# Arduino Workshop

(ESP32 Intermediate Level)

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มหาวิทยาลัยขอนแก่น

# **Agenda**

#### Content

- Serial Read
- Analog mapping
- Pulse-width modulation
- Timer
- Bluetooth communication
- I<sup>2</sup>C LCD display
- Arduino IDE plotter

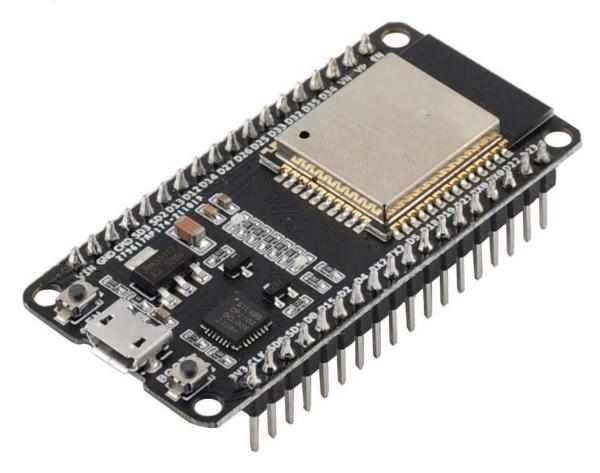
# **Prerequisite:**

- 1. Basic C/C++ programming language (Arduino IDE)
- 2. Basic ESP32 course
- 3. Electronics (not required, but will be advantageous)

# **ESP32 DEVKIT**

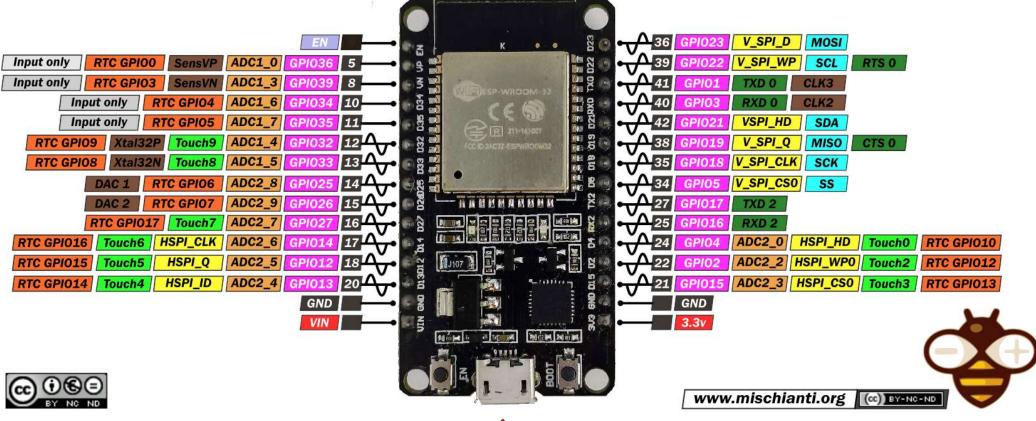
#### **ESP-WROOM-32 DevKit**

- utilizes ESP32 chip, 240MHz, RAM 512KB, 4MB flash memory
- WiFi 2.4GHz / Bluetooth



# **ESP32 DEVKIT Pinout**

### ESP32 DEV KIT V1 PINOUT

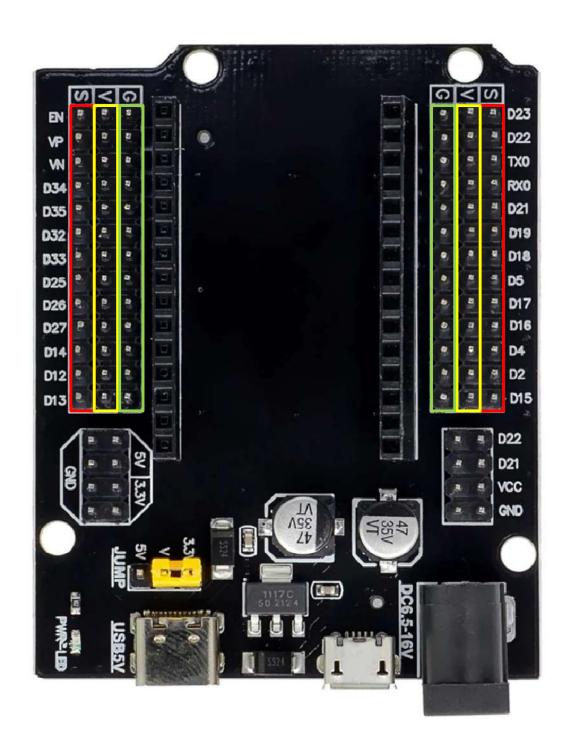




# **ESP32 Extension Board**

- Pins extension
- External power supply

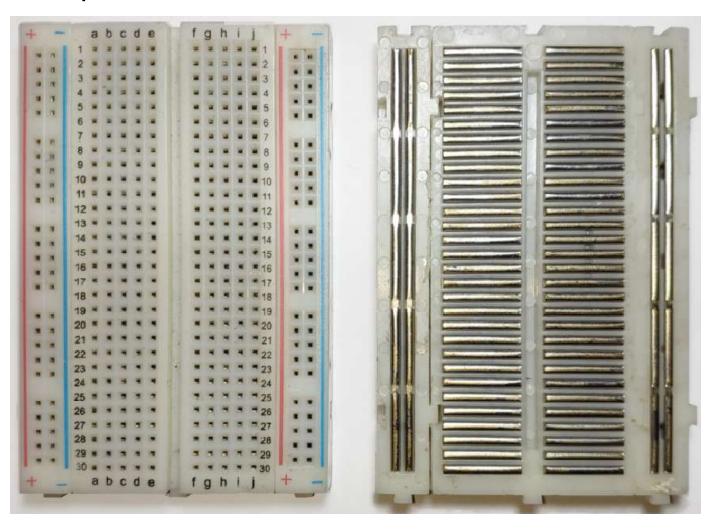
S (Signal) Pins
V (3V Power supply) Pins
G (Ground) Pins



# Circuit Construction

#### **Prototyping board**

- Pre-connected conductor stripes
- Horizontal stripes on 2 top rows and 2 bottom rows
- Vertical stripes in the middle



# Arduino Reference Sheet

### https://kku.world/e664b0

#### Arduino Programming Cheat Sheet

Primary source: Arduino Language Reference https://www.arduino.cc/reference/en/

int peek()

flush()

Libraries

Serial - comm. with PC or via RX/TX

int available() // #bytes available

int read() // -1 if none available

// Read w/o removing

write(char \* string)

// Only 1 can listen

println(data)

begin(long speed) // Up to 115200

#### Structure & Flow

```
Basic Program Structure
void setup() {
  // Runs once when sketch starts
void loop() {
 // Runs repeatedly
Control Structures
if (x < 5) { ... } else { ... }
while (x < 5) { ... }
for (int i = 0; i < 10; i++) { ... }
break: // Exit a loop immediately
continue: // Go to next iteration
switch (var) {
  case 1:
   break:
  case 2:
   break;
  default:
return x; // x must match return type
return:
         // For void return type
Function Definitions
<ret. type> <name>(<params>) { ... }
```

e.g. int double(int x) {return x\*2;}

#### Operators

```
General Operators
   assignment
                  subtract
   multiply
                  divide
   modulo
== equal to != not equal to
 less than > greater than
<= less than or equal to
>= greater than or equal to
&& and
              II or
Compound Operators
++ increment
-- decrement
+= compound addition
-= compound subtraction
*= compound multiplication
/= compound division
&= compound bitwise and
|= compound bitwise or
Bitwise Operators
& bitwise and
                    bitwise or
   bitwise xor
                 ~ bitwise not
<< shift left
                 >> shift right
```

Pointer Access

& reference: get a pointer

dereference: follow a pointer

#### Variables, Arrays, and Data

```
Data Types
                                           Numeric Constants
bool
               true | false
                                          123
                                                      decimal
               -128 - 127, 'a' '$' etc.
char
                                          0b01111011 binary
                 0 - 255
                                          0173
                                                      octal - base 8
unsigned char
                                                      hexadecimal - base 16
                 0 - 255
                                          Өх7В
byte
             -32768 - 32767
                                          12311
                                                      force unsigned
int
unsigned int
                 0 - 65535
                                          1231
                                                      force long
                 0 - 65535
                                          123UL
                                                      force unsigned long
       -2147483648 - 2147483647
                                          123.0
                                                       force floating point
long
unsigned long
                                          1.23e6
                                                      1.23*10^6 = 1230000
                0 - 4294967295
float -3.4028e+38 - 3.4028e+38
                                          Oualifiers
double currently same as float
                                          static
                                                      persists between calls
void
        return type: no return value
                                          volatile
                                                      in RAM (nice for ISR)
                                                      read-only
                                          const
                                          PROGMEM
                                                      in flash
char str1[8] =
  {'A','r','d','u','i','n','o','\0'};
  // Includes \0 null termination
                                          byte myPins[] = {2, 4, 8, 3, 6};
                                           int myInts[6]; // Array of 6 ints
  {'A','r','d','u','i','n','o'};
                                          myInts[0] = 42; // Assigning first
  // Compiler adds null termination
                                                           // index of myInts
char str3[] = "Arduino";
                                          myInts[6] = 12; // ERROR! Indexes
char str4[8] = "Arduino";
                                                           // are 0 though 5
```

#### Built-in Functions

```
Pin Input/Output
Digital I/O - pins 0-13 A0-A5
  pinMode(pin,
                                       sin(rad)
   {INPUT | OUTPUT | INPUT_PULLUP})
                                       sqrt(x)
  int digitalRead(pin)
 digitalWrite(pin, {HIGH|LOW})
Analog In - pins A0-A5
                                       Random Numbers
  int analogRead(pin)
  analogReference(
   {DEFAULT | INTERNAL | EXTERNAL })
PWM Out - pins 3 5 6 9 10 11
                                       Bits and Bytes
 analogWrite(pin, value) // 0-255
                                       bitRead(x, bitn)
Advanced T/O
tone(pin, freq_Hz, [duration_msec])
                                       bitSet(x, bitn)
noTone(pin)
                                       bitclear(x, bitn)
shiftOut(dataPin, clockPin,
                                       bit(bitn) // bitn: 0=LSB 7=MSB
  {MSBFIRST|LSBFIRST}, value)
shiftIn(dataPin, clockPin,
                                       Type Conversions
 {MSBFIRST|LSBFIRST})
unsigned long pulseIn(pin,
```

unsigned long millis() // Overflows at 50 days unsigned long micros() // Overflows at 70 minutes delay(msec) delayMicroseconds(usec)

{HIGH|LOW}, [timeout\_usec])

min(x, y) max(x, y) abs(x)cos(rad) tan(rad) pow(base, exponent) constrain(x, minval, maxval) map(val, fromL, fromH, toL, toH)

randomSeed(seed) // long or int long random(max) // 0 to max-1 long random(min, max)

lowByte(x) highByte(x) bitWrite(x, bitn, bit)

char(val) byte(val) int(val) word(val) long(val) float(val)

External Interrupts attachInterrupt(interrupt, func, {LOW|CHANGE | RISING | FALLING } ) detachInterrupt(interrupt) interrupts() noInterrupts()

#### print(data) write(byte) write(byte \* data, size) SerialEvent() // Called if data rdy SoftwareSerial.h - comm. on any pin SoftwareSerial(rxPin, txPin) begin(long speed) // Up to 115200 isListening() // at a time. read, peek, print, println, write // Equivalent to Serial library FEPROM.h - access non-volatile memory byte read(addr) write(addr, byte) EEPROM[index] // Access as array Servo.h - control servo motors attach(pin, [min\_usec, max\_usec]) write(angle) // 0 to 180 writeMicroseconds(uS)

// 1000-2000: 1500 is midpoint int read() // 0 to 180 bool attached() detach() Wire.h - I2C communication begin() // Join a master

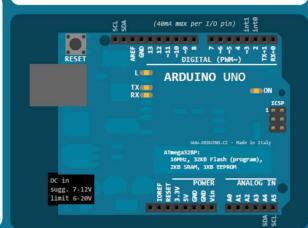
begin(addr) // Join a slave @ addr requestFrom(address, count) beginTransmission(addr) // Step 1 send(byte) send(char \* string) send(byte \* data, size) endTransmission() // Step 3 int available() // #bytes available byte receive() // Get next byte onReceive(handler) onRequest(handler)



#### (cc) (i) (i) by Mark Liffiton

Adapted from:

- Original: Gavin Smith
- SVG version: Frederic Dufourg - Arduino board drawing: Fritzing.org



# **ESP32 Serial Communication**

- ESP32 can use PC screen and keyboard
- Serial.print() is used for sending message to PC screen
- Open sketch: serial\_read\_basic.ino
- Serial.available() → use to check if there is a data sent from PC
- Serial.read() is used for receiving 1 character from PC keyboard
- This function returns ASCII code of a character
- For example: 'A' = 65, 'B' = 66, '\$' = 36, 'a' = 97, 'b' = 98
- Use (char) inside Serial.print() to convert ASCII code to character

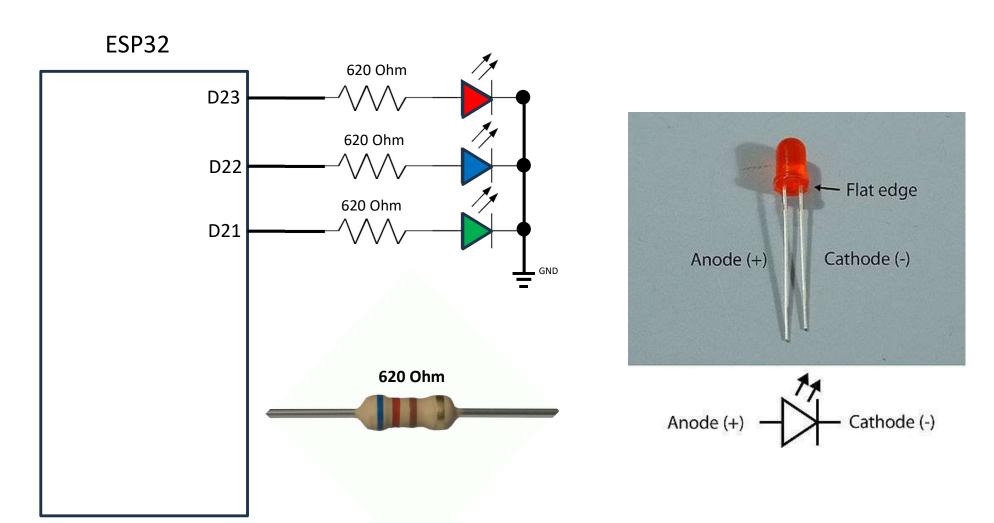
# **ESP32 Serial Communication**

#### **ASCII** code table

| V. |                     |    |                  |    |                |    |   |    |   |    |   |     |   |     |                  |
|----|---------------------|----|------------------|----|----------------|----|---|----|---|----|---|-----|---|-----|------------------|
| 0  | N <sub>U</sub> L    | 16 | D <sub>L</sub> E | 32 | S <sub>P</sub> | 48 | 0 | 64 | @ | 80 | Р | 96  | • | 112 | р                |
| 1  | S<br>O<br>H         | 17 | D <sub>C</sub> 1 | 33 | !              | 49 | 1 | 65 | Α | 81 | Q | 97  | а | 113 | q                |
| 2  | S<br>T <sub>X</sub> | 18 | D <sub>C</sub> 2 | 34 | 11 II          | 50 | 2 | 66 | В | 82 | R | 98  | b | 114 | r                |
| 3  | E <sub>T</sub>      | 19 | D <sub>C</sub> 3 | 35 | #              | 51 | 3 | 67 | С | 83 | S | 99  | С | 115 | s                |
| 4  | E <sub>O</sub> T    | 20 | D <sub>C</sub> 4 | 36 | \$             | 52 | 4 | 68 | D | 84 | Т | 100 | d | 116 | t                |
| 5  | E <sub>N</sub> Q    | 21 | N <sub>A</sub> K | 37 | %              | 53 | 5 | 69 | Е | 85 | U | 101 | е | 117 | u                |
| 6  | <sup>А</sup> с<br>к | 22 | S<br>Y<br>N      | 38 | &              | 54 | 6 | 70 | F | 86 | V | 102 | f | 118 | V                |
| 7  | B <sub>E</sub> L    | 23 | E <sub>T</sub> B | 39 | I.             | 55 | 7 | 71 | G | 87 | W | 103 | g | 119 | w                |
| 8  | B <sub>S</sub>      | 24 | C <sub>A</sub> N | 40 | (              | 56 | 8 | 72 | Н | 88 | Χ | 104 | h | 120 | х                |
| 9  | НТ                  | 25 | E                | 41 | )              | 57 | 9 | 73 | I | 89 | Υ | 105 | i | 121 | у                |
| 10 | L <sub>F</sub>      | 26 | S<br>U<br>B      | 42 | *              | 58 | : | 74 | J | 90 | Z | 106 | j | 122 | z                |
| 11 | v <sub>T</sub>      | 27 | E <sub>S</sub> C | 43 | +              | 59 | ; | 75 | K | 91 | [ | 107 | k | 123 | {                |
| 12 | F <sub>F</sub>      | 28 | F <sub>S</sub>   | 44 | 1              | 60 | < | 76 | L | 92 | \ | 108 | 1 | 124 | 1                |
| 13 | C <sub>R</sub>      | 29 | G <sub>S</sub>   | 45 | -              | 61 | = | 77 | М | 93 | ] | 109 | m | 125 | }                |
| 14 | s <sub>s</sub>      | 30 | R <sub>S</sub>   | 46 |                | 62 | > | 78 | Ν | 94 | ٨ | 110 | n | 126 | ~                |
| 15 | SI                  | 31 | u <sub>s</sub>   | 47 | /              | 63 | ? | 79 | 0 | 95 | _ | 111 | 0 | 127 | D <sub>E</sub> L |

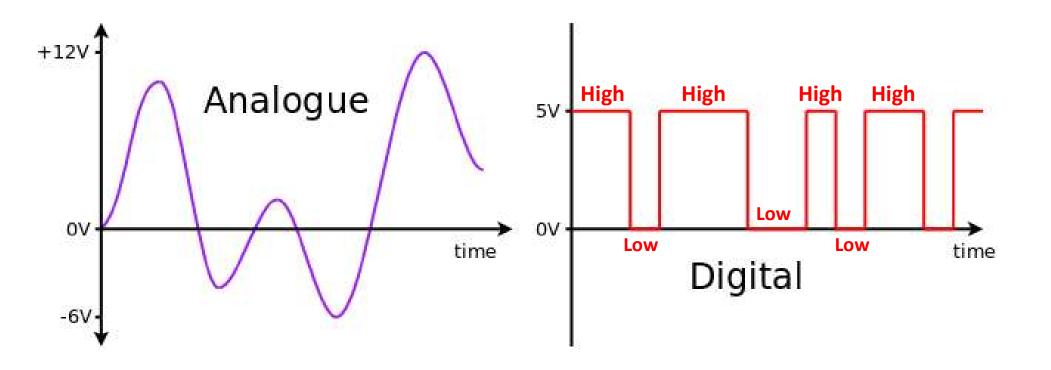
# **ESP32 Serial Communication**

- Application: Control LEDs from PC keyboard
- Open sketch: serial\_read\_LEDs.ino



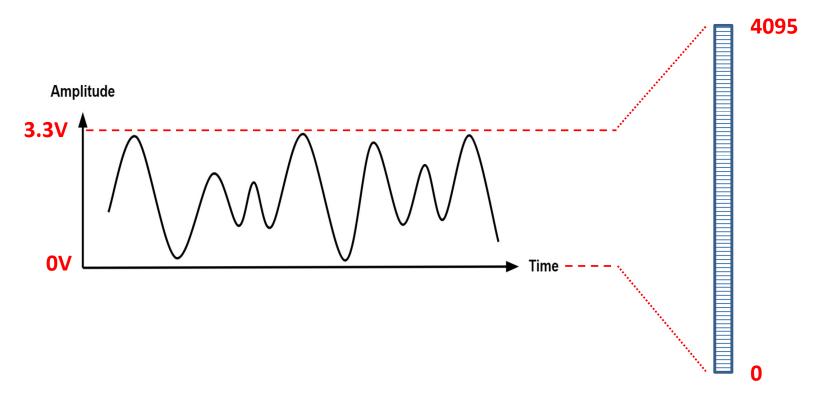
# **Analog Input**

- Analog signal is continuous and can be any value
- Digital signal is limited to two possible value 0 and 1 (low and high)
- Use AnalogRead() to get analog value



# **Analog Input** (revisited)

- Use AnalogRead() to get analog value
- Analog signal is continuous and can be any value
- Digital signal is limited to two possible value 0 and 1 (low and high)



- Max analog voltage is 3.3V and converted to 4095
- Formula:  $Analog\ value = 4095*(X/3.3)$
- Ex if analog input = 2.5V, analogRead() will return value of 4095\*(2.5/3.3) = 3102

# **Analog Input**

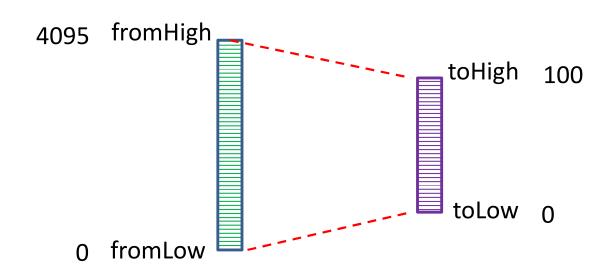
- AnalogRead() always gives value in range 0-4095
- Values in this range can be mapped to different ranges
- For example, 0-100 (for percentage calculation)
- Use map() to convert analog read value:

#### Syntax:

NewValue = map(Value, fromLow, fromHigh, toLow, toHigh);

#### **Example**

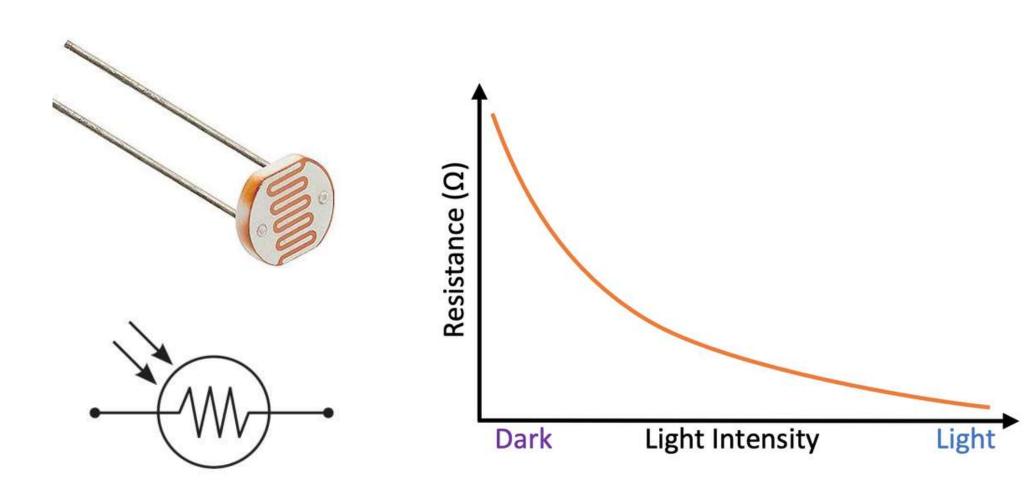
NewRange = map(val, 0, 4095, 0, 100);



# **Analog Sensor**

Light Dependent Resistor (LDR)

- LDR is a type of resistor whose resistance varies with light intensity
- Dark → high resistance, bright → low resistance

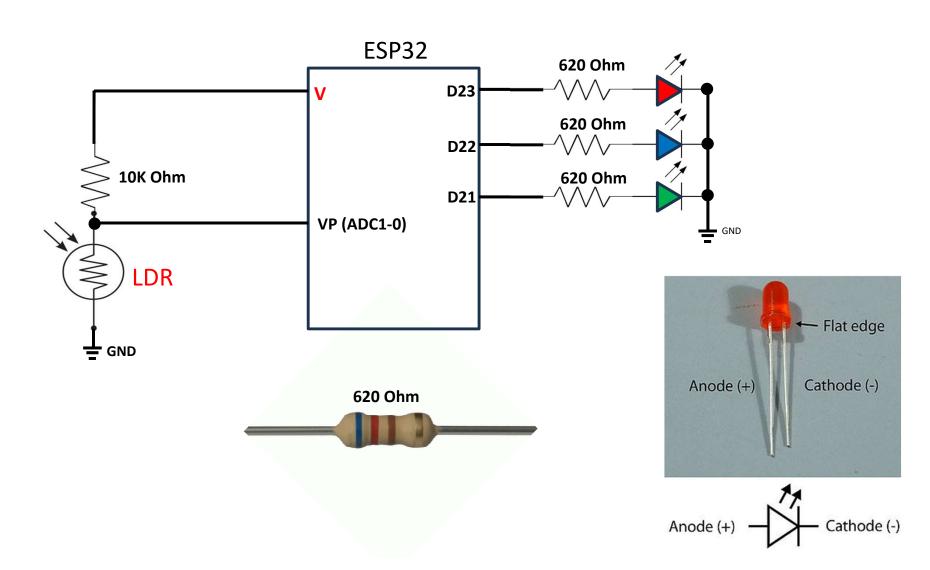


# **Analog Sensor**

Light Dependent Resistor (LDR)

- LDR is a type of resistor whose resistance varies with light intensity
- Dark → high resistance, bright → low resistance

Open sketch: LDR\_Test.ino

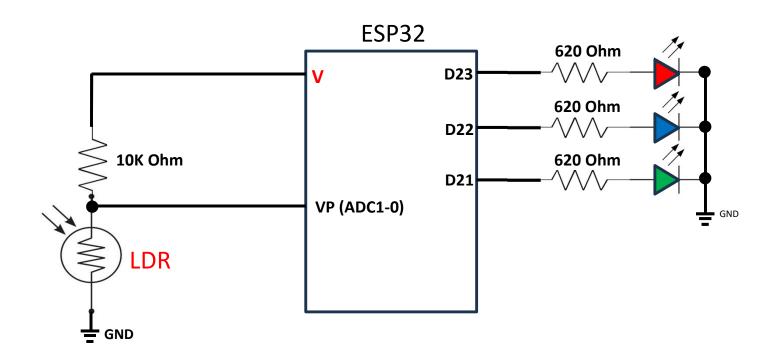


# **Analog Sensor**

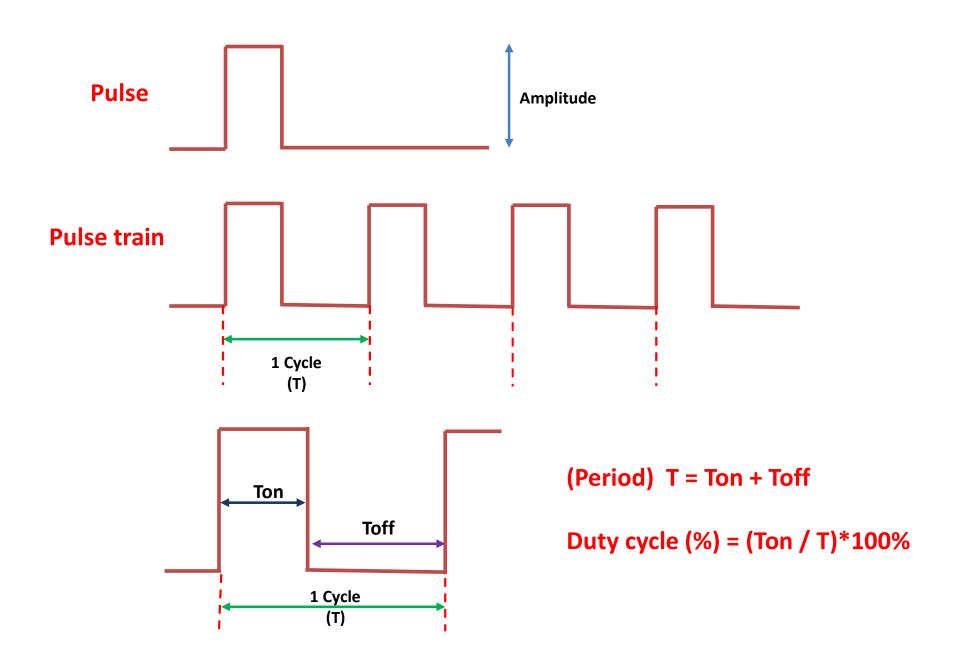
- Examine raw analog value obtained from analogRead()
- What is the minimum and maximum value?

#### • Exercise

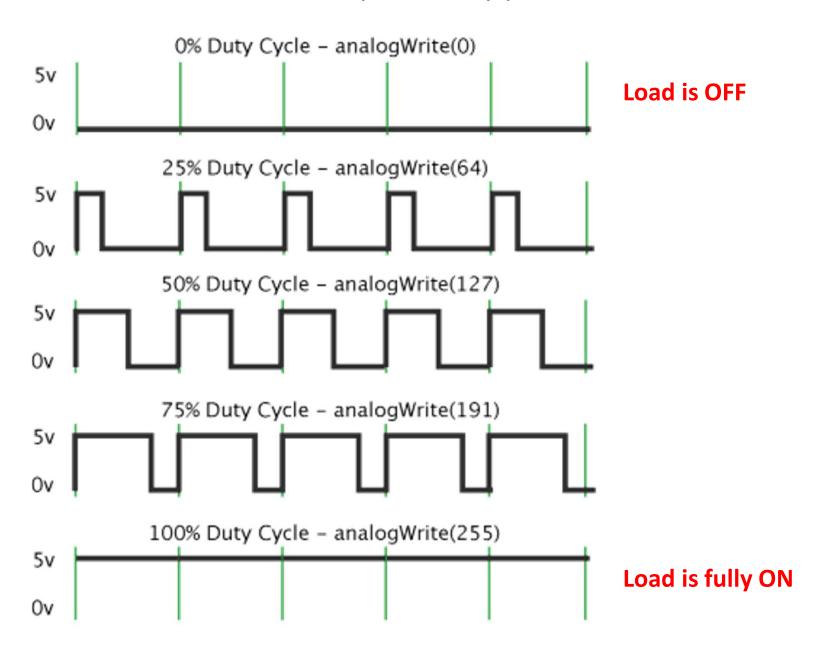
- Modify sketch to show light intensity in percentage
- 0% = darkest and 100% = brightest
- Further modification: turn on LEDs according to darkness
- Turn 3 LEDs on  $\rightarrow$  30% brightness, 2 LEDs  $\rightarrow$  60%, 1 LEDs  $\rightarrow$  90%
- Turn off all LEDs when brightness is greater than 90%



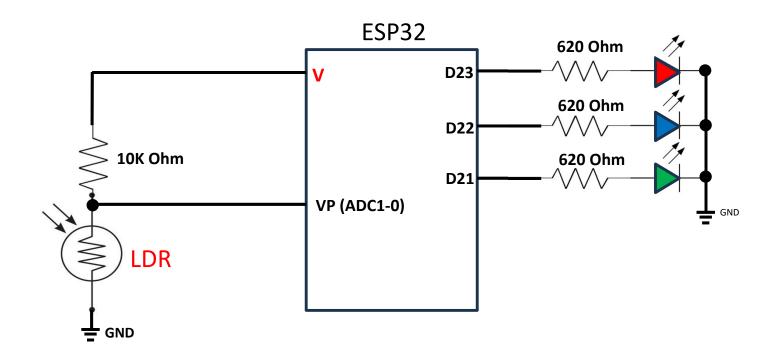
• Pulse is a rapid, transient change in the amplitude of a signal



PWM is used as a technique to vary power delivered to load

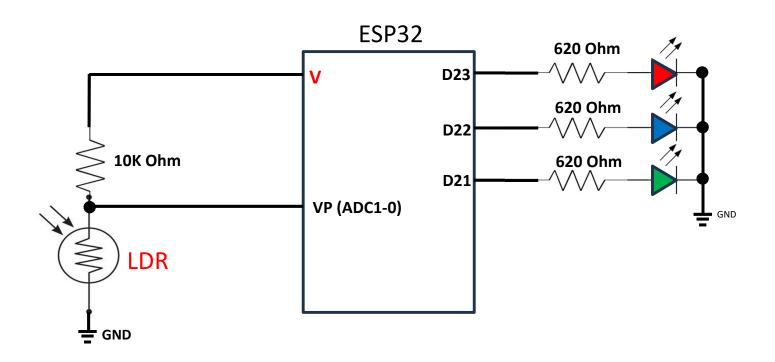


- Use analogWrite() function to control PWM
- Syntax: analogWrite(pin, duty\_cycle)
- Open sketch: PWM\_LED.ino



- A common application is to control brightness of LEDs
- Exercise

Write a program that dims LEDs when the LDR is in high brightness and brighten LEDs when the LDR is in dark

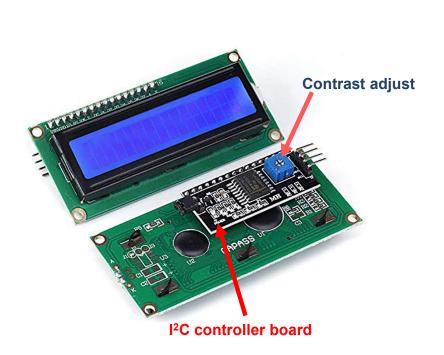


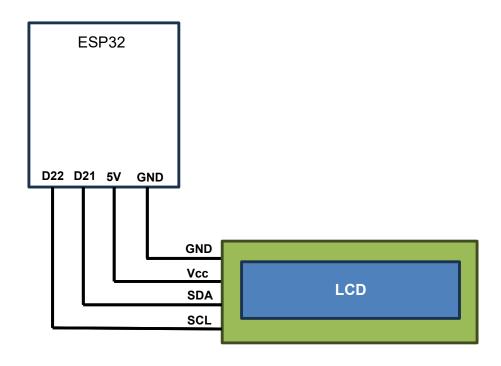
- Liquid Crystal Display (LCD) is an electronic component used for displaying Texts, numbers and symbols
- Available in several models measured by number of lines and characters
- For example: 1x16, 2x16, 2x20, 4x20, etc.
- Backlight is optional
- Typical LCD module requires 16 data lines for communication





- Inter-Integrated Circuit (IIC or I<sup>2</sup>C) is used to simplified communication between LCD module and ESP32
- I<sup>2</sup>C uses only 2 I/O lines for communication





- To use I<sup>2</sup>C LCD module, install "LiquidCrystal I2C" library from provided .zip file
- Run test code: I2C\_LCD\_Test.ino
- This library provides the following LCD display functions:
  - \*\*\* Icd object must be created first \*\*\*

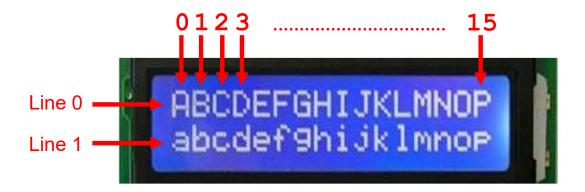
lcd.init() -- initialize LCD module

lcd.backlight()-- turn on backlight

lcd.noBacklight()-- turn off backlight

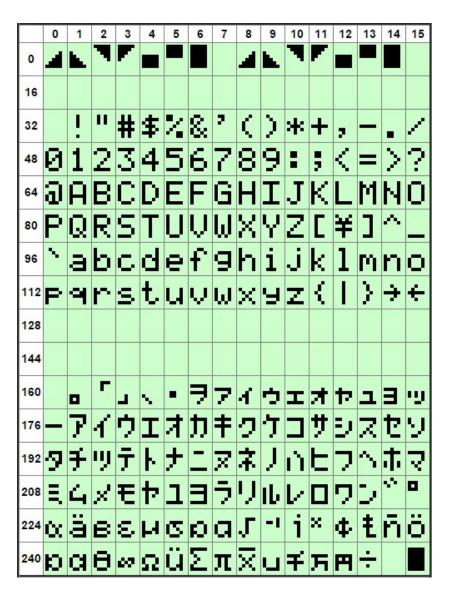
lcd.print(" ") -- print text message at current cursor position

lcd.setCursor(x, y) -- move cursor to column x, line y

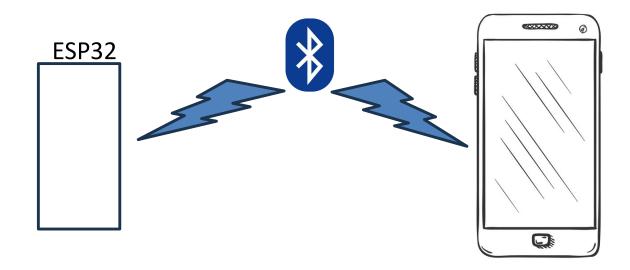


- Floating point numbers can be printed with specified number of fraction
- Run test code: I2C\_LCD\_Numbers.ino
- LCD display contain preloaded special characters:
  - To print these characters, use (char) x inside lcd.print()
  - For example:

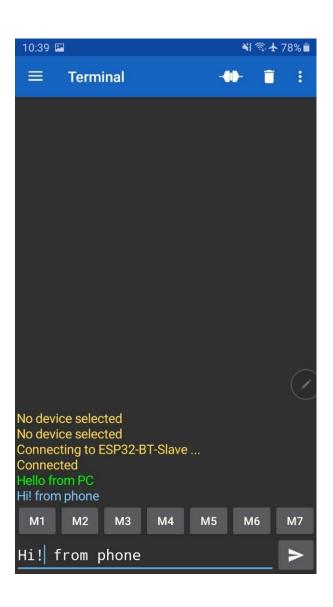
Icd.print((char) 247); // print  $\pi$ 

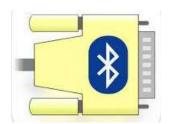


- ESP32 has built-in Bluetooth classic module for sending/receiving data
- To use ESP32 Bluetooth:
  - Add header file: #include "BluetoothSerial.h"
    - -Create object: BluetoothSerial SerialBT;
  - Initialize: SerialBT.begin(device\_name);
  - To receive data, use .read() method
  - To send data, use .write() method
- Need a paring Bluetooth device



On your mobile phone, install Serial Bluetooth Terminal App





- Open sketch: BT\_Test.ino
- Give your ESP32 Bluetooth a name (Line 2 in the sketch)

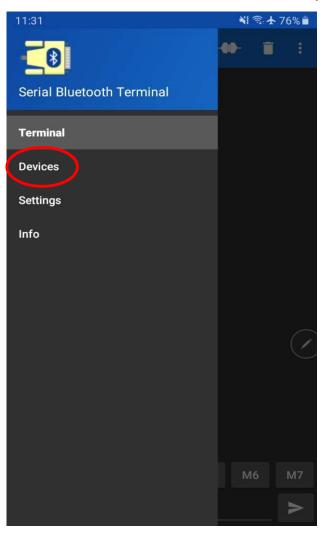
```
#include "BluetoothSerial.h"

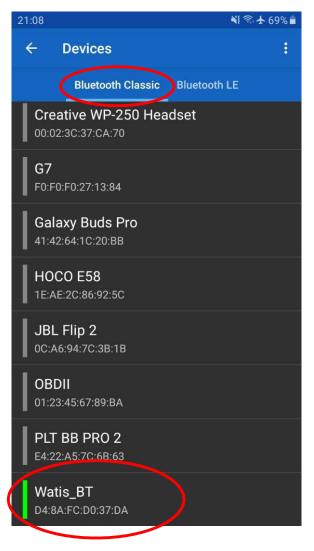
String device_name = "Watis_BT" //<--- Replace with your name

BluetoothSerial SerialBT;</pre>
```

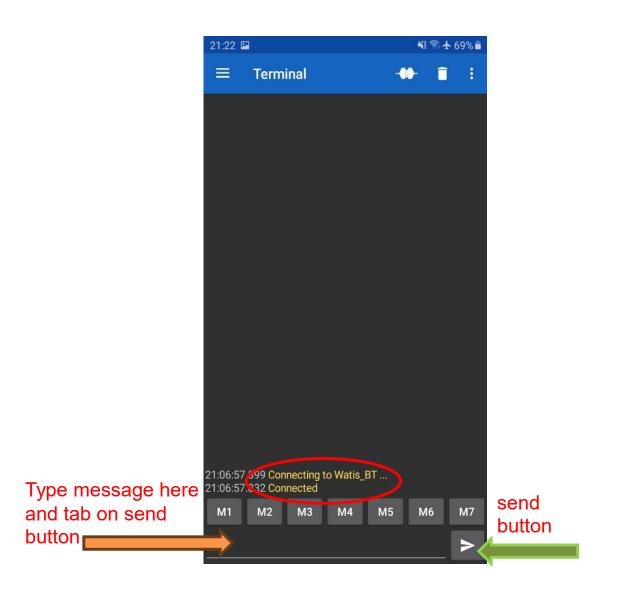
Upload the sketch to ESP32

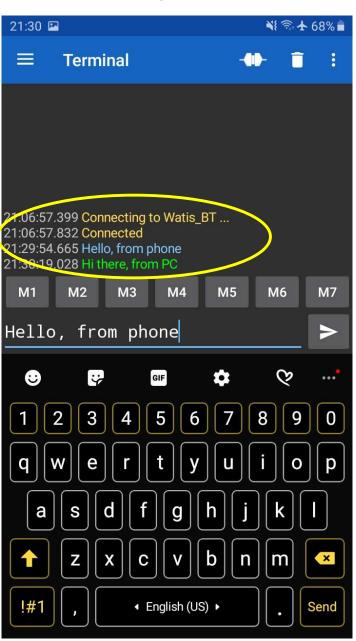
- Open Serial Bluetooth Terminal App
- Go to menu
- Choose Devices
- Under Bluetooth Classic tab, look for your ESP32 Bluetooth device





- After selecting your ESP32 Bluetooth device, go to Terminal screen
- Connection is established, you can send/receive message





- Application: LED control via Bluetooth
- Open sketch: BTLED.ino
- Give your ESP32 Bluetooth a name (Line 4 in the sketch)

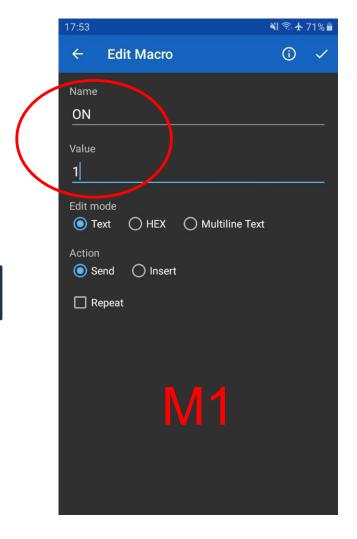
```
String device_name = "Watis_BT"; //<--- Replace with your name
BluetoothSerial SerialBT;</pre>
```

- Upload the sketch to ESP32
- From Serial Bluetooth Terminal App:
  - send number 1 to turn on the onboard LED
  - send number 0 to turn off the onboard LED

We can use available soft buttons on the application to send 0 or 1

Long press button to edit its function

Long press button to edit its function



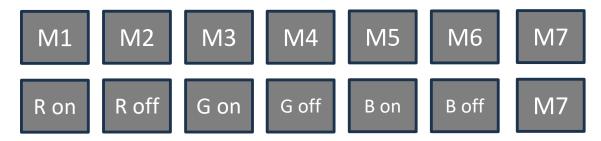
ON

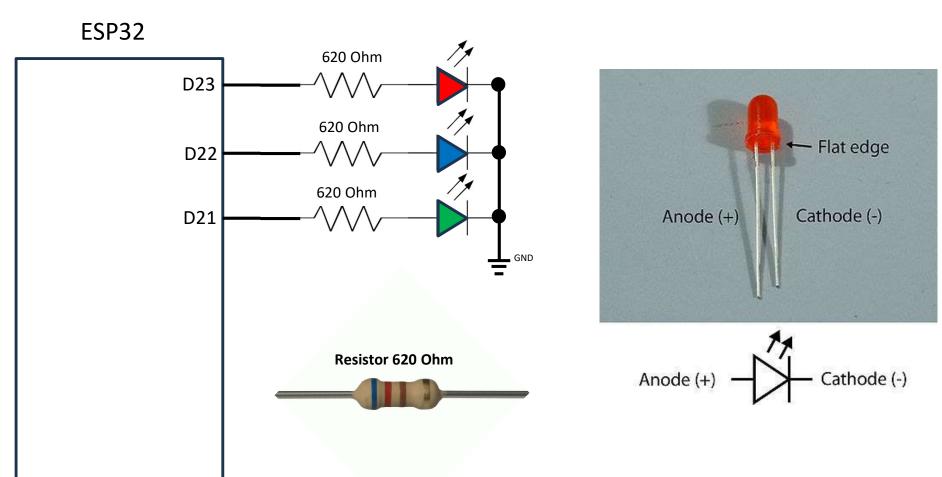




# **ESP32 Input/Output**

Exercise: Use Bluetooth to control 3 external LEDs

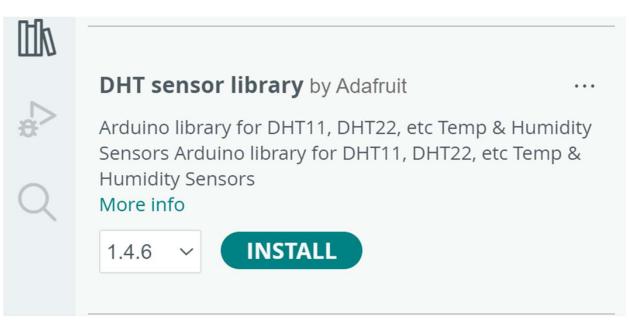


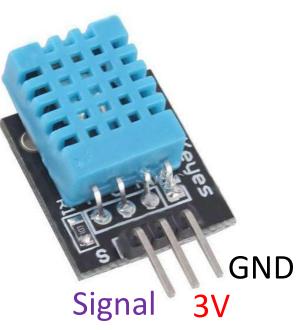


#### Specifications:

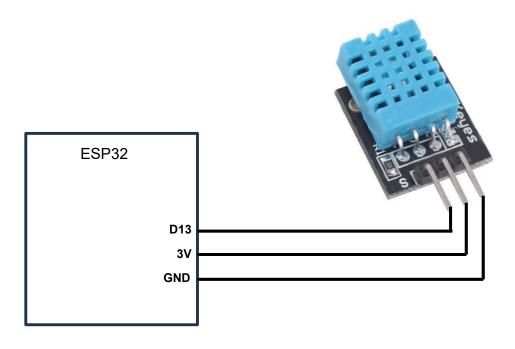
- Temperature 0-50°C
- Humidity 20-90%

In Arduino IDE, Install DHT sensor library





- Open sketch dht11\_demo.ino
- Open serial monitor to see current temperature and humidity



```
Output Serial Monitor X

Message (Enter to send message to 'ESP32 Dev Module' on 'COM3')

Humidity: 67.00% Temperature: 30.80°C 87.44°F

Humidity: 67.00% Temperature: 30.80°C 87.44°F

Humidity: 66.00% Temperature: 30.80°C 87.44°F

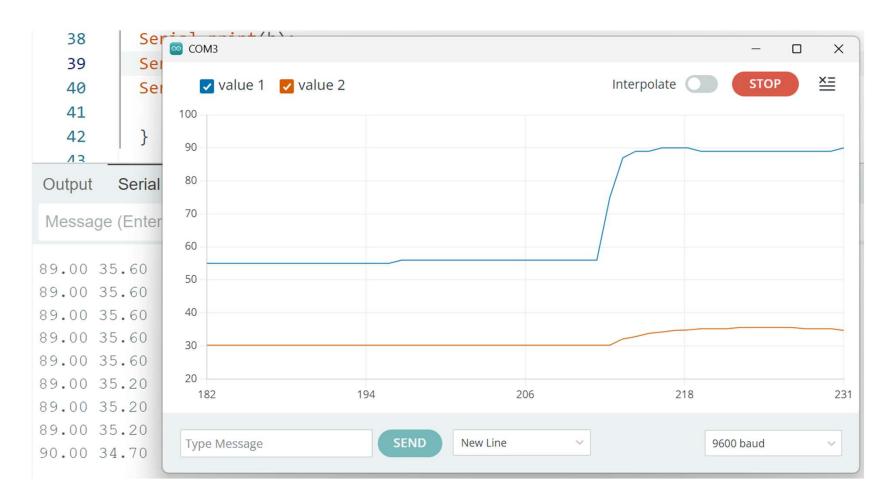
Humidity: 65.00% Temperature: 30.80°C 87.44°F

Humidity: 65.00% Temperature: 30.80°C 87.44°F

Humidity: 64.00% Temperature: 30.80°C 87.44°F

Humidity: 64.00% Temperature: 30.80°C 87.44°F
```

- Comment Serial.print() statements from lines 30 36
- Uncomment **Serial.print()** statements from lines 38 40
- Upload the sketch to ESP32
- Open serial plotter to see graphical plot of temperature and humidity



**Exercise:** Display temperature and humidity on LCD display

