

BLOCK PRECONDITIONERS FOR AN INCOMPRESSIBLE MAGNETOHYDRODYNAMICS PROBLEM

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Problem background

- MHD models electrically conductive fluids (such as liquid metals, plasma, salt water, etc) in an electric field
- Applications: electromagnetic pumping, aluminium electrolysis, the Earth's molten core and solar flares
- MHD models couple electromagnetism (governed by Maxwell's equations) and fluid dynamics (governed by the Navier-Stokes equations)
- Movement of the conductive material that induces and modifies any existing electromagnetic field
- Magnetic and electric fields generate a mechanical force on the fluid

Steady-state Navier-Stokes equations

Incompressible Navier-Stokes Equations:

$$\begin{aligned} -\nu \Delta u + (u \cdot \nabla)u + \nabla p &= f && \text{in } \Omega, \\ \nabla \cdot u &= 0 && \text{in } \Omega, \\ u &= u_D && \text{on } \partial\Omega \end{aligned}$$

where u is the fluids velocity; p is the fluids pressure; f is the body force acting on the fluid and ν the kinematic viscosity.

Steady-state Navier-Stokes equations

Corresponding linear system:

$$\mathcal{K}_{\text{NS}} = \begin{pmatrix} A + O & B^T \\ B & 0 \end{pmatrix} \begin{pmatrix} u \\ p \end{pmatrix} = \begin{pmatrix} f \\ 0 \end{pmatrix}$$

where $A \in \mathbb{R}^{n_u \times n_u}$ is the discrete Laplacian; $O \in \mathbb{R}^{n_u \times n_u}$ is the convection operator and $B \in \mathbb{R}^{m_u \times n_u}$ is a discrete divergence operator with full row rank.

Note: due to convection term the linear system is non-symmetric

For an extensive discussion of preconditioners we refer to [Elman, Silvester and Wathen 2005/2014](#).

Time-Harmonic Maxwell in mixed form

Maxwell operator in mixed form:

$$\nabla \times (\nabla \times b) - k^2 b + \nabla r = g \quad \text{in } \Omega,$$

$$\nabla \cdot b = 0 \quad \text{in } \Omega,$$

$$b \times n = b_D \quad \text{on } \partial\Omega,$$

$$r = 0 \quad \text{on } \partial\Omega,$$

where b is the magnetic vector field, r is the scalar multiplier and k is the wave number.

Note: for the MHD system $k = 0$

Discretised and linearised Incompressible Navier-Stokes system

$$\begin{pmatrix} M - k^2 X & D^T \\ D & 0 \end{pmatrix} \begin{pmatrix} b \\ r \end{pmatrix} = \begin{pmatrix} g \\ 0 \end{pmatrix},$$

where $M \in \mathbb{R}^{n_b \times n_b}$ is the discrete curl-curl operator; $X \in \mathbb{R}^{n_b \times n_b}$ the discrete mass matrix; $D \in \mathbb{R}^{m_b \times n_b}$ the discrete divergence operator

Note: M is semidefinite with nullity m_b .

A significant amount of literature on time-harmonic Maxwell: notably for us, work of [Hiptmair 1999](#) and [Hiptmair & Xu 2007](#) for solving shifted curl-curl equations in a fully scalable fashion.

MHD model: coupled Navier-Stokes and Maxwell's equations

$$\begin{aligned}
 -\nu \Delta u + (u \cdot \nabla)u + \nabla p - \kappa (\nabla \times b) \times b &= f && \text{in } \Omega, \\
 \nabla \cdot u &= 0 && \text{in } \Omega, \\
 \kappa \nu_m \nabla \times (\nabla \times b) + \nabla r - \kappa \nabla \times (u \times b) &= g && \text{in } \Omega, \\
 \nabla \cdot b &= 0 && \text{in } \Omega,
 \end{aligned}$$

with appropriate boundary conditions.

- $(\nabla \times b) \times b$: Lorentz force accelerates the fluid particles in the direction normal to the electric and magnetic fields.
- $\nabla \times (u \times b)$: electromotive force modifying the magnetic field

Discretisation

- Finite element discretisation based on the formulation in Schötzau 2004
- Fluid variables: lowest order Taylor-Hood ($\mathcal{P}_2/\mathcal{P}_1$)
- Magnetic variables: mixed Nédélec element approximation
- Nédélec elements capture solutions correctly on non-convex domains

Discretised and linearised MHD model:

$$\begin{pmatrix} A + O(u) & B^T & C(b)^T & 0 \\ B & 0 & 0 & 0 \\ -C(b) & 0 & M & D^T \\ 0 & 0 & D & 0 \end{pmatrix} \begin{pmatrix} \delta u \\ \delta p \\ \delta b \\ \delta r \end{pmatrix} = \begin{pmatrix} r_u \\ r_p \\ r_b \\ r_r \end{pmatrix},$$

with

$$\begin{aligned} r_u &= f - Au - O(u)u - C(b)^T b - B^T p, \\ r_p &= -Bu, \\ r_b &= g - Mu + C(b)b - D^T r, \\ r_r &= -Db. \end{aligned}$$

A : discrete Laplacian operator, O : discrete convection operator,
 B : discrete divergence operator, M : discrete curl-curl operator,
 C : coupling terms, D : discrete divergence operator.

Decoupling schemes

Magnetic Decoupling (MD):

$$\mathcal{K}_{\text{MD}} = \left(\begin{array}{cc|cc} A + O(u) & B^T & 0 & 0 \\ B & 0 & 0 & 0 \\ \hline 0 & 0 & M & D^T \\ 0 & 0 & D & 0 \end{array} \right)$$

Complete Decoupling (CD):

$$\mathcal{K}_{\text{CD}} = \left(\begin{array}{cc|cc} A & B^T & 0 & 0 \\ B & 0 & 0 & 0 \\ \hline 0 & 0 & M & D^T \\ 0 & 0 & D & 0 \end{array} \right)$$

Linear solver and Preconditioning

Consider

$$Ax = b,$$

to iteratively solve:

$$\text{find } x_k \in x_0 + \text{span}\{r_0, Ar_0, \dots, A^{k-1}r_0\}$$

where $r_0 = b - Ax_0$ and x_0 is the initial guess.

Key for success: preconditioning

1. the preconditioner P approximates A
2. P easy to solve for than A

Want eigenvalues of $P^{-1}A$ to be clusters

Ideal preconditioning

Non-singular (1,1) block

$$\mathcal{K} = \begin{pmatrix} F & B^T \\ B & 0 \end{pmatrix}; \quad \mathcal{P} = \begin{pmatrix} F & B^T \\ 0 & BF^{-1}B^T \end{pmatrix}$$

Murphy, Golub & Wathen 2000 showed exactly two eigenvalues: ± 1

Singular (1,1) block

$$\mathcal{K} = \begin{pmatrix} F & B^T \\ B & 0 \end{pmatrix}; \quad \mathcal{P} = \begin{pmatrix} F + B^T W^{-1} B & 0 \\ 0 & W \end{pmatrix}, \text{ where } W \text{ is SPD}$$

Greif & Schötzau 2006 showed exactly two eigenvalues: ± 1

Navier-Stokes subproblem

$$\mathcal{K}_{\text{NS}} = \begin{pmatrix} F & B^T \\ B & 0 \end{pmatrix}$$

where $F = A + O$ is the discrete convection diffusion operator. Shown in Elman, Silvester & Wathen 2005/2014 that

$$\mathcal{P}_{\text{NS}} = \begin{pmatrix} F & B^T \\ 0 & S \end{pmatrix}, \quad S = A_p F_p^{-1} Q_p$$

is a good approximation to the Schur complement preconditioner.

A_p : pressure space Laplacian, F_p : pressure space convection-diffusion operator, Q_p : pressure space mass matrix

Maxwell subproblem

$$\mathcal{K}_{\text{NS}} = \begin{pmatrix} M & B^T \\ B & 0 \end{pmatrix}$$

Note: M is highly rank deficient.

Greif & Schötzau 2007 shows that L (scalar Laplacian) is the appropriate choice for W

$$\mathcal{P}_{\text{iM}} = \begin{pmatrix} M + B^T L^{-1} B & 0 \\ 0 & L \end{pmatrix}$$

Practical preconditioner:

$$\mathcal{P}_{\text{M}} = \begin{pmatrix} M + X & 0 \\ 0 & L \end{pmatrix}$$

where X vector mass matrix is spectrally equivalent to $B^T L^{-1} B$

MHD problem

Combining the Navier-Stokes and Maxwell preconditioners

$$\mathcal{P}_{\text{MH}} = \begin{pmatrix} F & B^T & C^T & 0 \\ 0 & -S & 0 & 0 \\ -C & 0 & M + X & 0 \\ 0 & 0 & 0 & L \end{pmatrix}$$

Note: \mathcal{P}_{MH} remains impractical due to coupling terms. Dual Schur complement approximation for velocity-magnetic unknowns

$$\mathcal{P}_{\text{schurMH}} = \begin{pmatrix} F + N_C & B^T & 0 & 0 \\ 0 & -S & 0 & 0 \\ 0 & 0 & M + X & 0 \\ 0 & 0 & 0 & L \end{pmatrix}$$

where $N_C = C^T(M + X)^{-1}C$

Approximation for N_C

Summary of decoupling scheme preconditioners

Iteration scheme	Coefficient matrix	Preconditioner
(MD)	$\left(\begin{array}{cc cc} F & B^T & 0 & 0 \\ B & 0 & 0 & 0 \\ \hline 0 & 0 & M & D^T \\ 0 & 0 & D & 0 \end{array} \right)$	$\left(\begin{array}{cc cc} F & B^T & 0 & 0 \\ 0 & -S & 0 & 0 \\ \hline 0 & 0 & M + X & 0 \\ 0 & 0 & 0 & L \end{array} \right)$
(CD)	$\left(\begin{array}{cc cc} A & B^T & 0 & 0 \\ B & 0 & 0 & 0 \\ \hline 0 & 0 & M & D^T \\ 0 & 0 & D & 0 \end{array} \right)$	$\left(\begin{array}{cc cc} A & 0 & 0 & 0 \\ 0 & \frac{1}{\nu} Q_p & 0 & 0 \\ \hline 0 & 0 & M + X & 0 \\ 0 & 0 & 0 & L \end{array} \right)$

TABLE: Summary of coefficient matrices and corresponding preconditioners for each the decoupling scheme

Numerical software used

- Finite element software **FEniCS**: core libraries are the problem-solving interface **DOLFIN**, the compiler for finite element variational forms **FFC**, the finite element tabulator **FIAT** for creating finite element function spaces, the just-in-time compiler **Instant**, the code generator **UFC** and the form language **UFL**.
- Linear algebra software: **HYPRE** as a multigrid solver and the sparse direct solvers **UMFPACK**, **PASTIX**, **SuperLU** and **MUMPS**

Future work:

- Scalable inner solvers
- Release code on a public repository
- Parallelisation of the code
- Robustness with respect to kinematic viscosity
- Other non-linear solvers
- Different mixed finite element discretisations