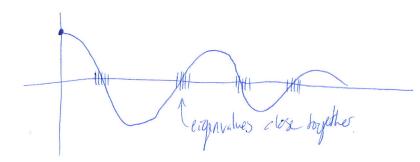
$$\Gamma_{k} = P_{k}(A) \Gamma_{0}$$
 $P_{k}(0) = 0$

GARES, basiz form:

$$\chi_n = \chi_o + Q_n Z_n$$



lest + right preconditioning

· Notice that the corresponding preconditional Krylor subspaces are a

```
M 3 nxn
  M should be much easier to hvert than A, but $11 M=A-1
  in a certain wry ... (clustering or less important, good condition.
  humber of M'AS
Note: instead of a matrix -vector product w/ A originally, now we have:
         mat-rec prod
      plus need to solve MZn=5k
       mat-vee prod w/ M-A
              Lagiveny, need M-Ay = Z
                  * Compute s=Ay
Also have split precorditioning: M. AMz (Mzx) = M. b
       M=M,Mz eg: M3SPD

M=FFT (Choleshy)

in Sactored form
 Split preconditioning + CG:
                               recall (6: Lanczos
                                         IKMZ = Pe,
      Ax = b
                                         \chi_n = \chi_0 + Q_n Z
     A 3 SPD; need MSPD
 PCG: M-A is not even symmetric
        but if M3 SPD: M=QAQT,
                           M/2 = Q N/2QT M/2M/2 Q N/2N/2QT = ONQT=M
```

(M-4AM-4) (M/2) = F-12b

2

if M=FFT xTFTAF'x = (F'x)TA(F'x) = yTAy > ().

if A 3 not symmetriz

Ax = b

ATAx = ATB

then ATA 3 SPD if A 3 nonsingular

CGLS

but if the condition number of A is large - the condition number of ATA squares it

ATA -> apply Cb only if A 3 well-conditioned L> A: non symmetriz

Preconditioners:

we can't M' & A' but much easier to invert

Simple precorditares:

M=I or &I: Richardson

M= drag(A) : Sacobi

M= tril(A) : Gauss Seidel

Incomplete LU:

A= LU

Static pattern ILU ? And sparse L. U dynamic pattern ILU ? S.t. A=LU in some places, A≈LU in some places, A≠LU in places we don't care about...

A= LUS

motead L= () U:

Impose: A=LU only for {(i,i)} for which Aij 70

4