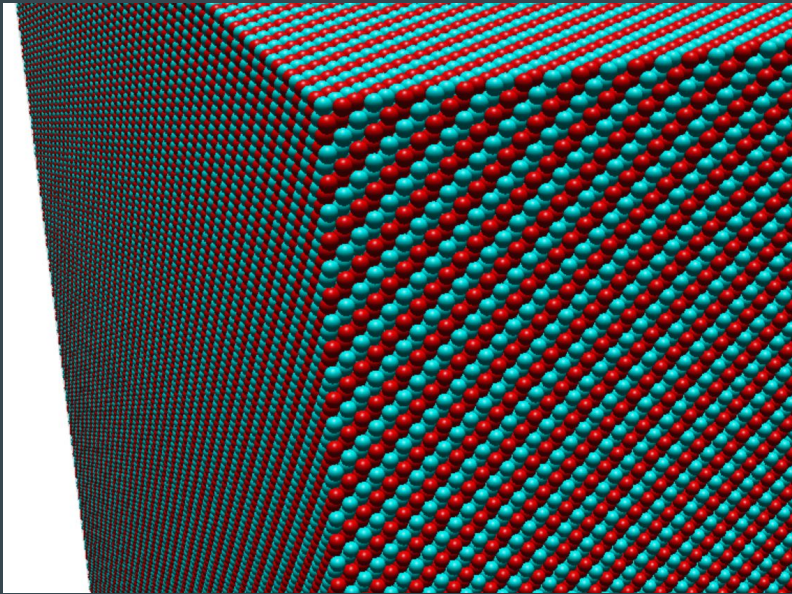
Dense Packing

- 200 x 200 x 200 box
- Sphere Radius = 1
- 1,395,985 spheres



Dense Packing

- 200 x 200 x 200 box
- Sphere Radius = 1
- 1,395,985 spheres



OpenGL Viewing Controls

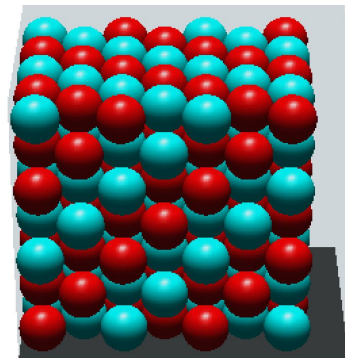
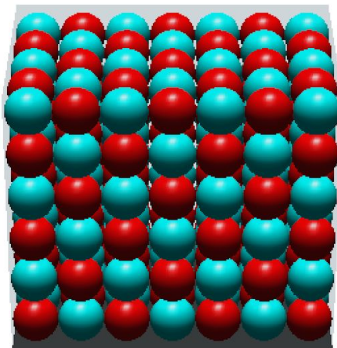
Controls:

x/X	-----	decrease/increase box length
y/Y	-----	decrease/increase box height
z/Z	-----	decrease/increase box depth
-/+	-----	zoom out/in
p	-----	switch pack normal/dense
i	-----	reprint instructions
ESC	-----	close
Arrow Keys	-----	move camera view

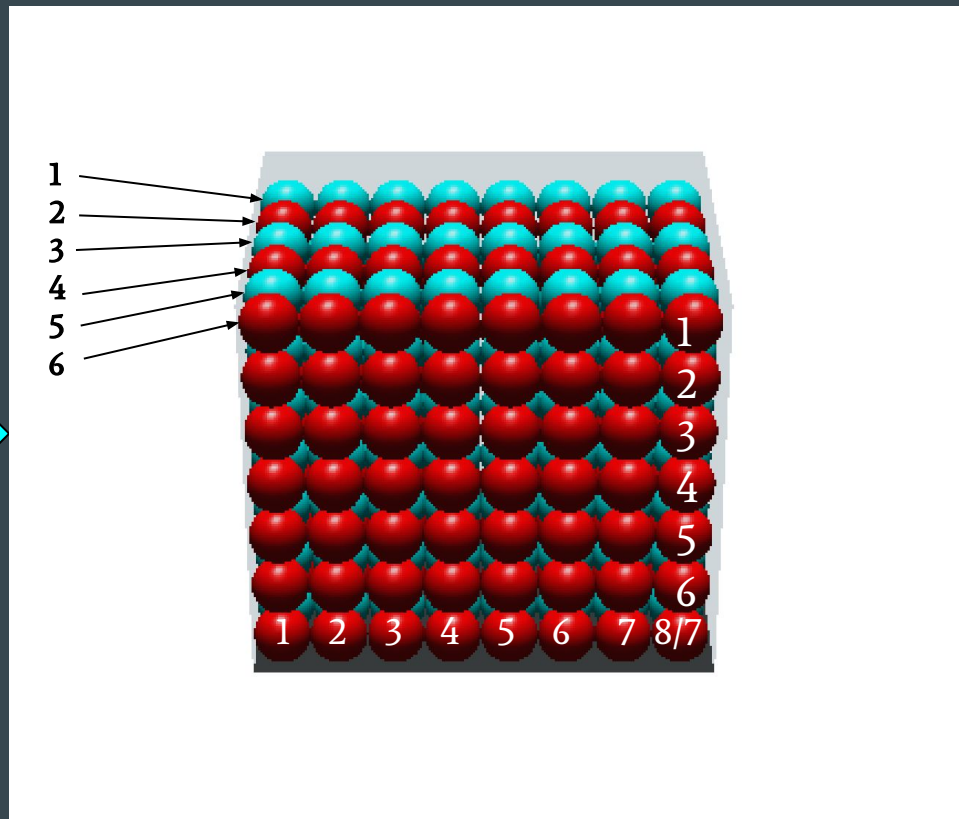
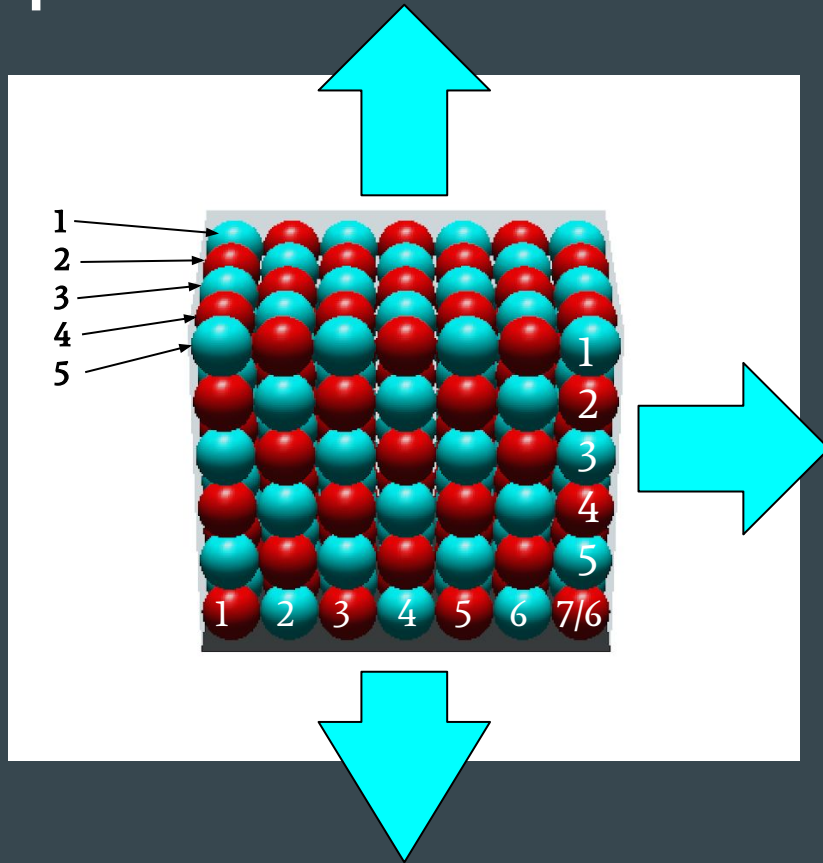
OpenGL Viewing

```
Enter the length of the Box in Inches: 10  
Enter the width of the Box in Inches: 14  
Enter the height of the Box in Inches: 12
```

```
Enter the radius of the Spheres in Inches: 1  
Normal packing real yields: 210 Spheres  
Dense packing real yields: 221 Spheres  
Dense Pack has 11 more.  
You should use Dense Pack!
```



OpenGL Animations



Conclusion

Final Thoughts

Overall, we were able to complete:

- Normal sphere packing algorithm, returning the number of spheres that can fit and their centers
- Hexagonal dense sphere packing algorithm, returning the number of spheres that can fit and their centers
- Visualization of the spheres when using both normal and dense packing
- Animation of expanding box and re-calculation of packing
- Switch visualization between dense and normal packing

References

- Close Sphere Packing - https://en.wikipedia.org/wiki/Close-packing_of_equal_spheres
- GLUT Functions - <https://www.opengl.org/resources/libraries/glut/spec3/spec3.html>
- GL Functions - <https://www.khronos.org/registry/OpenGL-Refpages/gl2.1/xhtml/>

Demo
