

October 15, 2013

This week: Tue / Thur

Next Tues: Eldad Haber

Only one more assignment

- project proposal & more questions

Assign 1 - this week by Friday

GMRES + CG: the gory details:

GMRES:

$$x_k = x_0 + V z_k$$

$$\text{where } z_k = \underset{z}{\operatorname{argmin}} \|p e_1 - H_{k+1,k} z\|_2$$

$$\rho = \|r_0\|_2$$

To generate $H_{k+1,k}$: Arnoldi ($AQ_k = Q_{k+1} H_{k+1,k}$)

Outline of algorithm:

$$r_0 = b - Ax_0$$

$$\rho = \|r_0\|_2$$

$$q_1 = \frac{r_0}{\rho}$$

For $j=1, \dots, K$ do

 Compute $w_j = Aq_j$

 For $i=1, \dots, j$

$$h_{ij} = (w_j, q_i)$$

$$w_j = w_j - h_{ij} q_i$$

 enddo

$$h_{j+1,j} = \|w_j\|_2$$

 if $h_{j+1,j} = 0$ set $k=j$ and jump out of loop

$$q_{j+1} = w_j / h_{j+1,j}$$

Arnoldi-Modified Gram-Schmidt.

$$H_{k+1,k} = \{h_{ij}\}$$

end do

$$z_k \leftarrow \min \|p_i - H_{k+1,k} z\|$$

$$x_k \leftarrow x_0 + Q z_k$$

We generate $H_{k+1,k}$ using Arnoldi MGS

↳ a (probably) better way: Householder Arnoldi:

* Note: solution is not explicitly given at every step

When do we stop?

look at the least squares problem...

$$\min \|p_i - H_{k+1,k} z\|$$

$$H_{k+1,k} = \begin{array}{c} \text{triangle} \end{array} \begin{array}{c} k=5 \\ h_{11} \ h_{12} \ h_{13} \ h_{14} \ h_{15} \\ h_{21} \qquad \qquad \qquad h_{55} \\ \qquad \qquad \qquad h_{56} \end{array}$$

problem: $\min \|b - Ax\|$ (note: not same A, b, x).

$$\begin{aligned} \phi(x) &= \|b - Ax\|^2 \\ &= (b - Ax)^T (b - Ax) \end{aligned}$$

$$\nabla \phi = 0 \Rightarrow A^T A x = A^T b \quad \leftarrow \text{normal equations}$$

$$\begin{aligned} \text{QR: } A = QR &\Rightarrow \underbrace{R^T Q^T Q R}_{I} x = R^T Q^T b \quad \text{very good if } A \text{ is well-conditional,} \\ x &= R^{-1} (Q^T b) \quad \text{otherwise use QR} \\ &\quad \text{economy size.} \end{aligned}$$

How to form QR:

① Gram-Schmidt: triangularly orthogonalize

② Householder: force $A \rightarrow R$

$$\|v\|_2 = 1$$

$$(I - 2vv^T)x$$

$$\underbrace{(I - 2vv^T)}_{Q_1} a_1 = \beta e_1$$

$$\begin{pmatrix} | & | & | \\ a_1 & a_2 & \dots \\ | & | & | \end{pmatrix} \xrightarrow[\text{transform}]{\text{orthogonal}} \begin{pmatrix} \beta & & \\ & \ddots & \\ 0 & & \end{pmatrix}$$

$a_1 = rV = \beta e_1$ * to choose sign, try to add rather than subtract (to reduce cancellation errors).

$$rV = a_1 - \beta e_1$$

$$|\beta| = \|a_1\|$$

take norms

$$|\beta| = \|a_1 - \beta e_1\|$$

$$V = \frac{a_1 - \beta e_1}{\|a_1 - \beta e_1\|}$$

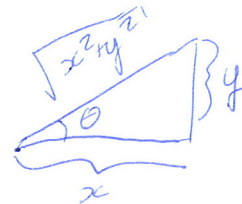
③ Given rotations:

$$\begin{pmatrix} C & S \\ -S & C \end{pmatrix} \begin{pmatrix} x & x \\ x & x \end{pmatrix} = \begin{pmatrix} x & x \\ 0 & x \end{pmatrix}$$

$$C = \cos \theta$$

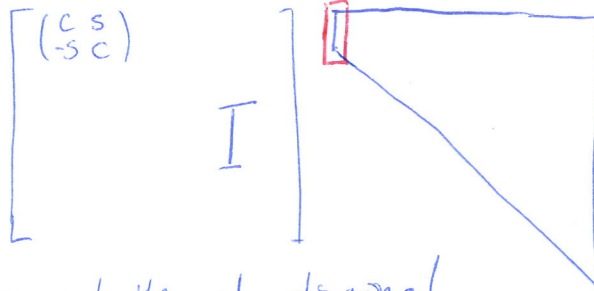
$$S = \sin \theta$$

$$C^2 + S^2 = 1$$



$$C = \frac{x}{\sqrt{x^2 + y^2}} \quad S = \frac{y}{\sqrt{x^2 + y^2}}$$

so



* Rotation is an orthogonal transformation (preserves the norm)

zero out the -1 diagonal

↳ so you get an upper triangular matrix

Apply $S_i = \frac{k_{21}}{\sqrt{k_{11}^2 + k_{21}^2}} \quad C_i = \frac{k_{11}}{\sqrt{k_{11}^2 + k_{21}^2}}$

$$P_i = \begin{pmatrix} C_i & S_i \\ -S_i & C_i \end{pmatrix} \quad I \quad H \rightarrow \begin{pmatrix} x & x & \dots & x \\ 0 & x & \dots & x \\ x & x & \dots & x \\ \vdots & \vdots & \ddots & \vdots \\ x & x & \dots & x \end{pmatrix} = P_i H$$

$$P_2 = \begin{pmatrix} C_2 & S_2 \\ -S_2 & C_2 \end{pmatrix} \quad I \quad \rightarrow P_2 P_i H = \begin{pmatrix} x & x & \dots & x \\ 0 & x & \dots & x \\ x & x & \dots & x \\ \vdots & \vdots & \ddots & \vdots \\ x & x & \dots & x \end{pmatrix}$$

$$H_{k+1,k} z \approx p e_i$$

$\left(\begin{array}{c} p \\ 0 \\ 0 \\ \vdots \\ 0 \end{array} \right)_{k+1 \text{ elements}}$
 $\xrightarrow{\text{apply } P_i}$
 $\left(\begin{array}{c} c_i p \\ -s_i p \\ 0 \\ \vdots \\ 0 \end{array} \right)$

in the end, we will have

$$\left(\begin{array}{c} \text{upper triangular } R \\ \text{zeros below} \end{array} \right)_{k+1} \quad \left(\begin{array}{c} r_1 \\ \vdots \\ r_{k+1} \end{array} \right)$$

we have taken

$$H_{k+1,k} z \approx p e_i \rightarrow \begin{pmatrix} R \\ 0 \end{pmatrix} z \approx \begin{pmatrix} r_1 \\ \vdots \\ r_{k+1} \end{pmatrix}$$

residual: $r_{k+1} = \|r_{k+1}\| = \text{norm of residual.}$

\hookrightarrow don't need to work extra to form residual.

so $\|r_{k+1}\|$ can be used as a stopping criteria

One final comment:

$$h_{j+1,j} = 0$$

\hookrightarrow lucky breakdown: means we have constructed the entire basis for

Krylov Subspace: quit + be happy!

\hookrightarrow how small is zero

FGMRES: Flexible GMRES - use $\{M_j\}$ preconditioners throughout...