

Bi-orthogonalization

Symmetric:

- short recurrences
 - optimality
- $\begin{matrix} & \swarrow & \searrow \\ \text{CG (SPD)} & & \text{MINRES (Symm)} \\ & \searrow & \swarrow \\ & \text{SYMMLQ} & \end{matrix}$

non-symmetric

- long recurrences
 - optimality
 - longish recurrences
 - quasi-optimality
 - short recurrences
 - no optimality
- $\left. \begin{matrix} \text{long recurrences} \\ \text{optimality} \end{matrix} \right\} \text{GMRES}$
 $\left. \begin{matrix} \text{longish recurrences} \\ \text{quasi-optimality} \end{matrix} \right\} \text{Restarted GMRES}$
 $\left. \begin{matrix} \text{short recurrences} \\ \text{no optimality} \end{matrix} \right\} \text{bi-orthogonalization}$

$$AV_k = V_{k+1} T_{k+1,k}$$

$$W_k^T (b - Ax_k) = 0$$

$$W_i^T V_j = 0$$

 $i \neq j$ bi-orthogonal.

$$W_k^T AV_k y = W_k^T b$$

$$T_k y = \|r\|_2 e_1 \quad - \text{Bi-Lanczos, two-sided Lanczos}$$

Suppose we have two Krylov subspaces

$$K_m(A, v_1) = \text{span}\{v_1, Av_1, \dots, A^{m-1}v_1\}$$

$$K_m(A^T, w_1) = \text{span}\{w_1, A^T w_1, \dots, (A^T)^{m-1} w_1\}$$

$$\text{recall: } Q_k^T A Q_k = T_k$$

$$A(q_1, \dots) = (q_1, q_2, \dots) \begin{pmatrix} \alpha_1 & \beta_2 & & \\ \beta_2 & \alpha_2 & & \\ & & \ddots & \\ & & & \alpha_k \end{pmatrix}$$

and we forced orthogonality
 \hookrightarrow find $q_j, \{\alpha_j\}, \{\beta_j\}$ using
 orthogonality

Now, use bi-orthogonality to find elements of $T_k, \{v_j\}, \{w_j\}$

Core of bi-lanczos

For $j=1:m$

$$\alpha_j = (AV_j, \omega_j)$$

$$\hat{v}_{j+1} = AV_j - \alpha_j v_j - \beta_j v_{j-1}$$

$$\hat{\omega}_{j+1} = A^T \omega_j - \alpha_j \omega_j - \delta_j \omega_{j-1}$$

end

where $(\omega_j, v_i) = \delta_{ij}$

$$AV_m = V_m T_m + \sum_{m+1} v_{m+1} e_m^T$$

$$A^T W_m = W_m T_m^T + \beta_{m+1} \omega_{m+1} e_m^T$$

$$W_m^T AV_m = T_m$$

Bi-CG:

$$x_m = x_0 + V_m T_m^{-1} (p e_1) \quad p = \|r_0\|_2$$

$$T_m = L_m U_m$$

define

$$P_m = V_m U_m^{-1}$$

$$P_m^* = W_m L_m^{-T}$$

What is

$$\begin{aligned} (P_m^*)^T A P_m &= D_m^* \\ &= L_m^{-1} \underbrace{W_m^T A V_m}_{T_m} U_m^{-1} \\ &= L_m^{-1} T_m U_m^{-1} \\ &= L_m^{-1} L_m U_m U_m^{-1} \\ &= I \end{aligned}$$

\uparrow
short recurrences

recall for CG: A conjugacy

$$P_j^T A P_i = \begin{cases} 0 & i \neq j \\ 1 & i = j \end{cases}$$

$$\begin{aligned} P_k^T A P_k &= D_k \\ &= I \end{aligned}$$

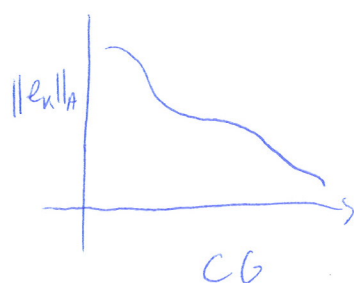
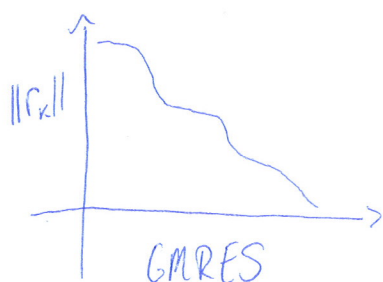
QMR:

$$\min \|V_m^T(p_{e_1} - T_k y)\|$$

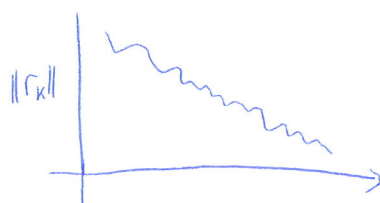
↳ pretend V_m are orthogonal ($\{V_m\}$ from Lanczos)

$$\min_y \|p_{e_1} - T_k y\|_2$$

Convergence behavior

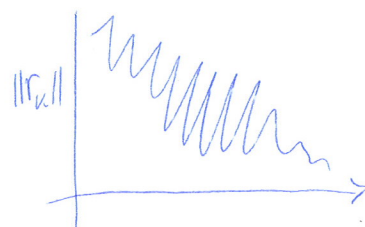


but



erratic convergence
behavior

BiCG



BiCG-STAB: smoother /
gentler oscillations

BiCG + QMR do require A^T

↳ Transpose free variants: CGS

BiCG-stab
TFQMR

Transpose Free versions are based on the observation that many of the parameters can be expressed as, say

$$\alpha_j = (\phi_j(A)r_0, \phi_j(A^T)r_0^*) = (\phi_j^2(A)r_0, r_0^*)$$

LSQR:

$$\min \|b - Ax\|_2$$



3 ways to solve:

1. Normal eq^s $A^T A x = A^T b$

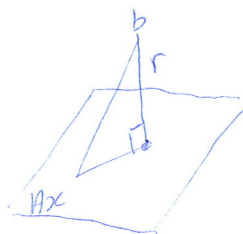
2. QR

3. SVD

Augmented form

$$\begin{pmatrix} I & A \\ A^T & 0 \end{pmatrix} \begin{pmatrix} r \\ x \end{pmatrix} = \begin{pmatrix} b \\ 0 \end{pmatrix}$$

$$r = b - Ax$$



bi-diagonalization:

$$A = U B V^T$$

$$A^T A = V \underbrace{B^T U^T U B}_{I} V^T = V \underbrace{B^T B}_{\text{tridiagonal}} V^T$$

Similarity transformation, the eigenvalues of $T = B^T B$ = eigenvalues of $A^T A$

Take T - iterate until finding eig.

For sparse case

$$A V = U B$$

$$A(v_1, v_2, \dots) = (u_1, u_2, \dots) \begin{pmatrix} \alpha_1 & B_1 & & \\ & \ddots & \ddots & \\ & & B_{k-1} & \\ & & & \alpha_k \end{pmatrix}$$

do this column by column

$$\begin{cases} A V_k = U_{k+1} B_k \\ A^T U_{k+1} = V_k B_k^T + \alpha_{k+1} V_{k+1} e_k^T \end{cases}$$

$$A^T A \rightsquigarrow B_k^T B_k$$

$$\begin{pmatrix} U_k^T \\ V_k^T \end{pmatrix} \begin{pmatrix} I & A \\ A^T & 0 \end{pmatrix} \begin{pmatrix} U_k \\ V_k \end{pmatrix} \approx \underbrace{\begin{pmatrix} I & B_k \\ B_k^T & 0 \end{pmatrix}}$$

solve
least-squares problem
on smaller space